



# Routing Protocol in Industrial IoT

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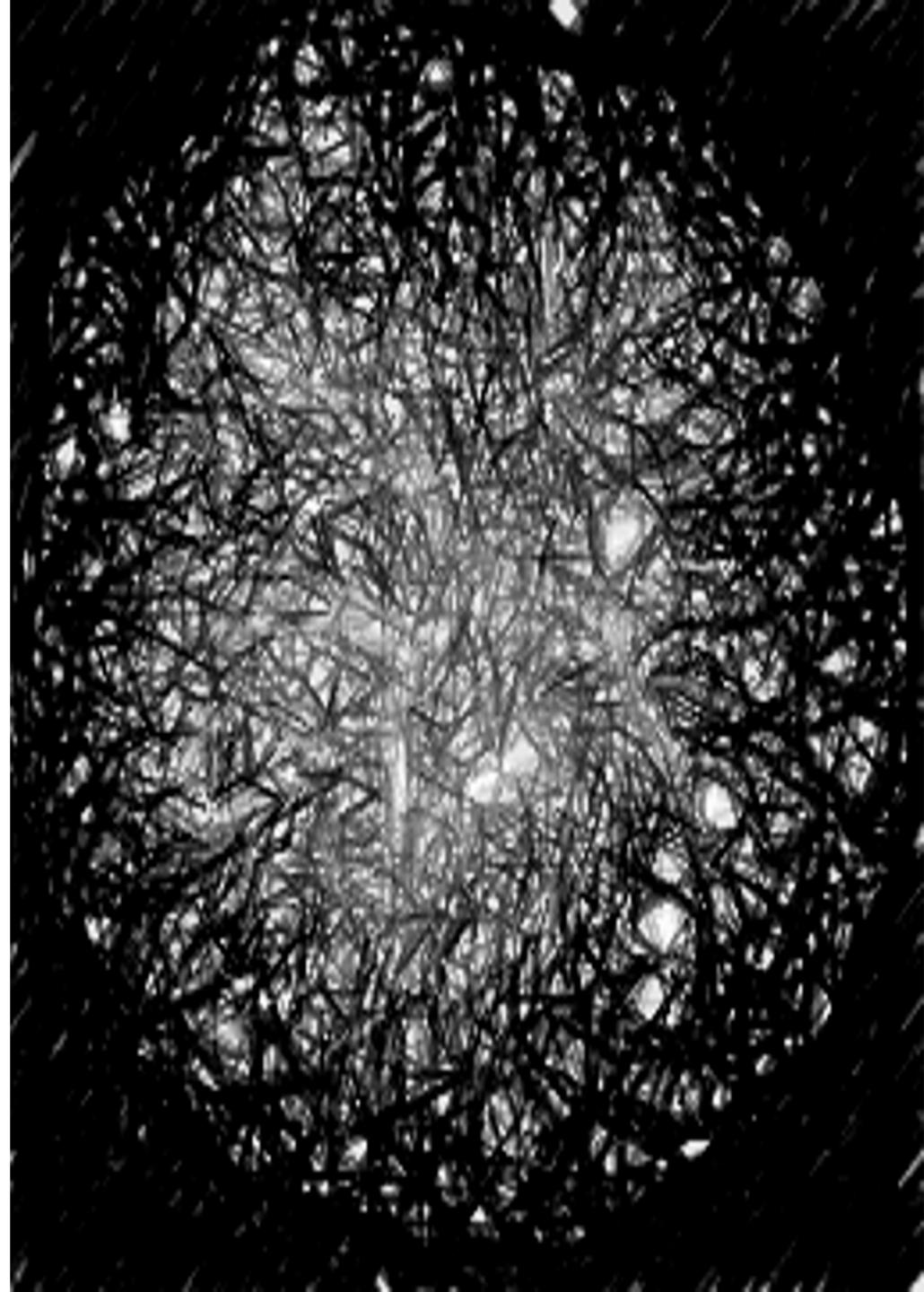


# **Part 1: RPL Design**

# Scaling to Pervasive IoT

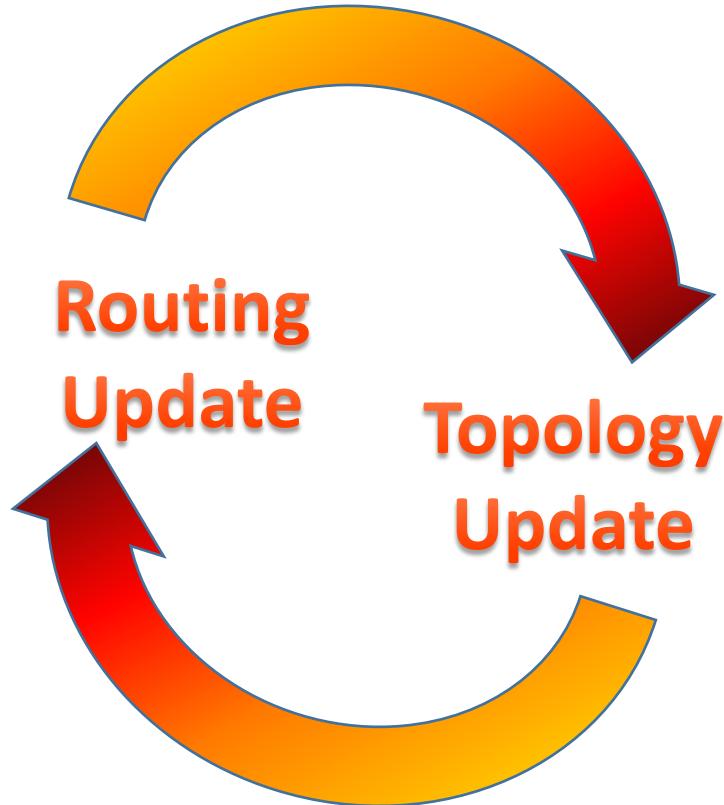
- 1000\*scale
  - => No leak in Internet
  - => Opaque operations
- Reachability
  - => Radio (IEEE)
- Addressing
  - => IPv6 (IETF)
- Density
  - => spatial reuse

=> Routing





# Dynamic topologies



No preexisting physical topology

- Can be computed by a mesh under protocol, but...
- Else Routing must infer its topology

Movement

- natural and unescapable
- Yet difficult to predict or detect

**quick and knowledgeable => expensive**

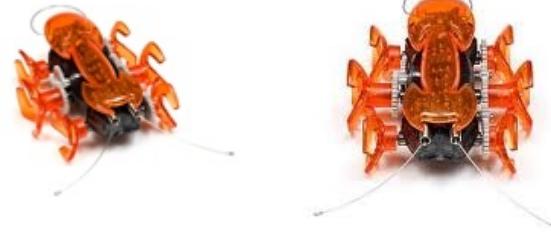
# Peer selection



Potentially **Large** Peer Set

Highly **Variable** Capabilities

Selection Per Objective



Metrics (e.g. RSSI, ETX...)

L3 Reachability (::/0, ...)

Constraints (Power ...)



# Constrained Objects

Smart objects are usually

- Small & Numerous
- « sensor Dust »

Battery is critical

- Deep Sleep
- Limited memory
- Small CPU

Savings are REQUIRED

- ⇒ Control plane (minimize state)
- ⇒ Data plane (minimize control messages)



# Fuzzy (non-deterministic) links



Neither transit nor P2P

More like a changing NBMA

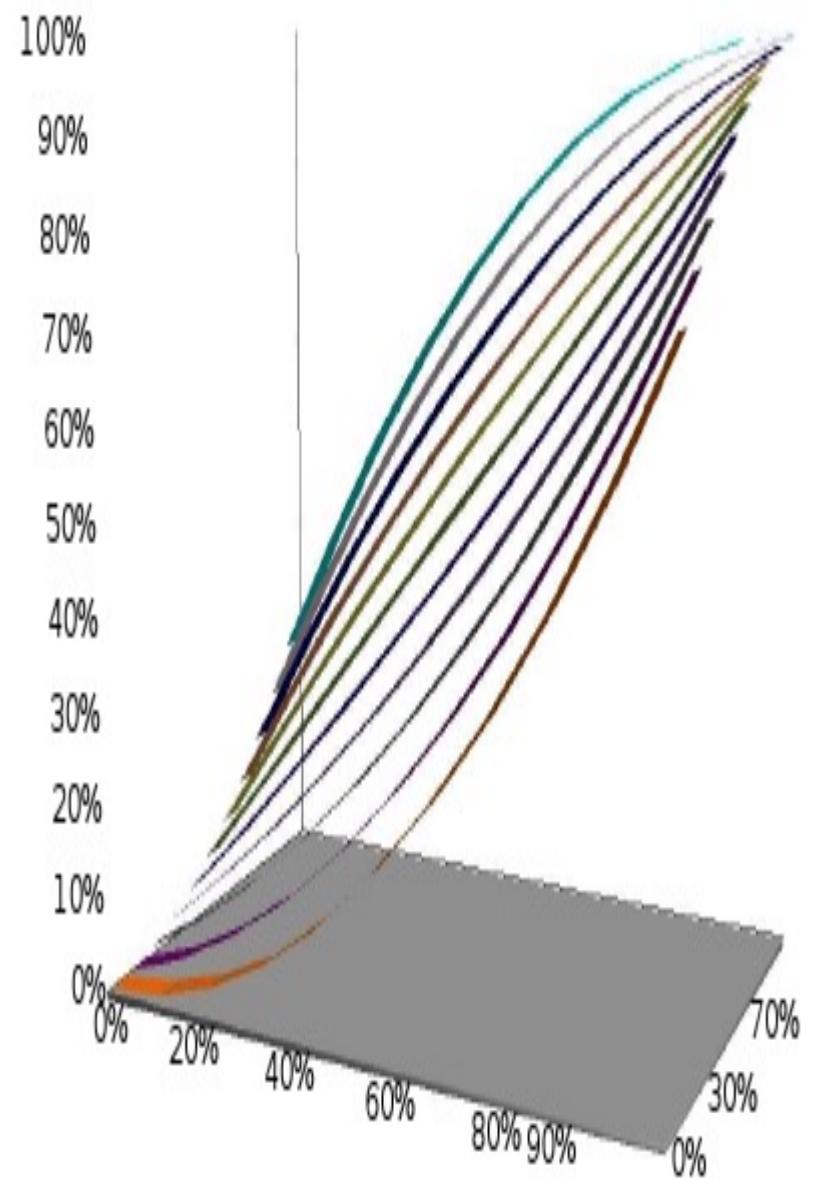
- a new paradigm for routing

Changing metrics

- (tons of them!)
- (but no classical cost!)

Inefficient flooding

- Self interfering

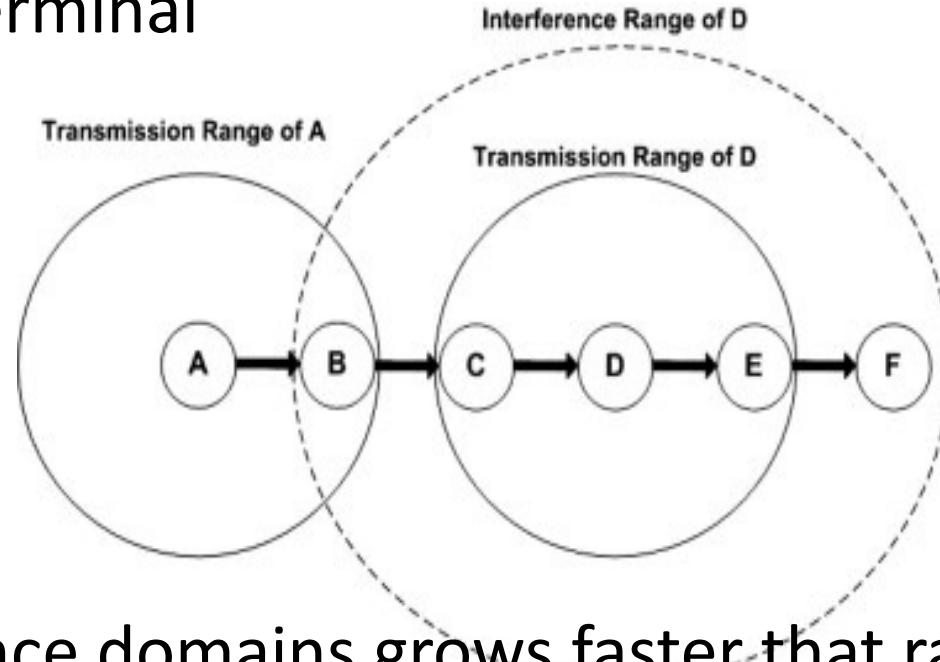


# Routing Concepts

# Routing for Spatial Reuse



- Hidden terminal



- Interference domains grows faster than range
- Density => low power => multihop => routing

# Centralized vs. Distributed Routing

(RPL now has both with the new DAO Projection)



**Centralized: A controller sets up the routes**

Pros

God's view, enables global optimization

Elastic resource management / NFV

Traffic Engineering, may compute per flow paths

Non Equal Cost Multipath, Replication & Elimination

Cons

Delays learning about breakage

Delays fixing breakage

NP complete optimization => limits scalability

**Distributed: A routing protocol sets up the routes**

Pros

Since ARPANET, enables high resilience

Different IGPs for different needs

Installed base

Cons

Microloops

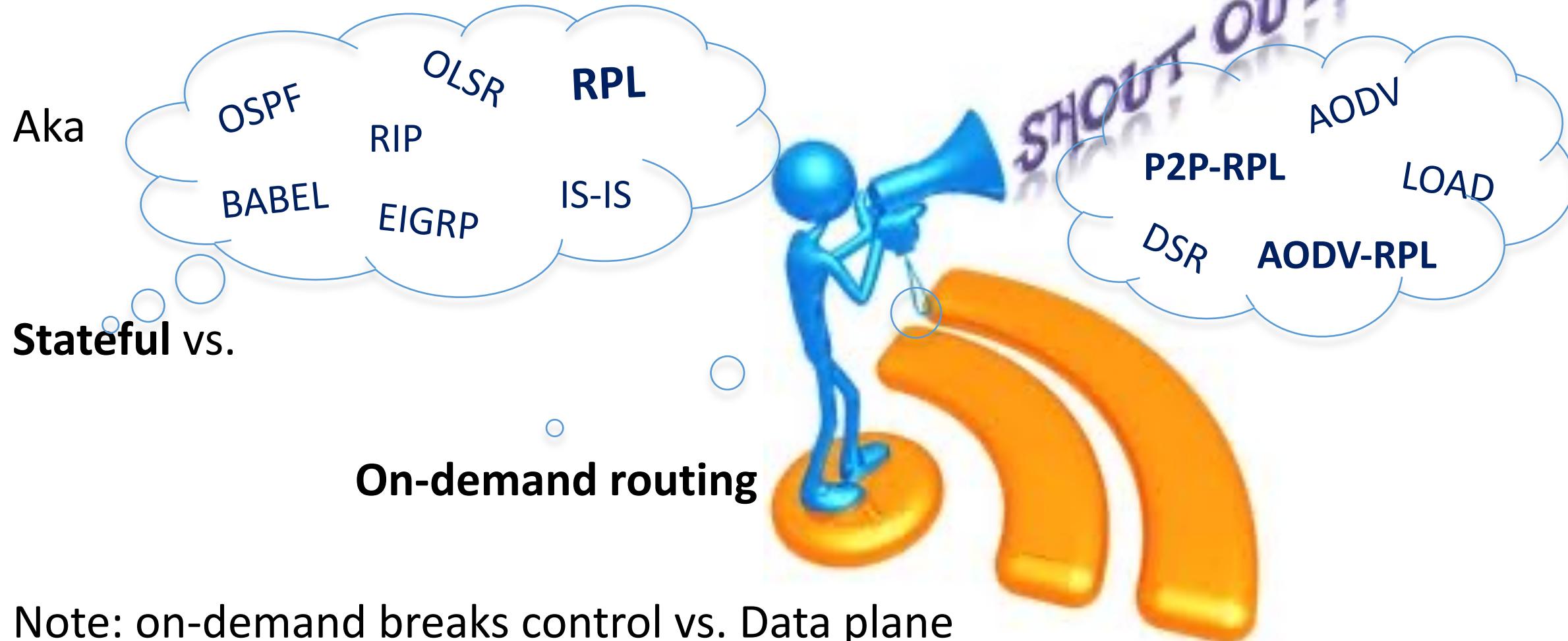
Tends to build crowded avenues, wastes bandwidth

Same costs for all, NECM difficult, manual TE

Need additions for reroute / fast reroute



# Proactive vs. Reactive AKA on-demand (RPL now has both with the new AODV work)



Note: on-demand breaks control vs. Data plane separation

# Stateful vs. Source-Routing (RPL has both modes)



**Stateful: routing decision at every hop**

## Pros

Resilient (DARPA), autonomic

## Cons

Requires routing state in every router

Tends to concentrate flows

Routing Loops



**Source Routing: The path is in the packet**

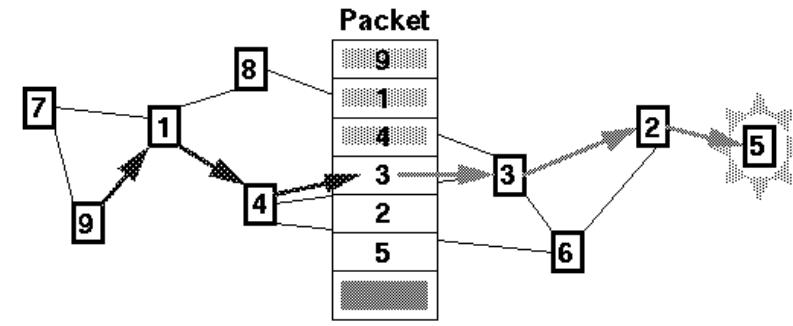
## Pros

Saves state in routers

Enables per flow routing (segment routing)

## Cons

Larger packets / Source Route Header (SRH)



