

## CSD1241 Tutorial 6 Solutions

**Remarks.** The solution should only be used as guidance for your study. There is no guarantee on errors and typos. Would appreciate if you let me know the errors.

**Problem 1.** The **matrix representation** of a linear transformation  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is an  $m \times n$  matrix  $M$  such that  $T(\vec{x}) = M\vec{x}$  for any  $\vec{x} \in \mathbb{R}^n$ .

Find the matrix representation of  $T$  in the following cases. In each case, find the points  $\vec{x}$  that are fixed by  $T$ , that is,  $T(\vec{x}) = \vec{x}$ .

(a)  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  with

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2x + y \\ y \end{pmatrix}$$

(b)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  with

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2x + y - z \\ y + z \\ x - y - z \end{pmatrix}$$

(c) Based on the results from a,b, we see that the map  $T$  always fixes the origin  $O = \vec{0}$ . Show that this property is true for any linear map, that is,  $T(\vec{0}) = \vec{0}$  whenever  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is a linear transformation.

(d) Let  $l$  be a line in  $\mathbb{R}^2$  which doesn't go through the origin. Using the result in c, could you explain that the map  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  which is the reflection through  $l$  is not a linear transformation?

**Solution.** The map  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  defined by  $T \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n \end{pmatrix}$

has matrix representation

$$M = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}.$$

We simply collect the coefficients which appear in the definition of  $T$  to form  $M$ .

(a) The matrix of  $T$  is

$$M = \begin{pmatrix} 2 & 1 \\ 0 & 1 \end{pmatrix}$$

Let  $\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix}$  be a fixed point of  $T$ . We have

$$T(\vec{x}) = \vec{x} \Leftrightarrow \begin{pmatrix} 2x + y \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} \Leftrightarrow y = -x$$

Therefore, all fixed points of  $T$  are  $\begin{pmatrix} x \\ -x \end{pmatrix}$ . These are all points on the line  $y = -x$ .

(b) The matrix of  $T$  is

$$M = \begin{pmatrix} 2 & 1 & -1 \\ 0 & 1 & 1 \\ 1 & -1 & -1 \end{pmatrix}$$

Let  $\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix}$  be a fixed point of  $T$ . We have

$$T(\vec{x}) = \vec{x} \Leftrightarrow \begin{pmatrix} 2x + y - z \\ y + z \\ x - y - z \end{pmatrix} = \begin{cases} 2x + y - z = x \\ y + z = y \\ x - y - z = z \end{cases}$$

The second equation implies  $z = 0$ . Substituting  $z = 0$  into the remaining equations, we obtain  $x + y = 0$  and  $x - y = 0$ , which implies  $x = y = 0$ . Therefore, the only fixed point of  $T$  is the origin, that is,  $O = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ .

(c) Since  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is linear, it preserves addition. We have

$$T(\vec{0} + \vec{0}) = T(\vec{0}) + T(\vec{0}) \Rightarrow 2T(\vec{0}) = T(\vec{0}) \Rightarrow T(\vec{0}) = \vec{0}.$$

(d) Since  $l$  doesn't go through the origin, the image of the origin  $O = \vec{0}$  is a point different from  $O$ , that is,  $T(\vec{0}) \neq \vec{0}$ . Therefore,  $T$  is not a linear transformation.  $\square$

**Problem 2.** Another way to find the matrix representation  $M$  of  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is to use the standard unit vectors  $\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n$  of  $\mathbb{R}^n$

$$M = [T(\vec{e}_1) \quad T(\vec{e}_2) \quad \cdots \quad T(\vec{e}_n)]$$

In the following cases, find the matrix representation of the linear transformation  $T$  by the method described above. In each case, find the points  $\vec{x}$  that are mapped to  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ ,

that is,  $T(\vec{x}) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .

(a)  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  with

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \quad T \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -5 \end{pmatrix}$$

(b)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  with

$$T \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad T \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}, \quad T \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -5 \\ 3 \end{pmatrix}$$

**Solution.** (a) Note that  $\vec{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\vec{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . Further  $\vec{e}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ . So

$$T(\vec{e}_2) = T \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} - T \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -5 \end{pmatrix} - \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ -4 \end{pmatrix}$$

We obtain

$$M = [T(\vec{e}_1) \ T(\vec{e}_2)] = \begin{pmatrix} 1 & 1 \\ -1 & -4 \end{pmatrix}.$$

Assume  $\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix}$  is mapped to  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ . We have

$$T(\vec{x}) = M\vec{x} = \begin{pmatrix} 1 & 1 \\ -1 & -4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x + y \\ -x - 4y \end{pmatrix},$$

which implies

$$\begin{cases} x + y = 1 \\ -x - 4y = 1 \end{cases} \Rightarrow x = \frac{5}{3}, \ y = -\frac{2}{3}.$$

We obtain  $\vec{x} = \begin{pmatrix} 5/3 \\ -2/3 \end{pmatrix}$ .

