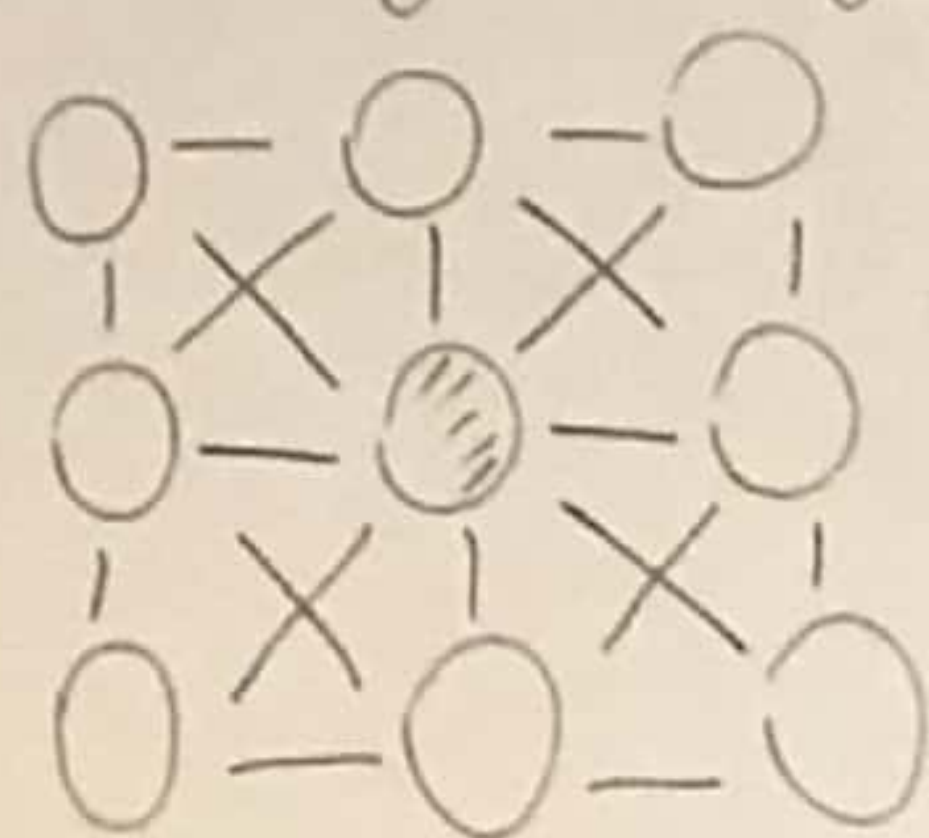


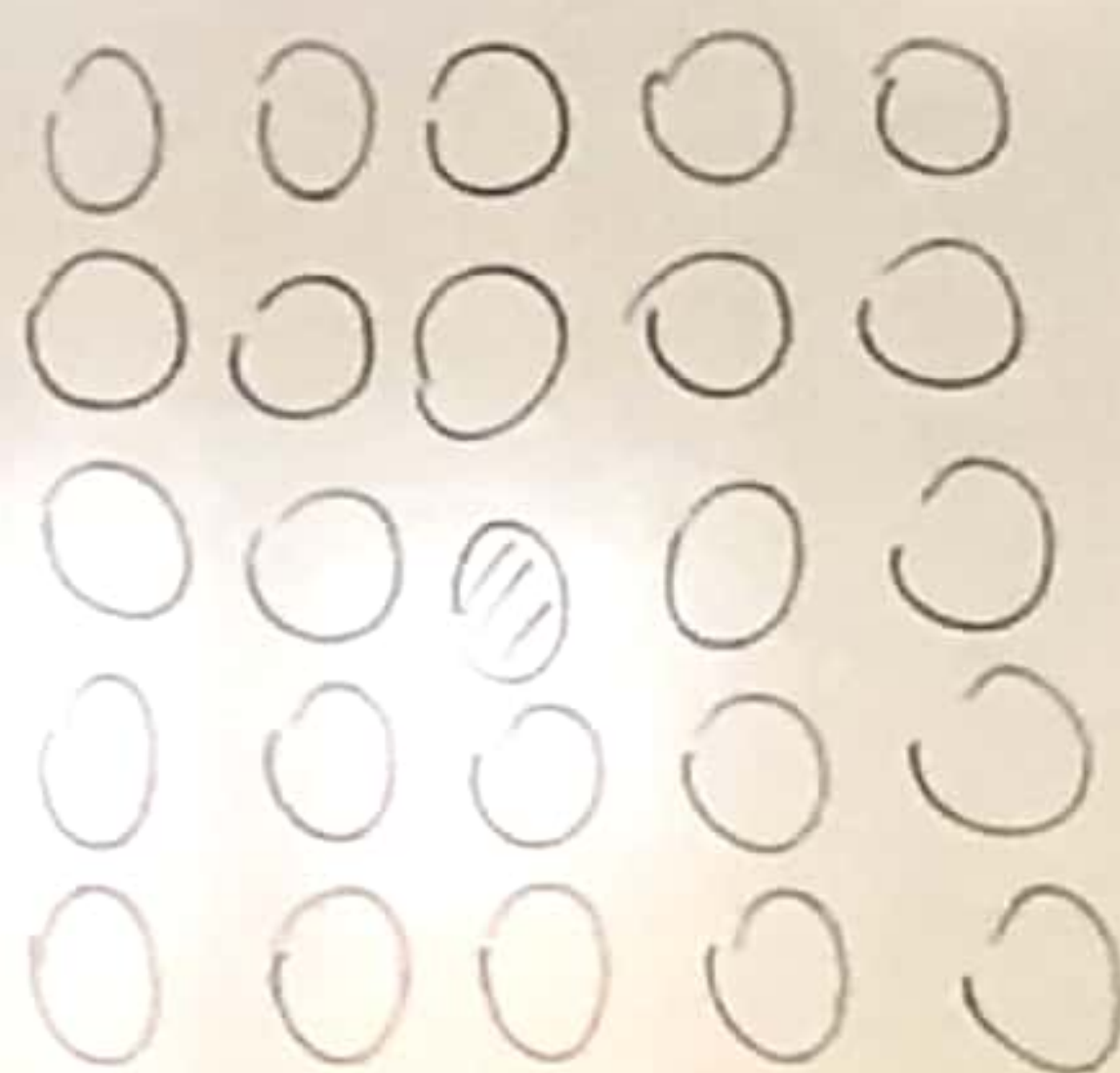
# CELLULAR NEURAL NETWORKS

A Cellular Neural Network (CNN) is an array of cells with local connections only. The communication is allowed just between neighbouring units.



$r=1$

$r$ : radius of neighborhood



$r=2$

If  $r=1$  then we call "3x3" neighborhood  
 $r=2$  " " " "5x5" "  
 $\vdots$  " " " " $(2n+1) \times (2n+1)$ " "  
 $r=n$  " " " "

