



Workflow Manuals

Computer Architecture

By

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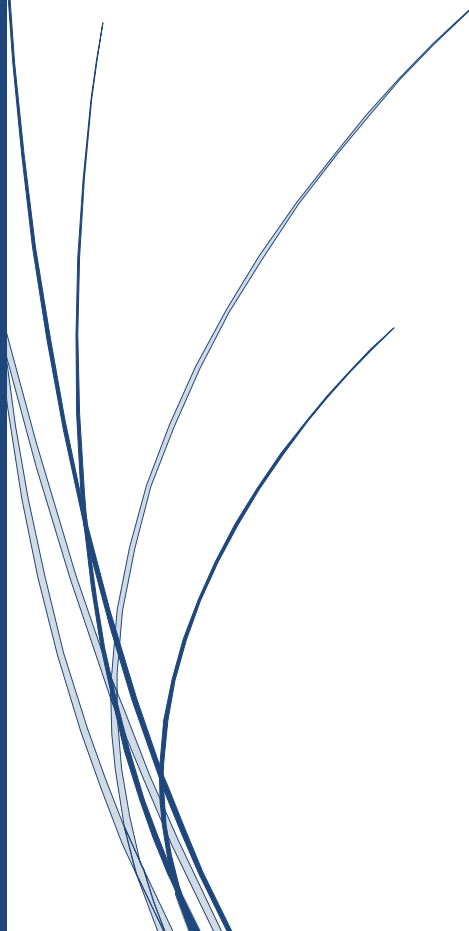


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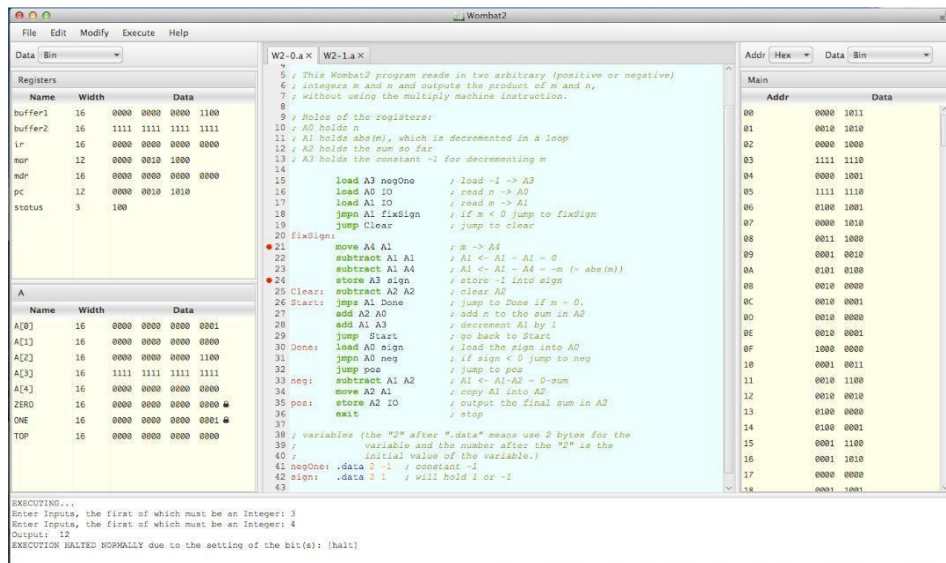
LAB 0749

LAB 0859

Tools & Technologies:

CPU Sim

CPU Sim is a tool used for simulating simple CPU architectures, helping students understand processor design, instruction execution, and debugging.



LAB 01

Introduction:

This lab introduces the fundamentals of CPU Sim, a simulation tool used to model basic CPU operations. Students will learn how to set up the software environment and explore key components of CPU architecture. By developing and testing simple assembly programs, they will gain hands-on experience in low-level programming. The lab also demonstrates the Fetch-Decode-Execute.

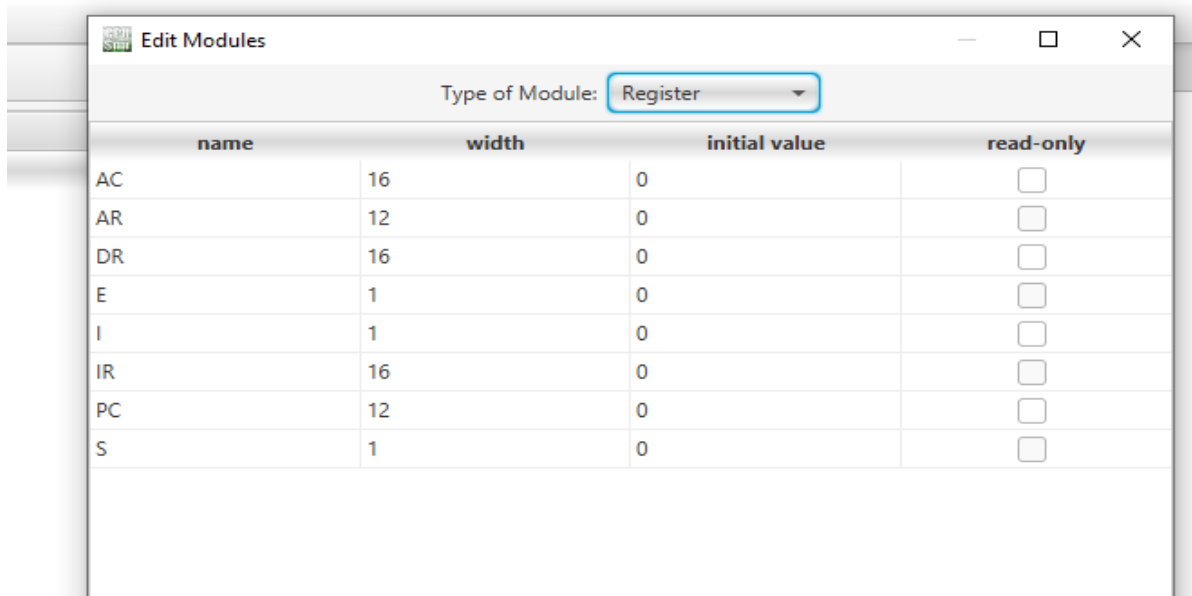
Registers used in CPU SIM

1. **Program Counter (PC)** – Stores the address of the next instruction (**12-bit**).
2. **Address Register (AR)** – Stores the memory address being accessed (**12-bit**).
3. **Instruction Register (IR)** – Holds the fetched instruction (**16-bit**).
4. **Accumulator Register (AC)** – Used for arithmetic operations (**16-bit**).
5. **Data Register (DR)** – Temporarily holds data being processed (**16-bit**).
6. **Temporary Register (TR)** – Optional register for intermediate calculations (**16-bit**).
7. **Condition Registers**
 - **E (Carry Bit)** – Used for carry operations.
 - **S (Status Register)** – Used for halt operations.
 - **I (Indexing Bit)** – Specifies direct or indirect addressing.

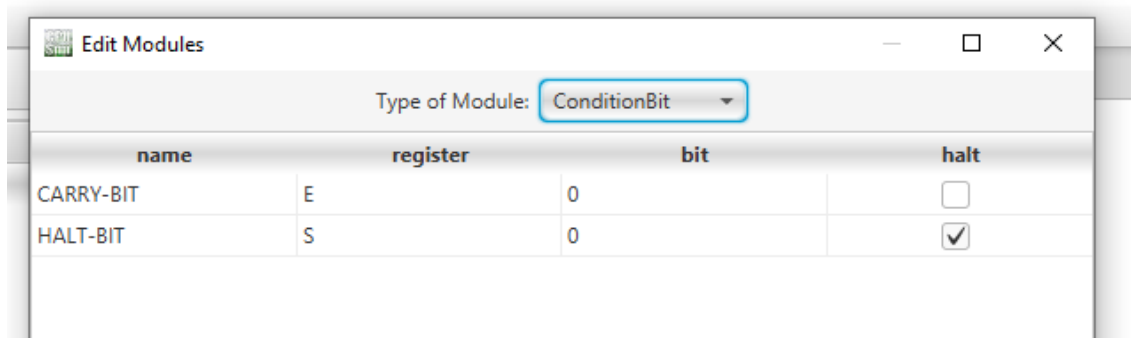
Registers											
IR		DR		AC		AR		PC		I	E
0	15	0	15	0	15	0	11	0	11	1 bit	1 Bit

Setting up the machine for CPU Sim

- Setting up the registers



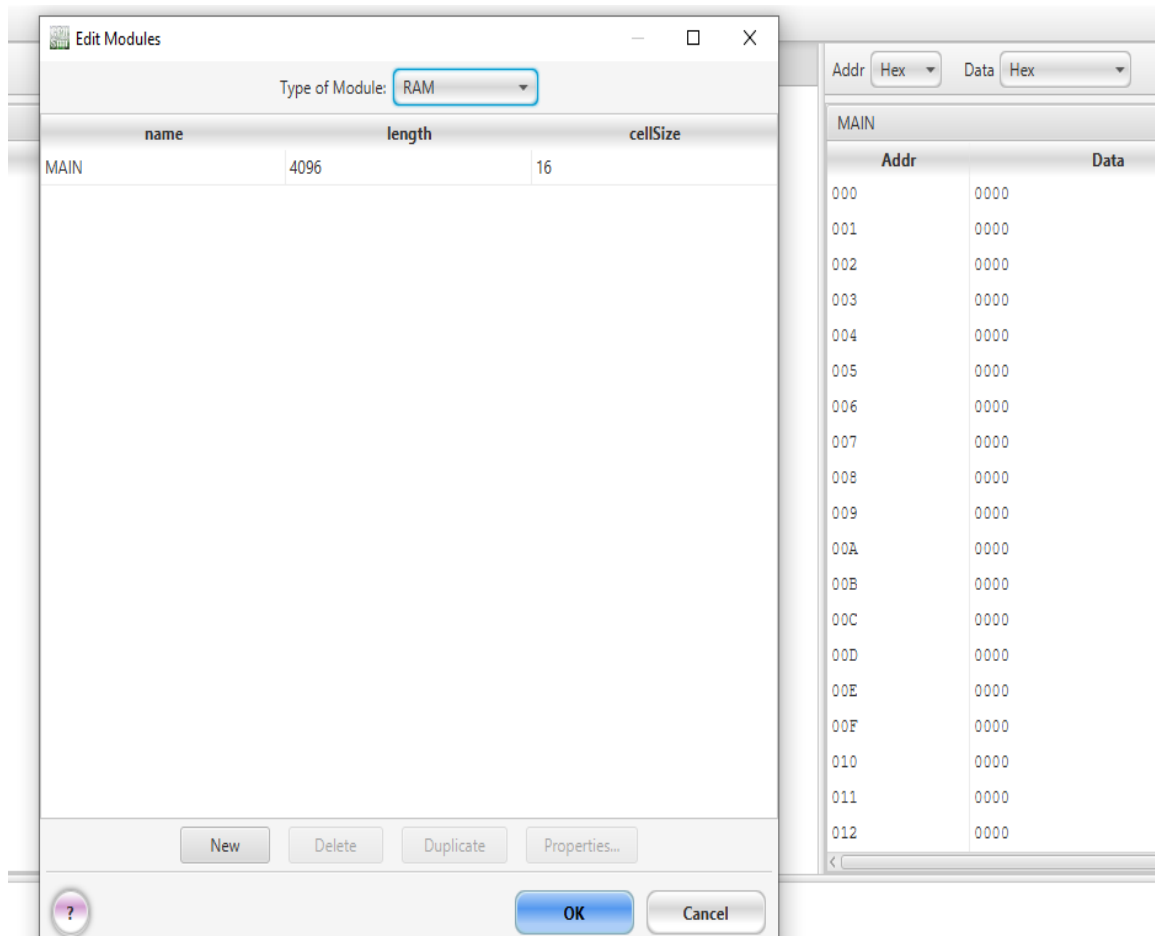
- Setting up condition registers



Setting up the memory

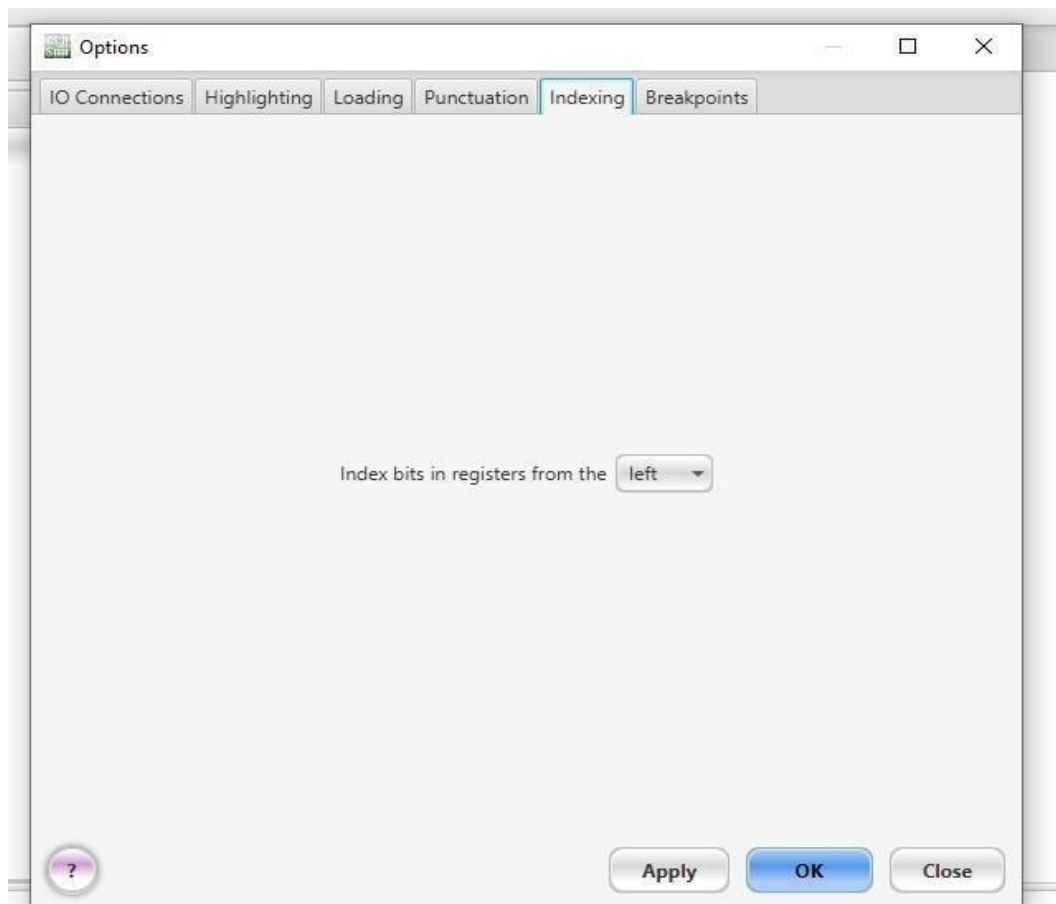
Open the **Hardware Module > Register > RAM**.

1. Create a new memory module:
 - **Size:** 4096 words
 - **Cell Size:** 16 bits
 - **Type:** RAM
2. Save the configuration with **.cpu** extension.



