tf.1_LSTM_vr.3

February 3, 2021

1 필요한 모듈을 가져오고 데이터를 로드합니다

```
[1]: import sys
    import warnings
    if not sys.warnoptions:
        warnings.simplefilter('ignore')
[2]: import tensorflow as tf
    import numpy as np
    import matplotlib.pyplot as plt
    import seaborn as sns
    import pandas as pd
    from sklearn.preprocessing import MinMaxScaler
    from datetime import datetime
    from datetime import timedelta
    from tqdm import tqdm
    sns.set()
    tf.compat.v1.random.set_random_seed(1234)
[3]: # 예측할 종목은 한양증권(001750) 입니다
    df = pd.read_csv('C:\Jupyter_Project\HanyangSecurities.csv')
    df.head()
[3]:
             Date Open High
                               Low Close Adj Close Volume
    0 2020-01-29 8740 9120 8740
                                     9120
                                                       96112
                                                9120
    1 2020-01-30 9350 9570
                              9200
                                     9370
                                                9370 175760
    2 2020-01-31 9380 9710 9380
                                     9570
                                                9570 226732
    3 2020-02-03 9440 9440
                              9030
                                     9140
                                                9140
                                                     99485
    4 2020-02-04 9140 9150
                              9020
                                     9110
                                                       30886
                                                9110
```

2 Normalization을 진행합니다

3 데이터를 분할하여 훈련 데이터를 생성합니다

```
[5]: test_size = 30
    simulation_size = 10

    df_train = df_log.iloc[:-test_size]
    df_test = df_log.iloc[-test_size:]
    df.shape, df_train.shape, df_test.shape
```

[5]: ((252, 7), (222, 1), (30, 1))

