

# A Parallel Algorithm for MISTs in Bubble-Sort Networks

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# **Selected Paper:**

**Title:** A parallel algorithm for constructing multiple independent spanning trees in bubble-sort networks

# **Drive Link:**

https://drive.google.com/file/d/1leYyetxK3SqK8abssBw3QsNsD-T\_Xwn\_/view?usp=sharing

# **Problem Statement**



# Challenge

Design fault-tolerant, secure networks with disjoint paths.



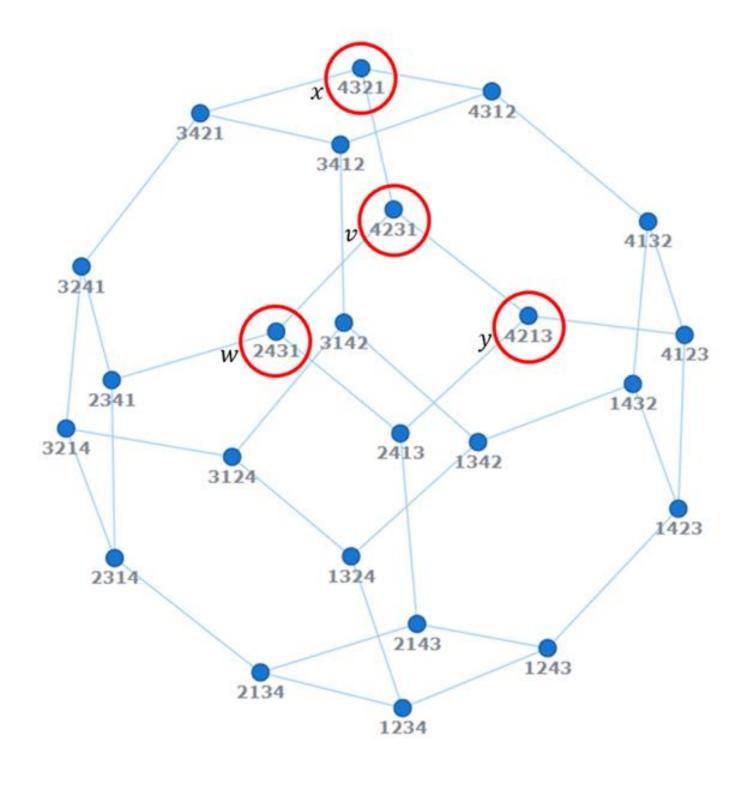
# **Solution**

Requires Multi-path routing and Multiple Independent Spanning Trees (MISTs).



# Limitations

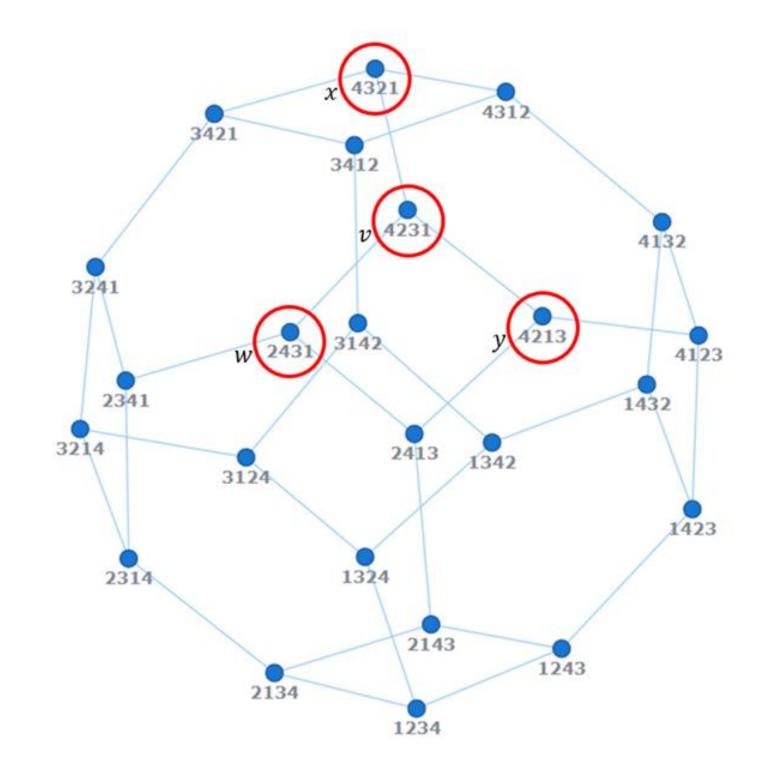
Existing recursive MIST algorithms in B<sub>n</sub> lack parallelization.





