CSE 221: Algorithms Dynamic Programming

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References

- Jon Kleinberg and Éva Tardos, Algorithm Design. Pearson Education, 2006.
- T. H. Cormen, C. E. Leiserson, R. L. Rivest, and C. Stein, Introduction to Algorithms, Second Edition. The MIT Press, September 2001.

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Introduction

- Memoization
- Dynamic programming
- Weighted interval scheduling problem
- 0/1 Knapsack problem
- Coin changing problem
- What problems can be solved by DP?
- Conclusion

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 Build up the solution by computing solutions to the subproblems.

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Dynamic Programming (DP)

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- Unlike Greedy algorithms, implicitly solve all subproblems.
- Motivating the case for DP with Memoization a top-down technique, and then moving on to Dynamic Programming – a bottom-up technique.
- *□ Greedy is evil, Dynamic Programming is good.* Prof. Jeff Erickson, University of Illinois, Urbana-Champaign.

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Recursive solution to Fibonacci numbers

Definition (Fibonacci numbers)

The Fibonacci numbers are given by the following sequence:

$$\langle 0, 1, 1, 2, 3, 5, 8, 21, 34, 55, 89, \ldots \rangle$$

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Recursive solution to Fibonacci numbers

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$$\langle 0, 1, 1, 2, 3, 5, 8, 21, 34, 55, 89, \ldots \rangle$$

and described by the following recurrence.

$$\operatorname{Fib}(n) = \left\{ \begin{array}{ll} n & \text{if } n = 0 \text{ or } 1 \\ \operatorname{Fib}(n-1) + \operatorname{Fib}(n-2) & \text{if } n \geq 2 \end{array} \right.$$

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Straightforward recursive algorithm

FIBONACCI(
$$n$$
) $\triangleright n \ge 0$

- **if** n = 0 or n = 1
- then return n
- 3 else return FIBONACCI(n-1) + FIBONACCI(n-2)

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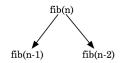
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fib(n)

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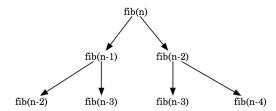
Recursion tree



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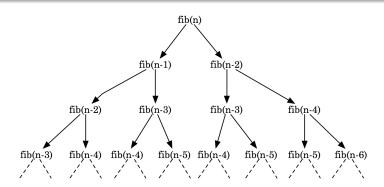
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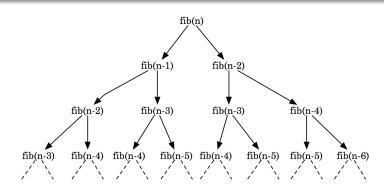
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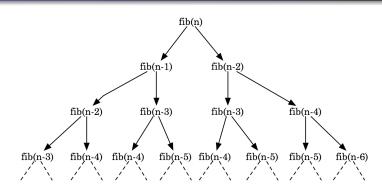
Recursion tree



Complexity

This recursive algorithm for Fibonacci numbers has exponential running time!

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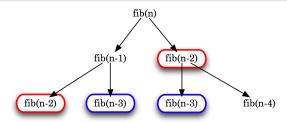
Complexity

This recursive algorithm for Fibonacci numbers has exponential running time!

To be precise, $T(n) = O(\varphi^n)$, where $\varphi = \frac{1+\sqrt{5}}{2}$ is the golden ratio.

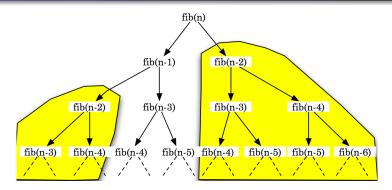
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Redundant computations



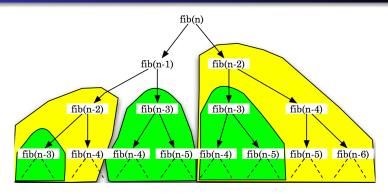
 \triangleright Note how FIB(n-2) and FIB(n-3) are each being computed twice.

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 \triangleright In fact, computing FIB(n-2) involves computing a whole subtree.