4 딥러닝 네트워크를 학습시킵니다

```
[6]: class Model:
         def __init__(
             self,
             learning_rate,
             num_layers,
             size,
             size_layer,
             output_size,
             forget_bias = 0.1,
         ):
             def lstm_cell(size_layer):
                 return tf.nn.rnn_cell.LSTMCell(size_layer, state_is_tuple = False)
             rnn_cells = tf.nn.rnn_cell.MultiRNNCell(
                 [lstm_cell(size_layer) for _ in range(num_layers)],
                 state_is_tuple = False,
             self.X = tf.placeholder(tf.float32, (None, None, size))
```

```
self.Y = tf.placeholder(tf.float32, (None, output_size))
        drop = tf.contrib.rnn.DropoutWrapper(
            rnn_cells, output_keep_prob = forget_bias
        self.hidden_layer = tf.placeholder(
            tf.float32, (None, num_layers * 2 * size_layer)
        self.outputs, self.last_state = tf.nn.dynamic_rnn(
            drop, self.X, initial_state = self.hidden_layer, dtype = tf.float32
        )
        self.logits = tf.layers.dense(self.outputs[-1], output_size)
        self.cost = tf.reduce_mean(tf.square(self.Y - self.logits))
        self.optimizer = tf.train.AdamOptimizer(learning_rate).minimize(
            self.cost
        )
def calculate_accuracy(real, predict):
    real = np.array(real) + 1
    predict = np.array(predict) + 1
    percentage = 1 - np.sqrt(np.mean(np.square((real - predict) / real)))
    return percentage * 100
def anchor(signal, weight):
    buffer = []
    last = signal[0]
    for i in signal:
        smoothed_val = last * weight + (1 - weight) * i
        buffer.append(smoothed_val)
        last = smoothed_val
    return buffer
```

```
[7]: num_layers = 1
    size_layer = 128
    timestamp = 5
    epoch = 300
    dropout_rate = 0.8
    future_day = test_size
    learning_rate = 0.01
```

```
[8]: def forecast():
    tf.reset_default_graph()
    modelnn = Model(
        learning_rate, num_layers, df_log.shape[1], size_layer, df_log.shape[1],
    dropout_rate
    )
    sess = tf.InteractiveSession()
    sess.run(tf.global_variables_initializer())
```

```
date_ori = pd.to_datetime(df.iloc[:, 0]).tolist()
  pbar = tqdm(range(epoch), desc = 'train loop')
  for i in pbar:
       init_value = np.zeros((1, num_layers * 2 * size_layer))
       total_loss, total_acc = [], []
       for k in range(0, df_train.shape[0] - 1, timestamp):
           index = min(k + timestamp, df_train.shape[0] - 1)
           batch_x = np.expand_dims(
               df_train.iloc[k : index, :].values, axis = 0
           batch_y = df_train.iloc[k + 1 : index + 1, :].values
           logits, last_state, _, loss = sess.run(
               [modelnn.logits, modelnn.last_state, modelnn.optimizer, modelnn.
⇔cost],
               feed_dict = {
                   modelnn.X: batch_x,
                   modelnn.Y: batch_y,
                   modelnn.hidden_layer: init_value,
               },
           )
           init_value = last_state
           total_loss.append(loss)
           total_acc.append(calculate_accuracy(batch_y[:, 0], logits[:, 0]))
       pbar.set_postfix(cost = np.mean(total_loss), acc = np.mean(total_acc))
  future_day = test_size
  output_predict = np.zeros((df_train.shape[0] + future_day, df_train.
\rightarrowshape[1]))
  output_predict[0] = df_train.iloc[0]
  upper_b = (df_train.shape[0] // timestamp) * timestamp
  init_value = np.zeros((1, num_layers * 2 * size_layer))
  for k in range(0, (df_train.shape[0] // timestamp) * timestamp, timestamp):
       out_logits, last_state = sess.run(
           [modelnn.logits, modelnn.last_state],
           feed dict = {
               modelnn.X: np.expand_dims(
                   df_train.iloc[k : k + timestamp], axis = 0
               modelnn.hidden_layer: init_value,
           },
       init_value = last_state
       output_predict[k + 1 : k + timestamp + 1] = out_logits
```

```
if upper_b != df_train.shape[0]:
             out_logits, last_state = sess.run(
                 [modelnn.logits, modelnn.last_state],
                 feed dict = {
                     modelnn.X: np.expand_dims(df_train.iloc[upper_b:], axis = 0),
                     modelnn.hidden_layer: init_value,
                 },
             )
             output_predict[upper_b + 1 : df_train.shape[0] + 1] = out_logits
             future_day -= 1
             date_ori.append(date_ori[-1] + timedelta(days = 1))
         init_value = last_state
         for i in range(future_day):
             o = output_predict[-future_day - timestamp + i:-future_day + i]
             out_logits, last_state = sess.run(
                 [modelnn.logits, modelnn.last_state],
                 feed_dict = {
                     modelnn.X: np.expand_dims(o, axis = 0),
                     modelnn.hidden_layer: init_value,
                 },
             )
             init_value = last_state
             output_predict[-future_day + i] = out_logits[-1]
             date_ori.append(date_ori[-1] + timedelta(days = 1))
         output_predict = minmax.inverse_transform(output_predict)
         deep_future = anchor(output_predict[:, 0], 0.3)
         return deep_future[-test_size:]
[9]: results = []
     for i in range(simulation_size):
         print('simulation %d'%(i + 1))
         results.append(forecast())
    simulation 1
    WARNING:tensorflow:From <ipython-input-6-d01d21f09afe>:12: LSTMCell.__init__
    (from tensorflow.python.ops.rnn_cell_impl) is deprecated and will be removed in
    a future version.
    Instructions for updating:
```

Instructions for updating:
This class is equivalent as tf.keras.layers.LSTMCell, and will be replaced by that in Tensorflow 2.0.
WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at
0x0000014232E560C8>: Using a concatenated state is slower and will soon be deprecated. Use state_is_tuple=True.

(from tensorflow.python.ops.rnn_cell_impl) is deprecated and will be removed in a future version.

Instructions for updating:

This class is equivalent as tf.keras.layers.StackedRNNCells, and will be replaced by that in Tensorflow 2.0.

WARNING: tensorflow:

The TensorFlow contrib module will not be included in TensorFlow 2.0. For more information, please see:

- * https://github.com/tensorflow/community/blob/master/rfcs/20180907-contribsunset.md
 - * https://github.com/tensorflow/addons
 - * https://github.com/tensorflow/io (for I/O related ops)

If you depend on functionality not listed there, please file an issue.

WARNING:tensorflow:From <ipython-input-6-d01d21f09afe>:27: dynamic_rnn (from tensorflow.python.ops.rnn) is deprecated and will be removed in a future version.

