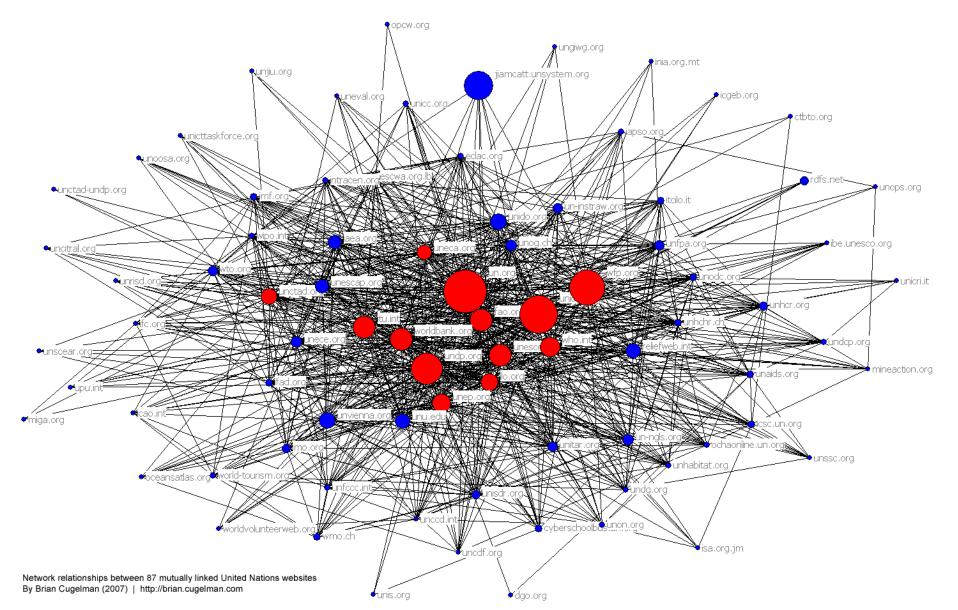
# Introduction to Graphs

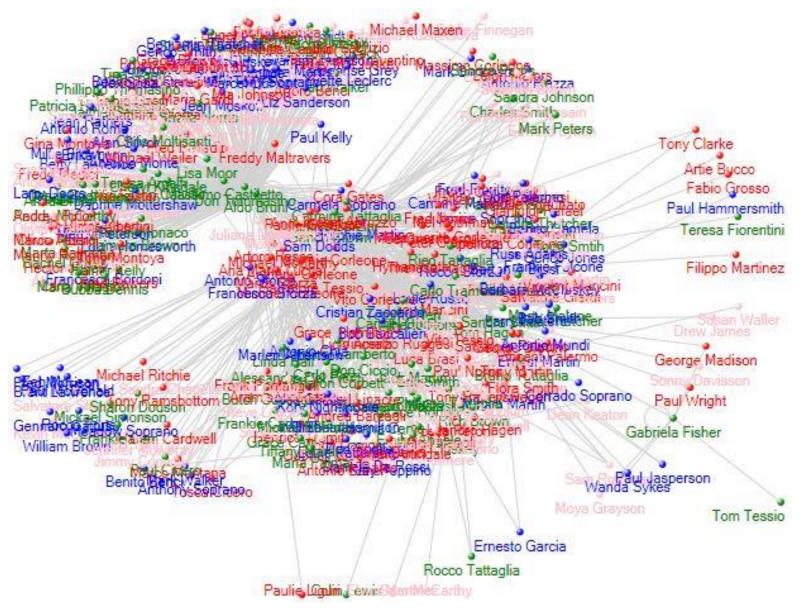
#### Outline

- Introduction & Terminology
- Representing Graphs
- Graph Traversals
- Spanning Trees
- Shortest Path Algorithms

