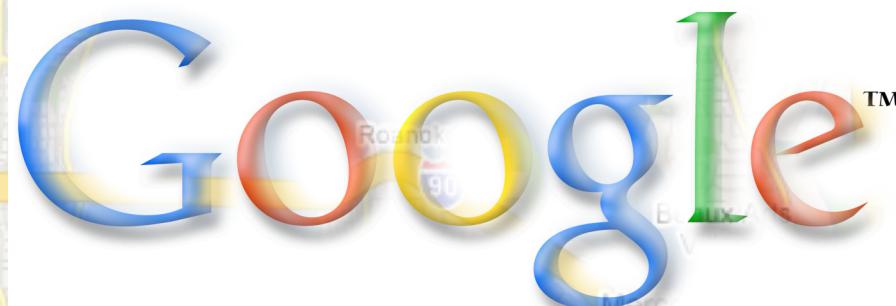


# MapReduce Design Patterns

Barry Brumitt

[barryb@google.com](mailto:barryb@google.com)  
Software Engineer



# About your speaker...

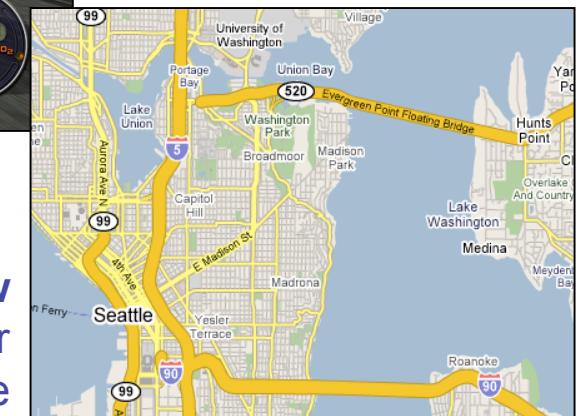


**Ph.D. Robotics, Carnegie Mellon, '91 - '97**  
Path Planning for Multiple Mobile Robots



**Researcher, Microsoft Research, '98 - '02**  
Ubiquitous Computing

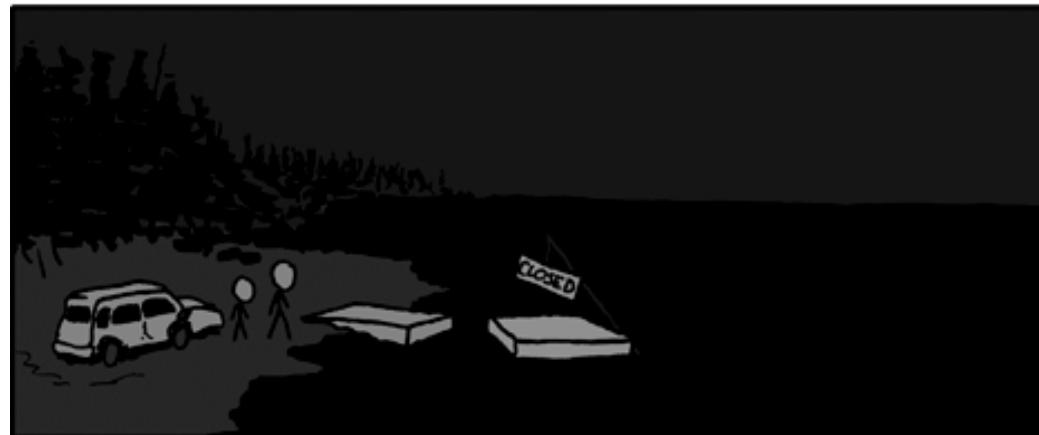
**Software Eng., Microsoft Games, '03 - '05**  
AI for Forza Motorsport

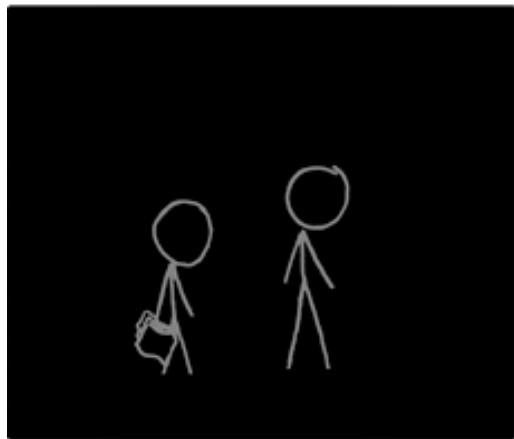


**Software Engineer, Google, '05 - now**  
Maps: Pathfinder  
Systems: Infrastructure

MY ROAD TRIP WITH MY BROTHER RAN INTO TROUBLE  
AROUND PAGE THREE OF THE GOOGLE MAPS PRINTOUT.