Setting up the indexing of instruction

1. Set the indexing from the left side.
2. Execute and then click on option and select indexing set it to left.

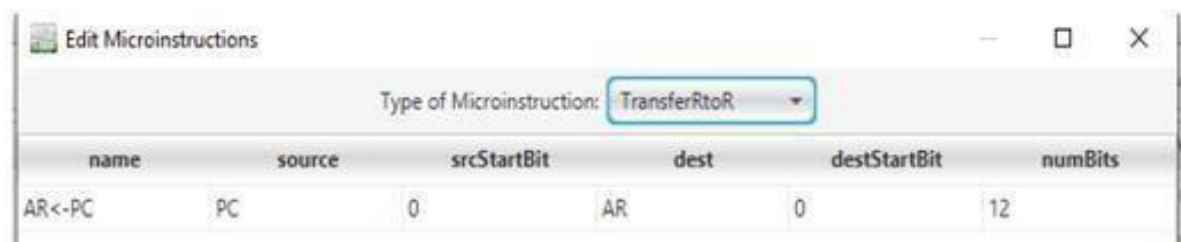


Fetch Cycle

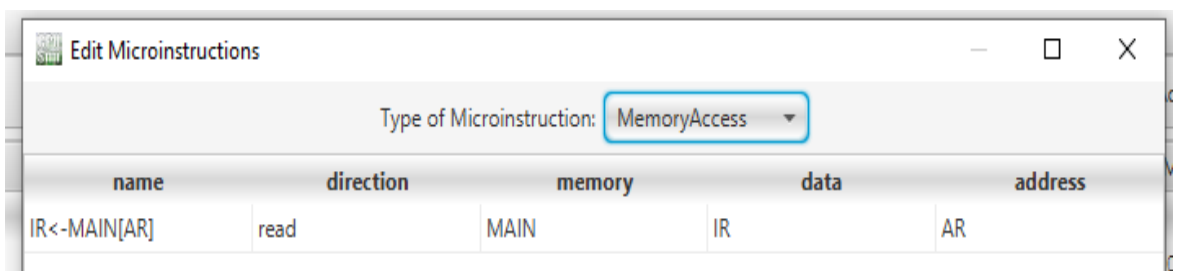
The Fetch Cycle involves the following steps:

1	AR <- PC
2	IR <- Main [AR]
3	PC - INCR
4	AR <- IR (4-15)
5	DECODE – IR

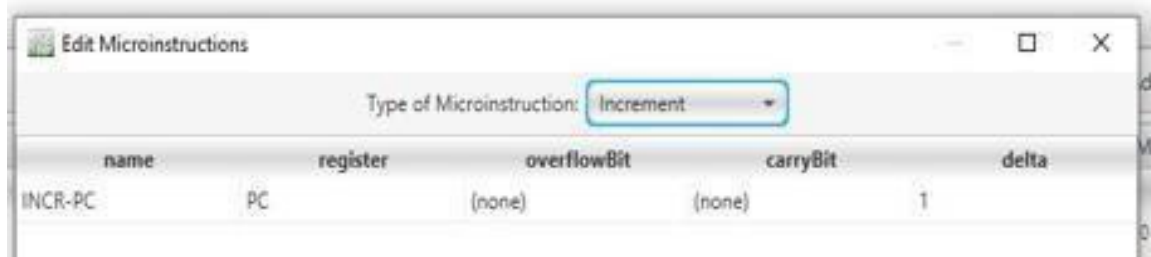
1. Transfer the address from **PC** to **AR**.



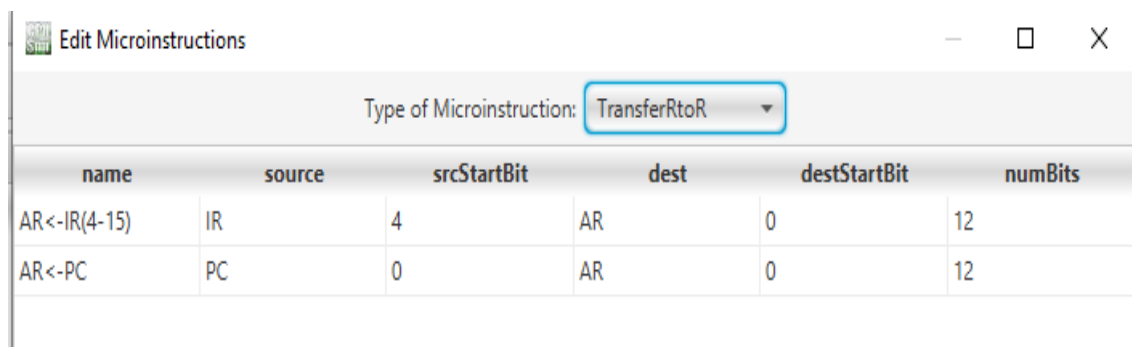
2. Read the instruction from memory into **IR**.



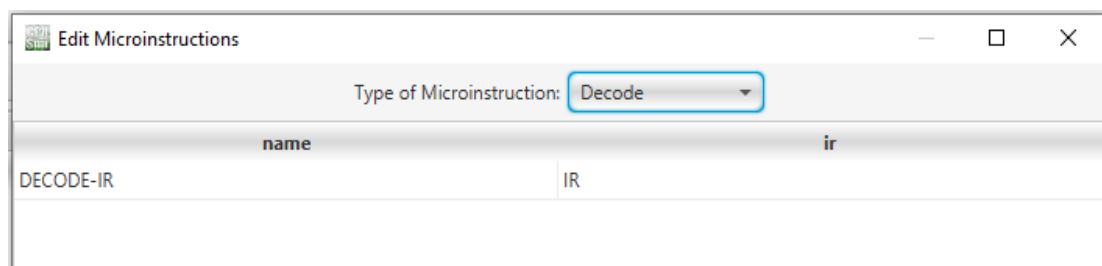
- Increment **PC** to point to the next instruction.



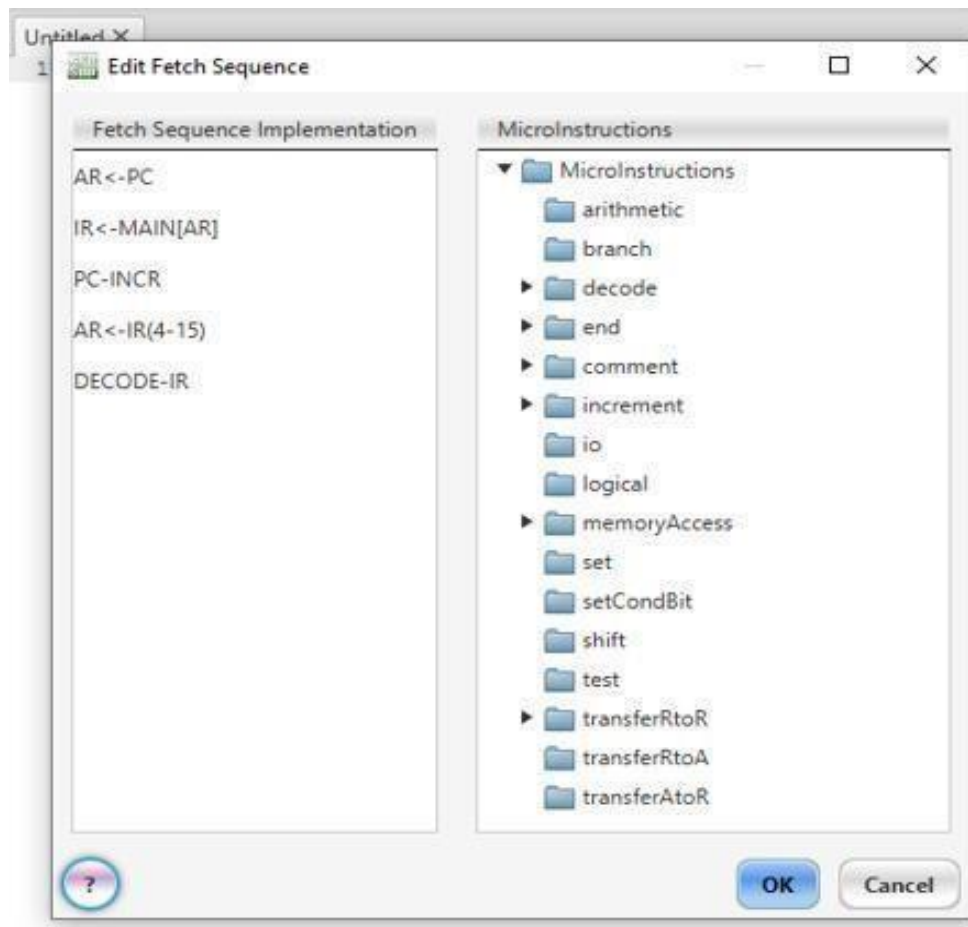
- Extract the address part of the instruction and transfer it to **AR**.



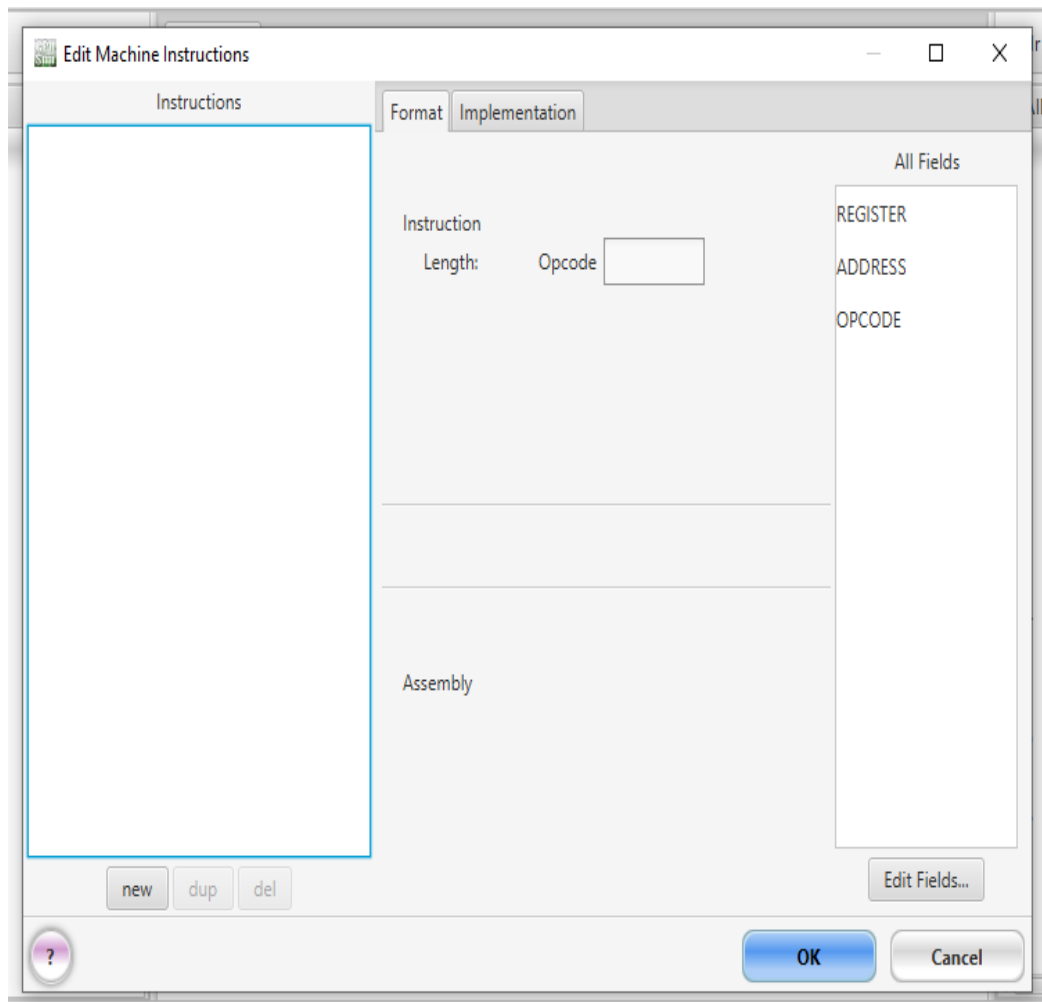
- Decode the instruction for execution.



Fetch Execution



Edit machine Instructions



LAB 02

Introduction:

This lab focuses on understanding machine instructions and their critical role in the execution process. Students will explore instruction formats, including fields like opcodes and operands. The step-by-step execution of microinstructions will be demonstrated to show how control flows within the CPU. A practical task of adding two numbers using basic instructions will reinforce these core concepts

Program

```
1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 INP      ; Input another value
5 ADD NUM  ; Add the value stored in "NUM" to the accumulator
6 OUT      ; Output the result
7 HLT      ; Halt execution
8 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
```

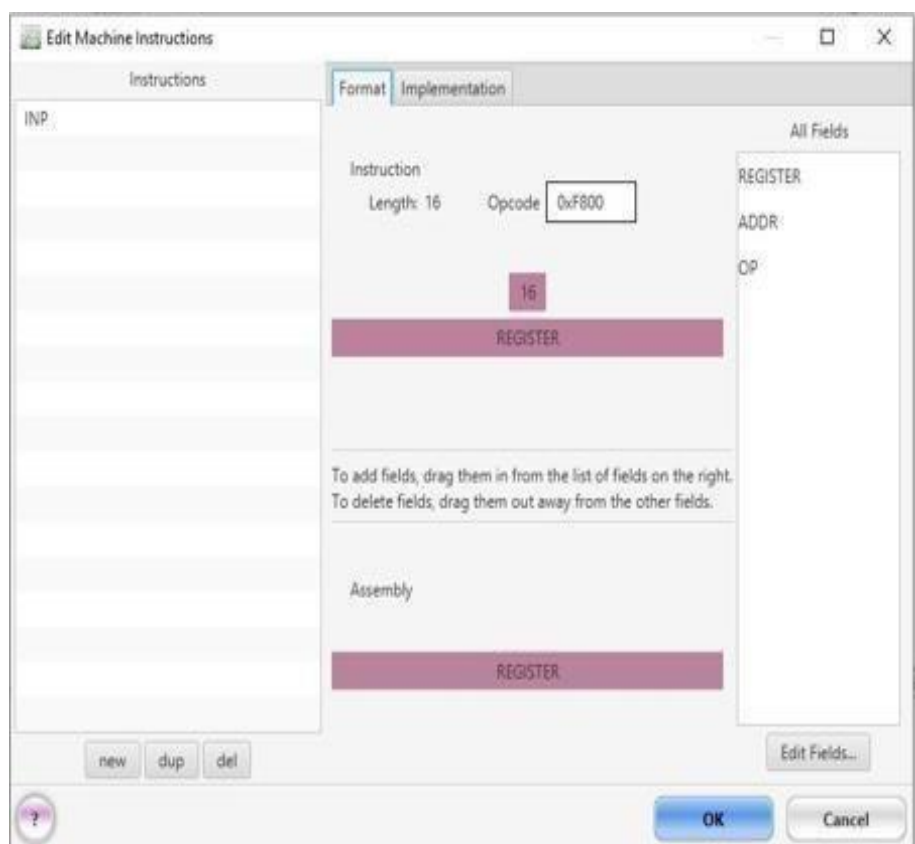
Edit machine instructions

1. First make a instructions for **INP**

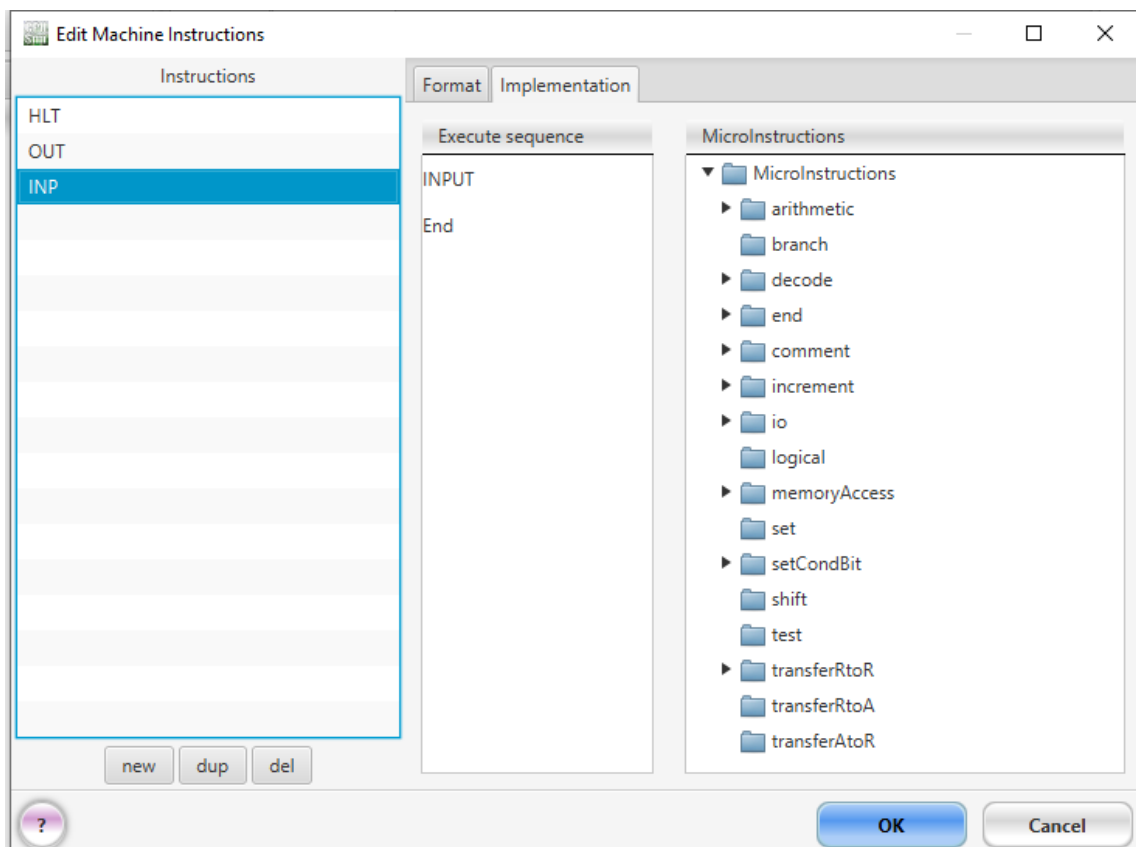
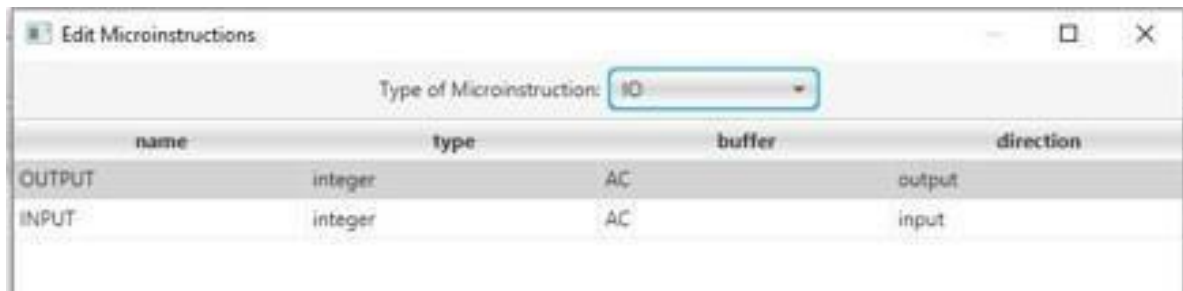
First make a format of instruction by adding opcode according to given address.

