

7. Work and Energy Part 1

Practice Question 7

A 20.0 kg rock is sliding on a rough, horizontal surface at 8.00 m/s and eventually stops due to friction. The coefficient of kinetic friction between the rock and the surface is 0.200. What average thermal power is produced as the rock stops?

$\Sigma F = ma: \mu_k mg = ma$

$a = \mu_k g = (0.200)(9.80 \text{ m/s}^2) = 1.96 \text{ m/s}^2$

$v = v_0 + at$

$0 = 8.00 \text{ m/s} - (1.96 \text{ m/s}^2)t$

$t = 4.08 \text{ s}$

$P = \frac{KE}{t} = \frac{\frac{1}{2}mv^2}{t}$

$= \frac{\frac{1}{2}(20.0 \text{ kg})(8.00 \text{ m/s}^2)}{4.08 \text{ s}} = 157 \text{ W}$

a is the acceleration that friction force is providing. Which will be negative.

9. Momentum and Collisions Part 1

Practice Question 3

On a frictionless, horizontal air table, puck A (with mass 0.250 kg) is moving towards puck B (with mass 0.350 kg), that is initially at rest. After the collision, puck A has a velocity of 0.120 m/s to the left, and puck B has velocity 0.650 m/s to the right. a) What was the speed of puck A before the collision? b) Calculate the change in the total kinetic energy of the system that occurs during the collision.

a) The final momentum is

$(0.250 \text{ kg})(-0.120 \text{ m/s}) + (0.350 \text{ kg})(0.650 \text{ m/s}) = 0.1975 \text{ kg} \cdot \text{m/s}$

taking positive direction to the right, a) Before the collision, puck A was at rest, so all of the momentum is due to puck A's motion, and

$v_{A_i} = \frac{P}{m_A} = \frac{0.1975 \text{ kg} \cdot \text{m/s}}{0.250 \text{ kg}} = 0.790 \text{ m/s}$

b)

$AK - K_f = K_i - \frac{1}{2}mv_{A_i}^2 - \frac{1}{2}mv_{B_i}^2 = \frac{1}{2}mv_{A_f}^2 + \frac{1}{2}mv_{B_f}^2$

$-\frac{1}{2}(0.250 \text{ kg})(-0.120 \text{ m/s})^2 + \frac{1}{2}(0.350 \text{ kg})(0.650 \text{ m/s})^2 = \frac{1}{2}(0.250 \text{ kg})(-0.790 \text{ m/s})^2 + \frac{1}{2}(0.350 \text{ kg})(0.650 \text{ m/s})^2$

$-0.0090 \text{ J} + 0.743 \text{ J} = 0.975 \text{ J} + 0.743 \text{ J}$

$-0.0090 \text{ J} + 0.743 \text{ J} = 1.718 \text{ J}$

Practice Question 4

On a greasy, essentially frictionless lunch counter, a 0.500 kg submarine sandwich, moving 3.00 m/s to the left, collides with a 0.250 kg galled cheese sandwich moving 1.20 m/s to the right. a) If the two sandwiches stick together, what is the final velocity? b) How much mechanical energy dissipates in the collision?

a) From $m_1v_1 + m_2v_2 = m_1v_1' + m_2v_2'$ ($v_1 + m_2v_2 = (m_1 + m_2)v_f$), taking positive velocities to the right, $v_1 = -3.00 \text{ m/s}$ and $v_2 = 1.20 \text{ m/s}$, so $v_f = 1.60 \text{ m/s}$.

b) $AK - K_f = K_i - \frac{1}{2}mv_1^2 - \frac{1}{2}mv_2^2 = \frac{1}{2}mv_f^2$

$AK - K_f = \frac{1}{2}(0.500 \text{ kg} + 0.250 \text{ kg})(-1.60 \text{ m/s})^2$

$-\frac{1}{2}(0.500 \text{ kg})(3.00 \text{ m/s})^2 - \frac{1}{2}(0.250 \text{ kg})(1.20 \text{ m/s})^2 = \frac{1}{2}(0.750 \text{ kg})(1.60 \text{ m/s})^2$