# Link State aka Dijkstra aka SPF vs. Distance Vector aka Bellman-Ford

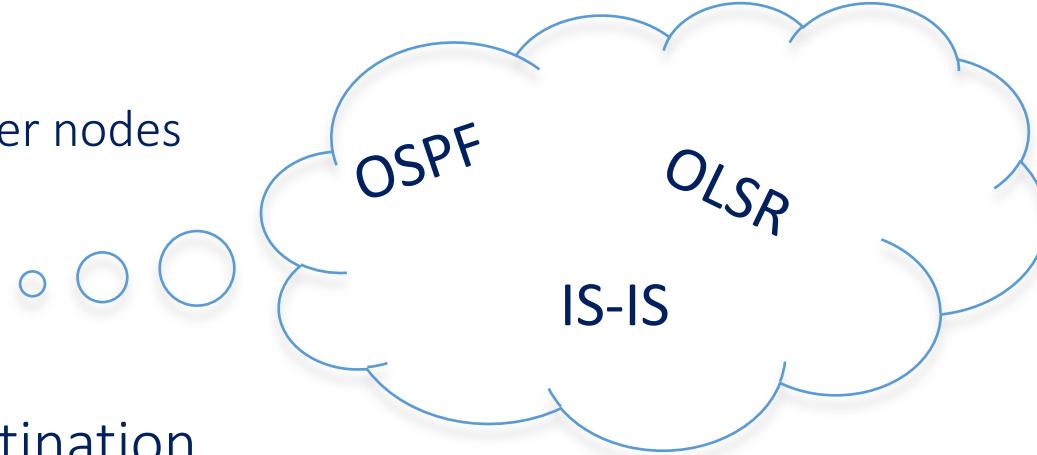
(RPL is DV)



LS requires full state and convergence

- Every node draws a same graph
- Then run the shortest path first algorithm to get to all other nodes
- Then associates node with reachable destinations

LS can be very quiet on stable topologies

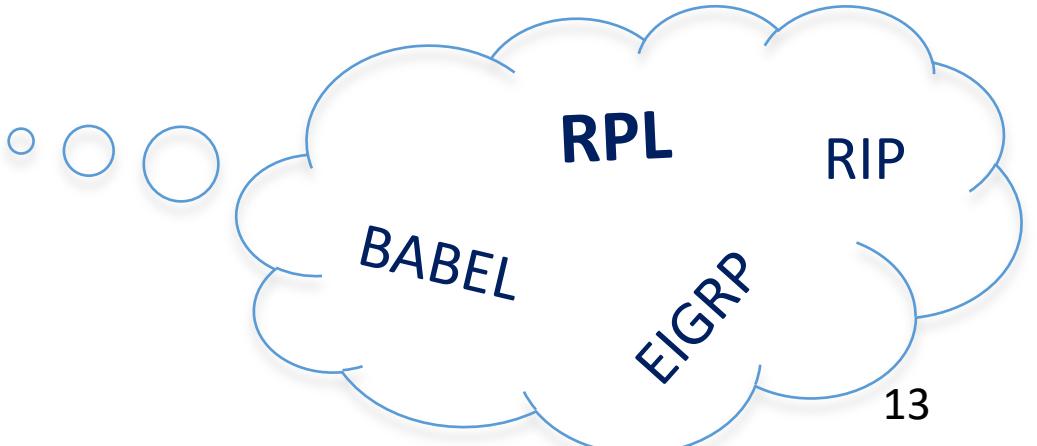


DV learns costs to destination asynchronously per destination

- Nodes advertise their distance to a destination
- Recursively other nodes learn their best successor
- and compute their own cost

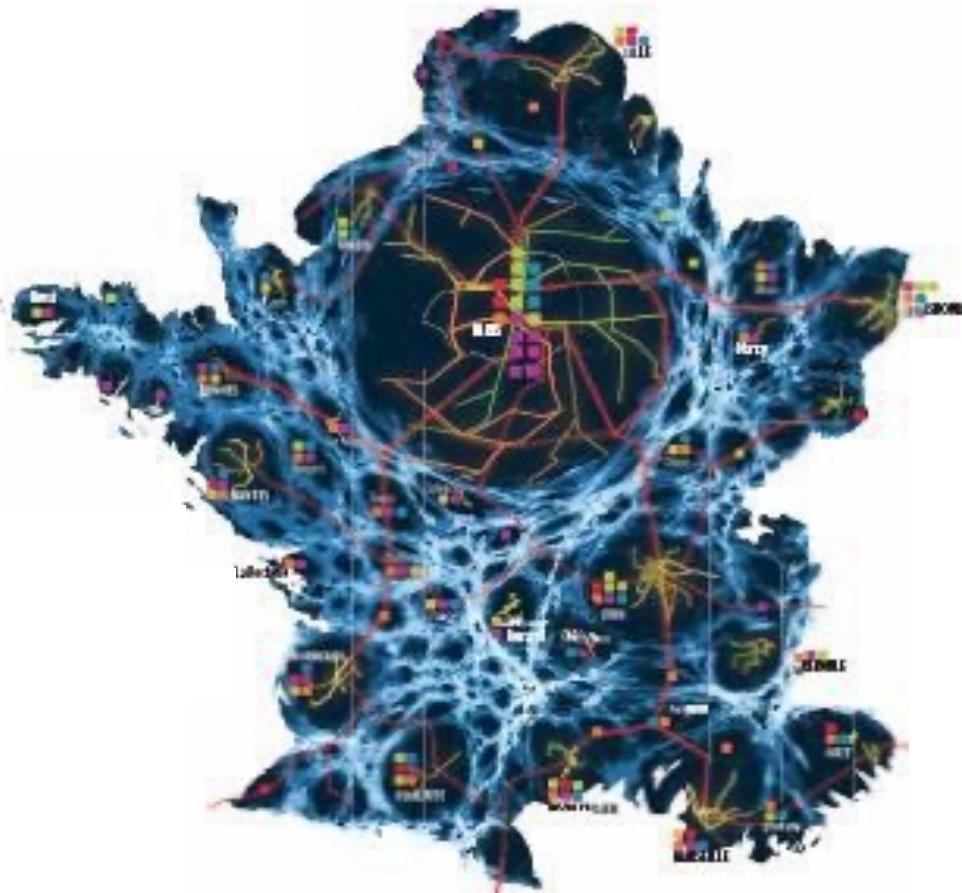
DV hides topological complexities and changes

DV enables multiple NECM feasible successors





# Route stretch vs Shortest Path (RPL stretches to save)



Most protocols are Optimized Routing Approach (ORA) and span advertisements for any change to maintain a shortest path to all

Routing overhead can be reduced if stretch is allowed: this is the Least Overhead Routing Approach (LORA) approach

=> (Nothing to do with the LoRa LPWAN protocol!)

The base RPL is an **anisotropic** form of LORA: it optimizes routes from and to a Root and stretches P2P

# Routing Trees

(RPL has a preferred parent tree)



Most classical routing structure

Typically what Internet Gateway Protocols (IGPs) Build or each reachable destination

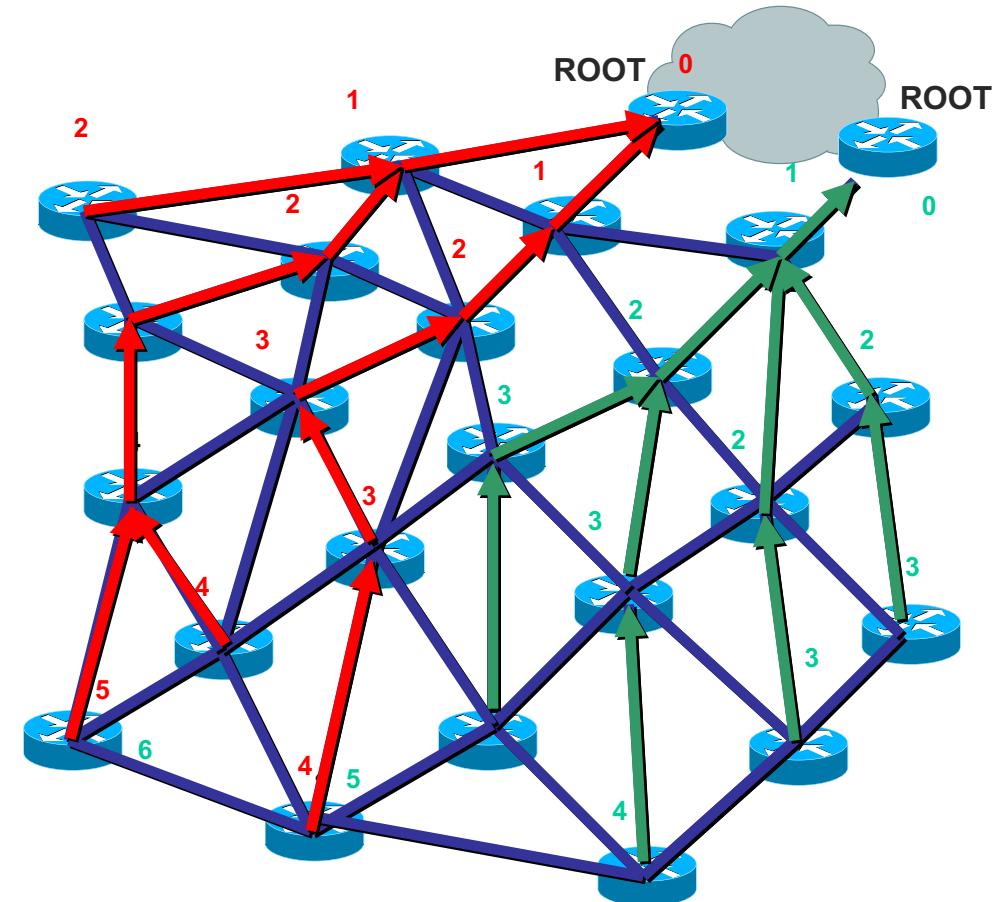
Only thing Link State builds, though Distance Vector has feasible successors

Must be reconstructed upon connectivity loss, service is interrupted

FRR techniques must be added (MRT, LFA with SR ...) on top

No inner load balancing capabilities

Walkable structure (e.g. depth first)



# DAGs and DODAGs

(RPL builds DODAGs)



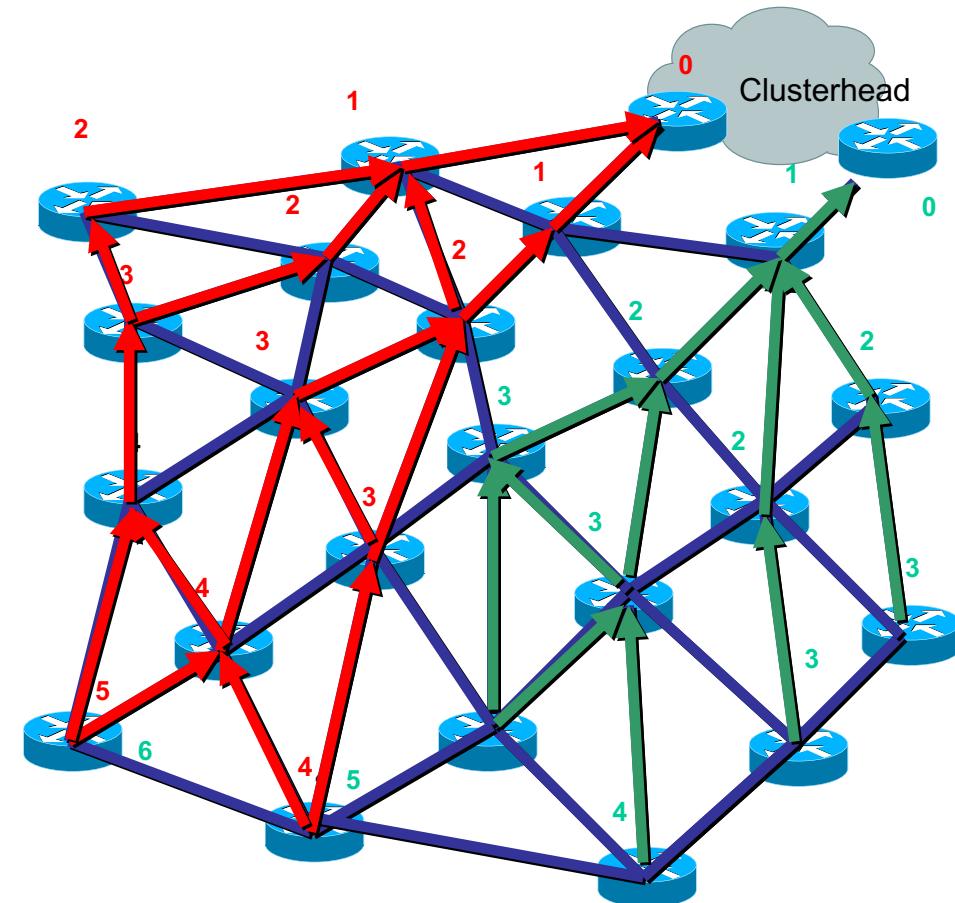
In the context of routing, a Directed Acyclic Graph (DAG) is formed by a collection of vertices (nodes) and edges (links).

Each edge connecting one node to another (directed) in such a way that it is not possible to start at Node X and follow a directed path that cycles back to Node X (acyclic).

Greedy => Not all nodes have 2 solutions even in biconnected networks

A Destination Oriented DAG (DODAG) is a DAG that comprises a single root node.

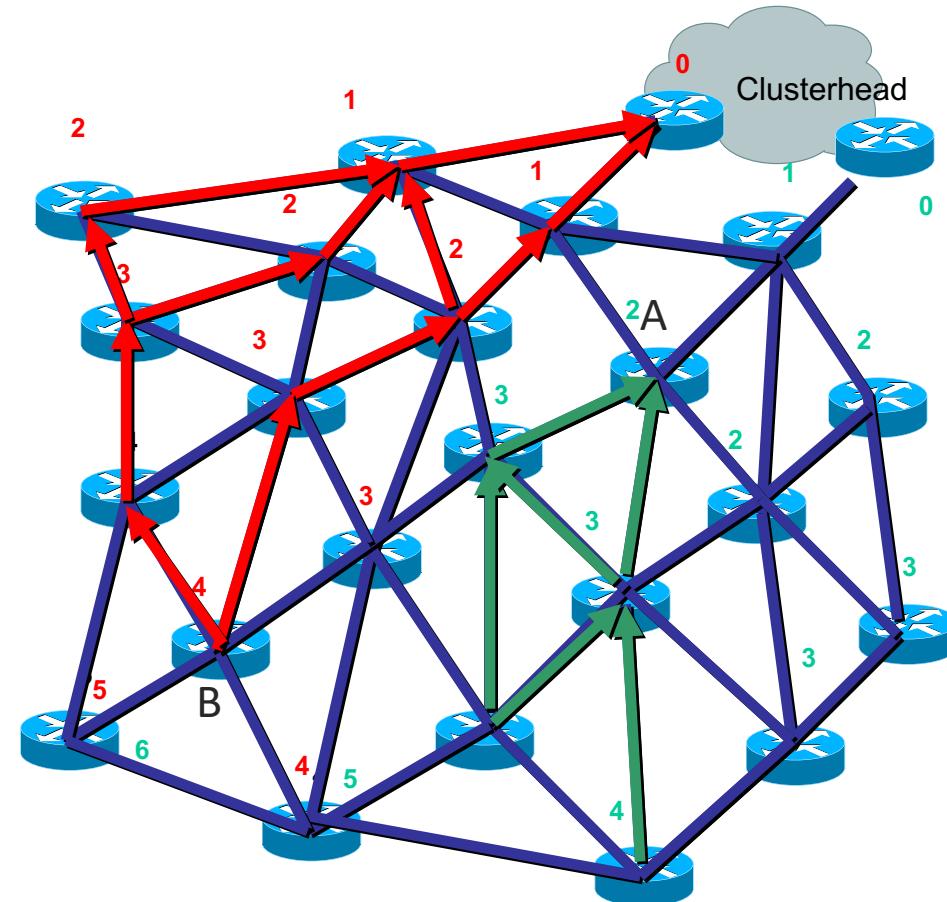
Here a DAG that is partitioned in 2 DODAG





# SubDAG, and Fanout DAG

- In Green: A's subDAG.
  - Impacted if A's connectivity is broken
  - Domain for routing recovery
- In Red: B's fanout DAG
  - (or reverse subDAG)
  - Potential SPAN on B's DAO
  - Thus potential return paths
  - Fanout must be controlled to limit intermediate states



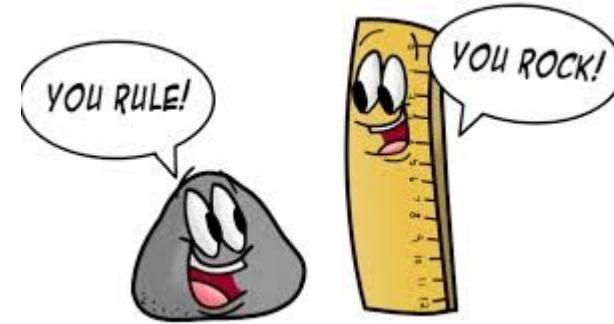
# Instances and Objectives

## RPL is objective driven

- e.g. reach a certain gateway, concept of a goal
- Instances are built to reach certain goals
- Instance ID tagged in packets

## RPL is generic and extensible

- RFC 6550 is a core distance vector functionality
- Objective functions plug in to adapt to use case / need
- Objective functions enforce policies



# Objective Function (OF)



Extend the generic behavior

- For a specific need / use case

Used in parent selection

- Constraints
- Policies
- Metrics

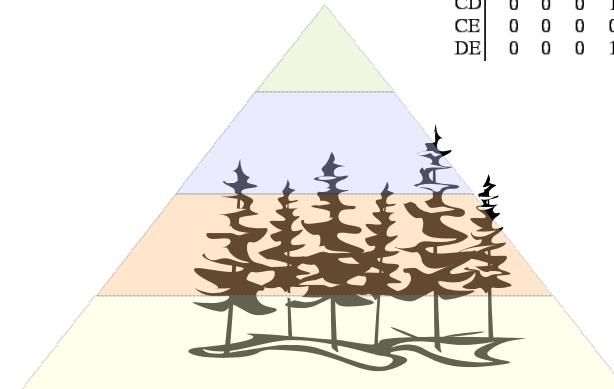


Position in the DAG



Computes the Rank increment

- Based on hop metrics
- Do NOT use OF0 for adhoc radios!
- (OF 0 uses traditional weighted hop count)



$$\begin{array}{c} \text{path-edge incidence matrix } A \quad \times \quad \begin{matrix} \text{edge} \\ \text{lengths} \\ e \end{matrix} = \begin{matrix} \text{path} \\ \text{lengths} \\ d \end{matrix} \\ \\ \begin{array}{c|ccccccc} & e_1 & e_2 & e_3 & e_4 & e_5 & e_6 & e_7 \\ \hline AB & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ AC & 1 & 0 & 1 & 0 & 1 & 1 & 0 \\ AD & 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ AE & 1 & 0 & 1 & 0 & 1 & 0 & 1 \\ BC & 0 & 1 & 1 & 0 & 1 & 1 & 0 \\ BD & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ BE & 0 & 1 & 1 & 0 & 1 & 0 & 1 \\ CD & 0 & 0 & 0 & 1 & 1 & 1 & 0 \\ CE & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ DE & 0 & 0 & 0 & 1 & 1 & 0 & 1 \end{array} \quad \times \quad \begin{pmatrix} 1 \\ 1 \\ 2 \\ 2 \\ 3 \\ 3 \end{pmatrix} = \begin{pmatrix} 2 \\ 7 \\ 4 \\ 7 \\ 7 \\ 6 \\ 7 \end{pmatrix} \end{array}$$