 Develop a parallelizable algorithm for constructing Multiple Independent Spanning Trees (MISTs).

 Proposed solution specifically designed for Bubble Sort Networks.



# Terminology: Spanning Trees

## **Definition**

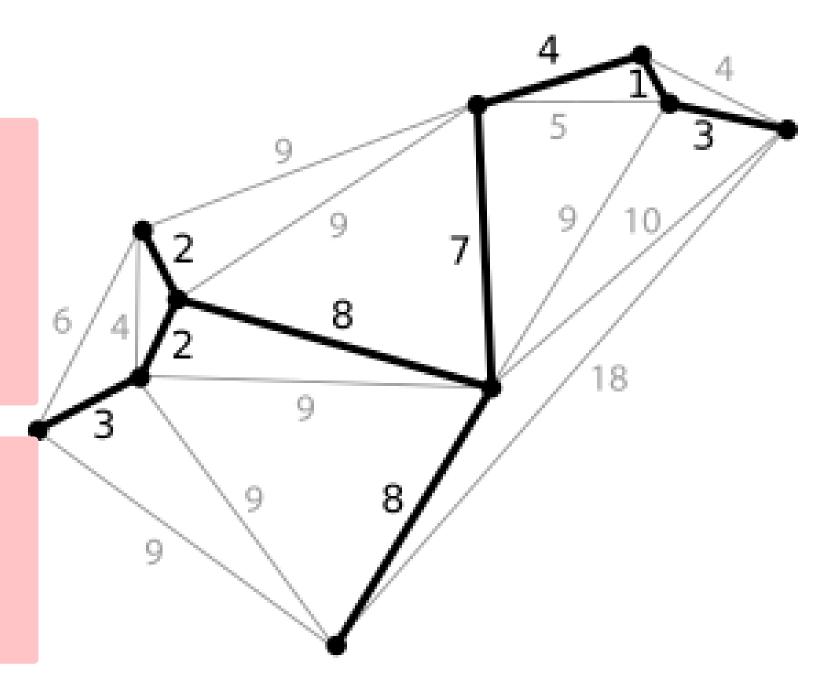
A spanning tree connects all nodes with no cycles.