$-0.750 \text{ J} - 0.150 \text{ J} = 0.600 \text{ J}$

$-0.900 \text{ J} = 0.600 \text{ J}$

-1.50 J

11. Rotation and Moment of Inertia Part 1

Practice Question 4

The rotating blade of a blender turns with constant angular acceleration 1.50 rad/s^2 . (a) How much time does it take to reach an angular velocity of 36.0 rad/s , starting from rest? (b) Through how many revolutions does the blade turn in this time interval?

IDENTIFY: Apply the constant angular acceleration equations to the motion. The target variables are t and $\theta - \theta_0$.

SET UP: (a) $\alpha = 1.50 \text{ rad/s}^2$; $\omega_0 = 0$ (starts from rest); $\omega = 36.0 \text{ rad/s}$; $t = ?$

$\omega = \omega_0 + \alpha t$

EXECUTE: $t = \frac{\omega - \omega_0}{\alpha} = \frac{36.0 \text{ rad/s} - 0}{1.50 \text{ rad/s}^2} = 24.0 \text{ s}$

(b) $\theta - \theta_0 = ?$

$\theta - \theta_0 = \omega_0 t + \frac{1}{2}\alpha t^2 = 0 + \frac{1}{2}(1.50 \text{ rad/s}^2)(24.0 \text{ s})^2 = 432 \text{ rad}$

$\theta - \theta_0 = 432 \text{ rad}(1 \text{ rev}/2\pi \text{ rad}) = 68.8 \text{ rev}$

EVALUATE: We could use $\theta - \theta_0 = \frac{1}{2}(\omega_0 + \omega)t$ to calculate $\theta - \theta_0 = \frac{1}{2}(0 + 36.0 \text{ rad/s})(24.0 \text{ s}) = 432 \text{ rad}$, which checks.

Practice Question 9

According to the shop manual, when drilling a 12.7-mm-diameter hole in wood, a drill should have a speed of 1250 rev/min. For a 12.7-mm-diameter drill bit turning at a constant 1250 rev/min, find (a) the maximum linear speed of any part of the bit and (b) the maximum radial acceleration of any part of the bit.

IDENTIFY: $v = r\omega$ and $a_{\text{rad}} = r\omega^2 = v^2/r$.

SET UP: $2\pi \text{ rad} = 1 \text{ rev}$, so $\pi \text{ rad/s} = 30 \text{ rev/min}$.

EXECUTE: (a) $\omega = (1250 \text{ rev/min})\left(\frac{\pi \text{ rad/s}}{30 \text{ rev/min}}\right)\left(\frac{12.7 \times 10^{-3} \text{ m}}{2}\right) = 0.831 \text{ m/s}$.

(b) $\frac{v^2}{r} = \frac{(0.831 \text{ m/s})^2}{(12.7 \times 10^{-3} \text{ m})/2} = 109 \text{ m/s}^2$.

EVALUATE: In $v = r\omega$, ω must be in rad/s.

Practice Question 5



A 0.100 kg potato is tied to a string with length 2.50 m, and the other end of the string is tied to a rigid support. The potato is held straight out horizontally from the point of support, with the string pulled taut, and is then released. a) What is the speed of the potato at the lowest point of its motion? b) What is the tension in the string at this point?

a) The kinetic energy of the potato is the work done by gravity (or the potential energy lost), $\frac{1}{2}mv^2 = mgh$, or $v = \sqrt{2gh} = \sqrt{2(9.80 \text{ m/s}^2)(2.50 \text{ m})} = 7.00 \text{ m/s}$.

b)

$T - mg = m\frac{v^2}{r} = 2mg$

$T = 3mg = 3(0.100 \text{ kg})(9.80 \text{ m/s}^2) = 2.94 \text{ N}$

a) The skier's kinetic energy at the bottom can be found from the potential energy at the top minus the work done by friction.

