

Unit Two

ONE AND TWO DIMENSIONAL MOTION

- **Displacement** of a particle is defined as its change in position in some time interval.

- As it moves from an initial position X_i to a final position X_f , the displacement of the particle is given by

$$\Delta x = x_f - x_i$$

- **Distance** is the length of a path followed by a particle.
- The **average velocity** \bar{v}_x of a particle is defined as the particle's displacement Δx divided by the time interval Δt during which that displacement occurs:

$$\bar{v}_x = \frac{\Delta x}{\Delta t}$$

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- The **average speed** of a particle, a scalar quantity, is defined as the total distance travelled divided by the total time interval required to travel that distance:

$$\text{Average speed} = \frac{\text{total distance}}{\text{total time}}$$

- The **instantaneous velocity** v_x equals the limiting value of the ratio $\Delta x/\Delta t$ as Δt approaches zero:

$$v_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$$

- The **instantaneous speed** of a particle is defined as the magnitude of its instantaneous velocity.

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- The **average acceleration** \bar{a}_x of the particle is defined as the change in velocity Δv_x divided by the time interval Δt during which that change occurs:

$$\bar{a}_x = \frac{\Delta v_x}{\Delta t} = \frac{v_{xf} - v_{xi}}{t_f - t_i}$$

- The **instantaneous acceleration** equals the limiting value of the average acceleration as Δt approaches zero.

$$a_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta v_x}{\Delta t} = \frac{dv_x}{dt}$$

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One-Dimensional Motion with Constant Acceleration

$$a_x = \frac{v_{xf} - v_{xi}}{t - 0} \quad \text{Where } t_i = 0 \text{ and } t_f = t$$

$$v_{xf} = v_{xi} + a_x t \quad \dots\dots\dots 1$$

- Because velocity at constant acceleration varies linearly in time according to Equation 1, we can express the average velocity in any time interval as the arithmetic mean of the initial velocity v_{xi} and the final velocity v_{xf} :

$$\bar{v}_x = \frac{v_{xi} + v_{xf}}{2} \quad \dots\dots\dots 2$$

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- From the definition of average velocity we can also derive the following equation

$$x_f = x_i + \frac{1}{2}(v_{xi} + v_{xf})t \quad \dots\dots\dots 3$$

- We can obtain another useful expression for the position of a particle moving with constant acceleration by substituting Equation 1 into Equation 3:

$$x_f = x_i + \frac{1}{2}[v_{xi} + (v_{xi} + a_x t)]t$$

$$x_f = x_i + v_{xi}t + \frac{1}{2}a_x t^2 \quad \dots\dots\dots 4$$

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- Finally, we can obtain an expression for the final velocity that does not contain time as a variable by substituting the value of t from Equation 1 into Equation 3:

$$x_f = x_i + \frac{1}{2}(v_{xi} + v_{xf})\left(\frac{v_{xf} - v_{xi}}{a_x}\right) = \frac{v_{xf}^2 - v_{xi}^2}{2a_x}$$

$$v_{xf}^2 = v_{xi}^2 + 2a_x(x_f - x_i) \quad \dots\dots\dots 5$$

- Equations 1 through 5 are kinematic equations that may be used to solve any problem involving one-dimensional motion at constant acceleration.

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- Kinematic Equations can be also Derived from Calculus
- The defining equation for acceleration,

$$a_x = \frac{dv_x}{dt}$$

$$dv_x = a_x dt \quad \text{Integrate both sides}$$

$$v_{xf} - v_{xi} = \int_0^t a_x dt \quad \text{For constant acceleration}$$

$$v_{xf} - v_{xi} = a_x \int_0^t dt = a_x(t - 0) = a_x t \quad \dots\dots\dots 1$$

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- Defining equation for velocity,

$$v_x = \frac{dx}{dt}$$

$$dx = v_x dt$$

$$x_f - x_i = \int_0^t v_x dt$$

$$v_x = v_{xf} = v_{xi} + a_x t$$

$$x_f - x_i = \int_0^t (v_{xi} + a_x t) dt = \int_0^t v_{xi} dt + a_x \int_0^t t dt = v_{xi}(t - 0) + a_x \left(\frac{t^2}{2} - 0 \right)$$

$$= v_{xi} t + \frac{1}{2} a_x t^2 \quad \dots\dots\dots 2$$

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Freely falling objects

- If a body is thrown up or down in the air the effect of the air resistance is neglected, this idealized motion is called free fall.
- The acceleration of freely falling body is acceleration due to gravity. Its denoted by g ($g = 9.8 \text{ m/s}^2$)
- Let us see the kinematic equation during down and up ward falling