# **Properties**

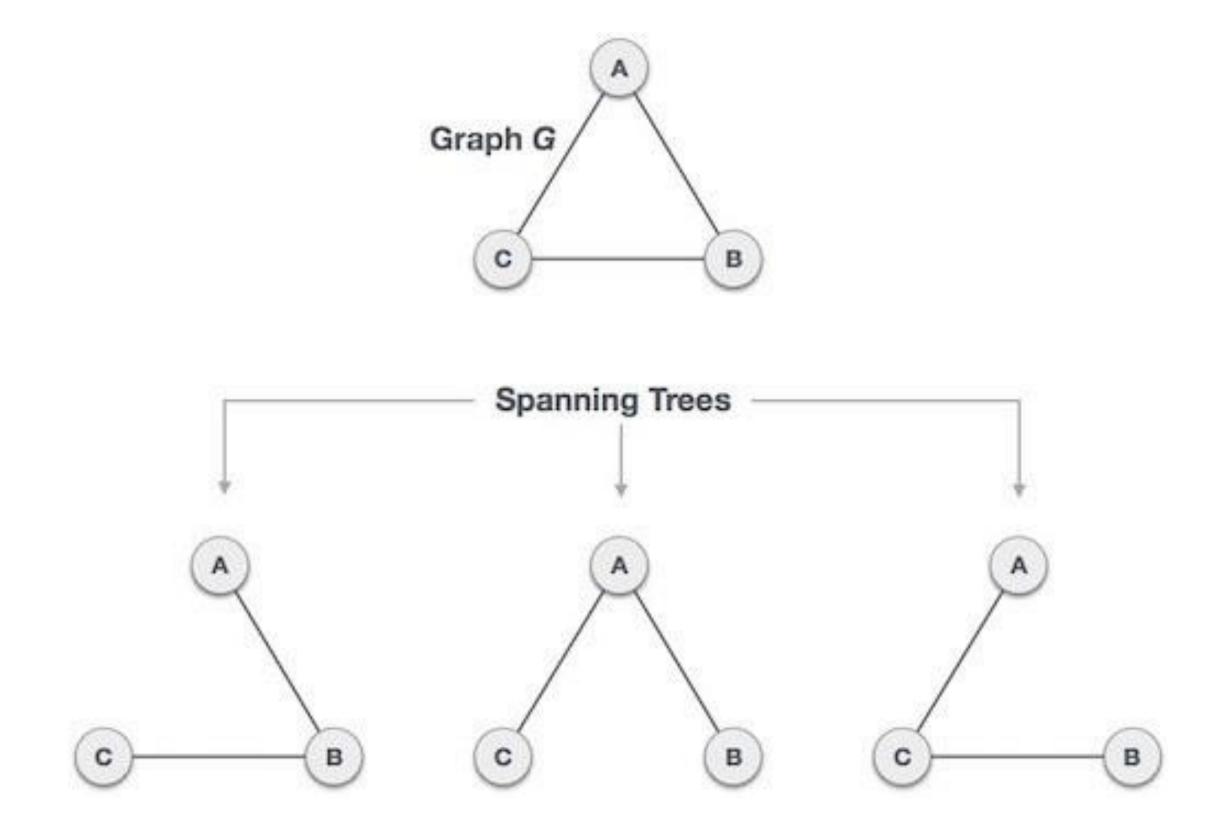
- Includes all vertices of graph
- No cycles, minimal edges

### Uses

Routing backbones, broadcast trees, minimize communication cost.



# Terminology: Spanning Trees



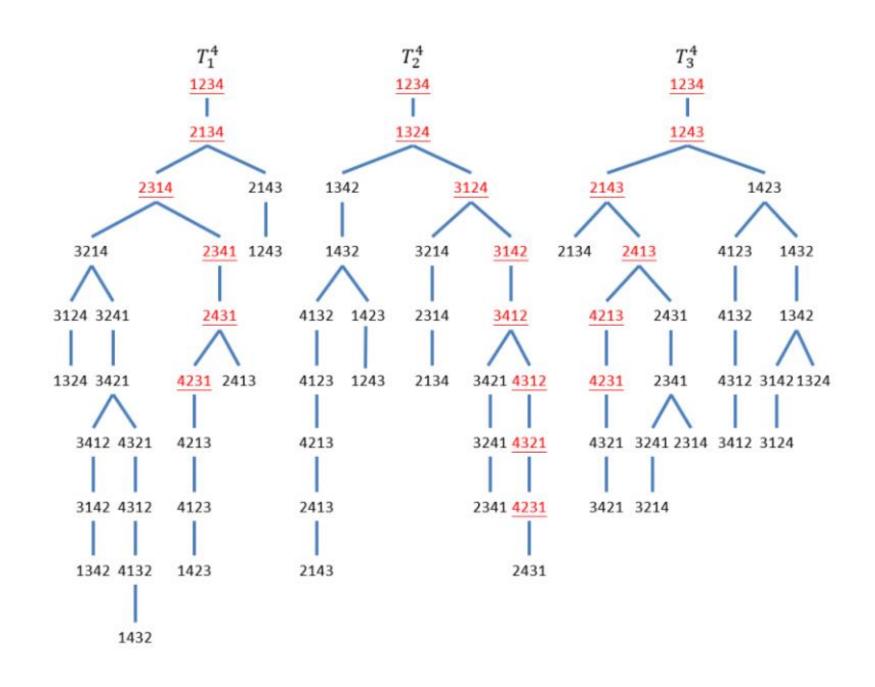
# Terminology: Multiple Independent Spanning Trees (MISTs)

### **Definition**

set of independent spanning trees constructed from the same connected graph G.