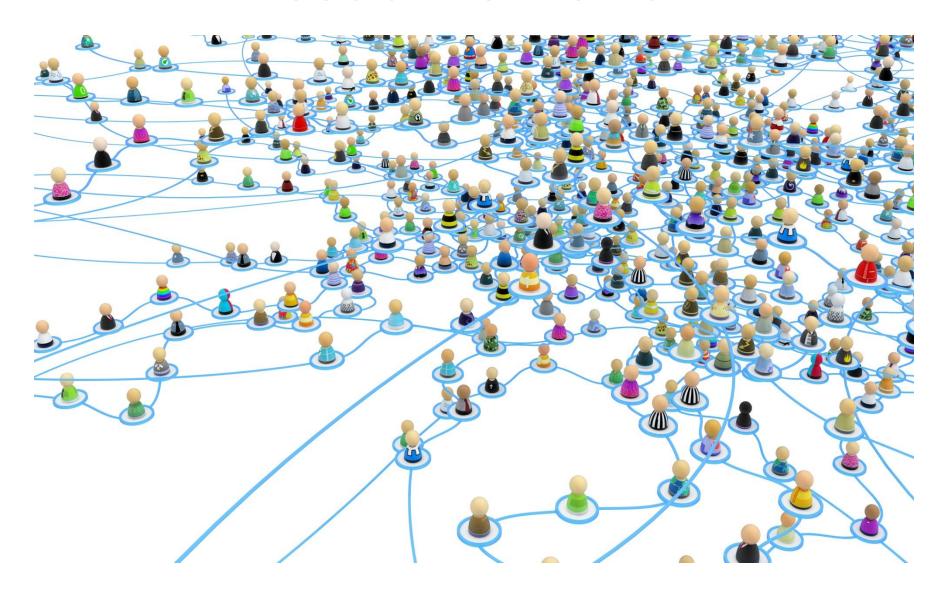
#### Internet



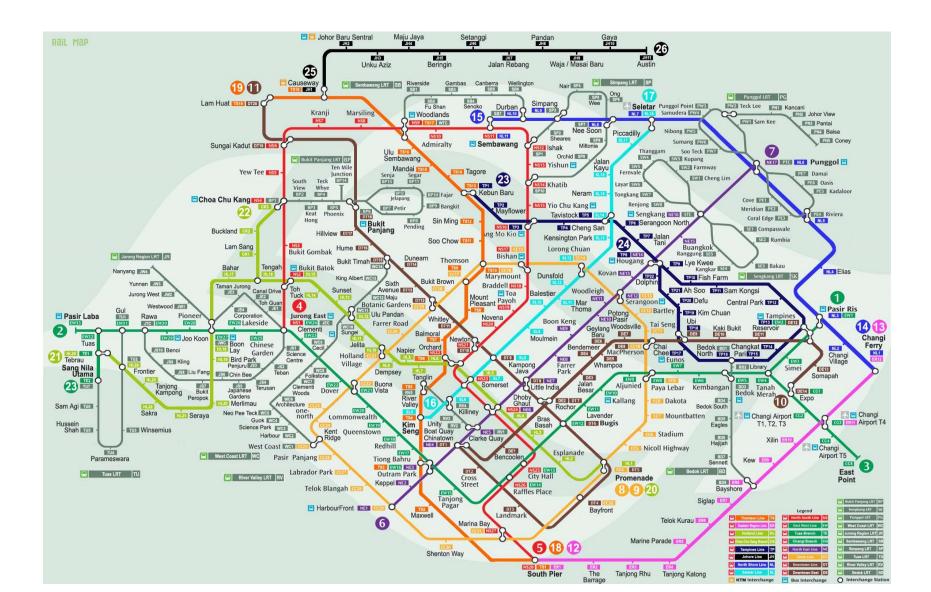
#### **Email Networks**



## **Social Networks**



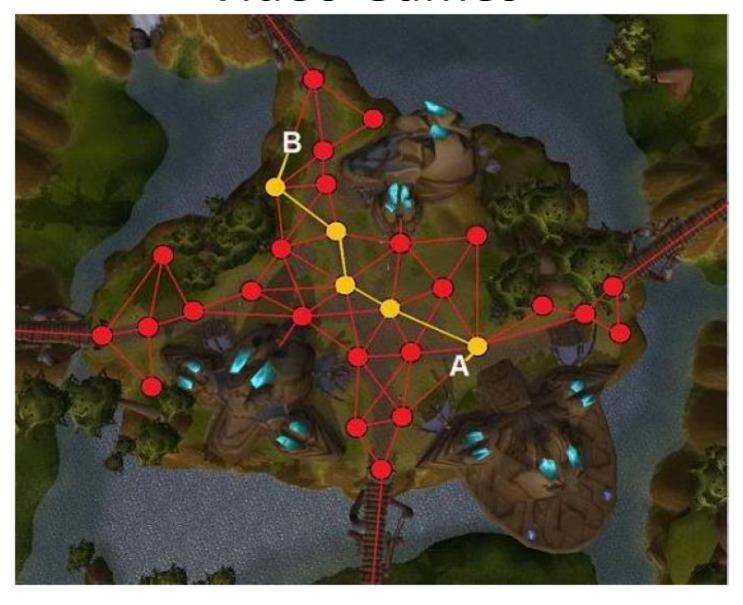
## **Public Transport**



# Video Games



# Video Games



# Introduction & Terminology

- One of the most useful data structures (A very large topic).
- Related to trees in that a tree is a special kind of graph (Trees are much simpler).
- Graphs are more general and have a wider range of use. (Generality trades simplicity).
- Represent problems involving interconnected (dependent) objects.
- Graph algorithms are complex. Need to account for cycles; trees have only one path between nodes.