Down ward thrown

$$V_{yf} = V_{yi} + gt$$

$$y_f - y_i = V_{yi}t + \frac{1}{2}gt^2$$

$$V_{yf}^2 = V_{yi}^2 + 2g(y_f - y_i)$$

Up ward thrown

$$V_{yf} = V_{yi} - gt$$

$$y_f - y_i = V_{yi}t - \frac{1}{2}gt^2$$

$$V_{yf}^2 = V_{yi}^2 - 2g(y_f - y_i)$$

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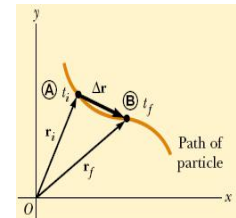
Motion in two dimensions

- **The position vector** of a particle is a vector drawn from the origin of a reference frame to the xy position of the particle. For a particle at the Point (xy) , its position vector \mathbf{r} is

$$\mathbf{r} = x\mathbf{i} + y\mathbf{j}$$

- At time t_i the particle is at point A, described by position vector \mathbf{r}_i . At some later time t_f it is at point B, described by position vector \mathbf{r}_f . The particle's change in position is the **displacement vector $\Delta \mathbf{r}$** :

$$\Delta \mathbf{r} \equiv \mathbf{r}_f - \mathbf{r}_i$$



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- Average velocity of the particle during the time interval Δt as the displacement of the particle divided by the time interval. i.e

$$\bar{\mathbf{v}} = \frac{\Delta \mathbf{r}}{\Delta t}$$

- The instantaneous velocity \mathbf{v} is defined as the limit of the average velocity $\Delta \mathbf{r}/\Delta t$ as Δt approaches zero:

$$\mathbf{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \mathbf{r}}{\Delta t} = \frac{d\mathbf{r}}{dt}$$

- The average acceleration vector is the ratio of the change in the Instantaneous-velocity vector $\Delta \mathbf{v}$ to the time interval:

$$\bar{\mathbf{a}} = \frac{\mathbf{v}_f - \mathbf{v}_i}{t_f - t_i} = \frac{\Delta \mathbf{v}}{\Delta t}$$

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- The instantaneous-acceleration vector is the limit of this ratio as Δt approaches zero; in other words, it is the derivative of the velocity vector with respect to time:

$$\mathbf{a} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \mathbf{v}}{\Delta t} = \frac{d\mathbf{v}}{dt}$$

Two-Dimensional Motion with Constant Acceleration

- The position vector for a particle moving in the xy plane can be written as:

$$\mathbf{r} = x\hat{\mathbf{i}} + y\hat{\mathbf{j}} \quad \dots\dots\dots 1 \quad \text{where } x, y, \text{ and } \mathbf{r} \text{ changes with time as the particle moves, while the unit vectors } \hat{\mathbf{i}} \text{ and } \hat{\mathbf{j}} \text{ remain constant.}$$

- the velocity of the particle can be given by:

$$\mathbf{v} = \frac{d\mathbf{r}}{dt} = \frac{dx}{dt}\hat{\mathbf{i}} + \frac{dy}{dt}\hat{\mathbf{j}} = v_x\hat{\mathbf{i}} + v_y\hat{\mathbf{j}} \quad \dots\dots\dots 2$$

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- The final velocity at any time t is:

$$\begin{aligned}\mathbf{v}_f &= (v_{xi} + a_x t)\hat{\mathbf{i}} + (v_{yi} + a_y t)\hat{\mathbf{j}} \\ &= (v_{xi}\hat{\mathbf{i}} + v_{yi}\hat{\mathbf{j}}) + (a_x\hat{\mathbf{i}} + a_y\hat{\mathbf{j}})t \\ \mathbf{v}_f &= \mathbf{v}_i + \mathbf{a}t\end{aligned}$$

- The x and y coordinates of a particle moving with constant acceleration are:

$$x_f = x_i + v_{xi}t + \frac{1}{2}a_x t^2 \quad y_f = y_i + v_{yi}t + \frac{1}{2}a_y t^2$$

