CSE 221: Algorithms Introduction to graphs

Mumit Khan

Computer Science and Engineering BRAC University

References

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- T. H. Cormen, C. E. Leiserson, R. L. Rivest, and C. Stein, Introduction to Algorithms, Second Edition. The MIT Press, September 2001.
- M. Goodrich and R. Tamassia, Algorithm Design. John-Wiley and Sons. 2002.

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- 1 Introduction to Graphs
 - Graph basics
 - Graph traversal

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 - Graph traversal

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What is a Graph?

- **Graph** G is a pair (V, E), where V is a finite set (set of vertices) and E is a finite set of pairs from V (set of edges). We will often denote n = |V|, m = |E|.
- Graph G can be directed, if E consists of ordered pairs, or undirected, if E consists of unordered pairs. If (u, v) ∈ E, then vertices u and v are adjacent.
- We can assign weight function to the edges: $w_G(e)$ is a weight of edge $e \in E$. The graph which has such function assigned is called **weighted**.
- Degree of a vertex v is the number of vertices u for which (u, v) ∈ E or (v, u) ∈ E (denote deg(v)). The number of incoming edges to a vertex v is called in-degree of the vertex (denote indeg(v)). The number of outgoing edges from a vertex is called out-degree (denote outdeg(v)).

Transportation networks How should you design the highway network in a country? What is the quickest way to drive from Badda to Naraynganj?

Communication networks How to send a network packet from Bracu intranet to Yahoo mail server?

Information networks Is the World wide a directed or undirected network?

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Dependency networks What courses must you take before you can take CSE-423?

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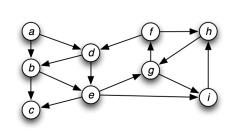
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What is a Graph?

Definition (Graph)

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Example

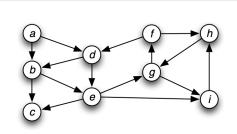


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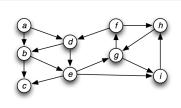
$$V = \{a, \ldots, i\}, n = 9, m = 15.$$

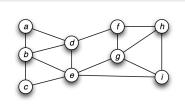
Directed vs. undirected graphs

Definition (Directed vs. undirected graph)

Graph G can be **directed**, if E consists of ordered pairs, or **undirected**, if E consists of unordered pairs. If $(u, v) \in E$, then vertices u and v are **adjacent**.

Example



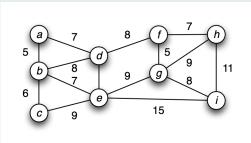


Weighted graphs

Definition (Weighted graph)

We can assign weight function to the edges: $w_G(e)$ is a weight of edge $e \in E$. The graph which has such function assigned is called **weighted**.

Example

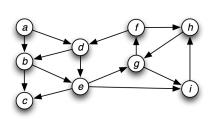


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Definition (Degree of vertices)

Degree of a vertex v is the number of vertices u for which $(u, v) \in E$ or $(v, u) \in E$ (denote deg(v)). The number of **incoming edges** to a vertex v is called **in-degree** of the vertex (denote indeg(v)). The number of **outgoing edges** from a vertex is called **out-degree** (denote outdeg(v)).

Example (Directed graph)

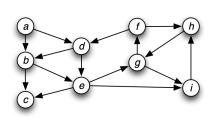


Vertex in out

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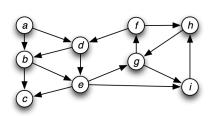


| Vertex | in | out |
|--------|----|-----|
| а | 0 | 2 |

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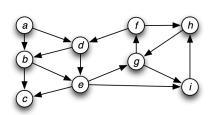


| Vertex | in | out |
|--------|----|-----|
| а | 0 | 2 |
| b | 2 | 2 |

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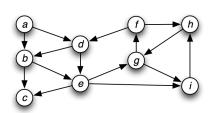


| Vertex | in | out |
|--------|----|-----|
| а | 0 | 2 |
| b | 2 | 2 |
| С | 2 | 0 |

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Example (Directed graph)

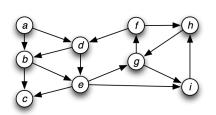


| Vertex | in | out |
|--------|----|-----|
| а | 0 | 2 |
| b | 2 | 2 |
| С | 2 | 0 |
| d | 2 | 2 |