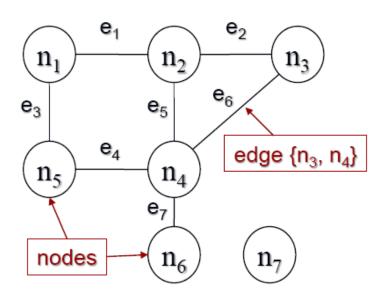
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- A graph is essentially a collection of points connected by line segments.
- The points are referred to as nodes or vertices; the segments are called edges.

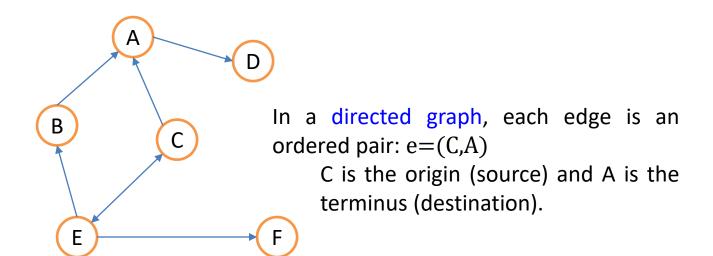


$$V = \{n_1, n_2, n_3, n_4, n_5, n_6, n_7\}$$

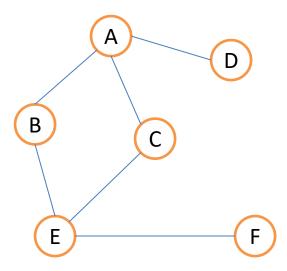
$$E = \{e_1, e_2, e_3, e_4, e_5, e_6, e_7\}$$

$$= \{(n_1, n_2), (n_2, n_3), (n_1, n_5), (n_4, n_5), (n_2, n_4), (n_3, n_4), (n_4, n_6)\}$$

 If the edges have a direction (arrowheads in a diagram), the graph is a directed graph, or digraph.

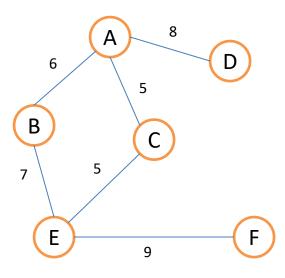


 If the graph edges has no values is called a undirected graph.



In an undirected graph, each edge is an unordered pair:  $e=(v_1,v_2)$ 

• If the graph has values (weights or costs) assigned to edges is called a weighted graph.



#### **Notation**

- Two vertices, x and y are said to be adjacent if there is an edge connecting them.
- We use the notation sGd to mean that s is adjacent to d. With a digraph, sGd implies direction. (xGy is not the same as yGx).
- The set of nodes adjacent to s is called the adjacency set of s or neighbors of s.
  - This set is fundamental to many graph algorithms.

#### **Notation**

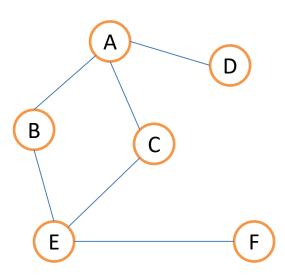
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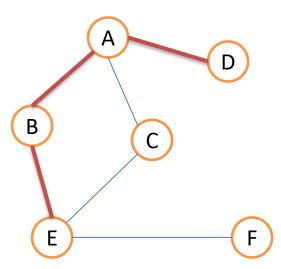
## Paths and Connectivity

• A (contiguous) sequence of edges is a path



## Paths and Connectivity

- A (contiguous) sequence of edges is a path path D to E: {D, A, B,E}
- If there is a path from x to y, y is reachable from x
- The length of a path is the number of edges on the path: 3 for the example
- Two vertices are connected if there is a path from one to the other
- A connected component is a subset, S, of vertices that are all connected

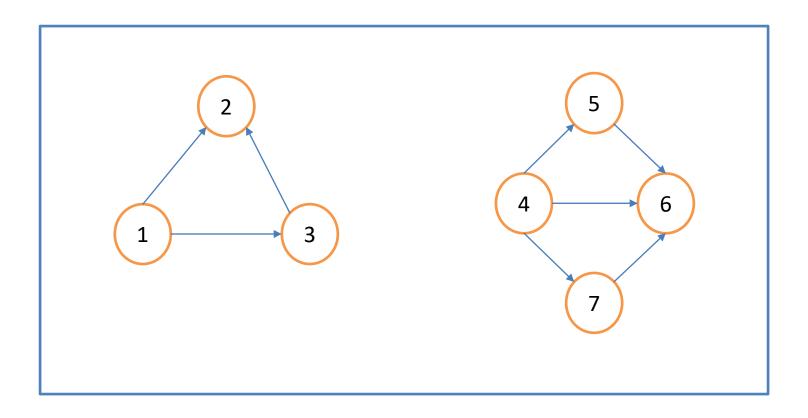


#### Connectedness

- Connectedness is an equivalence relation on the node set of a graph
  - Reflexive: every node is in a path of length 0 with itself
  - Symmetric: if  $(n_i, n_i)$  ∈ path, then  $(n_i, n_i)$  ∈ path
  - Transitive: if  $(n_i, n_j) \in \text{path}$  and  $(n_j, n_w) \in \text{path}$ , then  $(n_i, n_w) \in \text{path}$ .

