

## CSD1241 Tutorial 8 Solutions

**Problem 1.** Let  $T$  be the orthogonal projection onto the plane  $\alpha : x - 3y + 2z = 0$ .

(a) Find the matrix representation of  $T$ .

(b) Find the images of the points

$$\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 8 \end{pmatrix}, \begin{pmatrix} 3 \\ -3 \\ 1 \end{pmatrix}$$

(c) Find all the points  $\vec{x}$  that are fixed under this transformation, that is,  $T(\vec{x}) = \vec{x}$ .

(d) Find the image of the plane  $\beta$  under  $T$  with

$$\beta : \vec{x} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + s \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -8 \\ 0 \\ 1 \end{pmatrix}$$

(e) Find the image of  $\gamma : x + y + z = 1$  under  $T$ .

(f) Find the image of the line  $l : \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 6 \\ -20 \\ 9 \end{pmatrix} + t \begin{pmatrix} 3 \\ -3 \\ 1 \end{pmatrix}$  under  $T$ .

**Solution.** (a) The plane  $\alpha$  has normal  $\vec{n} = \begin{bmatrix} 1 \\ -3 \\ 2 \end{bmatrix}$ . The matrix of  $T$  is

$$\begin{aligned} M &= I_3 - \frac{1}{\|\vec{n}\|^2} \vec{n} \vec{n}^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} - \frac{1}{14} \begin{pmatrix} 1 \\ -3 \\ 2 \end{pmatrix} [1 \ -3 \ 2] \\ &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} - \frac{1}{14} \begin{pmatrix} 1 & -3 & 2 \\ -3 & 9 & -6 \\ 2 & -6 & 4 \end{pmatrix} = \frac{1}{14} \begin{pmatrix} 13 & 3 & -2 \\ 3 & 5 & 6 \\ -2 & 6 & 10 \end{pmatrix} \end{aligned}$$

(b) The images of the given 4 points are the 4 columns of the following matrix

$$\frac{1}{14} \begin{pmatrix} 13 & 3 & -2 \\ 3 & 5 & 6 \\ -2 & 6 & 10 \end{pmatrix} \begin{pmatrix} 1 & 3 & 1 & 3 \\ 1 & 1 & 1 & -3 \\ 1 & 1 & 8 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 20/7 & 0 & 2 \\ 1 & 10/7 & 4 & 0 \\ 1 & 5/7 & 6 & -1 \end{pmatrix}$$

(c) Since  $T$  is an orthogonal projection onto  $\alpha$ , all points that are fixed under  $T$  are all points on  $\alpha : x - 3y + 2z = 0$ .

(d) The image of  $\beta$  is

$$\begin{aligned}\beta' : \vec{x} &= \frac{1}{14} \begin{pmatrix} 13 & 3 & -2 \\ 3 & 5 & 6 \\ -2 & 6 & 10 \end{pmatrix} \left( \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + s \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -8 \\ 0 \\ 1 \end{pmatrix} \right) \\ &= \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \frac{s}{7} \begin{pmatrix} 5 \\ -1 \\ -4 \end{pmatrix} + \frac{t}{7} \begin{pmatrix} -53 \\ -9 \\ 13 \end{pmatrix}\end{aligned}$$

(e) The plane  $\gamma$  has normal vector  $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ . So it has 2 direction vectors  $\vec{u} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$ . A vector equation of  $\gamma$  is

$$\vec{x} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

The image of  $\gamma$  is

$$\begin{aligned}\gamma' : \vec{x} &= \frac{1}{14} \begin{pmatrix} 13 & 3 & -2 \\ 3 & 5 & 6 \\ -2 & 6 & 10 \end{pmatrix} \left( \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right) \\ &= \begin{pmatrix} 13/14 \\ 3/14 \\ -2/14 \end{pmatrix} + \frac{s}{7} \begin{pmatrix} 5 \\ -1 \\ -4 \end{pmatrix} + \frac{t}{14} \begin{pmatrix} 5 \\ -1 \\ -4 \end{pmatrix} \\ &= \begin{pmatrix} 13/14 \\ 3/14 \\ -2/14 \end{pmatrix} + \left( \frac{s}{7} + \frac{t}{14} \right) \begin{pmatrix} 5 \\ -1 \\ -4 \end{pmatrix} = \begin{pmatrix} 13/14 \\ 3/14 \\ -2/14 \end{pmatrix} + r \begin{pmatrix} 5 \\ -1 \\ -4 \end{pmatrix},\end{aligned}$$

where  $r = \frac{s}{7} + \frac{t}{14}$ . Note that  $\gamma'$  is a line which is the intersection of  $\alpha$  and  $\gamma$ . This happens because  $\alpha$  and  $\gamma$  are perpendicular.