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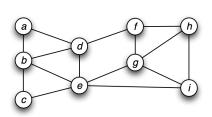


| Vertex | in | out |
|--------|----|-----|
| а | 0 | 2 |
| b | 2 | 2 |
| С | 2 | 0 |
| d | 2 | 2 |
| e | 2 | 3 |

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Example (Undirected graph)

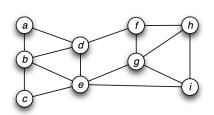


Vertex | deg

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Example (Undirected graph)



| Vertex | deg |
|--------|-----|
| а | 2 |

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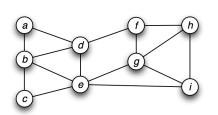
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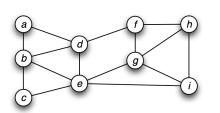


| Vertex | deg |
|--------|-----|
| а | 2 |
| b | 4 |

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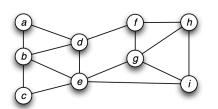


| Vertex | deg |
|--------|-----|
| а | 2 |
| b | 4 |
| С | 2 |

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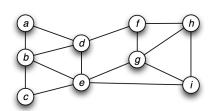


| Vertex | deg |
|--------|-----|
| а | 2 |
| b | 4 |
| С | 2 |
| d | 4 |

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Example (Undirected graph)



| Vertex | deg |
|--------|-----|
| а | 2 |
| b | 4 |
| С | 2 |
| d | 4 |
| е | 5 |

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Relationship of n = |V| and m = |E|

Theorem

If G is a graph with m edges, then

$$\sum_{v \in G} deg(v) = 2m.$$

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Theorem

If G is a graph with m edges, then

$$\sum_{v\in G} deg(v) = 2m.$$

Proof.

An edge (u, v) is counted twice in the above summation; once by its endpoint u and once by its endpoint v. Thus, the total contribution of the edges to the degrees of the vertices is twice the number of edges.

Theorem

If G is a directed graph (digraph) with m edges, then

$$\sum_{v \in G} indeg(v) = \sum_{v \in G} outdeg(v) = m.$$

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Theorem

If G is a directed graph (digraph) with m edges, then

$$\sum_{v \in G} indeg(v) = \sum_{v \in G} outdeg(v) = m.$$

Proof.

In a directed graph, an edge (u, v) contributes one unit to the **out-degree** of its origin u and one unit to the **in-degree** of its destination v. Thus, the total contribution of the edges to the out-degrees of the vertices is equal to the number of edges, and similarly for the in-degrees.



Theorem

If G is a simple **undirected** graph with n vertices and m edges, then $m \le n(n-1)/2$.

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Theorem

If G is a simple **undirected** graph with n vertices and m edges, then $m \le n(n-1)/2$.

Proof.

Since G is a simple undirected graph without self-loops, the maximum degree of a vertex is n-1. And, since there are n vertices, and each edge is counted twice (once for each end of an edge (u, v), the maximum number of edges is n(n-1)/2. Thus,

$$m \le n(n-1)/2$$
, or $m = \Theta(n^2)$.



Theorem

If G is a simple **directed** graph with n vertices and m edges, then $m \le n(n-1)$.

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Theorem

If G is a simple **directed** graph with n vertices and m edges, then $m \le n(n-1)$.

Proof.

Since G is a simple graph without self-loops, the maximum in-degree of a vertex is n-1. And, since there are n vertices, and no two edges can have the same origin and destination, $m \le n(n-1)$, or $m = \Theta(n^2)$.



Paths and connectivity

Definition (Path)

A **path** in a undirected graph G = (V, E) is sequence P of vertices $v1, v_2, \ldots, v_{k-1}, v_k$ with the property that for $i \in \{1, \ldots, k-1\}$, $(v_i, v_{i+1}) \in E$.

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Definition (Simple and cyclic paths)

A path is **simple** if all vertices are distinct. A **cycle** is a path $v_1, v_2, \ldots, v_{k-1}, v_k$ in which $k \ge 2$, and the first k-1 nodes are all distinct, and $v_1 = v_k$.

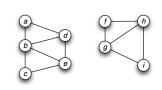
Connected vs. unconnected graphs

Definition (Connected graph)

The undirected graph G is **connected**, if for every pair of vertices u, v there exists a **path** from u to v.

