

Abstract Data Types (ADTs) (Part II)

Outline

- Abstract Data Types (ADTs)
 - Definition
 - ADTs vs Data Structures
 - Client vs Implementation
 - Benefits
- Implementations of ADTs
 - Stack
 - Implementation using array and linked list
 - Application: Postfix Notation
 - Queue
 - Array and Linked List
 - Application: Breadth-first search on a graph
 - Priority queue

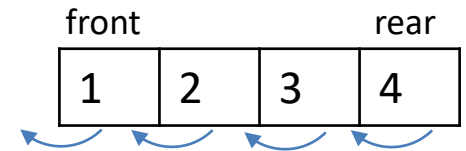
Queue

- A queue is an ADT that adopts a **FIFO** (first-in first-out) policy.
- Two basic operations:
 - Add (push) a new item to the rear
 - Remove (pop) the item at the front (one that has been in the queue the longest)



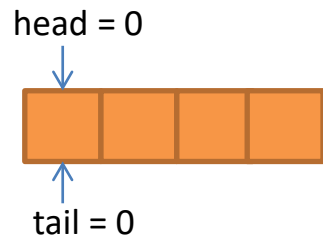
Implementation: Array or Linked List

- Linked List
 - Constant time for removing from the front: $O(1)$
 - Expensive to add to the rear using a just a head pointer: $O(n)$
 - Use a tail pointer for adding to the rear: $O(1)$
 - Implementing a FIFO Queue using a linked list is trivial.
- Array
 - Constant time for adding to the end: $O(1)$
 - Expensive to remove from the front: $O(n)$
 - Use a **circular array**.
 - Implementation using an array (efficiently) is slightly more interesting.

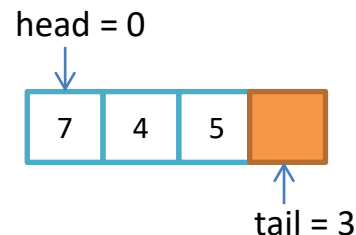


Queue Implementation using a Circular Array

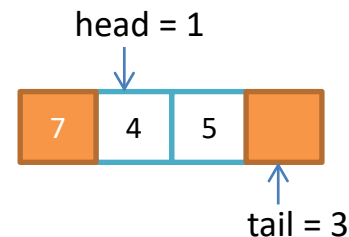
- We will use
 - head: index of the first item (front) of the queue
 - tail: index after the position of the last item (rear) of the queue
- Initially: head = tail = 0, indicating an empty queue.
- When we add an item, we increment tail.
- When we remove an item, we increment head.
- head and tail will “wrap around” at the end of the queue. This leads to a circular array.
- A circular array gives us $O(1)$ for both adding and removing.



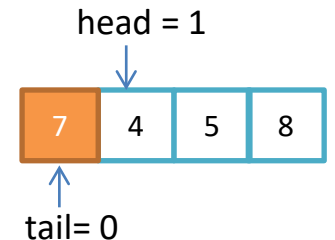
Initially: head = tail = 0



Add: increment tail



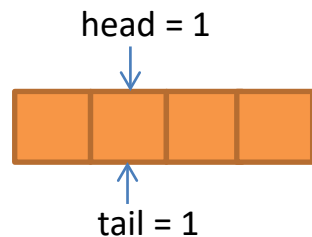
Remove: increment head.



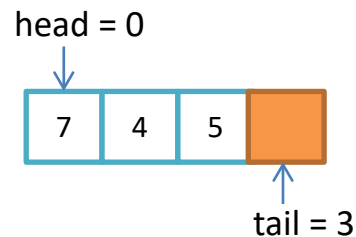
“Wrap around” at the end of the queue

Implementation using a Circular Array

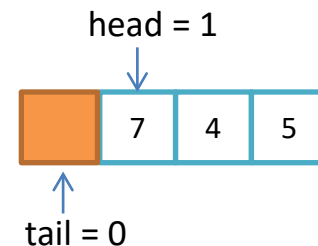
- We will use an array of **SIZE** elements.
- We keep **one unused slot** to distinguish between full and empty.
 - Array of size N can only hold $N-1$ elements.
- We have to keep track of the start and end of the array.
 - if $(\text{tail} == \text{head})$, the queue is empty.
 - if $((\text{tail}+1)\% \text{SIZE} == \text{head})$, the queue is full.
 - Number of items in queue is $(\text{tail} - \text{head} + \text{SIZE}) \% \text{SIZE}$.