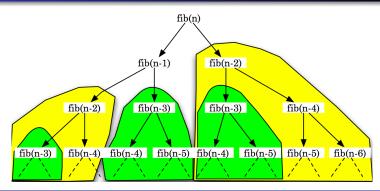
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 \triangleright Likewise for computing FIB(n-3).

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Redundant computations

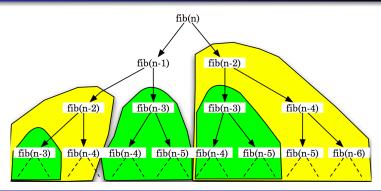


Observations

Spectacular redundancy in computation

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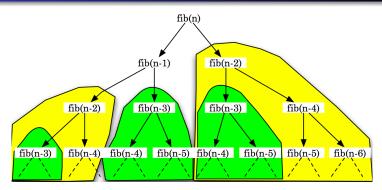
Redundant computations



Observations

• Spectacular redundancy in computation - how many times are we computing FIB(n-2)?

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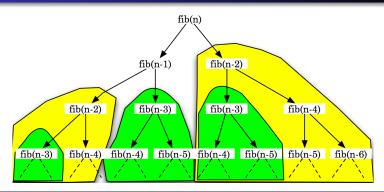


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 Spectacular redundancy in computation – how many times are we computing FIB(n-2)? FIB(n-3)?

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Redundant computations

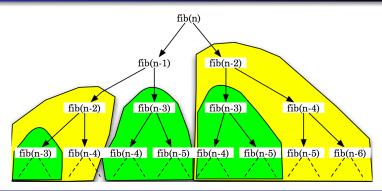


Observations

- Spectacular redundancy in computation how many times are we computing FIB(n-2)? FIB(n-3)?
- What if we compute and save the result of FIB(i) for $i = \{2, 3, ..., n\}$ the first time, and then re-use it each time afterward?

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Redundant computations



Observations

- Spectacular redundancy in computation how many times are we computing FIB(n-2)? FIB(n-3)?
- What if we compute and save the result of FIB(i) for $i = \{2, 3, ..., n\}$ the first time, and then re-use it each time afterward?
- Ah, we've just (re)discovered Memo(r)ization!

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Definition (Memoization)

The process of saving solutions to subproblems that can be re-used later without redundant computations.

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Basic idea

Typically, the solutions to subproblems (i.e., the intermediate solutions) are saved in a global array, which are later looked up and re-used as needed.

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• At each step of computation, first see if the solution to the subproblem has already been found and saved.

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- At each step of computation, first see if the solution to the subproblem has already been found and saved.
- 2 If so, simply return the solution.
- If not, compute the solution, and save it before returning the solution.

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Memoized recursive algorithm for Fibonacci numbers

```
M-FIBONACCI(n) \triangleright n \ge 0, global F = [0 ... n]
   if n = 0 or n = 1
                                                Our base conditions.
       then return n
   if F[n] is empty
                                   \triangleright No saved solution found for n.
       then F[n] \leftarrow \text{M-FIBONACCI}(n-1) + \text{M-FIBONACCI}(n-2)
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• What is this global array F?

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- What is an appropriate sentinel to indicate that $F[i], 0 \le i \le n$ has not been solved yet (i.e., empty)? Use -1, which is guaranteed to be an invalid value.

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Memoized ... Fibonacci numbers (continued)

```
FIBONACCI(n) \triangleright n > 0
   \triangleright Allocate an array F[0..n] to save results (LENGTH[F] = n+1).
   for i \leftarrow 0 to n
         do F[i] \leftarrow -1
                          \triangleright No solution computed for i yet (sentinel)
   return M-FIBONACCI(F, n)
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```

Running time

Each element $F[2] \dots F[n]$ is filled in just once in $\Theta(1)$ time, so $T(n) = \Theta(n)$.

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Memoization highlights

• Idea is to re-use saved solutions, trading off space for time.

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Questions to ask (and remember)

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- Would all recursive algorithms benefit from memoization?

