

# Mukul Shingwani

B20AI023

Lab10

```
pip install GEKKO
```

```
Looking in indexes: https://pypi.org/simple, https://us-python.pkg.dev/colab-wheels/public/simple
Requirement already satisfied: GEKKO in /usr/local/lib/python3.7/dist-packages (1.0.5)
Requirement already satisfied: numpy>=1.8 in /usr/local/lib/python3.7/dist-packages (from GEKKO)
```

```
from gekko import GEKKO
from numpy import *
```

## Question 1

```
m = GEKKO(remote=False)
c = array([[9],[5],[6],[4]])
A = array([[6,3,5,2],[1,0,0,1],[-1,0,1,0],[0,-1,0,1]])
b = array([[10],[1],[0],[0]])
z = m.Array(m.Var,4,integer=True,lb=0,ub=1)
m.qobj(c,x=z,otype='max')
m.axb(A,b,x=z,etype('<='))
m.options.SOLVER = 1
m.solve()
print('Objective: ', m.options.OBJFCNVAL)
print(z)
```



```
A
[[ 6.  3.  5.  2.]
 [ 1.  0.  0.  1.]
 [-1.  0.  1.  0.]
 [ 0. -1.  0.  1.]]
b
[[10.  1.  0.  0.]]
```

```
-----
APMonitor, Version 1.0.1
APMonitor Optimization Suite
-----
```

```
----- APM Model Size -----
```

Each time step contains

```

Objects      :      2
Constants    :      0
Variables    :      4
Intermediates:      0
Connections  :      8
Equations    :      0
Residuals    :      0

```

```

Number of state variables:      4
Number of total equations: -    4
Number of slack variables: -    0

```

```

-----
Degrees of freedom      :      0

```

-----  
Steady State Optimization with APOPT Solver  
-----

```

Iter:   1 I:  0 Tm:   0.00 NLPi:   1 Dpth:   0 Lvs:   3 Obj: -1.52E+01 Gap:      NaN
--Integer Solution: -1.40E+01 Lowest Leaf: -1.52E+01 Gap:  7.90E-02
Iter:   2 I:  0 Tm:   0.00 NLPi:   1 Dpth:   1 Lvs:   2 Obj: -1.40E+01 Gap:  7.90E-02
Iter:   3 I: -1 Tm:   0.00 NLPi:   3 Dpth:   1 Lvs:   1 Obj: -1.52E+01 Gap:  7.90E-02
--Integer Solution: -1.40E+01 Lowest Leaf: -1.40E+01 Gap:  0.00E+00
Iter:   4 I:  0 Tm:   0.00 NLPi:   1 Dpth:   1 Lvs:   1 Obj: -1.40E+01 Gap:  0.00E+00
Successful solution

```

```

-----
Solver      :  APOPT (v1.0)
Solution time :  1.200000000062573E-002 sec
Objective    :  -14.000000000000000
Successful solution

```

```

Objective:  -14.0
[[1.0] [1.0] [0.0] [0.0]]

```

## ▼ Question 2

```

m = GEKKO(remote=False)
c = array([[7.0],[3.0]])
A = array([[5,7],[4,1],[3,-2],[-1,0],[0,-1]])
b = array([[27],[14],[9],[0],[0]])
z1=m.Var(1,integer=True)
z2=m.Var(1,integer=False)
z=[z1,z2]
print(z1,z2,z)
m.qobj(c,x=z,otype='max')
m.axb(A,b,x=z,etype='<=')

m.options.SOLVER = 1

```

```
m.solve()
print('Objective: ', m.options.OBJFCNVAL)
print(z)
```

```
int_v1 v2 [1, 1]
```

```
A
```

```
[[ 5.  7.]
 [ 4.  1.]
 [ 3. -2.]
 [-1.  0.]
 [ 0. -1.]]
```

```
b
```

```
[[27. 14.  9.  0.  0.]]
```

```
-----
APMonitor, Version 1.0.1
APMonitor Optimization Suite
-----
```

```
----- APM Model Size -----
```

```
Each time step contains
```

```
Objects      :      2
Constants    :      0
Variables    :      2
Intermediates:      0
Connections  :      4
Equations    :      0
Residuals    :      0
```

```
Number of state variables:      2
Number of total equations: -      5
Number of slack variables: -      0
```

```
-----
Degrees of freedom      :      -3
```

```
* Warning: DOF <= 0
```

```
-----
Steady State Optimization with APOPT Solver
-----
```

```
Iter:   1 I:  0 Tm:   0.00 NLPi:   2 Dpth:   0 Lvs:   2 Obj: -2.66E+01 Gap:      NaN
Iter:   2 I: -1 Tm:   0.00 NLPi:   3 Dpth:   1 Lvs:   1 Obj: -2.66E+01 Gap:      NaN
--Integer Solution: -2.61E+01 Lowest Leaf: -2.61E+01 Gap:  0.00E+00
Iter:   3 I:  0 Tm:   0.00 NLPi:   3 Dpth:   1 Lvs:   1 Obj: -2.61E+01 Gap:  0.00E+00
Successful solution
```

```
-----
Solver      :  APOPT (v1.0)
Solution time :  1.239999999961583E-002 sec
Objective    :  -26.1428571428571
Successful solution
-----
```

```
Objective:  -26.142857143
[[3.0], [1.7142857143]]
```