Empty queue
 $\text{head} = \text{tail}$



Full queue: $(3+1)\%4==0$
No. items: $(3-0+4)\%4=3$



Full queue: $(0+1)\%4==1$
No. items: $(0-1+4)\%4=3$

Queue Operations Example

```
Queue queue(5);
```

head = 0



tail = 0

```
queue.Push(7);
```

head = 0



tail = 1

```
queue.Push(4);  
queue.Push(5);
```

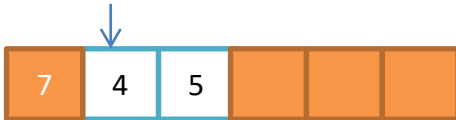
head = 0



tail = 3

```
queue.Pop(); // 7
```

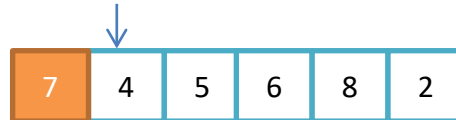
head = 1



tail = 3

```
queue.Push(6);  
queue.Push(8);  
queue.Push(2);
```

head = 1



tail = 0

```
queue.Pop(); // 4  
queue.Pop(); // 5  
queue.Pop(); // 6  
queue.Pop(); // 8
```

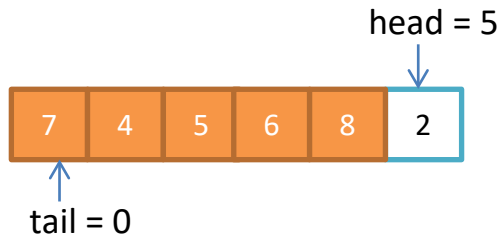
head = 5



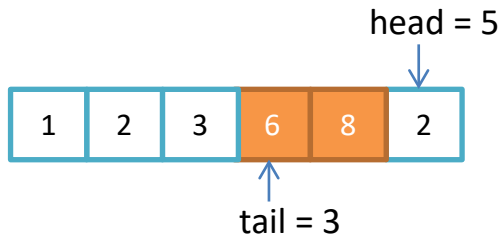
tail = 0

QUEUE IS FULL

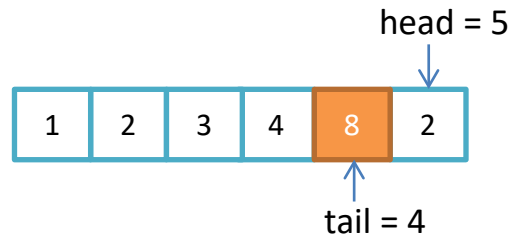
Queue Operations Example



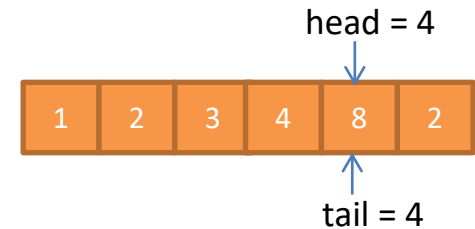
```
queue.Push(1);  
queue.Push(2);  
queue.Push(3);
```



```
queue.Push(4);
```



```
Queue.Remove(); // 2  
Queue.Remove(); // 1  
Queue.Remove(); // 2  
Queue.Remove(); // 3  
Queue.Remove(); // 4  
Queue.Remove(); // empty!
```