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Questions to ask (and remember)

- What are the drawbacks, if any, of memoization?
- Would all recursive algorithms benefit from memoization? For example, would the recursive algorithm to compute the factorial of a number benefit from memoization?

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Dynamic programming

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- Idea: why not build up the solution bottom-up, starting from the base case(s) all the way to n?

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 $T(n) = \Theta(n)$

Dynamic programming (continued)

The pattern

Formulate the problem recursively.



Dynamic programming (continued)

The pattern

1 Formulate the problem recursively. Write a formula for the whole problem as a simple combination of of the answers to smaller subproblems.



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- Formulate the problem recursively. Write a formula for the whole problem as a simple combination of the answers to smaller subproblems.
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Observations

- Must ensure that the recurrence is correct of course!
- 2 Need a "place" to store the solutions to subproblems, and need to look these solutions up when needed. Typically, but not always, a multi-dimensional table is used as storage.

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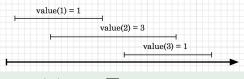
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Weighted interval scheduling problem

Definition (Weighted interval scheduling problem)

Given a set of schedules $I = \{I_i\}$, with associated weights $W = \{w_i\}$, find $A \subseteq I$ such that the members of A are non-conflicting and the total weight $\sum_{i \in A} w_i$ is maximized.

Example (an instance of weighted interval problem)



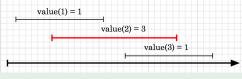
$$|A| = ???$$
, $\sum_{i \in A} w_i = ???$.

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Example (using an optimal strategy)



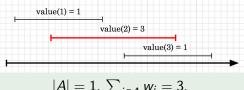
$$|A| = 1$$
, $\sum_{i \in A} w_i = 3$.

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Example (using an optimal strategy)



|A| = 1, $\sum_{i \in \Delta} w_i = 3$.

What now?

First step is to formulate a recursive solution, but first we need to figure out what the subproblems are.

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Developing a recursive solution

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- As in the greedy approach, we sort the intervals according to finish times such that $f_i \leq f_j$ for i < j ("a natural order of the subproblems").

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Developing a recursive solution

- Let W be an instance of a weighted interval problem.
- As in the greedy approach, we sort the intervals according to finish times such that $f_i \leq f_j$ for i < j ("a natural order of the subproblems").
- Let ϑ be an optimal solution (even if we have no idea what it is yet).

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- Let W be an instance of a weighted interval problem.
- As in the greedy approach, we sort the intervals according to finish times such that $f_i \leq f_i$ for i < j ("a natural order of the subproblems").
- Let ϑ be an optimal solution (even if we have no idea what it is yet).
- All we can say about ϑ is the following: interval n (the last interval) either belongs to ϑ , or it doesn't.

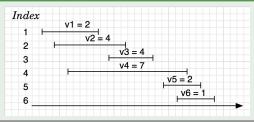
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Developing a recursive solution

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- All we can say about ϑ is the following: interval n (the last interval) either belongs to ϑ , or it doesn't.
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 - If $n \notin \vartheta$ Then ϑ contains an optimal solution for the intervals $\{i_1, i_2, ..., i_{n-1}\}$.

Example (an instance of a weighted interval problem)



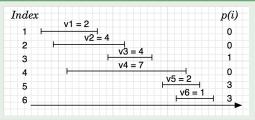
 \triangleright For each interval i, compute p(i), the leftmost interval that does not conflict with i. Define p(i) = 0 if not request i < j is disjoint from j.

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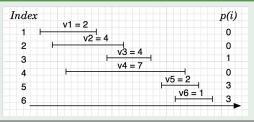
Developing a recursive solution (continued)

Example (an instance of a weighted interval problem)



 \triangleright For a given interval i, p(i) means that intervals $\{p(i)+1,p(i)+2,\ldots,i-1\}$ overlap with it. For example, p(6) = 3, which means that intervals $\{4, 5\}$ overlap interval 6.

Example (an instance of a weighted interval problem)



 \triangleright Alternatively, intervals $\{1, 2, ..., p(i)\}$ do not overlap interval i. For example, p(6) = 3 means that intervals $\{1, 2, 3\}$ do not overlap interval 6.