Input

OPCODE: F800

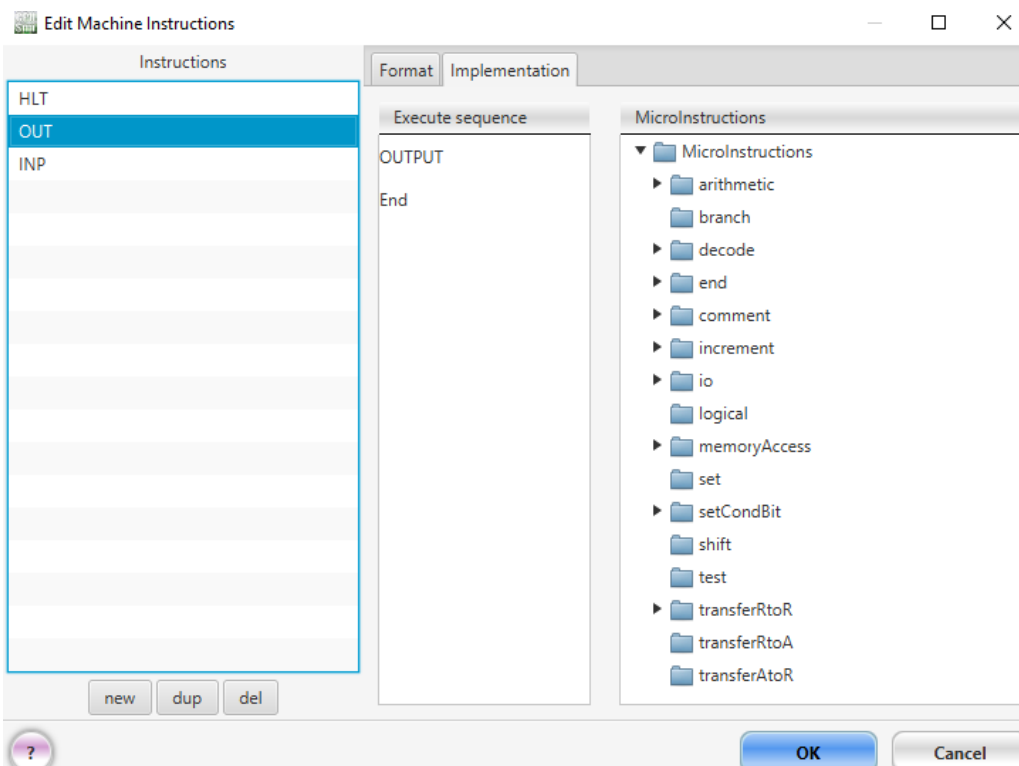
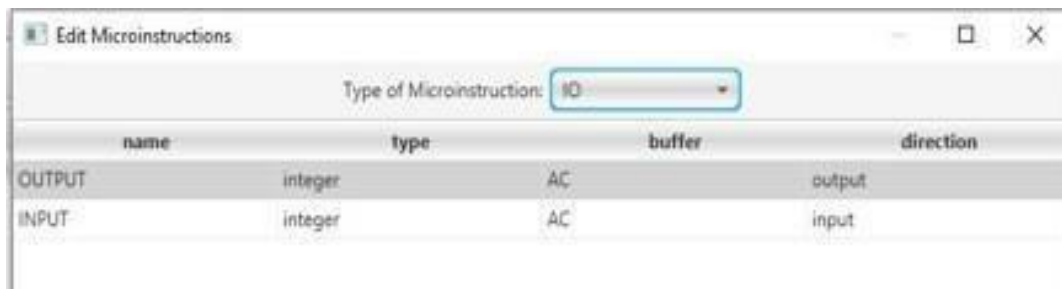
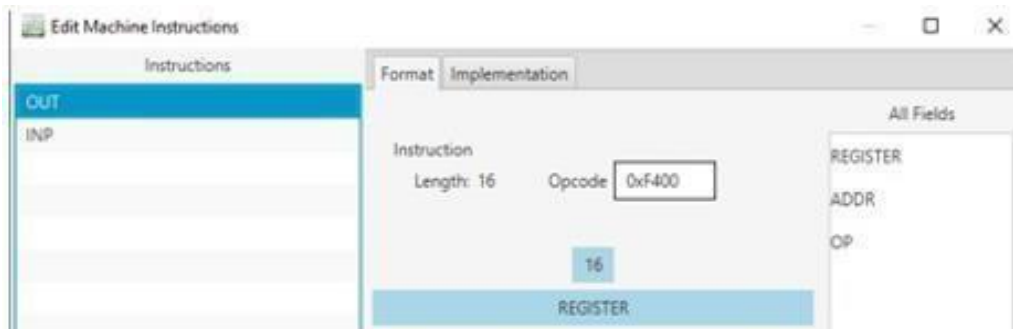


2. Second make a instructions for Microinstructions for input and set buffer.



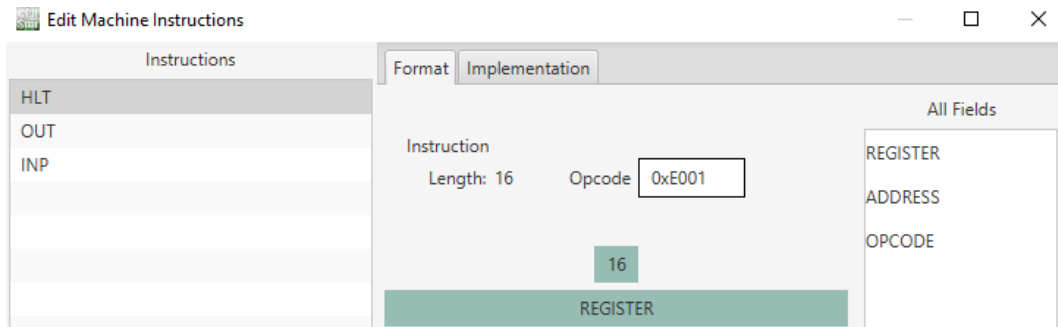
Output

OPCODE: F400

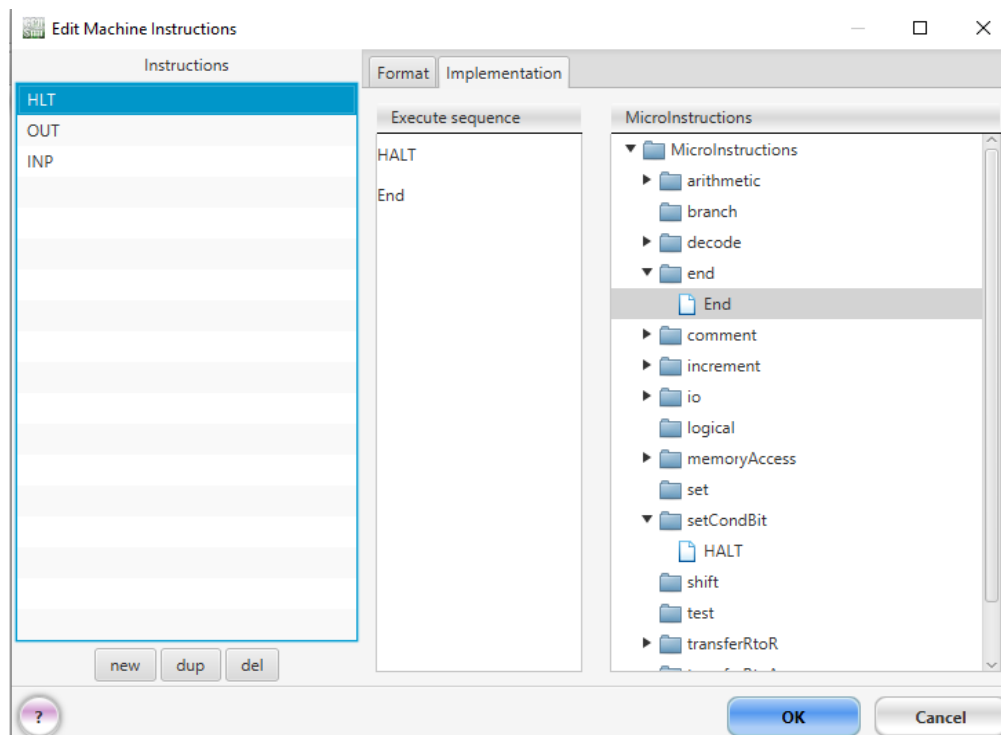


Halt

OPCODE: E001

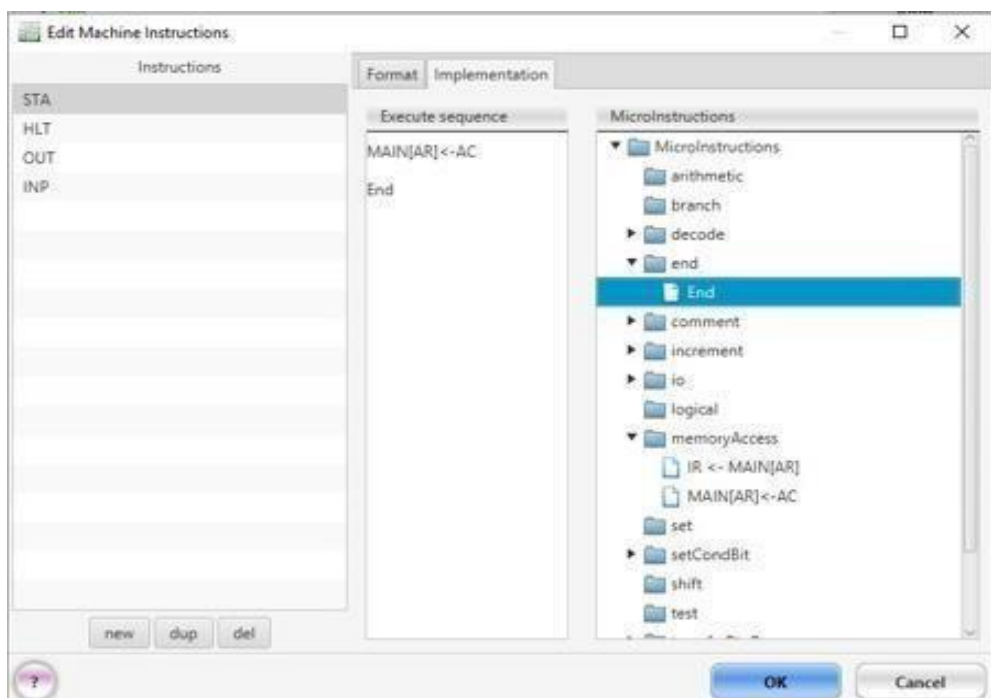
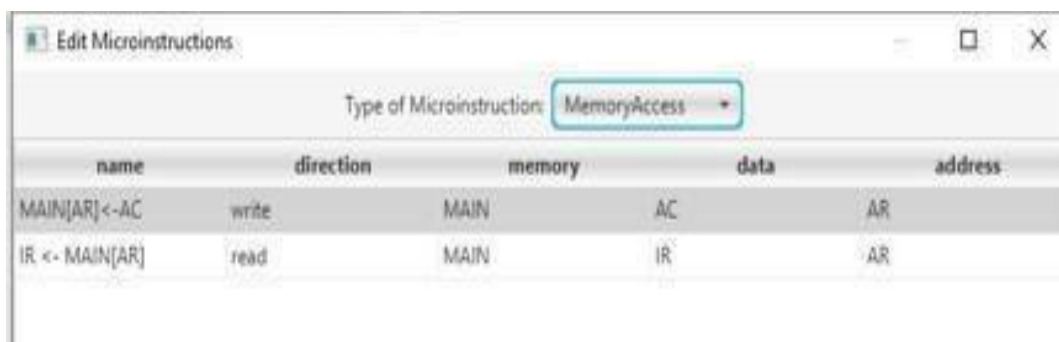


Set condition bit, for halt that is S



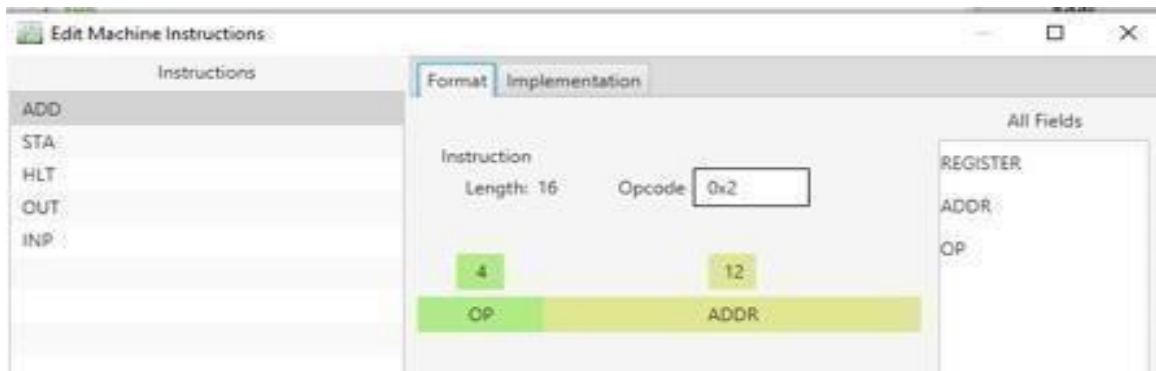
STA

OPCODE: 6



ADD

OPCODE: 2

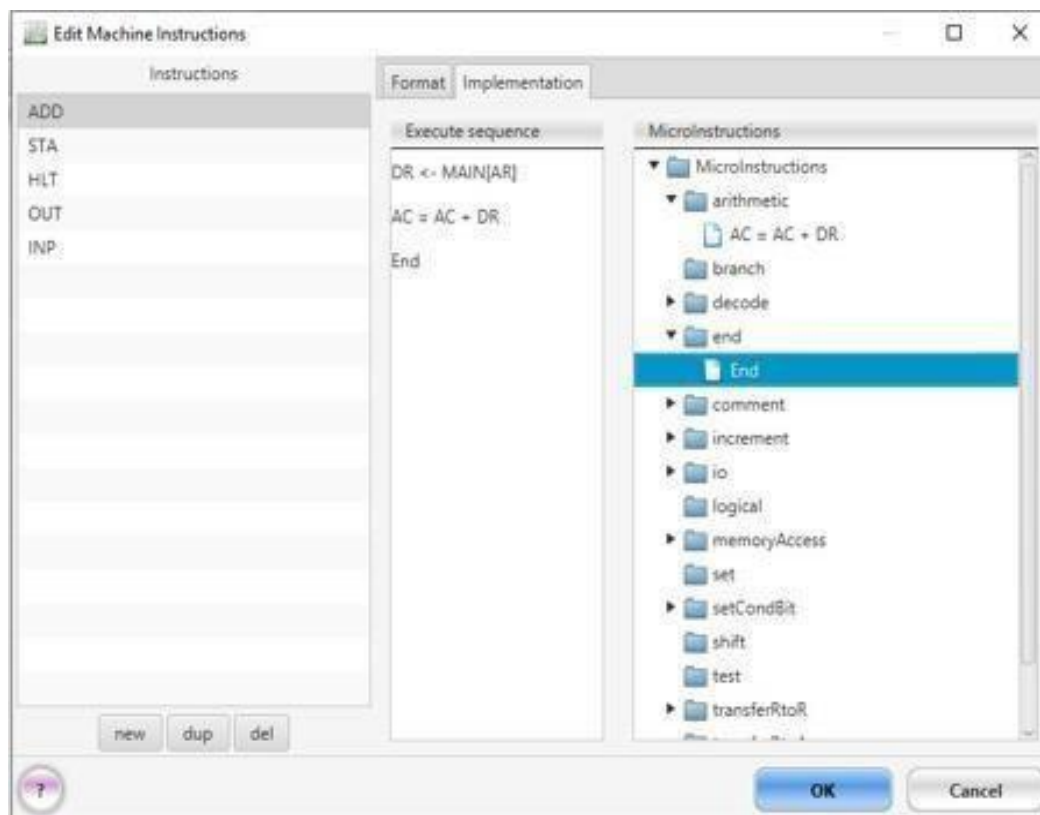


The 'Edit Microinstructions' window shows the 'MemoryAccess' type. The table below lists the microinstructions for this type.