Queue Implementation using a Circular Array

```
template <typename T>
class Queue{
private:
    T *items;
    int head;
    int tail;
    int SIZE;

public:
    Queue (int maxItem){
        SIZE = maxItem + 1;
        items = new T [SIZE];
        head = 0;
        tail = 0;
    }

    bool IsEmpty(void) const {
        return (tail == head);
    }

    bool IsFull(void) const{
        return ((tail+1)%SIZE==head);
    }
};
```

```
void Push(T item){
    if (!IsFull()){
        items[tail++] = item;
        if (tail==SIZE)
        {
            tail = 0;
        }
    }
}

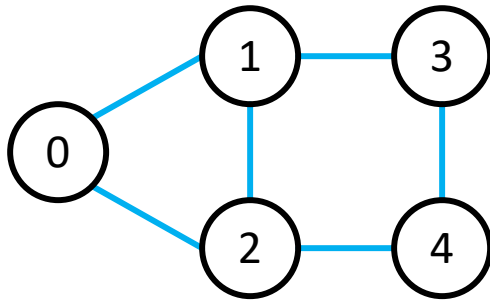
T Pop(void){
    if (!IsEmpty()) {
        T temp = items[head];
        head++;
        if (head==SIZE){
            head = 0;
        }
        return temp;
    }
};
```

Choice of Queue Implementation

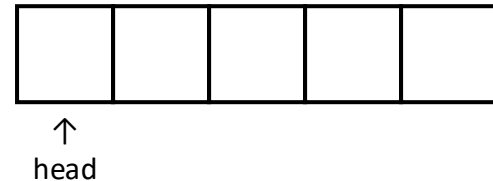
- Circular array: fixed size, costly resizing, better cache locality, lower memory overhead
- Linked list: dynamic size, flexibility, more memory overhead per element
- The choice between a circular array-based queue and a linked list-based queue depends on the specific requirements of the application. E.g.,
 - For application where cache locality is important (e.g., real time system), a circular array based queue might be more suitable.
 - If the size of the queue is not known in advance and may vary dynamically, a linked list-based queue can be more flexible.

Queue Application: Breadth-first Search (BFS) on a Graph

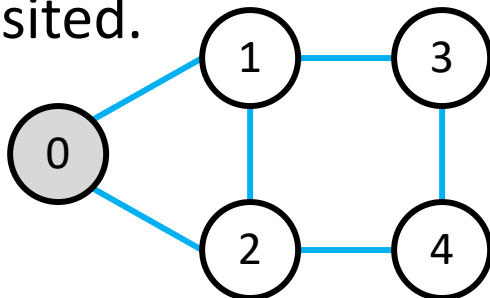
- BFS is used for traversing or searching a graph.
- All vertices at the current level are visited before moving on to vertices at the next level.
- Step 1: Initial queue is empty.



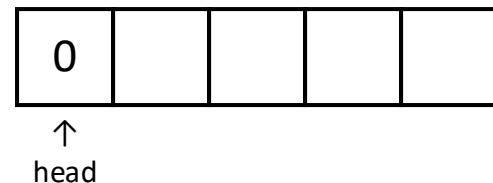
Queue



- Step 2: Start from node 0 and push it into the queue and mark it visited.

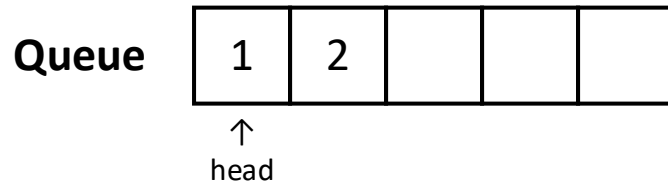
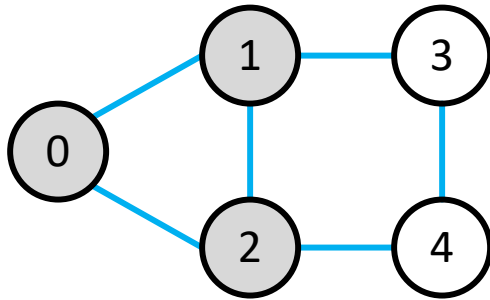