# Trickle: An Optimized Diffusion

## Suppression of redundant copies

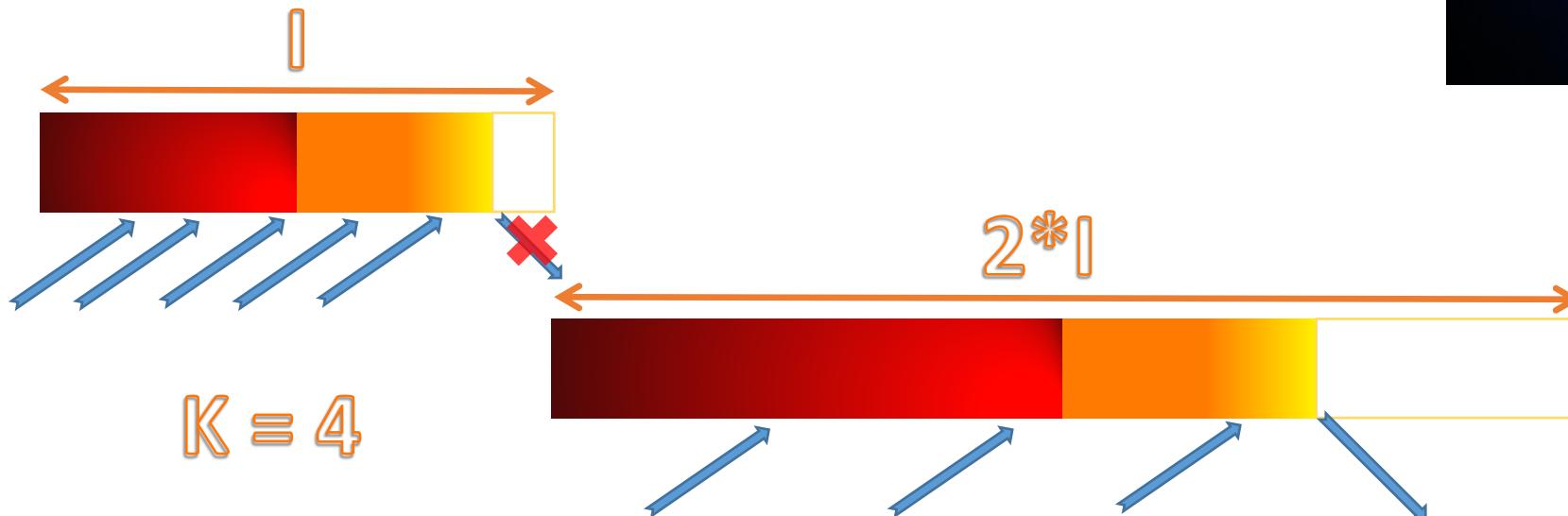
- Do not send copy if  $K$  copies received

## Jitter for Collision Avoidance

- First half is mute, second half is jittered

## Exponential backoff

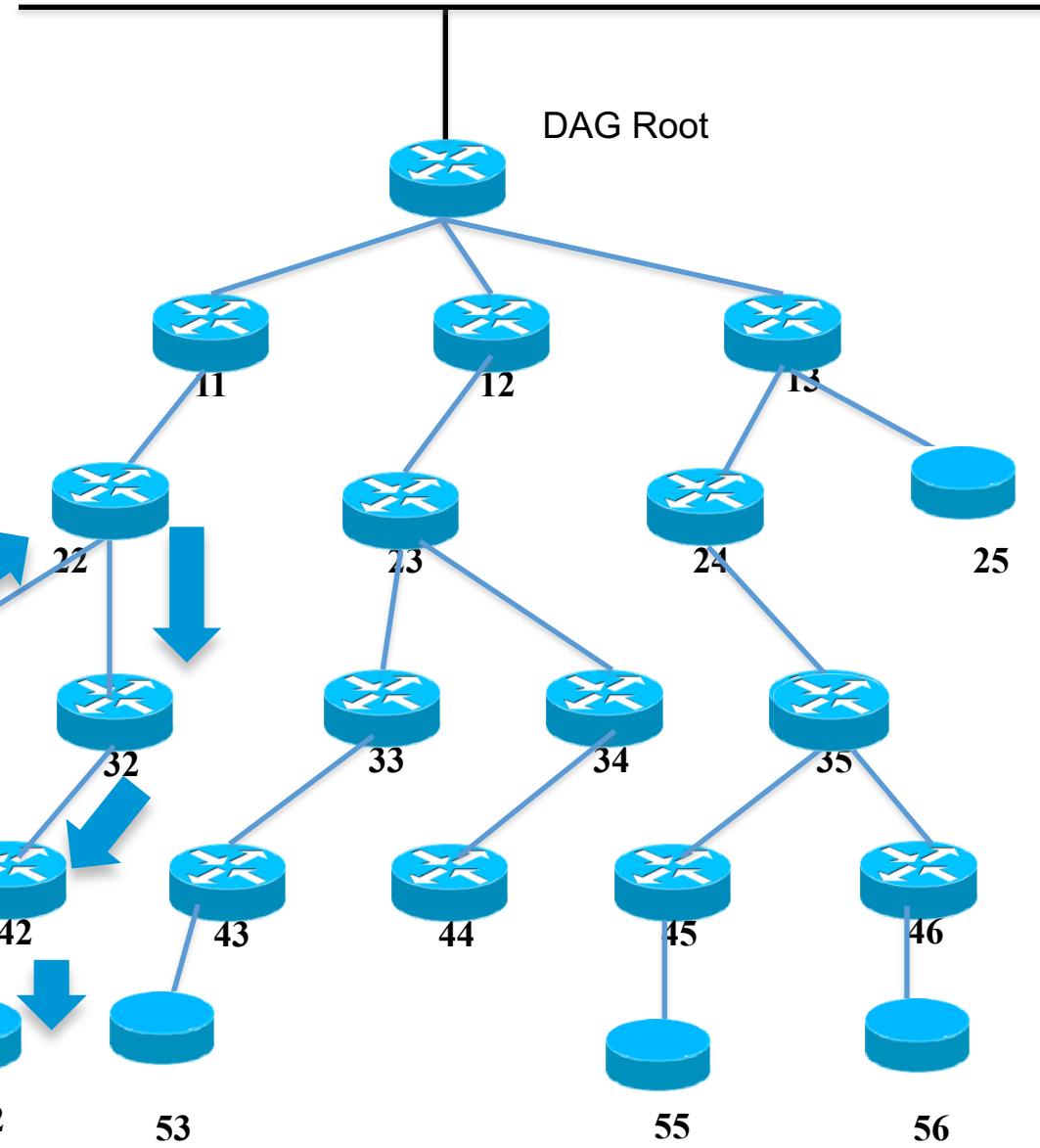
- Double  $I$  after period  $I$ , Reset  $I$  on inconsistency



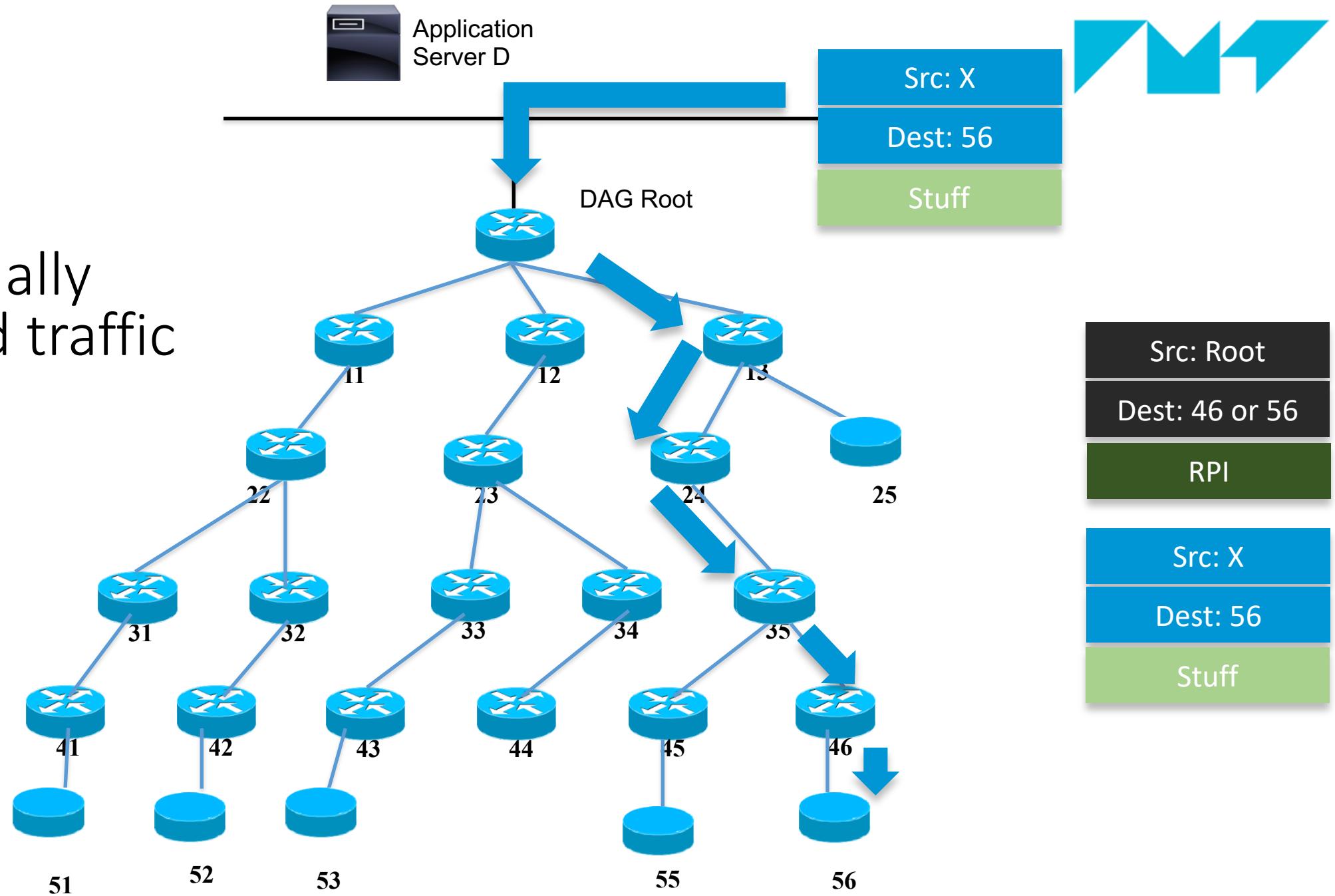
# Storing Mode Routing stretch



Application  
Server D



# Storing Mode Overhead For Externally Originated traffic



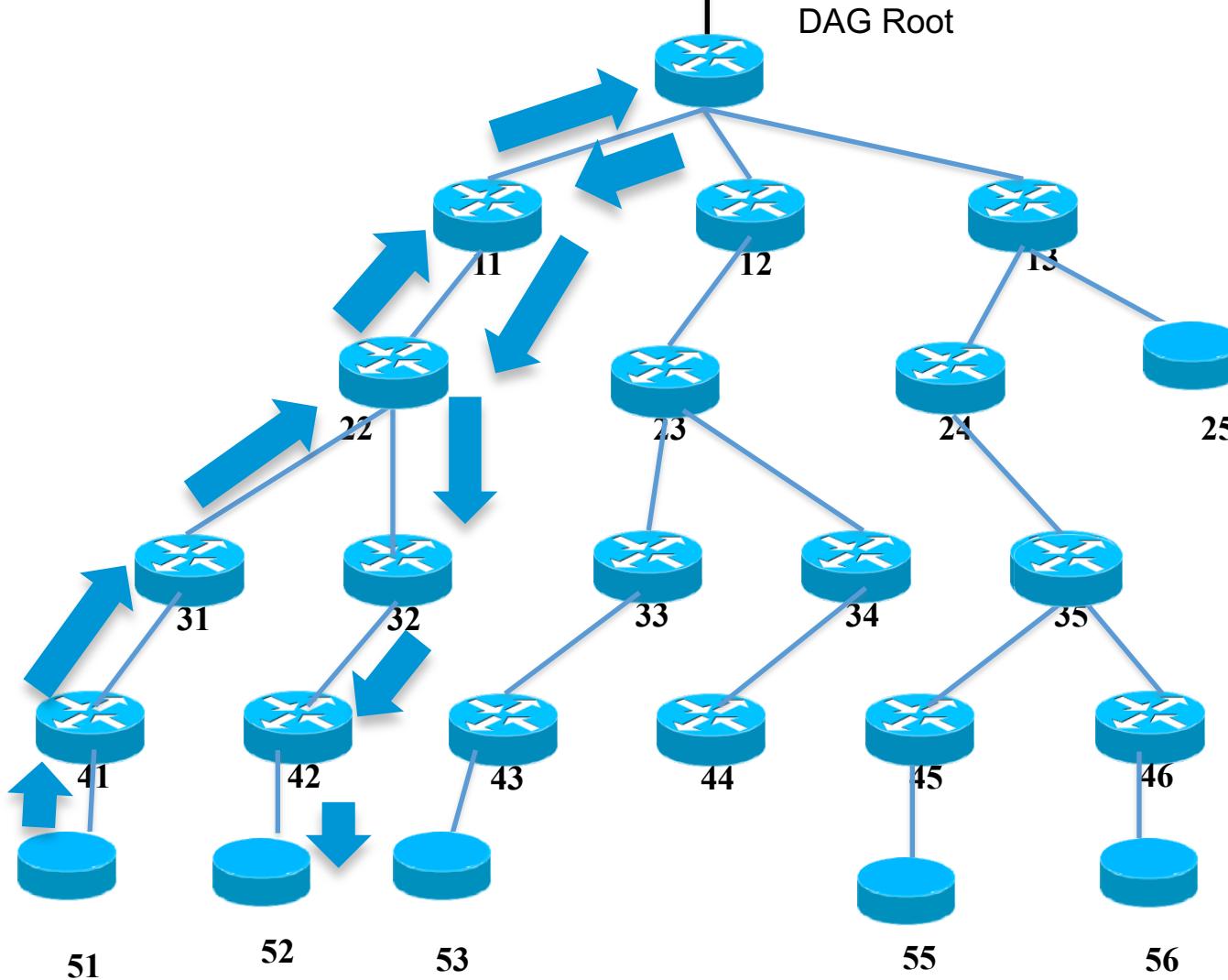
# Non-Storing Routing stretch



Application  
Server D

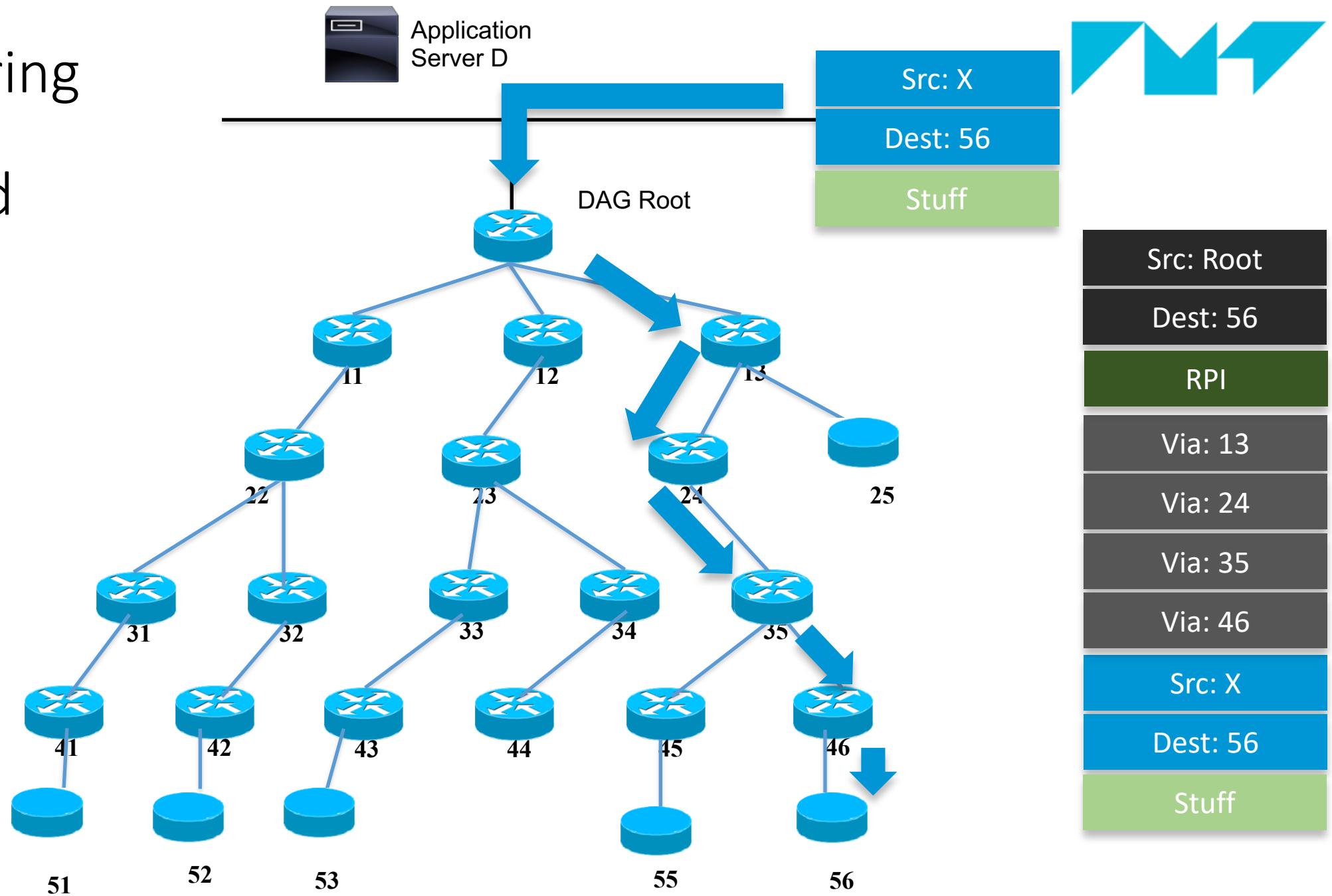


Src: 51
Dest: Root
RPI
Src: 51
Dest: 52
Stuff
OR
Src: 51
Dest: 52
RPI
Stuff



Src: Root
Dest: 56
RPI
Via: 11
Via: 22
Via: 32
Via: 42
Src: X
Dest: 52
Stuff

# Non-Storing Mode overhead





# Discussion: What makes RPL green?

- Anisotropic (stretch)
- Neighbor selection (Trickle)
- DV (limited topological knowledge)
- Compatible with scheduled MAC (6TiSCH)
- Multipath (saves retries)