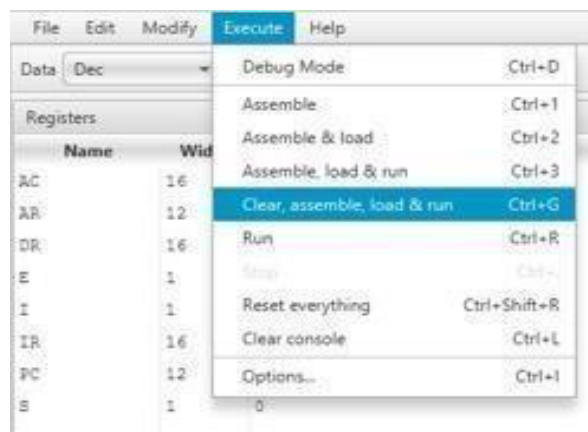
name	direction	memory	data	address
DR <- MAIN[AR]	read	MAIN	DR	AR
IR <- MAIN[AR]	read	MAIN	IR	AR
MAIN[AR] <- AC	write	MAIN	AC	AR

The 'Edit Microinstructions' window shows the 'Arithmetic' type. The table below lists the microinstructions for this type.

name	type	source1	source2	destination	overflowBit	carryBit
AC <- AC + DR	ADD	AC	DR	AC	(none)	CARRY-BIT



3. Execute the instructions



4. Enter inputs of numbers

```
EXECUTING...  
Enter Inputs, the first of which must be an Integer: 3  
Enter Inputs, the first of which must be an Integer: 4  
Output: 7  
EXECUTION HALTED NORMALLY due to the setting of the bit(s): [HALT-BIT]
```

LAB 03

Introduction:

This lab explores subtraction in low-level programming using the Two's Complement method. Students will perform bitwise operations to carry out subtraction and understand its underlying logic. The step-by-step execution of subtraction instructions in assembly will be analyzed. Through hands-on practice, learners will strengthen their grasp of arithmetic operations at the machine level.

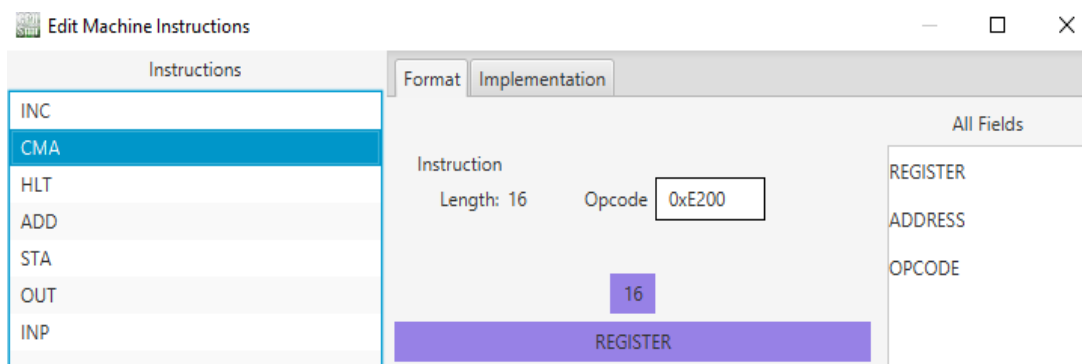
Program

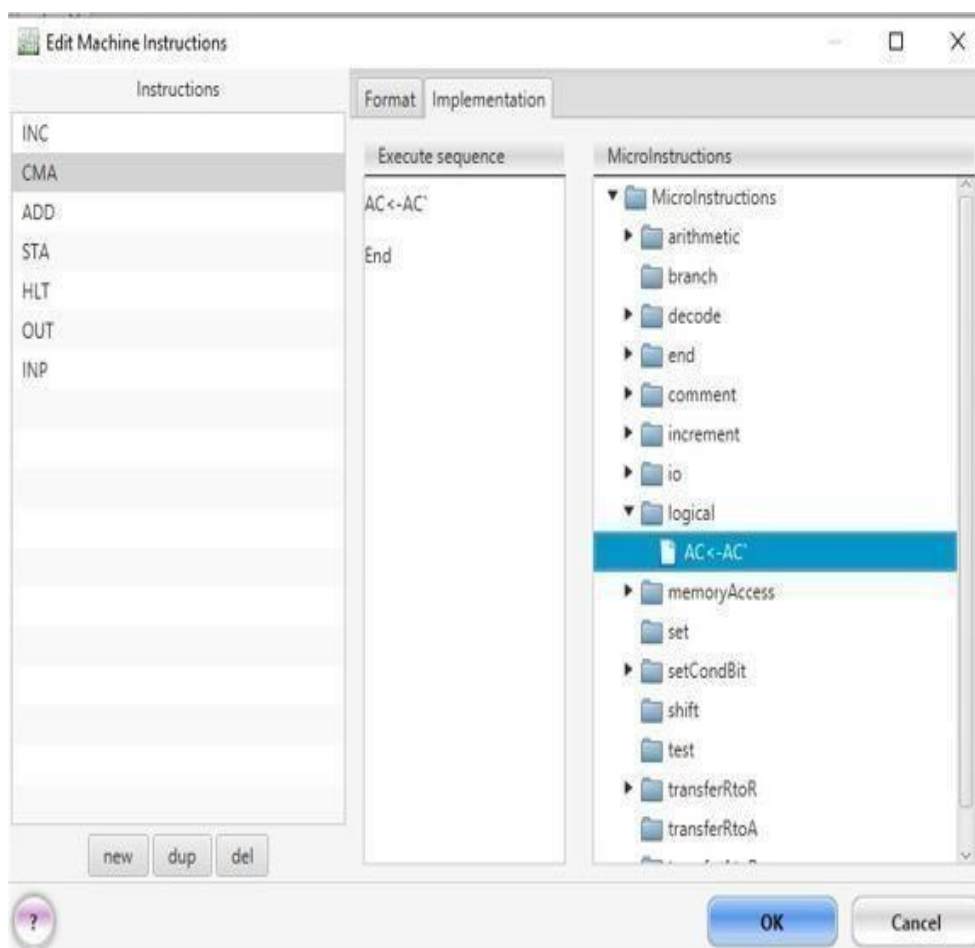
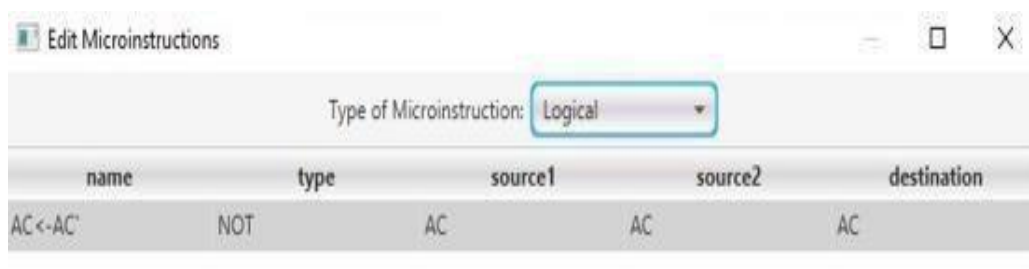
```
1 START:
2 INP
3 STA NUM
4 INP
5 CMA      ;Complement (invert) all bits of the second input
6          ;(Two's complement preparation for subtraction)
7
8 INC      ; Add 1 to the complemented value (
9          ;Completing Two's complement to get negative of the second input)
10
11 ADD NUM  ; Add the stored first input (NUM) with the negated second input
12          ;(Effectively performing subtraction: First Input - Second Input)
13 OUT
14 HLT
15 NUM: .data 1 0
16
```

Edit machine instructions

1. CMA instruction:

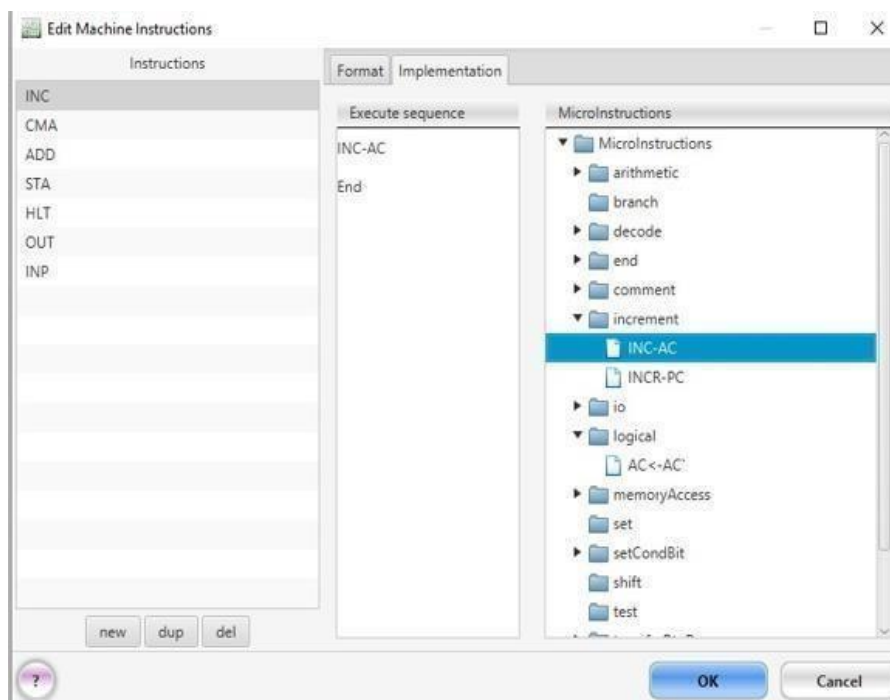
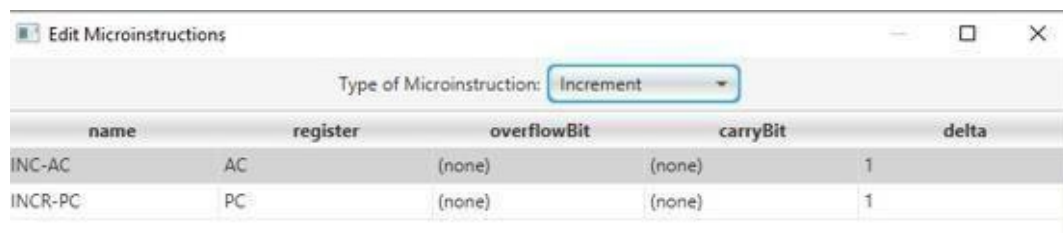
- Set the **Opcode** for CMA as **E200**.
- Set it as a **Register Instruction**.
- Go to **Implementation** and select **Logical Instruction** with the operation $AC \leftarrow AC'$.



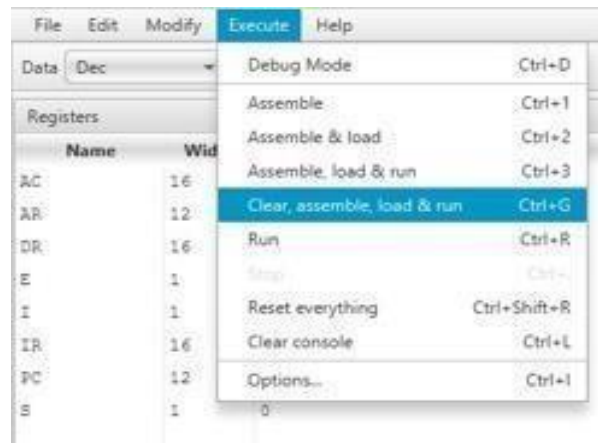


2. INC instruction:

- Set the **Opcode** for INC as **E020**.
- Set it as a **Register Instruction**.
- Select **Increment Instruction** with operation $AC \leftarrow AC + 1$.



3. Execute the instructions



4. Enter inputs of numbers

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 3
Enter Inputs, the first of which must be an Integer: 5
Output: -2
EXECUTION HALTED NORMALLY due to the setting of the bit(s): [HALT-BIT]
```

LAB 04

Introduction:

This lab introduces the use of fundamental bitwise operators essential in digital logic and low-level programming. Students will perform operations using AND, OR, NOT, NAND, NOR, and XOR to manipulate binary data. Each operator's behavior will be explored through practical examples and simulations. This hands-on approach enhances understanding of how binary logic supports system operations.

Bitwise AND

```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 INP      ; Input another value
5 AND NUM  ; use logical shift AND operator
6 OUT      ; Output the result
7 HLT      ; Halt execution
8 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
9

```

1. AND instruction:

- Set the **Opcode** for AND as **0**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **Logical Instruction** with the operation

$$AC \leftarrow AC \wedge DR$$

- **Accumulator (AC) and a memory location (M).**
- **Define a Sequence Instruction for execution**

name	type	source1	source2	destination
AC ← AC ∧ DR	AND	AC	DR	AC

Edit Microinstructions

Type of Microinstruction: **MemoryAccess**

name	direction	memory	data	address
DR<-MAIN[AR]	read	MAIN	DR	AR
IR<-MAIN[AR]	read	MAIN	IR	AR
MAIN[AR]<-AC	write	MAIN	AC	AR

Edit Machine Instructions

Instructions

Format Implementation

Execute sequence

DR<-MAIN[AR]

AC<-AC^DR

End

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

new dup del

OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 1
Enter Inputs, the first of which must be an Integer: 1
Output: 1
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

Bitwise OR

```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 INP      ; Input another value
5 OR NUM   ; use logical shift OR operator
6 OUT      ; Output the result
7 HLT      ; Halt execution
8 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
9

```

2. OR instruction:

- Set the **Opcode** for OR as **0**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **Logical Instruction** with the operation

$AC \leftarrow AC \wedge DR$

- **Accumulator (AC) and a memory location (M).**
- **Define a Sequence Instruction for execution.**

name	type	source1	source2	destination
AC←-AC^DR	OR	AC	DR	AC

Edit Microinstructions

Type of Microinstruction: MemoryAccess

name	direction	memory	data	address
DR<-MAIN[AR]	read	MAIN	DR	AR
IR<-MAIN[AR]	read	MAIN	IR	AR
MAIN[AR]<-AC	write	MAIN	AC	AR

Edit Machine Instructions

Instructions

- OR
- HLT
- STA
- OUT
- INP

new dup del

Format Implementation

Execute sequence

```
DR<-MAIN[AR]
AC<-AC^DR
End
```

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess**
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

?

OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 0
Enter Inputs, the first of which must be an Integer: 1
Output: 1
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

Bitwise NOT

```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 NOT NUM  ; use logical shift NOT operator
5 OUT      ; Output the result
6 HLT      ; Halt execution
7 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
8

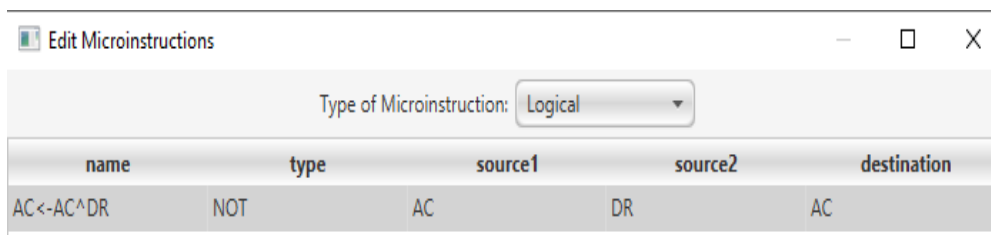
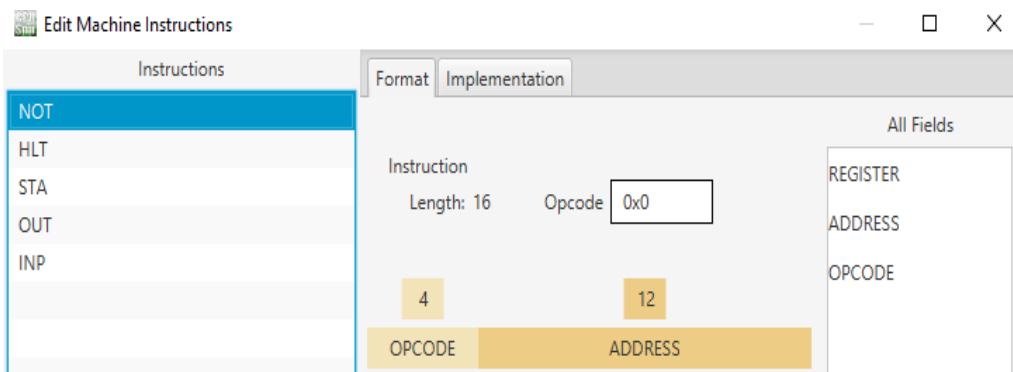
```

3. NOT instruction:

- Set the **Opcode** for NOT as **0**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **Logical Instruction** with the operation

AC<-AC^DR

- **Accumulator (AC) and a memory location (M).**
- **Define a Sequence Instruction for execution**



Edit Microinstructions

Type of Microinstruction: MemoryAccess

name	direction	memory	data	address
DR<-MAIN[AR]	read	MAIN	DR	AR
IR<-MAIN[AR]	read	MAIN	IR	AR
MAIN[AR]<-AC	write	MAIN	AC	AR

Edit Machine Instructions

Instructions

NOT

HLT

STA

OUT

INP

new dup del

Format Implementation

Execute sequence

DR<-MAIN[AR]

AC<-AC^DR

End

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess**
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

? OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 1
Output: -2
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

NAND Operator

