# DATA STRUCTURES AND ALGORITHMS

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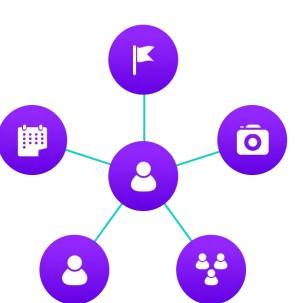


# Graph Data Structure

A graph data structure is a collection of nodes that have data and are connected to other nodes.

Let's try to understand this through an example. On facebook, everything is a node. That includes User, Photo, Album, Event, Group, Page, Comment, Story, Video, Link, Note...anything that has data is a node.

Every relationship is an edge from one node to another. Whether you post a photo, join a group, like a page, etc., a new edge is created for that relationship.

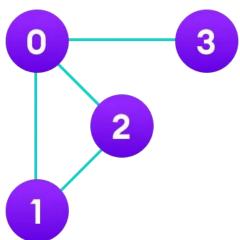


# Graph Data Structure

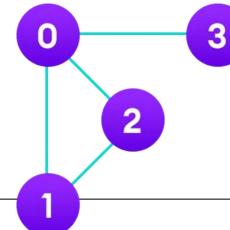
### A graph is a data structure (V, E) that consists of

- >A collection of vertices V
- >A collection of edges E, represented as ordered pairs of vertices (u,v)

$$V = \{0, 1, 2, 3\}$$
  
 $E = \{(0,1), (0,2), (0,3), (1,2)\}$   
 $G = \{V, E\}$ 



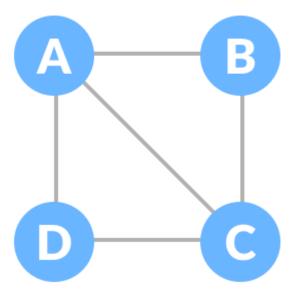
# **Graph Terminology**



- •Adjacency: A vertex is said to be adjacent to another vertex if there is an edge connecting them. Vertices 2 and 3 are not adjacent because there is no edge between them.
- •Path: A sequence of edges that allows you to go from vertex A to vertex B is called a path. 0-1, 1-2 and 0-2 are paths from vertex 0 to vertex 2.
- •Directed Graph: A graph in which an edge (u,v) doesn't necessarily mean that there is an edge (v, u) as well. The edges in such a graph are represented by arrows to show the direction of the edge.

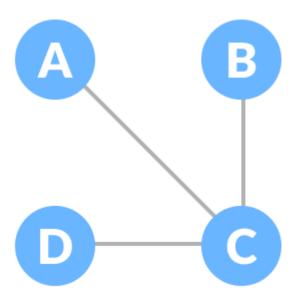
# Undirected Graphs

An **undirected graph** is a graph in which the edges do not point in any direction (ie. the edges are bidirectional).



# Connected Graphs

A **connected graph** is a graph in which there is always a path from a vertex to any other vertex.



## **Graph Representation**

Graphs are commonly represented in two ways:

- 1. Adjacency Matrix
- 2. Adjacency List

### **Graph Representation: Adjacency Matrix**

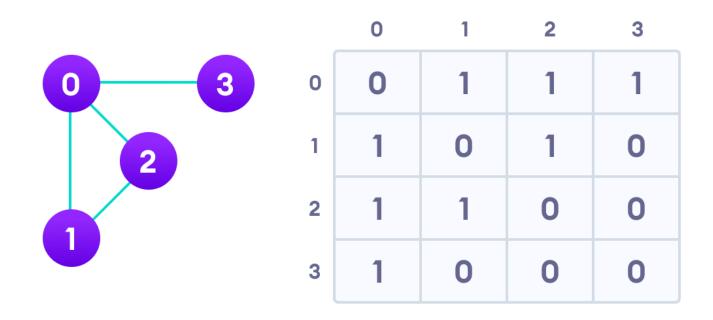
### **Adjacency Matrix**

An adjacency matrix is a 2D array of V x V vertices.

Each row and column represent a vertex.

If the value of any element a[i][j] is 1, it represents that there is an edge connecting vertex i and vertex j.

### **Graph Representation: Adjacency Matrix**



It is an undirected graph, for edge (0,2), we also need to mark edge (2,0); making the adjacency matrix symmetric about the diagonal.

### **Graph Representation : Adjacency Matrix**

Each cell in the above table/matrix is represented as  $A_{ij}$ , where i and j are vertices. The value of  $A_{ij}$  is either 1 or 0 depending on whether there is an edge from vertex i to vertex j.

If there is a path from i to j, then the value of  $A_{ij}$  is 1 otherwise its 0. For instance, there is a path from vertex 1 to vertex 2, so  $A_{12}$  is 1 and there is no path from vertex 1 to 3, so  $A_{13}$  is 0.

