DESIGN AND ANALYSIS OF ALGORITHMS

Presented to Sir Waheed Abro

Abstract

The complete report for the project.

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Abstract

This document is the proper documentation of the project developed for the course of Design and Analysis of Algorithms submitted to our instructor Dr. Waheed Abro. The project includes an introduction of the project and the group members, the project design of programming, the experimental setup, results and discussions, conclusions and references used.

Introduction

This project includes a visual representation of multiple sorting algorithms. These are executed on test files with input. The visualization of the sorts is a key feature. We receive the execution time, and the space complexity. The group members are Mustafa Zahid 20K-1045 and Munir Abbasi 20K-0244.

Project Programming Design

The programming language chosen was python. This language was used since python is easy to use and its libraries can be used to make an interactive GUI and manage the backend as well. We were also able to implement the algorithm for fast parallel sort. This was coded in C++ language as multiple processors were incorporated using threads and the OpenMP library. All relevant research paper logic are matched with our code in images.

```
Parallel fast sorting
```

```
int max_threads=dimensions*cbrt(dimensions);
num_buckets=cbrt(dimensions);
 buckets = (struct bucket *) calloc(dimensions-cbrt(dimensions), sizeof(struct bucket));
Algorithm 4—parallel sort using n^{4/3} processors
1. Partition the n input numbers into n^{2/3} groups each having n^{1/3}
elements.
   int buck sum=0;
   for (j=cur id; j< num buckets*num threads; j=j+num threads){</pre>
       buck sum += buckets[j].element;
Within each group do
  For each element, j, determine count[j] = # of i such that c_i < c_j)
  + (# of i \le j such that c_i = c_j).
for (i=0; i< dimensions ;i++){
    j = A[i]/w;
    if (j > num_buckets -1)
           j = num_buckets-1;
    k = j + cur_id*num_buckets;
    b_index = buckets[k].curr_ind++;
    B[b_{index}] = A[i];
```

```
int j,k;
                     int local_index;
                     for(int i=0;i<=local index;i++)</pre>
                     binarySearch(A,j,k,i);
.nt binarySearch(int arr[], int l, int r, int x)
                 if (r >= 1) {
                                    int mid = 1 + (r - 1) / 2;
                                    if (arr[mid] == x)
                                                        return mid;
                                    if (arr[mid] > x)
                                                        return binarySearch(arr, 1, mid - 1, x);
                                    return binarySearch(arr, mid + 1, r, x);
               return -1;
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  (globals)
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                                     buckets = (struct bucket *) calloc(dimensions-cbrt(dimensions), sizeof(struct bucket));//define the bucket structure used
t1 = omp_get_wtime();
    int j,k;
int local_index;
#pragma omp parallel
#fragma omp parallel
                                            num_threads = omp_get_num_threads();
int real_bucket_index; // [0 : num_buckets * num_threads)
int run_id = omp_get_thread_num();
workload = dimensions/num_threads/as per paper divide total_buckets numbers per processor
int prevoius_index;
#pragma omp for private(i,local_index)
for (i=0; i4 dimensions;i++){
    local_index = A[i]/w;
    if (local_index > num_buckets-1)
    | local_index = num_buckets-1;
    real_bucket_index = local_index + cur_id*num_buckets;
    buckets[real_bucket_index].element+;//implement on the local_bucket registers
}
                                              }
int buck_sum=0;
for (j=cur_id; j< num_buckets*num_threads; j=j*num_threads){
    buck_sum += buckets[j].element;</pre>
                                              }
global_n_elem[cur_id]=buck_sum;
#pragma omp barrier
#pragma omp master
E:\MUNIRABBASI\university\semester 5\algo\ALGOCOde\parallelsort.cpp - Dev-C++ 5.11
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                                                 }
mpragma omp barrier
for (j-cur_id-num_buckets; j< num_buckets*num_threads; j=j-num_threads)(
int prevolus_index = j-num_buckets;//barrier for each bucket
buckets[j].start_ind = buckets[prevolus_index].start_ind + buckets[prevolus_index].element;
buckets[j].curr_ind = buckets[prevolus_index].curr_ind + buckets[prevolus_index].element;
| // binarySearch(A,j,k,i)
                                              ##pragma omp barrier
##pragma omp for private(i, b index)
for (i=0; i c dimensions ;i++){
    j = A[i]/w;
    if (j > num buckets -1) // final bucket sort
    k = j + cur_id*num_buckets;
    b_index = buckets[k].curr_ind++;
    ##pragma = A[i];
```

Then evaluate count [j] = the sum (over k) of count [j, k].

