Method of Partial Fractions Part 2 Numerical Integration Part 1

Dr. Ronald Koh ronald.koh@digipen.edu (Teams preferred over email)

AY 23/24 Trimester 1

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Tangent/secant integrals, Partial fractions (1) and (2)

- We learnt how to integrate $tan^m x sec^n x$:
 - n is even: take out a copy of $\sec^2 x$, convert rest of $\sec^2 x$ to $\tan^2 x + 1$. sub $u = \tan x$.
 - m is odd and n > 1: take out one copy of $\sec x \tan x$, convert rest of $\tan^2 x$ to $\sec^2 x - 1$, sub $u = \sec x$.
 - m is even and n is odd: convert all $tan^2 x$ to $sec^2 x 1$, reduce the power of sec by 2 every integration by parts iteration.
- Partial fraction decomposition: only works on **proper** fractions; use long division to convert to proper otherwise.
- Factorization of denominator Q(x):

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Non-repeated linear factors: one partial fraction for each factor.

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• Repeated (power m) linear factors: for each factor that is repeated, one partial fraction for each power k = 1, ..., m.

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Exercise 3 from last week's lecture

Evaluate the following integrals.

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Exercise 3 from last week's lecture

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Exercise 4 from last week's lecture

Evaluate the following integrals.

$$\int \frac{1}{x^3 + x^2} dx$$

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Exercise 4 from last week's lecture

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Exercise 4 from last week's lecture

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Method for Non-repeating Irreducible Quadratic Factors

Definition

A quadratic polynomial $ax^2 + bx + c$ is said to be **irreducible** (in the reals) if $b^2 - 4ac < 0$.

If Q(x) factors into a non-repeated, irreducible factor $ax^2 + bx + c$, then the partial fraction decomposition of $\frac{R(x)}{Q(x)}$ must contain

$$\frac{Ax+B}{ax^2+bx+c},$$

where A and B are constants to be determined.

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Evaluate
$$\int \frac{x+1}{x^4+x^2} dx$$
.

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Use the substitution x = au to show that

$$\int \frac{1}{a^2 + x^2} dx = \frac{1}{a} \tan^{-1} \left(\frac{x}{a}\right) + C.$$

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Evaluate the following integral.

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Not every function has simple antiderivatives

It turns out that not every function has simple antiderivatives. For example,

$$\int_0^1 e^{x^2} dx \quad \text{and} \quad \int_0^1 \cos(x^2) dx$$

cannot be evaluated exactly because there is no *simple* antiderivative for e^{x^2} and $\cos(x^2)$.

We instead turn to approximations to help us get (close to) the answer.

The Midpoint Rule

The **Midpoint Rule** is a Riemann sum, with sample points as the **midpoints** of the subintervals. Let f be a function on the interval [a, b]. We use n rectangles, so

$$\Delta x = \frac{b-a}{n}$$
, and $x_i = a + i\Delta x$ (i from 0 to n).

The *n* subintervals are $[x_0, x_1], [x_1, x_2], \dots, [x_{n-1}, x_n]$. The sample points are the midpoints of these intervals:

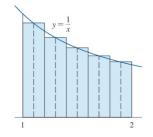
$$\overline{x_i} = \frac{x_i + x_{i-1}}{2} = a + \left(\frac{2i-1}{2}\right) \Delta x$$
, (*i* from 1 to *n*).

The **Midpoint Rule** M_n is

$$\int_a^b f(x) dx \approx M_n = \Delta x \left[f(\overline{x_1}) + f(\overline{x_2}) + \dots + f(\overline{x_n}) \right].$$

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Use the Midpoint Rule with n=5 to approximate the integral $\int_1^2 \frac{1}{x} dx$. Give your final answer in 6 decimal places.



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The Trapezoidal Rule

The **Trapezoidal Rule** is the average of the left Riemann sum L_n (left endpoints as sample points) and the right Riemann sum R_n (right endpoints as sample points). Recall that the left and right endpoints on [a,b] with $x_i=a+i\Delta x$ are

Left endpoints : $x_0, x_1, \ldots, x_{n-1}$,

Right endpoints : x_1, x_2, \ldots, x_n .

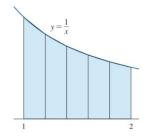
The Trapezoidal Rule T_n is the average of L_n and R_n :

$$T_n = \frac{L_n + R_n}{2} = \frac{\Delta x}{2} [f(x_0) + f(x_1) + \ldots + f(x_{n-1}) + f(x_1) + \ldots + f(x_{n-1}) + f(x_n)]$$

$$\implies \int_{a}^{b} f(x) dx \approx T_{n} = \frac{\Delta x}{2} [f(x_{0}) + 2f(x_{1}) + \ldots + 2f(x_{n-1}) + f(x_{n})].$$

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Use the Trapezoidal Rule with n=5 to approximate the integral $\int_1^2 \frac{1}{x} dx$. Give your final answer in 6 decimal places.



Approximations and errors

As with most approximations, we would expect some error. The error of the Midpoint Rule is

$$E_M = \int_a^b f(x) \, dx - M_n,$$

and the error of the Trapezoidal Rule is

$$E_T = \int_a^b f(x) \, dx - T_n.$$

Most of the time, we are unable to evaluate the error exactly, because we don't know the exact value of the definite integral. But we know that it cannot exceed a certain value, i.e. it is **bounded** by a certain value.

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Error bounds

Theorem

Suppose K is a constant where $|f''(x)| \leq K$ on [a, b]. The **magnitude** of errors of the Trapezoidal (E_T) and Midpoint Rule (E_M) have the following upper bounds:

$$|E_T| \leq rac{K(b-a)^3}{12n^2}$$
 and $|E_M| \leq rac{K(b-a)^3}{24n^2}$.

In other words, even if we do not know the exact error of the approximation, we know that the magnitude of the error can **never** exceed a certain number. A helpful inequality that you can use to find the bound K for |f''(x)| is the **triangle inequality**:

Theorem (Triangle Inequality)

For any $a,b\in\mathbb{R}$,

$$|a+b| \le |a| + |b|.$$

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- Find error bounds for the Midpoint and Trapezoidal Rule approximations in Examples 2 and 3.
- ② How large should we take n in order to guarantee that the Midpoint and Trapezoidal Rule approximations for $\int_{1}^{2} \frac{1}{x} dx$ are accurate to within 0.0001?

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- Use both the Midpoint and Trapezoidal Rule with n = 10 to approximate the integral $\int_0^1 \cos(x^2) dx$.
- 4 How large should we take n in order to guarantee that these approximations for this integral are accurate to within 0.0001?

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