$K_f = mgh - W_f = (60.0 \text{ kg})(9.8 \text{ N/kg})(65.0 \text{ m}) - 10,500 \text{ J}$, or

$K_f = 38,200 \text{ J} - 10,500 \text{ J} = 27,700 \text{ J}$. Then $v_1 = \sqrt{\frac{2K_f}{m}} = \sqrt{\frac{2(27,700 \text{ J})}{60.0 \text{ kg}}} = 30.4 \text{ m/s}$.

b) $K_f = K_i - (W_f + W_{\text{air}}) = 27,700 \text{ J} - (\mu_k mgd + f_{\text{air}}d)$. $K_f = 27,700 \text{ J} - [(2)(688 \text{ N})(82 \text{ m}) + (160 \text{ N})(82 \text{ m})]$, or $K_f = 27,700 \text{ J} - 22,763 \text{ J} = 4,937 \text{ J}$. Then,

$v_1 = \sqrt{\frac{2K_f}{m}} = \sqrt{\frac{2(4,937 \text{ J})}{60 \text{ kg}}} = 12.85 \text{ m/s} \approx 12.9 \text{ m/s}$.

c) Use the Work-Energy Theorem to find the force. $W = AKF$.

$F = KE/d = (4,937 \text{ J})/(2.5 \text{ m}) = 1,975 \text{ N} \approx 1,983 \text{ N}$.

8. Work and Energy Part 2

On a horizontal surface, a crate with mass 50.0 kg is placed against a spring that stores 360 J of energy. The spring is released and the crate slides 5.60 m before coming to rest. What is the speed of the crate when it is 2.00 m from its initial position?

Work done by friction against the crate brings it to a halt:

$f_k x = \text{potential energy of compressed spring}$

$f_k = \frac{200 \text{ J}}{5.60 \text{ m}} = 35.7 \text{ N}$

The friction force working over a 2.00 m distance does work

$W_f = (-35.7 \text{ N})(2.00 \text{ m}) = -71.4 \text{ J}$. The kinetic energy of the crate at this point is thus

$360 \text{ J} - 71.4 \text{ J} = 288.6 \text{ J}$, and its speed is found from

$\frac{1}{2}mv^2 = 288.6 \text{ J}$

$v^2 = \frac{2(288.6 \text{ J})}{50.0 \text{ kg}} = 11.54 \text{ m}^2/\text{s}^2$

$v = 3.39 \text{ m/s}$

10. Momentum and Collisions Part 2

Practice Question 2

SET UP: Use coordinates with the axis at the hinge and the x - and y -axes along the horizontal and vertical bars in the figure in the problem. Let (x_1, y_1) and (x_2, y_2) be the coordinates of the bar before and after the vertical bar is pivoted. Let object 1 be the horizontal bar, object 2 be the vertical bar and 3 be the ball.

EXECUTE: $x_1 = \frac{m_1v_1 + m_2v_2 + m_3v_3}{m_1 + m_2 + m_3} = \frac{(1.00 \text{ kg})(6.250 \text{ m/s}) + 0 + 0}{1.00 \text{ kg} + 3.00 \text{ kg} + 2.00 \text{ kg}} = 0.333 \text{ m}$.

$y_1 = \frac{m_1y_1 + m_2y_2 + m_3y_3}{m_1 + m_2 + m_3} = \frac{0 + (3.00 \text{ kg})(0.900 \text{ m}) + (2.00 \text{ kg})(1.80 \text{ m})}{1.00 \text{ kg} + 3.00 \text{ kg} + 2.00 \text{ kg}} = 0.700 \text{ m}$.

$x_2 = \frac{(4.00 \text{ kg})(0.750 \text{ m}) + (3.00 \text{ kg})(-0.900 \text{ m}) + (2.00 \text{ kg})(-1.80 \text{ m})}{1.00 \text{ kg} + 3.00 \text{ kg} + 2.00 \text{ kg}} = -0.366 \text{ m}$.