Queue

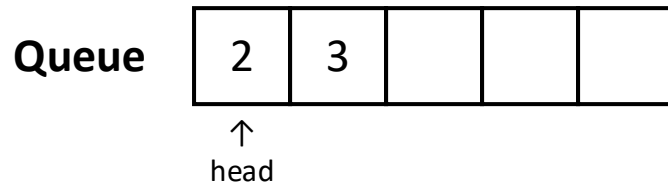
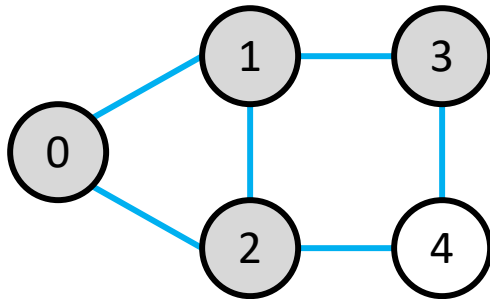


Queue Application: Breadth-first Search on a Graph

- Step 3: Remove node 0 from the front of queue and visit the unvisited neighbours and push them into queue.

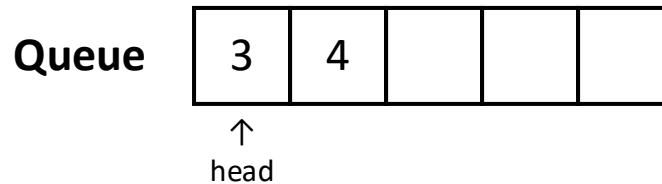
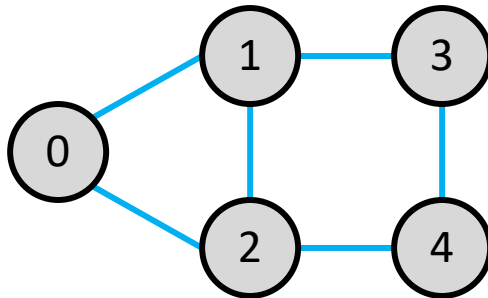


- Step 4: Remove node 1 from the front of queue and visit the unvisited neighbours and push them into queue.

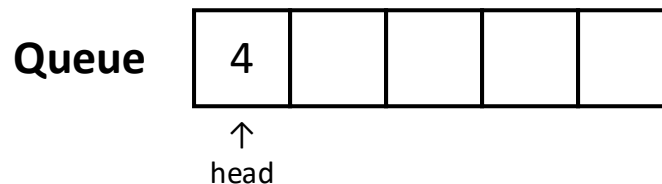
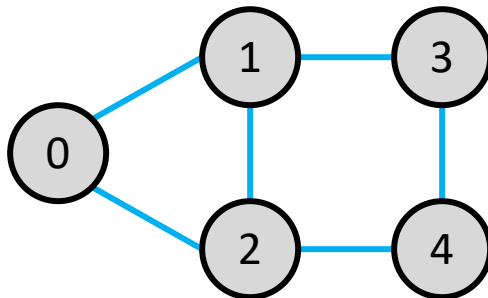


Queue Application: Breadth-first Search on a Graph

- Step 5: Remove node 2 from the front of queue and visit the unvisited neighbours and push them into queue.

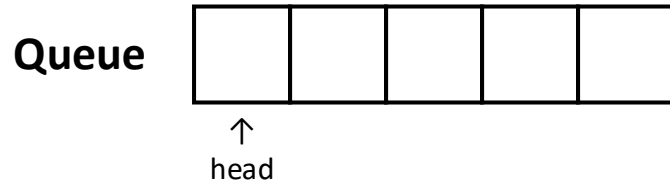
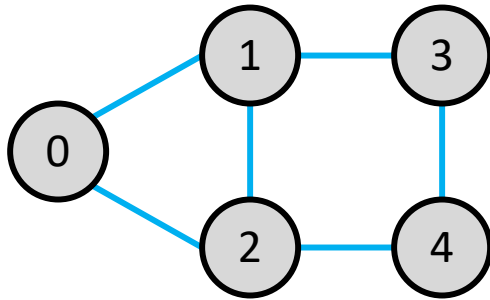


- Step 6: remove node 3 from the front of queue and visit the unvisited neighbours and push them into queue.



Queue Application: Breadth-first Search on a Graph

- Step 7: Remove node 4 from the front of queue and visit the unvisited neighbours and push them into queue.