# Applying SFAAC to RPL

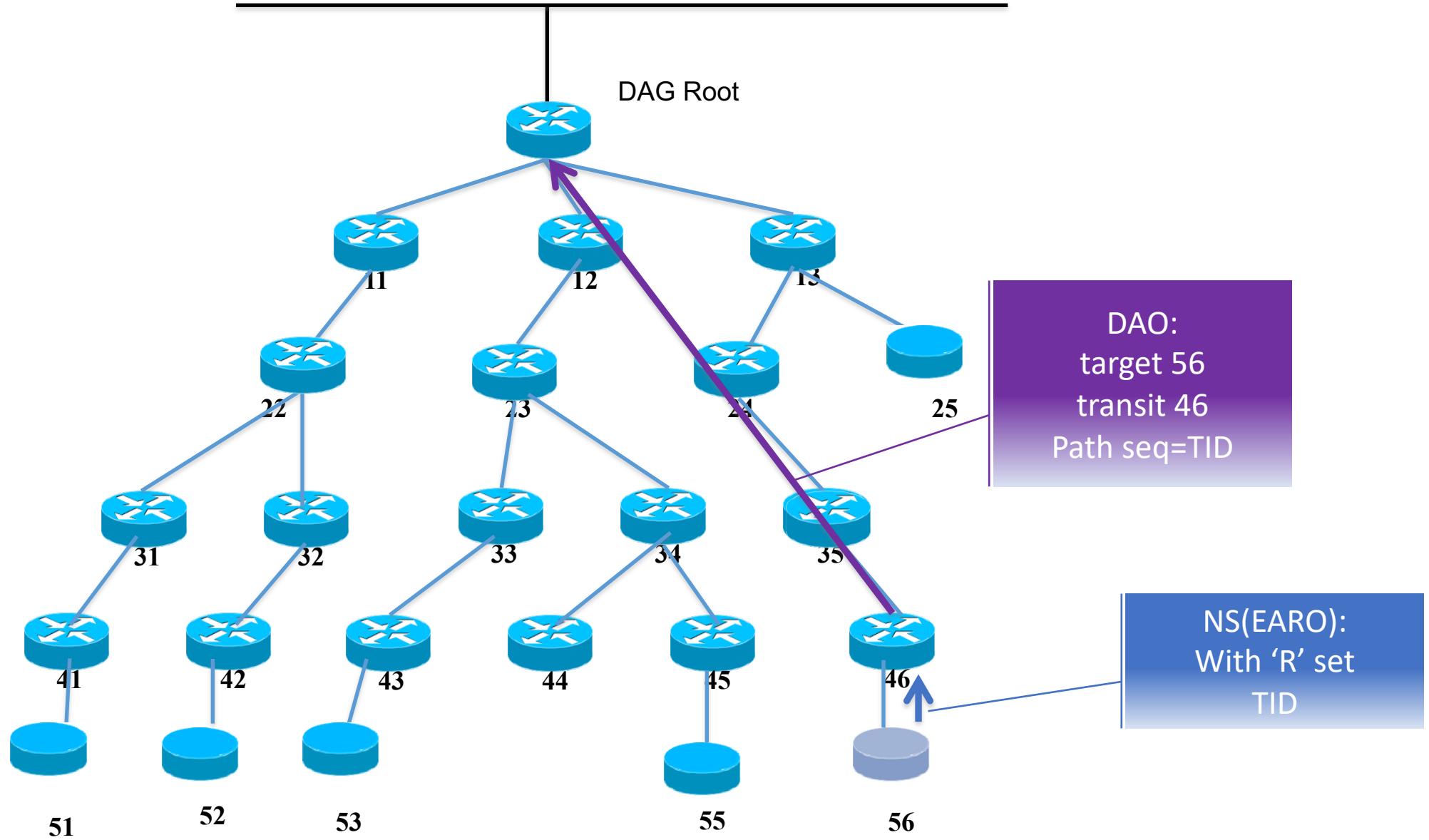


# RPL Unaware Leaves (RFC 9010)

- Unaware Leaves Register their addresses
  - ‘R’ flag set: 6LR generates the DAO on behalf of RUL
  - DAO has ‘E’ external flag set to indicate external destination
- RFC 9008 provides the encapsulation rules
  - Describes external destination for which RPL is transit, e.g., RUL
  - RPL Non-Storing DAO signaling is used in all cases for RULs
  - Data Traffic tunneled between Root and 6LR, decapsulated and delivered
- draft-ietf-6lo-multicast-registration
  - Extends to multicast and anycast registrations
  - New RPL MOP for ingress replication in non storing mode

