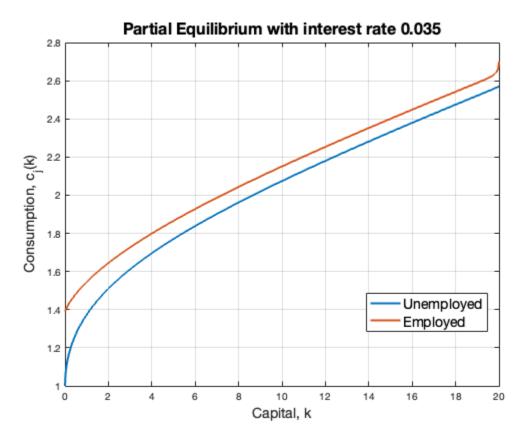
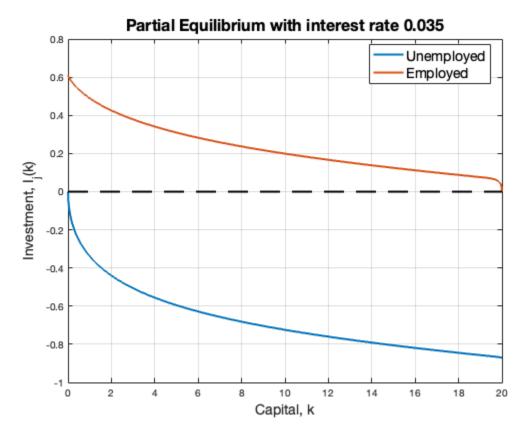
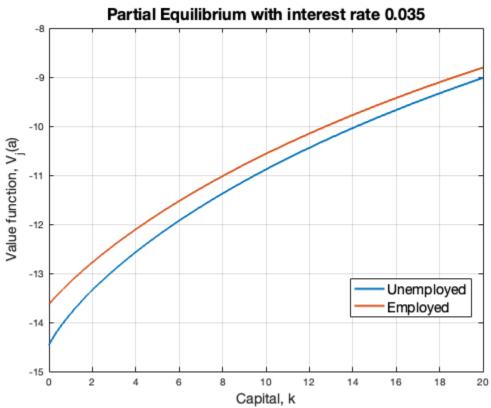
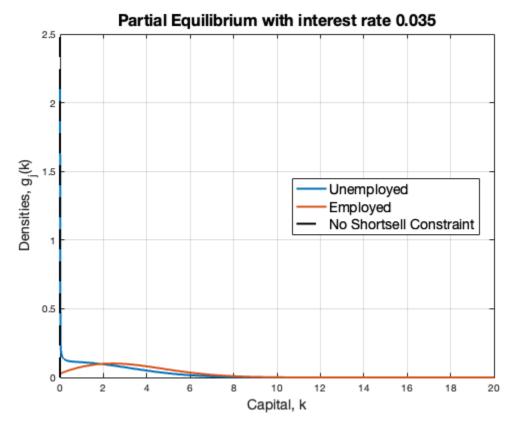
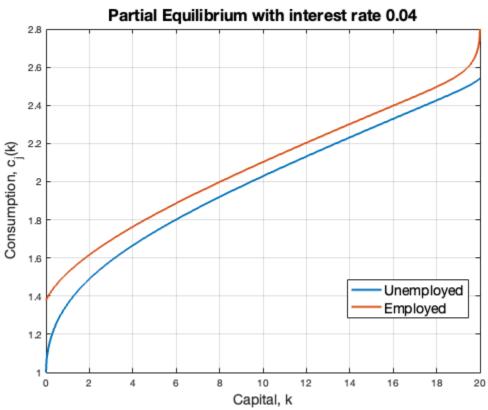
Partial Equilibrium Model