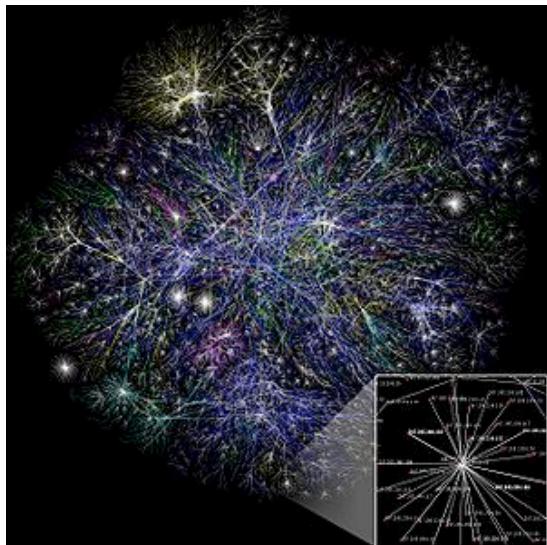
← 70. SLIGHT LEFT AT RT-22.	GO 6.8 MI
→ 71. TURN RIGHT TO STAY ON RT-22.	GO 2.6 MI
← 72. TURN LEFT AT LAKE SHORE RD.	GO 312 FT
→ 73. TURN RIGHT AT DOCK ST.	GO 427 FT
~~~ 74. TAKE THE FERRY ACROSS THE LAKE.	GO 2.8 MI





74. TAKE THE **FERRY** ACROSS THE **LAKE**. GO 2.8 MI
- ↗ 75. CLIMB THE **HILL** TOWARD **HANGMAN'S RIDGE**,  
AVOIDING ANY **MOUNTAIN LIONS**. UP 1,172 FT
- ↶ 76. WHEN YOU REACH AN **OLD BARN**, GO AROUND  
BACK, KNOCK ON THE **SECOND DOOR**, AND GO 52 FT  
ASK FOR **CHARLIE**.
- 🚐 77. TELL **CHARLIE** THE **DANCING STONES** ARE  
**RESTLESS**. HE WILL GIVE YOU HIS **VAN**. CAREFUL
- ↗ 78. TAKE **CHARLIE'S VAN** DOWN **OLD MINE ROAD**.  
DO NOT WAKE THE **STRAW MAN**. GO 11 MI
- ← 79. TURN LEFT ON **COMSTOCK**. WHEN YOU FEEL  
THE **BLOOD CHILL** IN YOUR **VEINS**, STOP THE GO 3.2 MI  
**VAN** AND **GET OUT**.
- ↓ 80. STAND VERY STILL. EXITS ARE **NORTH**, **SOUTH**, AND  
**EAST**, BUT ARE BLOCKED BY A **SPECTRAL WOLF**. GO 0 FT
- ≈ 81. THE **SPECTRAL WOLF** FEARS ONLY **FIRE**. THE  
**GOOGLE MAPS TEAM** CAN NO LONGER HELP  
YOU, BUT IF YOU MASTER THE **WOLF**, HE GO ?? MI  
WILL GUIDE YOU. **GODSPEED**.

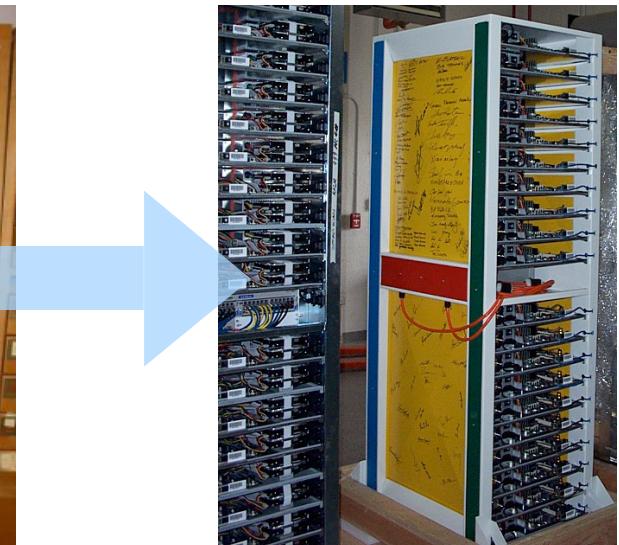
# Indexing Large Datasets



All web pages



Index Files



Data Center

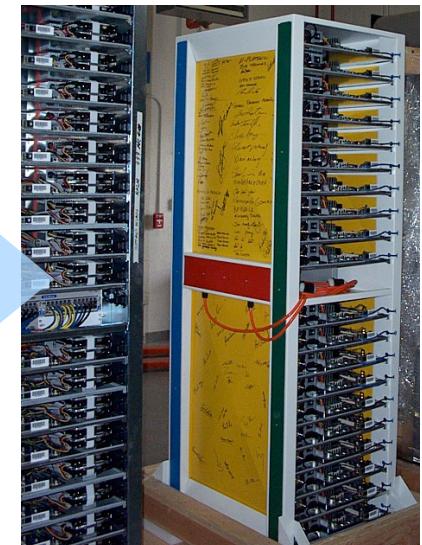
# Indexing Large Datasets



Geographic Data



Index Files



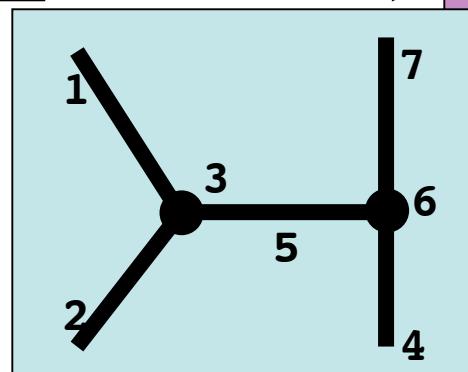
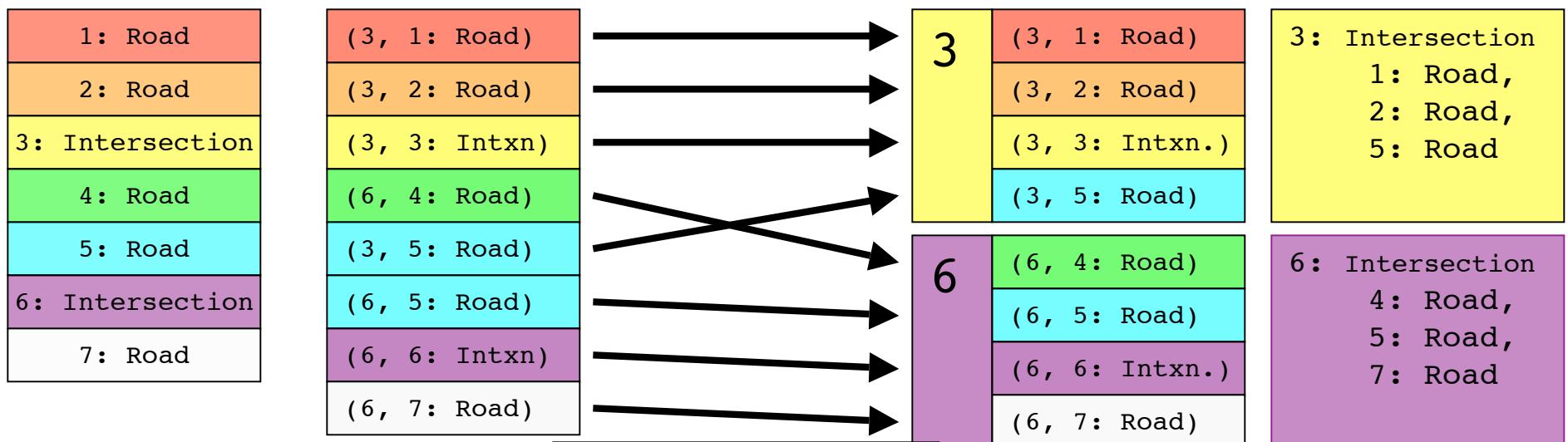
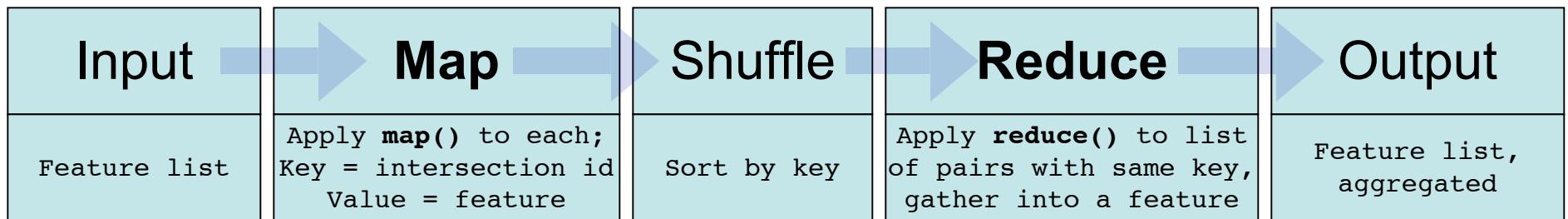
Data Center

...not so useful for user-facing applications...

# Pointer Following (or) Joining

Input	Output
<p><b>Feature List</b></p> <pre>1: &lt;type=Road&gt;, &lt;intersections=(3)&gt;, &lt;geom&gt;, ... 2: &lt;type=Road&gt;, &lt;intersections=(3)&gt;, &lt;geom&gt;, ... 3: &lt;type=Intersection&gt;, stop_type, POI? ... 4: &lt;type=Road&gt;, &lt;intersections=(6)&gt;, &lt;geom&gt;, 5: &lt;type=Road&gt;, &lt;intersections=(3,6)&gt;, &lt;geom&gt;, ... 6: &lt;type=Intersection&gt;, stop_type, POI?, ... 7: &lt;type=Road&gt;, &lt;intersections=(6)&gt;, &lt;geom&gt;, ... 8: &lt;type=Town&gt;, &lt;name&gt;, &lt;geom&gt;, ... . . .</pre> <pre>graph LR; 1((1)) --- 3((3)); 1 --- 3((3)); 2((2)) --- 3((3)); 3((3)) --- 5((5)); 5((5)) --- 6((6)); 6((6)) --- 7((7)); 4((4)) --- 6((6));</pre>	<p><b>Intersection List</b></p> <pre>3: &lt;type=Intersection&gt;, stop_type, &lt;roads=(     1: &lt;type=Road&gt;, &lt;geom&gt;, &lt;name&gt;, ...     2: &lt;type=Road&gt;, &lt;geom&gt;, &lt;name&gt;, ...     5: &lt;type=Road&gt;, &lt;geom&gt;, &lt;name&gt;, ... )&gt;, ... 6: &lt;type=Intersection&gt;, stop_type, &lt;roads=(     4: &lt;type=Road&gt;, &lt;geom&gt;, &lt;name&gt;, ... ,     5: &lt;type=Road&gt;, &lt;geom&gt;, &lt;name&gt;, ... ,     7: &lt;type=Road&gt;, &lt;geom&gt;, &lt;name&gt;, ... )&gt;, ... . . .</pre>

# Inner Join Pattern



# Inner Join Pattern in SQL

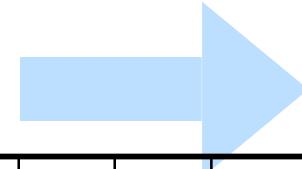
roads

R	D	I
1	a	3
2	b	3
4	c	6
5	d	6
7	e	6

ints

I	D
3	x
6	y

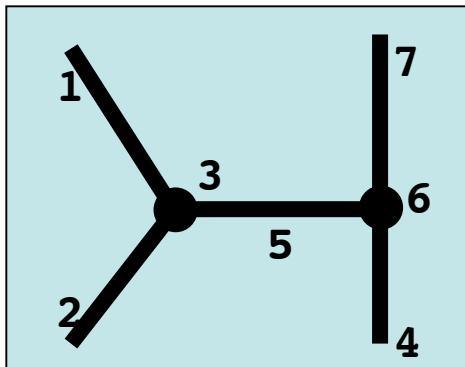
SELECT roads.R, roads.D, ints.D  
FROM roads INNER JOIN ints  
ON roads.I = ints.I



r.R	r.D	r.I	i.I	i.D
1	a	3	3	x
2	b	3	3	x
4	c	6	3	x
5	d	6	3	x
7	e	6	3	x
1	a	3	6	y
2	b	3	6	y
4	c	6	6	y
5	d	6	6	y
7	e	6	6	y

r.R	r.D	i.D
1	a	x
2	b	x
4	c	y
5	d	y
7	e	x

“Cross Join”



# Inner Join Pattern in SQL

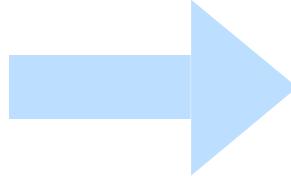
roads

R	D	I
1	a	3
2	b	3
4	c	6
5	d	6
7	e	5

ints

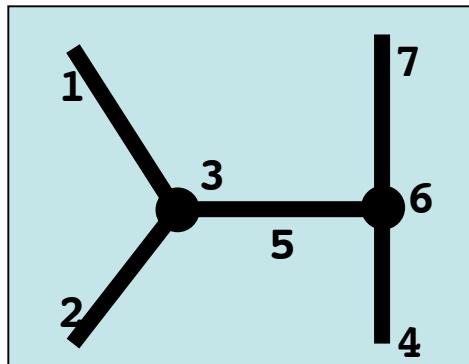
I	D
3	x
6	y

```
SELECT roads.R, roads.D, ints.D  
FROM roads INNER JOIN ints  
ON roads.I = ints.I
```



```
SELECT roads.R, roads.D, ints.D  
FROM roads, ints  
WHERE roads.I = ints.I
```

r.R	r.D	i.D
1	a	x
2	b	x
4	c	y
5	d	y
7	e	x



(aka “an Equi Join”)

# Tables vs. Flat File?

## Tables

Roads			

Intersections			

Towns			

## Flat File

Features		
Road	Intersection	Town
Road	Intersection	Town
Road	Intersection	Town

```
Message GeoFeature {  
    enum Type {  
        ROAD = 1;  
        INTERSECTION = 2;      " Protocol Buffer "  
        TOWN = 3;  
    }  
    required Type type = 0;  
    optional Road road = 1;  
    optional Intersection intersection = 2;  
    optional Town town = 3 ;  
}
```

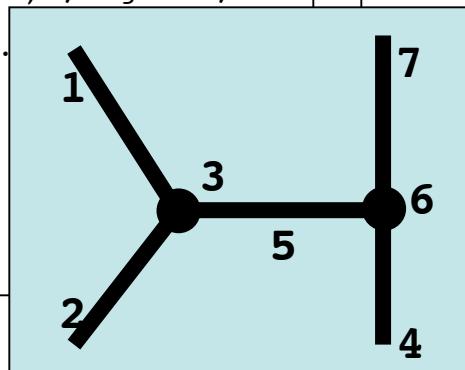
# References vs. Duplication?

## References