- 8. Do a bucket sort of all n elements.
- END of Algorithm 4.

```
#pragma omp for private(i)
      for(i=0; i<num_buckets; i++)</pre>
          qsort(B+global_starting_position[i], global_n_elem[i], sizeof(int), cmpfunc);
- }
     total = omp_get_wtime() - t1;
      tmp = A;
      A = B;
      B = tmp;
3
     if (dimensions <= 40) {
          printf("A \n");
3
          for(i=0;i<dimensions;i++) {</pre>
              printf("%d ",A[i]);
          printf("\n");
      printf("Sorting %d elements took %f seconds\n", dimensions,total);
      int sorted = 1;
      for(i=0;i<dimensions-1;i++) {</pre>
3
```

Experimental results

Parallel sort code execution

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■ E:\MUNIRABBASI\university\semester 5\algo\ALGOCOde\parallelsort.exe
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number of buckets is 4
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             Sorted final bucket is
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Sorting 99 elements took 0.000000 seconds
 Process exited after 1.499 seconds with return value 0
 Press any key to continue . . .
```

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  Sorting 399 elements took 0.000000 seconds
Process exited after 0.1446 seconds with return value 0 Press any key to continue . . .
```

```
total = omp_get_wtime() - t1;
tmp = A;
A = B;
B = tmp;
if (dimensions <= 400) {
    //printf("\t");
    printf("\tSorted final bucket is \n");
    for(i=0;i<dimensions;i++) {
        printf("%d\t ",A[i]);
    }
    printf("\n\n");
}
printf("Sorting %d elements took %f seconds\n", dimensions,total);</pre>
```

Note how sorting elements takes such small time that the system clock can only show 0.0000000 since the time taken is so much less of the parallel sort. Now normal bucket sort takes how much time lets see.

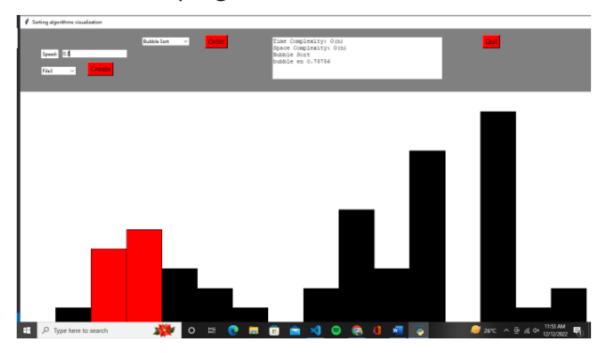
Normal bucket Sort for 399 elements.

We cannot even deduce mathematically how fast the parallel bucket sort is as compared to a normal bucket sort as the clock time of parallel one is 0.000000, for sake of execution let's assume it is 0.1446 as mentioned in program end. For normal bucket it is less, but extremely large when compared to parallel bucket one as time is 1.179 seconds and 0.812311 for bucket.

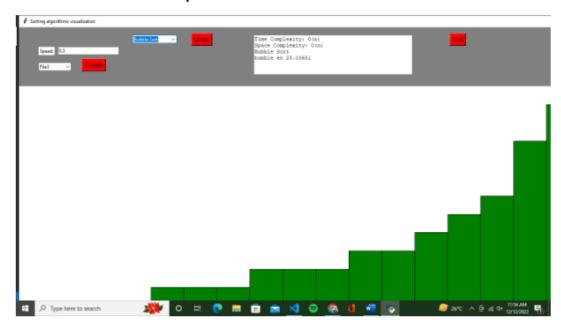
Experimental Setup

The setup for the programming was done by using Visual Studio. The code was written here. These are some screenshots for all the 10 implemented sorts.

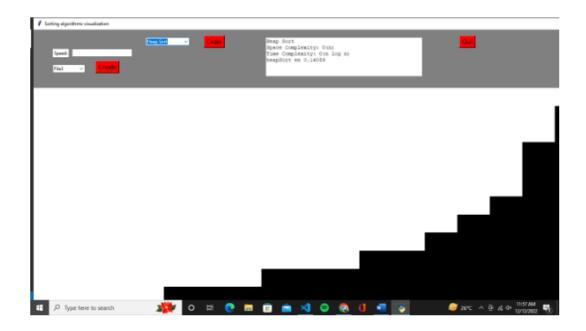
Bubble Sort in progress



Bubble Sort completed



Heap sort



Results and discussions

Let us compile some results for each sort.