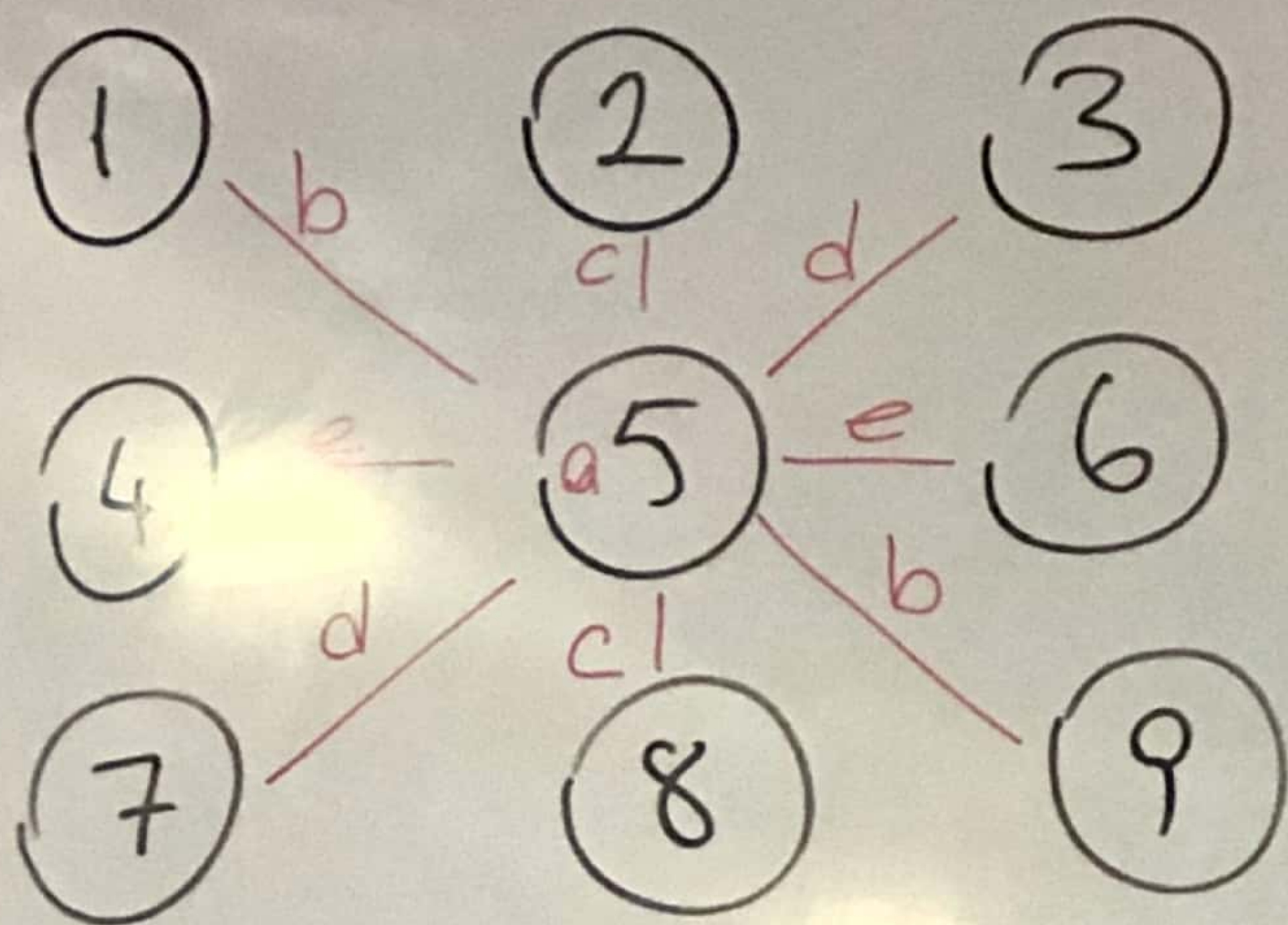
In order to calculate the state of the cells, it is necessary to define the template of the network.

$$T: \begin{Bmatrix} b & c & d \\ e & a & e \\ d & c & b \end{Bmatrix}$$

3x3 neighborhood

$T$ : template (symmetric)  
 $(2r+1) \times (2r+1)$   
 Dimension of the template.





a: feedback of the central cell

c: " of the above and below neighbor cells.

d: " of the right-above and left-below " "

b: " " " left-above and right-below " "

e: " " " right and left " "



The CNN dynamics are described by a system of nonlinear differential equations:

$$\dot{x} = -x + Ay(x) + u$$

or

$$\dot{x}_i = -x_i + \sum_{j=1}^n q_{ij} \cdot y(x_j) + u_i, \quad i=1,2,\dots,n$$

where

$x = [x_1 \ x_2 \ \dots \ x_n]^T$ : State of cell

$A = \{q_{ij}\}_{n \times n}$ : Feedback matrix that contains the weights of the network