```
1: <type=Road>, <intersections=(3)>, <geom>, ...
2: <type=Road>, <intersections=(3)>, <geom>, ...
3: <type=Intersection>, <roads=(1,2,5)>, ...
4: <type=Road>, <intersections=(6)>, <geom>,
5: <type=Road>, <intersections=(3,6)>, <geom>, ...
6: <type=Intersection>, <roads=(5,6,7)>, ...
7: <type=Road>, <intersections=(6)>, <geom>, ...
8: <type=Town>, <name>, <geom>,
.
.
```

## Duplication

```
3: <type=Intersection>, <roads=(  
    1: <type=Road>, <geom>, <name>, ...  
    2: <type=Road>, <geom>, <name>, ...  
    5: <type=Road>, <geom>, <name>, ...), ...  
6: <type=Intersection>, <roads=(  
    4: <type=Road>, <geom>, <name>, ... >  
    5: <type=Road>, <geom>, <name>, ... >  
    7: <type=Road>, <geom>, <name>, ...), ...  
. . .
```



- References: Common primary key; easy restructuring
- Duplication: Avoids additional MR passes; denormalizes data
- ...an engineering space / time / complexity tradeoff

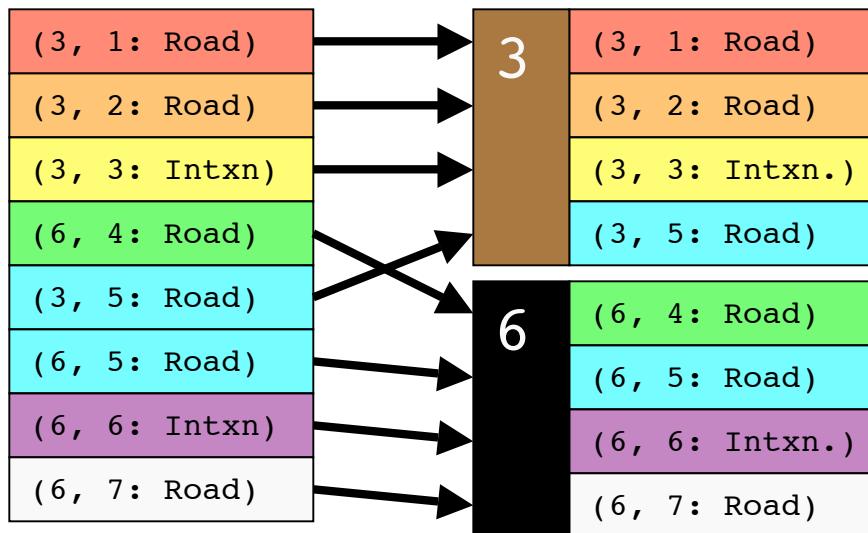
# Code Example

```

class IntersectionAssemblerMapper : public
    Mapper {
    virtual void Map(MapInput* input) {
        GeoFeature feature;
        feature.FromMapInput(input);
        if (feature.type() == INTERSECTION) {
            Emit(feature.id(), input);
        } else if (feature.type() == ROAD) {
            Emit(feature.intersection_id(0), input);
            Emit(feature.intersection_id(1), input);
        }
    }
};

REGISTER_MAPPER(IntersectionAssemblerMapper);

```



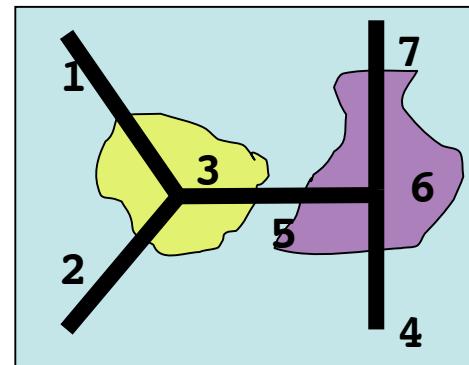
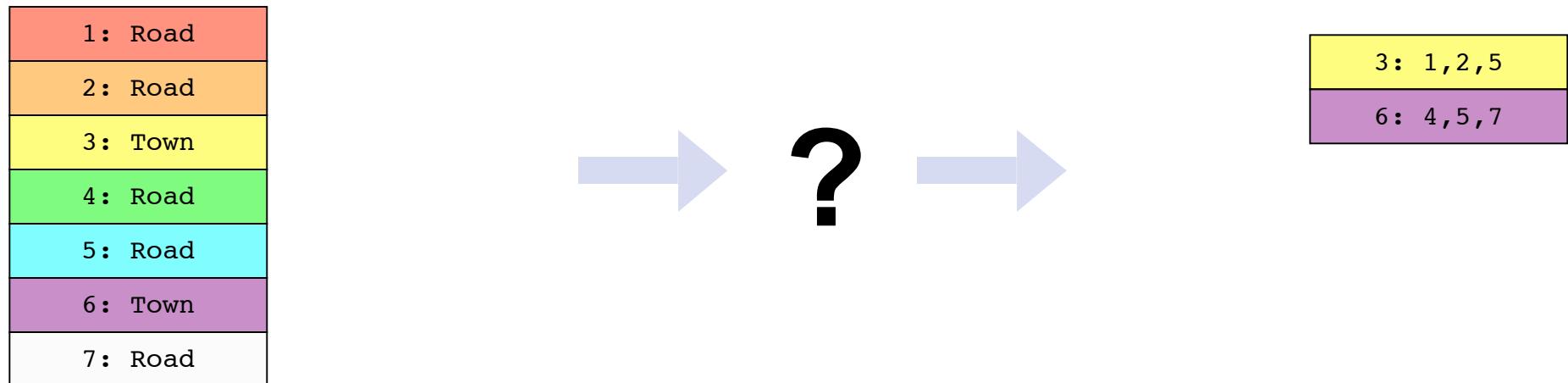
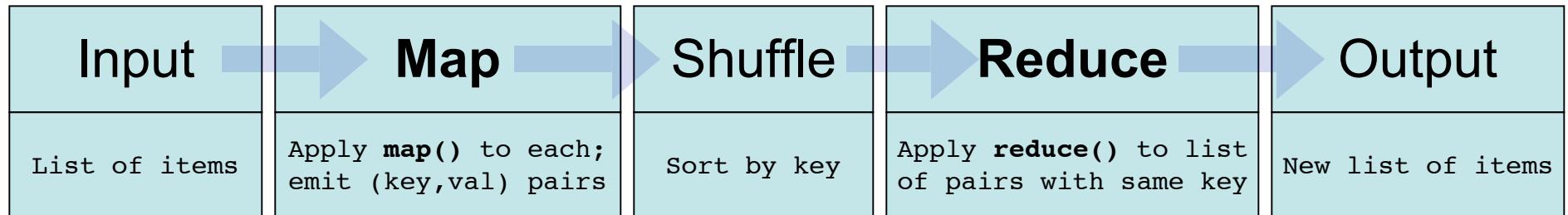
```

class IntersectionAssemblerReducer : public
    Reducer {
    virtual void Reduce(ReduceInput* input) {
        GeoFeature feature;
        GraphIntersection intersection;
        intersection.id = input->key();
        while(!input->done()) {
            feature.FromMapInput(input->value());
            if (feature.type() == INTERSECTION)
                intersection.SetIntersection(feature);
            else
                intersection.AddRoadFeature(feature);
            input->next();
        }
        Emit(intersection);
    }
};