Priority Queue

- Priority queue is an ADT that pushes a new item to the rear and pops the item with the **highest priority**.
 - Priority is user-defined
 - Could be the item with the highest id.
 - Could be the item with the oldest timestamp (think of messaging systems).
- It can be implemented using an array or a linked-list.

Priority Queue: Public Interface

```
class PriorityQueue{  
    private:  
        // private data  
  
    public:  
        PriorityQueue(int capacity);  
        ~PriorityQueue(void);  
        void Push(int Item);  
        int Pop(void);  
        bool IsEmpty(void) const;  
        bool IsFull(void) const;  
        void Dump(void) const;  
};
```


Priority Queue: Private Interface

```
class PQArray{  
    private:  
        int *array_;  
        int capacity_;  
        int count_;  
    public:  
        // public interface  
};
```

```
struct PQNode{  
    PQNode *next;  
    int data;  
};  
  
class PQList{  
    private:  
        PQNode *list_;  
        int capacity_;  
        int count_;  
    public:  
        // public interface  
};
```

Priority Queue

- Complexity depends on whether the list/array is sorted or unsorted.

Operations	Unsorted	Sorted
Push	$O(1)$	$O(n)$
Pop	$O(n)$	$O(1)$

Priority Queue using a Sorted Linked List

```
int main(void){
    PQList pq(10);
    // Sorted linked list implementation

    pq.Add(4);  pq.Add(7);  pq.Add(2);
    pq.Add(5);  pq.Add(8);  pq.Add(1);

    pq.Dump();

    printf("Removing: %i\n", pq.Remove());
    pq.Dump();

    printf("Removing: %i\n", pq.Remove());
    pq.Dump();

    printf("Removing: %i\n", pq.Remove());
    pq.Dump();

    return 0;
}
```

Output:

8 7 5 4 2 1

Removing: 8

7 5 4 2 1

Removing: 7

5 4 2 1

Removing: 5

4 2 1

Priority Queue using an Unsorted Array

```
int main(void){
    PQArray pq(10);
    // Unsorted array implementation

    pq.Add(4);  pq.Add(7);  pq.Add(2);
    pq.Add(5);  pq.Add(8);  pq.Add(1);

    pq.Dump();

    printf("Removing: %i\n", pq.Remove());
    pq.Dump();

    printf("Removing: %i\n", pq.Remove());
    pq.Dump();

    printf("Removing: %i\n", pq.Remove());
    pq.Dump();

    return 0;
}
```

Output:

4 7 2 5 8 1

Removing: 8

4 7 2 5 1

Removing: 7

4 1 2 5

Removing: 5

4 1 2

Priority Queue

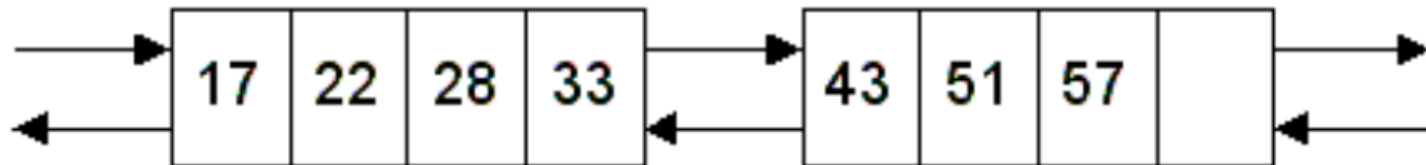
- Result is the same.
- Implementation are different.
- Complexities are different.

Summary

- Abstract Data Types (ADTs)
 - Definition
 - ADTs vs Data Structures
 - Client vs Implementation
 - Benefits
- Implementations of ADTs
 - Stack
 - Implementation using array and linked list
 - Application: Postfix Notation
 - Queue
 - Array and Linked List
 - Application: Breadth-first search on a graph
 - Priority queue

BList

- Also known as unrolled linked list
- A linear data structure
- A linked list of arrays of the same size
- Example: A BList of 4 items per node



Advantages of BList

- Linked list
 - Advantages
 - Insertion and deletion: $O(1)$
 - Disadvantages
 - Traversal is slow due to poor cache locality: $O(n)$
 - Memory overhead for storing references
- Advantages of BList over linked list
 - Faster traversal due to better cache locality
 - Reduced memory overhead to store references

BList Operations

- Push back
- Push front
- Insert
- Split

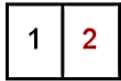
BList Operations: Push back

- Add an element to the back of a Blist.