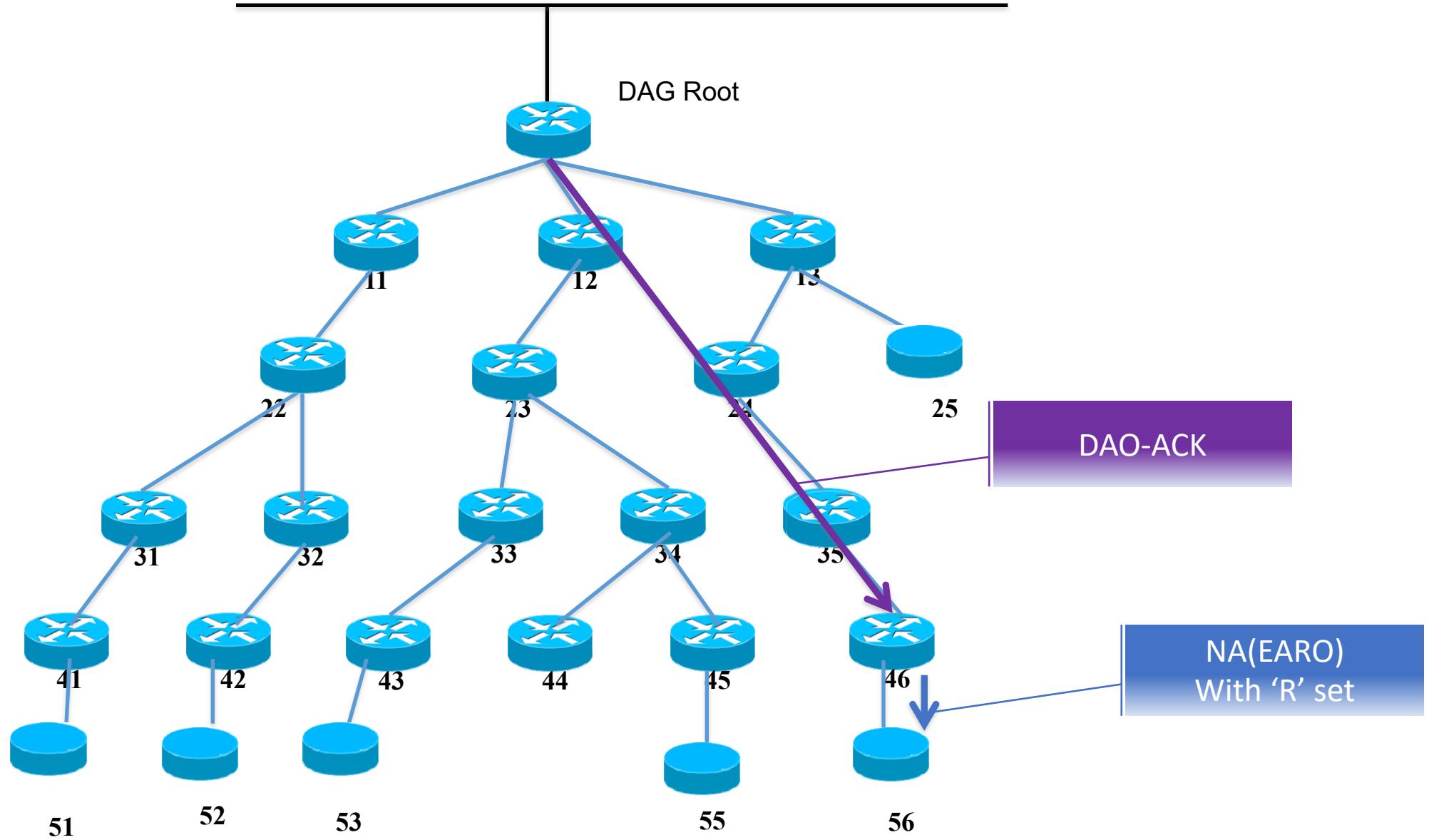


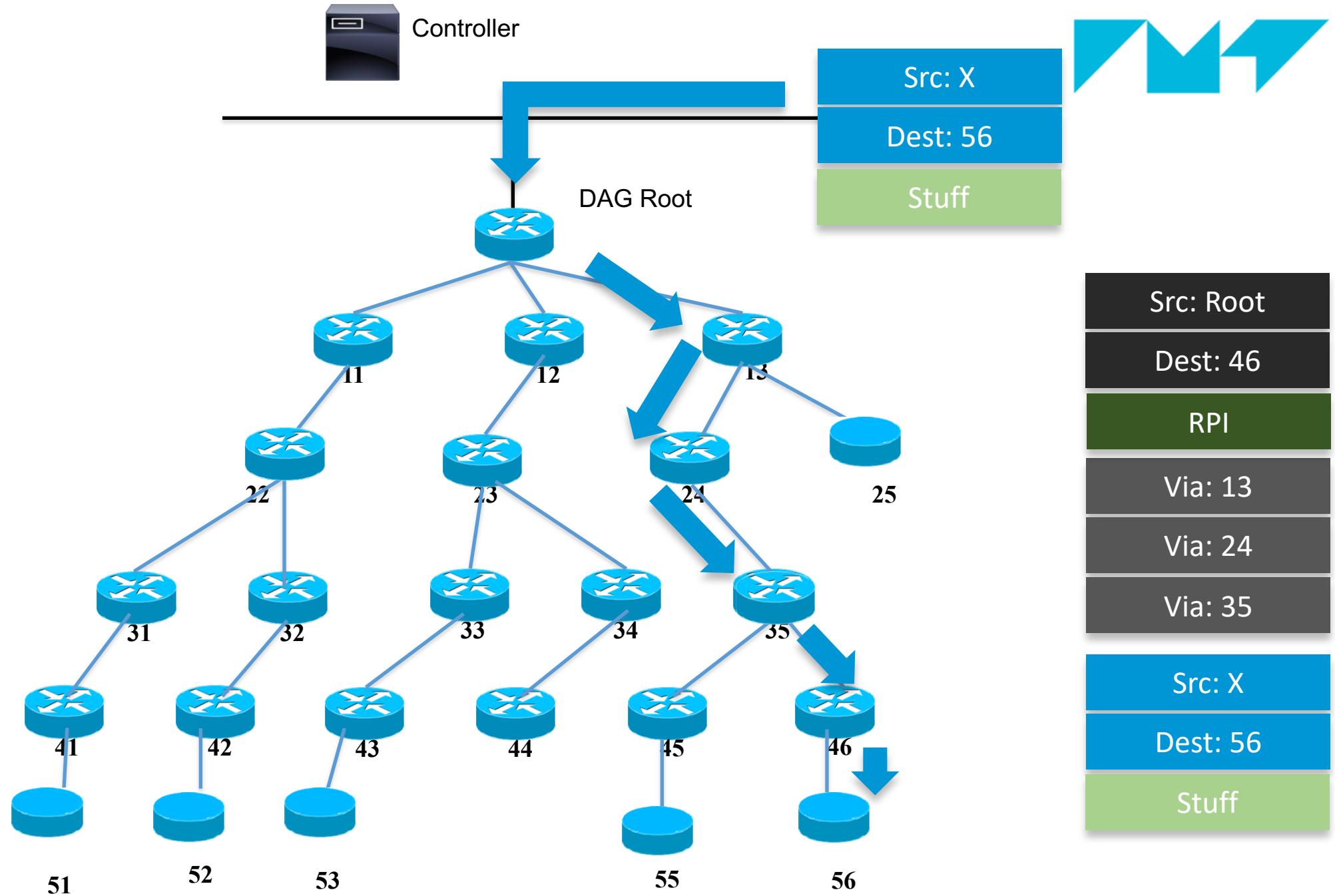
Controller

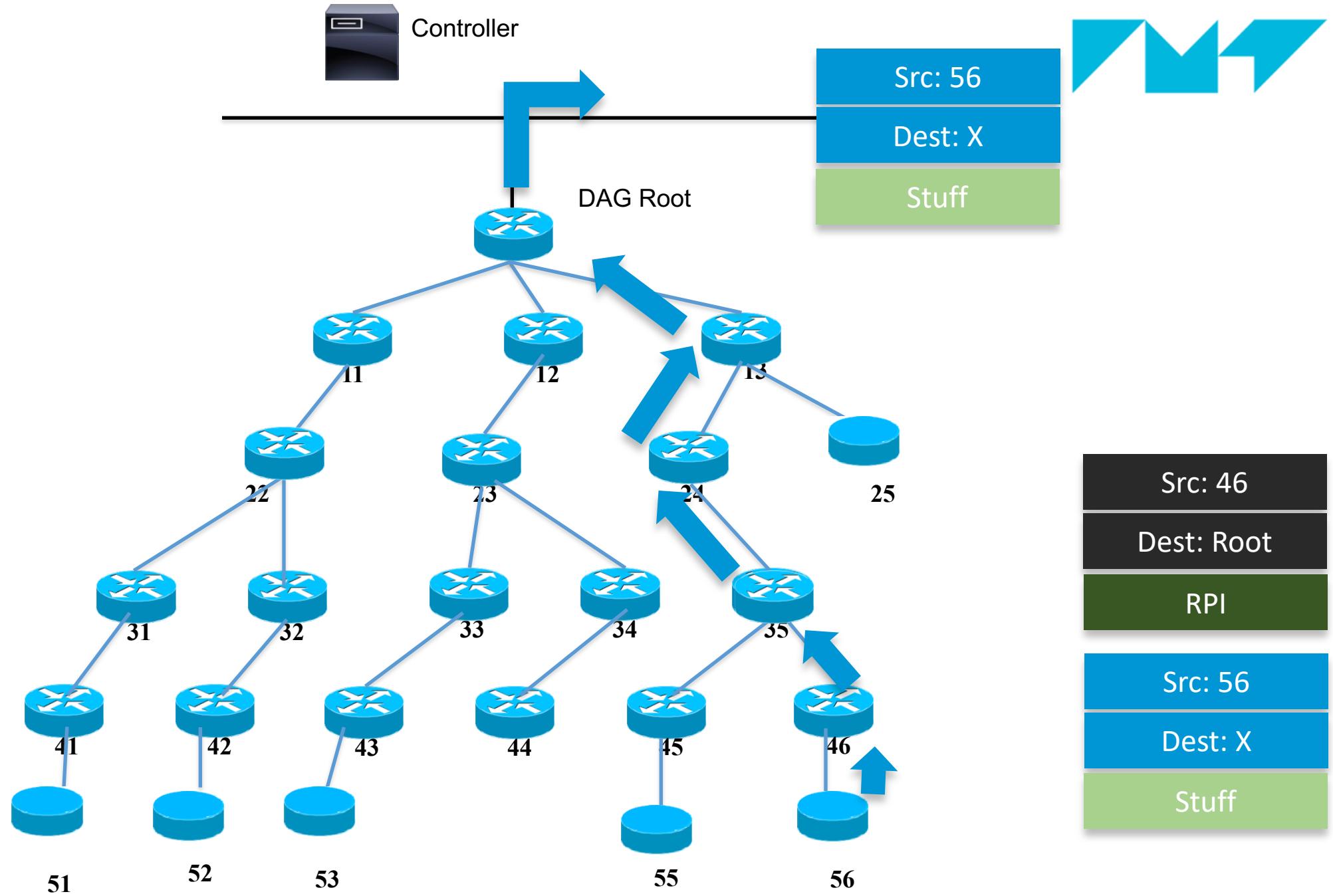




Controller









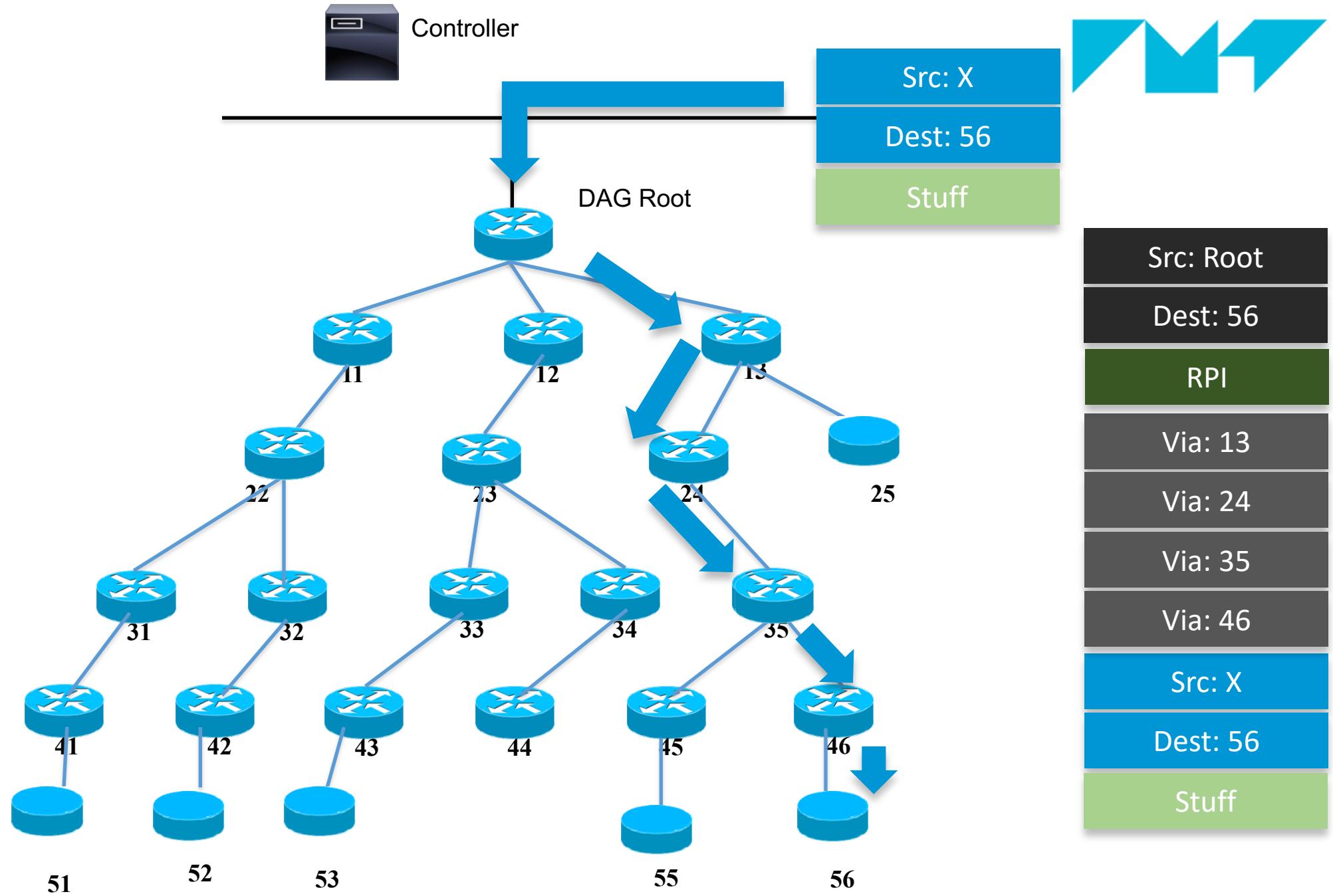
## **Part 2: RPL Next Steps**

# DAO Projection



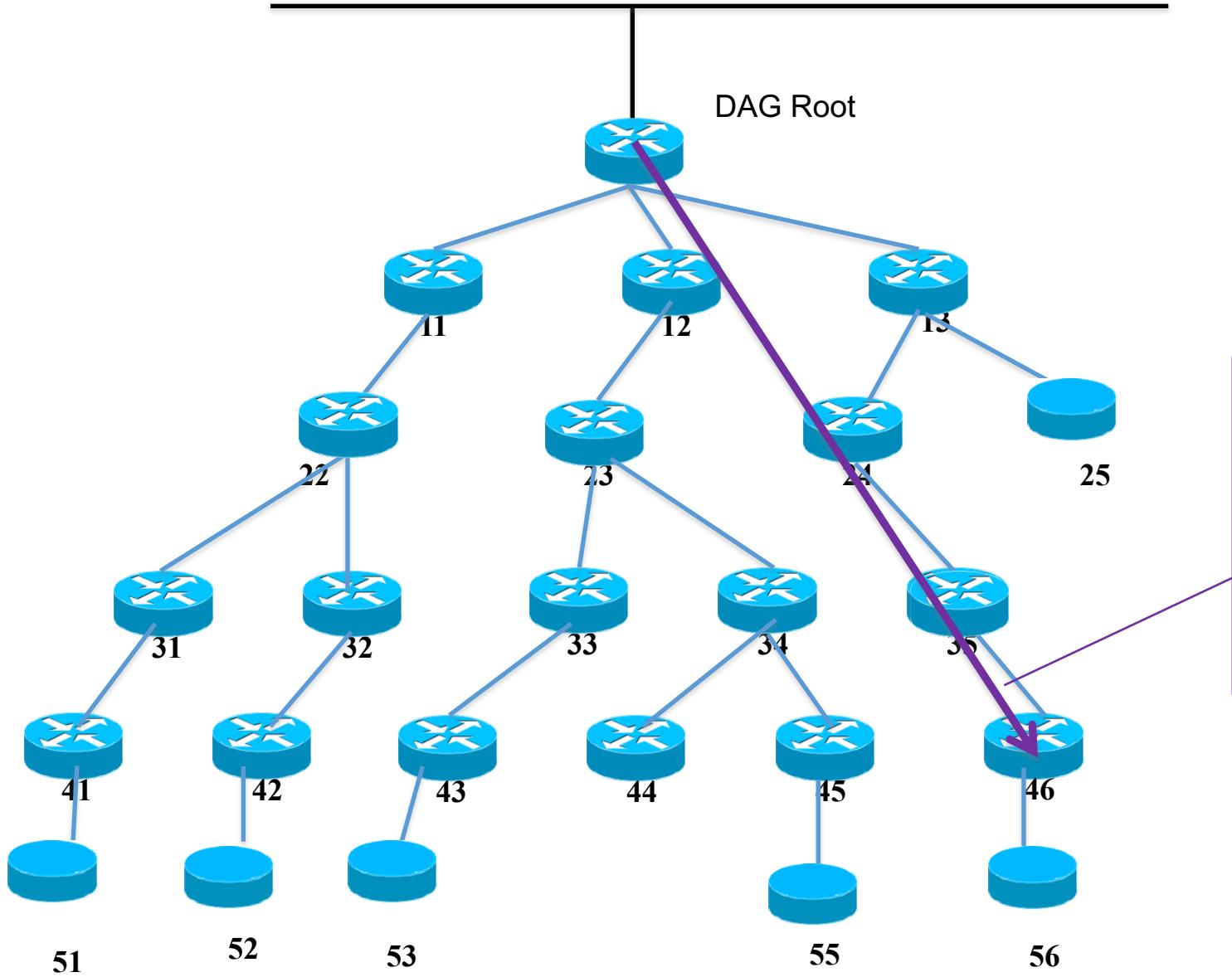
# DAO Projection (Centralized RPL)

- Root connected-to or acting-as controller
  - Uses topological info from main DODAG
  - New Sibling Information Option (and P-DAO request)
  - Uses Projected DAO to install paths in the network
- Builds Segments to compress SHR
  - Compresses selected long paths in main DODAG
  - Uses Storing Mode Projected DAO to install strict (serial) paths
- Builds new DODAGs called Tracks
  - Enables optimized P2P (east – west) routing
  - Uses Non-Storing Mode Projected DAO to install loose (dotted-line) graphs
  - Leveraging Segments to complete the graph