```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 INP      ; Input another value
5 NAND NUM ; use logical shift NAND operator
6 OUT      ; Output the result
7 HLT      ; Halt execution
8 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
9

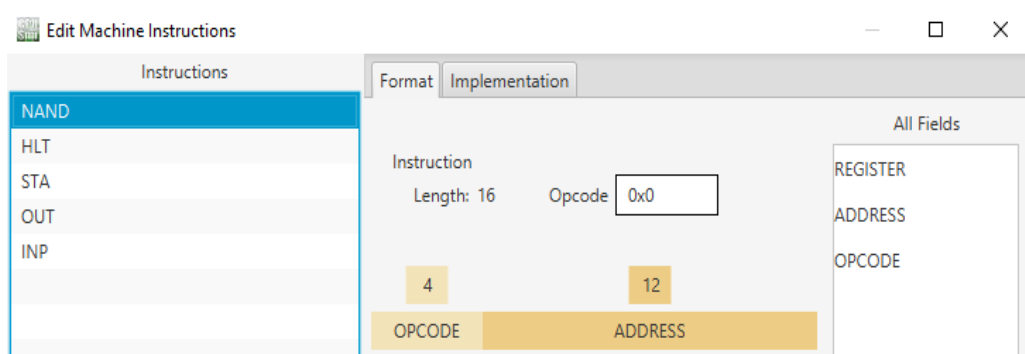
```

4. NAND instruction:

- Set the **Opcode** for NAND as **0**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **Logical Instruction** with the operation

AC<-AC^DR

- **Accumulator (AC) and a memory location (M).**
- **Define a Sequence Instruction for execution.**



Edit Microinstructions				
Type of Microinstruction: Logical				
name	type	source1	source2	destination
AC<-AC^DR	NAND	AC	DR	AC

Edit Microinstructions

Type of Microinstruction: MemoryAccess

name	direction	memory	data	address
DR<-MAIN[AR]	read	MAIN	DR	AR
IR<-MAIN[AR]	read	MAIN	IR	AR
MAIN[AR]<-AC	write	MAIN	AC	AR

Edit Machine Instructions

Instructions

NAND

HLT

STA

OUT

INP

new dup del

Format Implementation

Execute sequence

DR<-MAIN[AR]

AC<-AC^DR

End

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 3
Enter Inputs, the first of which must be an Integer: 2
Output: -3
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

NOR Operator

```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 INP      ; Input another value
5 NOR NUM  ; use logical shift NOR operator
6 OUT      ; Output the result
7 HLT      ; Halt execution
8 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
9

```

5. NOR instruction:

- Set the **Opcode** for NOR as **0**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **Logical Instruction** with the operation

AC<-AC^DR

- **Accumulator (AC) and a memory location (M).**
- **Define a Sequence Instruction for execution.**

name	type	source1	source2	destination
AC<-AC^DR	NOR	AC	DR	AC

Edit Microinstructions

Type of Microinstruction: MemoryAccess

name	direction	memory	data	address
DR<-MAIN[AR]	read	MAIN	DR	AR
IR<-MAIN[AR]	read	MAIN	IR	AR
MAIN[AR]<-AC	write	MAIN	AC	AR

Edit Machine Instructions

Instructions

NOR

HLT

STA

OUT

INP

new dup del

Format Implementation

Execute sequence

DR<-MAIN[AR]

AC<-AC^DR

End

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 7
Enter Inputs, the first of which must be an Integer: 5
Output: -8
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

XOR Operator

```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 INP      ; Input another value
5 XOR NUM  ; use logical shift XOR operator
6 OUT      ; Output the result
7 HLT      ; Halt execution
8 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
9

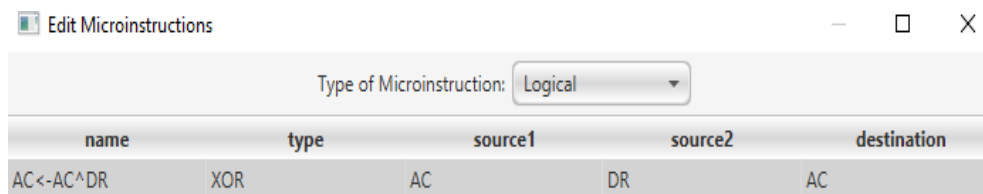
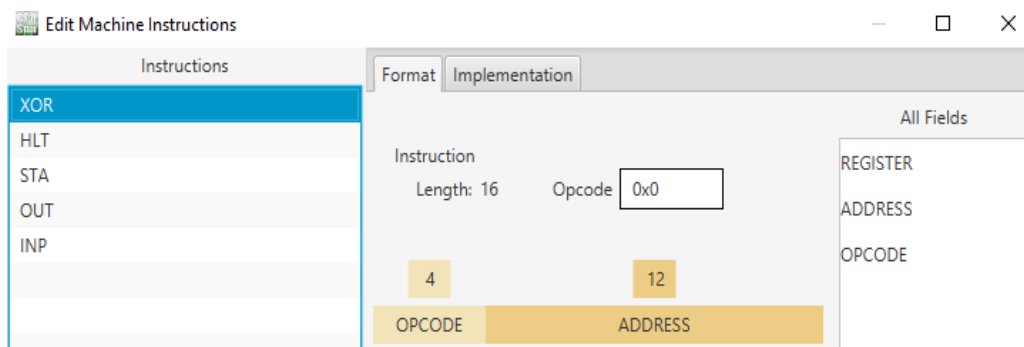
```

6. XOR instruction:

- Set the **Opcode** for XOR as **0**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **Logical Instruction** with the operation

$AC \leftarrow AC \wedge DR$

- **Accumulator (AC) and a memory location (M).**
- **Define a Sequence Instruction for execution**



Edit Microinstructions

Type of Microinstruction:
MemoryAccess

name	direction	memory	data	address
DR<-MAIN[AR]	read	MAIN	DR	AR
IR<-MAIN[AR]	read	MAIN	IR	AR
MAIN[AR]<-AC	write	MAIN	AC	AR

Edit Machine Instructions

Instructions

Format
Implementation

Execute sequence

DR<-MAIN[AR]
AC<-AC^DR
End

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

new dup del

?

OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 7
Enter Inputs, the first of which must be an Integer: 5
Output: 2
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

LAB 05

Introduction:

This lab focuses on implementing multiplication using basic assembly instructions. Students will learn how to take user input, store it in memory with the STA instruction, and retrieve it using LDA. The use of the BUN instruction will demonstrate control flow by jumping to specified memory locations. Through these exercises, learners will deepen their understanding of data handling.

Multiplication

```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 INP      ; Input another value
5 MUL NUM  ; multiply the value stored in "NUM" to the accumulator
6 OUT      ; Output the result
7 HLT      ; Halt execution
8 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
9

```

1. MUL instruction:

- Set the **Opcode** for MUL as **2**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **Arithmetic Instruction** with the operation
 $AC \leftarrow AC * DR$
- **Accumulator (AC) and a memory location (M).**
- **Define a Sequence Instruction for execution**

name	type	source1	source2	destination	overflowBit	carryBit
AC ← AC * DR	MULTIPLY	AC	DR	AC	(none)	CARRY-BIT

Edit Microinstructions

Type of Microinstruction: MemoryAccess

name	direction	memory	data	address
DR<-MAIN[AR]	read	MAIN	DR	AR
IR<-MAIN[AR]	read	MAIN	IR	AR
MAIN[AR]<-AC	write	MAIN	AC	AR

Edit Machine Instructions

Instructions

- HLT
- MUL
- STA
- OUT
- INP

new dup del

Format Implementation

Execute sequence

```
DR<-MAIN[AR]
AC<-AC * DR
End
```

MicroInstructions

- MicroInstructions
 - arithmetic
 - AC<-AC * DR
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA

OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 2
Enter Inputs, the first of which must be an Integer: 3
Output: 6
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

LDA

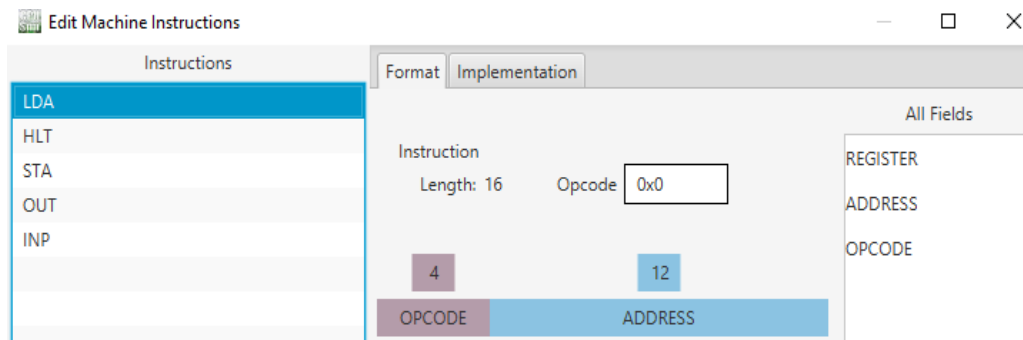
```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 LDA NUM  ;
5 OUT      ; Output the result
6 HLT      ; Halt execution
7 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
8

```

2. LDA instruction:

- Set the **Opcode** for LDA as **0**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **transferRtoR Instruction** with the operation **AC<-DR**
- **Accumulator (AC) and a memory location (M).**
- **Define a Sequence Instruction for execution.**



Edit Microinstructions						
Type of Microinstruction: TransferRtoR						
name	source	srcStartBit	dest	destStartBit	numBits	
AC<-DR	DR	0	AC	0	0	

Edit Microinstructions

Type of Microinstruction: MemoryAccess

name	direction	memory	data	address
DR<-MAIN[AR]	read	MAIN	DR	AR
IR<-MAIN[AR]	read	MAIN	IR	AR
MAIN[AR]<-AC	write	MAIN	AC	AR

Edit Machine Instructions

Instructions

- LDA
- HLT
- STA
- OUT
- INP

new dup del

Format Implementation

Execute sequence

```

MAIN[AR]<-AC
DR<-MAIN[AR]
AC<-DR
End

```

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

OK Cancel

Result

```

EXECUTING...
Enter Inputs, the first of which must be an Integer: 3
Output: 3
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.

```

Branch (BUN)

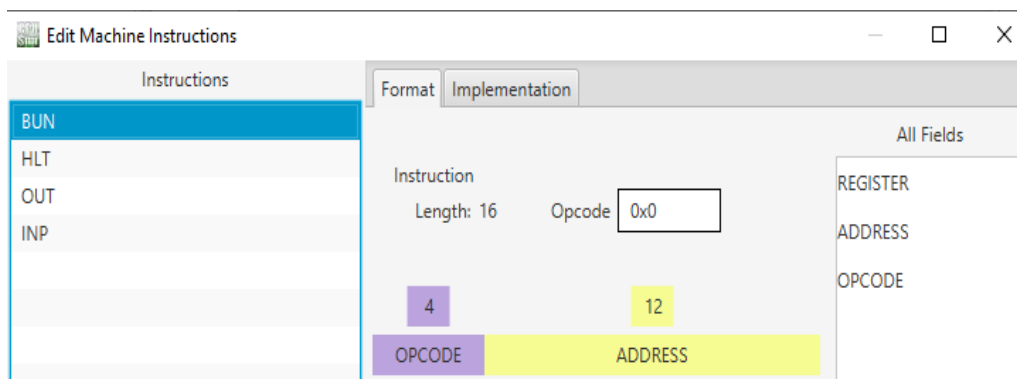
```