$y_2 = 0$. $x_2 - x_1 = -0.700 \text{ m}$ and $y_2 - y_1 = -0.700 \text{ m}$. The center of mass moves 0.700 m to the right and 0.700 m upward.

EVALUATE: The vertical bar moves upward and to the right so it is sensible for the center of mass of the machine part to move in these directions.

Practice Question 4



A 5.00 g bullet is shot through a 1.00 kg wood block suspended on a string 2.00 m long. The center of mass of the block rises a distance of 0.45 cm. Find the speed of the bullet as it emerges from the block if its initial speed is 450 m/s.

IDENTIFY: Apply conservation of momentum to the collision and conservation of energy to the motion of the block after the collision.

SET UP: Let v be to the right. Let the bullet be x and the block be B . Let V be the velocity of the block just after the collision.

EXECUTE: Motion of block after the collision: $K_f = U_{\text{spring}} = \frac{1}{2}mv^2 = mgh$.

$V = \sqrt{2gh} = \sqrt{2(9.80 \text{ m/s}^2)(0.45 \times 10^{-2} \text{ m})} = 0.297 \text{ m/s}$.

Collision: $v_{1i} = 0.297 \text{ m/s}$. $P_{1i} = P_{2i}$ gives $m_1v_{1i} = m_2v_{2i} + m_3v_{3i}$.

$v_{1i} = \frac{m_2v_{2i} + m_3v_{3i}}{m_1} = \frac{(5.00 \times 10^{-3} \text{ kg})(450 \text{ m/s}) + (1.00 \text{ kg})(0.297 \text{ m/s})}{5.00 \times 10^{-3} \text{ kg}} = 391 \text{ m/s}$.

EVALUATE: We assume the block moves very little during the time it takes the bullet to pass through it.

12. Rotation and Moment of Inertia Part 2

Practice Question 4

A thin, rectangular sheet of metal has mass M and sides of length a and b . Use the parallel-axis theorem to calculate the moment of inertia of the sheet for an axis that is perpendicular to the plane of the sheet and that passes through one corner of the sheet.

EXECUTE: $I_P = I_{\text{cm}} + Md^2$.

$I_{\text{cm}} = \frac{1}{12}M(a^2 + b^2)$. The distance d of P from the cm is $d = \sqrt{(a/2)^2 + (b/2)^2}$.

Thus $I_P = I_{\text{cm}} + Md^2 = \frac{1}{12}M(a^2 + b^2) + M\left(\frac{1}{4}a^2 + \frac{1}{4}b^2\right) = \left(\frac{1}{3} + \frac{1}{4}\right)M(a^2 + b^2) = \frac{7}{12}M(a^2 + b^2)$.

A passenger bus in Zurich, Switzerland, derived its motive power from the energy stored in a large flywheel. The wheel was brought up to speed periodically, when the bus stopped at a station, by an electric motor, which could then be attached to the electric power lines. The flywheel was a solid cylinder with mass 1000 kg and diameter 1.80 m. Its top angular speed was 3000 rev/min. (a) At this angular speed, what is the kinetic energy of the fly wheel? (b) If the average power required to operate the bus is $1.86 \times 10^4 \text{ W}$, how long could it operate between stops?

IDENTIFY: $K = \frac{1}{2}I\omega^2$, with ω in rad/s. $P = \frac{\text{energy}}{\text{time}}$.

SET UP: For a solid cylinder, $I = \frac{1}{2}MR^2$. $1 \text{ rev/min} = (2\pi/60) \text{ rad/s}$.

EXECUTE: (a) $\omega = 3000 \text{ rev/min} = 314 \text{ rad/s}$. $I = \frac{1}{2}(1000 \text{ kg})(0.900 \text{ m})^2 = 405 \text{ kg} \cdot \text{m}^2$.

$K = \frac{1}{2}(405 \text{ kg} \cdot \text{m}^2)(314 \text{ rad/s})^2 = 2.00 \times 10^7 \text{ J}$.