Instructions for updating:

Please use `keras.layers.RNN(cell)`, which is equivalent to this API WARNING:tensorflow:From C:\ProgramData\Anaconda3\envs\tf-1\lib\site-packages\tensorflow_core\python\ops\rnn_cell_impl.py:958: Layer.add_variable (from tensorflow.python.keras.engine.base_layer) is deprecated and will be removed in a future version.

Instructions for updating:

Please use `layer.add_weight` method instead.

WARNING:tensorflow:From C:\ProgramData\Anaconda3\envs\tf-1\lib\site-packages\tensorflow_core\python\ops\rnn_cell_impl.py:962: calling Zeros.__init__(from tensorflow.python.ops.init_ops) with dtype is deprecated and will be removed in a future version.

Instructions for updating:

Call initializer instance with the dtype argument instead of passing it to the constructor

WARNING:tensorflow:From <ipython-input-6-d01d21f09afe>:29: dense (from tensorflow.python.layers.core) is deprecated and will be removed in a future version.

Instructions for updating:

Use keras.layers.Dense instead.

WARNING:tensorflow:From C:\ProgramData\Anaconda3\envs\tf-1\lib\site-packages\tensorflow_core\python\layers\core.py:187: Layer.apply (from tensorflow.python.keras.engine.base_layer) is deprecated and will be removed in a future version.

Instructions for updating:

Please use `layer.__call__` method instead.

train loop: 100%|| 300/300

[00:39<00:00, 7.55it/s, acc=97, cost=0.00313]

simulation 2

WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at

Ox000001423242C908>: Using a concatenated state is slower and will soon be deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300

[00:39<00:00, 7.57it/s, acc=96.9, cost=0.0026]

simulation 3

WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at 0x0000014236F57748>: Using a concatenated state is slower and will soon be deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300

[00:39<00:00, 7.55it/s, acc=97.8, cost=0.00135]

simulation 4

WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at 0x00000142381BD848>: Using a concatenated state is slower and will soon be deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300

[00:40<00:00, 7.45it/s, acc=97.3, cost=0.00224]

simulation 5

WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at 0x00000142380A21C8>: Using a concatenated state is slower and will soon be deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300

[00:41<00:00, 7.29it/s, acc=97.4, cost=0.00226]

simulation 6

WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at 0x00000142381E2608>: Using a concatenated state is slower and will soon be deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300

[00:41<00:00, 7.28it/s, acc=97.4, cost=0.00197]

simulation 7

WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at 0x0000014239587B48>: Using a concatenated state is slower and will soon be deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300

[00:41<00:00, 7.16it/s, acc=97.8, cost=0.00143]

simulation 8

WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at 0x000001423A8EEE88>: Using a concatenated state is slower and will soon be deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300

[00:41<00:00, 7.21it/s, acc=97.3, cost=0.0023]

```
simulation 9
WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at
0x000001423A71EF08>: Using a concatenated state is slower and will soon be
deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300
[00:41<00:00, 7.19it/s, acc=96.8, cost=0.00289]

simulation 10
WARNING:tensorflow:<tensorflow.python.ops.rnn_cell_impl.LSTMCell object at
0x000001423CC89248>: Using a concatenated state is slower and will soon be
deprecated. Use state_is_tuple=True.

train loop: 100%|| 300/300
[00:41<00:00, 7.19it/s, acc=97.1, cost=0.00253]</pre>
```

5 Visualize

vr.1,2 모델과는 다른 예측기법이 적용되었습니다. 실값(true trend)과 10개의 예측모델(forcast 1~10)이 그래프 상에 나열되어 있기 때문에 차트를 추종하는지의 여부는 확인하기 어렵지만 model loss만을 측정하는 앞선 두 모델과는 달리 average accurracy(정확도)를 측정하는데에 의의가 있다고 생각합니다

```
accuracies = [calculate_accuracy(df['Close'].iloc[-test_size:].values, r) for r
in results]

plt.figure(figsize = (15, 5))
for no, r in enumerate(results):
    plt.plot(r, label = 'forecast %d'%(no + 1))
plt.plot(df['Close'].iloc[-test_size:].values, label = 'true trend', c = 'black')
plt.legend()
plt.title('average accuracy: %.4f'%(np.mean(accuracies)))
plt.show()
```