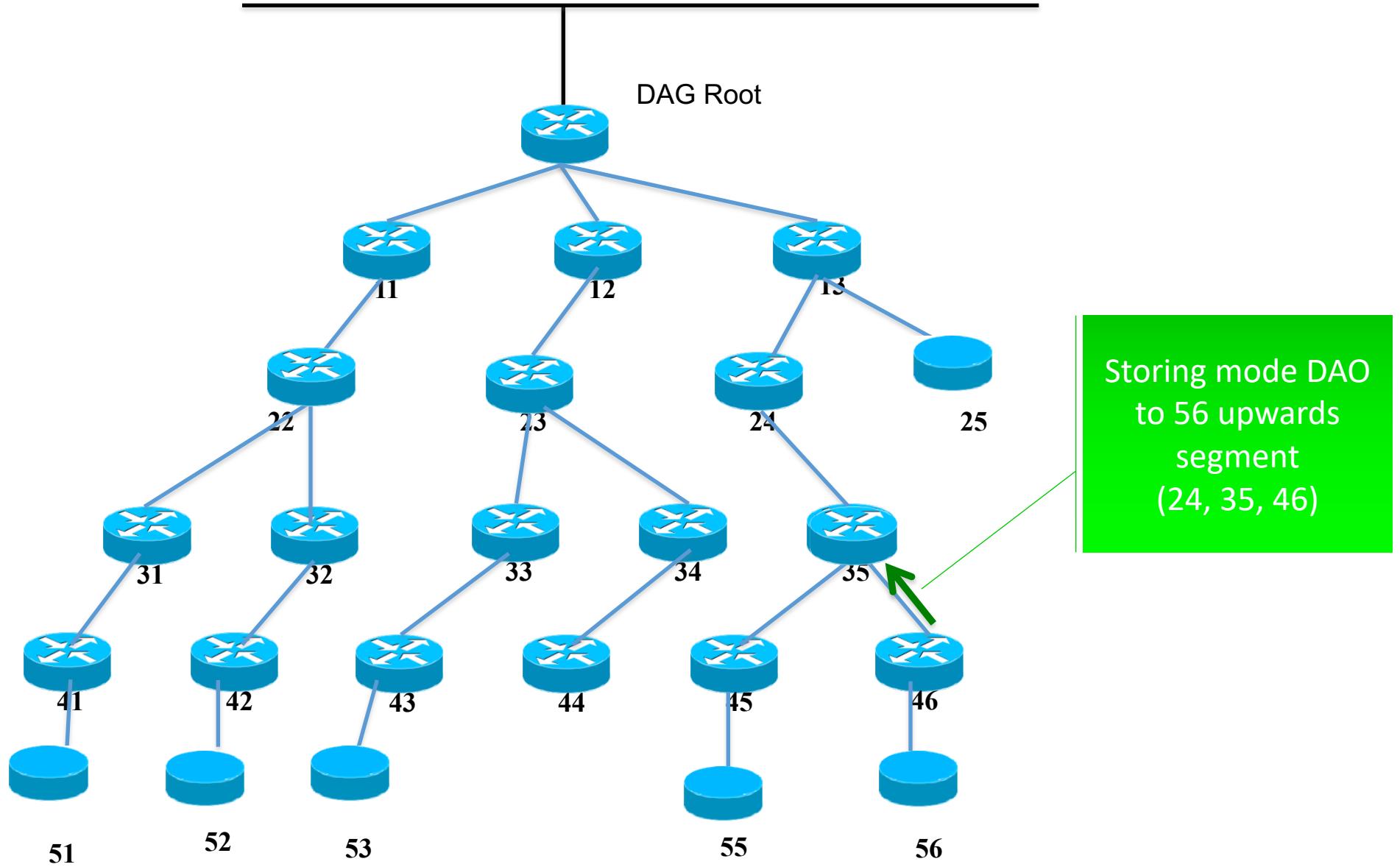


Controller



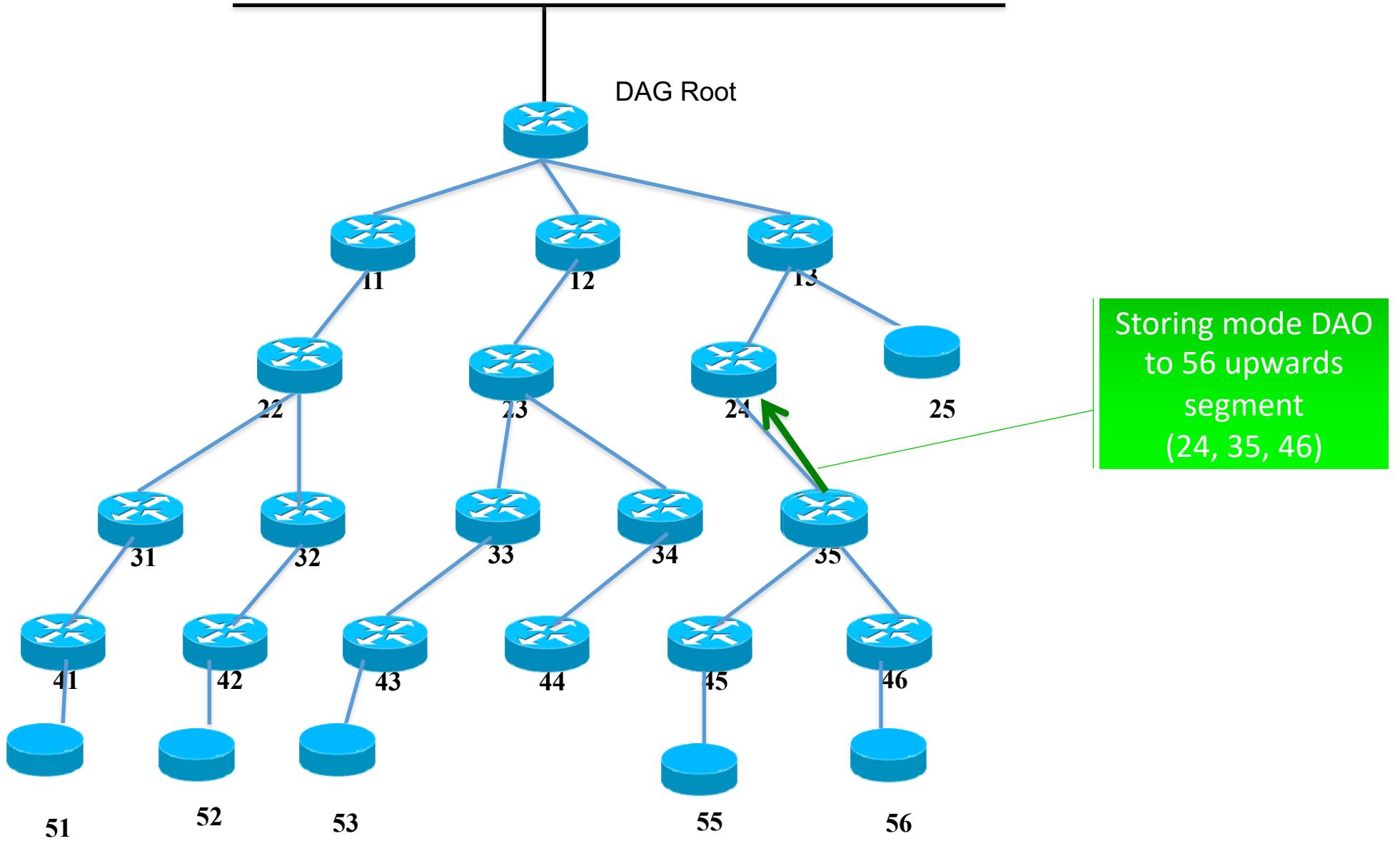


Controller



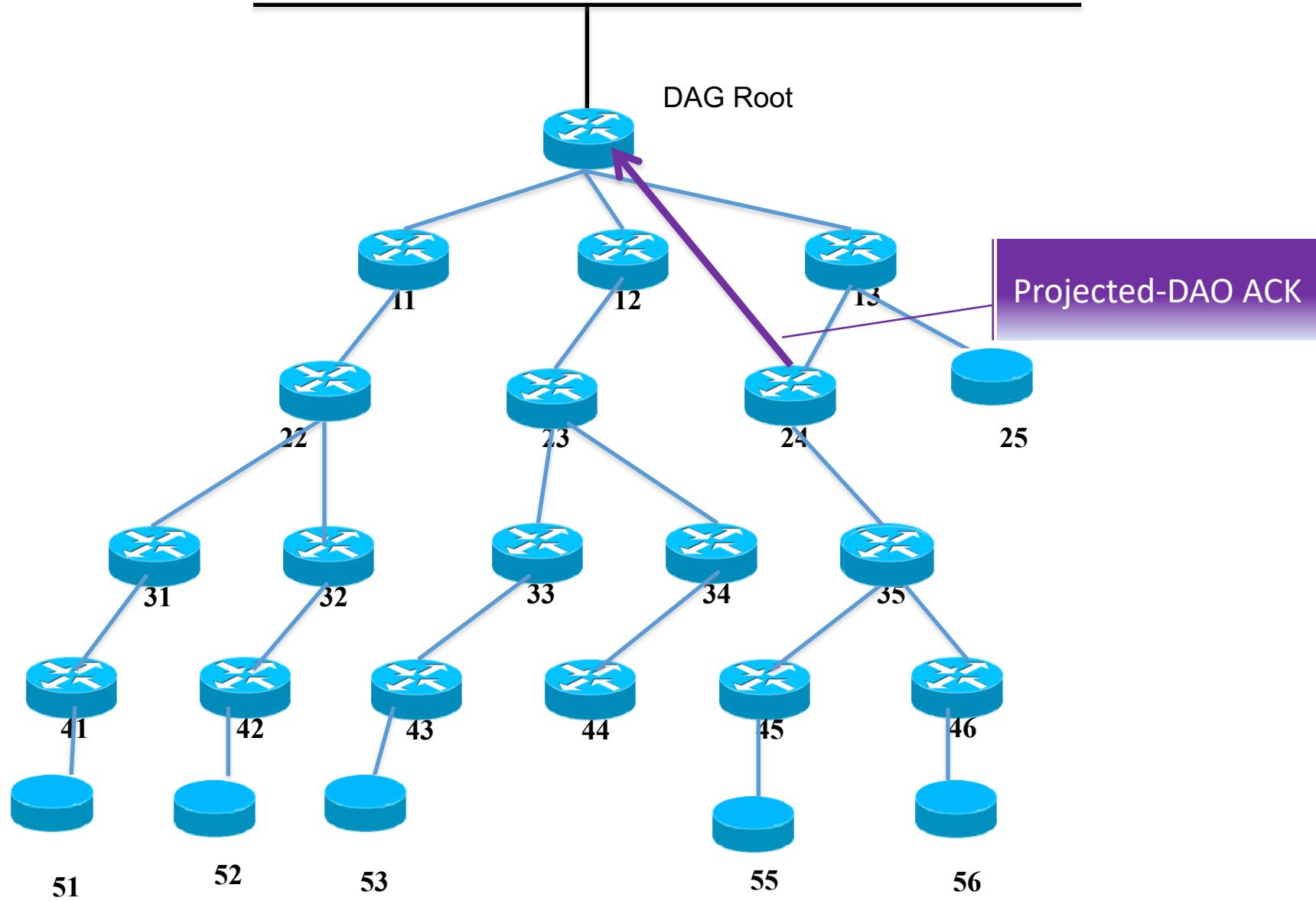


Controller



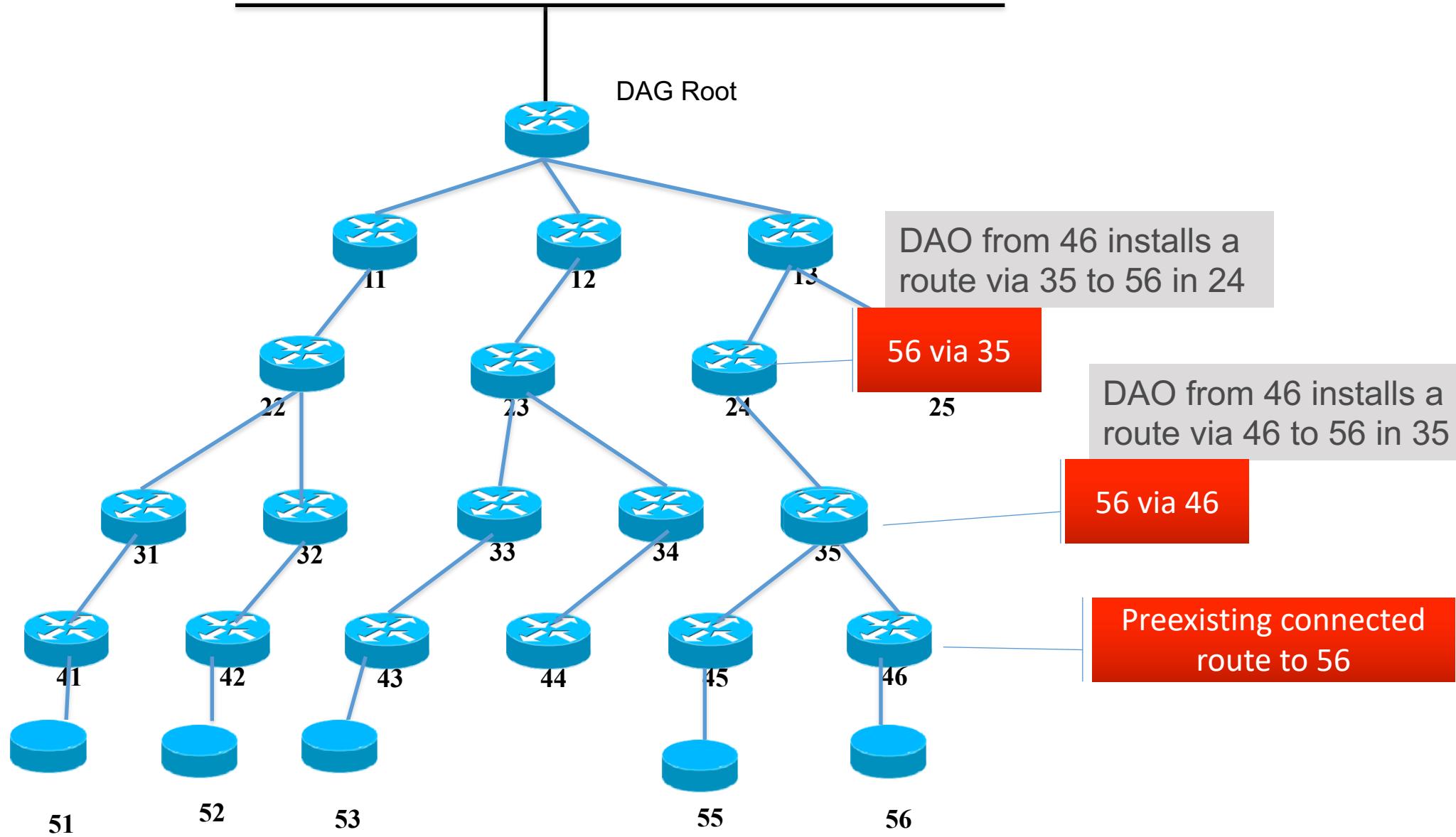


Controller



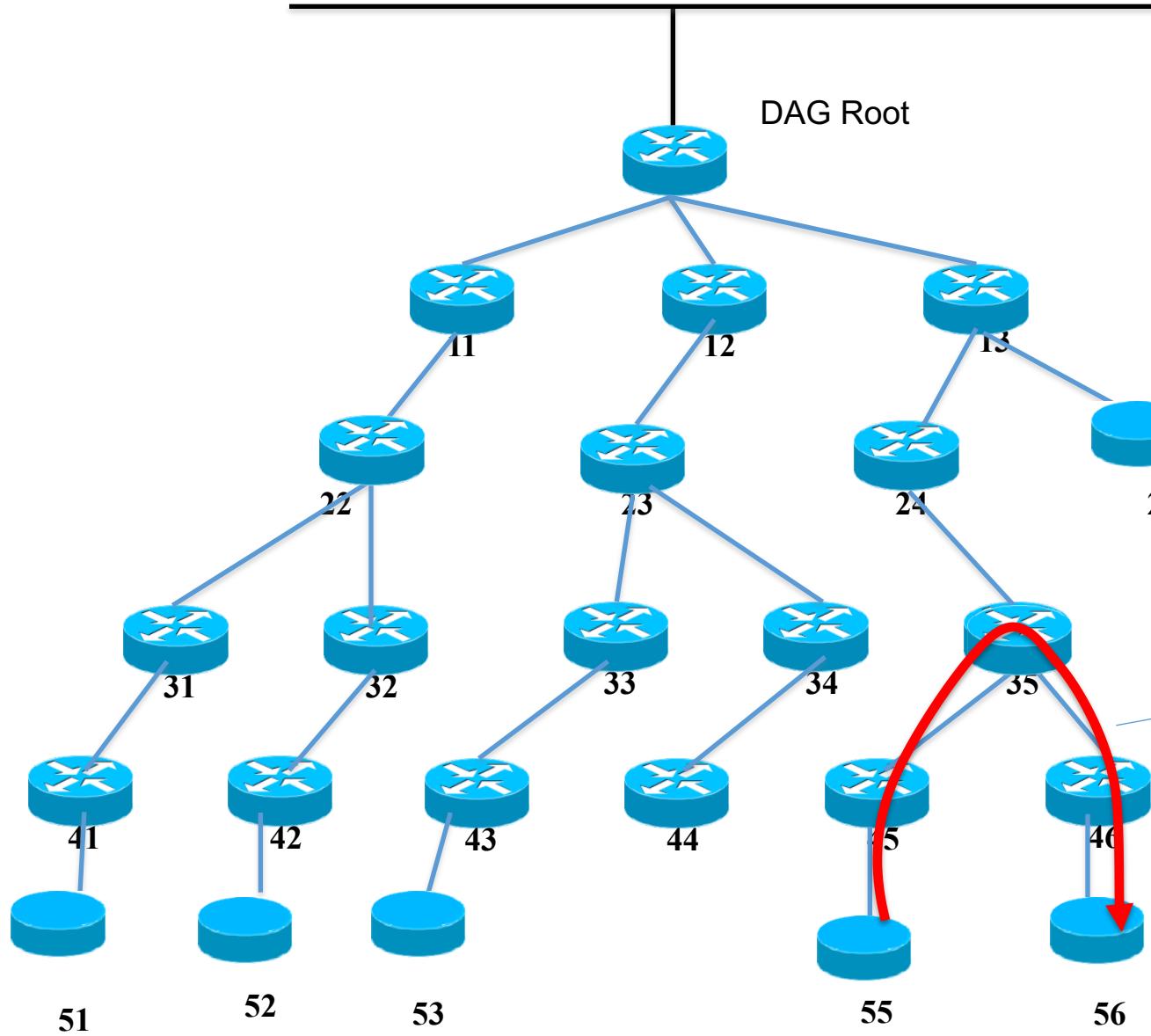


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Server D



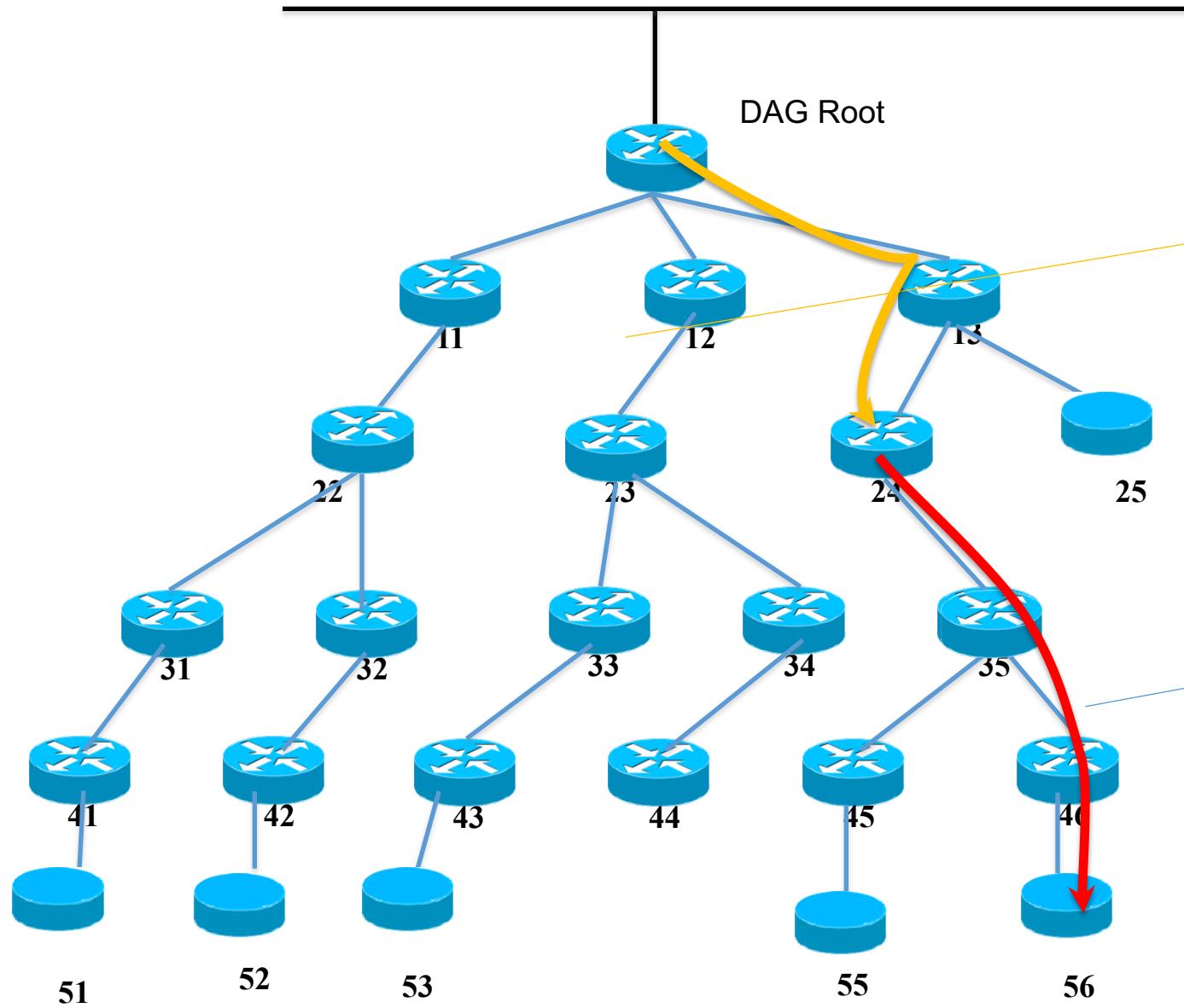


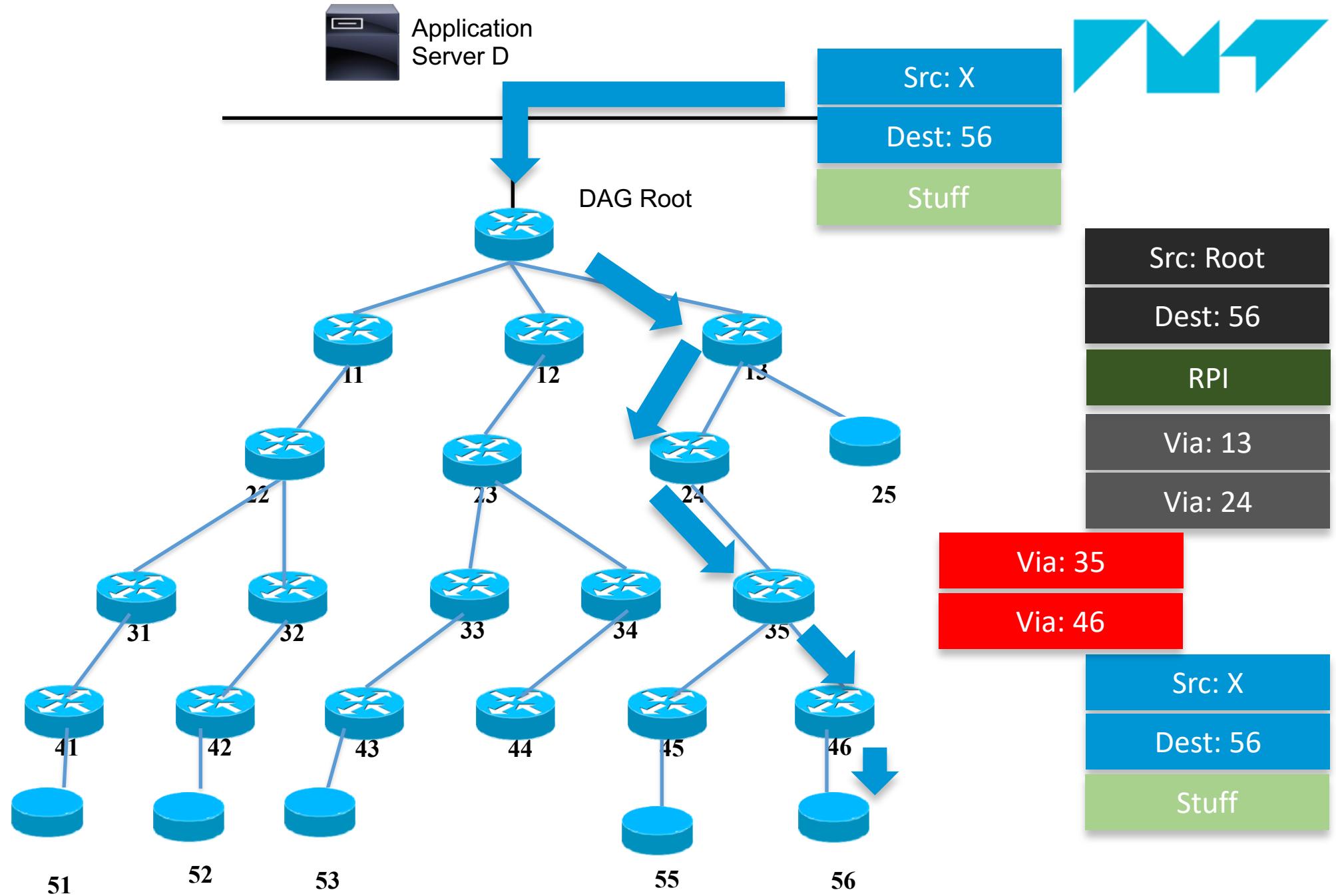
Controller





Application  
Server D





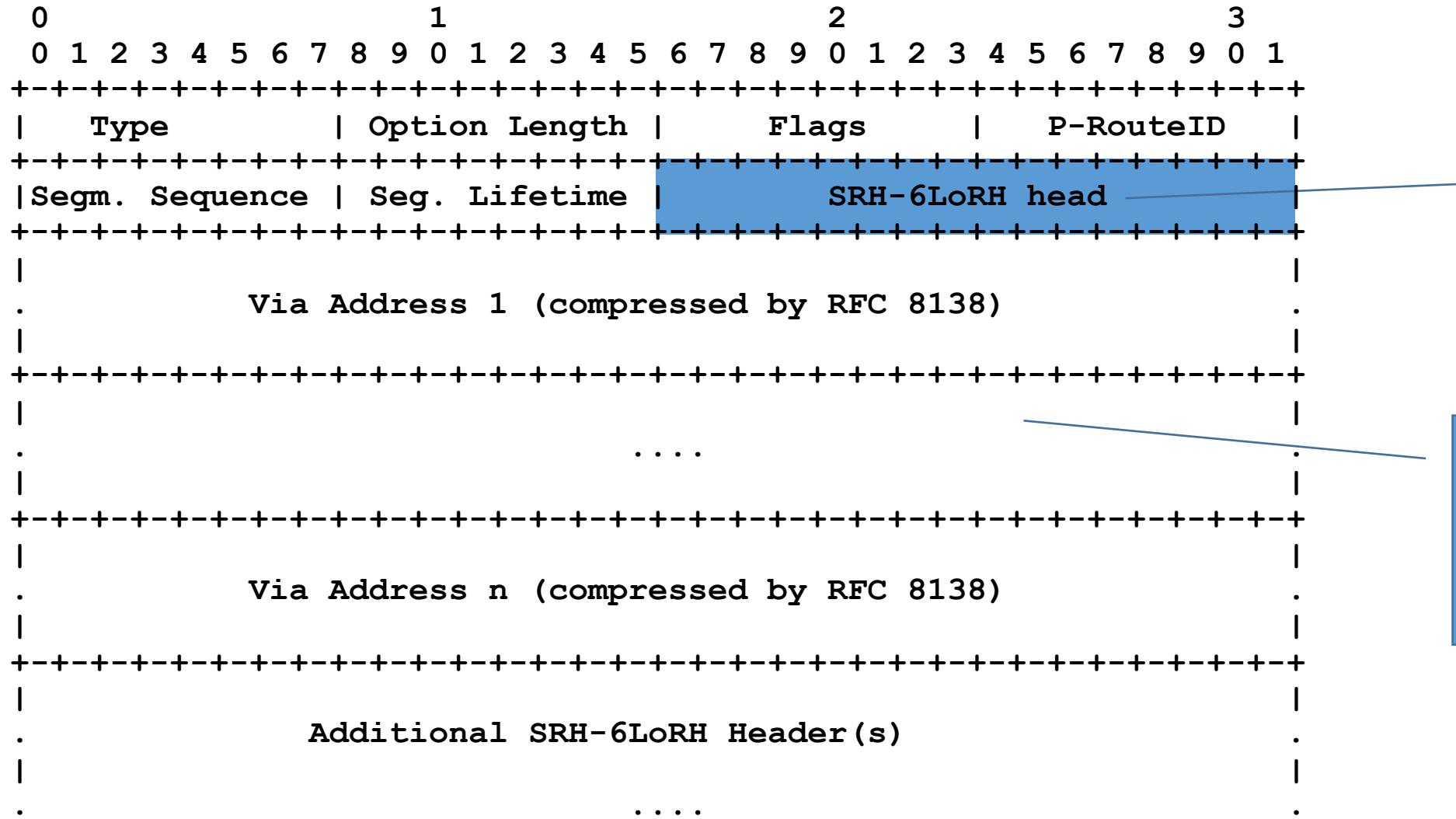


# P-DAO construction

- RPL Target Options can be factorized
- But there is one and only one VIO (SF-VIO or SR-VIO)
- So the Ack management is easier
- VIO sent to egress; SR-VIO sent to ingress
- Track ID is a RPL local instance ID
- Taken from the Track Egress Name Space



