*GT = (P, L) P m*

*L li,j ∈ L*

*pi pj w(pi) w(li,j) li,i w(li,i) ∞*

*G = (V, E, w)*

*V = {v1, v2, ………,vn}*

*E ⊆ V x V*

*ei,j = (i,j) ∈ E*

*vi  vj w(vi) w(ei,j) Si  px*

*tp(vi,px) = w(vi)/w(px)*

*tc(ei,j,lk,x) = w(ei,j)/w(lk,x)*

**pred***(vi)*

**succ***(vi)*

*ventry*

*vexit*

*λ*

*λli,j*

*λi*

*e-λd*