

Formulation of the problem:

The 2D Navier-Stokes equation for incompressible flow:

$$\frac{\partial U}{\partial t} + U \frac{\partial U}{\partial x} + V \frac{\partial U}{\partial y} = -\frac{1}{\rho} \frac{\partial P}{\partial x} + \frac{1}{Re} \left(\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} \right) \quad (1)$$

$$\frac{\partial V}{\partial t} + U \frac{\partial V}{\partial x} + V \frac{\partial V}{\partial y} = -\frac{1}{\rho} \frac{\partial P}{\partial y} + \frac{1}{Re} \left(\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} \right) \quad (2)$$

$$\frac{\partial V}{\partial x} + \frac{\partial U}{\partial y} = 0 \quad (3)$$

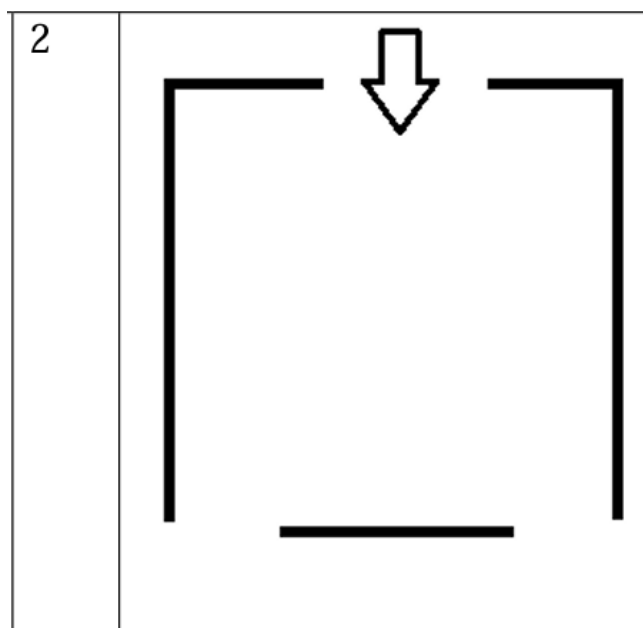
U – velocity compnent of x , V – velocity component of y

P – pressure, Re – Reynold's number

(1) - (2) Momentum equations

(3) Continuity equation

The following conditions:



$$x \in [0, 1], y \in [0, 1]$$

Initial condition:

$$U = 0, \quad V = 0, \quad P = 0$$

Inlet:

$$U = 0, \quad V = -1, \quad P = 1$$

Outlet:

$$\frac{\partial U}{\partial n} = 0, \quad \frac{\partial V}{\partial n} = 0, \quad P = 0$$

Walls:

$$U = 0, \quad V = 0, \quad \frac{\partial P}{\partial n} = 0$$

Numerical method: Projection method (Метод расщепления по физическим параметрам)

Projection method:

1)

$$\frac{U^{n+1} - U^n}{\Delta t} = -\frac{1}{\rho} \frac{\partial P}{\partial x} + L_1$$

$$\frac{V^{n+1} - V^n}{\Delta t} = -\frac{1}{\rho} \frac{\partial P}{\partial y} + L_2$$

$$L_1 = -U \frac{\partial U}{\partial x} - V \frac{\partial U}{\partial y} + \frac{1}{Re} \left(\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} \right)$$

$$L_2 = -U \frac{\partial V}{\partial x} - V \frac{\partial V}{\partial y} + \frac{1}{Re} \left(\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} \right)$$

$$\frac{U^{n+1} - U^n + U^* - U^*}{\Delta t} = -\frac{1}{\rho} \frac{\partial P}{\partial x} + L_1$$

$$\frac{V^{n+1} - V^n + V^* - V^*}{\Delta t} = -\frac{1}{\rho} \frac{\partial P}{\partial y} + L_2$$