# New Via Information Option Format

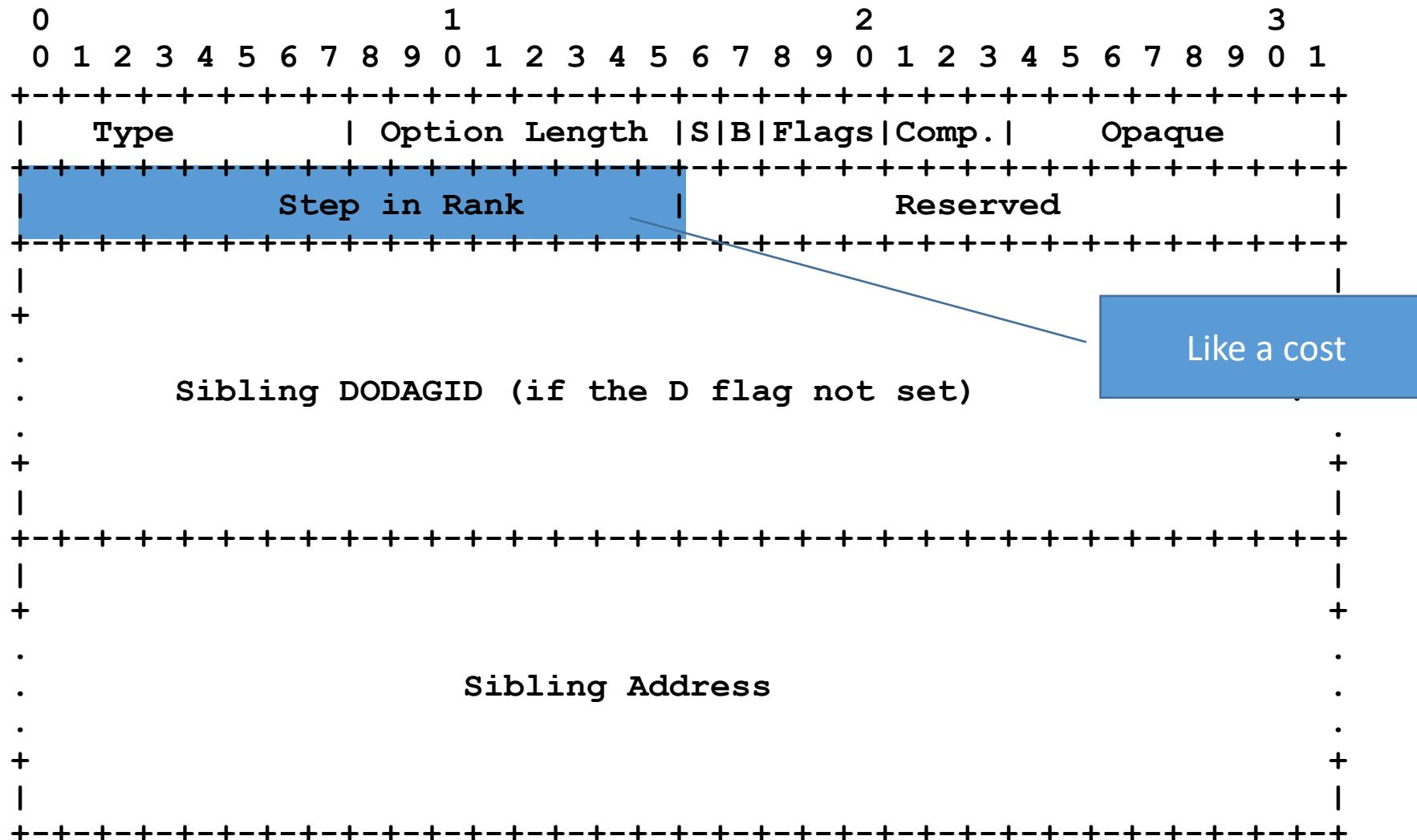


May be more than one in Non-storing Mode

Must be optimized in Non-storing Mode, to be used as is in packets



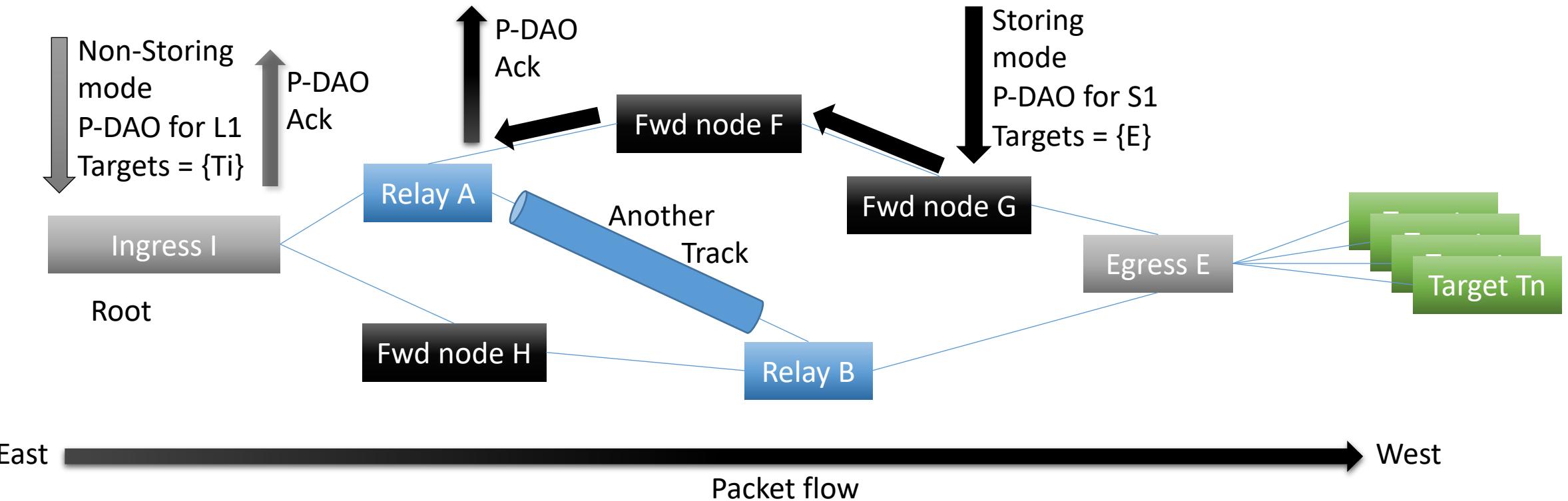
# New Sibling Information Option Format



In DAO and mcast DAO; mcast DAO allows indirect forwarding



# The RPL Track: A local DODAG rooted at Ingress



Targets {Tx }

Legs

L1 = I->A->E to {Ti} , L2 = I->B->E to {Ti} , L3 = I->A->B->E to {Ti}

Segments

S1 = A=>F=>G to E , S2 = I=>H to B

SubTracks

Any Set  $\subset \{L1, L2, L3\}$  but {}



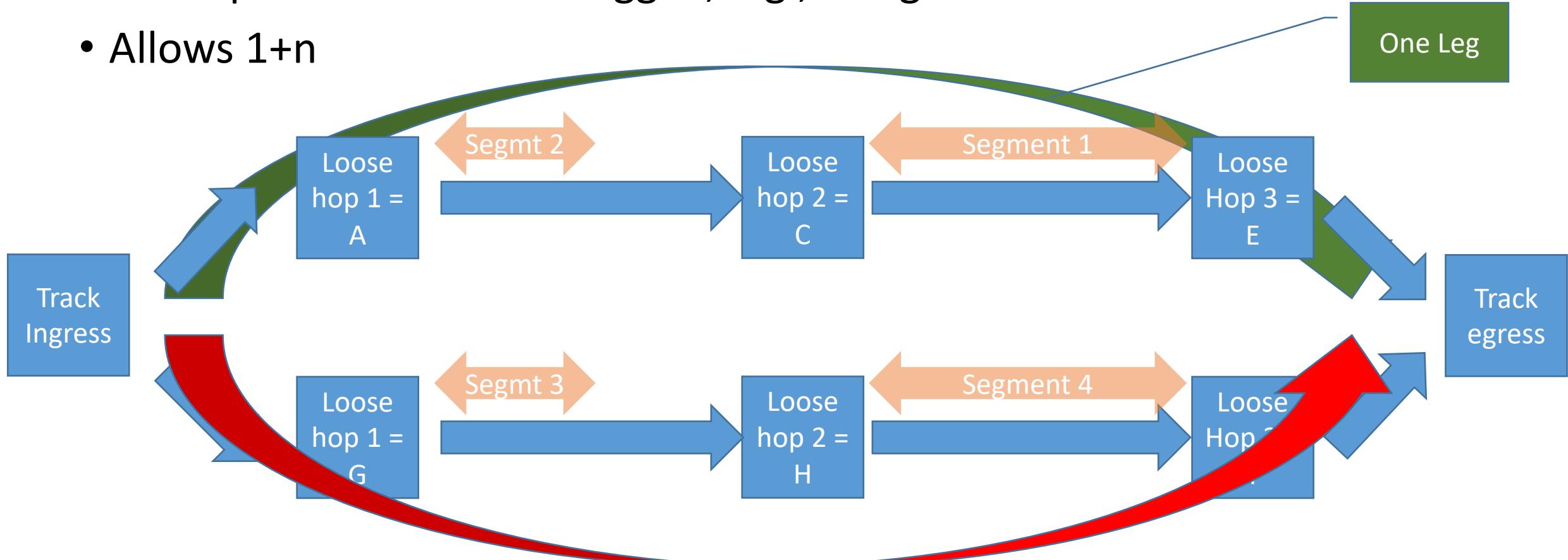
# Some rules

- Track is set up by installing Legs and Segment
  - with the same Track ID
- Non-Storing Mode P-DAO signals a Leg
- Storing Mode P-DAO signals a Segment
- Storing Mode P-DAO enables loose hops
  - in Non-Storing main DODAG (typically TrackId is Global instance ID)
  - in Tracks (typically TrackId is Local instance ID to track Ingress)
- Track Egress is implicit Target in Non-Storing Mode
- Leg hop is either a Segment of this Track or another Track



# Complex track

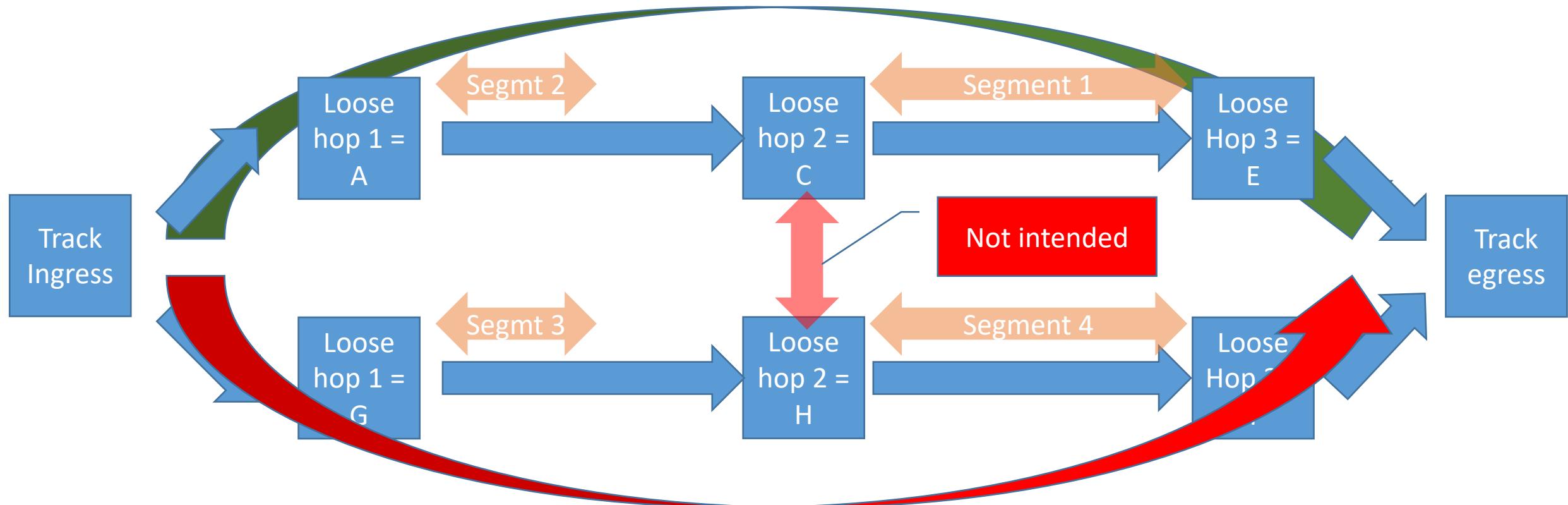
- A complex track is multi-legged, e.g., 2 Legs below
- Allows 1+n





# RPL vs RAW

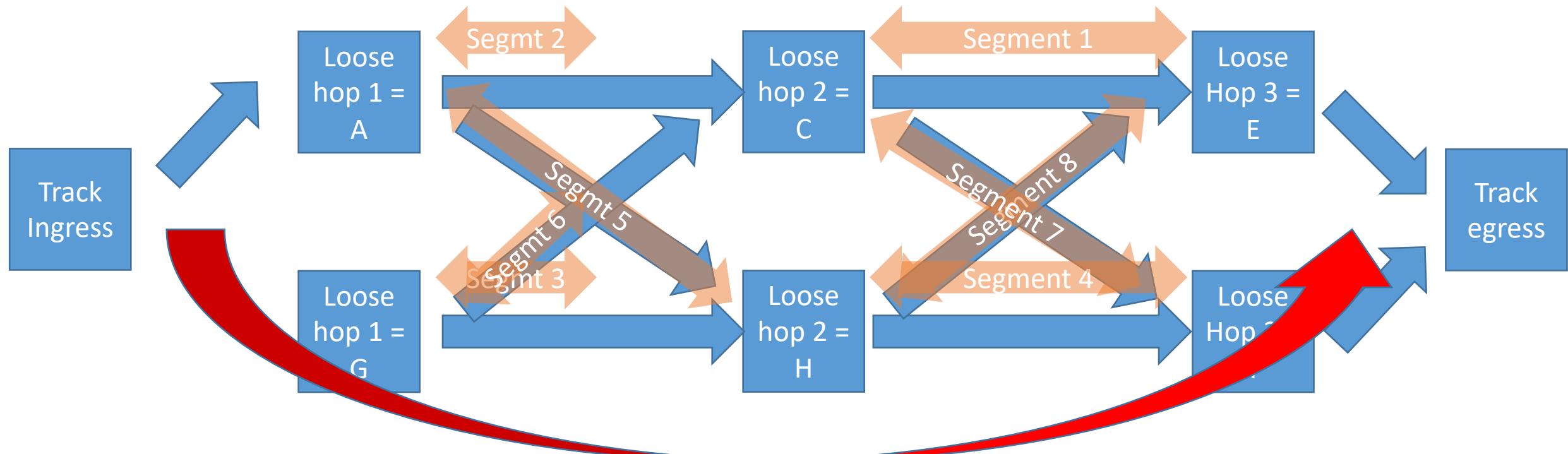
- RPL has no North-South Segment





# Inter Leg

- RFC 6550 non-storing Target and Transit to indicate loose parent child relationship, many of them in one P-DAO

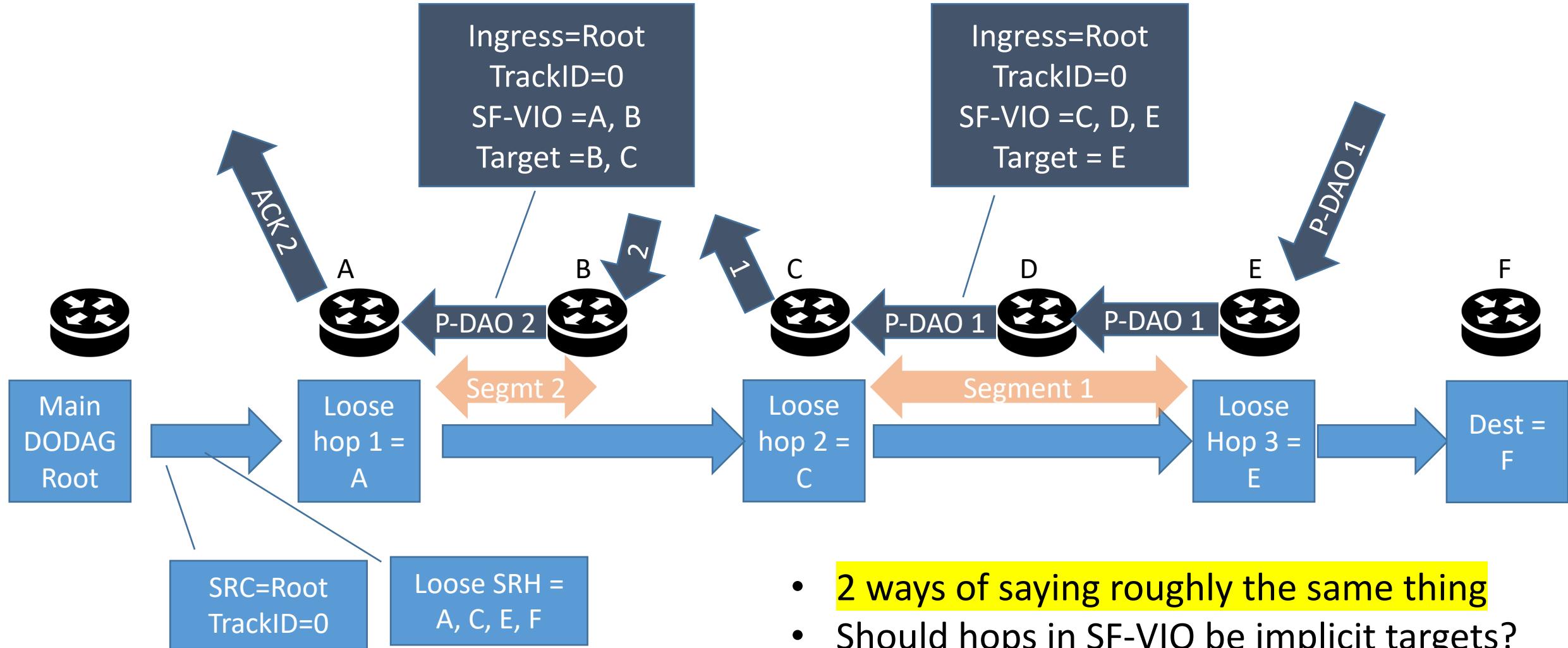




# Encapsulation Details

- Source of outer header MUST be Track Ingress- think DODAG Root
- RPL Instance ID in RPI MUST indicate TrackID (if not main DODAG)
- SR-VIO: Loose from Track Ingress, excluded, to Egress, included
  - Copied Verbatim in inserted SRH-6LoRH,
  - Requires encapsulation (can be recursive)
- SF-VIO: Strict from Segment Ingress to Egress, both included
  - No Encapsulation if Source and RPI both match Segment definition
  - A Segment is an Implicit Track if P-DAO Ingress == 1<sup>st</sup> SF-VIO entry
- TBD: matching rules, Flow Info option, when to tunnel?