If a graph is not connected, the vertices of the graph can be divided into **connected components**. Two vertices are in the same **connected component** iff they are connected by a **path**.

Example (Connected components)



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Trees

Definition (Trees)

A undirected graph is a *tree* if it is *connected* and does not contain a *cycle* (implies that every n-node tree has exactly n-1 edges).

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A undirected graph is a *tree* if it is *connected* and does not contain a *cycle* (implies that every n-node tree has exactly n-1 edges).

Theorem

For undirected graph G, any two of the following implies the third.

- G is connected.
- 2 G does not contain a cycle.
- \bullet G has n-1 edges.

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Example (Trees (or not))



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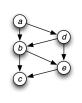
Definition (Adjacency Matrix)

Represents the graph as an $n \times n$ matrix $A = (a_{i,j})$, where

$$a_{i,j} = \begin{cases} 1, & \text{if } (v_i, v_j) \in E, \\ 0, & \text{otherwise.} \end{cases}$$

The matrix is symmetric in case of undirected graph, while it may be asymmetric if the graph is directed.

Example (Directed graph)



| | а | Ь | с | d | е |
|---|---|---|---|---|---|
| а | 0 | 1 | 0 | 1 | 0 |
| Ь | 0 | 0 | 1 | 0 | 1 |
| С | 0 | 0 | 0 | 0 | 0 |
| d | 0 | 1 | 0 | 0 | 1 |
| е | 0 | 0 | 1 | 0 | 0 |

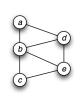
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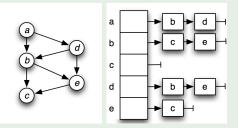


| | а | Ь | с | d | e |
|---|---|---|---|---|---|
| а | 0 | 1 | 0 | 1 | 0 |
| Ь | 1 | 0 | 1 | 1 | 1 |
| С | 0 | 1 | 0 | 0 | 1 |
| d | 1 | 1 | 0 | 0 | 1 |
| e | 0 | 1 | 1 | 1 | 0 |

Definition (Adjacency List)

Represent the graph by listing for each vertex v_i its outgoing vertices in a list $out(v_i)$. (Representation can be linked list, or another appropriate structure.)

Example (Directed graph)



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Representation of graphs

Definition (Adjacency List)

Represent the graph by listing for each vertex v_i its outgoing vertices in a list $out(v_i)$. (Representation can be linked list, or another appropriate structure.)

If the graph is directed, it makes sense to build for each vertex v_i also list of its incoming vertices $in(v_i)$.

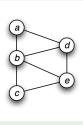
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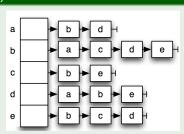
Definition (Adjacency List)

Represent the graph by listing for each vertex v_i its outgoing vertices in a list $out(v_i)$. (Representation can be linked list, or another appropriate structure.)

If the graph is undirected, all incident edges are listed for each vertex v_i .

Example (Undirected graph)



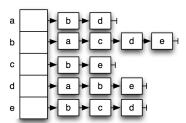


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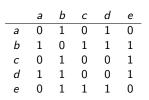
Comparison of graph representations

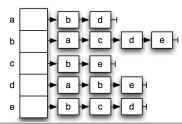
| | а | Ь | С | d | е |
|---|---|---|---|---|---|
| а | 0 | 1 | 0 | 1 | 0 |
| Ь | 1 | 0 | 1 | 1 | 1 |
| С | 0 | 1 | 0 | 0 | 1 |
| d | 1 | 1 | 0 | 0 | 1 |
| e | 0 | 1 | 1 | 1 | 0 |



| Operation | Adjacency matrix | Adjacency list |
|----------------------------|------------------|---------------------|
| Is $(u, v) \in E$? | $\Theta(1)$ | $\Theta(outdeg(u))$ |
| List edges outgoing from u | $\Theta(n)$ | $\Theta(outdeg(u))$ |
| Memory | $\Theta(n^2)$ | $\Theta(m+n)$ |

Comparison of graph representations





| Operation | Adjacency matrix | Adjacency list |
|----------------------------|------------------|---------------------|
| Is $(u, v) \in E$? | Θ(1) | $\Theta(outdeg(u))$ |
| List edges outgoing from u | | $\Theta(outdeg(u))$ |
| Memory | $\Theta(n^2)$ | $\Theta(m+n)$ |

Representation note

We will be using adjacency lists to represent graphs, unless stated otherwise.