$$\frac{U^* - U^n}{\Delta t} = L_1, \text{Burger's equation}$$

$$\frac{V^* - V^n}{\Delta t} = L_2, \text{Burger's equation}$$

$$\frac{U^{n+1} - U^*}{\Delta t} = -\frac{1}{\rho} \frac{\partial P^{n+1}}{\partial x}$$

$$\frac{V^{n+1} - V^*}{\Delta t} = -\frac{1}{\rho} \frac{\partial P^{n+1}}{\partial y}$$

$$U^{n+1} = U^* - \frac{\Delta t}{\rho} \frac{\partial P^{n+1}}{\partial x}$$

$$V^{n+1} = V^* - \frac{\Delta t}{\rho} \frac{\partial P^{n+1}}{\partial y}$$

2)

$$\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} = 0$$

$$\frac{\partial U^{n+1}}{\partial x} + \frac{\partial V^{n+1}}{\partial y} = 0$$

$$\frac{\partial}{\partial x} \left(U^* - \frac{\Delta t}{\rho} \frac{\partial P^{n+1}}{\partial x} \right) + \frac{\partial}{\partial y} \left(V^* - \frac{\Delta t}{\rho} \frac{\partial P^{n+1}}{\partial y} \right) = 0$$

$$\frac{\partial U^*}{\partial x} - \frac{\Delta t}{\rho} \frac{\partial^2 P^{n+1}}{\partial x^2} + \frac{\partial V^*}{\partial y} - \frac{\Delta t}{\rho} \frac{\partial^2 P^{n+1}}{\partial y^2} = 0$$

$$\frac{\partial^2 P^{n+1}}{\partial x^2} + \frac{\partial^2 P^{n+1}}{\partial y^2} = \frac{\rho}{\Delta t} \left(\frac{\partial U^*}{\partial x} + \frac{\partial V^*}{\partial y} \right), \quad \text{Poisson equation}$$

3)

$$U^{n+1} = U^* - \frac{\Delta t}{\rho} \frac{\partial P^{n+1}}{\partial x}$$

$$V^{n+1} = V^* - \frac{\Delta t}{\rho} \frac{\partial P^{n+1}}{\partial y}$$

Algorithm:

1) Solve Burger's equation to find U^*, V^* .

$$\frac{U^* - U^n}{\Delta t} = L_1$$
$$\frac{V^* - V^n}{\Delta t} = L_2$$

You can solve it with different numerical methods (Explicit, FSM, ADM, Tridiagonal matrix method).

2) Solve Poisson equation to find P.

$$\frac{\partial^2 P^{n+1}}{\partial x^2} + \frac{\partial^2 P^{n+1}}{\partial y^2} = \frac{\rho}{\Delta t} \left(\frac{\partial U^*}{\partial x} + \frac{\partial V^*}{\partial y} \right)$$

You can solve it with different numerical methods (Jacobi, Gauss-Seidel, Relaxation methods, Tridiagonal matrix method).

3) Correct velocity components U^{n+1}, V^{n+1} :

$$U^{n+1} = U^* - \frac{\Delta t}{\rho} \frac{\partial P^{n+1}}{\partial x}$$
$$V^{n+1} = V^* - \frac{\Delta t}{\rho} \frac{\partial P^{n+1}}{\partial y}$$

Numerical solution:

1) Burger's equation

$$\frac{\partial U}{\partial t} + U \frac{\partial U}{\partial x} + V \frac{\partial U}{\partial y} = \frac{1}{Re} \left(\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} \right)$$

$$\frac{\partial V}{\partial t} + U \frac{\partial V}{\partial x} + V \frac{\partial V}{\partial y} = \frac{1}{Re} \left(\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} \right)$$

a) Explicit method (Euler's method)

$$\frac{U^* - U^n}{\Delta t} = -U \frac{\partial U}{\partial x} - V \frac{\partial U}{\partial y} + \frac{1}{Re} \left(\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} \right)$$

$$U^* = U^n + \Delta t \left(-U \frac{\partial U}{\partial x} - V \frac{\partial U}{\partial y} + \frac{1}{Re} \left(\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} \right) \right)$$

$$\frac{V^* - V^n}{\Delta t} = -U \frac{\partial V}{\partial x} - V \frac{\partial V}{\partial y} + \frac{1}{Re} \left(\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} \right)$$

$$V^* = V^n + \Delta t \left(-U \frac{\partial V}{\partial x} - V \frac{\partial V}{\partial y} + \frac{1}{Re} \left(\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} \right) \right)$$