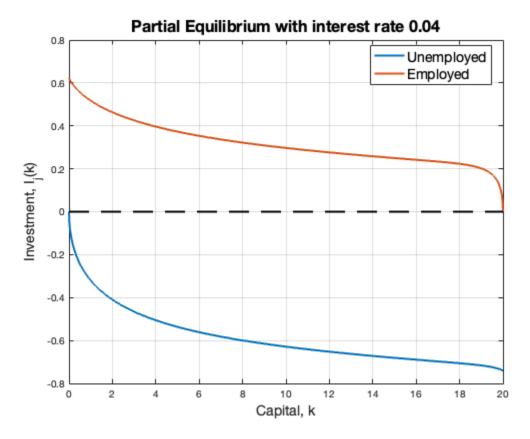


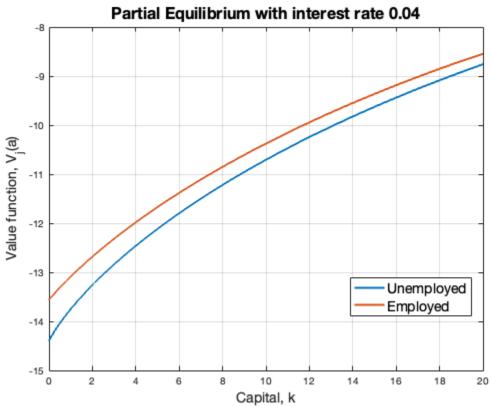


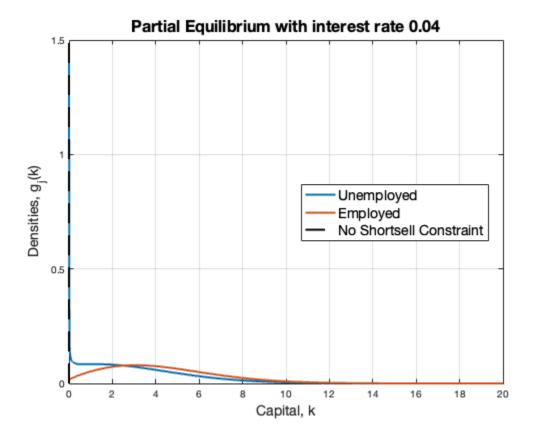












General Equilibrium Model & Transition Path

```
cd('/Users/muhammadbashir/GitHub/MuhammadCourses/DynamicProgramming2024/
ProblemSetSolutions/PS5/GE/');
main_GE
Value function converged Iteration =
```

Value function converged. Iteration = 10

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RCOND = 4.068430e-18.

Value function converged. Iteration = 10

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RCOND = 1.132293e-17.

RCOND = 5.587138e-17.

Value function converged. Iteration =

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Value function converged. Iteration =

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RCOND = 3.259508e-17.

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Value function converged. Iteration =

