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```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% MATLAB Code: HJB_ramsey_implicit_upwind
%
% Author: Muhammad (Follows closely Kiyea and Benn Moll's versions)
% Date: Nov 8, 2024
%
% Description:
% This MATLAB script implements implicit method to solve the HJB equation
% Hugget Model using upwind scheme.
%
% Reference:
% HJB_NGM_implicit.m by Benjamin Moll
% ramsey_implicit.m by Pontus Rendahl
%
% Notes:
% - CRRA utility function:  $U(c) = (c^{1-\gamma})/(1-\gamma)$ 
% - Production function:  $f(k) = A*k^\alpha$ 
% - Relative risk aversion coefficient ( $\gamma$ ): 2
% - Discount rate ( $\rho$ ): 0.03
% - Depreciation rate ( $\delta$ ): 0.025
% - Elasticity of output with respect to capital ( $\alpha$ ): 1/3
% - Total factor productivity ( $A$ ): 1
% -  $\Delta = 1000$  (Can be arbitrarily large in implicit method)
% - Try with  $\rho = \delta = 0.05$ 
%
% Code Structure:
% 1. DEFINE PARAMETERS
% 2. INITIALIZE GRID POINTS
% 3. PRE-ITERATION INITIALIZATION
% 4. VALUE FUNCTION ITERATION
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

clear all;
close all;
clc;

clear all;
close all;
clc;
```

1. DEFINE PARAMETERS

```
p = define_parameters_Hugget();
```

2. INITIALIZE GRID POINTS

```
% log(k_min) = log(kss)-p.klim
a_min = p.a_min;
a_max = p.a_max;          % This is what Bell Moll uses

a = linspace(a_min, a_max, p.I)';          % Grid for wealth
da = (a_max - a_min)/(p.I-1);              % Grid size

% Every period we are going to have two wealth levels for employed and unemployed
aa = [a,a];
zz = ones(p.I,1)*p.z;          % Income grid
Aswitch = [-speye(p.I)*p.la(1),speye(p.I)*p.la(1);speye(p.I)*p.la(2),-speye(p.I)*p.la(2)]; % Transition matrix, same as our definitions in slides,
```

3. PRE-ITERATION INITIALIZATION

```
% 3-1. Construct the forward and backward differential operator
% Df such that Df*V=dVf and Db such that Db*V=dVb

Df = zeros(p.I, p.I);
for i = 1:p.I-1
    Df(i,i) = -1/da; Df(i,i+1) = 1/da;      % Forward differencing
end
Df = sparse(Df);

Db = zeros(p.I, p.I);
for i = 2:p.I
    Db(i,i-1) = -1/da; Db(i,i) = 1/da;      % Backward differencing
end
Db = sparse(Db);

% 3-2. Guess an initial value of the value function (I evaluate utility at the income paths, follows Benn Moll!)

v0(:,1) = p.u(p.z(1)+p.r.*a)/p.rho;
```

```

v0(:,2) = p.u(p.z(2)+p.r.*a)/p.rho;

v = v0;

% 3-3. Pre-allocate arrays for solutions

dvf = zeros(p.I,2);
dvb = zeros(p.I,2);
c = zeros(p.I,2);

```

4. VALUE FUNCTION ITERATION

```

tic;

for n = 1:p.maxit
    V= v;
    % 4-1. Compute the derivative of the value function
    dvf(:,1) = Df*V(:,1);
    dvb(:,1) = Db*V(:,1);
    dvf(:,2) = Df*V(:,2);
    dvb(:,2) = Db*V(:,2);

    % BOUNDARY CONDITIONS
    dvf(end,:) = p.mu(p.z+p.r.*a_max); % k<=k_max is enforced which helps stability of the algorithm
    dvb(1,:) = p.mu(p.z+p.r.*a_min); % k>=k_min is enforced which helps stability of the algorithm

    % 4-2. Compute the optimal consumption and savings with forward differences
    cf = p.inv_mu(dvf);
    cb = p.inv_mu(dvb);

    sf = zz +p.r.*aa - cf; % Savings
    sb = zz +p.r.*aa - cb;

    % UPWIND SCHEME
    If = sf>0; % If savings is positive, positive drift
    Ib = sb<0; % If savings is negative, negative drift
    I0 = 1-If-Ib; % If savings is zero, no drift
    dV0 = p.mu(zz+p.r.*a);

    dV_upwind = dvf.*If + dvb.*Ib + dV0.*I0;

    c = p.inv_mu(dV_upwind);
    u = p.u(c); % Benn Moll tracks utility as well, I am also going to keep it for now

    % 4-4. Update the value function: V^(n+1) = [(rho+1/Delta)*I - SD]^(-1)[u(c) + 1/Delta*V^n]

    %CONSTRUCT MATRIX
    X = - min(sb,0)/da;
    Y = - max(sf,0)/da + min(sb,0)/da;
    Z = max(sf,0)/da;

    A1=spdiags(Y(:,1),0,p.I,p.I)+spdiags(X(2:p.I,1),-1,p.I,p.I)+spdiags([0;Z(1:p.I-1,1)],1,p.I,p.I);
    A2=spdiags(Y(:,2),0,p.I,p.I)+spdiags(X(2:p.I,2),-1,p.I,p.I)+spdiags([0;Z(1:p.I-1,2)],1,p.I,p.I);
    A = [A1,sparse(p.I,p.I);sparse(p.I,p.I),A2] + Aswitch;

    % @Muhammad, all clear except definition of A1,A2, and A. Definition of Aswitch is also very clear.

    B = (p.rho + 1/p.Delta)*speye(2*p.I) - A;

    u_stacked = [u(:,1);u(:,2)];
    V_stacked = [V(:,1);V(:,2)];

    b = u_stacked + V_stacked/p.Delta;
    V_stacked = B\b; %SOLVE SYSTEM OF EQUATIONS

    V = [V_stacked(1:p.I),V_stacked(p.I+1:2*p.I)];

    Vchange = V - v;
    v = V;

    dist(n) = max(max(abs(Vchange)));
    if dist(n)<p.tol
        disp('Value Function Converged, Iteration = ')
        disp(n)
        break
    end
end

toc;

```

Value Function Converged, Iteration =
12

Elapsed time is 0.024695 seconds.

5. Graphs

```

figure
set(gca,'FontSize',14)

```