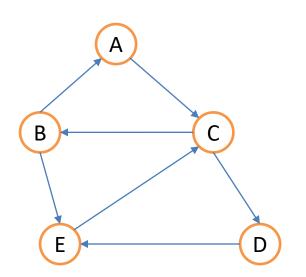
## Connected Component: Example

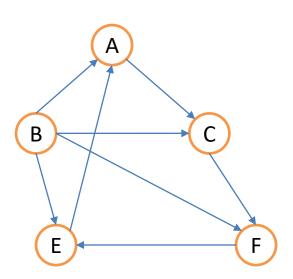
A single directed graph with two components:



## **Connection Types**

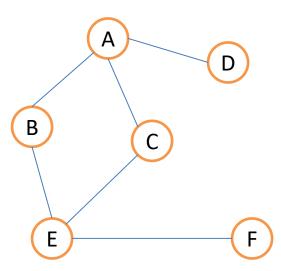
- Digraphs can be strongly connected or weakly connected.
  - Strongly connected: There is a path from every node to every other node
  - Weakly connected: There is NOT a path from each node to every other node (see Node C)





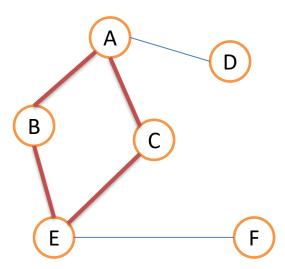
## Cycles

- A cycle is a path whose source and destination node are the same
- A cycle is simple if all nodes on the path are distinct (with the exception of the first and last). A simple cycle must include at least 3 vertices



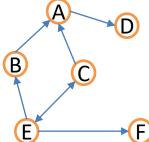
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- If a graph has no cycles, it is acyclic. A directed acyclic graph is called a DAG



## Degree

- For an undirected graph, the degree is the number of edges connecting a node
  - A: 3
  - B: 2
- For directed graph:
  - In-degree: Is the number of incoming edges into a node(node is a destination).
    - A:2
    - B:1
  - Out-degree: Is the number of outgoing edges from a node (node is a source).
    - A:1
    - B:1



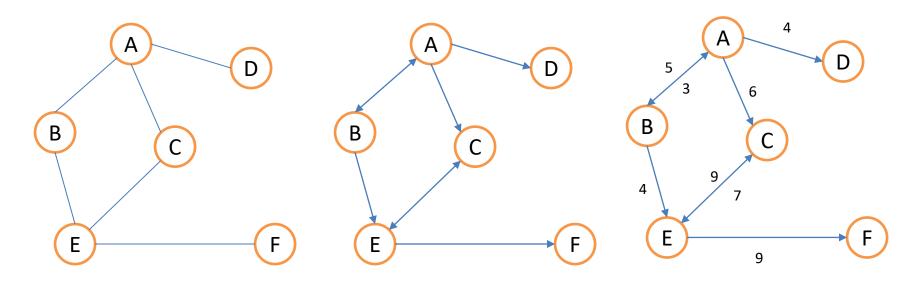
F

# Tree vs Graph

Characteristics	Tree	Graph
Cycle	X	<b>~</b>
Root	<b>✓</b>	X
Reachability of Nodes	<b>~</b>	X
Direction	<b>~</b>	Optional

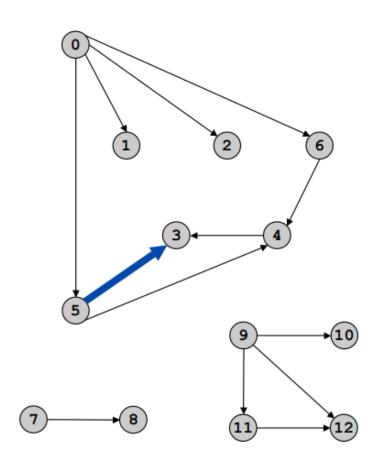
## Representing Graphs

- A graph G with N nodes represented by an N  $\times$  N boolean array (matrix).
- For each x and y, G(x,y) = TRUE if xGy, otherwise false.



## Adjacency Matrix - Example

from



to 10 11

- Space required is  $O(N^2)$ 
  - A sparse graph has few edges
    - Sparse graphs will have many matrix entries of 0.
  - a dense graph has many edges.
    - Dense graphs will have many matrix entries of 1.
- Determining if two nodes are adjacent is O(1)
- The size of the matrix is **independent** of the number of edges.
- An adjacency matrix may be a more desirable representation for dense graphs.