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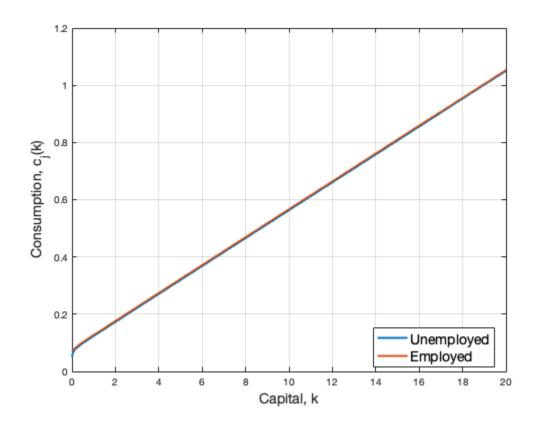
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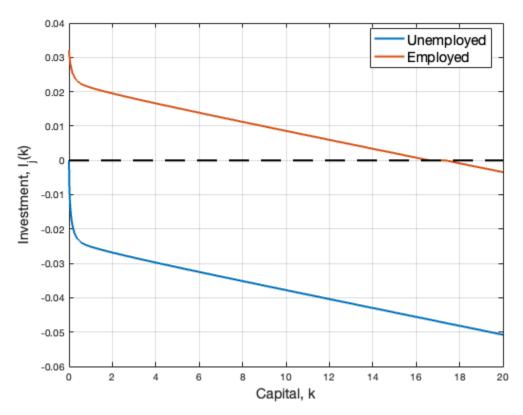
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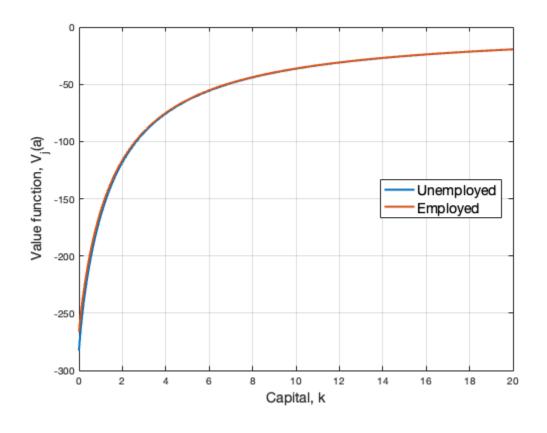
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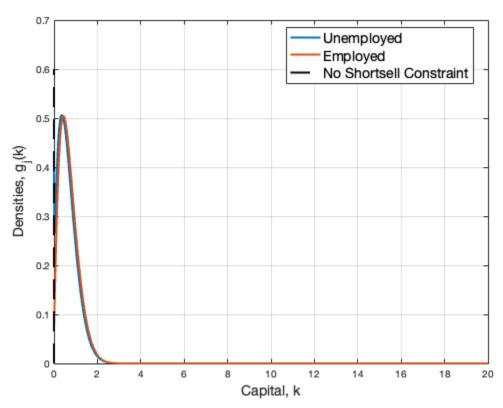
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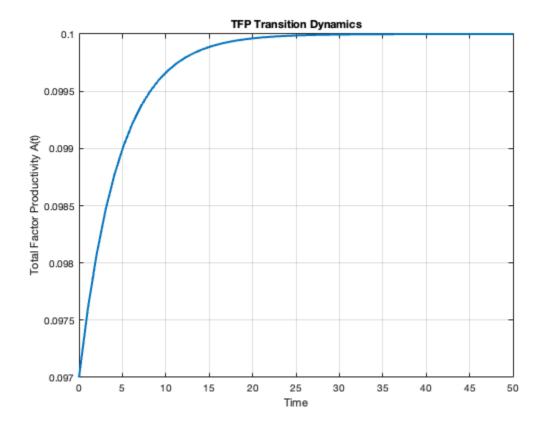
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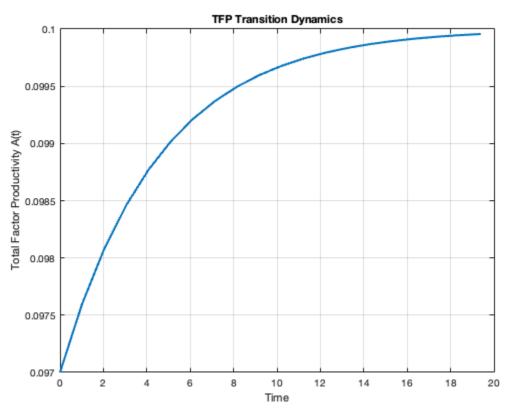


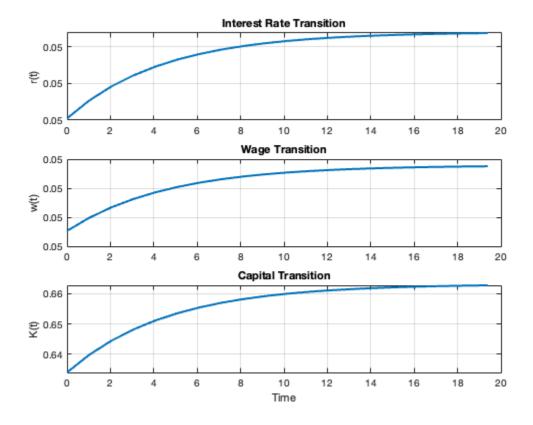












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