

We have a car PUF that uses 2 arbiter PUFs – a working PUF and a reference PUF, as well as a secret threshold value $\tau > 0$.

Let Δ_w, Δ_r be the difference in timings experienced for the two PUFs on the same challenge. The response to this challenge is 0 if $|\Delta_w - \Delta_r| \leq \tau$ and the response is 1 if $|\Delta_w - \Delta_r| > \tau$ where $\tau > 0$ is the secret threshold value.

We have

$$\Delta_{31} = w_0 \cdot x_0 + w_1 \cdot x_1 + \dots + w_{31} \cdot x_{31} + \beta_{31} = \mathbf{w}^T \mathbf{x} + b$$

where

$$\begin{aligned} x_i &= d_i \cdot d_{i+1} \cdot \dots \cdot d_{31} \\ w_0 &= \alpha_0 \\ w_i &= \alpha_i + \beta_{i-1} \text{ (for } i > 0) \end{aligned}$$

Where $d_i = (1 - 2c_i)$; c_i is the i^{th} index of challenge vector \mathbf{C} .

where $\alpha_i = \frac{(p_i - q_i + r_i - s_i)}{2}$ and $\beta_i = \frac{(p_i - q_i - r_i + s_i)}{2}$

If $\Delta_{31} < 0$, upper signal wins and the answer is 0.

If $\Delta_{31} > 0$, lower signal wins and the answer is 1.

Thus, answer is simply $\frac{\text{sign}(\mathbf{w}^T \mathbf{x} + b) + 1}{2}$

Now we will implement same model for our both working and reference PUFs:

Let $(\mathbf{u}, p), (\mathbf{v}, q)$ be the two linear models that can exactly predict the outputs of the two arbiter PUFs sitting inside the CAR-PUF.

For working PUF:

$$\Delta_w = w_0 \cdot x_0 + w_1 \cdot x_1 + \dots + w_{31} \cdot x_{31} + \beta_{31} = \mathbf{u}^T \mathbf{x} + p$$

For reference PUF:

$$\Delta_r = w_0 \cdot x_0 + w_1 \cdot x_1 + \dots + w_{31} \cdot x_{31} + \beta_{31} = \mathbf{v}^T \mathbf{x} + q$$

If $|\Delta_w - \Delta_r| - \tau \leq 0 \rightarrow 0$

If $|\Delta_w - \Delta_r| - \tau > 0 \rightarrow 1$

And $|\Delta_w - \Delta_r| - \tau = |(\mathbf{u} - \mathbf{v})^T \mathbf{x} + p - q| - \tau$ {since we are using same challenge for the both PUFs}

For our problem response is:

$$\text{Response} = \frac{1 + \text{sign}(\mathbf{w}^T \phi(c) + b)}{2} = r \rightarrow \text{giveneqn(1)}$$

$$\text{Response} = \frac{1 + \text{sign}(|\Delta_w - \Delta_r| - \tau)}{2} = \frac{1 + \text{sign}(|(\mathbf{u} - \mathbf{v})^T \mathbf{x} + p - q| - \tau)}{2} \rightarrow \text{we haveeqn(2)}$$

$$\text{Let } \Delta = \Delta_w - \Delta_r = (\mathbf{u} - \mathbf{v})^T \mathbf{x} + p - q$$

If we multiply $|\Delta| - \tau$ by a positive number, then the $\text{sign}(|\Delta_w - \Delta_r| - \tau)$ remains same. We will multiply it by $|\Delta| + \tau$ (which is always positive).

$$\rightarrow (|\Delta| - \tau) * (|\Delta| + \tau) = \Delta^2 - \tau^2$$

So, we can write the above response as:

$$\text{Response} = \frac{1+\text{sign}(|\Delta_w - \Delta_r| - \tau)}{2} = \frac{1+\text{sign}(\Delta^2 - \tau^2)}{2} \dots\dots\dots \text{eqn(3)}$$

Let $\mathbf{w} = (\mathbf{u} - \mathbf{v})^T$ and $k = p - q$.

$$\Delta^2 = (w_0 \cdot x_0 + w_1 \cdot x_1 + \dots + w_{31} \cdot x_{31} + k) * (w_0 \cdot x_0 + w_1 \cdot x_1 + \dots + w_{31} \cdot x_{31} + k)$$

$$\Delta^2 = \sum_{i=0}^{31} w_i \cdot x_i^2 + \sum_{i=0}^{31} 2kw_i \cdot x_i + \sum_{i=0 \text{ \& } i \neq j}^{31} \sum_{j=0}^{31} 2w_i w_j \cdot x_i \cdot x_j + k^2$$

This equation has total $32+32+496+1=561$ terms but x_i^2 terms will merge into constant since $x_i = \pm 1 \Rightarrow$ its square will be 1 always. Let this whole constant is K which further will merge into τ^2 term and make new constant. In such way $\Delta^2 - \tau^2$ has $561-32-1=528$ variables in the form 2nd and 3rd term in the above equation.

So,

$$\Delta^2 - \tau^2 = \sum_{i=0}^{31} 2kw_i \cdot x_i + \sum_{i=0 \text{ \& } i \neq j}^{31} \sum_{j=0}^{31} 2w_i w_j \cdot x_i \cdot x_j + b \dots\dots\dots \text{eqn(4)}$$

Where $b = K - \tau^2$

As we are given our response in the form of above-mentioned equation.

From equations 1,2 and 3:

$$\mathbf{W}^T \phi(c) + b = \Delta^2 - \tau^2$$

After putting the values of right-hand side term from the equation (3),

$$\phi(c) = (x_0, x_1 \dots x_{31}, x_0 x_1 \dots \dots x_{30} x_{31})$$

Thus, the dimensionality of the function $\phi(c)$ is 528.