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- Substituting these expressions into Equation 1 (and labeling the final position vector \mathbf{r}_f) gives

$$\begin{aligned}\mathbf{r}_f &= (x_i + v_{xi}t + \frac{1}{2}a_x t^2)\hat{\mathbf{i}} + (y_i + v_{yi}t + \frac{1}{2}a_y t^2)\hat{\mathbf{j}} \\ &= (x_i\hat{\mathbf{i}} + y_i\hat{\mathbf{j}}) + (v_{xi}\hat{\mathbf{i}} + v_{yi}\hat{\mathbf{j}})t + \frac{1}{2}(a_x\hat{\mathbf{i}} + a_y\hat{\mathbf{j}})t^2 \\ \mathbf{r}_f &= \mathbf{r}_i + \mathbf{v}_i t + \frac{1}{2}\mathbf{a}t^2 \\ \mathbf{r}_f &= \mathbf{r}_i + \mathbf{v}_i t + \frac{1}{2}\mathbf{a}t^2 \quad \begin{cases} x_f = x_i + v_{xi}t + \frac{1}{2}a_x t^2 \\ y_f = y_i + v_{yi}t + \frac{1}{2}a_y t^2 \end{cases}\end{aligned}$$

Example:

A particle starts from the origin at $t = 0$ with an initial velocity having an x component of 20 m/s and a y component of -15 m/s. The particle moves in the xy plane with an x component of acceleration only, given by $a_x = 4 \text{ m/s}^2$.

- (a) Determine the components of the velocity vector at any time and the total velocity vector at any time.

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Solution

- The components of the initial velocity tell us that the particle starts by moving toward the right and downward. The x component of velocity starts at 20 m/s and increases by 4.0 m/s every second. The y component of velocity never changes from its initial $v_{xi} = 20 \text{ m/s}$, $v_{yi} = -15 \text{ m/s}$, $a_x = 4 \text{ m/s}^2$, and $a_y = 0$. From Equations 3a

$$(1) \quad v_{xf} = v_{xi} + a_x t = (20 + 4.0t) \text{ m/s}$$

$$(2) \quad v_{yf} = v_{yi} + a_y t = -15 \text{ m/s} + 0 = -15 \text{ m/s}$$

- Therefore, $\mathbf{v}_f = v_{xi}\hat{\mathbf{i}} + v_{yi}\hat{\mathbf{j}} = [(20 + 4.0t)\hat{\mathbf{i}} - 15\hat{\mathbf{j}}] \text{ m/s}$

(B) Calculate the velocity and speed of the particle at $t = 5 \text{ s}$.

Solution

With $t = 5 \text{ s}$, the result from part (A) gives

$$\mathbf{v}_f = [(20 + 4.0(5.0))\hat{\mathbf{i}} - 15\hat{\mathbf{j}}] \text{ m/s} = (40\hat{\mathbf{i}} - 15\hat{\mathbf{j}}) \text{ m/s}$$

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- From this result, we have At $t = 5 \text{ s}$, $v_{xf} = 40 \text{ m/s}$ and $v_{yf} = -15 \text{ m/s}$.
- To determine the angle θ

$$\tan \theta = v_{yf} / v_{xf}$$

$$(3) \quad \theta = \tan^{-1}\left(\frac{v_{yf}}{v_{xf}}\right) = \tan^{-1}\left(\frac{-15 \text{ m/s}}{40 \text{ m/s}}\right) \quad \text{where the negative sign indicates an angle of } 21^\circ \text{ below the positive } x \text{ axis.}$$

$$= -21^\circ$$

- The speed is the magnitude of \mathbf{v}_f

$$\begin{aligned}v_f = |\mathbf{v}_f| &= \sqrt{v_{xf}^2 + v_{yf}^2} = \sqrt{(40)^2 + (-15)^2} \text{ m/s} \\ &= 43 \text{ m/s}\end{aligned}$$

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- (C) Determine the x and y coordinates of the particle at any time t and the position vector at this time.

Solution

- Because $x_i = y_i = 0$ at $t = 0$, From Equation 4a

$$x_f = v_{xi}t + \frac{1}{2}a_x t^2 = (20t + 2.0t^2) \text{ m}$$

$$y_f = v_{yi}t = (-15t) \text{ m}$$

- Therefore, the position vector at any time t is

$$(4) \quad \mathbf{r}_f = x_f\hat{\mathbf{i}} + y_f\hat{\mathbf{j}} = [(20t + 2.0t^2)\hat{\mathbf{i}} - 15t\hat{\mathbf{j}}] \text{ m}$$

- At $t = 5 \text{ s}$, $x = 150 \text{ m}$, $y = -75 \text{ m}$, and The magnitude of the displacement of the particle from the origin at $t = 5 \text{ s}$ is the magnitude of \mathbf{r}_f at this time:

$$r_f = |\mathbf{r}_f| = \sqrt{(150)^2 + (-75)^2} \text{ m} = 170 \text{ m}$$

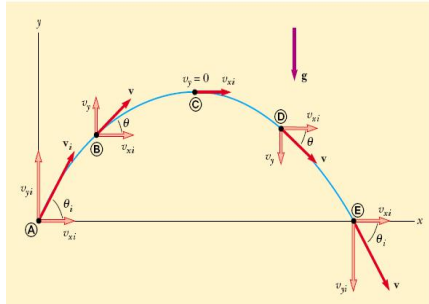
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Projectile Motion