Discretization:

$$U_{ij}^* = U_{ij}^n + \Delta t \left(-U_{ij}^n \frac{U_{i+1j}^n - U_{i-1j}^n}{2\Delta x} - V_{ij}^n \frac{U_{ij+1}^n - U_{ij-1}^n}{2\Delta y} + \frac{1}{Re} \left(\frac{U_{i+1j}^n - 2U_{ij}^n + U_{i-1j}^n}{\Delta x^2} + \frac{U_{ij+1}^n - 2U_{ij}^n + U_{ij-1}^n}{\Delta y^2} \right) \right)$$

$$V_{ij}^* = V_{ij}^n + \Delta t \left(-U_{ij}^n \frac{V_{i+1j}^n - V_{i-1j}^n}{2\Delta x} - V_{ij}^n \frac{V_{ij+1}^n - V_{ij-1}^n}{2\Delta y} + \frac{1}{Re} \left(\frac{V_{i+1j}^n - 2V_{ij}^n + V_{i-1j}^n}{\Delta x^2} + \frac{V_{ij+1}^n - 2V_{ij}^n + V_{ij-1}^n}{\Delta y^2} \right) \right)$$

b) Implicit method FSM (Fractional step method)

First step:

$$\frac{U_{ij}^{n+1/2} - U_{ij}^n}{\Delta t} = \frac{1}{2} (\Lambda_1 U^{n+1/2} + \Lambda_1 U^n) + \Lambda_2 U^n$$

Second step:

$$\frac{U_{ij}^{n+1} - U_{ij}^{n+1/2}}{\Delta t} = \frac{1}{2} (\Lambda_2 U^{n+1} - \Lambda_2 U^n)$$

Here is the Λ_1, Λ_2 operators have the following form:

$$\Lambda_1 = \frac{1}{Re} \frac{\partial^2}{\partial x^2} - U \frac{\partial}{\partial x}, \quad \Lambda_2 = \frac{1}{Re} \frac{\partial^2}{\partial y^2} - V \frac{\partial}{\partial y}$$

First step:

$$\begin{aligned} \frac{U_{ij}^{n+1/2} - U_{ij}^n}{\Delta t} = & \frac{1}{2} \left(\frac{1}{Re} \frac{U_{i+1j}^{n+1/2} - 2U_{ij}^{n+1/2} + U_{i-1j}^{n+1/2}}{\Delta x^2} - U_{ij}^n \frac{U_{i+1j}^{n+1/2} - U_{ij}^{n+1/2}}{\Delta x} + \frac{1}{Re} \frac{U_{i+1j}^n - 2U_{ij}^n + U_{i-1j}^n}{\Delta x^2} - U_{ij}^n \frac{U_{i+1j}^n - U_{ij}^n}{\Delta x} \right) \\ & + \frac{1}{Re} \frac{U_{ij+1}^n - 2U_{ij}^n + U_{ij-1}^n}{\Delta y^2} - V_{ij}^n \frac{U_{ij+1}^n - U_{ij}^n}{\Delta y} \end{aligned}$$

*It also will work if you take a backward or central scheme for the first derivative. *

We are going to perform in this form to solve the Thomas algorithm.