• If $n \in \emptyset$, then \emptyset must include, in addition to interval n, an optimal solution to the subproblem consisting of intervals $\{1, 2, \ldots, p(n)\}.$

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 $\triangleright \vartheta(n) = \vartheta(n-1)$

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- Since an optimal solution must maximize the sum of the weights in the intervals it contains, we accept the larger of the two.

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- Since an optimal solution must maximize the sum of the weights in the intervals it contains, we accept the larger of the two.
 - $\vartheta(n) = \text{MAX}(w_n + \vartheta(p(n)), \vartheta(n-1))$

Recursive algorithm for an optimal value

If OPT(j) is an optimal solution to the subproblem for intervals $\{1, 2, \dots, j\}$, for any $j \in \{1, 2, \dots, n\}$, then:

$$OPT(j) = MAX(w_j + OPT(p(j)), OPT(j-1))$$

Recursive algorithm for an optimal value

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Extracting the intervals in an optimal solution

The interval j is in an optimal solution OPT(j) if and only if the first of the two options is larger than the second.

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Extracting the intervals in an optimal solution

The interval j is in an optimal solution OPT(j) if and only if the first of the two options is larger than the second.

Interval j belongs to an optimal solution on the set $\{1, 2, ..., j\}$ if and only if

$$w_j + OPT(p(j)) \geq OPT(j-1)$$

A recursive algorithm

```
WIS(j)
  if i = 0
      then return 0
3
     else return MAX(w_i + WIS(p(j)),
                      WIS(j-1)
```

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• The initial call is WIS(n) for intervals $\{1, 2, ..., n\}$ sorted in non-decreasing order of the finishing times.

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- The initial call is WIS(n) for intervals $\{1, 2, ..., n\}$ sorted in non-decreasing order of the finishing times.
- The tree grows very rapidly, leading to exponential running time. The tree when p(j) = j - 2 for all j shows how quickly it grows.

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- The tree grows very rapidly, leading to exponential running time. The tree when p(j) = j - 2 for all j shows how quickly it grows.
- There are many overlapping subproblems, so the obvious choice is to memoize the recursion.

```
M-WIS(i)
   if i = 0
       then return 0
3
   elseif M[i] is empty
       then M[j] \leftarrow \text{MAX}(w_i + \text{M-WIS}(p(j)),
4
                            M-WIS(i-1)
5
    return M[i]
```

Memoizing the recursion

```
M-WIS(i)
   if i = 0
       then return 0
3
   elseif M[i] is empty
4
       then M[j] \leftarrow \text{MAX}(w_i + \text{M-WIS}(p(j)),
                            M-WIS(i-1)
5
   return M[i]
```

• Each entry in M[j] gets filled in only once at $\Theta(1)$ time, and there are n+1 entries, so M-WIS(n) takes $\Theta(n)$ time.

```
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- Of course, sorting the intervals by the finish times takes $\Theta(n \lg n)$ time.

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   return M[i]
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- Of course, sorting the intervals by the finish times takes $\Theta(n \lg n)$ time.
- This memoized algorithm *plus* sorting the intervals takes $\Theta(n \lg n) + \Theta(n) = \Theta(n \lg n)$ time.

Computing a solution in addition to its values

- The memoized algorithm only computes the optimal value, but does not extract the intervals that make up the solution.
- The key to extracting the solution is to note that item j is in ϑ if and only if $w_i + M[p(j)] \ge M[j-1]$. This provides two ways of extracting the intervals in the optimal solution:
 - Trace back from M[n] and extract the solution by checking which choice was made -j-1 or p(j) – when M[j] was included in the optimal set of intervals.
 - 2 Whenever a choice is made between two options, save in pred[j], the predecessor pointer, the choice that was made between i-1 and p(i).

- The first way recursively extracts an optimal set of intervals for a problem size of $1 \le j \le n$.
- Calling WIS-FIND-SOLUTION(n) extracts all the intervals in the optimal solution.

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- The first way recursively extracts an optimal set of intervals for a problem size of 1 < i < n.
- Calling WIS-FIND-SOLUTION(n) extracts all the intervals in the optimal solution.