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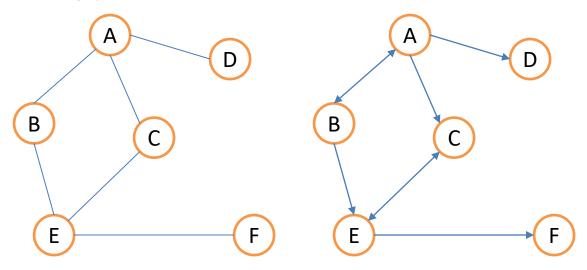
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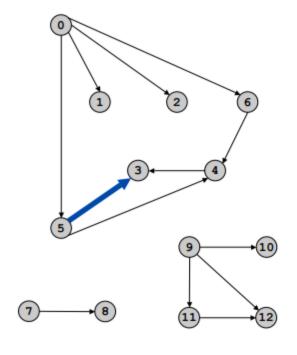
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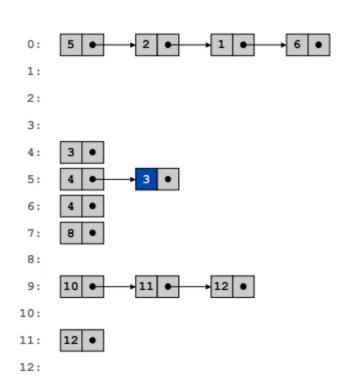
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- A graph G with N nodes represented by an array of N linked lists.
- For each x and y, if xGy is TRUE, y is on x's list.



### Adjacency Lists - Example





- Space required is  $O(N^2)$
- Density affects the lists:
  - Sparse graphs will have shorter lists.
  - Dense graphs will have longer lists.
- The order of the nodes in a list may be arbitrary.
  - A weighted graph may order them by weight
- Determining if two nodes are adjacent is O(N) in the worst case. Could be much less if there are few edges.
- The number of nodes in the lists is **dependent** on the number of edges.
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- Unlike tree traversals, there is no "starting" (i.e. root) node in a graph.
- Choosing an arbitrary starting node will not guarantee that all nodes are visited.
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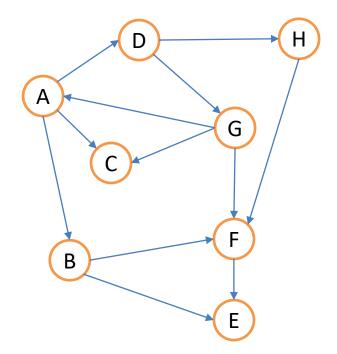
- Breath-first traversal
- Depth-first traversal

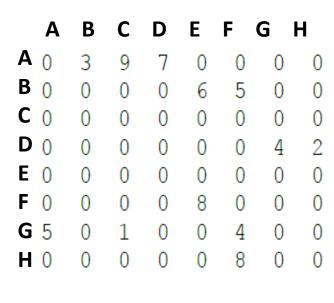
#### Pseudo-code for Graphs Traversals

```
GraphSearch(G is the graph to search, v is the starting vertex){
  Put v into container C;
  while (container C is not empty){
     Remove a vertex, x, from container C;
     if (x has not been visited){
       Visit x;
       Set x.visited to TRUE;
       for (each vertex, w, adjacent to x){
         if (w has not been visited)
           Put w into container C;
       }//end for
     }//end if
   }//end while
} //end GraphSearch
```

#### Example

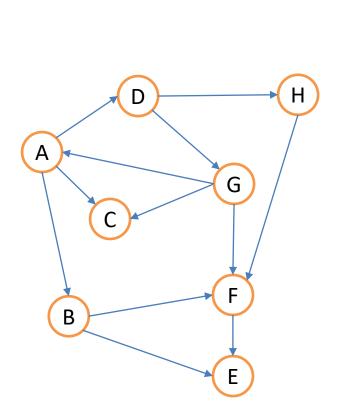
 Given this graph, determine the sequence of nodes that are visited from different starting nodes. Starting at A/G, using Stack/Queue