$$A_{ij}U_{i+1j}^{n+1/2} + B_{ij}U_{ij}^{n+1/2} + C_{ij}U_{i-1j}^{n+1/2} = D_{ij}, \quad i = \overline{1, N-1}, j \text{ is fixed}$$

$$\begin{aligned} A_{ij} &= -\frac{1}{2Re\Delta x^2} + \frac{U_{ij}^n}{2\Delta x}, \quad B_{ij} = \frac{1}{\Delta t} + \frac{1}{Re\Delta x^2} - \frac{U_{ij}^n}{2\Delta x}, \quad C_{ij} = -\frac{1}{2Re\Delta x^2} \\ D_{ij} &= \frac{U_{ij}^n}{\Delta t} + \frac{1}{2} \left(\frac{1}{Re} \frac{U_{i+1j}^n - 2U_{ij}^n + U_{i-1j}^n}{\Delta x^2} - U_{ij}^n \frac{U_{i+1j}^n - U_{ij}^n}{\Delta x} \right) + \frac{1}{Re} \frac{U_{ij+1}^n - 2U_{ij}^n + U_{ij-1}^n}{\Delta y^2} - V_{ij}^n \frac{U_{ij+1}^n - U_{ij}^n}{\Delta y} \end{aligned}$$

Second step:

$$\frac{U_{ij}^{n+1} - U_{ij}^{n+1/2}}{\Delta t} = \frac{1}{2} \left(\frac{1}{Re} \frac{U_{i+1j}^{n+1} - 2U_{ij}^{n+1} + U_{i-1j}^{n+1}}{\Delta y^2} - V_{ij}^n \frac{U_{i+1j}^{n+1} - U_{ij}^{n+1}}{\Delta y} - \frac{1}{Re} \frac{U_{ij+1}^n - 2U_{ij}^n + U_{ij-1}^n}{\Delta y^2} + V_{ij}^n \frac{U_{ij+1}^n - U_{ij}^n}{\Delta y} \right)$$

Thomas algorithm for y:

$$A_{ij}U_{ij+1}^{n+1} + B_{ij}U_{ij}^{n+1} + C_{ij}U_{ij-1}^{n+1} = D_{ij}, \quad j = \overline{1, M-1}, i \text{ is fixed}$$

$$\begin{aligned} A_{ij} &= -\frac{1}{2Re\Delta y^2} + \frac{V_{ij}^n}{2\Delta y}, \quad B_{ij} = \frac{1}{\Delta t} + \frac{1}{Re\Delta y^2} - \frac{V_{ij}^n}{2\Delta y}, \quad C_{ij} = -\frac{1}{2Re\Delta y^2} \\ D_{ij} &= \frac{U_{ij}^{n+1/2}}{\Delta t} - \frac{1}{2} \left(\frac{1}{Re} \frac{U_{ij+1}^n - 2U_{ij}^n + U_{ij-1}^n}{\Delta y^2} - V_{ij}^n \frac{U_{ij+1}^n - U_{ij}^n}{\Delta y} \right) \end{aligned}$$

Do the same for V.

Derivations of alpha and betta:

$$U_{ij} = \alpha_{i+1j}U_{i+1j} + \beta_{i+1j}, \quad i = \overline{N-1, 1} \quad (3)$$

$$A_{ij}U_{i+1j} + B_{ij}U_{ij} + C_{ij}U_{i-1j} = D_{ij}, \quad i = \overline{1, N-1} \quad (4)$$

$$U_{i-1j} = \alpha_{ij}U_{ij} + \beta_{ij}, \quad i = \overline{1, N-1} \quad (5)$$

Substitute equation (5) into (4)

$$A_{ij}U_{i+1j} + B_{ij}U_{ij} + C_{ij}(\alpha_{ij}U_{ij} + \beta_{ij}) = D_{ij}$$

$$A_{ij}U_{i+1j} + (B_{ij} + C_{ij}\alpha_{ij})U_{ij} + C_{ij}\beta_{ij} = D_{ij}$$

$$U_{ij} = -\frac{A_{ij}}{B_{ij} + C_{ij}\alpha_{ij}}U_{i+1j} + \frac{D_{ij} - C_{ij}\beta_{ij}}{B_{ij} + C_{ij}\alpha_{ij}} \quad (6)$$