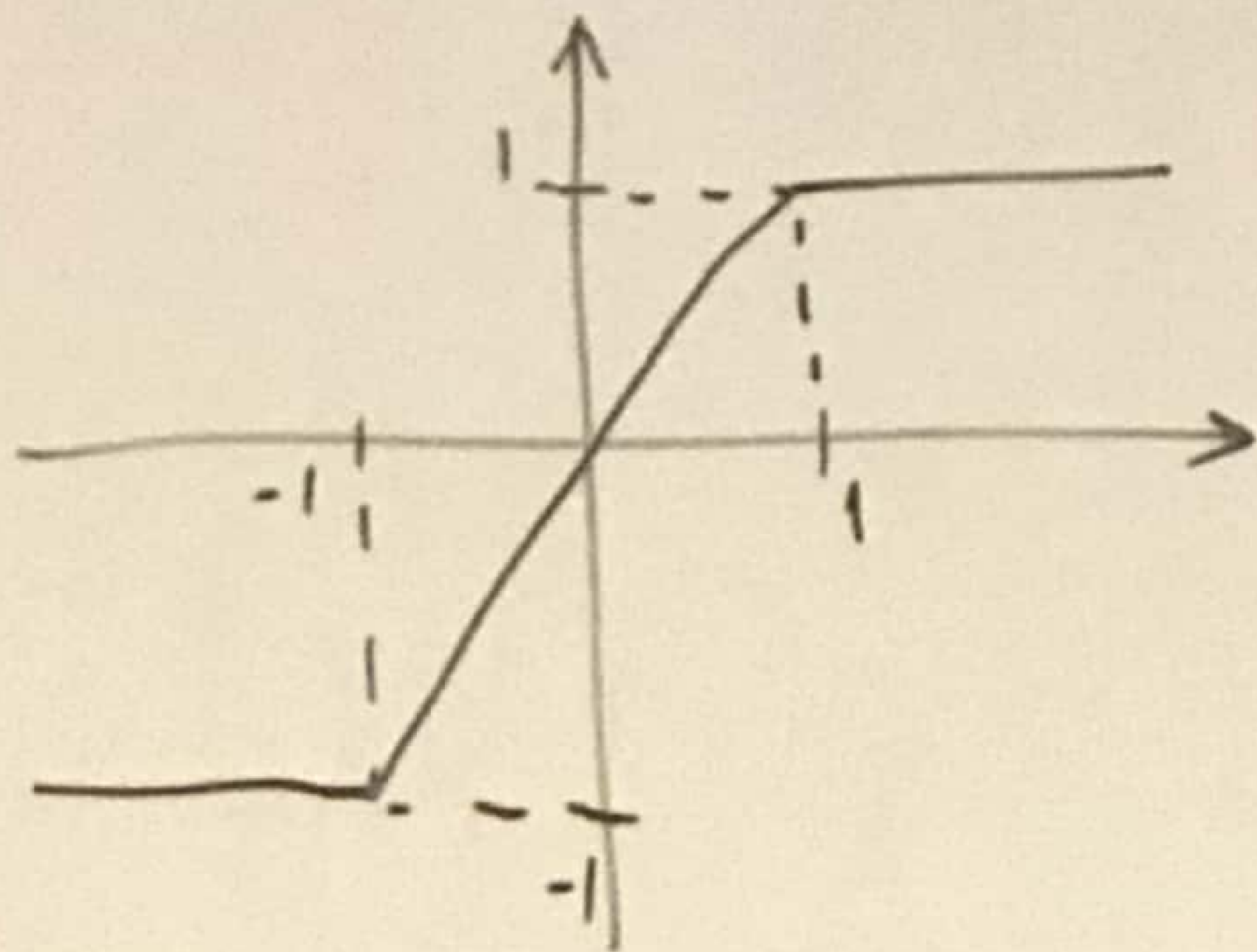
$u = [u_1 \ u_2 \ \dots \ u_n]^T$ : Input

$y(x) = [y(x_1) \ y(x_2) \ \dots \ y(x_n)]^T$ : Output



The expression for the output  $y$  is :

$$y(x_i) = \frac{1}{2} [ |x_i + 1| - |x_i - 1| ]$$



piece-wise linear function



Ex.1

$$T: \begin{Bmatrix} b & c & d \\ e & a & e \\ d & c & b \end{Bmatrix}$$

(1) (2) (3)

(4) (5) (6)

(7) (8) (9)

The state equations of the CNN:

$$\dot{x}_1 = -x_1 + a y(x_1) + e y(x_2) + c y(x_4) + b y(x_5) + u_1$$

$$\dot{x}_2 = -x_2 + e y(x_1) + a y(x_2) + e y(x_3) + a y(x_4) + c y(x_5) + b y(x_6) + u_2$$

$$\dot{x}_3 = -x_3 + e y(x_2) + a y(x_3) + d y(x_5) + c y(x_6) + u_3$$

$$\dot{x}_4 = -x_4 + c y(x_1) + d y(x_2) + a y(x_4) + e y(x_5) + c y(x_7) + b y(x_8) + u_4$$

$$\dot{x}_5 = -x_5 + b y(x_1) + c y(x_2) + d y(x_3) + e y(x_4) + a y(x_5) + e y(x_6) + d y(x_7) + c y(x_8) + b y(x_9) + u_5$$

