

## 第四课课程笔记

### 概念

#### Dojo的核心组成部分

1. ECS (entity component system)
2. Torii
3. Katana
4. Sozo CLI

#### Autonomous World(自治世界)

1. 持久性和去中心化
2. 开放参与
3. 去中心化的数据可用性层
4. 无需许可的扩展

### 搭建环境与基本命令

1. 安装Dojoup

```
curl -L https://install.dojoengine.org | bash
```

2. 安装Torii, Katana, Sozo

```
dojoup
```

3. 新建项目

```
sozo init
```

4. 编译

```
sozo build
```

5. 运行 Katana/

```
katana --disable-fee
```

6. 部署到 Katana

```
sozo migrate --name test
```

7. 打开torii索引 // 复制 sozo migrate 输出的 world address

```
torii --world <WORLD_ADDRESS>
```

8. 与action交互 // 复制 sozo migrate 输出的 action address

```
sozo execute <SYSTEM_ACTION_ADDRESS> spawn
sozo execute <SYSTEM_ACTION_ADDRESS> move -c 1
```

9. 查询访问最新状态 `http://0.0.0.0:8080/graphql`

```
query {
  movesModels {
    edges {
      node {
        player
        remaining
        last_direction
      }
    }
  }
}
```

```

    }
  },
  positionModels {
    edges {
      node {
        vec {
          x,
          y
        }
      }
    }
  }
}
}
}

```

## 项目解析

```

.
├── LICENSE
├── README.md
├── Scarb.lock
├── Scarb.toml
├── assets
│   ├── cover.png
│   └── icon.png
├── scripts
│   └── default_auth.sh
├── src
│   ├── lib.cairo
│   ├── models
│   │   ├── moves.cairo
│   │   └── position.cairo
│   ├── systems
│   │   └── actions.cairo
│   └── tests
│       └── test_world.cairo
└── target
    ├── CACHEDIR.TAG
    └── dev
        ├── dojo::base::base.json
        ├── dojo::executor::executor.json
        ├── dojo::world::world.json
        ├── dojo_starter::models::moves::moves.json
        ├── dojo_starter::models::position::position.json
        ├── dojo_starter::systems::actions::actions.json
        └── manifest.json

```

**models** (代表components, 组件编写)

`Into` `#[key]` `Introspect`

**systems** (游戏逻辑实现)

`get!` `set!` `emit!`

**tests** (components和system的测试)

```
#[cfg(test)]
```

```

mod tests {
  use core::debug::PrintTrait;
  use core::option::OptionTrait;
  use core::traits::TryInto;
  use dojo_starter::models::position::Vec2Trait;
  use core::traits::Into;
  use starknet::class_hash::Felt252TryIntoClassHash;

  // import world dispatcher
  use dojo::world::{IWorldDispatcher, IWorldDispatcherTrait}; //system

  // import test utils
  use dojo::test_utils::{spawn_test_world, deploy_contract}; // system

  // import test utils
  use dojo_starter::{
    systems::{actions::{actions, IActionsDispatcher,
IActionsDispatcherTrait}},
    models::{position::{Position, Vec2, position}, moves::{Moves, Direction,
moves}}
  };

  /////////////// models test
  #[test]
  #[available_gas(3000000000000)]
  fn test_direction_into() {
    let dir = Direction::Left;
    assert(dir.into() == 1, 'NOT 1');
  }

  #[test]
  #[available_gas(2000000)]
  fn test_vec_is_zero() {
    let vec2 = Vec2 { x: 1, y: 1 };
    assert(vec2.is_zero(), 'VEC NOT 0');
  }

  #[test]
  #[available_gas(2000000)]
  fn test_vec_is_equal() {
    let vec2_1 = Vec2 { x: 100, y: 100 };
    let vec2_2 = Vec2 { x: 100, y: 100 };
    assert(vec2_1.is_equal(vec2_2), '1 should equal 2');
  }

  /////////////// systems test
  #[test]
  #[available_gas(2000000000000)]
  fn test_spawn() {
    let caller = starknet::contract_address_const::<0x0>();
    let mut models = array![position::TEST_CLASS_HASH,
moves::TEST_CLASS_HASH];
    let world = spawn_test_world(models);

    let contract_address = world

```

```

        .deploy_contract('salt',
actions::TEST_CLASS_HASH.try_into().unwrap());

    let actions_system = IActionsDispatcher { contract_address };

    actions_system.spawn();

    let (moves, positions) = get!(world, caller, (Moves, Position));

    assert(moves.remaining == 100, 'not 100');
    assert(moves.last_direction.into() == 0, 'not 0');

    assert(positions.vec.x == 10, 'not 10');
    assert(positions.vec.y == 10, 'not 10');
}

#[test]
#[available_gas(300000000)]
fn test_move() {
    // caller
    let caller = starknet::contract_address_const::<0x0>();

    // models
    let mut models = array![position::TEST_CLASS_HASH,
moves::TEST_CLASS_HASH];

    // deploy world with models
    let world = spawn_test_world(models);

    // deploy systems contract
    let contract_address = world
        .deploy_contract('salt',
actions::TEST_CLASS_HASH.try_into().unwrap());
    let actions_system = IActionsDispatcher { contract_address };

    // call spawn()
    actions_system.spawn();

    // call move with direction right
    actions_system.move(Direction::Right);

    // Check world state
    let moves = get!(world, caller, Moves);

    // casting right direction
    let right_dir_felt: felt252 = Direction::Right.into();

    // check moves
    assert(moves.remaining == 99, 'moves is wrong');

    // check last direction
    assert(moves.last_direction.into() == right_dir_felt, 'last direction is
wrong');

```

```
// get new_position
let new_position = get!(world, caller, Position);

// check new position x
assert(new_position.vec.x == 11, 'position x is wrong');

// check new position y
assert(new_position.vec.y == 10, 'position y is wrong');
}
}
```

## 参考资料

<https://hackmd.io/@wongssh/dojo>

<https://book.dojoengine.org/>

[https://www.veradiverdict.com/p/dojo?r=cfxn&utm\\_campaign=post&utm\\_medium=email](https://www.veradiverdict.com/p/dojo?r=cfxn&utm_campaign=post&utm_medium=email)

<https://github.com/keep-starknet-strange/tsubasa>