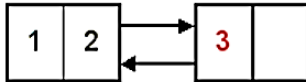
Push back 1:



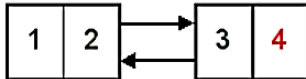
Push back 2:



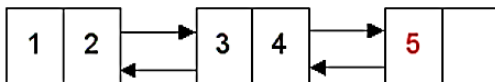
Push back 3:



Push back 4:



Push back 5:



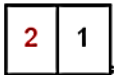
BList Operations: Push front

- Add an element to the front of a BList

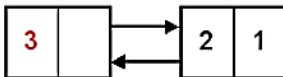
Push front **1**:



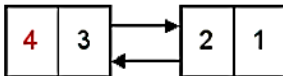
Push front **2**:



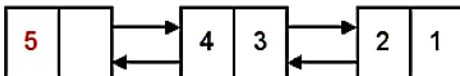
Push front **3**:



Push front **4**:



Push front **5**:

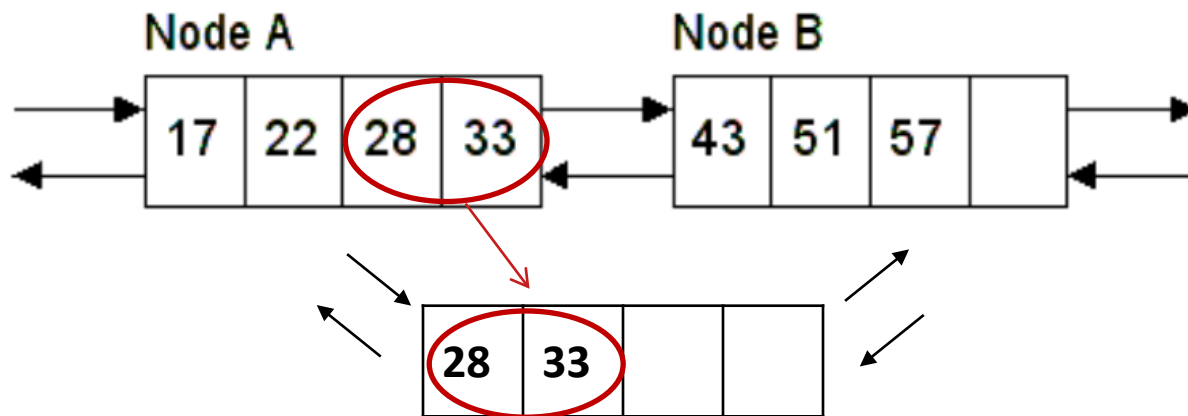


BList Operations: Insertion

- Insert an element to a **sorted** Blist.
- First, find the node where the element is to be inserted.
 - The node to be inserted into is not full.
 - The node to be inserted into is full.

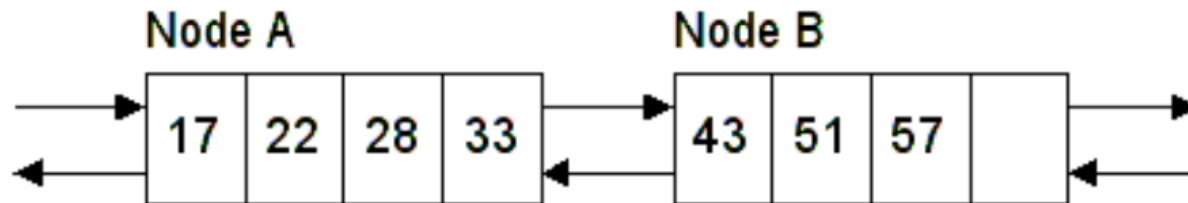
BList Operations: Split

- If the node to be inserted into is a full node, **split** it into two.
 - Insert a new node after the full node.
 - Move 2nd half of the elements in the full node to the 1st half of the new node