- Projectile** is a two dimensional motion which is a body thrown with some initial velocity and then allowed to move under the influence of the gravity alone.
- Trajectory** is the path followed by the projectile.
- Angle of departure** is the angle which the direction of the projectile makes with the horizontal.
- Time of flight** is the time taken by the body to return to the same horizontal plane from it was projected from the instant it is released
- Maximum height** is the greatest vertical distance by the projectile above the horizontal plane.
- Horizontal range** is the total horizontal distance travelled by the body during the time of flight.

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- Assume that a body of mass m is given an initial velocity V_i near the earth's surface.



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- From the definitions of the cosine and sine functions we have

$$\cos \theta_i = v_{xi}/v_i \quad \sin \theta_i = v_{yi}/v_i \dots\dots\dots 1$$

- Therefore, the initial x and y components of velocity are

$$v_{xi} = v_i \cos \theta_i \quad v_{yi} = v_i \sin \theta_i \dots\dots\dots 2$$

- We know that

$$x_f = x_i + v_{xi}t + \frac{1}{2}a_x t^2$$

$$y_f = y_i + v_{yi}t + \frac{1}{2}a_y t^2 \dots\dots\dots 3$$

- For the horizontal motion (x-direction),** Substituting the x component into Eqn (3) with $x_i = 0$ and $a_x = 0$, we find that

$$x_f = v_{xi}t = (v_i \cos \theta_i)t \dots\dots\dots 4 \text{ horizontal position component}$$

- For the vertical motion, repeating with the y component and using $y_i = 0$ and $a_y = -g$, we obtain

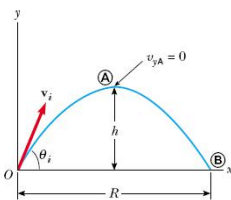
$$y_f = v_{yi}t + \frac{1}{2}a_y t^2 = (v_i \sin \theta_i)t - \frac{1}{2}gt^2 \dots\dots\dots 5 \text{ vertical position}$$

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- From eqn (4) substituting t into eqn (5), we get

$$y = (\tan \theta_i)x - \left(\frac{g}{2v_i^2 \cos^2 \theta_i} \right)x^2 \dots\dots\dots 6 \text{ equation of trajectory}$$

Horizontal Range and Maximum Height of a Projectile



Here, two points are especially interesting to analyze: the peak point A, which has Cartesian coordinates $(R/2, h)$, and the point B, which has coordinates $(R, 0)$. The distance R is called the horizontal range of the projectile, and the distance h is its maximum height. Now, let's determine h by taking $V_{yA} = 0$

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- At point A, $V_{yA} = 0$ and $t = t_A$

$$v_{yf} = v_{yi} + a_y t$$

$$0 = v_i \sin \theta_i - gt_A$$

$$t_A = \frac{v_i \sin \theta_i}{g} \dots\dots\dots 1$$

Time to reach the maximum height

- Replacing $y = y_A$ with h ,

$$h = (v_i \sin \theta_i) \frac{v_i \sin \theta_i}{g} - \frac{1}{2}g \left(\frac{v_i \sin \theta_i}{g} \right)^2$$

$$h = \frac{v_i^2 \sin^2 \theta_i}{2g} \dots\dots\dots 2 \text{ maximum height of projectile}$$

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- At point B, the range R is the horizontal position of the projectile at a time that is twice the time at which it reaches its peak, that is, at time $t_B = 2t_A$

$$v_{xi} = v_{xB} = v_i \cos \theta_i \text{ and setting } x_B = R \text{ at } t = 2t_A$$

$$t = t_B = 2 \frac{v_i \sin \theta_i}{g} \dots\dots\dots 2 \text{ Time of flight}$$

$$R = v_{xi}t_B = (v_i \cos \theta_i)2t_A$$

$$= (v_i \cos \theta_i) \frac{2v_i \sin \theta_i}{g} = \frac{2v_i^2 \sin \theta_i \cos \theta_i}{g}$$

$$\text{But } \sin 2\theta = 2 \sin \theta \cos \theta$$

$$R = \frac{v_i^2 \sin 2\theta_i}{g} \dots\dots\dots 3 \text{ Range projectile}$$