Equation (6) looks like (3) so we can find $\alpha_{i+1j}, \beta_{i+1j}$

$$\alpha_{i+1j} = -\frac{A_{ij}}{B_{ij} + C_{ij}\alpha_{ij}}, \quad \beta_{i+1j} = \frac{D_{ij} - C_{ij}\beta_{ij}}{B_{ij} + C_{ij}\alpha_{ij}}, \quad (7)$$

$i = \overline{1, N-1}, j \text{ is fixed}$

c) Implicit method ADM (Alternating direction method)

First step:

$$\frac{U_{ij}^{n+1/2} - U_{ij}^n}{\Delta t} = \Lambda_1 U^{n+1/2} + \Lambda_2 U^n$$

Second step:

$$\frac{U_{ij}^{n+1} - U_{ij}^{n+1/2}}{\Delta t} = \Lambda_1 U^{n+1/2} + \Lambda_2 U^{n+1}$$

Here is the Λ_1 and Λ_2 operators have the following form:

$$\Lambda_1 = \frac{1}{Re} \frac{\partial^2}{\partial x^2} - U \frac{\partial}{\partial x}, \quad \Lambda_2 = \frac{1}{Re} \frac{\partial^2}{\partial y^2} - V \frac{\partial}{\partial y}$$

First step:

$$\frac{U_{ij}^{n+1/2} - U_{ij}^n}{\Delta t} = \frac{1}{Re} \frac{U_{i+1j}^{n+1/2} - 2U_{ij}^{n+1/2} + U_{i-1j}^{n+1/2}}{\Delta x^2} - U_{ij}^n \frac{U_{i+1j}^{n+1/2} - U_{ij}^{n+1/2}}{\Delta x} + \frac{1}{Re} \frac{U_{ij+1}^n - 2U_{ij}^n + U_{ij-1}^n}{\Delta y^2} - V_{ij}^n \frac{U_{ij+1}^n - U_{ij}^n}{\Delta y}$$

We are going to perform in this form to solve the Thomas algorithm.

$$A_{ij}U_{i+1j}^{n+1/2} + B_{ij}U_{ij}^{n+1/2} + C_{ij}U_{i-1j}^{n+1/2} = D_{ij}, \quad i = \overline{1, N-1}, j \text{ is fixed}$$

$$A_{ij} = -\frac{1}{Re\Delta x^2} + \frac{U_{ij}^n}{\Delta x}, \quad B_{ij} = \frac{1}{\Delta t} + \frac{2}{Re\Delta x^2} - \frac{U_{ij}^n}{\Delta x}, \quad C_{ij} = -\frac{1}{Re\Delta x^2}$$

$$D_{ij} = \frac{U_{ij}^n}{\Delta t} + \frac{1}{Re} \frac{U_{ij+1}^n - 2U_{ij}^n + U_{ij-1}^n}{\Delta y^2} - V_{ij}^n \frac{U_{ij+1}^n - U_{ij}^n}{\Delta y}$$

Second step:

$$\begin{aligned} \frac{U_{ij}^{n+1} - U_{ij}^{n+1/2}}{\Delta t} &= \\ &= \frac{1}{Re} \frac{U_{i+1j}^{n+1/2} - 2U_{ij}^{n+1/2} + U_{i-1j}^{n+1/2}}{\Delta x^2} - U_{ij}^n \frac{U_{i+1j}^{n+1/2} - U_{ij}^{n+1/2}}{\Delta x} + \frac{1}{Re} \frac{U_{ij+1}^{n+1} - 2U_{ij}^{n+1} + U_{ij-1}^{n+1}}{\Delta y^2} - V_{ij}^n \frac{U_{ij+1}^{n+1} - U_{ij}^{n+1}}{\Delta y} \end{aligned}$$