REGISTER_REDUCER(IntersectionAssemblerReducer);

```

# Join, but no pointers or keys?

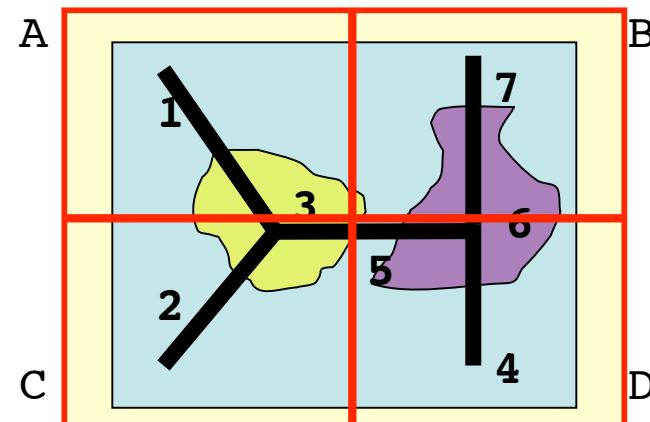


# Bucketing (or) Grace Hash Join

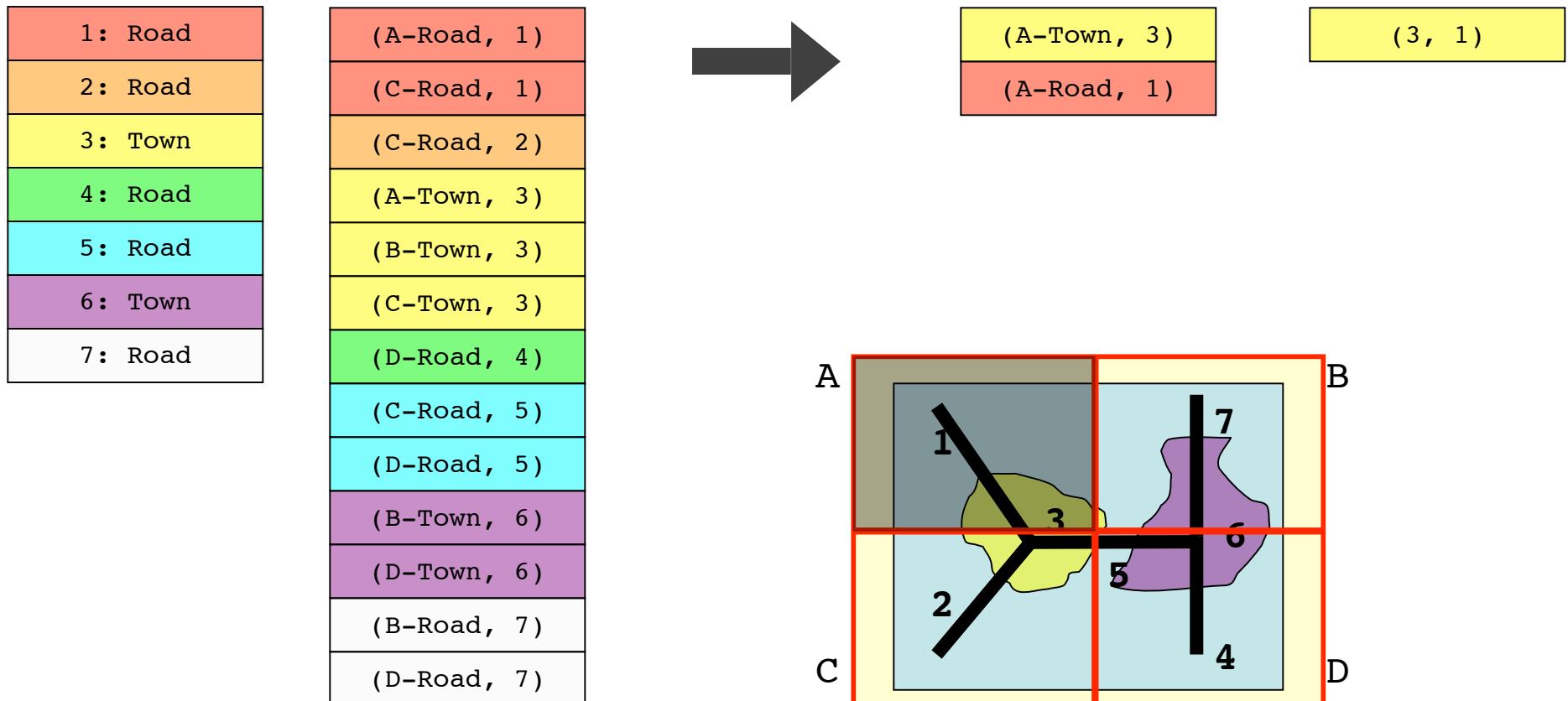
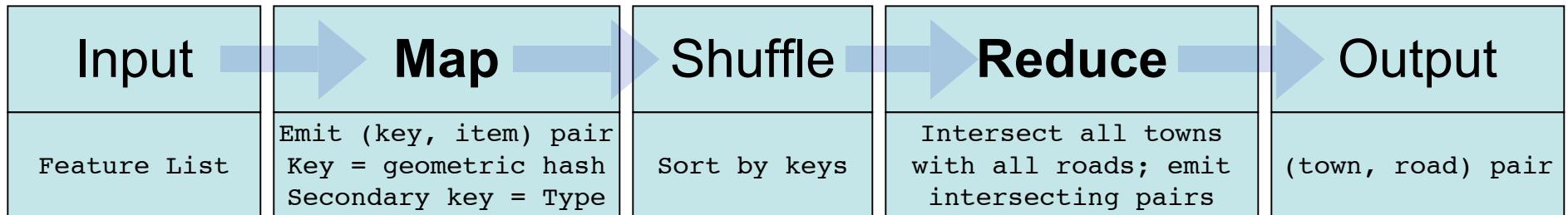


1: Road
2: Road
3: Town
4: Road
5: Road
6: Town
7: Road

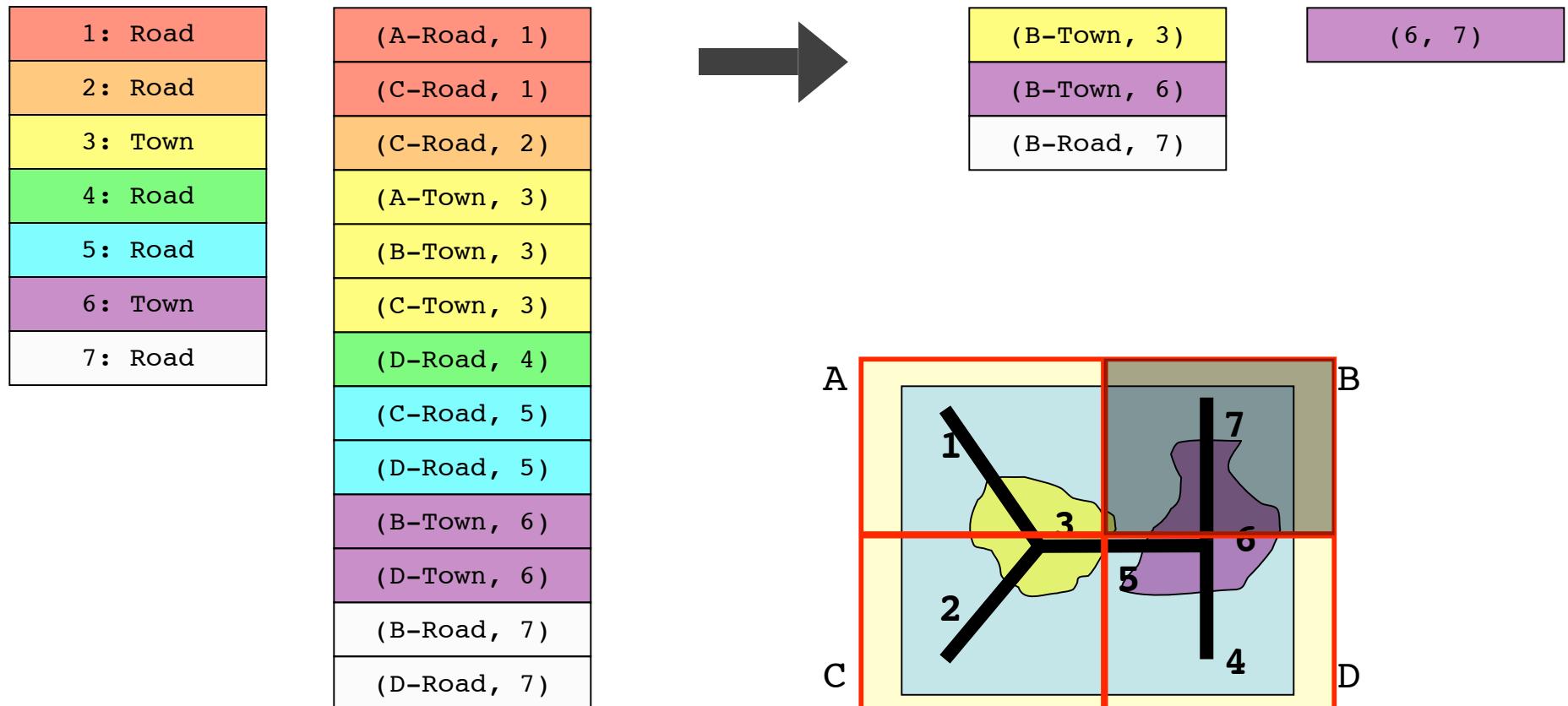
(A-Road, 1)
(C-Road, 1)
(C-Road, 2)
(A-Town, 3)
(B-Town, 3)
(C-Town, 3)
(D-Road, 4)
(C-Road, 5)
(D-Road, 5)
(B-Town, 6)
(D-Town, 6)
(B-Road, 7)
(D-Road, 7)



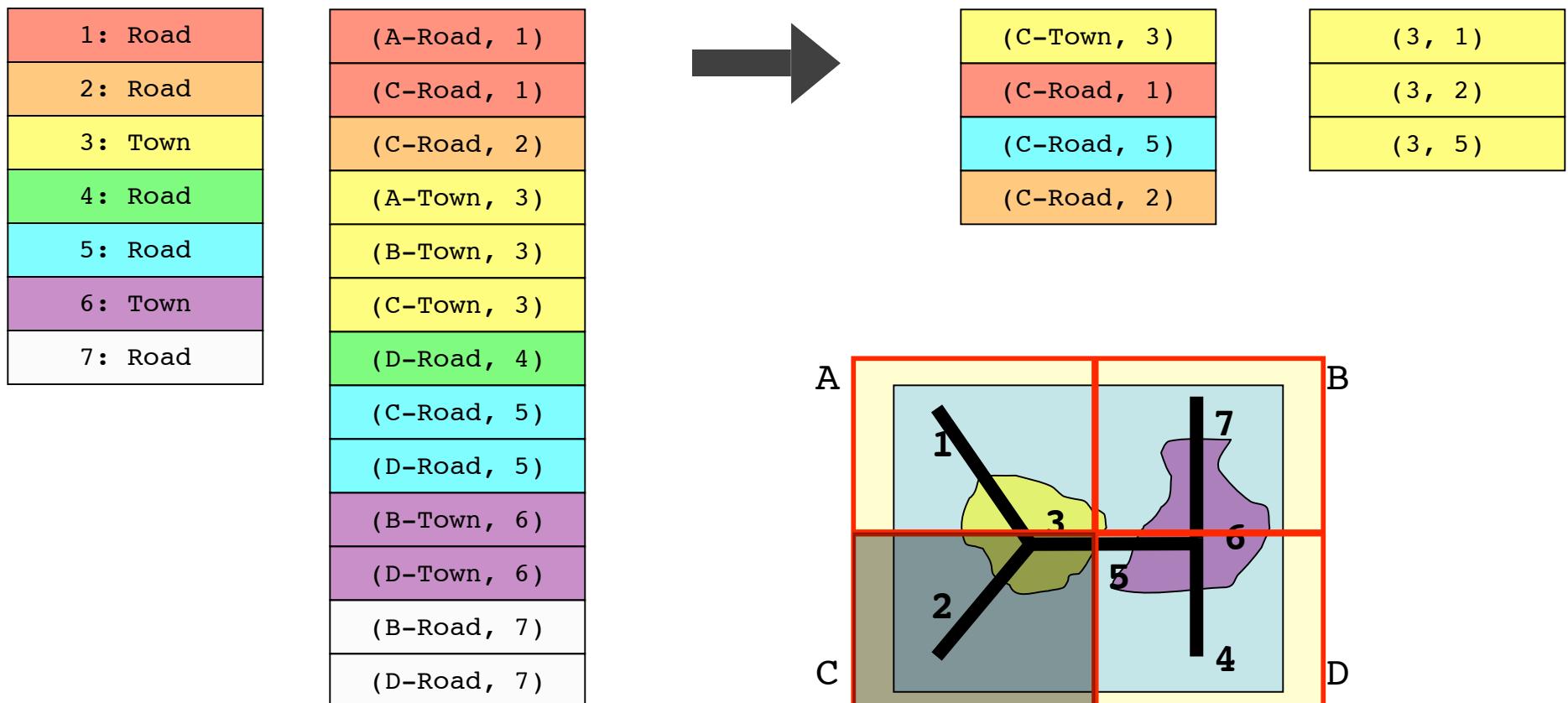
# Reduce on Key A



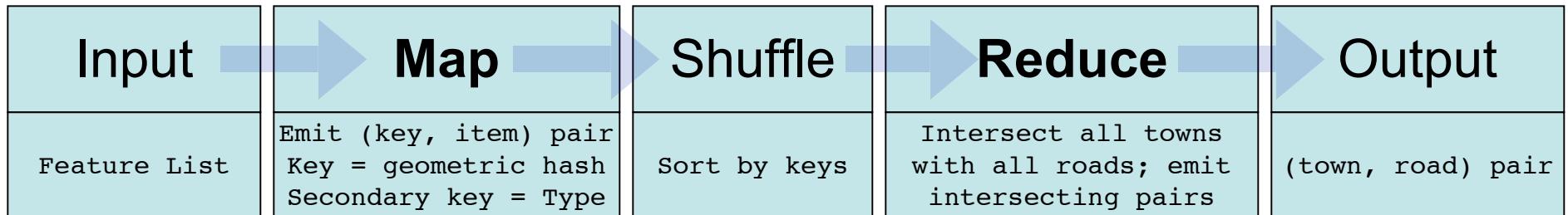
# Reduce on Key B



# Reduce on Key C



# Reduce on Key D



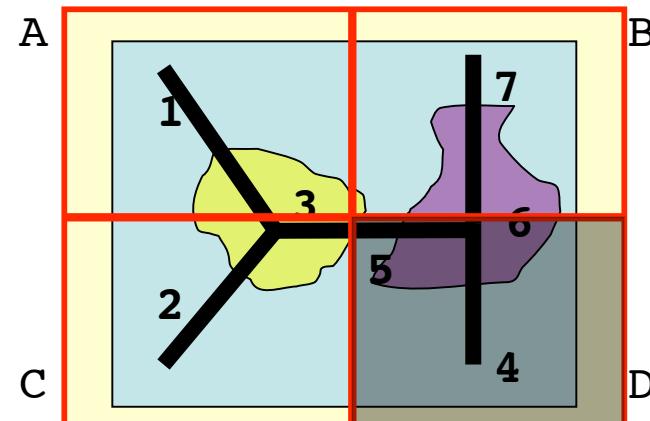
