view_frames Result Recorded at time: 854.761 map Broadcaster: /amcl Average rate: 45.760 Hz Most recent transform: 855.198 (-0.437 sec old) Buffer length: 3.125 sec odom Broadcaster: /gazebo Average rate: 10.370 Hz Most recent transform: 854.711 (0.050 sec old) Buffer length: 2.700 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.378 Hz Average rate: 10.378 Hz Most recent transform: 0.000 (854.761 sec old) Most recent transform: 0.000 (854.761 sec old) Most recent transform: 854.692 (0.069 sec old) Most recent transform: 854.692 (0.069 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 2.698 sec Buffer length: 2.698 sec hokuyo left_wheel right_wheel camera