(b) Note that  $\vec{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ ,  $\vec{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$  and  $\vec{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ . Further  $\vec{e}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$  and

$$\vec{e}_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}. \text{ So}$$

$$\begin{aligned} T(\vec{e}_2) &= T \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} - T \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \end{pmatrix} \\ T(\vec{e}_3) &= T \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} - T \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -5 \\ 3 \end{pmatrix} - \begin{pmatrix} -2 \\ 1 \end{pmatrix} = \begin{pmatrix} -3 \\ 2 \end{pmatrix} \end{aligned}$$

We obtain

$$M = [T(\vec{e}_1) \ T(\vec{e}_2) \ T(\vec{e}_3)] = \begin{pmatrix} 1 & -2 & -3 \\ 1 & 1 & 2 \end{pmatrix}.$$

Assume  $\vec{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$  is mapped to  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ . We have

$$T(\vec{x}) = M\vec{x} = \begin{pmatrix} 1 & -2 & -3 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x - 2y - 3z \\ x + y + 2z \end{pmatrix},$$

which implies

$$\begin{cases} x - 2y - 3z = 1 \\ x + y + 2z = 1 \end{cases} \Rightarrow \begin{cases} x - 2y - 3z = 1 \\ 3y + 5z = 0 \end{cases}$$

From the 2nd equation, we have  $y = -\frac{5}{3}z$ . Substituting this into the first equation, we obtain  $x = 1 + 2y + 3z = 1 - \frac{1}{3}z$ . The points  $\vec{x}$  which are mapped to  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$  have coordinates

$$\vec{x} = \begin{pmatrix} 1 - 1/3z \\ -5/3z \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \frac{z}{3} \begin{pmatrix} -1 \\ -5 \\ 3 \end{pmatrix},$$

which is a line in  $\mathbb{R}^3$  going through the point  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$  and having direction  $\begin{pmatrix} -1 \\ -5 \\ 3 \end{pmatrix}$ .  $\square$

**Problem 3.** Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the orthogonal projection onto the line  $l : x - 2y = 0$ .

(a) Find the matrix  $M$  of  $T$ .

(b) Find the image of the points  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 5 \\ 5 \end{pmatrix}$ .

(c) Find the image of the line  $m : x + y = 3$  under this map (find normal equation).

*Hint.* Use the vector equation of  $m$  to express its coordinates.

(d) Find the image of the line  $n : 2x + y = 15$  under this map (find normal equation).

**Solution.** (a) The line  $l$  has direction  $\vec{d} = \begin{bmatrix} -b \\ a \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ . So the matrix of  $T$  is

$$M = \frac{1}{\|\vec{d}\|^2} \vec{d} \vec{d}^T = \frac{1}{5} \begin{bmatrix} 2 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix}$$

(b) The images of  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 5 \\ 5 \end{pmatrix}$  are

$$\frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \text{ and } \frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{pmatrix} 5 \\ 5 \end{pmatrix} = \begin{pmatrix} 6 \\ 3 \end{pmatrix}$$

(c) The line  $m$  goes through the point  $\vec{x}_0 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and has direction  $\vec{d} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ . So it has vector equation

$$\vec{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Any point  $\vec{x}$  on  $m$  is mapped to

$$\begin{aligned} M\vec{x} &= M \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) = \frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \\ &= \begin{pmatrix} 2 \\ 1 \end{pmatrix} + \frac{t}{5} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \end{aligned}$$

where  $s = t/5$ . This is a point on the line  $m' : \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ . Note that  $m'$  has normal equation  $x - 2y = 0$ , which is exactly the line  $l$ . This makes sense because we are projecting onto  $l$ .

(d) The line  $n$  goes through the point  $\vec{x}_0 = \begin{pmatrix} 5 \\ 5 \end{pmatrix}$  and has direction  $\vec{d} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ . So it

has vector equation

$$\vec{x} = \begin{pmatrix} 5 \\ 5 \end{pmatrix} + t \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

Any point  $\vec{x}$  on  $m$  is mapped to

$$M\vec{x} = M \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) = \frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{pmatrix} 5 \\ 5 \end{pmatrix} + t \frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 6 \\ 3 \end{pmatrix}$$

Therefore, the whole line  $n$  is mapped to the point  $\begin{pmatrix} 6 \\ 3 \end{pmatrix}$ . This happens because  $n$  is perpendicular to  $l$  and the point  $\begin{pmatrix} 6 \\ 3 \end{pmatrix}$  is the intersection of  $n$  and  $m$ .  $\square$

**Problem 4.** Redo Problem 3 with  $T$  be the skew projection onto  $l : x - 2y = 0$  along the direction  $\vec{v} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ .

**Solution.** (a) Note that  $l$  has normal  $\vec{n} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$ . The matrix of  $T$  is

$$M = I_2 - \frac{1}{\vec{v} \cdot \vec{n}} \vec{v} \vec{n}^T = \frac{1}{4} \begin{pmatrix} 6 & -4 \\ 3 & -2 \end{pmatrix}$$

(b) The images of  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 5 \\ 5 \end{pmatrix}$  are

$$\frac{1}{4} \begin{pmatrix} 6 & -4 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \text{ and } \frac{1}{4} \begin{pmatrix} 6 & -4 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} 5 \\ 5 \end{pmatrix} = \begin{pmatrix} 2.5 \\ 1.25 \end{pmatrix}$$

(c) Any point  $\vec{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  on the line  $m$  mapped to

$$\frac{1}{4} \begin{pmatrix} 6 & -4 \\ 3 & -2 \end{pmatrix} \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} 2 \\ 1 \end{pmatrix},$$

where  $s = \frac{5t}{4}$ . Similar to Problem 3c, this is exactly the line  $l : x - 2y = 0$ .

(d) Similar to c. The answer is the line  $l$ .  $\square$

**Problem 5.** Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the orthogonal reflection through the line  $l : x - 2y = 0$ .

(a) Find the matrix  $M$  of  $T$ .

(b) Find the image of the points  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ 3 \end{pmatrix}$ .

(c) Find the image of the line  $m : x + y = 3$  under this map (find normal equation).

(d) Find the image of the line  $n : 2x + y = 5$  under this map (find normal equation).

**Solution.** (a) The line  $l$  has direction vector  $\vec{d} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ . The matrix of  $T$  is

$$M = \frac{2}{\|\vec{d}\|^2} \vec{d} \vec{d}^T - I_2 = \frac{1}{5} \begin{pmatrix} 3 & 4 \\ 4 & -3 \end{pmatrix}$$

(b) The images of  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ 3 \end{pmatrix}$  are

$$\frac{1}{5} \begin{pmatrix} 3 & 4 \\ 4 & -3 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \text{ and } \frac{1}{5} \begin{pmatrix} 3 & 4 \\ 4 & -3 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

(c) The line  $m$  has vector equation  $\vec{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ . So any point  $\vec{x}$  on  $m$  is mapped to

$$\frac{1}{5} \begin{pmatrix} 3 & 4 \\ 4 & -3 \end{pmatrix} \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} -1 \\ 7 \end{pmatrix},$$

where  $s = \frac{t}{5}$ . This is a point on the line  $m' : \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} -1 \\ 7 \end{pmatrix}$ , which is a line through the point  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and having normal  $\vec{n}' = \begin{pmatrix} 7 \\ 1 \end{pmatrix}$ . The normal equation of  $m'$  is

$$7(x - 2) + 1(y - 1) = 0 \Leftrightarrow 7x + y = 15.$$

(d) The line  $n$  has vector equation  $\vec{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ . So any point  $\vec{x}$  on  $n$  is mapped to

$$\frac{1}{5} \begin{pmatrix} 3 & 4 \\ 4 & -3 \end{pmatrix} \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} -1 \\ 2 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} 1 \\ -2 \end{pmatrix},$$

where  $s = \frac{t}{5}$ . This is a point on the line  $n' : \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} 1 \\ -2 \end{pmatrix}$ , which is a line containing the point  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and having normal vector  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ . Its normal equation is

$$2(x - 2) + 1(y - 1) = 0 \Leftrightarrow 2x + y = 5,$$

which is the line  $l$  itself. This makes sense because  $n$  is perpendicular to  $l$ , which implies that its orthogonal projection is itself.  $\square$

**Problem 6.** Redo Problem 5 with  $T$  be the skew reflection through  $l : x - 2y = 0$  along the direction  $\vec{v} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ .

**Solution.** (a) Note that  $l$  has normal  $\vec{n} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$ . The matrix of  $T$  is

$$M = I_2 - \frac{2}{\vec{v} \cdot \vec{n}} \vec{v} \vec{n}^T = \frac{1}{2} \begin{pmatrix} 4 & -4 \\ 3 & -4 \end{pmatrix}$$

(b) The images of  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 3 \\ 1 \end{pmatrix}$  are

$$\frac{1}{2} \begin{pmatrix} 4 & -4 \\ 3 & -4 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \text{ and } \frac{1}{2} \begin{pmatrix} 4 & -4 \\ 3 & -4 \end{pmatrix} \begin{pmatrix} 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 2.5 \end{pmatrix}$$

(c) Any point  $\vec{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  on the line  $m$  mapped to

$$\frac{1}{2} \begin{pmatrix} 4 & -4 \\ 3 & -4 \end{pmatrix} \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$

where  $s = \frac{7t}{2}$ . Note that the direction vector of the above line is the vertical vector  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  (also the unit vector on  $y$ -axis). So the image of  $m$  is the vertical line  $m' : x = 2$ .

(d) Any point  $\vec{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} -1 \\ 2 \end{pmatrix}$  on the line  $m$  mapped to

$$\frac{1}{2} \begin{pmatrix} 4 & -4 \\ 3 & -4 \end{pmatrix} \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} -1 \\ 2 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + s \begin{pmatrix} 12 \\ 11 \end{pmatrix}.$$

This line has normal equation  $11x - 12y = 10$ .  $\square$