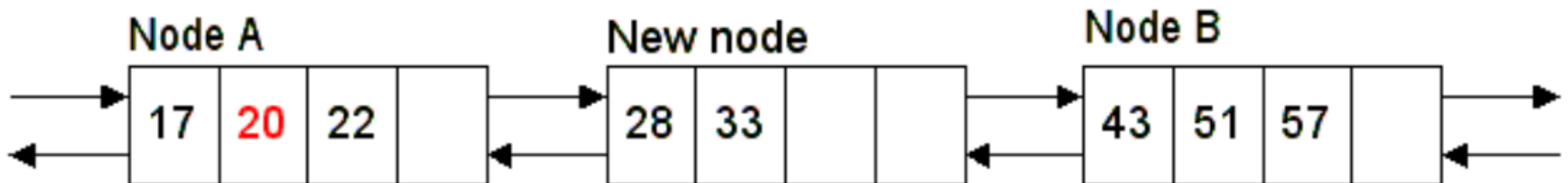


BList Operations: Insertion

- Insert 20
 - Before insertion

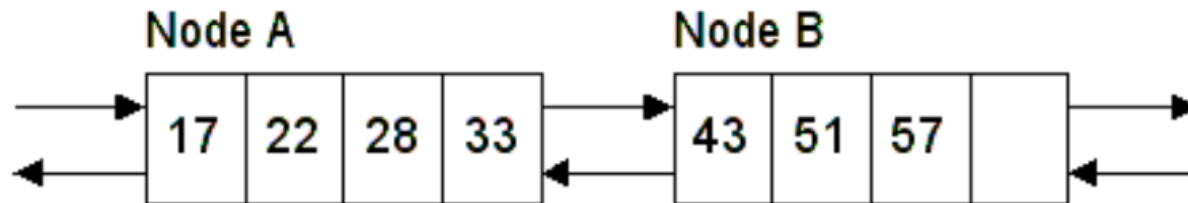


- After insertion

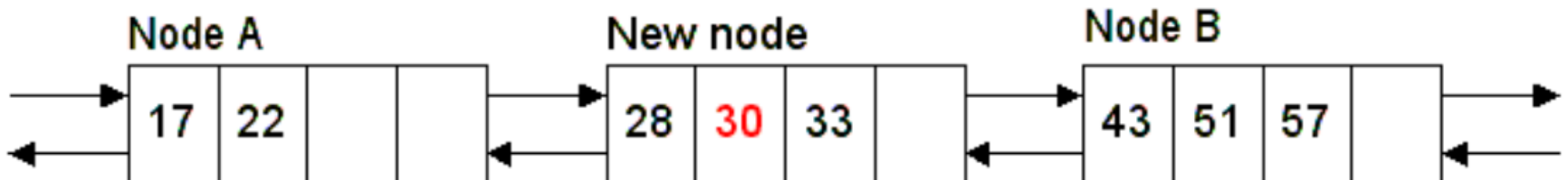


BList Operations: Insertion

- Insert 30
 - Before insertion

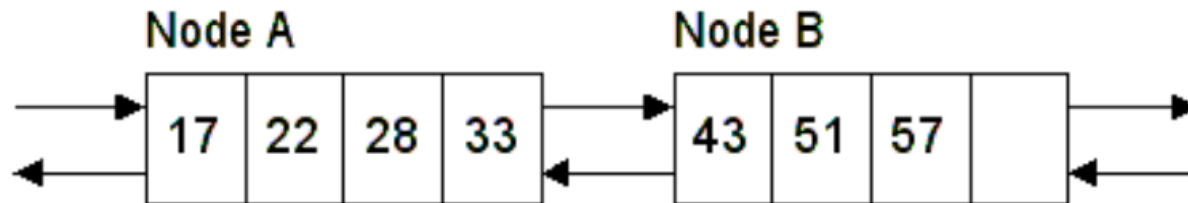


- After insertion

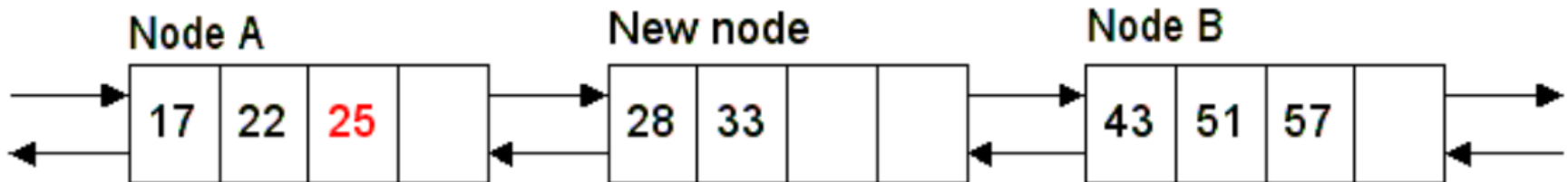


BList Operations: Insertion

- Insert 25
 - Before insertion



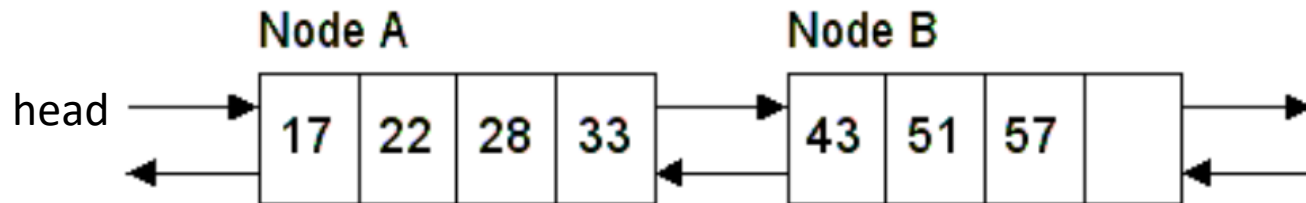
- After insertion



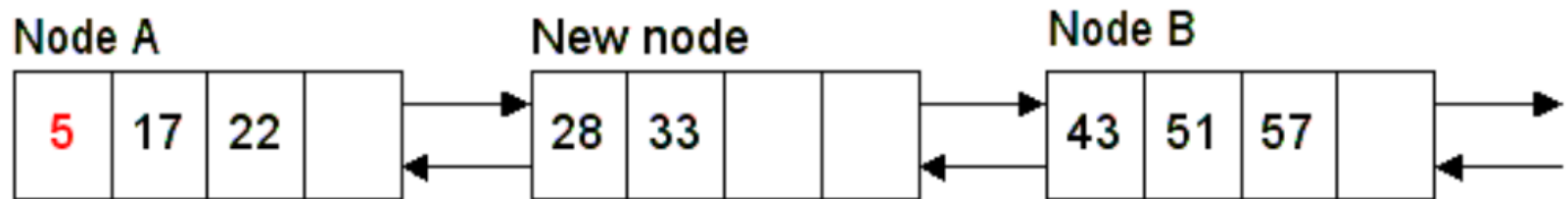
Even though the value 25 can go in either node above (both have room), we want to minimize the shifting of existing elements.

BList Operations: Insertion

- Insert 5
 - Before insertion



- After insertion

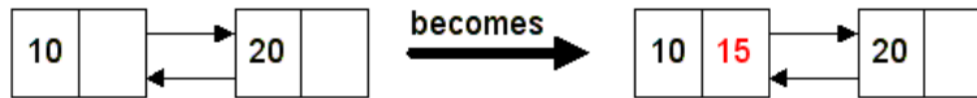


BList Operations: Insertion

- Which node to insert?

Inserting the value **15** in four different cases.

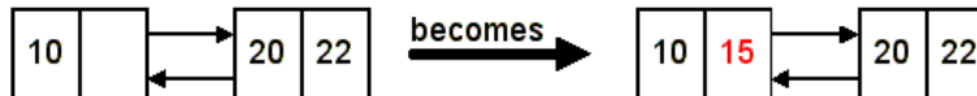
- Both the left and right nodes have room:



- Both the left and right nodes are full: (Split the left node)



- The left node has room and right node is full:



- The left node is full and the right node has room:

