
Project Report for ECE 351

Lab 4: System Step Response Using Convolution

Isaias Munoz

September 20, 2022

UNIVERSITY OF IDAHO

Contents

1	Introduction	1
2	Methodology	1
2.1	Part 1	1
2.2	Part 2	2
3	Results	5
3.1	Part 1	5
3.2	Part 2	5
4	Questions	6

1 Introduction

The purpose of this lab is to compute a systems step response as the forcing function and become familiar with convolution.

2 Methodology

2.1 Part 1

The first task that was assigned was to use Lab 3 user defined functions for a step function and write the following functions and plot them in a single figure.

$$h_1(t) = (e^{-2t}) * [u(t - 2) - u(t - 3)]$$

$$h_2(t) = u(t - 2) - u(t - 6)$$

$$h_3(t) = \cos(w_0 * t) * u(t)$$

Figure 1 shows the code that was used to plot the functions. Where $w = 2 * \pi * f$. It was simple enough since the user defined functions for step were already created in Lab 2 and therefore I just typed my equations and made them all as subplots to achieve one graph located in the results section.

```
26 #####
27 #Part 1 graphin the h(t)
28 steps = 1e-2 # Define step size
29 t = np . arange (-10 , 10 + steps , steps )
30 # q = np . arange (-1 , 14 + steps , steps )
31
32 def stepfunc ( t ) : #creating step function
33     y = np.zeros ( t.shape ) #initializing y as all zeroes
34     for i in range (len ( t ) ) : #startingforloop
35         if t [ i ] < 0 :
36             y[i]=0
37         else:
38             y[i]=1
39     return y
40
41 def rampfunc ( t ) :
42     y = np.zeros ( t . shape )
43     for i in range (len ( t ) ) :
44         if t [ i ] < 0 :
45             y[i]=0
46         else:
47             y[i]=t[i]
48     return y
49 #####Better to make a function
50
51 #w=2pif
52 w=2*math.pi*.25
53
54 h1t=(np.exp(-t))*(stepfunc(t)-stepfunc(t-3))
55 h2t=stepfunc(t-2)-stepfunc(t-6)
56 h3t=np.cos(w*t)*stepfunc(t)
57
```

Figure 1: Using Lab 2 Step function code

2.2 Part 2

Part 2 task was to create a user define function in which it would convolve the functions created above with a unit step function. The unit step function would be a forcing function which the convolution of a random function with a step function is the integral of the random function.

```

82 def my_conv(f1,f2):
83
84     Nf1=len(f1)
85     Nf2=len(f2)    #Just defining a length  being passed into function
86
87     x1extended=np.append(f1,np.zeros((1,Nf2-1))) #Combining both  and extending
88     x2extended=np.append(f2,np.zeros((1,Nf1-1))) #Combining botha nd extedning
89
90     result=np.zeros(x1extended.shape) #iniitalizing new result array using one the new arra
91
92     for i in range(Nf2+Nf1-2): #combin lengths of f1 nad f2
93         result[i]=0#Is this initliazing the resultant array?
94         for j in range(Nf1):
95             #if(len(Nf1) and len(Nf2) > len(x1extended)):
96             if(i-j+1>0):
97                 try:
98                     result[i]+=x1extended[j]*x2extended[i-j+1]
99                 except:
100                     print(i,j)
101     return result
102 forcingfunc=stepfunc(t)
103
104 h1c = my_conv(h1t, forcingfunc)*steps
105 h2c = my_conv(h2t, forcingfunc) *steps
106 h3c = my_conv(h3t, forcingfunc)*steps
107
108 #not sure why times 2???
109 #the time axis should not matter where to starts
110 #my time axis needs to match with my new length of the convolution created which is doubled
111 #original is from -10 to 10 so a length of 20
112 #now after the convolution i double it and it reads -20 to 20 meaning length of 40
113 #now my starting point of my time array is still at -10 to 10 which is 20 therefore i
114 #have to double that bad boy as well or do it like below
115 tconvo = np . arange (2*t[0] , 2*t[len(t)-1]+steps , steps )
116 plt.figure(figsize=(10,7))
117 plt.subplot(3,1,1)
118 plt.plot(tconvo,h1c)
119 plt.grid()
120 plt.ylabel('Output')
121 plt.title('h1, h2, and h3 Step Response')
122 plt.subplot(3,1,2)

```

Figure 2: Using Lab 3 convolution code to convole with a step function

Calling the convolution function from Lab 3 and passing it my "random" function $h(t)$ and step-function non-shifted. I then continued to graph that. It's important to know I multiply by the steps so my output wasn't as tall and was scaled down. The trickiest part here was setting your time axis to be proper. Since before the convolution the time axis was defined and spans from -10 to 10 or a range of 20. After the convolution my axis needs to be double to make room for the shifts that are made and will span from -20 to

20 or a range of 40 which therefore require a new time range. Therefore *tconvo* is made and that way I am not plotting different ranges. This took me a while to grasp and was the most challenging task on this lab. The results of the convolution made with python are in Figure 6 under the result section.

Continuing task 2 we were also assigned to integrate $h(t)$ by hand and plot those results and compare them as well. I continued to solve by hand. Figure 3 and 4 shows the hand calculations and code to graph the hand calculations. .

$$\text{Equation1} = .5[1 - e^{-2t}]u(t) - .5[1 - e^{-2(t-3)}]u(t-3)$$

$$\text{Equation2} = (t-2)u(t-2) - (t-6)u(t-6)$$

$$\text{Equation3} = (1/w)\sin(wt)u(t)$$

1

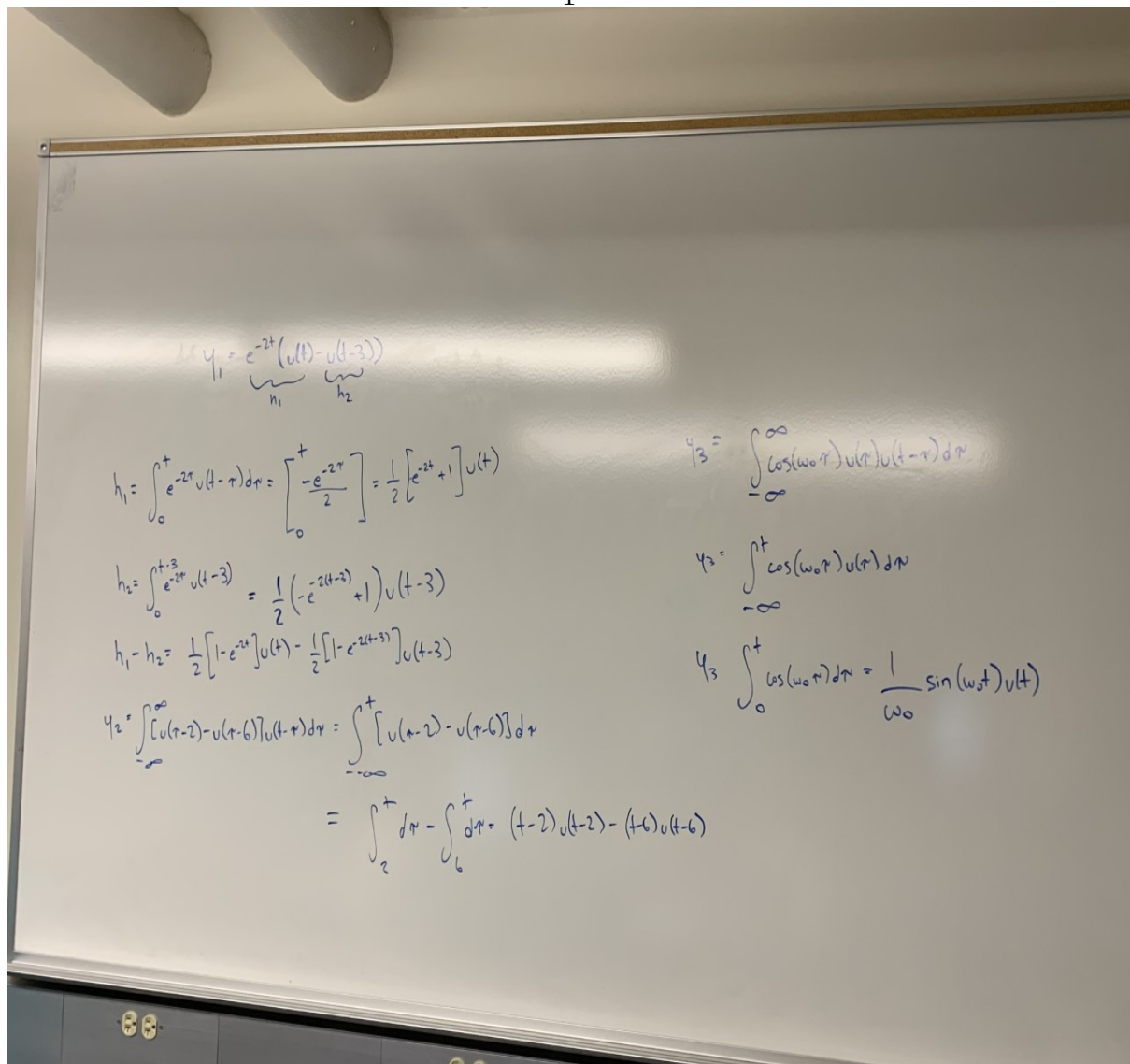


Figure 3: Solving integrals by hand

```

137 handh1= .5*(1-np.exp(-2*t))*stepfunc(t)-.5*(1-np.exp(-2*(t-3)))*stepfunc(t-3)
138 handh2=(t-2)*stepfunc(t-2)-(t-6)*stepfunc(t-6)
139 handh3=(1/w)*np.sin(w*t)*stepfunc(t)
140
141
142
143 plt.figure(figsize=(10,7))
144 plt.subplot(3,1,1)
145 plt.plot(t,handh1)
146 plt.grid()
147 plt.ylabel('Output')
148 plt.title('h1, h2, and h3 Step Response by hand')
149
150 plt.subplot(3,1,2)
151 plt.plot(t,handh2)
152 plt.grid()
153 plt.ylabel('Output')
154
155
156 plt.subplot(3,1,3)
157 plt.plot(t,handh3)
158 plt.grid()
159 plt.ylabel('Output')
160
161

```

Figure 4: Code for hand calculation graphs

The code shows the plotting of the functions that were derived from the hand integrals. For the time-step I used the original with a range-span of 20 from -10 to 10 and plotted. The results are below. Both graphs match like they should.

3 Results

3.1 Part 1

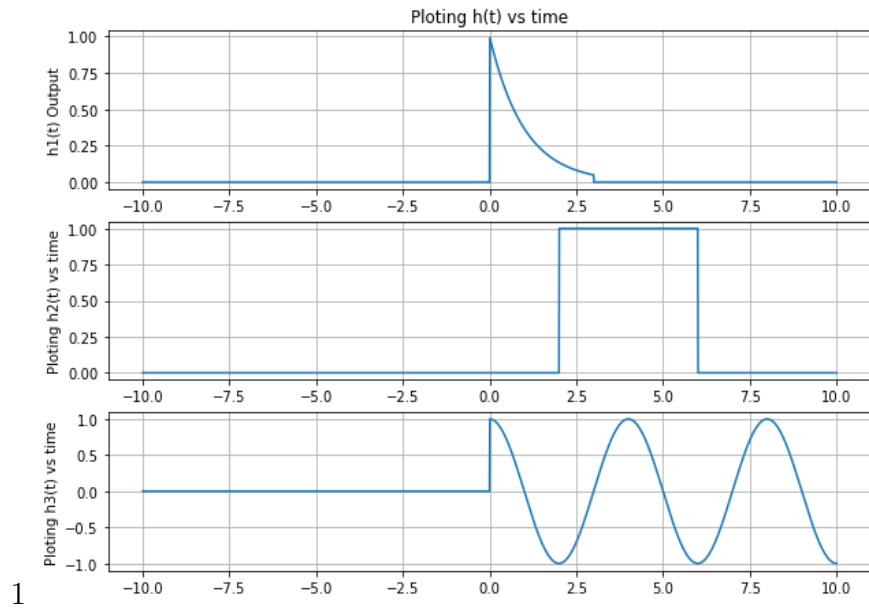


Figure 5: Combination of $h_1(t), h_2(t), h_3(t)$

3.2 Part 2

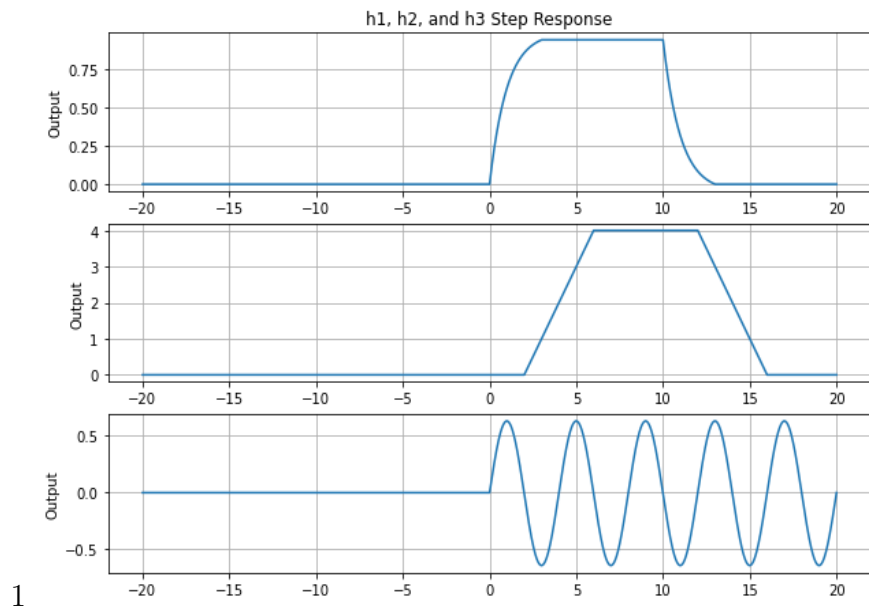


Figure 6: $h_1(t), h_2(t), h_3(t)$ step response

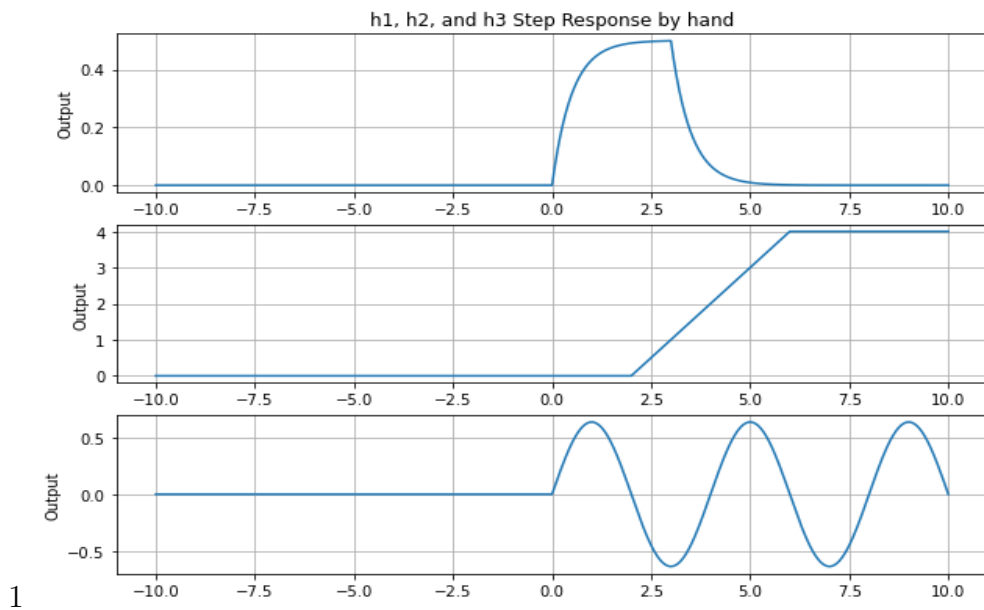


Figure 7: Hand calculation graphs of $h_1(t), 2_2(t), h_3(t)$

4 Questions

The lab was straightforward after figuring out the time range axis needs to be the same for whatever you are plotting. I think stating the quantity number of graphs total needed in the deliverable overview would be helpful. A number given so we can double check we have the correct amount of graphs at least because I kind of got lost trying to find how many graphs we needed to have in our report but maybe it was just me. Aside from that everything was clear.