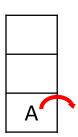




Container: Stack

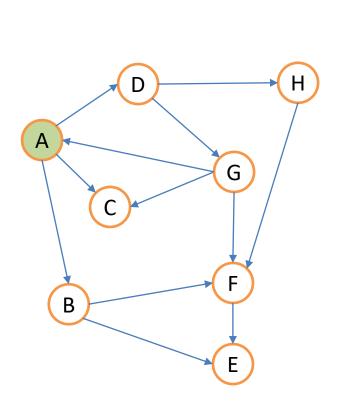
Start at A





Container: Stack

Start at A

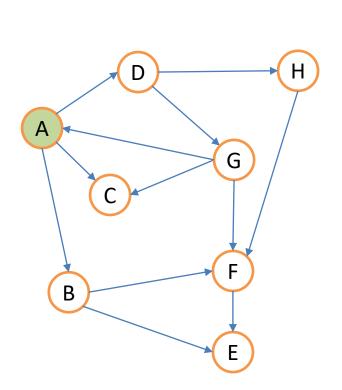


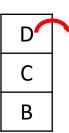


Traversal Order A

Container: Stack

Start at A

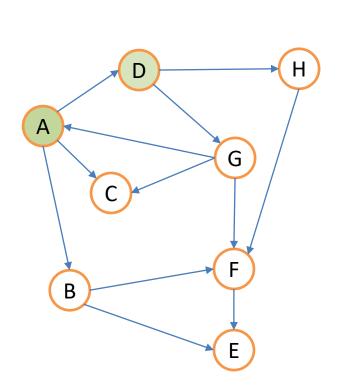


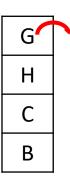


Traversal Order A

Container: Stack

Start at A

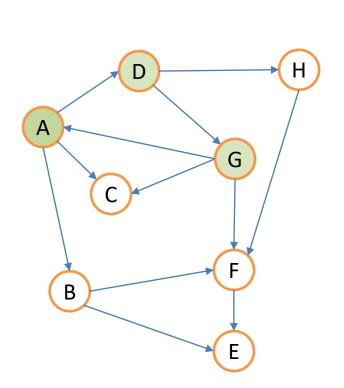


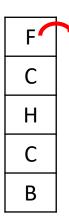


Traversal Order AD

Container: Stack

Start at A

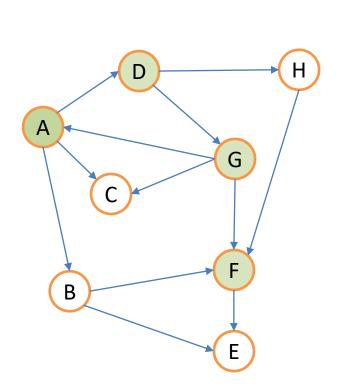




Traversal Order ADG

Container: Stack

Start at A

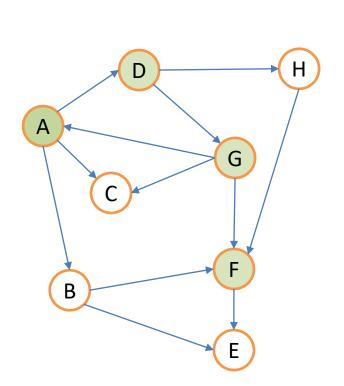


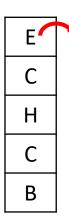
E C H C

Traversal Order ADGF

Container: Stack

Start at A

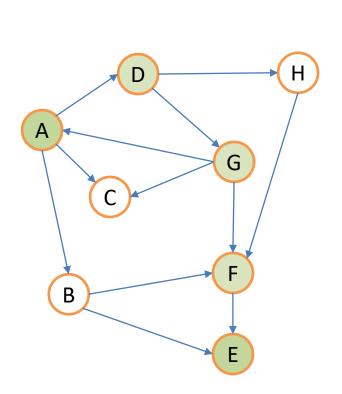


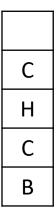


Traversal Order ADGF

Container: Stack

Start at A

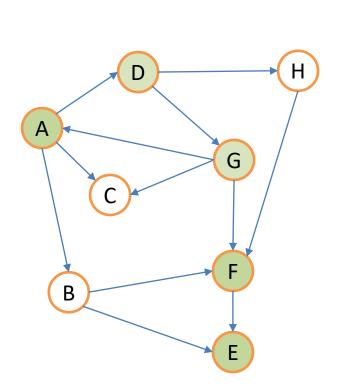


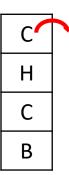


Traversal Order ADGFE

Container: Stack

Start at A

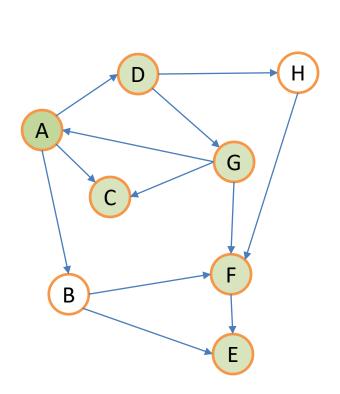


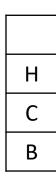


Traversal Order ADGFE

Container: Stack

Start at A

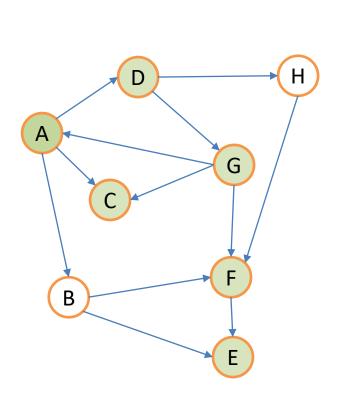


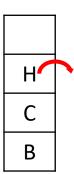


Traversal Order ADGFEC

Container: Stack

Start at A