1: Road
2: Road
3: Town
4: Road
5: Road
6: Town
7: Road

(A-Road, 1)
(C-Road, 1)
(C-Road, 2)
(A-Town, 3)
(B-Town, 3)
(C-Town, 3)
(D-Road, 4)
(C-Road, 5)
(D-Road, 5)
(B-Town, 6)
(D-Town, 6)
(B-Road, 7)
(D-Road, 7)

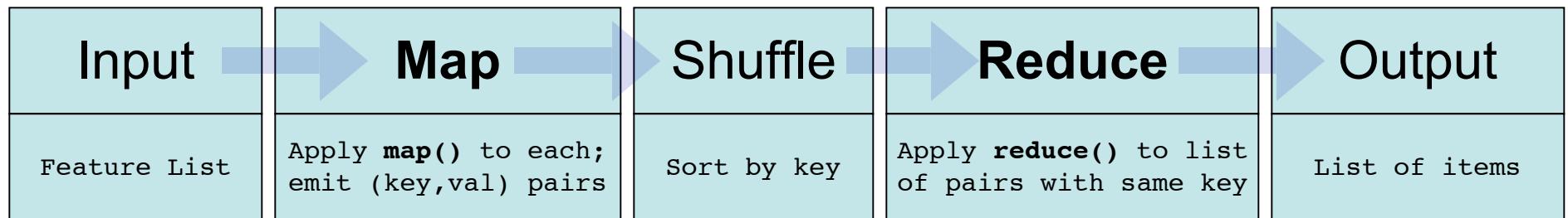


(D-Town, 6)
(D-Road, 4)
(D-Road, 5)
(D-Road, 7)

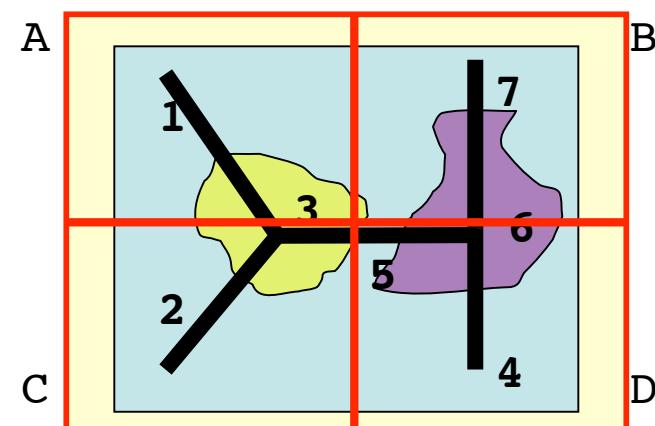
(6, 4)
(6, 5)
(6, 7)



# Output... not quite...

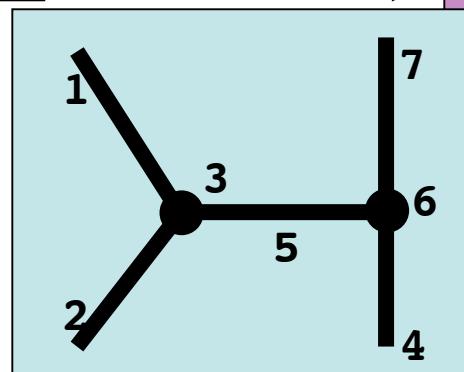
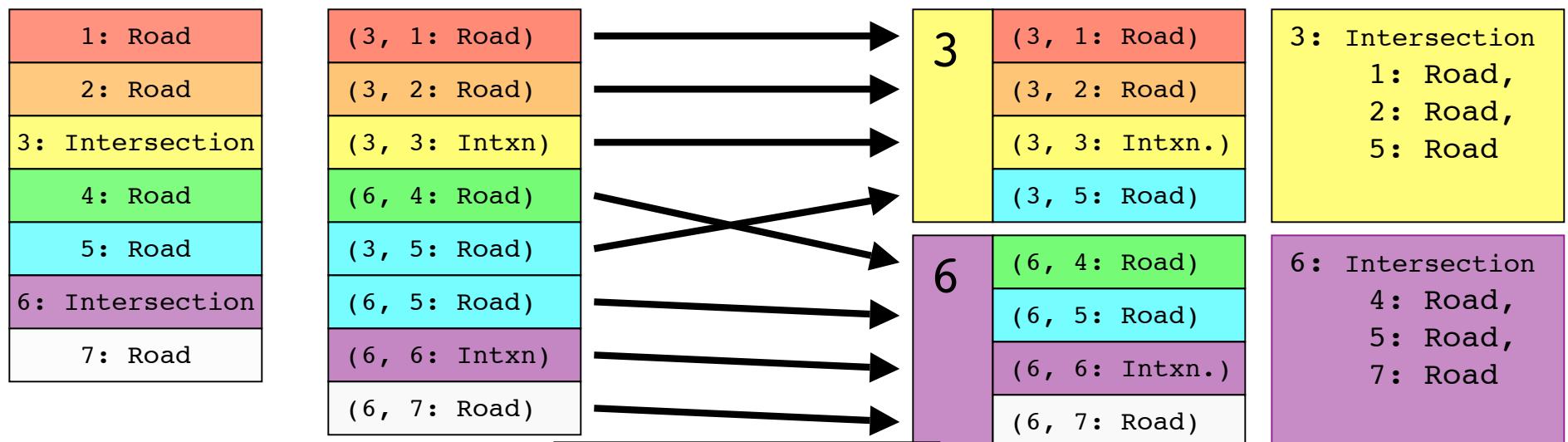
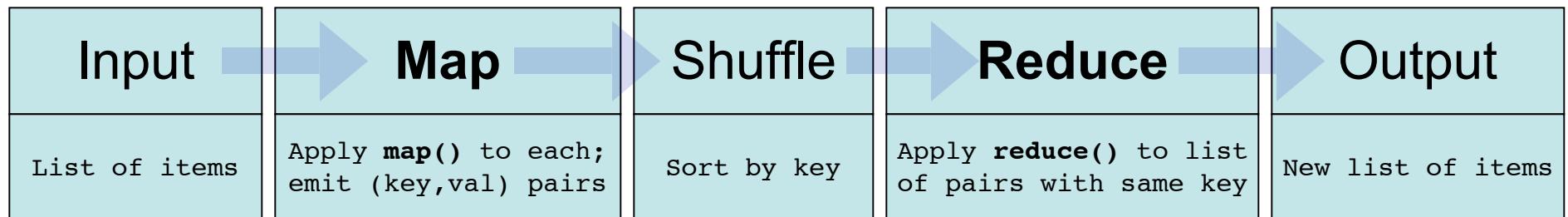


- 1: Road
- 2: Road
- 3: Town
- 4: Road
- 5: Road
- 6: Town
- 7: Road

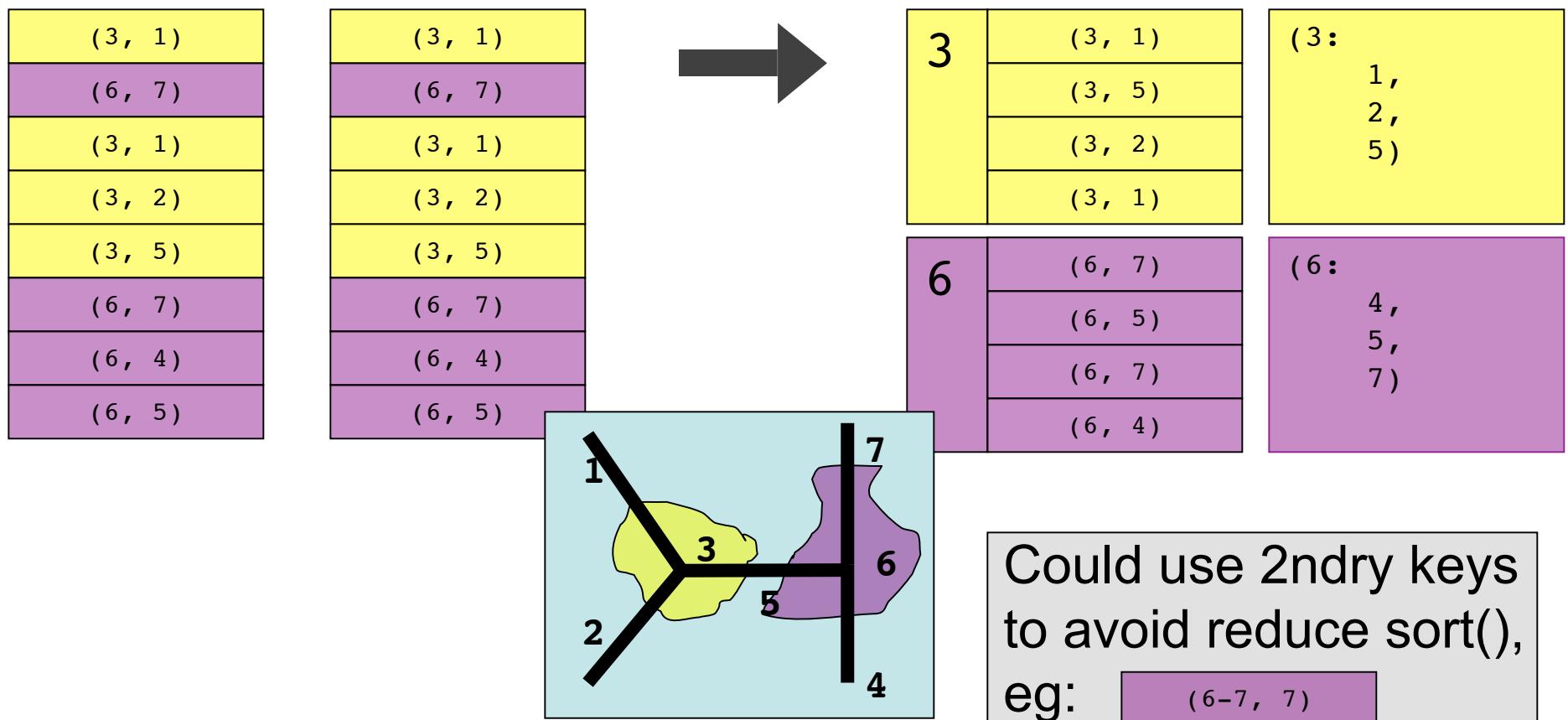