## ▼ Question 3

```

m = GEKKO(remote=False)
c = array([[1.0],[1.0]])
A = array([[3,-2],[-8,10]])
b = array([-1],[10])
z1=m.Var(1,integer=False,lb=0.3)
z2=m.Var(1,integer=True,lb=0,ub=1)
z=[z1,z2]
print(z1,z2,z)
m.qobj(c,x=z,otype='min')
m.axb(A,b,x=z,etype='<=')

m.options.SOLVER = 1
m.solve()
print('Objective: ', m.options.OBJFCNVAL)
print(z)

```

```
v1 int_v2 [1, 1]
```

```
A
```

```
[[ 3. -2.]
 [-8. 10.]]
```

```
b
```

```
[-1. 10.]
```

```

-----
APMonitor, Version 1.0.1
APMonitor Optimization Suite
-----

```

```
----- APM Model Size -----
```

```
Each time step contains
```

```

Objects      :      2
Constants    :      0
Variables    :      2
Intermediates:      0
Connections  :      4
Equations    :      0
Residuals    :      0

```

```

Number of state variables:      2
Number of total equations: -    2
Number of slack variables: -    0

```

```

-----
Degrees of freedom      :      0

```

```

-----
Steady State Optimization with APOPT Solver
-----

```

```

Iter:      1 I:  0 Tm:      0.00 NLPi:      2 Dpth:      0 Lvs:      2 Obj:  1.25E+00 Gap:      NaN
--Integer Solution:  1.30E+00 Lowest Leaf:  1.25E+00 Gap:  3.92E-02
Iter:      2 I:  0 Tm:      0.00 NLPi:      1 Dpth:      1 Lvs:      1 Obj:  1.30E+00 Gap:  3.92E-02
Iter:      3 I: -1 Tm:      0.00 NLPi:      0 Dpth:      1 Lvs:      0 Obj:  1.25E+00 Gap:  3.92E-02
No additional trial points, returning the best integer solution
Successful solution

```

```

-----
Solver          :  APOPT (v1.0)
Solution time   :  1.159999999981665E-002 sec
Objective       :  1.3000000000000000
Successful solution
-----

```

```

Objective:  1.3
[[0.3], [1.0]]

```

## ▼ Question 4

```

m = GEKKO(remote=False)
c = array([[120],[85],[105],[140],[70]])
A = array([[55,45,60,50,30],[40,35,25,35,30],[25,20,0,30,0],[0,0,1,1,0]])
b = array([[150],[110],[60],[1]])
z = m.Array(m.Var,5,integer=True,lb=0,ub=1)
m.qobj(c,x=z,otype='max')
m.axb(A,b,x=z,etype='<=')
m.options.SOLVER = 1
m.solve()
print('Objective: ', m.options.OBJFCNVAL)
print(z)

```

```

A
[[55. 45. 60. 50. 30.]
 [40. 35. 25. 35. 30.]
 [25. 20.  0. 30.  0.]
 [ 0.  0.  1.  1.  0.]]
b
[[150. 110.  60.   1.]]

```

```

-----
APMonitor, Version 1.0.1
APMonitor Optimization Suite
-----

```

```

----- APM Model Size -----
Each time step contains
  Objects      :      2
  Constants    :      0
  Variables    :      5
  Intermediates:      0

```

```

Connections :      10
Equations   :        0
Residuals   :        0

```

```

Number of state variables:      5
Number of total equations: -    4
Number of slack variables: -    0

```

```

-----
Degrees of freedom      :      1

```

```

-----
Steady State Optimization with APOPT Solver
-----

```

```

Iter:   1 I:  0 Tm:   0.00 NLPi:   2 Dpth:   0 Lvs:   3 Obj: -3.42E+02 Gap:      NaN
--Integer Solution: -3.30E+02 Lowest Leaf: -3.42E+02 Gap:   3.72E-02
Iter:   2 I:  0 Tm:   0.00 NLPi:   1 Dpth:   1 Lvs:   2 Obj: -3.30E+02 Gap:   3.72E-02
Iter:   3 I:  0 Tm:   0.00 NLPi:   2 Dpth:   1 Lvs:   4 Obj: -3.34E+02 Gap:   3.72E-02
--Integer Solution: -3.30E+02 Lowest Leaf: -3.34E+02 Gap:   1.15E-02
Iter:   4 I:  0 Tm:   0.00 NLPi:   2 Dpth:   1 Lvs:   3 Obj: -3.30E+02 Gap:   1.15E-02
Iter:   5 I:  0 Tm:   0.00 NLPi:   2 Dpth:   2 Lvs:   2 Obj: -2.81E+02 Gap:   1.15E-02
Iter:   6 I:  0 Tm:   0.00 NLPi:   2 Dpth:   2 Lvs:   1 Obj: -3.25E+02 Gap:   1.15E-02
Iter:   7 I:  0 Tm:   0.00 NLPi:   3 Dpth:   2 Lvs:   0 Obj: -3.20E+02 Gap:   1.15E-02

```

```

No additional trial points, returning the best integer solution
Successful solution

```

```

-----
Solver           : APOPT (v1.0)
Solution time    : 1.2099999999991851E-002 sec
Objective        : -330.00000000000000
Successful solution
-----

```

```

Objective: -330.0
[[1.0] [0.0] [0.0] [1.0] [1.0]]

```

```

-----END-----

```

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