# **Properties**

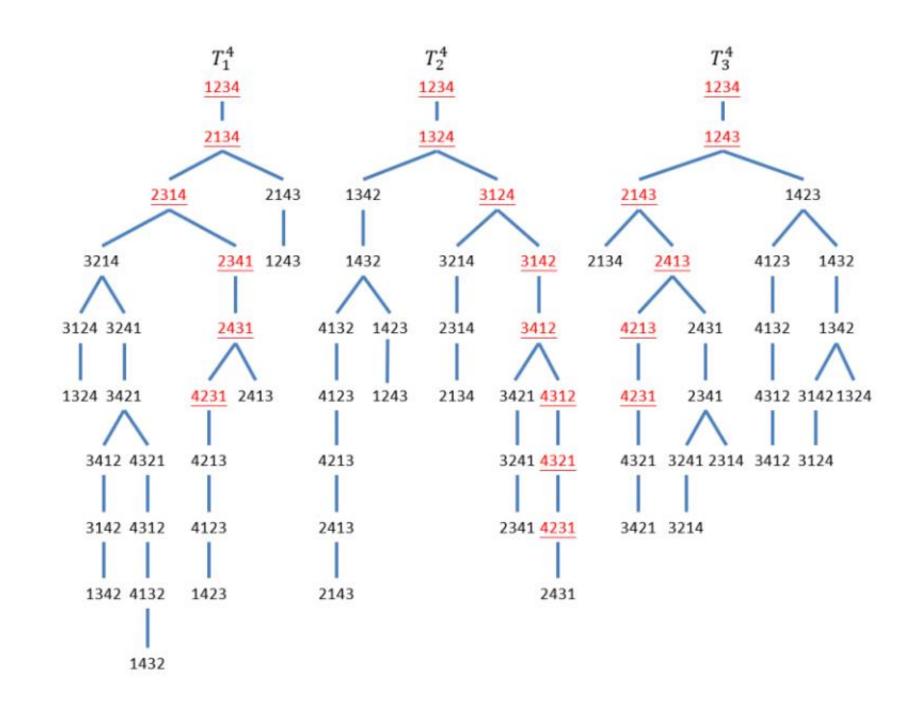
- Valid spanning trees of graph
- Edge-disjoint or vertex-disjoint paths
- Up to k trees in a k-connected graph



# Terminology: Multiple Independent Spanning Trees (MISTs)

# Uses

- Fault Tolerance: If a node or edge fails in one tree, others can still function — crucial in network reliability.
- Parallel Routing: Allows load balancing and reduced congestion by routing data over multiple trees simultaneously.
- **Security & Resilience:** Splitting messages across trees improves confidentiality and resistance to data loss.



# Terminology: Bubble-Sort Network (B<sub>n</sub>)

### **Definition**

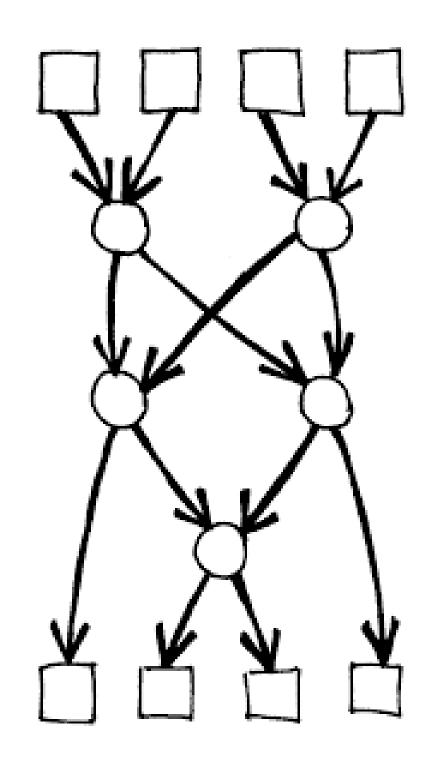
A graph where nodes are all permutations of n elements, and edges represent adjacent swaps (like bubble sort).