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• Starting from a given *source* vertex, can I reach a *target* vertex? *s-t connectivity problem*.

- Starting from a given source vertex, can I reach a target vertex? s-t connectivity problem.
- Starting from a given source vertex, how can I visit all the other vertices that have a path from it?

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- Starting from a given source vertex, can I reach a target vertex? s-t connectivity problem.
- Starting from a given source vertex, how can I visit all the other vertices that have a path from it?
- Is the graph connected? If not, what are the connected components?

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- Starting from a given *source* vertex, can I reach a *target* vertex? *s-t connectivity problem*.
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- Given a source vertex in weighted graph, what is the shortest distance to all the other vertices? Single-source shortest path problem.
- How to compute the minimum spanning tree?

Contents

- 1 Introduction to Graphs
 - Graph basics
 - Graph traversal

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Graph traversal techniques

The graph traversal problem

Given a graph G = (V, E), and a distinguished vertex s, how do you visit each vertex $v \in V$ exactly once.

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Graph traversal techniques

The graph traversal problem

Given a graph G = (V, E), and a distinguished vertex s, how do you visit each vertex $v \in V$ exactly once.

Breadth-first search (BFS)

- Start with the source vertex, and *fan out* from there.
- Finds the distance (in terms of edges) of each node from the source.

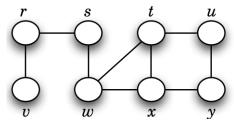
Depth-first search (DFS)

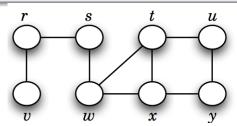
- Start with the source vertex, recursively visit each neighbor, only backtracking when choices are exhausted.
- Remember pre-order tree traversal?

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Basic idea behind breadth first search (BFS)

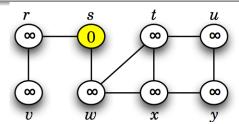
Given a undirected graph G = (V, E), and a distinguished vertex s, systematically visit each vertex $v \in V$ that is reachable from s.





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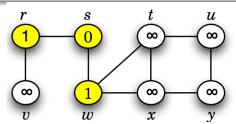
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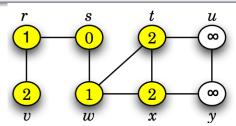
```
\begin{array}{ll} \operatorname{BFS}(G,s) & \rhd G = (V,E) \\ 1 \quad Q \leftarrow \{s\} \\ 2 \quad d[v] \leftarrow \infty, \forall v \in V; \ d[s] \leftarrow 0 \\ 3 \quad \text{while } Q \neq \emptyset \\ 4 \quad \text{do } u \leftarrow \operatorname{DEQUEUE}(Q) \\ 5 \quad \text{for each } v \in Adj[u] \\ 6 \quad \text{do if } d[v] = \infty \\ 7 \quad \text{then } d[v] = d[u] + 1 \\ 8 \quad \operatorname{ENQEUEUE}(Q,v) \end{array}
```