1 START:
2 INP      ; Input a value and store it in the accumulator
3 BUN K    ; jump to K block
4 INP
5 K: OUT    ; Output the result
6 HLT      ; Halt execution
7 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
8

```

3. BUN instruction:

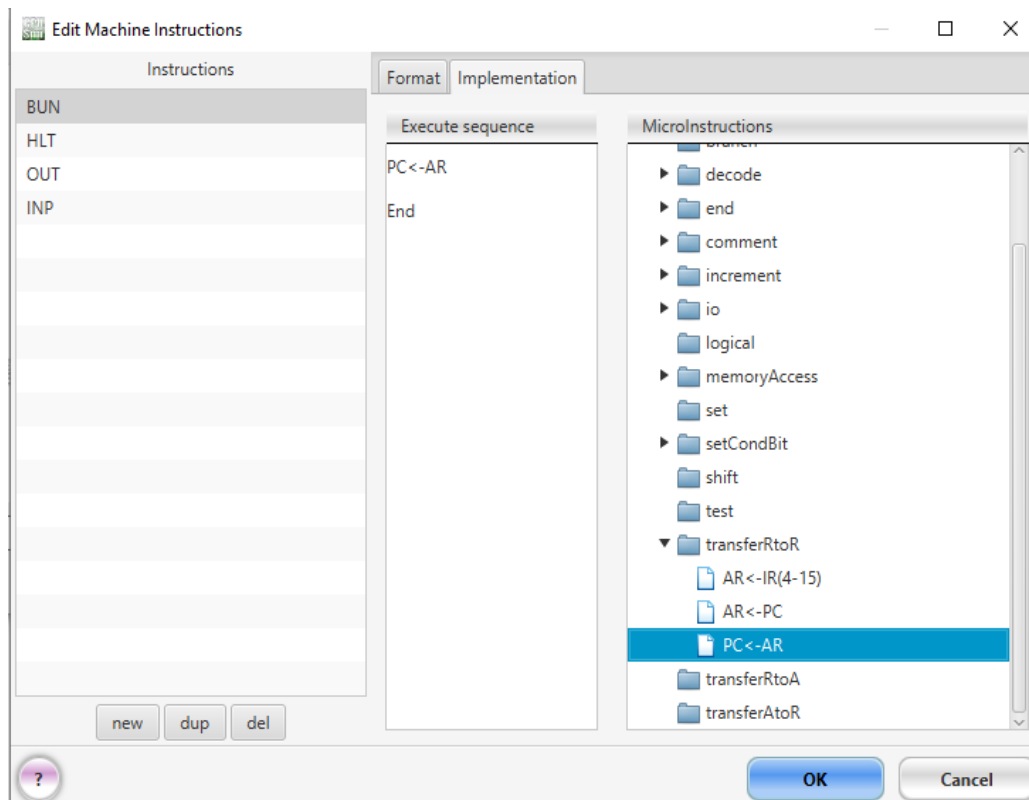
- It jumps to another part of the program without any condition.
- Set the **Opcode** for BUN as **0**.
- Set it as **opcode** and **address**.
- Go to **Implementation** and select **transferRtoR Instruction** with the operation **PC<-AR**
- **Define a Sequence Instruction for execution**



Edit Microinstructions

Type of Microinstruction: TransferRtoR

name	source	srcStartBit	dest	destStartBit	numBits
AR<-IR(4-15)	IR	4	AR	0	12
AR<-PC	PC	0	AR	0	12
PC<-AR	AR	0	PC	0	0



Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 2
Output: 2
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

LAB 06

Introduction:

This lab introduces the Increment and Skip if Zero (ISZ) instruction used in assembly language programming. Students will explore how ISZ operates by incrementing a memory value and conditionally skipping the next instruction. The lab highlights its usefulness in loop control and conditional execution. Through these, learners will gain insight into efficient low-level program design.

ISZ (Increment and Skip if Zero) Operation

The **ISZ (Increment and Skip if Zero)** instruction increments the value stored at a specified memory location. If the result after incrementing is **zero**, the next instruction in the program is **skipped**.

Program

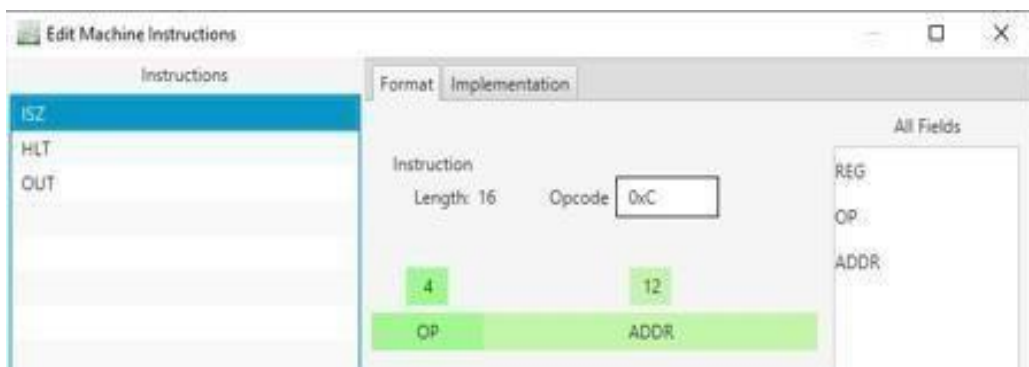
```
1 START:
2 ISZ 008
3 OUT
4 HLT
5 NUM: .data 1 0
6
```

Step-by-Step Execution:

1. **ISZ 009 (Increment and Skip if Zero)**
 - Reads the value stored at memory location 009.
 - Increments it by 1.
 - If the new value becomes 0, it skips the next instruction (OUT).
 - Otherwise, it proceeds to the next instruction.
2. **OUT (Output the value in AC)**
 - If ISZ does not skip, this instruction executes.
 - Outputs the value in the accumulator (AC) to the display/output device.
3. **HLT (Halt Execution)**
 - Stops program execution.

Machine instructions

- **Set the upcode and format.**



- **Fetch the value from memory (Address Register - AR) into Data Register (DR).**

The screenshot shows the 'Edit Microinstructions' window. At the top, 'Type of Microinstruction' is set to 'MemoryAccess'. Below is a table with the following data:

name	direction	memory	data	address
DR ← MAIN[AR]	read	MAIN	DR	AR
IR ← MAIN[AR]	read	MAIN	IR	AR
MAIN[AR] ← AC	write	MAIN	AC	AR
MAIN[DR] ← AR	write	MAIN	DR	AR

- **Increment the value in DR.**

Edit Microinstructions

Type of Microinstruction: MemoryAccess

name	direction	memory	data	address
DR ← MAIN[AR]	read	MAIN	DR	AR
IR ← MAIN[AR]	read	MAIN	IR	AR
MAIN[AR] ← AC	write	MAIN	AC	AR
MAIN[DR] ← AR	write	MAIN	DR	AR

- **Store the updated value back into memory.**

Edit Microinstructions

Type of Microinstruction: MemoryAccess

name	direction	memory	data	address
DR ← MAIN[AR]	read	MAIN	DR	AR
IR ← MAIN[AR]	read	MAIN	IR	AR
MAIN[AR] ← AC	write	MAIN	AC	AR
MAIN[DR] ← AR	write	MAIN	DR	AR

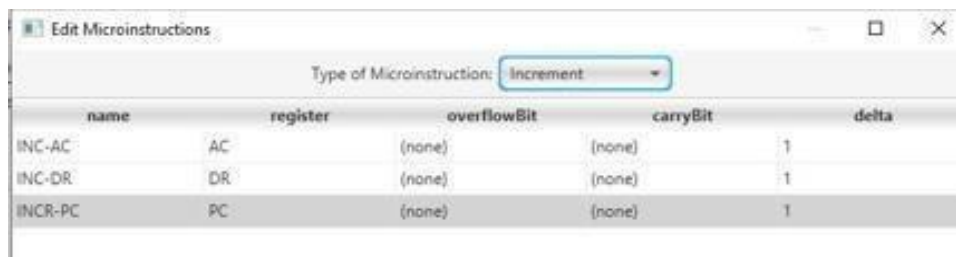
- **Check if the new value in DR is zero.**

Edit Microinstructions

Type of Microinstruction: Test

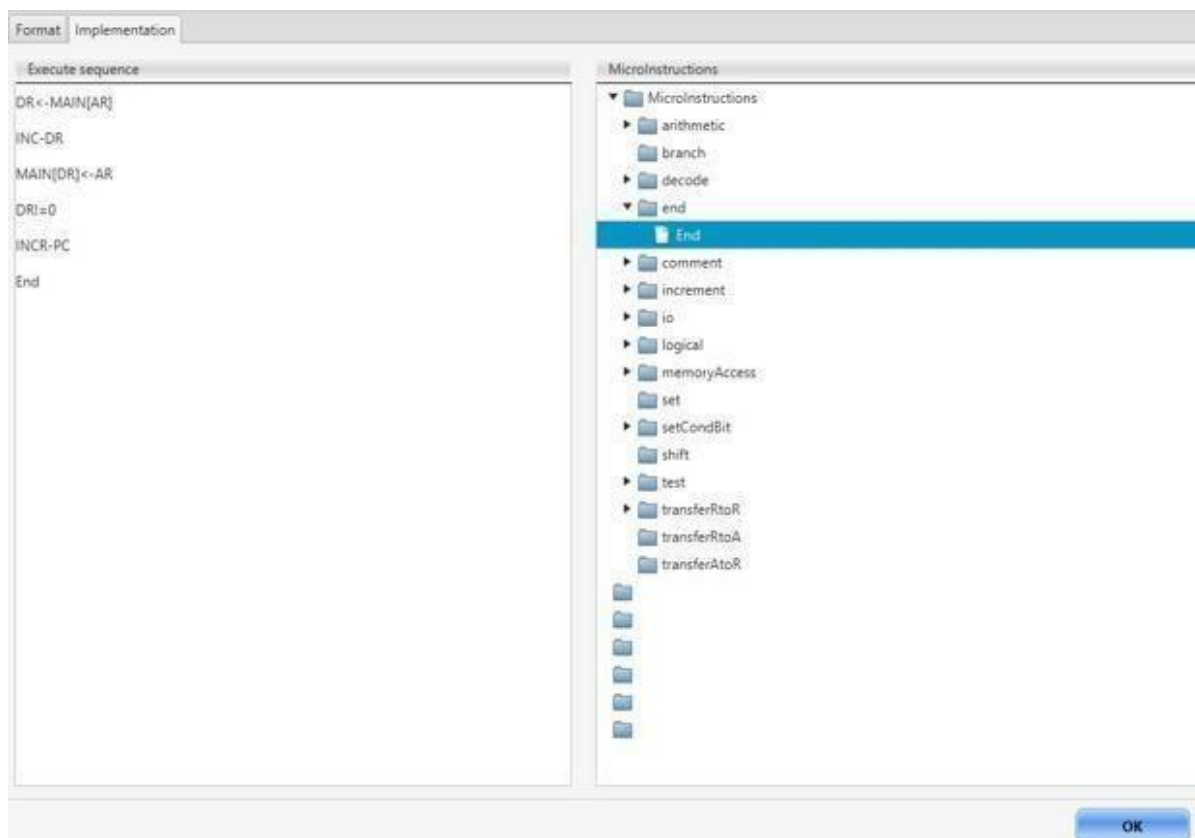
name	register	start	numBits	comparison	value	omission
DR == 0	DR	0	16	NE	0	1

- If the value is zero, increment the Program Counter (PC) to skip the next instruction.



name	register	overflowBit	carryBit	delta
INC-AC	AC	(none)	(none)	1
INC-DR	DR	(none)	(none)	1
INCR-PC	PC	(none)	(none)	1

- End the microinstruction sequence



Format Implementation

Execute sequence

```
DR <- MAIN[AR]
INC-DR
MAIN[DR] <- AR
DR! = 0
INCR-PC
End
```

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - End
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

OK

Result

```
EXECUTING...
Output: 0
EXECUTION HALTED NORMALLY due to the setting of the bit(s): [HALT-BIT]
```

LAB 07

Introduction:

This lab focuses on understanding key instructions such as CLA, CMA, SPA, and SNA. These operations are essential for performing logical and conditional tasks in assembly programming. Through hands-on practice, learners will enhance their ability to write efficient code.

ADD 3 Numbers

ADD instruction is used in performing this task just like the addition of 2 numbers using this **instruction**.

Program

```
1 START:
2 INP      ; Input a value and store it in the accumulator
3 STA NUM  ; Store the accumulator value in memory location "NUM"
4 INP      ; Input another value
5 ADD NUM  ; Add the value stored in "NUM" to the accumulator
6 STA NUM
7 INP
8 ADD NUM
9 OUT      ; Output the result
10 HLT     ; Halt execution
11 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
12
```

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 3
Enter Inputs, the first of which must be an Integer: 3
Enter Inputs, the first of which must be an Integer: 1
Output: 7
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

CLA Instruction

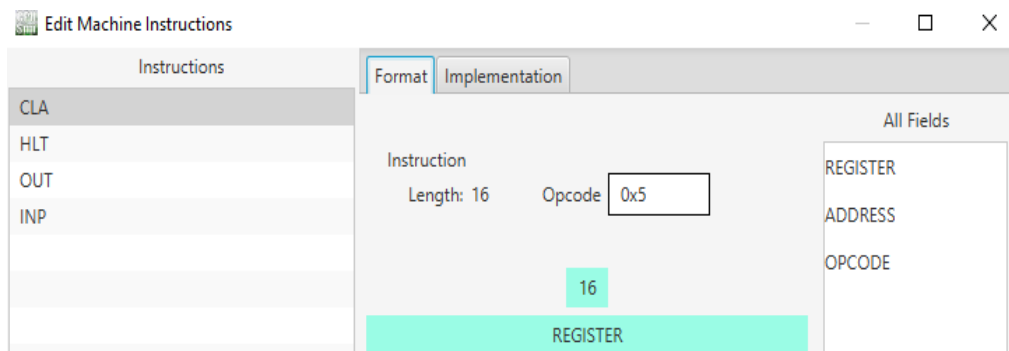
CLA stands for **Clear Accumulator**. It is used to set the value of the accumulator to zero.

Program

```
1 START:
2 INP      ; Input a value and store it in the accumulator
3 CLA      ; Clear the accumulator
4 OUT      ; Output the result
5 HLT      ; Halt execution
6 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
7
```

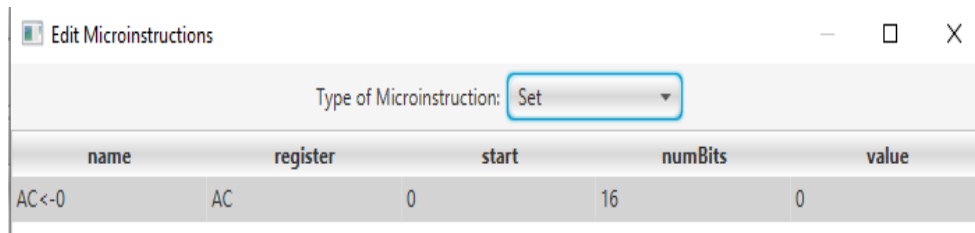
Machine instructions

- Set the upcode and format.



- Go to **Implementation** and select **Set** with the operation.

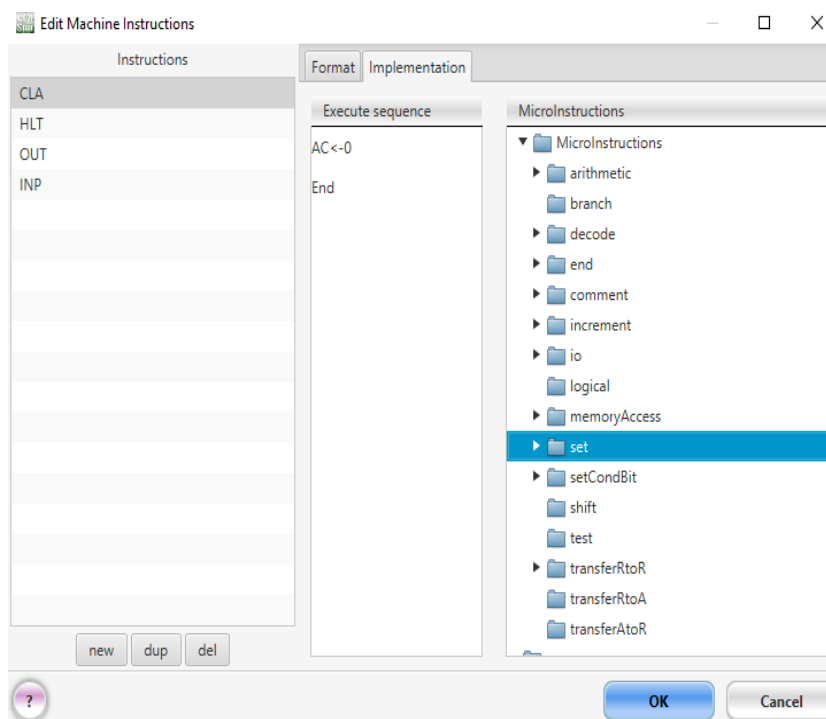
AC < - 0



The 'Edit Microinstructions' dialog box shows the 'Type of Microinstruction' dropdown set to 'Set'. Below it is a table with the following data:

name	register	start	numBits	value
AC < - 0	AC	0	16	0

- Define a **Sequence Instruction** for execution.



The 'Edit Machine Instructions' dialog box has the 'Implementation' tab selected. The 'Execute sequence' list contains 'AC < - 0' and 'End'. The 'MicroInstructions' tree on the right shows the 'set' instruction selected under the 'logical' category. At the bottom, there are 'new', 'dup', and 'del' buttons, a help icon, and 'OK' and 'Cancel' buttons.

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 2
Output: 0
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

CMA Instruction

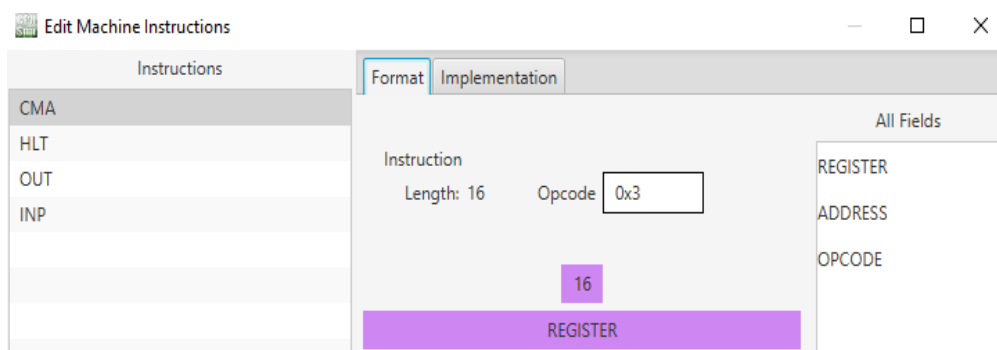
CMA stands for **Complement Accumulator**. It is an instruction that performs the operation of bitwise NOT (1's complement) on the accumulator.

Program