# **Properties**

- Vertices: All n! permutations
- Edges: Adjacent transpositions
- Structure: Cayley graph
- Connectivity: n−1
- Diameter: n(n−1)/2

### Uses

- Test routing algorithms
- Simulate broadcasting
- Study network resilience



# Terminology: Bubble-Sort Network (B<sub>n</sub>)

# Example: Bubble sort graph of dimension 3

Permutations:

• Edges:

Each node is connected to others by swapping adjacent elements

 Each edge is an adjacent transposition (like how bubble sort makes swaps).

```
123 — 132

I I

213 — 231

I I

312 — 321
```

# Algorithm Overview

1

### **Core Function**

Parent(v, t, n) computes parent of vertex v in tree  $T_n^t$ .

2

# **Preprocessing**

- Compute v<sup>-1</sup> (inverse permutation)
- Find r(v): first misplaced symbol position

3

### **Decision Rules**

Swap based on conditions of t, rightmost incorrect symbol, or default position v t.

4

### **Parallelism**

Each vertex's parent computed independently, suitable for parallelization.

### **Algorithm 1:** Parent1(v, t, n)

```
Input: v: the vertex v = v_1 \dots v_n \in V(B_n) \setminus \{1_n\}
                 t: the t-th tree T_t^n in IST
                n: the dimension of B_n
    Output: p: p = Parent1(v, t, n) the parent of v in T_t^n
    if v_n = n then
          if t \neq n-1 then p = \text{FindPosition}(v)
          else p = \operatorname{Swap}(v, v_{n-1})
    end
    else
         if v_n = n - 1 and v_{n-1} = n and \operatorname{Swap}(v, n) \neq \mathbf{1}_n then
               if t = 1 then p = \text{Swap}(v, n)
(3)
               else p = \operatorname{Swap}(v, t - 1)
(4)
          end
          else
              if v_n = t then p = \operatorname{Swap}(v, n)
(5)
              else p = \operatorname{Swap}(v, t)
(6)
         end
    end
    return p
```

### Function FindPosition(v)

```
Input: v: the vertex v = v_1 \cdots v_n in B_n
Output: p: the vertex adjacent to v in B_n

(1.1) if t = 2 and \operatorname{Swap}(v, t) = \mathbf{1}_n then p = \operatorname{Swap}(v, t - 1)

(1.2) else if v_{n-1} \in \{t, n-1\} then j = r(v), p = \operatorname{Swap}(v, j)

(1.3) else p = \operatorname{Swap}(v, t)
return p
```

### Function Swap(v, x)

```
Input : v: the vertex v = v_1 \cdots v_n in B_n

x: the symbol in the vertex v_1 \cdots v_n

Output: p: the vertex adjacent to v in B_n

i = v^{-1}(x), p = v\langle i \rangle

return p
```

**Table 1** The parent of every vertex  $v \in V(B_4) \setminus \{\mathbf{1}_4\}$  in  $T_t^4$  for  $t \in \{1, 2, 3\}$  calculated by Algorithm 1

# **Results and Complexity**

# **Time Complexity Analysis:**

- Per Vertex: O(n) time to compute parent
- Total:  $O(n \times n!)$  for all vertices in  $B_n$

# Parallelism:

Fully parallelizable — each vertex's parent computed independently

# **Upper Bound:**

Asymptotically optimal for Bubble Sort Network of size n!

v	t	$v_4$	Rule	p	v	t	$v_4$	Rule	p
1234						1		(1.3)	3214
	-	-	-	-	3124	2	4	(1.2)	1324
						3		(2)	3142
1243	1		(6)	2143		1		(6)	3412
	2	3	(6)	1423	3142	2	2	(5)	3124
	3		(5)	1234		3		(6)	1342
1324	1		(1.3)	3124		1		(1.2)	2314
	2	4	(1.2)	1234	3214	2	4	(1.3)	3124
	3		(2)	1342		3		(2)	3241
1342	1		(6)	3142		1		(5)	3214
	2	2	(5)	1324	3241	2	1	(6)	3421
	3		(6)	1432		3		(6)	2341
1423	1		(6)	4123		1		(6)	3421
	2	3	(6)	1432	3412	2	2	(5)	3142
	3		(5)	1243		3		(6)	4312
1432	1		(6)	4132		1		(5)	3241
	2	2	(5)	1342	3421	2	1	(6)	3412
	3		(6)	1423		3		(6)	4321
2134	1		(1.2)	1234		1		(6)	4213
	2	4	(1.1)	2314	4123	2	3	(6)	4132
	3		(2)	2143		3		(5)	1423
2143	1		(3)	2134		1		(6)	4312
	2	3	(4)	2413	4132	2	2	(5)	1432
	3		(4)	1243		3		(6)	4123
2314	1		(1.2)	2134		1		(6)	4231
	2	4	(1.3)	3214	4213	2	3	(6)	4123
	3		(2)	2341		3		(5)	2413
2341	1		(5)	2314		1		(5)	2431
	2	1	(6)	3241	4231	2	1	(6)	4321
	3		(6)	2431		3		(6)	4213
2413	1		(6)	2431		1		(6)	4321
	2	3	(6)	4213	4312	2	2	(5)	3412
	3		(5)	2143		3		(6)	4132
2431	1		(5)	2341		1		(5)	3421
	2	1	(6)	4231	4321	2	1	(6)	4312
	3		(6)	2413		3		(6)	4231