In case of undirected graphs, the matrix is symmetric about the diagonal because of every edge (i,j), there is also an edge (j,i).

### **Graph Representation : Adjacency Matrix**

#### **Pros of Adjacency Matrix**

- The basic operations like adding an edge, removing an edge, and checking whether there is an edge from vertex i to vertex j are extremely time efficient, constant time operations.
- If the graph is dense and the number of edges is large, an adjacency matrix should be the first choice.
- The biggest advantage, however, comes from the use of matrices. The recent advances in hardware enable us to perform even expensive matrix operations on the GPU.
- By performing operations on the adjacent matrix, we can get important insights into the nature of the graph and the relationship between its vertices.

### **Graph Representation : Adjacency Matrix**

### **Cons of Adjacency Matrix**

- The VxV space requirement of the adjacency matrix makes it a memory hog. Graphs out in the wild usually don't have too many connections and this is the major reason why adjacency lists are the better choice for most tasks.
- While basic operations are easy, operations like inEdges and outEdges are expensive when using the adjacency matrix representation.

```
// Adjacency Matrix representation in
C++
#include <iostream>
using namespace std;
class Graph {
 private:
 bool** adjMatrix;
 int numVertices;
```

```
public:
// Initialize the matrix to zero
Graph(int numVertices) {
 this->numVertices = numVertices;
 adjMatrix = new bool*[numVertices];
 for (int i = 0; i < numVertices; i++) {
    adjMatrix[i] = new bool[numVertices];
    for (int j = 0; j < numVertices; j++)
         adjMatrix[i][j] = false;
```

```
// Add edges
 void addEdge(int i, int j) {
  adjMatrix[i][j] = true;
  adjMatrix[j][i] = true;
 // Remove edges
 void removeEdge(int i, int j) {
  adjMatrix[i][j] = false;
  adjMatrix[j][i] = false;
```

```
// Print the martix
void toString() {
  for (int i = 0; i < numVertices; i++) {
    cout << i << ":";
    for (int j = 0; j < numVertices; j++)
        cout << "j"<< adjMatrix[i][j] << " ";
    cout << "\n";
  }
}</pre>
```

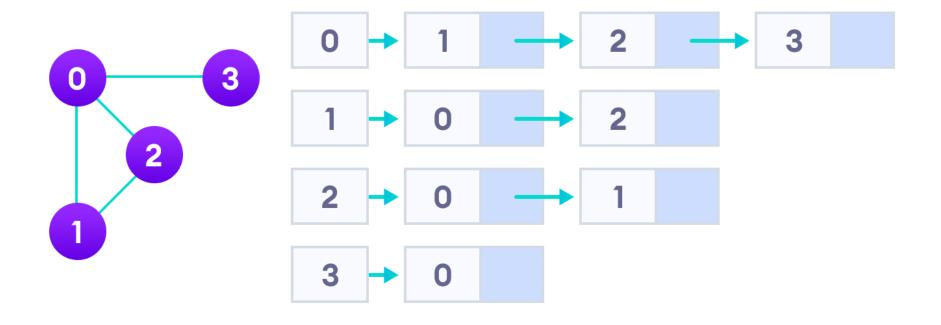
```
int main() {
~Graph() {
                                                      Graph g(4);
 for (int i = 0; i < numVertices; i++)
                                                      g.addEdge(0, 1);
     delete[] adjMatrix[i];
                                                      g.addEdge(0, 2);
                                                      g.addEdge(1, 2);
 delete[] adjMatrix;
                                                      g.addEdge(2, 0);
                                                      g.addEdge(2, 3);
                                                      g.toString();
```

## **Graph Representation: Adjacency List**

#### **Adjacency List**

An adjacency list represents a graph as an array of linked lists.

The index of the array represents a vertex and each element in its linked list represents the other vertices that form an edge with the vertex.



# **Graph Representation: Adjacency List**

#### **Pros of Adjacency List**

- •An adjacency list is efficient in terms of storage because we only need to store the values for the edges. For a sparse graph with millions of vertices and edges, this can mean a lot of saved space.
- •It also helps to find all the vertices adjacent to a vertex easily.

# **Graph Representation: Adjacency List**

#### **Cons of Adjacency List**

•Finding the adjacent list is not quicker than the adjacency matrix because all the connected nodes must be first explored to find them.

## **Graph Operations**

The most common graph operations are:

- Check if the element is present in the graph
- Graph Traversal
- Add elements(vertex, edges) to graph
- •Finding the path from one vertex to another

# Credits and Acknowledgements

https://www.gatevidyalay.com

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