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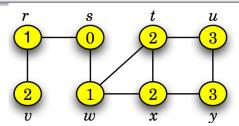
```
 BFS(G,s) > G = (V,E) 
 1    Q \leftarrow \{s\} 
 2    d[v] \leftarrow \infty, \forall v \in V; d[s] \leftarrow 0 
 3    while Q \neq \emptyset 
 4     do u \leftarrow DEQUEUE(Q) 
 5         for each v \in Adj[u] 
 6         do if d[v] = \infty 
 7         then d[v] = d[u] + 1 
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Breadth first search (BFS)

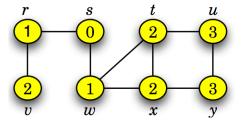
```
BFS(G,s) \Rightarrow G = \overline{(V,E)}
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            do u \leftarrow \text{DEQUEUE}(Q)
5
                 for each v \in Adi[u]
6
                       do if d[v] = \infty
                               then d[v] = d[u] + 1
                                       ENQEUEUE(Q, v)
8
```

Analysis

Time = O(V + E).

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What does this BFS(G, s) algorithm tell us?

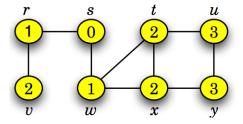


• This graph G = (V, E) is connected since BFS visits all vertices $v \in V$ starting from s.

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What does this BFS(G, s) algorithm tell us?

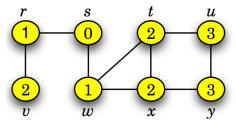


- This graph G = (V, E) is connected since BFS visits all vertices $v \in V$ starting from s.
- The minimum number of hops or edges between s and any vertex $t \in V$.

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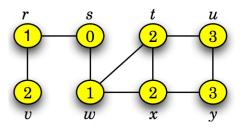
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What does this BFS(G, s) algorithm not tell us?



• Is there a cycle in this graph?

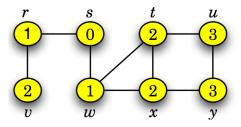
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- Is there a cycle in this graph?
- Given a target vertex $t \in V$, what is the path with smallest number of edges back to s?

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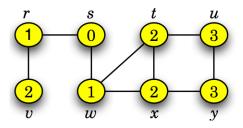
What does this BFS(G, s) algorithm not tell us?



- Is there a cycle in this graph?
- Given a target vertex $t \in V$, what is the path with smallest number of edges back to s?
- If this were not a connected graph, how to visit all the vertices?

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What does this BFS(G, s) algorithm not tell us?



- Is there a cycle in this graph?
- Given a target vertex $t \in V$, what is the path with smallest number of edges back to s?
- If this were not a connected graph, how to visit all the vertices?
- Equivalently, how to compute all the connected components of a graph?

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Idea

Since each node is visited no more than once $(d[v] \neq \infty)$ after the first visit), simply apply the BFS algorithm over each vertex $v \in V$, creating a new component each time a vertex is found for which $d[v] = \infty$.



Computing connected components

Idea

Since each node is visited no more than once $(d[v] \neq \infty)$ after the first visit), simply apply the BFS algorithm over each vertex $v \in V$, creating a new component each time a vertex is found for which $d[v] = \infty$.

```
BFS(G)
                 \triangleright G = (V, E)
```

```
d[v] \leftarrow \infty, \forall v \in V
    for each v \in V
3
            do if d[v] = \infty
                   then BFS(G, v)
4
```

Information during traversal

1 color[v]: the color of each vertex visited



Information during traversal

- 1 color[v]: the color of each vertex visited
 - white: undiscovered



Information during traversal

- 1 color[v]: the color of each vertex visited
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 - gray: discovered but not finished processing

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Information during traversal

- 1 color[v]: the color of each vertex visited
 - white: undiscovered
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- 2 $\pi[v]$: the predecessor pointer

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Information during traversal

- 1 color[v]: the color of each vertex visited
 - white: undiscovered
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- 3 d[v]: the discovery time (or hops from the start)

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Information during traversal

- color[v]: the color of each vertex visited
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- $2\pi[v]$: the predecessor pointer
- 3 d[v]: the discovery time (or hops from the start)

```
BFS(G) \triangleright G = (V, E)