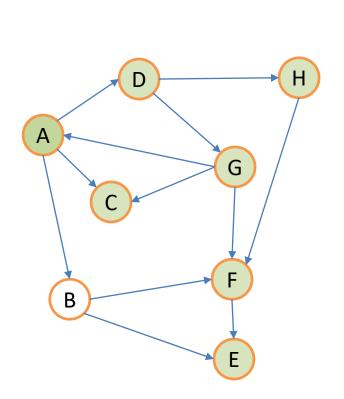


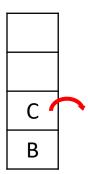


Traversal Order ADGFEC

Container: Stack

Start at A

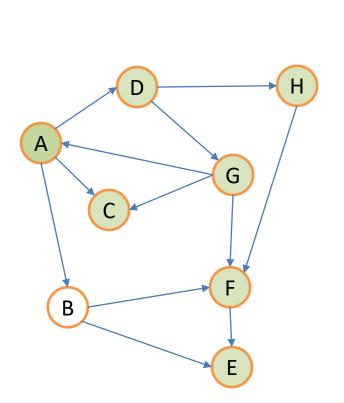


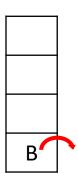


Traversal Order ADGFECH

Container: Stack

Start at A

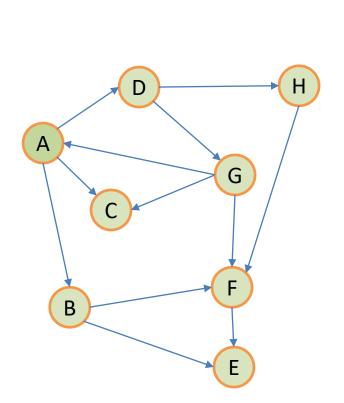




Traversal Order ADGFECH

Container: Stack

Start at A



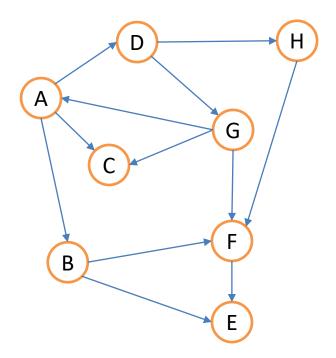


Traversal Order ADGFECHB

Container: Queue

Start at A

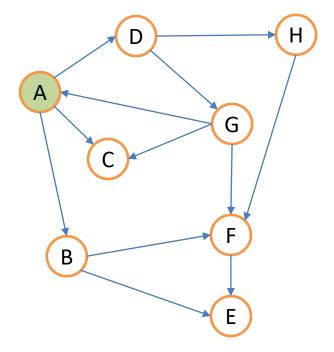




Container: Queue

Start at A



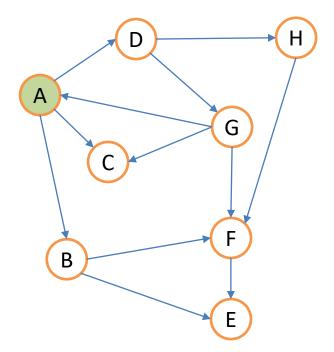


Traversal Order A

Container: Queue

Start at A



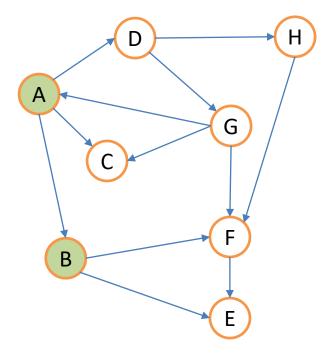


Traversal Order A

Container: Queue

Start at A

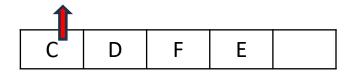


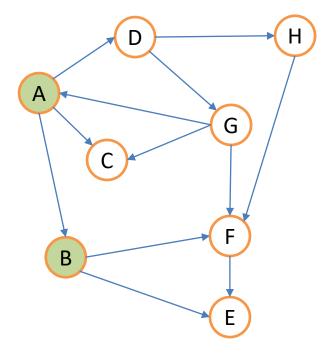


Traversal Order A B

Container: Queue

Start at A



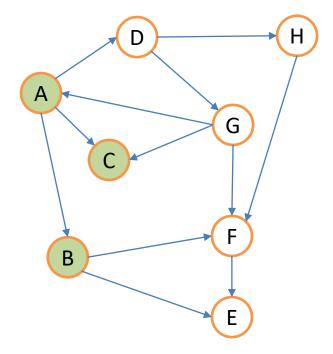


Traversal Order A B

Container: Queue

Start at A

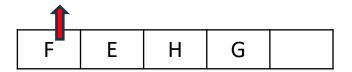


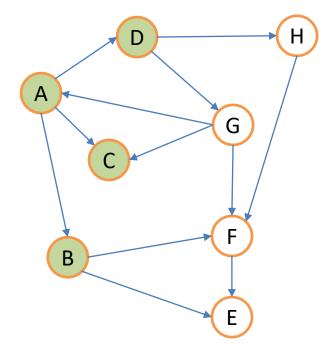


Traversal Order A B C

Container: Queue

Start at A

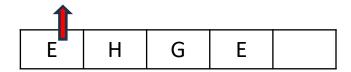


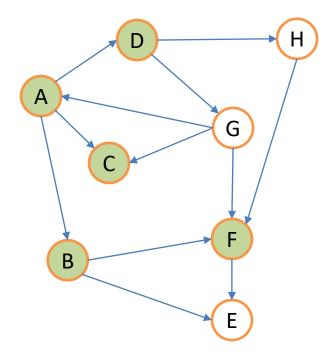


Traversal Order A B C D

Container: Queue

Start at A



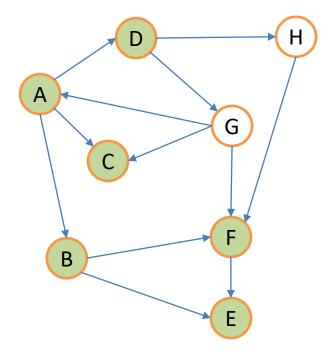


Traversal Order A B C D F

Container: Queue

Start at A



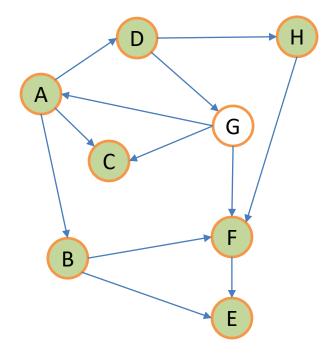