(f) The image of  $l$  is

$$\begin{aligned} l' : \vec{x} &= \frac{1}{14} \begin{pmatrix} 13 & 3 & -2 \\ 3 & 5 & 6 \\ -2 & 6 & 10 \end{pmatrix} \left( \begin{pmatrix} 6 \\ -20 \\ 9 \end{pmatrix} + t \begin{pmatrix} 3 \\ -3 \\ 1 \end{pmatrix} \right) \\ &= \begin{pmatrix} 0 \\ -2 \\ -3 \end{pmatrix} + t \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix} \end{aligned}$$

**Problem 2.** Let  $T$  be the skew projection onto the plane  $\alpha : x - 3y + 2z = 0$  along the vector  $\vec{v} = \begin{pmatrix} 1 \\ 1 \\ 8 \end{pmatrix}$ . Redo (a,c,e,f) of Problem 1.

**Solution.** (a) Note that  $\vec{v} = \begin{pmatrix} 1 \\ 1 \\ 8 \end{pmatrix}$  and  $\vec{n} = \begin{pmatrix} 1 \\ -3 \\ 2 \end{pmatrix}$ . The matrix of  $T$  is

$$\begin{aligned} M = I_3 - \frac{1}{\vec{v} \cdot \vec{n}} \vec{v} \vec{n}^T &= I_3 - \frac{1}{14} \begin{pmatrix} 1 \\ 1 \\ 8 \end{pmatrix} \begin{pmatrix} 1 & -3 & 2 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} - \frac{1}{14} \begin{pmatrix} 1 & -3 & 2 \\ 1 & -3 & 2 \\ 8 & -24 & 16 \end{pmatrix} \\ &= \frac{1}{14} \begin{pmatrix} 13 & 3 & -2 \\ -1 & 17 & -2 \\ -8 & 24 & -2 \end{pmatrix} \end{aligned}$$

(c) All fixed points are the points on  $\alpha : x - 3y + 2z = 0$ .

(e,f) can be done the same way as Problem 1.

**Problem 3.** Let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be the orthogonal reflection through the line

$$l : \vec{x} = t \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$$

(a) Find the matrix of  $T$ .

(b) Find the image of the line  $k : \vec{x} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$  under  $T$ .

**Solution.** (a) The line  $l$  has direction  $\vec{d} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$ . The matrix of  $T$  is

$$\begin{aligned} M = \frac{2}{\|\vec{d}\|^2} \vec{d} \vec{d}^T - I_3 &= \frac{2}{6} \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \begin{pmatrix} 1 & 2 & -1 \end{pmatrix} - I_3 \\ &= \frac{1}{3} \begin{pmatrix} 1 & 2 & -1 \\ 2 & 4 & -2 \\ -1 & -2 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \\ &= \frac{1}{3} \begin{pmatrix} -2 & 2 & -1 \\ 2 & 1 & -2 \\ -1 & -2 & -2 \end{pmatrix} \end{aligned}$$

(b) The image of  $k$  is the line

$$k' : \vec{x} = \frac{1}{3} \begin{pmatrix} -2 & 2 & -1 \\ 2 & 1 & -2 \\ -1 & -2 & -2 \end{pmatrix} \left( \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right) = \begin{pmatrix} -1/3 \\ -2/3 \\ -11/3 \end{pmatrix} + t \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

□

**Problem 4.** Let  $T$  be the orthogonal projection onto the plane  $\alpha : x - 2y + z = 0$ .

(a) Find the matrix  $M$  of  $T$ .

(b) Find the images of the points  $\begin{pmatrix} 3 \\ 1 \\ 5 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ -5 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$ .

(c) Find the image of  $\beta : x - z = 6$  under  $T$ .

(d) Find the image of  $l : \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 5 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$  under  $T$ .

(e) Let  $Q$  be the intersection of  $\beta$  and  $l$ . Find the image of  $Q$  under  $T$ .