```
WIS-find-solution(i)
   if i = 0
      then Output nothing
3
      else
           if w_i + M[p(j)] \ge M[j-1]
4
5
             then Output i
6
                  WIS-FIND-SOLUTION(p(i))
             else WIS-FIND-SOLUTION(j-1)
```

- The second way requires that M-WIS use an auxiliary array pred[0...n] to save the predecessor of each interval in the solution.
- Initialize pred[j] = 0 for all $0 \le j \le n$.

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- The second way requires that M-WIS use an auxiliary array pred[0...n] to save the predecessor of each interval in the solution.
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```
M-WIS(i)
   if i = 0
        then return 0
3
    elseif M[i] is empty
4
        then if w_i + \text{M-WIS}(p(j)) > \text{M-WIS}(j-1)
                 then M[j] \leftarrow w_i + \text{M-WIS}(p(j))
5
6
                        pred[i] \leftarrow p(i)
                 else M[i] \leftarrow \text{M-WIS}(i-1)
                        pred[i] \leftarrow i - 1
8
9
    return M[i]
```

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Now that we have pred[j] filled in, we start from M[n] and work backwards.

- If pred[j] = p(j), then we did add the j^{th} interval in the final solution, and we continue with $pred[i] \leftarrow p(i)$.
- 2 if $pred[j] \neq p(j)$, then we did not add the j^{th} interval in the final solution, and we continue with $pred[i] \leftarrow i - 1$.

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```
WIS-FIND-SOLUTION(i)
   if i = 0
      then Output nothing
3
      else
4
           if pred[i] = p(i)
5
             then Output j
                  WIS-FIND-SOLUTION(p(i))
6
             else WIS-FIND-SOLUTION(i-1)
```

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Computing a solution in addition to its values (continued)

Now that we have pred[j] filled in, we start from M[n] and work backwards.

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5
             then Output j
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             else WIS-FIND-SOLUTION(i-1)
```

Can you come up with an iterative version?

Developing a Dynamic Programming algorithm

• The value of an optimal solution OPT(i) for any $j \in \{1, 2, 3, \dots, n\}$ depends on the values of OPT(p(j)) and OPT(j-1).

Developing a Dynamic Programming algorithm

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- We can build the table M[i] bottom-up, starting from the base case of i = 0, up to n by using the memoized recursive formulation: $M[j] = \text{MAX}(w_j + M[p(j)], M[j-1]).$

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Dynamic programming algorithm

```
WIS(n)
   M[0] \leftarrow 0
2
  for i \leftarrow 1 to n
3
         do M[j] = MAX(w_i + M[p(j)], M[j-1])
4
   return M[n]
```

Developing a Dynamic Programming algorithm

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4
   return M[n]
                     T(n) = \Theta(n)
```

```
WIS(n)
   M[0] \leftarrow 0
   for j \leftarrow 1 to n
3
         do if w_i + M[p(j) > M[j-1]
               then M[i] = w_i + M[p(i)]
4
5
                     pred[i] = p(i)
6
               else M[i] = M[i-1]
                     pred[i] = i - 1
8
   return M[n]
```

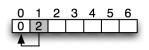
Computing a solution in addition to its values

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4
5
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6
               else M[i] = M[i - 1]
                     pred[i] = i - 1
8
   return M[n]
WIS-find-solution(i)
   j ← n
   while i > 0
         do if pred[i] = p(i)
               then Output j
4
5
             i \leftarrow pred[i]
```

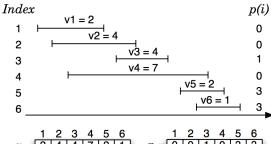
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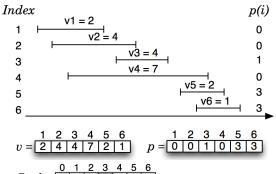