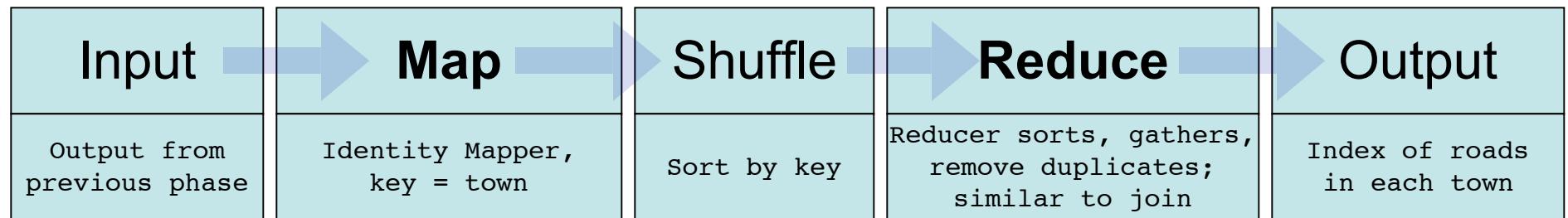


(3, 1)
(6, 7)
(3, 1)
(3, 2)
(3, 5)
(6, 7)
(6, 4)
(6, 5)

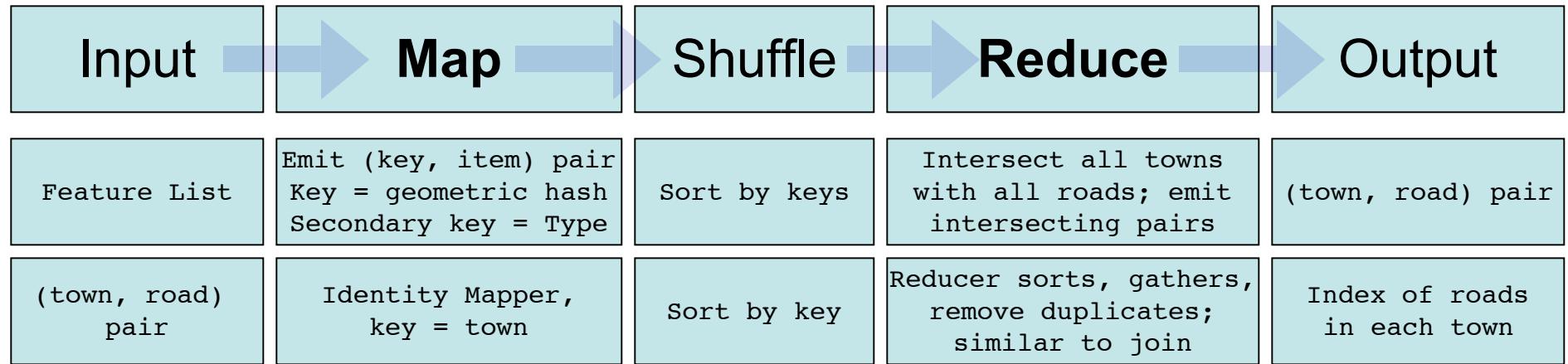
# ...recall earlierJoin Pattern



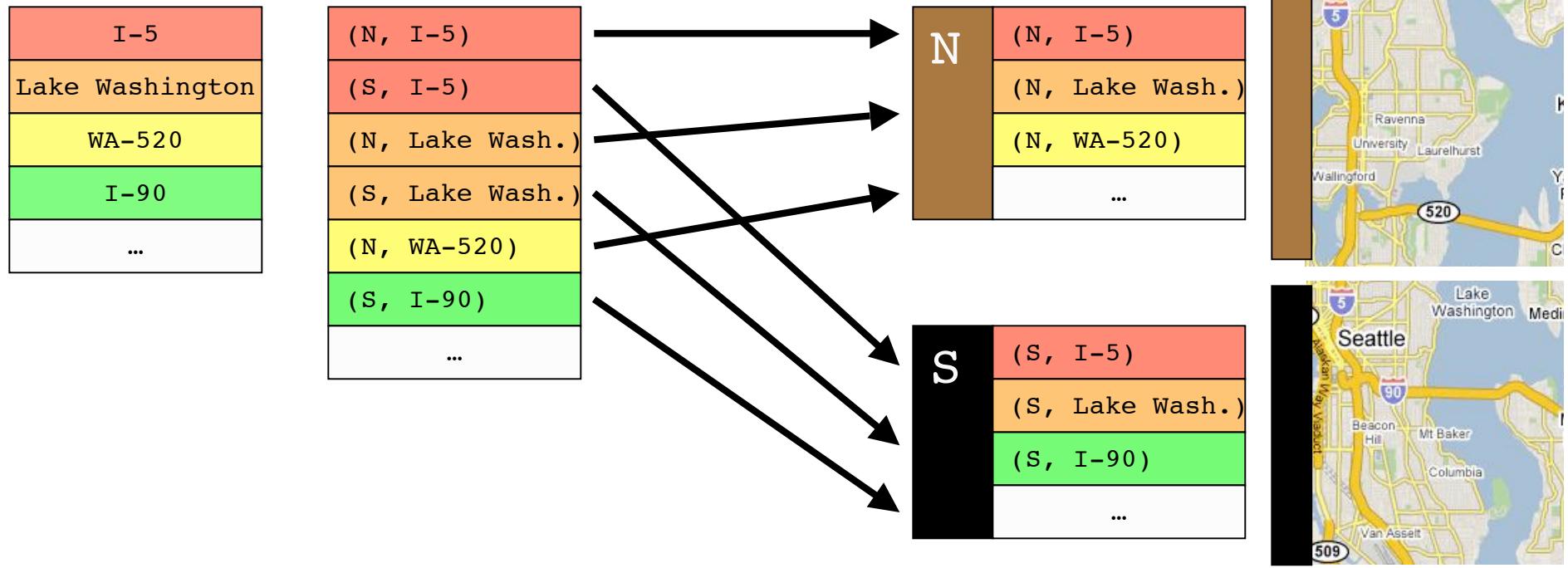
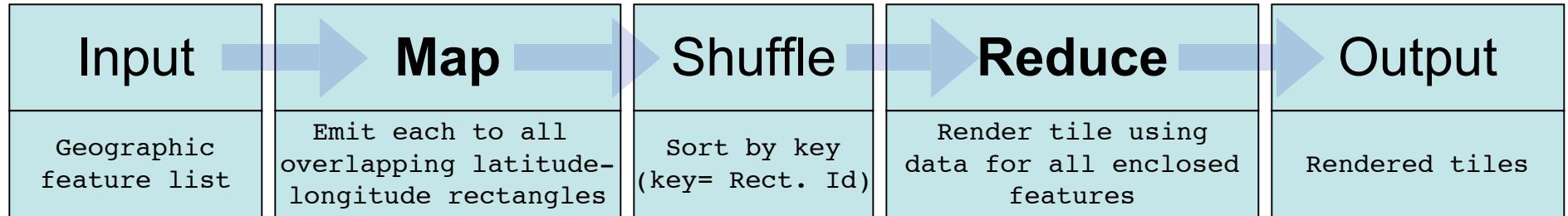
# Recursive Key Join Pattern



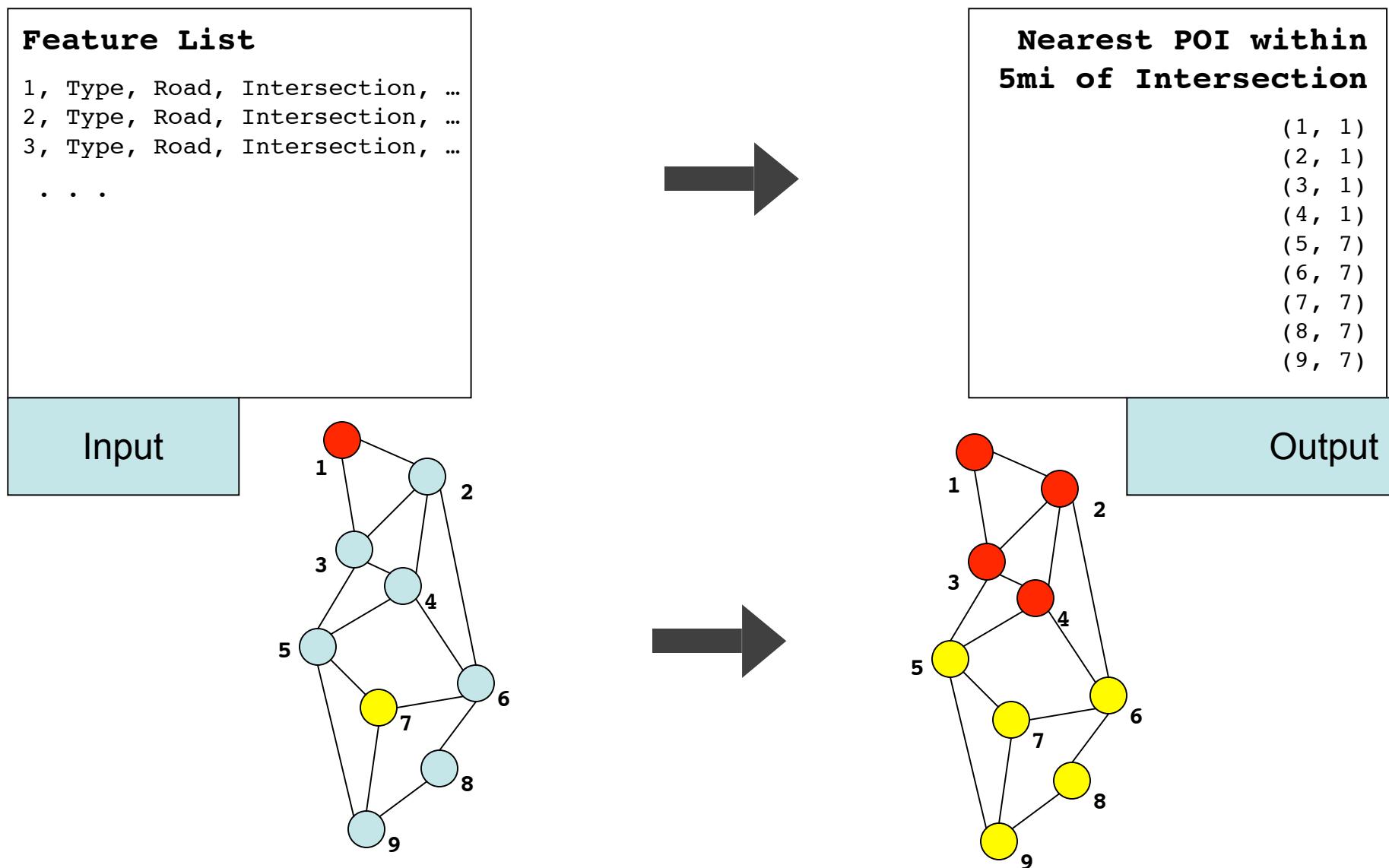
# Chained MapReduce's Pattern



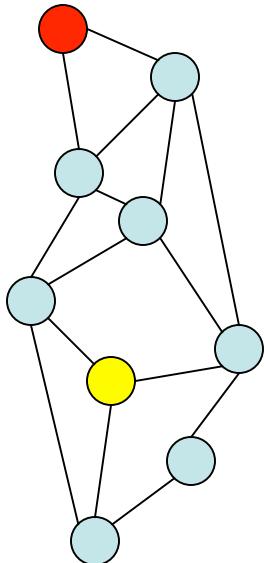
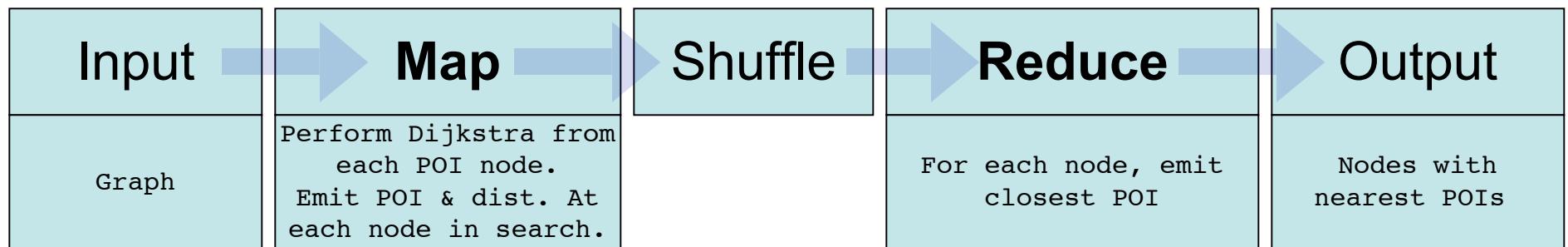
# Distributing Costly Computation: e.g. Rendering Map Tiles



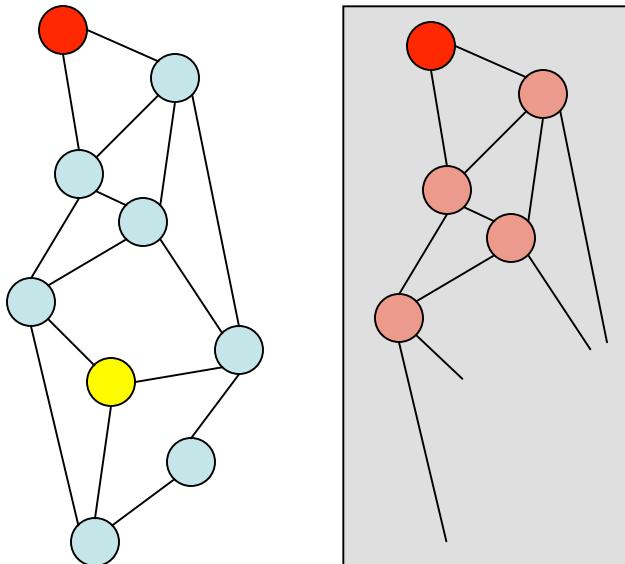
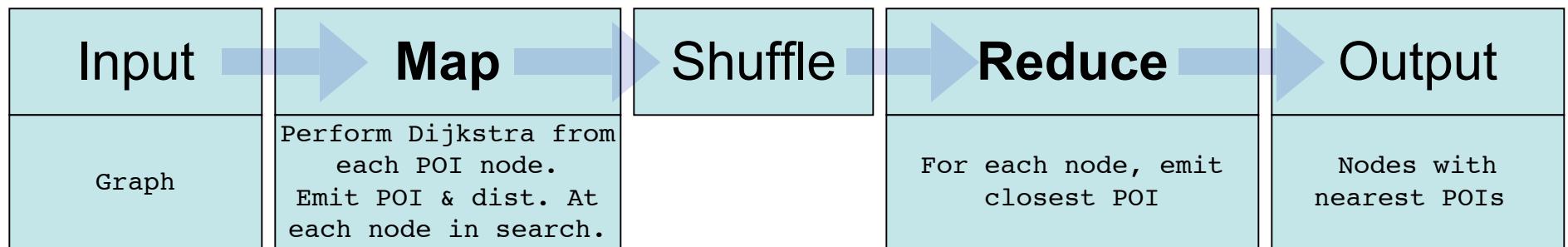
# Finding Nearest Points Of Interest (POIs)



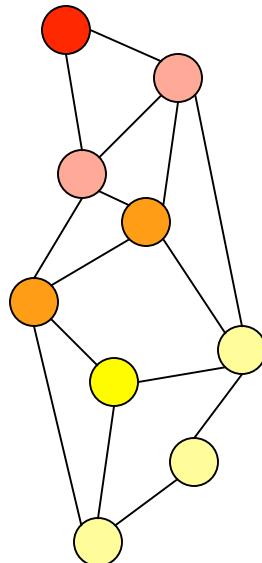
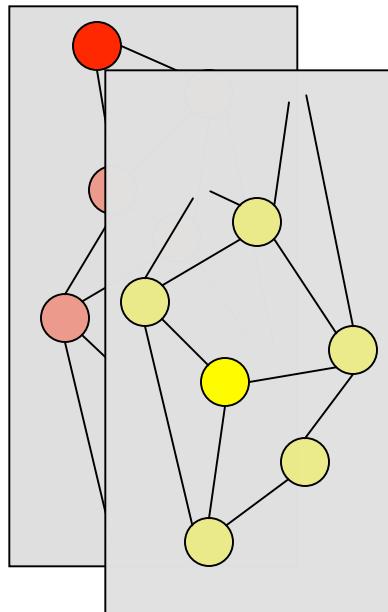