```
1 START:
2 INP      ; Input a value and store it in the accumulator
3 CMA      ;Complements the accumulator value
4 OUT      ; Output the result
5 HLT      ; Halt execution
6 NUM: .data 1 0 ; Memory location labeled "NUM", initialized with 0
7
```

Machine instructions

- Set the upcode and format.

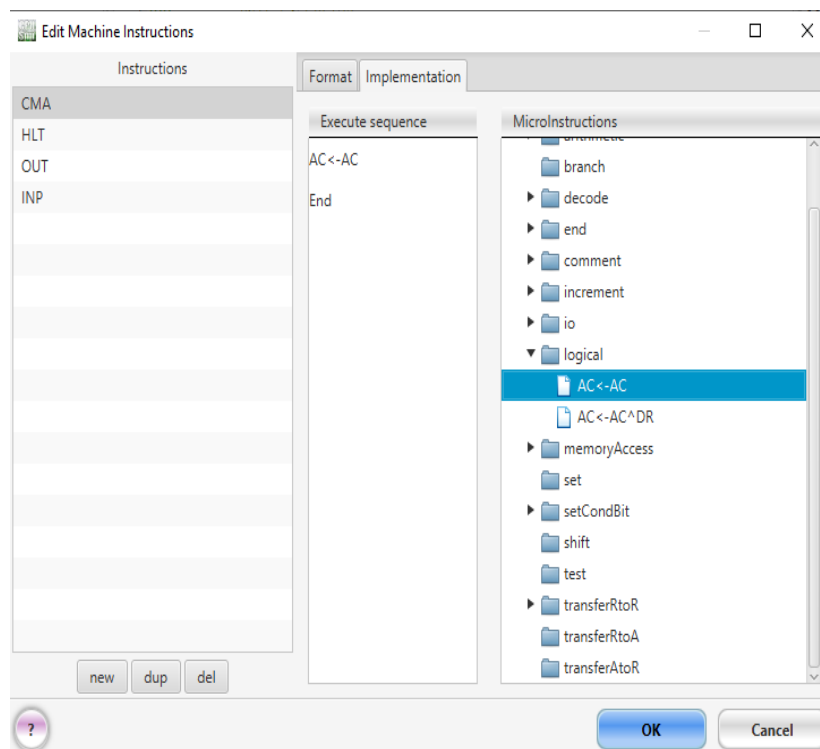


- Go to **Implementation** and select **Logical Instruction** with the operation.

AC<-AC

Edit Microinstructions				
Type of Microinstruction: Logical				
name	type	source1	source2	destination
AC<-AC	NOT	AC	AC	AC

- Define a **Sequence Instruction** for execution.



Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 5
Output: -2
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

SPA Instruction

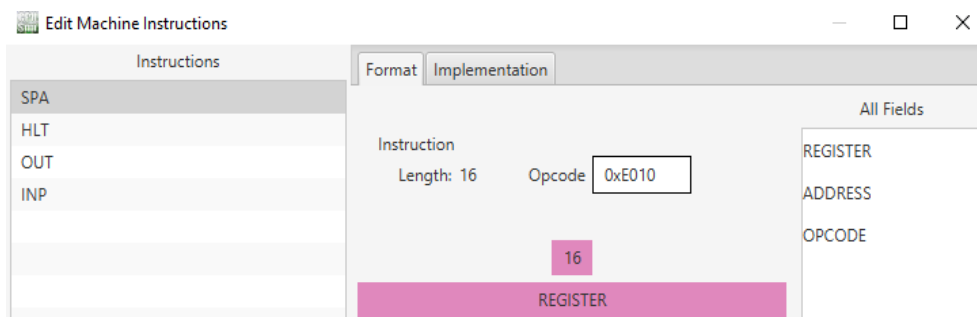
SNA stands for **Skip if Positive Accumulator**. It skips the next instruction if the accumulator holds a Positive value.

Program

```
1 START:
2 INP
3 SPA
4 OUT
5 HLT
6 NUM: .data 1 0
7
```

Machine instructions

- Set the upcode and format.



- Go to **Implementation** and select **Test** with the operation.

AC != 0

Type of Microinstruction: Test						
name	register	start	numBits	comparison	value	omission
AC!=0	AC	0	1	NE	0	1

- **Go to Implementation** and select **Instruction** with the operation.

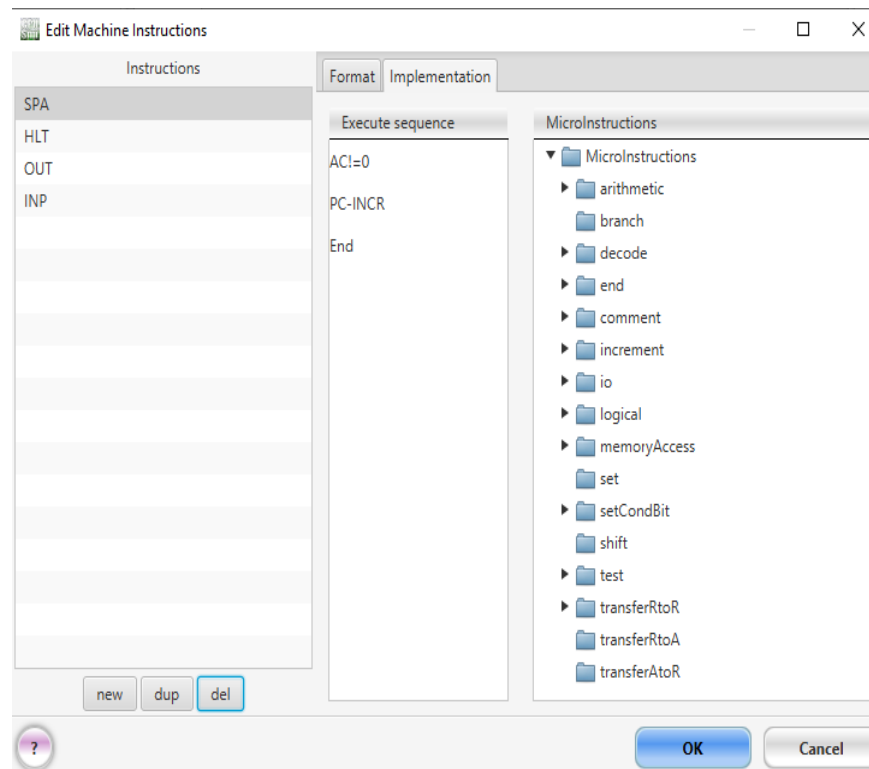
PC - INCR



The dialog box titled "Edit Microinstructions" has a dropdown menu for "Type of Microinstruction:" set to "Increment". Below it is a table with the following data:

name	register	overflowBit	carryBit	delta
PC-INCR	PC	(none)	(none)	1

- Define a **Sequence Instruction** for execution.



Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 3
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

SNA Instruction

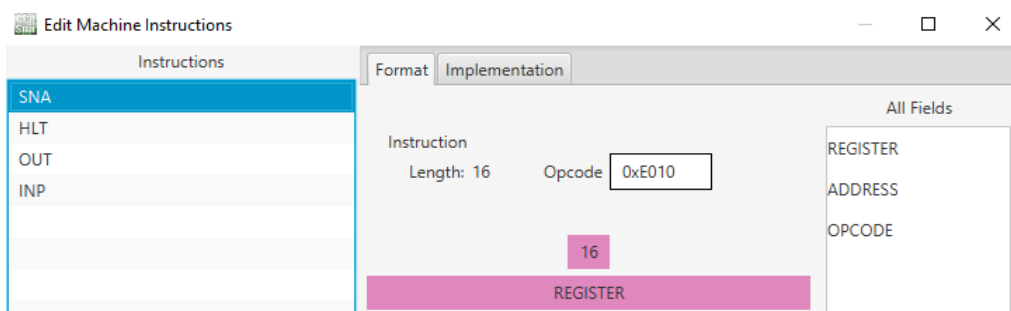
SNA stands for **Skip if Negative Accumulator**. It skips the next instruction if the accumulator holds a negative value.

Program

```
1 START:
2 INP
3 SNA
4 OUT
5 HLT
6 NUM: .data 1 0
7
```

Machine instructions

- Set the upcode and format.



- Go to **Implementation** and select **Test** with the operation.

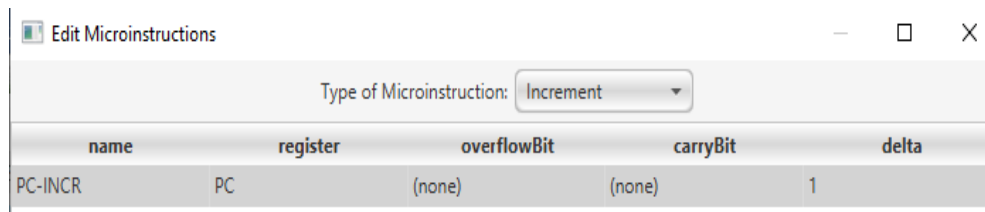
AC != 0

The screenshot shows a window titled "Edit Microinstructions". The "Type of Microinstruction" dropdown is set to "Test". Below it is a table with the following data:

name	register	start	numBits	comparison	value	omission
AC!=0	AC	0	1	EQ	0	1

- **Go to Implementation** and select **Increment** with the operation.

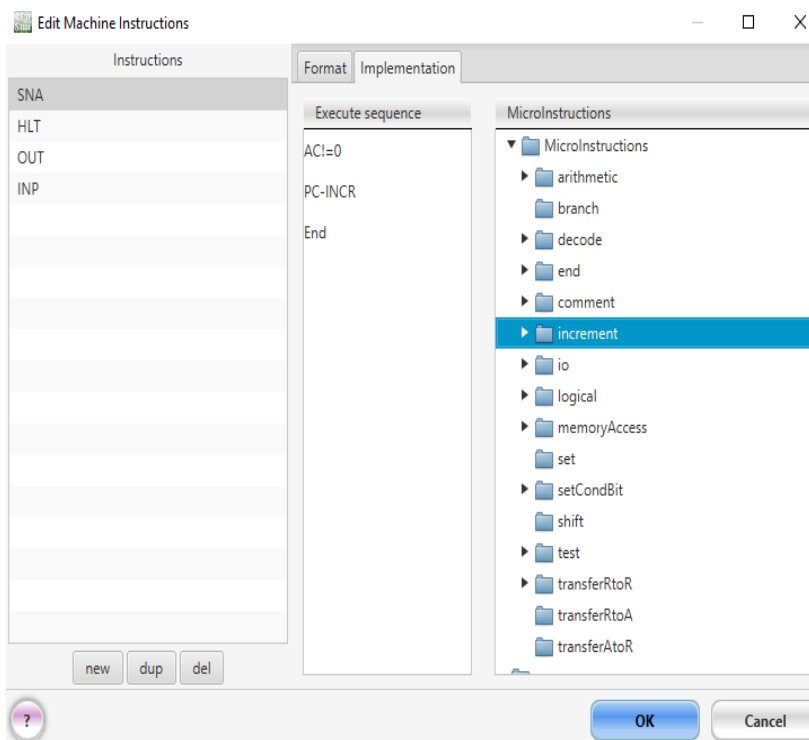
PC - INCR



The dialog box titled "Edit Microinstructions" shows a dropdown menu for "Type of Microinstruction" set to "Increment". Below the dropdown is a table with the following data:

name	register	overflowBit	carryBit	delta
PC-INCR	PC	(none)	(none)	1

- Define a **Sequence Instruction** for execution.



The dialog box titled "Edit Machine Instructions" has two tabs: "Format" and "Implementation". The "Implementation" tab is active, showing a list of microinstructions on the left and a tree view of microinstruction categories on the right. The "Execute sequence" list contains:

- ACI=0
- PC-INCR
- End

The tree view on the right shows the following categories:

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment** (highlighted)
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

At the bottom, there are buttons for "new", "dup", "del", "OK", and "Cancel".

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: -2
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

LAB 08

Introduction:

This lab explores the use of SZA, CIR, and CIL instructions in assembly programming. Students will learn how these instructions manipulate data and control program flow. The lab also introduces the JUMPN instruction to create loops that sum input values until a negative number is entered. These tasks provide practical insight into conditional execution and bit-level operations.

SZA Instruction

SZA stands for **Skip if Zero Accumulator**.

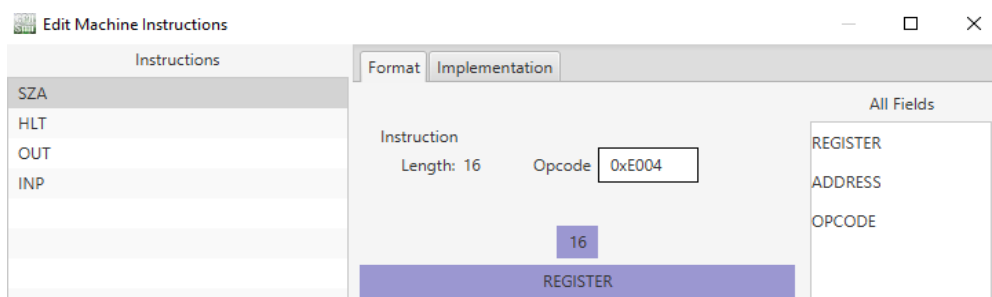
- It's a conditional skip instruction.
- It checks if the accumulator (AC) is zero, and if so, it **skips the next instruction**.

Program

```
1 START:
2 INP    ;Take input from the user
3 SZA    ;Skip the next instruction if the value in AC is zero
4 OUT    ;Output the value in AC (only if AC ≠ 0)
5 HLT    ;Halt the program
6 NUM: .data 1 0
```

Machine instructions

- Set the upcode and format.

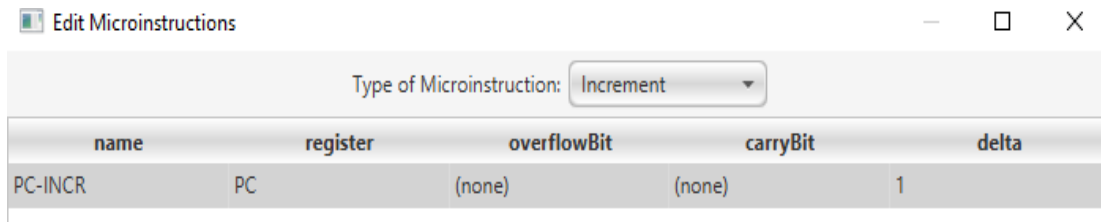


- Go to **Implementation** and select **Test** with the operation.

AC! = 0

Type of Microinstruction: Test						
name	register	start	numBits	comparison	value	omission
AC!=0	AC	0	16	NE	0	1

- Increment the value in PC.

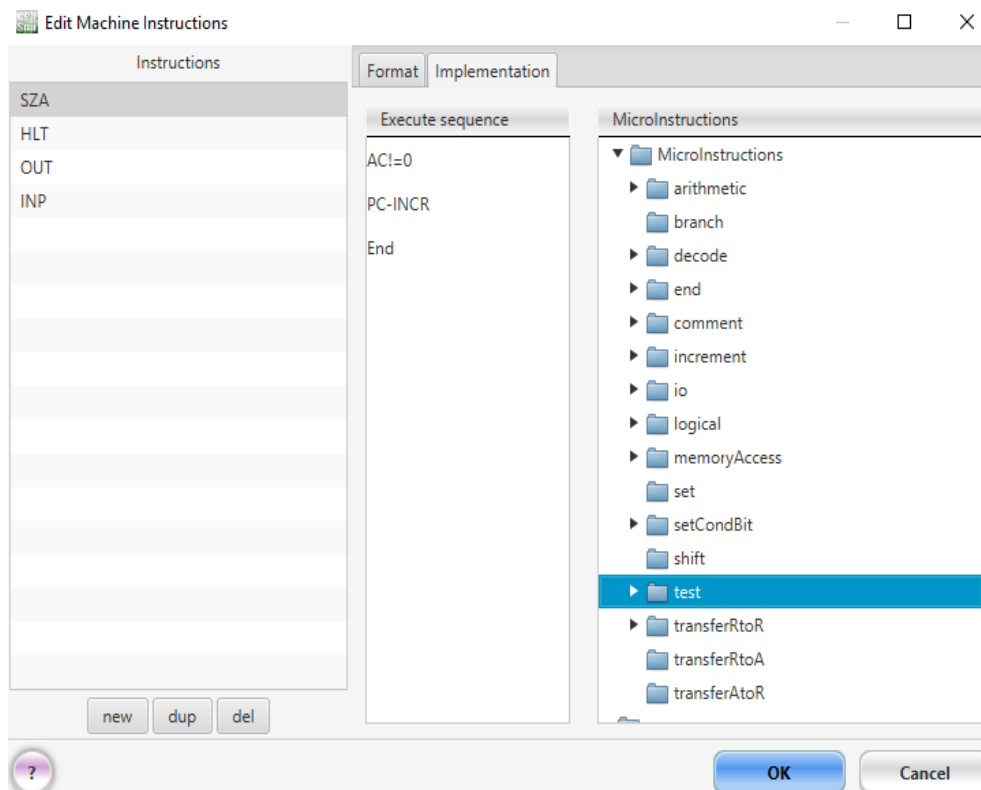


Edit Microinstructions

Type of Microinstruction: **Increment**

name	register	overflowBit	carryBit	delta
PC-INCR	PC	(none)	(none)	1

- Define a **Sequence Instruction** for execution.



Edit Machine Instructions

Instructions

- SZA
- HLT
- OUT
- INP

new dup del

Format Implementation

Execute sequence

```
ACI=0
PC-INCR
End
```

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test**
 - transferRtoR
 - transferRtoA
 - transferAtoR

OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 0
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```


CIR Instruction

CIR stands for **Circular Rotate Right**. It rotates the bits in the AC to the right **by one bit**.

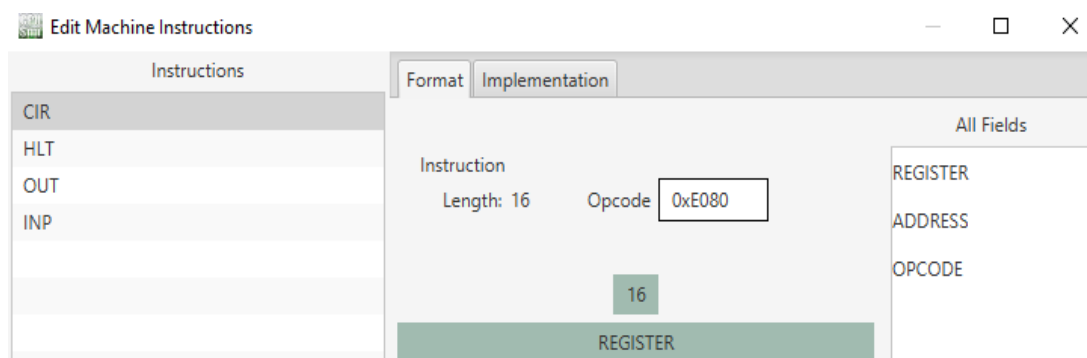
- In CIR, least significant bit (**LSB**) moves to the most significant bit (**MSB**) position.
- This is mathematically similar to **dividing** by 2.
- It gives correct division results only for even numbers.

Program