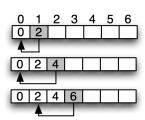
Pred = 0 0 0 0 0 0 0

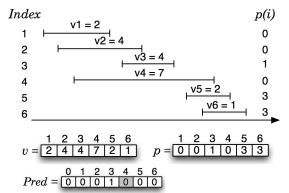


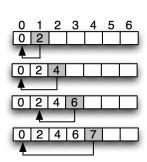
0	1	2	3	4	5	6
0	2					
4	_		_	_	_	_
0	2	4				
\mathbf{T}	_	1	_	_	_	-

$$Pred = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$









Weighted Interval Scheduling DP algorithm in action

Index
$$v1 = 2$$

$$v1 = 2$$

$$v3 = 4$$

$$v4 = 7$$

$$v6 = 1$$

$$v = 2$$

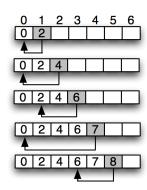
$$v = 3$$

$$v = 2$$

$$v = 2$$

$$v = 3$$

$$v$$



Weighted Interval Scheduling DP algorithm in action

Index
$$v1 = 2 \qquad v2 = 4 \qquad 0$$

$$2 \qquad v3 = 4 \qquad 1$$

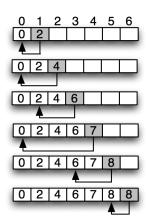
$$4 \qquad v4 = 7 \qquad 0$$

$$5 \qquad v6 = 1 \qquad 3$$

$$v = 2 \quad 4 \quad 7 \quad 2 \quad 1$$

$$p = 0 \quad 1 \quad 2 \quad 3 \quad 4 \quad 5 \quad 6$$

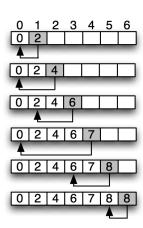
$$Pred = 0 \quad 0 \quad 1 \quad 0 \quad 3 \quad 5$$



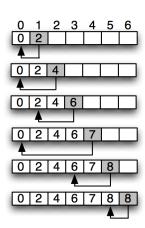
Weighted Interval Scheduling DP algorithm in action

Optimal value: 8

Optimal solution: {5, 3, 1}



Optimal value: 8 Optimal solution: $\{1, 3, 5\}$



Answer the following questions

Instead of sorting the intervals by finish time, what if we sorted the requests by start time?

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Answer the following questions

- Instead of sorting the intervals by finish time, what if we sorted the requests by start time?
- What if we didn't sort the requests at all? Would it still work?
- **1** If all the *weights* are the same, what does this problem become? Can you solve it using DP?

- Introduction
- Memoization
- Dynamic programming
- Weighted interval scheduling problem
- 0/1 Knapsack problem
- Coin changing problem
- What problems can be solved by DP?
- Conclusion

Definition (0/1 knapsack problem)

Given a set S of n items, such that each item i has a positive benefit v_i and a positive weight w_i , the goal is to find the maximum-benefit subset that does not exceed a given weight W.

0/1 knapsack problem

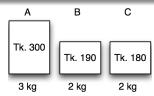
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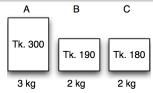


Maximum weight: W = 4 kg

$$W = 4 \text{ kg}$$

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Maximum weight: W = 4 kg

$$W = 4 \text{ kg}$$

Optimal solution: items B and C

Benefit:

Licensed under Mumit Khan CSE 221: Algorithms 32 / 53 • Let S be an instance of a 0/1 Knapsack problem, and ϑ be an optimal solution (even if we have no idea what it is yet).

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 - If $n \in \vartheta$ Then the optimal solution contains n, plus an optimal solution for the other n-1 items, but with a reduced maximum weight of $W - w_n$.

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- Note that the presence of an item i in ϑ does not preclude any other item $i \neq i$ in ϑ .
- If item n weighs more than the maximum allowed weight, it will not be in ϑ .
- Otherwise, all we can say about ϑ is the following: item n (the last one) either belongs to ϑ , or it doesn't.
 - If $n \in \vartheta$ Then the optimal solution contains n, plus an optimal solution for the other n-1 items, but with a reduced maximum weight of $W - w_n$.
 - If $n \notin \vartheta$ Then ϑ simply contains an optimal solution for the first n-1 items, with the maximum allowed weight W remaining unchanged.