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Example:- A projectile is projected with initial velocity 98 m/s at an angle of 30.0° with the horizontal. Calculate the time of flight, Range and the maximum height of the projected object

Solution

$$\text{i). } t = t_B = 2 \frac{v_i \sin \theta_i}{g}$$

$$= 9.8 \text{ sec}$$

$$\text{ii). } R = \frac{v_i^2 \sin 2\theta_i}{g}$$

$$= 825.9 \text{ m}$$

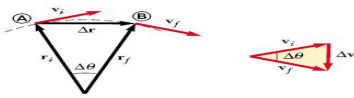
$$\text{iii). } h = \frac{v_i^2 \sin^2 \theta_i}{2g}$$

$$= 120.05 \text{ m}$$

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Uniform Circular Motion

- Uniform circular motion is defined as a particle moving in a circular path with constant linear velocity.
- The velocity vector is always tangent to the path of the object and perpendicular to the radius of the circular path.
- For uniform circular motion, the acceleration vector can only have a component perpendicular to the path, which is toward the centre of the circle.



- The particle is at A at time t_i , and its velocity at that time is v_i ; it is at B at some later time t_f and its velocity at that time is v_f . v_i and v_f differ only in direction; their magnitudes are the same, that is,

$$v_i = v_f = v \quad \mathbf{a} = \frac{\mathbf{v}_f - \mathbf{v}_i}{t_f - t_i} = \frac{\Delta \mathbf{v}}{\Delta t}$$

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- The vector $\Delta \mathbf{v}$ connects the tips of the vectors, representing the vector addition

$$\mathbf{v}_f = \mathbf{v}_i + \Delta \mathbf{v}.$$

- Because the velocity vector v is always perpendicular to the position vector r . Thus, the two triangles are *similar*. So, we can write a relationship between the lengths of the sides for the two triangles:

$$\frac{|\Delta \mathbf{v}|}{v} = \frac{|\Delta \mathbf{r}|}{r} \quad \text{where } v = v_i = v_f \text{ and } r = r_i = r_f.$$

- The magnitude of the average acceleration over the time interval for the particle to move from A to B:

$$|\bar{\mathbf{a}}| = \frac{|\Delta \mathbf{v}|}{\Delta t} = \frac{v}{r} \frac{|\Delta \mathbf{r}|}{\Delta t}$$

- As A and B approach each other, Δt approaches zero, and the ratio $|\Delta \mathbf{r}|/\Delta t$ approaches the speed v . In addition, the average acceleration becomes the instantaneous acceleration at point A.

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- Therefore, the magnitude of the acceleration is

$$a_c = \frac{v^2}{r} \quad \text{Centripetal acceleration}$$

- And period of circular motion is given by

$$T = \frac{2\pi r}{v} \quad \text{Period of circular motion}$$

Tangential and Radial Acceleration

- The total acceleration vector \mathbf{a} can be written as the vector sum of the component vectors:

$$\mathbf{a} = \mathbf{a}_r + \mathbf{a}_t \quad \text{Total acceleration}$$

- The tangential acceleration component causes the change in the speed of the particle. This component is parallel to the instantaneous velocity, and is given by

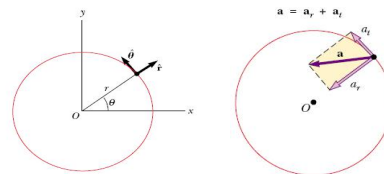
$$a_t = \frac{d|\mathbf{v}|}{dt} \quad \text{Tangential acceleration}$$

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- The radial acceleration component arises from the change in direction of the velocity vector and is given by

$$a_r = -a_c = -\frac{v^2}{r} \quad \text{Radial acceleration}$$

- Let's write the acceleration of a particle moving in a circular path in terms of unit vectors, by defining the unit vectors $\hat{\mathbf{r}}$ and $\hat{\boldsymbol{\theta}}$



- Both $\hat{\mathbf{r}}$ and $\hat{\boldsymbol{\theta}}$ move along with the particle and so vary in time.

$$\mathbf{a} = \mathbf{a}_t + \mathbf{a}_r = \frac{d|\mathbf{v}|}{dt} \hat{\boldsymbol{\theta}} - \frac{v^2}{r} \hat{\mathbf{r}}$$

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Exercise:-

An automobile whose speed is increasing at a rate of 0.6 m/s^2 travels along a circular road of radius 20 m. When the instantaneous speed of the automobile is 4 m/s, find

- the tangential acceleration component,
- the centripetal acceleration component, and
- the magnitude and direction of the total acceleration

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