Thomas algorithm for y:

$$\begin{aligned} A_{ij} U_{ij+1}^{n+1} + B_{ij} U_{ij}^{n+1} + C_{ij} U_{ij-1}^{n+1} &= D_{ij}, \quad j = \overline{1, M-1}, i \text{ is fixed} \\ A_{ij} &= -\frac{1}{Re \Delta y^2} + \frac{V_{ij}^n}{\Delta y}, \quad B_{ij} = \frac{1}{\Delta t} + \frac{2}{Re \Delta y^2} - \frac{V_{ij}^n}{\Delta y}, \quad C_{ij} = -\frac{1}{Re \Delta y^2} \\ D_{ij} &= \frac{U_{ij}^{n+1/2}}{\Delta t} + \frac{1}{Re} \frac{U_{i+1j}^{n+1/2} - 2U_{ij}^{n+1/2} + U_{i-1j}^{n+1/2}}{\Delta x^2} - U_{ij}^n \frac{U_{i+1j}^{n+1/2} - U_{ij}^{n+1/2}}{\Delta x} \end{aligned}$$

Do the same for V.

2) Poisson equation

$$\frac{\partial^2 P^{n+1}}{\partial x^2} + \frac{\partial^2 P^{n+1}}{\partial y^2} = \frac{\rho}{\Delta t} \left(\frac{\partial U^*}{\partial x} + \frac{\partial V^*}{\partial y} \right)$$

We need to solve this equation until steady condition is reached:

$$\begin{aligned} \max(|P^{n+1} - P^n|) &< \varepsilon \\ \varepsilon &= \text{small number}, 10^{-6} \end{aligned}$$

a) Explicit method. Jacobi.

Discretization:

$$\begin{aligned} \frac{P_{i+1j}^n - 2P_{ij}^{n+1} + P_{i-1j}^n}{\Delta x^2} + \frac{P_{ij+1}^n - 2P_{ij}^{n+1} + P_{ij-1}^n}{\Delta y^2} &= \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \\ P_{ij}^{n+1} \left(\frac{2}{\Delta x^2} + \frac{2}{\Delta y^2} \right) &= \frac{P_{i+1j}^n + P_{i-1j}^n}{\Delta x^2} + \frac{P_{ij+1}^n + P_{ij-1}^n}{\Delta y^2} - \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \\ P_{ij}^{n+1} &= \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)} \left(\frac{P_{i+1j}^n + P_{i-1j}^n}{\Delta x^2} + \frac{P_{ij+1}^n + P_{ij-1}^n}{\Delta y^2} - \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \right) \end{aligned}$$

Final iterative formula:

$$P_{ij}^{n+1} = \frac{\Delta y^2 (P_{i+1j}^n + P_{i-1j}^n) + \Delta x^2 (P_{ij+1}^n + P_{ij-1}^n)}{2(\Delta x^2 + \Delta y^2)} - \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)} \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right)$$

b) Explicit method. Gauss-Seidel.

Discretization:

$$\begin{aligned}\frac{P_{i+1j}^n - 2P_{ij}^{n+1} + P_{i-1j}^{n+1}}{\Delta x^2} + \frac{P_{ij+1}^n - 2P_{ij}^{n+1} + P_{ij-1}^{n+1}}{\Delta y^2} &= \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \\ P_{ij}^{n+1} \left(\frac{2}{\Delta x^2} + \frac{2}{\Delta y^2} \right) &= \frac{P_{i+1j}^n + P_{i-1j}^{n+1}}{\Delta x^2} + \frac{P_{ij+1}^n + P_{ij-1}^{n+1}}{\Delta y^2} - \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \\ P_{ij}^{n+1} &= \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)} \left(\frac{P_{i+1j}^n + P_{i-1j}^{n+1}}{\Delta x^2} + \frac{P_{ij+1}^n + P_{ij-1}^{n+1}}{\Delta y^2} - \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \right)\end{aligned}$$

Final iterative formula.

$$P_{ij}^{n+1} = \frac{\Delta y^2 (P_{i+1j}^n + P_{i-1j}^{n+1}) + \Delta x^2 (P_{ij+1}^n + P_{ij-1}^{n+1})}{2(\Delta x^2 + \Delta y^2)} - \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)} \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right)$$

c) Explicit method. Relaxation methods.