    ▷ Initialize the vertex colors and predecessors

    for each vertex v \in V
          do color[v] = WHITE
3
             \pi[v] = \text{NULL}
   for each vertex v \in V
5
          do if color[v] = WHITE
                then BFS(G, v)
6
```

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BFS
$$(G, s) \triangleright G = (V, E)$$

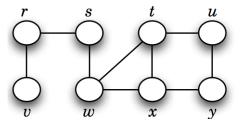
1 $color[s] = GRAY; \pi[s] = NULL; d[s] = 0$
2 $Q = \emptyset; ENQUEUE(Q, s)$



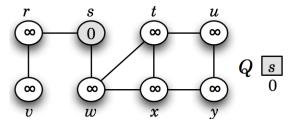
```
BFS(G,s) \triangleright G = (V,E)
     color[s] = GRAY; \pi[s] = NULL; d[s] = 0
   Q = \emptyset; Enqueue(Q, s)
 3
     while Q \neq \emptyset
 4
           do u = \text{Dequeue}(Q)
 5
              for each vertex v \in Adi[u]
 6
                   do if color[v] = WHITE
                          then color[v] = GRAY
                                d[v] = d[u] + 1
 8
 9
                                \pi[v] = u
10
                                ENQUEUE(Q, v)
11
              color[u] = BLACK
```

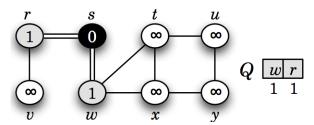
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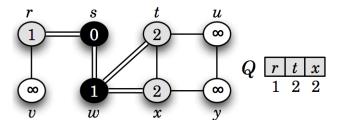
Application of BFS

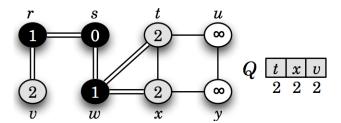


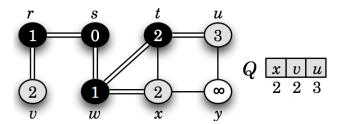
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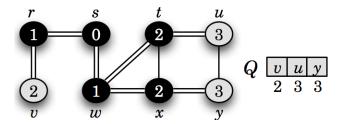


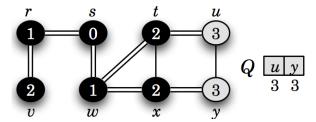


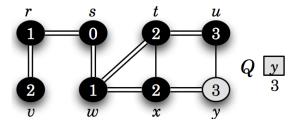


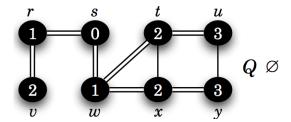






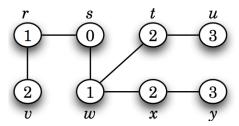




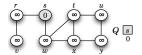


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Application of BFS

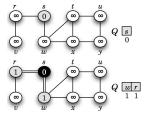


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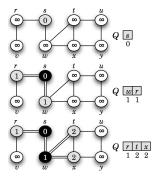


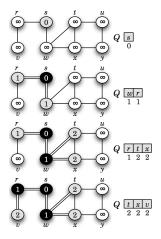
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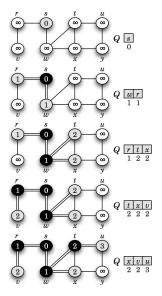
Application of BFS



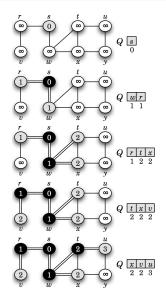
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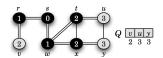


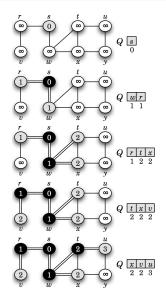


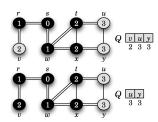


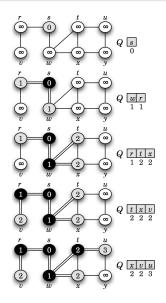
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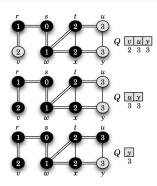


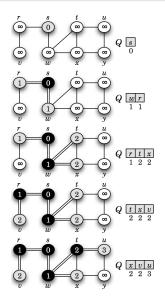


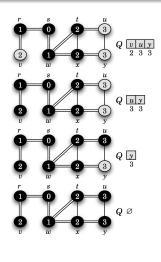




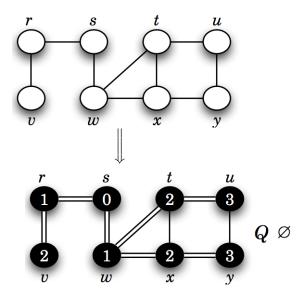








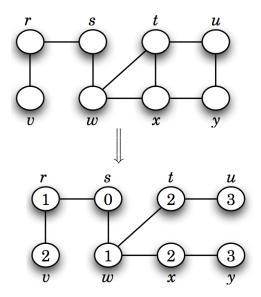
Breadth first search (BFS) tree



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Breadth first search (BFS) tree



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Depth first search (DFS)

- Starts from an initial vertex.
- Recursively visits each adjacent vertex.
- Strategy to search deeper into the graph, unlike BFS which fans out.

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- Starts from an initial vertex.
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- Strategy to search deeper into the graph, unlike BFS which fans out.

Information during traversal

color[v]: the color of each vertex visited

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- Starts from an initial vertex.
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- Strategy to search deeper into the graph, unlike BFS which fans out.

Information during traversal

- October of each vertex visited
 Output
 Description
 - white: undiscovered

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- Starts from an initial vertex.
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- Strategy to search deeper into the graph, unlike BFS which fans out.

Information during traversal

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 - white: undiscovered
 - gray: discovered but not finished processing

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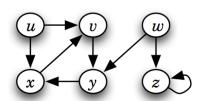
- f[v]: the finish time when processing of v and all its descendants have finished

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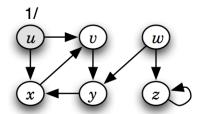
DFS algorithm