# **Proposed Solution**

# No Need for METIS

- Parent computation is fully local, so graph partitioning is unnecessary.
- Embarrassingly Parallel Problem (No communication needed between machines)

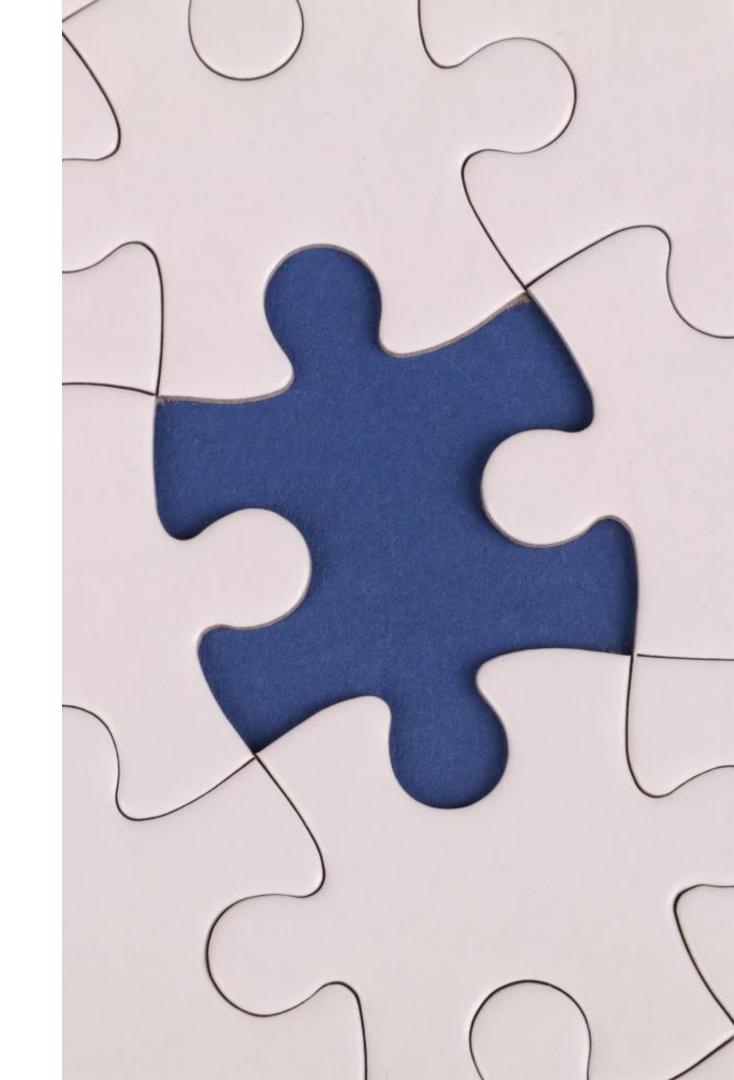
# **MPICH – Inter-node Parallelism**

- Distributes Spanning Tree Construction across machines
- Master assigns tree ranges to each machine
- Workers return constructed subtrees to master

# **Proposed Solution**

# OpenMP – Intra-node Parallelism

- Used within each machine for vertex-level parallelism
- Parent computation parallelized using OpenMP threads
- No synchronization needed due to independence of iterations



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