Discretization:

$$\begin{aligned}\frac{P_{i+1j}^n - 2P_{ij}^{n+1} + P_{i-1j}^{n+1}}{\Delta x^2} + \frac{P_{ij+1}^n - 2P_{ij}^{n+1} + P_{ij-1}^{n+1}}{\Delta y^2} &= \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \\ P_{ij}^{n+1} \left(\frac{2}{\Delta x^2} + \frac{2}{\Delta y^2} \right) &= \frac{P_{i+1j}^n + P_{i-1j}^{n+1}}{\Delta x^2} + \frac{P_{ij+1}^n + P_{ij-1}^{n+1}}{\Delta y^2} - \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \\ P_{ij}^{n+1} &= \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)} \left(\frac{P_{i+1j}^n + P_{i-1j}^{n+1}}{\Delta x^2} + \frac{P_{ij+1}^n + P_{ij-1}^{n+1}}{\Delta y^2} - \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \right) \\ P_{ij}^{n+1} &= \frac{\Delta y^2 (P_{i+1j}^n + P_{i-1j}^{n+1}) + \Delta x^2 (P_{ij+1}^n + P_{ij-1}^{n+1})}{2(\Delta x^2 + \Delta y^2)} - \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)} \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right) \\ \frac{P_{ij}^{n+1}}{w} + \left(1 - \frac{1}{w} \right) P_{ij}^n &= \frac{\Delta y^2 (P_{i+1j}^n + P_{i-1j}^{n+1}) + \Delta x^2 (P_{ij+1}^n + P_{ij-1}^{n+1})}{2(\Delta x^2 + \Delta y^2)} - \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)} \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right)\end{aligned}$$

Final iterative formula.

$$\begin{aligned}P_{ij}^{n+1} &= \\ &= (1 - w)P_{ij}^n + w \frac{\Delta y^2 (P_{i+1j}^n + P_{i-1j}^{n+1}) + \Delta x^2 (P_{ij+1}^n + P_{ij-1}^{n+1})}{2(\Delta x^2 + \Delta y^2)} - w \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)} \frac{\rho}{\Delta t} \left(\frac{U_{i+1j}^* - U_{i-1j}^*}{2\Delta x} + \frac{V_{ij+1}^* - V_{ij-1}^*}{2\Delta y} \right)\end{aligned}$$

w – relaxation parameter

$w \in (0, 1)$ Under relaxation

$w \in (1, 2)$ Over relaxation

3) Correction

$$U^{n+1} = U^* - \frac{\Delta t}{\rho} \frac{\partial P}{\partial x}$$

$$V^{n+1} = V^* - \frac{\Delta t}{\rho} \frac{\partial P}{\partial y}$$

Discretization:

$$U_{ij}^{n+1} = U_{ij}^* - \frac{\Delta t}{\rho} \frac{P_{i+1j}^{n+1} - P_{i-1j}^{n+1}}{2\Delta x}$$

$$V_{ij}^{n+1} = V_{ij}^* - \frac{\Delta t}{\rho} \frac{P_{ij+1}^{n+1} - P_{ij-1}^{n+1}}{2\Delta y}$$

Do it this algorithm until steady condition is reached:

$$\max(|U^{n+1} - U^n|, |V^{n+1} - V^n|) < \varepsilon$$

ε – small number, 10^{-6}

Flow chart of the Projection method