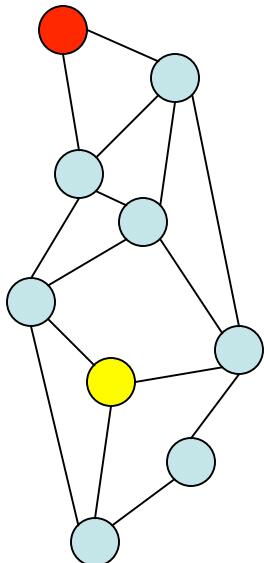
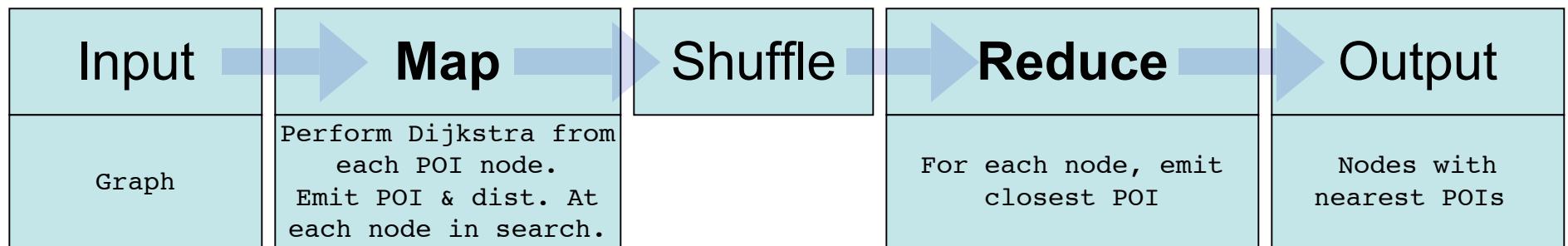
# Finding Nearest POI on a Graph



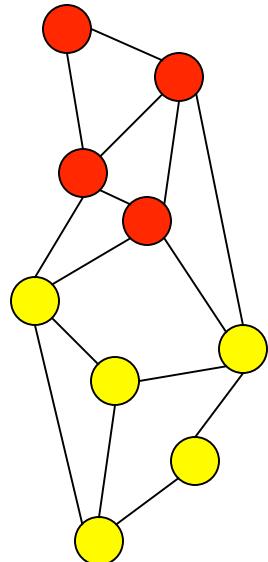
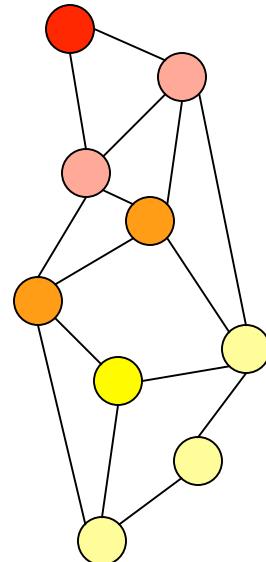
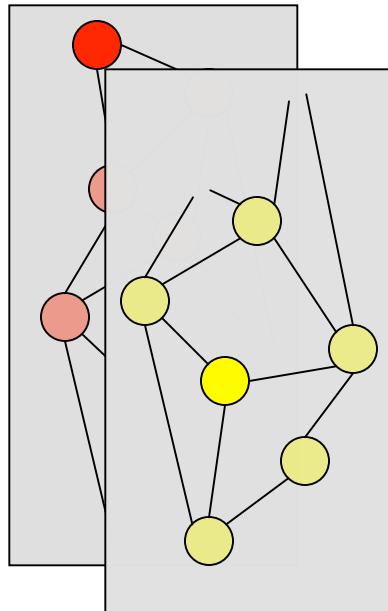
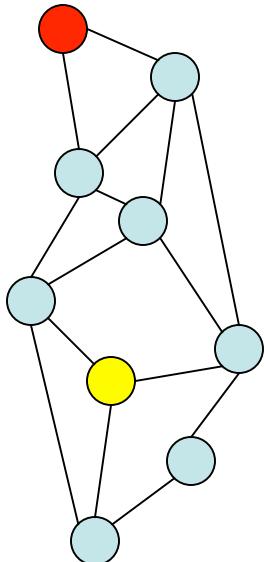
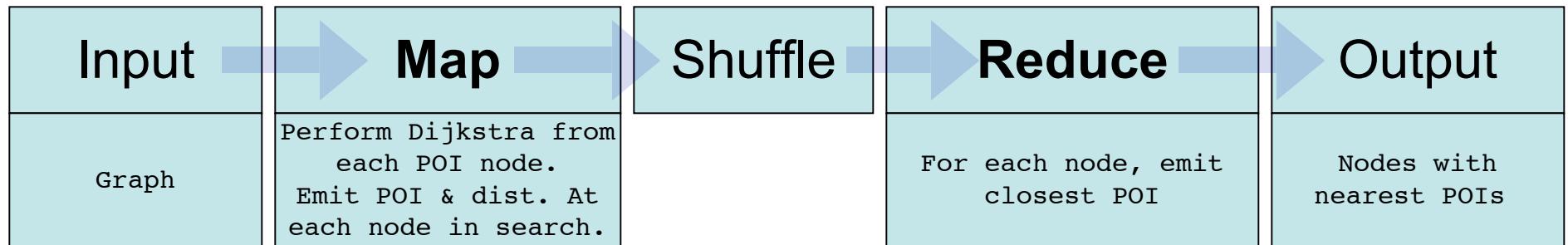
# Finding Nearest POI on a Graph



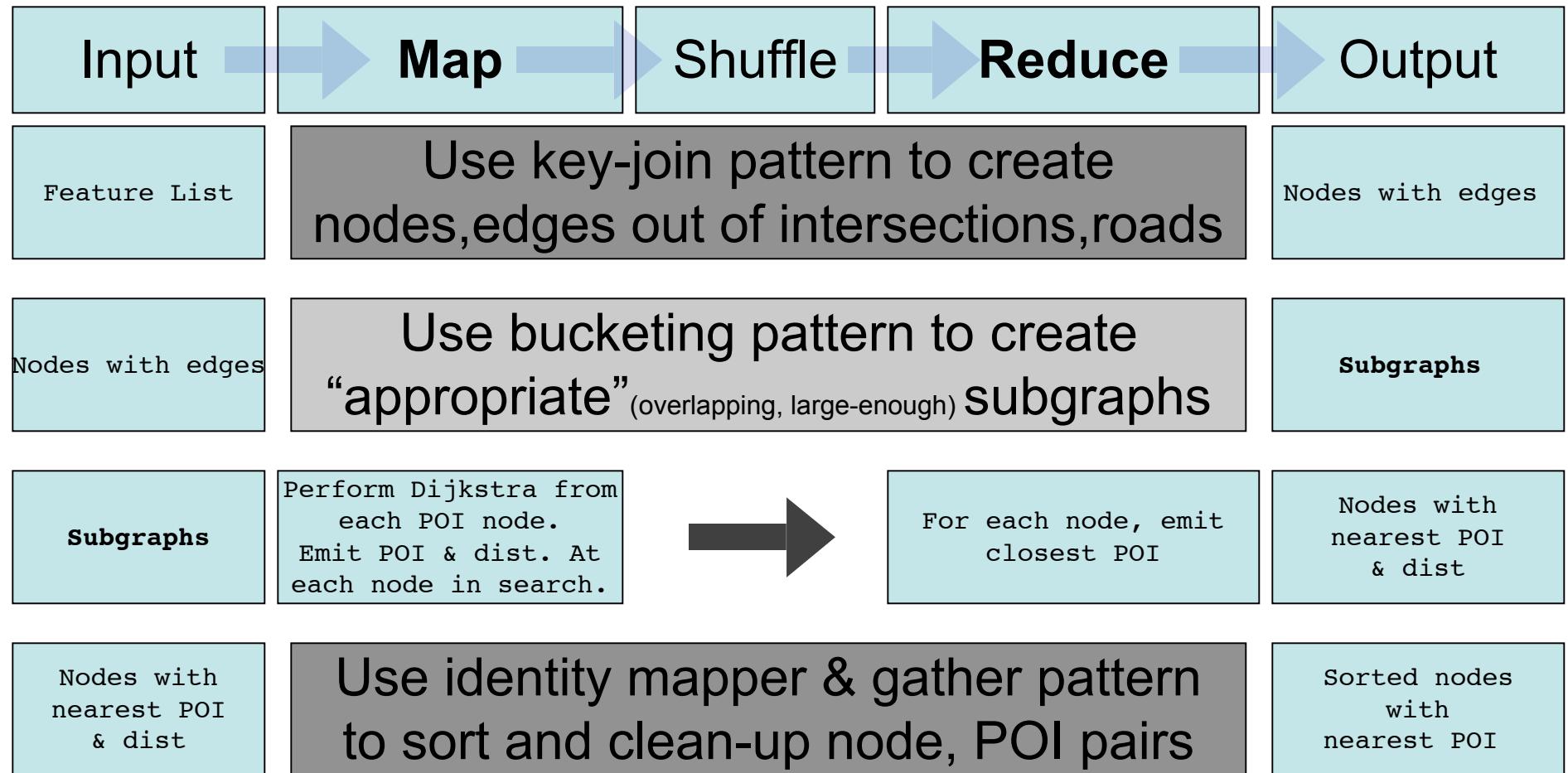
# Finding Nearest POI on a Graph



# Finding Nearest POI on a Graph



# Putting it all together: Nearest POI



# Hard Problems for MapReduce

- Following multiple pointer hops
- Iterative algorithms
- Algorithms with global state
- Operations on graphs without good embeddings
- [insert your favorite challenge here]

# Summary

## MapReduce eases:

- Machine coordination
- Network communication
- Fault tolerance
- Scaling
- Productivity

## MapReduce patterns:

- “Flat” data structures
- Foreign / Recursive Key Joins  
(aka pointer following)
- Hash Joins (aka bucketing)
- Distribute \$\$ computation
- Chain MapReduce phases
- Simplify Reduce() by using secondary keys
- [ insert your pattern here ]

# Questions?

- *MapReduce: Simplified Data Processing on Large Clusters,  
Jeffrey Dean and Sanjay Ghemawat  
OSDI'04: Sixth Symposium on Operating System Design and  
Implementation*
- Contact: [barryb@google.com](mailto:barryb@google.com)