Traversal Order A B C D F E

Container: Queue

Start at A

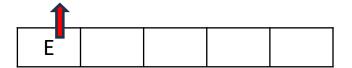


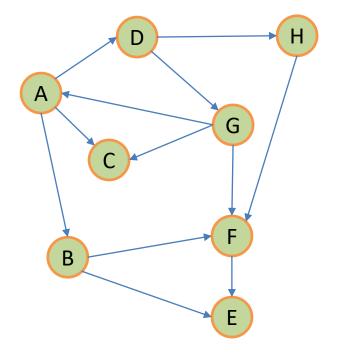


Traversal Order A B C D F E H

Container: Queue

Start at A



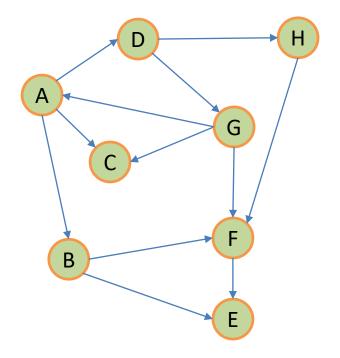


Traversal Order A B C D F E H G

Container: Queue

Start at A





Traversal Order A B C D F E H G

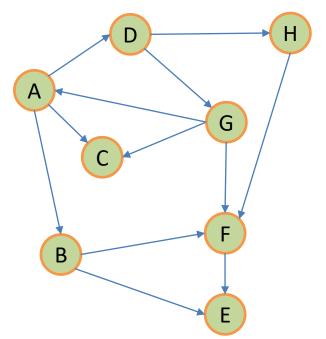
#### **Graph Traversals**

- Breath-first traversal
- Depth-first traversal
- Example 1: Starting at A
  - If C is a Stack, one order of traversal is:
    - A, D, H, F, E, G, C, B
    - Another traversal is: A, B, E, F, C, D, G, H
  - If C is a Queue, one order of traversal is:
    - A, B, C, D, E, F, G, H
    - Another traversal is: A, D, C, B, H, G, F, E

#### **Graph Traversals**

- Exercise: Starting at G
  - If C is a Stack, one order of traversal is:

- If C is a Queue, one order of traversal is:



#### **Notes**

- Depth-first: Descendants are visited before siblings.
  - To traverse depth-first, use a Stack.
- Breadth-first: siblings are visited before descendants.
  - To traverse breadth-first, use a Queue.
- For all vertices to be visited from any node, the graph must be strongly connected.
- For weakly connected graphs, you'd need to exhaustively traverse from every vertex.

```
for each vertex, v, in graph, G
    GraphSearch(G, v)
```