Finish.vi
C:\Users\doggl\Documents\GitHub\RAN2023\2024RobotCode\2024StateMachineDevelopment\
Finish.vi
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Finish.vi

This VI is called just before exiting. It is expected to close I/O refnum, save collected data, etc.

The robot controller program is about to finish.

Save collected data to files, and carry out any other tasks you'd like before exiting. You can close refnums opened earlier in your program, but they will be cleaned up automatically anyway.

Joystick 0

Left and Right Motors

Close Refs, save data, etc.

STOP

Stop all parallel loops, exit program

FIRST
Main

Finish