```
1 START:
2 INP    ;Take input from user
3 CIR    ;Perform a Circular Rotate Right on AC
4 OUT    ;Output the value in AC
5 HLT    ;Halt execution
6 NUM: .data 1 0
-
```

Machine instructions

- **Set the upcode and format.**



- Go to Implementation and select **TransferRtoR** with the operation.

E – AC(15)

Edit Microinstructions

Type of Microinstruction: TransferRtoR

name	source	srcStartBit	dest	destStartBit	numBits
E<-AC(15)	AC	15	E	0	1

- Go to Implementation and select **Shift** with the operation.

SHR - AC

Edit Microinstructions

Type of Microinstruction: Shift

name	source	destination	type	direction	distance
SHR-AC	AC	AC	cyclic	right	1

- Go to Implementation and select **TransferRtoR** with the operation.

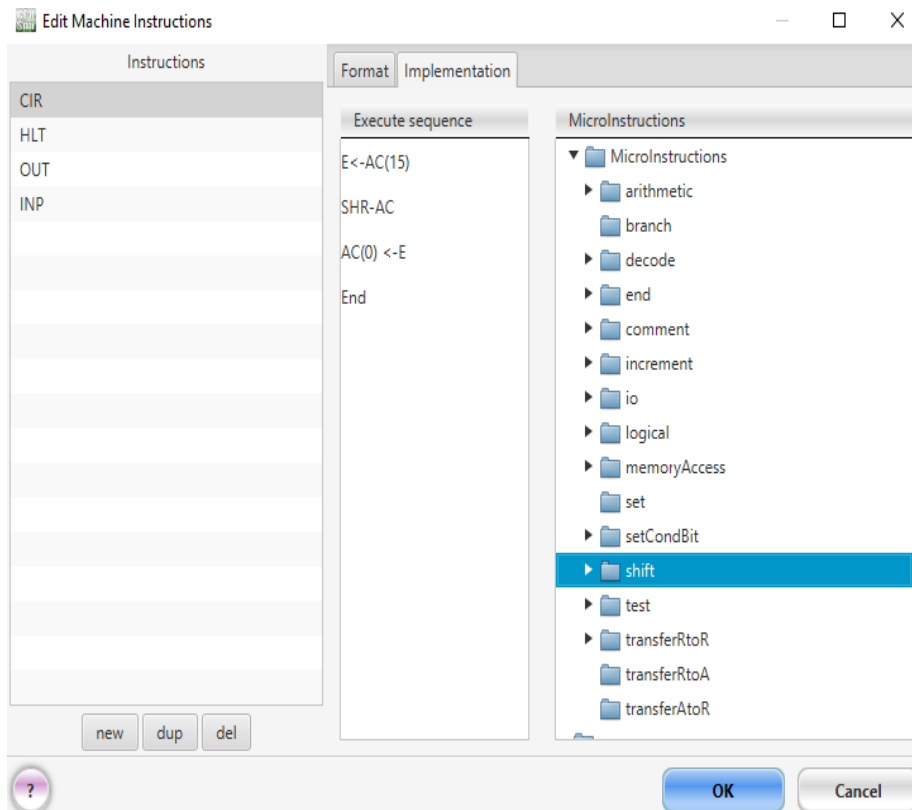
AC(0)<- E

Edit Microinstructions

Type of Microinstruction: TransferRtoR

name	source	srcStartBit	dest	destStartBit	numBits
AC(0) <-E	E	0	AC	0	1
E<-AC(15)	AC	15	E	0	1

- Define a **Sequence Instruction** for execution.



Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 6
Output: 3
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

CIL Instruction

CIL stands for **Circular Rotate Left**. It rotates the bits in the **AC** to the Left **by one bit**.

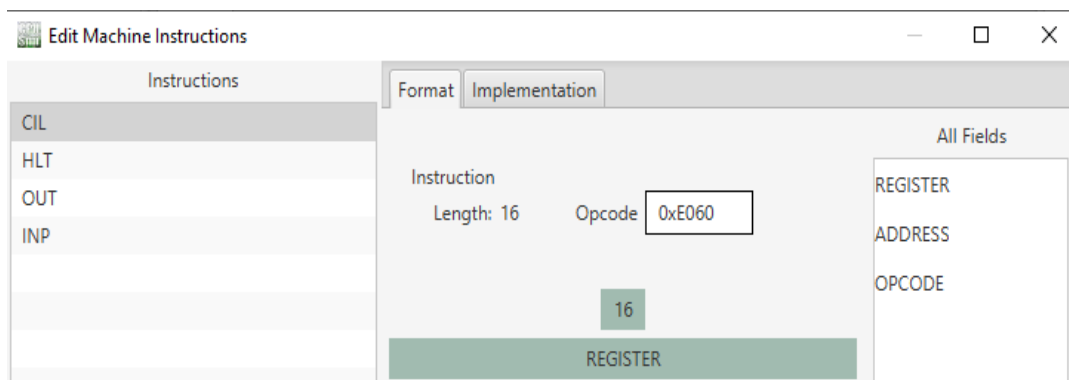
- In CIL, most significant bit (**MSB**) moves to the least significant bit (**LSB**) position.
- This is mathematically similar to **multiplying** by 2.
- It gives correct multiplication results only for even numbers.

Program

```
1 START:
2 INP    ;Take input from user
3 CIL    ;Perform a Circular Rotate Left on AC
4 OUT    ;Output the value in AC
5 HLT    ;Halt execution
6 NUM:   .data 1 0
7
```

Machine instructions

- Set the upcode and format.



- Go to Implementation and select **TransferRtoR** with the operation.

E ← AC(15)

Edit Microinstructions

Type of Microinstruction: TransferRtoR

name	source	srcStartBit	dest	destStartBit	numBits
E ← AC(15)	AC	15	E	0	1

- Go to Implementation and select **Shift** with the operation.

SHL - AC

Edit Microinstructions

Type of Microinstruction: Shift

name	source	destination	type	direction	distance
SHL-AC	AC	AC	cyclic	left	1

- Go to Implementation and select **TransferRtoR** with the operation.

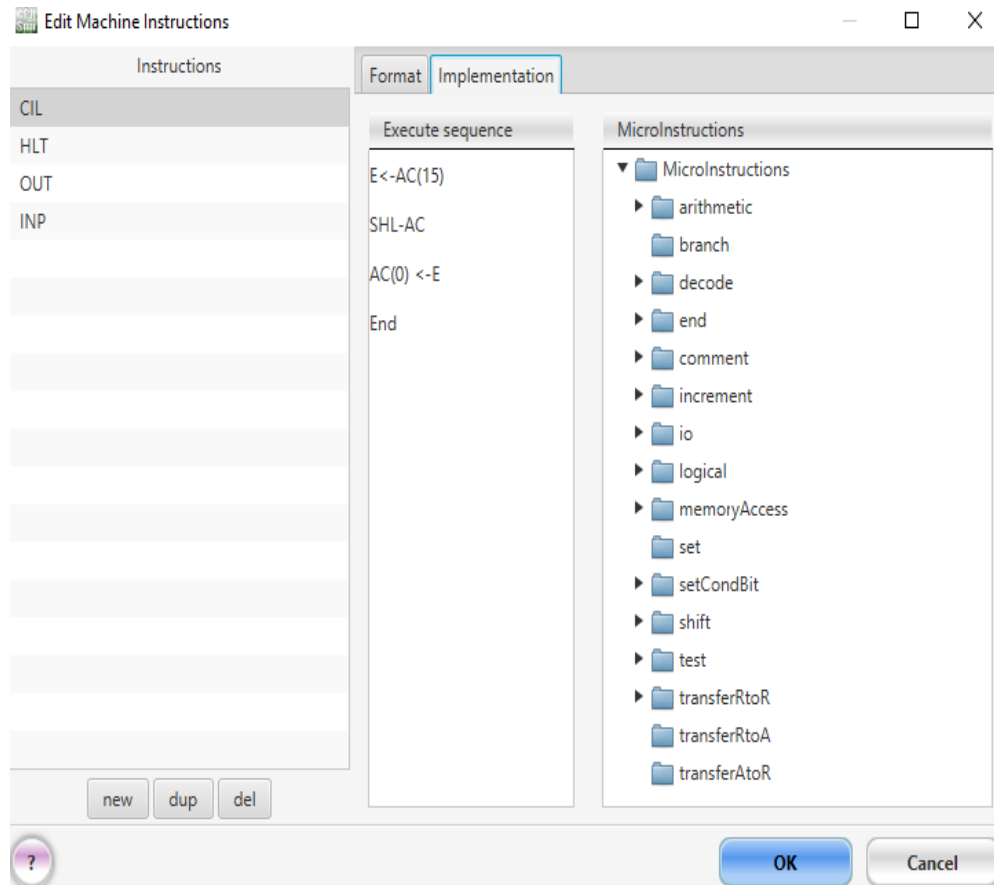
AC(0) ← E

Edit Microinstructions

Type of Microinstruction: TransferRtoR

name	source	srcStartBit	dest	destStartBit	numBits
AC(0) ← E	E	0	AC	0	1
E ← AC(15)	AC	15	E	0	1

- Define a **Sequence Instruction** for execution.



Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 2
Output: 4
EXECUTION HALTED DUE TO AN EXCEPTION: The step is out of range
at step 0 of HLT.
```

JUMPN Instruction

JUMPN stands for **Jump if Negative**.

- It checks the value in the **Accumulator (AC)**.
- If the value is **negative**, it **jumps to the specified address/label**.
- If the value is **zero or positive**, it **continues with the next instruction**.

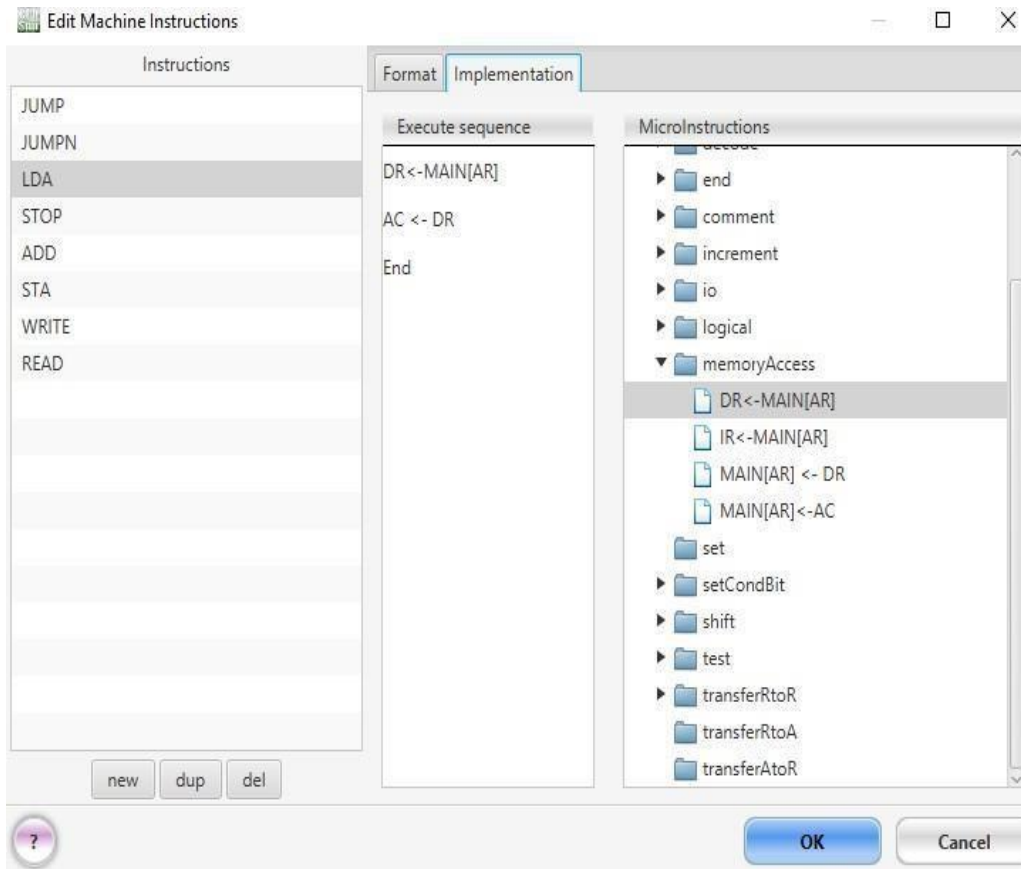
Program

```
1  START:
2  READ          ;Read a number from the user
3  JUMPN DONE    ;If the number is negative, jump to DONE
4  ADD SUM       ;Add the value
5  STA SUM
6  JUMP START    ;jump to Start
7
8  DONE:
9  LDA SUM       ;Load the final sum into AC
10 WRITE        ;Output
11 STOP         ;End the program
12
13 SUM: .data 2 0
```

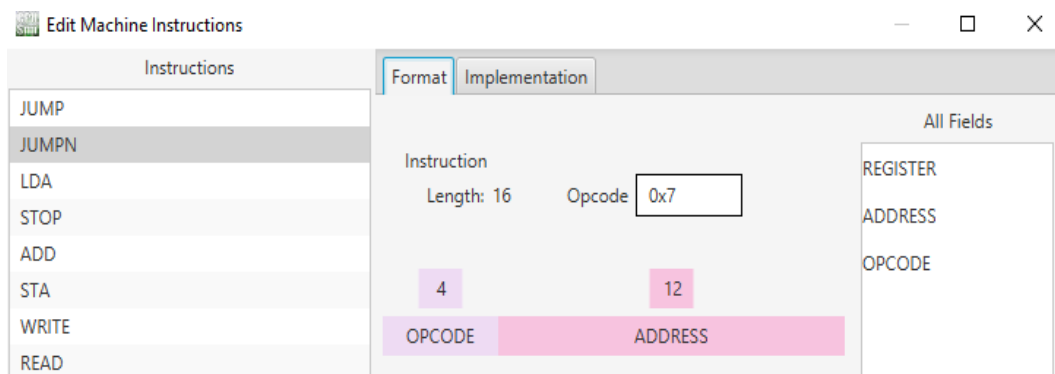
Machine instructions

- Rename **INP** to **Read**.
- Rename **OUT** to **Write**.
- Rename **HLT** to **STOP**
- **STA** remains same.
- **ADD** remains same.
- **JUMP** also remains same.

- Define a **Sequence Instruction** for execution for **LDA**.



- Set the upcode and format for JUMPN.



- Go to **Implementation** and select **Test** with the operation.

IF(AC>0)SKIP - 1

Edit Microinstructions

Type of Microinstruction: Test

name	register	start	numBits	comparison	value	omission
IF(AC>0)SKIP-1	AC	0	16	GT	0	1

- Go to **Implementation** and select **TransferRtoR** with the operation. **PC<- AR**

Edit Microinstructions

Type of Microinstruction: TransferRtoR

name	source	srcStartBit	dest	destStartBit	numBits
AC <- DR	DR	0	AC	0	16
AR <- IR(4-15)	IR	4	AR	0	12
AR <- PC	PC	0	AR	0	12
PC <- AR	AR	0	PC	0	12

- Define a **Sequence Instruction** for execution.

Edit Machine Instructions

Instructions:

- JUMP
- JUMPN
- LDA
- STOP
- ADD
- STA
- WRITE
- READ

new dup del

Format Implementation

Execute sequence

IF(AC>0)SKIP-1

PC<-AR

End

MicroInstructions

- MicroInstructions
 - arithmetic
 - branch
 - decode
 - end
 - comment
 - increment
 - io
 - logical
 - memoryAccess
 - set
 - setCondBit
 - shift
 - test
 - transferRtoR
 - transferRtoA
 - transferAtoR

OK Cancel

Result

```
EXECUTING...
Enter Inputs, the first of which must be an Integer: 2
Enter Inputs, the first of which must be an Integer: 2
Enter Inputs, the first of which must be an Integer: 2
Enter Inputs, the first of which must be an Integer: -3
Output: 6
EXECUTION HALTED NORMALLY due to the setting of the bit(s): [HALT-BIT]
```