(b) $t = \frac{K}{P} = \frac{2.00 \times 10^7 \text{ J}}{1.86 \times 10^4 \text{ W}} = 1.08 \times 10^3 \text{ s} = 17.9 \text{ min}$.

EVALUATE: In $K = \frac{1}{2}I\omega^2$, we must use ω in rad/s.

About what axis will a uniform sphere have the same moment of inertia as does a thin-walled, hollow, lead sphere of the same mass and radius, with the axis along a diameter?

SET UP: For a thin-walled hollow sphere, axis along a diameter, $I = \frac{2}{3}MR^2$. For a solid sphere with mass M and radius R , $I_{\text{cm}} = \frac{2}{5}MR^2$, for an axis along a diameter.

EXECUTE: Find d such that $I_P = I_{\text{cm}} + Md^2$ with $I_P = \frac{2}{3}MR^2$.

$\frac{2}{3}MR^2 = \frac{2}{5}MR^2 + Md^2$

The factors of M divide out and the equation becomes $(\frac{2}{3} - \frac{2}{5})R^2 = d^2$

$d = \sqrt{(10-6)/15}R = 2R/\sqrt{15} = 0.516R$.

The axis is parallel to a diameter and is 0.516R from the center.

Work Done

W = F . S(Constant)

W = KE = ½mv²²(Kinetic)

W = GPE = mg

h (Gravitational)

W = SE = ½kx²²(Spring)

W = KE = ½mv²² - ½v²²

W = KE_f + GPE_f = KE_i + GPE_i

(Same idea for GPE & SE when displacement occur)

Momentum from start and end is the same(conserved)

Power

P = mv(Momentum)

P_{av} = W/t

SI unit : Watt(W)

1 horsepower = 746W

1 kWh = 10³ x 3600 Ws = 3.6 MJ

Reminder

F = μmg = ma = mg

J = F x T

Properties of conservative force

Force is independent of path.

Force at end = Force at start

Scalar Product of 2 Vectors

A = A_xi + A_yj + A_zk
B = B_xi + B_yj + B_zk

A · B = (A_xi + A_yj + A_zk) · (B_xi + B_yj + B_zk)

A · B = A_xB_x + A_yB_y + A_zB_z

F_x = kx (Hooke's Law)

Cannot arbitrarily assign zero value.

Momentum and Collision

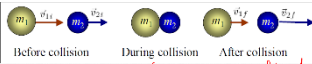
P = mv (Momentum)

P = KE = p = √2mK

p_{tot} = p₁ + p₂ = const.

Remember where all forces and momentum are present.

Elastic Collision

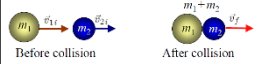


Momentum conservation: m1v1i + m2v2i = m1v1f + m2v2f
Energy conservation: ½m1v1i² + ½m2v2i² = ½m1v1f² + ½m2v2f²

Final Velocity

v1f = (m1 - m2) / (m1 + m2) v1i + (2m2) / (m1 + m2) v2i
v2f = (2m1) / (m1 + m2) v1i + (m2 - m1) / (m1 + m2) v2i

Inelastic Collision



Momentum conservation: m1v1i + m2v2i = (m1 + m2)v_f
v_f = (m1v1i + m2v2i) / (m1 + m2)

Inelastic Collision

e = Relative speed of separation / Relative speed of approach
= (v2f - v1f) / (v1i - v2i)

e	Type
0	Perfectly inelastic
<1	Inelastic
1	Elastic
>1	e²

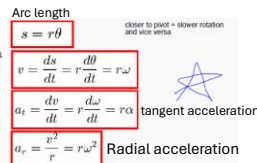
Momentum found at collision.

Angular Motion (Rotational motion of body)

Angular displacement (θ) is the angle through which a point revolves around a centre.

Angular velocity (ω) is the rate of change of angular displacement.

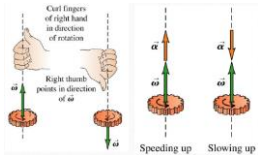
Angular acceleration (α) is the rate of change of angular velocity.