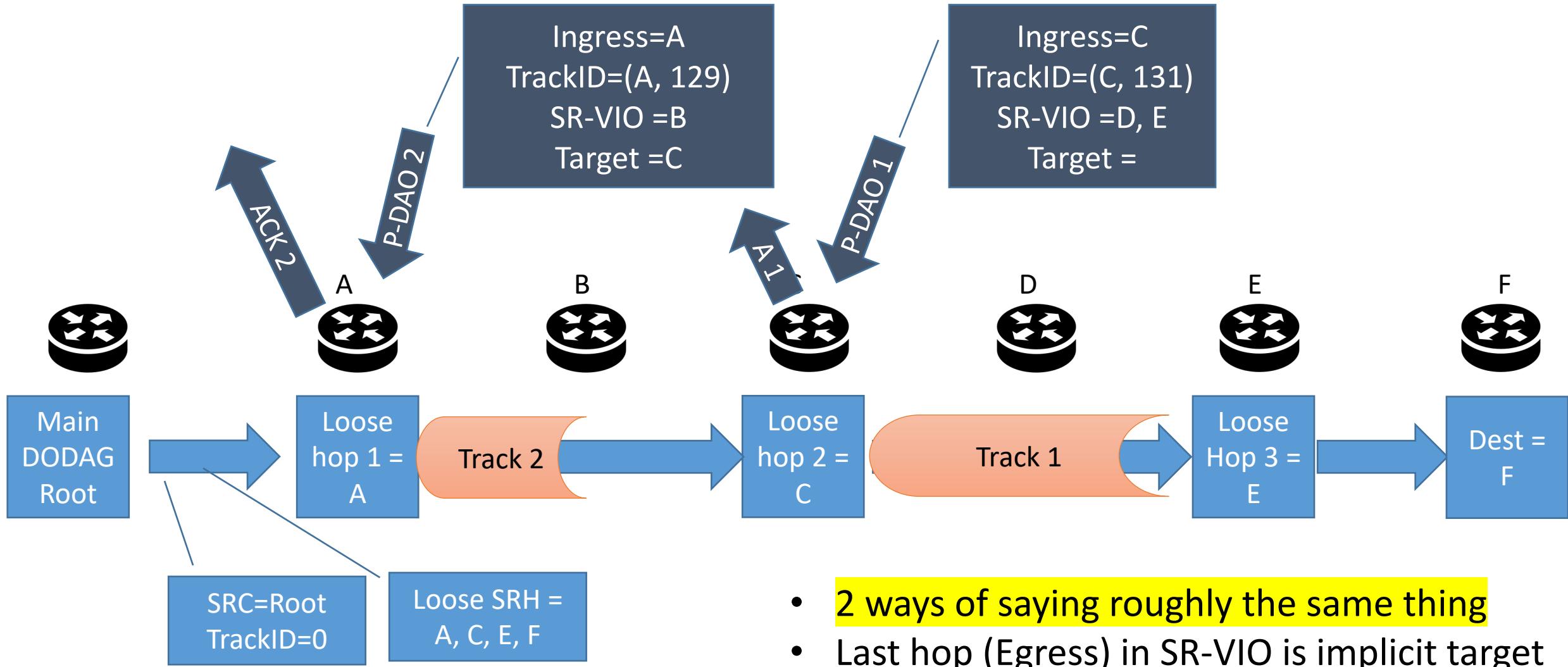
# Profile 1: Compress SRH in main DODAG with strict SM Segments



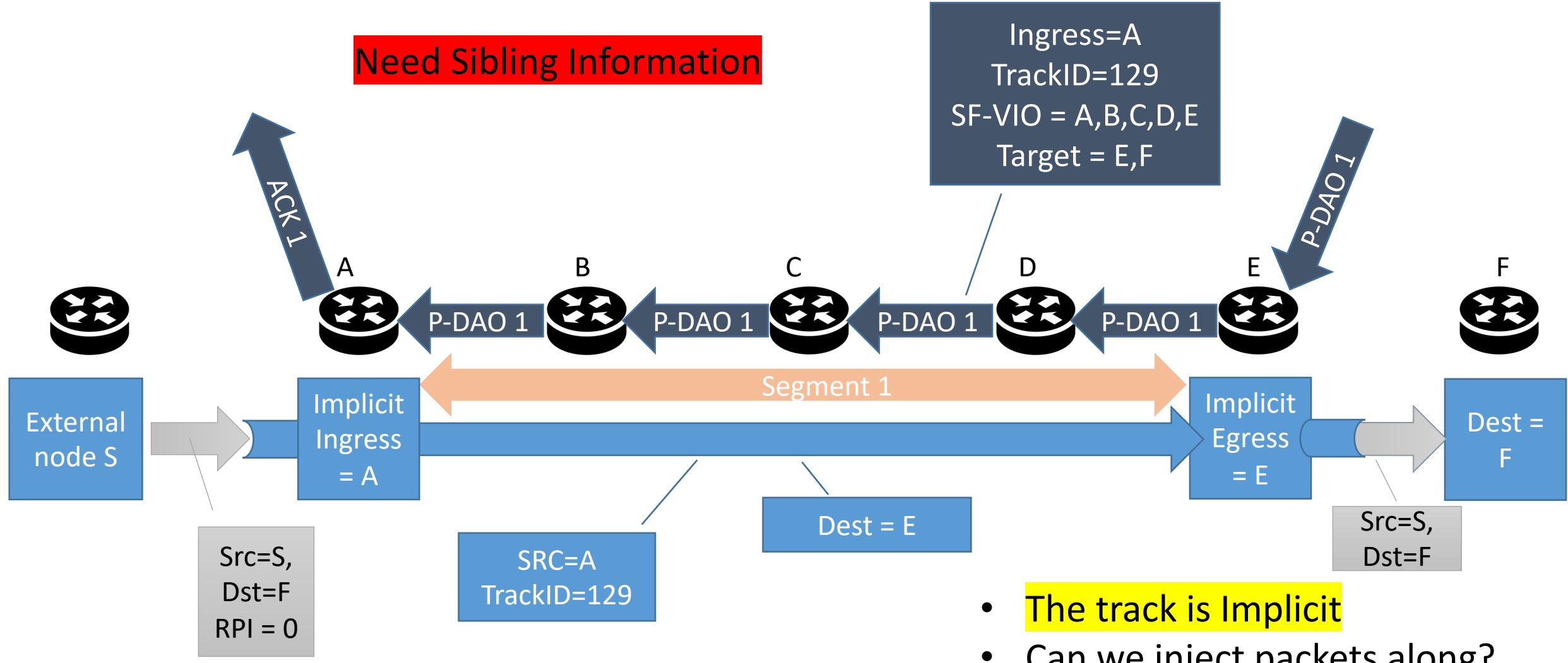
- 2 ways of saying roughly the same thing
- Should hops in SF-VIO be implicit targets?



# Profile 2: Compress SRH in main DODAG with Strict NSM Tracks

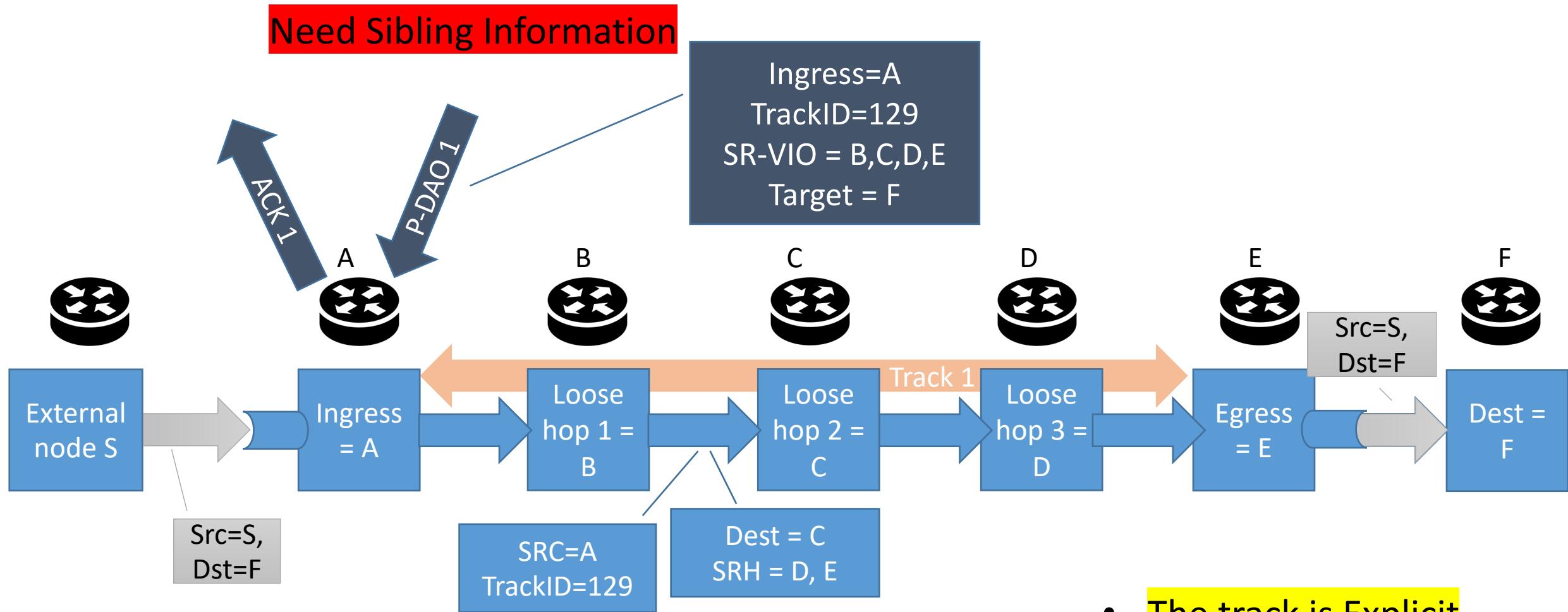


# Profile 3: Implicit Track with Strict SM Segments,





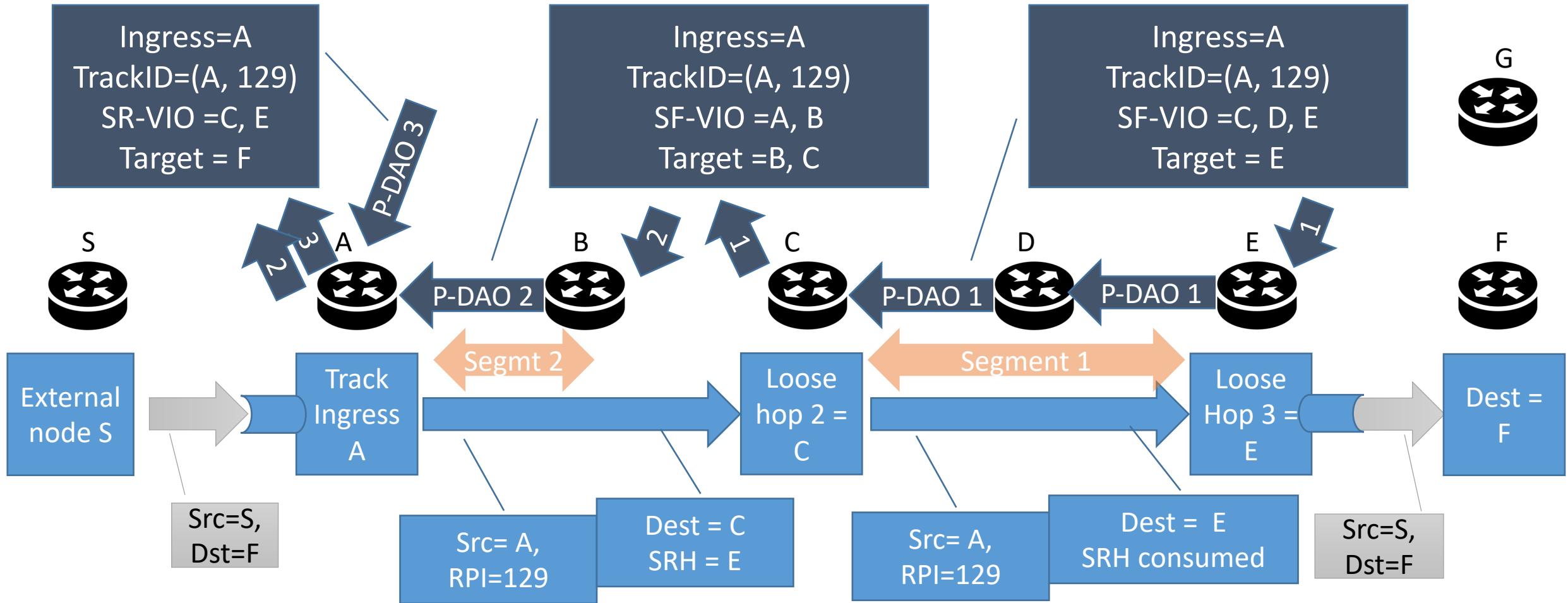
# Profile 4: Strict NSM Explicit Track



- The track is **Explicit**
- Same encapsulation as profile 2

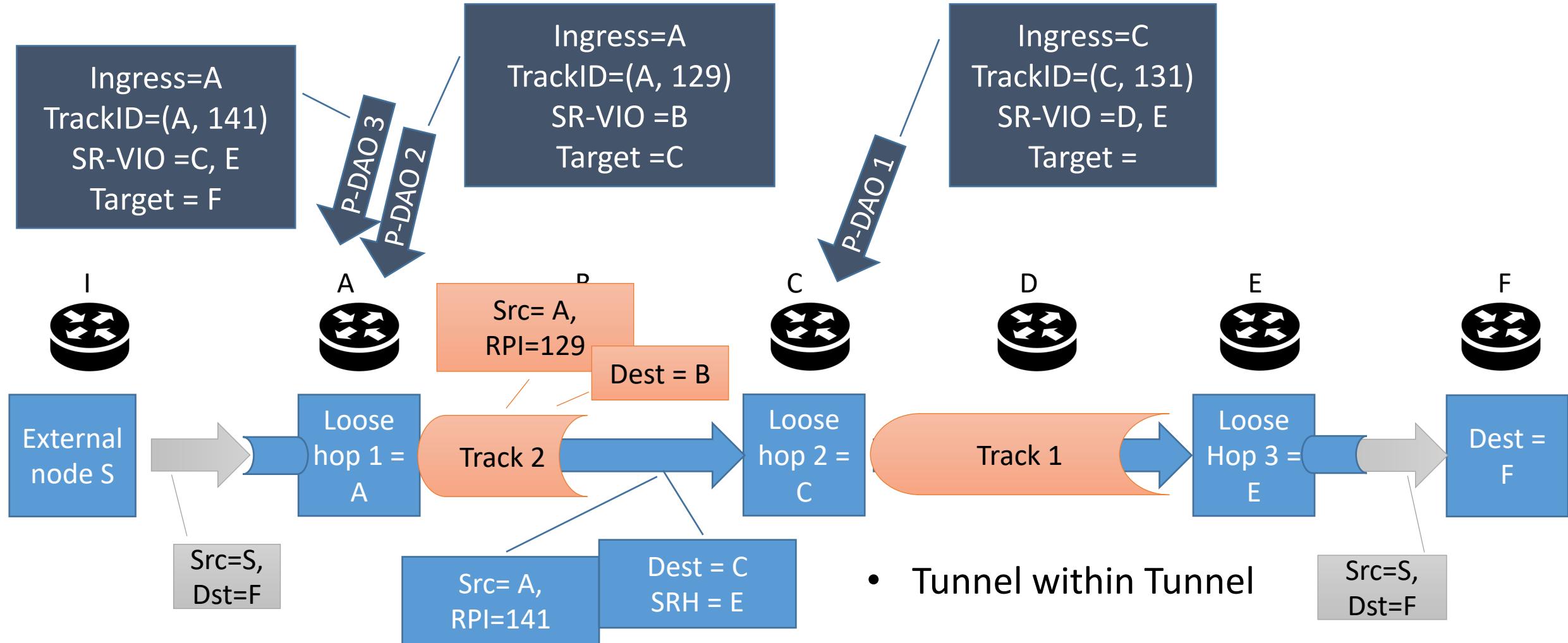
# Profile 5: Compress SRH in Track with Strict SM Segments

Need Sibling Information



- Same as Profile 1, but for Track

# Profile 6: Compress SRH in Track with NSM Tracks (Recursive?)



# RPL key concepts

RPL is an adaptable anisotropic IPv6 DV protocol

- Proactive routing for MP2P, P2MP, and stretched P2P

- P2P (reactive) and SDN (centralized) variations

RPL specifically designed for LLNs

- Agnostic to underlying link layer technologies (802.15.4, PLC, Low Power WiFi)

- Adapted to use case(s) with Objective Functions

Objective Functions => instantiation per constraints/metrics

Anisotropic Routing => minimum topological awareness

Data Path validation => lazy / reactive maintenance

Trickle Algorithm => Optimized Diffusion over NBMA

Non-Equal Cost Multipath Forwarding

Multi-topology proactive routing

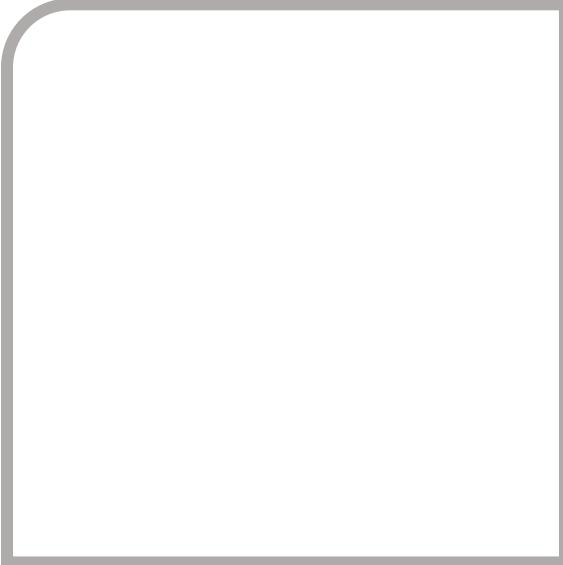
Autonomic (carries its own configuration)





# Questions ?

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# Controlling the control ... by design

## Distance Vector as opposed to Link State

- Knowledge of SubDAG addresses and children links
- Lesser topology awareness => lesser sensitivity to change
- No database Synchronization => Adapted to movement

## Optimized for Edge operation

- Optimized for P2MP / MP2P, stretch for arbitrary P2P
- Anisotropic Least Overhead Routing Approach via common ancestor

## Proactive route installation, reactive failure discovery

- Actually both with AODV (P2P) draft

## Datapath validation

- Loop Avoidance and inconsistency detection