$$\dot{x}_6 = -x_6 + b y(x_2) + c y(x_3) + e y(x_5) + a y(x_6) + d y(x_8) + c y(x_9) + u_6$$

$$\dot{x}_7 = -x_7 + c y(x_4) + d y(x_5) + a y(x_7) + e y(x_8) + u_7$$

$$\dot{x}_8 = -x_8 + b y(x_4) + c y(x_5) + d y(x_6) + e y(x_7) + a y(x_8) + e y(x_9) + u_8$$

$$\dot{x}_9 = -x_9 + b y(x_5) + c y(x_6) + e y(x_8) + a y(x_9) + u_9$$

$$\dot{x} = -$$

$$\dot{x}_1$$

$$\dot{x}_2$$

$$\dot{x}_3$$

$$\dot{x}_4$$

$$\dot{x}_5$$

$$\dot{x}_6$$

$$\dot{x}_7$$

$$\dot{x}_8$$

$$\dot{x}_9$$

$$\dot{x}_{10}$$

$$\dot{x}_{11}$$

$$\dot{x}_{12}$$

$$\dot{x}_{13}$$

$$\dot{x}_{14}$$

$$\dot{x}_{15}$$



$$\dot{x} = -x + A \cdot y(x) + u$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \\ \dot{x}_4 \\ \dot{x}_5 \\ \dot{x}_6 \\ \dot{x}_7 \\ \dot{x}_8 \\ \dot{x}_9 \end{bmatrix} = - \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \\ x_9 \end{bmatrix} + \begin{bmatrix} a & e & 0 & c & b & 0 & 0 & 0 & 0 \\ e & a & e & d & c & b & 0 & 0 & 0 \\ 0 & e & a & 0 & d & c & 0 & 0 & 0 \\ c & d & 0 & 0 & e & 0 & c & b & 0 \\ b & c & d & e & a & e & d & c & b \\ 0 & b & c & 0 & e & a & 0 & d & c \\ 0 & 0 & 0 & c & d & 0 & a & e & 0 \\ 0 & 0 & 0 & b & c & d & e & a & e \\ 0 & 0 & 0 & 0 & b & c & 0 & e & a \end{bmatrix} \begin{bmatrix} y(x_1) \\ y(x_2) \\ y(x_3) \\ y(x_4) \\ y(x_5) \\ y(x_6) \\ y(x_7) \\ y(x_8) \\ y(x_9) \end{bmatrix} + \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ u_6 \\ u_7 \\ u_8 \\ u_9 \end{bmatrix}$$

9) + u<sub>5</sub>



described by a  
differential equations:

,  $i=1,2,\dots,n$

contains

Ex.

$$T: \begin{Bmatrix} b & c & d \\ e & a & e \\ d & c & b \end{Bmatrix}$$

(1) (2) (3)

(4) (5) (6)

(7) (8) (9)

$$\begin{bmatrix} e & 0 & c & b & 0 & 0 & 0 & 0 \\ e & a & e & d & c & b & 0 & 0 & 0 \\ 0 & e & a & 0 & d & c & 0 & 0 & 0 \end{bmatrix}$$

The state equations of the CNN:

$$\dot{x}_1 = -x_1 + a \cdot y(x_1) + e y(x_2) + c y(x_4) + b y(x_6)$$

$$\dot{x}_2 = -x_2 + e y(x_1) + a y(x_2) + e y(x_3) + d y(x_5)$$

$$\dot{x}_3 = -x_3 + e y(x_2) + a y(x_3) + d y(x_5) + c y(x_7)$$

$$\dot{x}_4 = -x_4 + c y(x_1) + d y(x_2) + a y(x_4) + e y(x_6)$$

$$\dot{x}_5 = -x_5 + b y(x_1) + c y(x_2) + d y(x_3) + e y(x_4) + a y(x_6)$$

$$\dot{x}_6 = -x_6 + b y(x_2) + c y(x_3) + e y(x_5) + a y(x_6)$$

$$\dot{x}_7 = -x_7 + c y(x_4) + d y(x_5) + a y(x_7) + e y(x_8)$$

$$\dot{x}_8 = -x_8 + b y(x_4) + c y(x_5) + d y(x_6) + e y(x_7) + a y(x_9)$$

$$\dot{x}_9 = -x_9 + b y(x_5) + c y(x_6) + e y(x_8) + a y(x_9)$$