Time present = use a.
Else use a_r (if ask for centipetal, use a_r)

Kinematics (Angular vs Linear)

θ ↔ x, ω ↔ v, α ↔ a
v = v₀ + at, ω = ω₀ + αt
x = x₀ + v₀t + ½at², θ = θ₀ + ω₀t + ½αt²
v² = v₀² + 2a(x - x₀), ω² = ω₀² + 2α(θ - θ₀)



The direction of ω is determined by right-hand rule.

θ => can be use to find m and angle/rad

Radians = (π / 180°) × degrees

Degrees = (180° / π) × radians

Centre of Mass (Shaped object)

m1x1 + m2x2 + m3x3 / m1 + m2 + m3

X_{cm} =

Centre of Mass (System of particles)

r_CM = Σ m_i r_i / M

Centre of Mass (Extended Object)

r_CM = 1/M ∫ r dm

Characteristics of CM

For a homogenous (constant density) body that has a geometric centre, the CM is the geometric centre (eg, solid sphere, cube, and cylinder.)
The centre of mass of any symmetric object lies on an axis of symmetry and on any plane of symmetry.
If g is constant over the mass distribution, the centre of gravity coincides with the centre of mass. If an object is hung freely from any point, the vertical line through this point must pass through the centre of mass.
CM needs not be within the body itself.

Centre of mass (Right angle triangle)

x_CM = 2/3 a, y_CM = 1/3 b

Centre of mass (Cone)

z_CM = 3/4 h, x_CM = 0, y_CM = 0

Motion of system of particles

r_CM = Σ m_i r_i / M
v_CM = dv_CM/dt = 1/M Σ m_i dv_i/dt = Σ m_i a_i / M
Mv_CM = Σ m_i v_i = Σ p_i = P_tot
The total linear momentum of the system is equal to that of a single particle of mass M moving with a velocity v_CM.
a_CM = dv_CM/dt = 1/M Σ m_i dv_i/dt = Σ m_i a_i / M
M a_CM = Σ m_i a_i = Σ F_i
Σ F_ext = M a_CM = dP_CM/dt
F_i includes int. & ext. forces
Internal forces cancel out.

The CM moves like an imaginary particle of mass M under the influence of the external resultant force on the system.

Moment of Inertia for different objects

Long thin rod (about centre) I _{CM} = 1/12 ML²	Long thin rod (about end) I = 1/3 ML²
Solid sphere I _{CM} = 2/5 MR²	Thin spherical shell I _{CM} = 2/3 MR²

Hoop or thin cylindrical shell I _{CM} = MR²	Hollow cylinder I _{CM} = 1/2 M (R₁² + R₂²)
Solid cylinder or disk I _{CM} = 1/2 MR²	Rectangular plate I _{CM} = 1/12 M (a² + b²)

Moment of Inertia

Kinetic energy can be written as: K_R = Σ K_i = 1/2 Σ m_i r_i² ω² = 1/2 I ω²
I = 1/2 MR²

Moment of inertia, I, is defined as: I = 1/2 MR²

For an extended rigid object (divide into small elements):

I = lim Σ Δm_i r_i² = ∫ r² dm = ∫ r² dV, n = ρ · V

A measure of the resistance of an object to changes in its rotational motion, just as mass is a measure of the tendency of an object to resist changes in its linear motion.

Mass is an intrinsic property of an object, but I depends on the physical arrangement of that mass.

Also depends on the axis of rotation.

Dimension: ML²; units kg·m²

Parallel axis theorem

The moment of inertia about any axis parallel to and at distance D away from the axis that passes through the centre of mass is:

I = I_{CM} + MD²

Theorem works for any solids and shapes.

Circular Acceleration
Centripetal acceleration: v²/R = 4π²R/T²
Radial acceleration: v²/R
Tangential acceleration: dv/dt
T = 2πR/v
v = 2πR/T
Projectile motion