

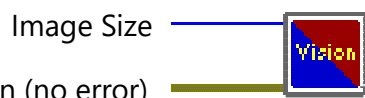


Vision Processing.vi

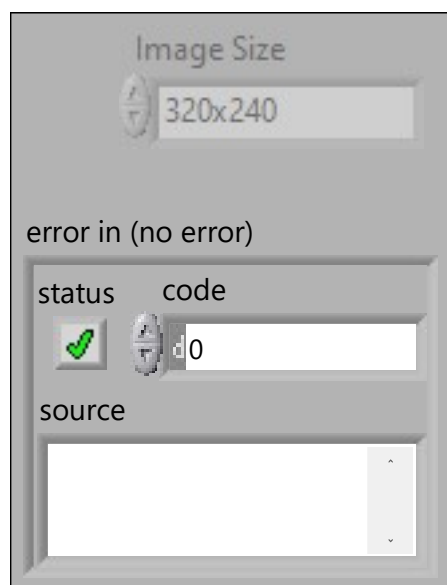
C:\Users\doggl\Documents\GitHub\RAN2023\2024RobotCode\2024StateMachineDevelopment\Vision Processing.vi

Last modified on 4/17/2024 at 6:21 PM

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Vision Processing.vi

This VI runs in parallel to other tasks. It gets images from the camera, processes them for color or shape and use that information to affect robot behavior.

**error in (no error)**

error in can accept error information wired from VIs previously called. Use this information to decide if any functionality should be bypassed in the event of errors from other VIs.

Right-click the **error in** control on the front panel and select **Explain Error** or **Explain Warning** from the shortcut menu for more information about the error.

**status**

status is TRUE (X) if an error occurred or FALSE (checkmark) to indicate a warning or that no error occurred.

Right-click the **error in** control on the front panel and select **Explain Error** or **Explain Warning** from the shortcut menu for more information about the error.

**code**

code is the error or warning code.

Right-click the **error in** control on the front panel and select **Explain Error** or **Explain Warning** from the shortcut menu for more information about the error.

**source**

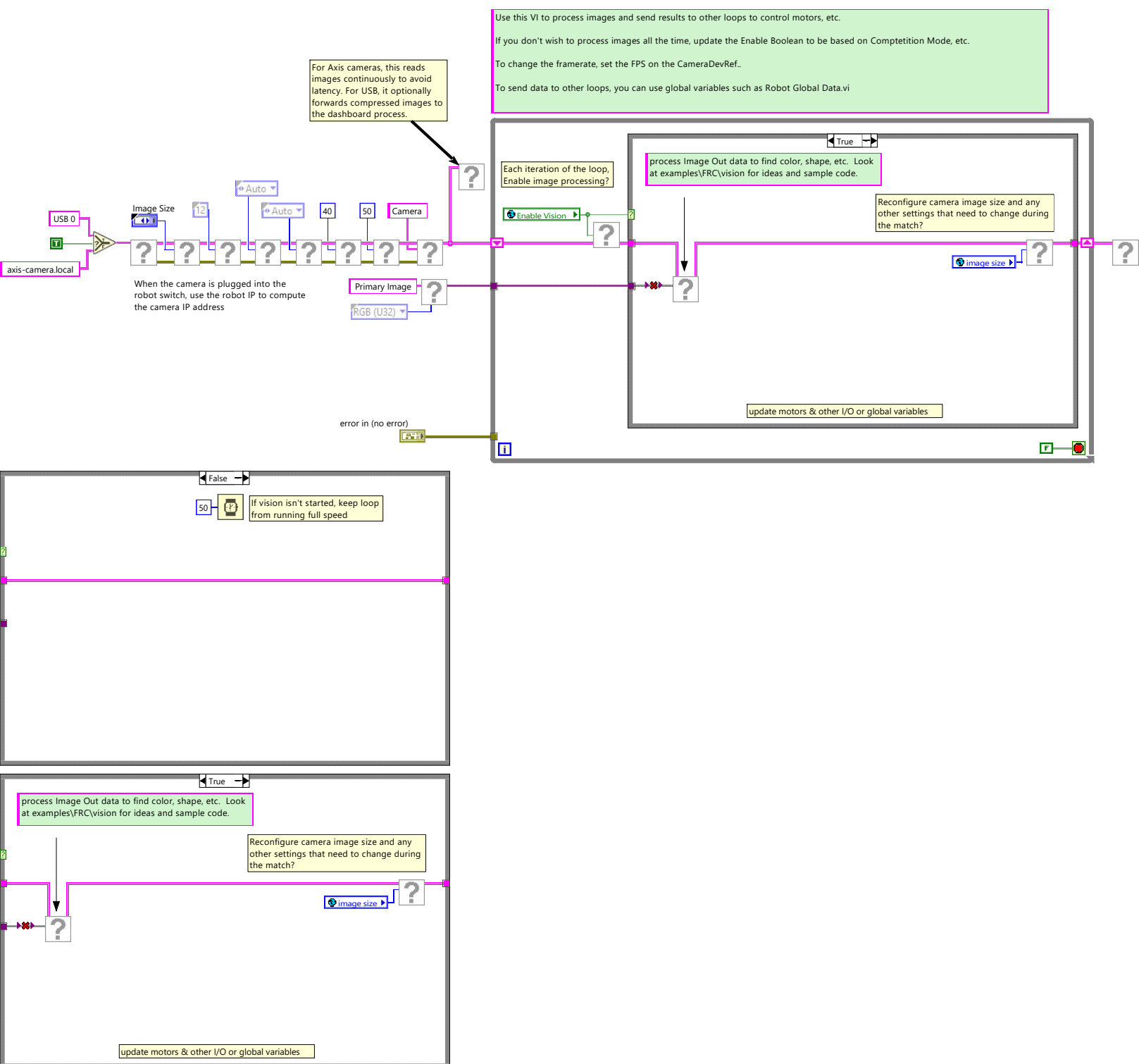
source describes the origin of the error or warning.

Right-click the **error in** control on the front panel and select **Explain Error** or **Explain Warning** from the shortcut menu for more information about the error.

**Image Size**

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Vision Processing.vi

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