**Solution.** (a) The plane  $\alpha$  has normal  $\vec{n} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$ . The matrix of  $T$  is

$$M = I_3 - \frac{1}{\|\vec{n}\|^2} \vec{n} \vec{n}^T = \frac{1}{6} \begin{pmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{pmatrix}$$

(b) The images of the given points are the last 3 columns of the following matrix

$$\frac{1}{6} \begin{pmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{pmatrix} \begin{pmatrix} 3 & 1 & 1 \\ 1 & 1 & -1 \\ 5 & -5 & 3 \end{pmatrix} = \begin{pmatrix} 2 & 2 & 0 \\ 3 & -1 & 1 \\ 4 & -4 & 2 \end{pmatrix}$$

(c) The plane  $\beta$  has normal  $\vec{n}_\beta = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ . So its direction vectors are  $\vec{u} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$  and

$\vec{v} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ . Hence  $\beta$  has vector equation

$$\beta : \vec{x} = \begin{pmatrix} 1 \\ 1 \\ -5 \end{pmatrix} + s \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

The image of  $\beta$  is  $\beta'$  which has equation

$$\begin{aligned} \vec{x} &= \frac{1}{6} \begin{pmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{pmatrix} \left( \begin{pmatrix} 1 \\ 1 \\ -5 \end{pmatrix} + s \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right) \\ &= \begin{pmatrix} 2 \\ -1 \\ -4 \end{pmatrix} + \frac{s}{6} \begin{pmatrix} 4 \\ 4 \\ 4 \end{pmatrix} + \frac{t}{6} \begin{pmatrix} 2 \\ 2 \\ 2 \end{pmatrix} \\ &= \begin{pmatrix} 2 \\ -1 \\ -4 \end{pmatrix} + \left( \frac{2s}{3} + \frac{t}{3} \right) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ -4 \end{pmatrix} + r \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \end{aligned}$$

which is a line through the point  $\begin{pmatrix} 2 \\ -1 \\ -4 \end{pmatrix}$  and having direction vector  $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ .

(d) The image of  $l$  is the line  $l'$  which has equation

$$\vec{x} = \frac{1}{6} \begin{pmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{pmatrix} \left( \begin{pmatrix} 3 \\ 1 \\ 5 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$$

(e) First, we find the point  $Q = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ . Since  $Q$  is on both  $l$  and  $\beta$ , we have

$$\begin{cases} x = 3 + t \\ y = 1 - t \\ z = 5 + 3t \end{cases} \quad \text{and} \quad x - z = 6$$

We have

$$(3 + t) - (5 + 3t) = 6 \Rightarrow -2 - 2t = 6 \Rightarrow t = -4$$

Thus  $Q = \begin{pmatrix} 3 + t \\ 1 - t \\ 5 + 3t \end{pmatrix} = \begin{pmatrix} -1 \\ 5 \\ -7 \end{pmatrix}$ . The image of  $Q$  is

$$Q' = \frac{1}{6} \begin{pmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{pmatrix} \begin{pmatrix} -1 \\ 5 \\ -7 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ -4 \end{pmatrix}.$$

□

**Problem 5.** Let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be the reflection in the  $xz$ -plane, and let  $S : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  the reflection in the plane  $x - y = 0$ .

The composition  $T \circ S : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is defined by  $T \circ S(\vec{x}) = T(S(\vec{x}))$ .

(a) Find the matrix  $K$  of the composition  $T \circ S$ .

*Hint:*  $M, N$  = matrices of  $T, S \Rightarrow$  matrix of  $T \circ S$  is  $K = MN$ .

(b) Find the matrix  $L$  of the composition  $S \circ T$ . (*Hint:*  $L = NM$ ).

(c) Check that  $K$  and  $L$  are inverses of each other, that is,

$$KL = LK = I_3.$$

**Solution.** The  $xz$ -plane has equation  $y = 0$ , so a normal vector is  $\vec{n}_1 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ . The matrix of  $T$  is

$$M_T = I_3 - \frac{2}{\|\vec{n}_1\|^2} \vec{n}_1 \vec{n}_1^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} - 2 \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

The plane  $x - y = 0$  has normal vector  $\vec{n}_2 = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$ . The matrix of  $S$  is

$$M_S = I_3 - \frac{2}{\|\vec{n}_2\|^2} \vec{n}_2 \vec{n}_2^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} - \frac{2}{2} \begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

(a) The matrix of  $T \circ S$  is

$$K = M_{T \circ S} = M_T M_S = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

(b) The matrix of  $S \circ T$  is

$$L = M_{S \circ T} = M_S M_T = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

(c) It is straightforward to verify that  $KL = LK = I_3$

$$\begin{aligned} KL &= \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3 \\ LK &= \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3 \end{aligned}$$

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