```
DFS(G) \triangleright G = (V, E)
    for each vertex u \in V[G]
2
           do color[u] \leftarrow \text{WHITE}
3
               \pi[u] \leftarrow \text{NIL}
    time \leftarrow 0
    for each vertex u \in V[G]
6
           do if color[u] = WHITE
                  then DFS-VISIT(G, u)
DFS-VISIT(G, u) \triangleright G = (V, E), u \in V
    color[u] \leftarrow GRAY
2 time \leftarrow time +1
3 d[u] \leftarrow time
    for each vertex v \in Adj[u]
5
           do if color[v] = WHITE
6
                  then \pi[v] \leftarrow u
7
                          DFS-VISIT(G, \nu)
    color[u] \leftarrow BLACK
    f[u] \leftarrow time + 1
```

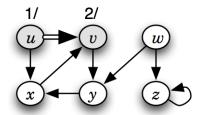
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                   then \pi[v] \leftarrow u
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                          DFS-VISIT(G, v)
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    f[u] \leftarrow time + 1
```



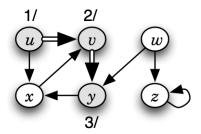
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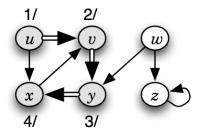
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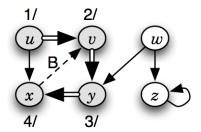
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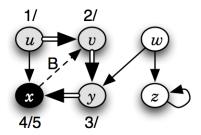
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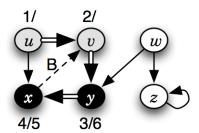
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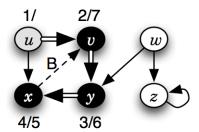
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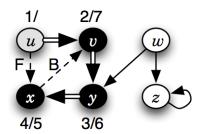
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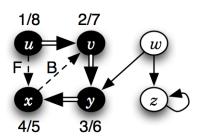
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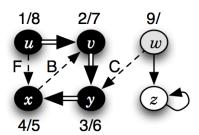
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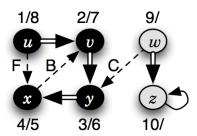
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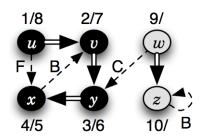
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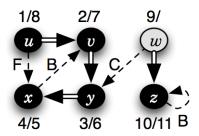
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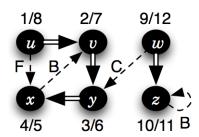
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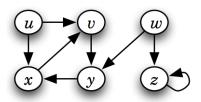
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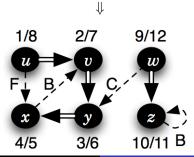


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Depth first search (DFS) tree (or, forest)

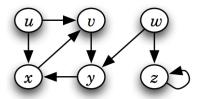


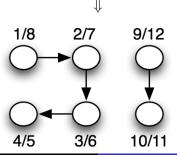


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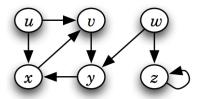


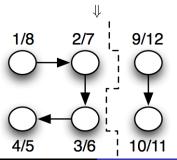


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CSE 221: Algorithms

• How to detect a cycle in the graph?



- How to detect a cycle in the graph?
- How to compute the connected components? (Hint: line 7 in the DFS(G) starts a new tree, with each tree representing a connected component)

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- . . .

- DAG: Directed Acyclic Graph
 Topological Sort
- 3. Back Edges, Tree Edges, Cross Edge
 - 4. Strongly Connected Components

Note: Study from class notes and book