Algorithm	Ti	ime Complexi	Space Complexity	Stable?	
	Best	Average	Worst		
Bubble Sort	Ω(n)	θ(n^2)	O(n^2)	O(1)	Yes
Insertion Sort	Ω(n)	θ(n^2)	O(n^2)	O(1)	Yes
Heap Sort	Ω(n log(n))	θ(n log(n))	O(n log(n))	O(1)	No

Algorithm	Ti	me Complexi	Space Complexity	Stable?	
	Best	Average	Worst		
Quick Sort	Ω(n log(n))	θ(n log(n))	O(n^2)	O(n)	No
Merge Sort	Ω(n log(n))	θ(n log(n))	O(n log(n))	O(n)	Yes
Bucket Sort	Ω(n + k)	θ(n + k)	O(n^2)	O(n)	Depends
Radix Sort	Ω(n.k)	θ(n.k)	O(n.k)	O(n + k)	Yes
Count Sort	Ω(n + k)	θ(n + k)	O(n + k)	O(k)	Yes

Space complexity restrictions

When we have a priority of using less space, then it is best to use bubble sort, insertion sort and heap sort. However in the least space for an unsorted array, it is best to use heap sort and on average and worst cases it will perform better than the other two. Heap is best if the stability of the sort is not a problem.

Time complexity restrictions

When we have a time restriction, it is best to use merge sort. It gives a fixed complexity of running time. It is stable as well. If stability is not an issue, we can use heap sort.

File 1=> Big Range, unique data

File 2=>Small range, repeated numbers

File 3=>Already sorted data

File 4=>Big range, repeated numbers

File 5=>Nearly sorted

Algorithm	Time Taken (seconds)								
	File 1	File 2	File 3	File 4	File 5				
Bubble Sort	0.32318	0.11126	0.00908	1.42703	0.01392				
Insertion Sort	0.32601	0.12561	0.01283	1.37864.	0.01659				
Heap Sort	0.09544	0.04476	0.07625	0.25297	0.03766				
Quick Sort	0.57128	0.23902	0.92755	2.17132	0.23413				
Merge Sort	0.19647	0.09125	0.13542	0.47491	0.08237				
Bucket Sort	0.13652	0.05219	0.07081	0.14463	0.04503				
Radix Sort	0.62434	0.31078	0.62312	0.6209	0.30793				
Count Sort	0.13651	0.13381	0.11689	0.28774	0.28388				

- 1. For the modified quicksort or 7.4.5, we make the following deductions for the value of K.
- T(N) = running time of quicksort + running time of insertion sort (for the remaining N/K arrays of size K(or less than K))
- N (log N log K and n/k for in bracket due to division) + N/K (K^2 as n square) = > N log(N/K) + NK.
- In theory, K has to be chosen such that: NK + N log (N/K) = N log N for same complexity==>
- K = log N (K can't be more than log N otherwise the total running time will be more than N log N which deems the change pointless).
- In practice, K should be the largest list length on which insertion sort is faster than quicksort which can be observed as well through experimental analysis.

Finding => Quicksort algorithm is efficient if the size of the input is very large. But, insertion sort is more efficient than quick sort in case of small arrays as the number of comparisons and swaps are less compared to quicksort. So we combine the two algorithms to sort efficiently using both approaches.

For the 8.2.4 or the modified counting sort/range. We make use of counting sort. We know that
in counting sort we maintain the sum of the occurrences of all the elements in the array.
 So array[b]-array[a-1] will return the answer in O(1) time.

- 3. The parallel bucket sort is almost 800% faster (with the assumed values which are still very big 0.8 normal vs 0.1 parallel) than the normal bucket sort. We can be sure that this factor depends upon the number of threads used which can be the buckets as per the paper.
- 4. Heap sort was best for sorting files that had big range and unique data along with those with a small range and repeated numbers.
- 5. On already sorted data bubbles sort was fastest, had a close call with insertion sort.
- 6. Bucket sort was best on big range with repeated numbers.
- 7. Bubble sort was fastest on nearly sorted data with an again close call with insertion sort.

Conclusion

We can conclude that different sorts are feasible in different scenarios as we see from the time complexities. Another important finding is that we can design modified algorithms as per our needs to get the accurate results while keeping in mind our constraints and like time and space.

References

- 1. www.youtube.com
- 2. Geeksforgeeks.com
- 3. Wikipedia.com