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Developing a recursive solution

- Let S be an instance of a 0/1 Knapsack problem, and ϑ be an optimal solution (even if we have no idea what it is yet).
- Note that the presence of an item i in ϑ does not preclude any other item $i \neq i$ in ϑ .
- If item n weighs more than the maximum allowed weight, it will not be in ϑ .
- Otherwise, all we can say about ϑ is the following: item n (the last one) either belongs to ϑ , or it doesn't.
 - If $n \in \vartheta$ Then the optimal solution contains n, plus an optimal solution for the other n-1 items, but with a reduced maximum weight of $W - w_n$.
 - If $n \notin \vartheta$ Then ϑ simply contains an optimal solution for the first n-1 items, with the maximum allowed weight W remaining unchanged.
- We have two parameters for each subproblem the items 5, and the maximum allowed weight W.

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•
$$w_n > W \implies n \notin \vartheta$$
.
• $\vartheta(n, W) = \vartheta(n - 1, W)$

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- $w_n > W \implies n \notin \vartheta$. $\triangleright \vartheta(n, W) = \vartheta(n-1, W)$
- Otherwise, *n* is either $\in \vartheta$ or $\notin \vartheta$.
 - If $n \in \vartheta$, then $\vartheta(n, W)$ is an optimal solution to the subproblem for items $\{1, 2, \ldots, n\}$:

$$\triangleright \vartheta(n, W) = v_n + \vartheta(n-1, W-w_n)$$

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Recursive algorithm for an optimal value

If OPT(j, w) is an optimal solution to the subproblem for items $\{1,2,\ldots,j\}$, for any $j\in\{1,2,\ldots,n\}$, and with a maximum allowed weight of w, then:

$$OPT(j,w) = \left\{ \begin{array}{ll} OPT(j-1,w) & \text{if } w_j > w, \\ \max(v_j + OPT(j-1,w-w_j), & \\ OPT(j-1,w)) & \text{otherwise.} \end{array} \right.$$

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Recursive algorithm for an optimal value

If OPT(j, w) is an optimal solution to the subproblem for items $\{1,2,\ldots,j\}$, for any $j\in\{1,2,\ldots,n\}$, and with a maximum allowed weight of w, then:

$$OPT(j, w) = \begin{cases} OPT(j-1, w) & \text{if } w_j > w, \\ \max(v_j + OPT(j-1, w - w_j), & \text{otherwise.} \end{cases}$$

Extracting the items in an optimal solution

The item j is in an optimal solution OPT(j, w) if and only if the first of the two options is larger than the second.

$$v_j + OPT(j-1, w-w_j) \ge OPT(j-1, w)$$

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A recursive algorithm

```
KNAPSACK(j, w)
   if i = 0 or w = 0
      then return 0
3
   elseif w_i > w
      then return KNAPSACK(j-1, w))
5
   else return MAX(v_i + KNAPSACK(j-1, w-w_i),
                   KNAPSACK(i-1, w)
```

```
KNAPSACK(j, w)

1 if j = 0 or w = 0

2 then return 0

3 elseif w_j > w

4 then return KNAPSACK(j - 1, w))

5 else return MAX(v_j + \text{KNAPSACK}(j - 1, w - w_j), \text{KNAPSACK}(j - 1, w))
```

• The initial call is KNAPSACK(n, W).

A recursive algorithm

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- The initial call is KNAPSACK(n, W).
- The tree grows very rapidly, leading to exponential running time.

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5
                   KNAPSACK(i-1, w)
```

- The initial call is KNAPSACK(n, W).
- The tree grows very rapidly, leading to exponential running time.
- There are many overlapping subproblems, so the obvious choice is to memoize the recursion.

```
M-KNAPSACK(i, w)
   if j = 0 or w = 0
      then return 0
3
   elseif M[i, w] is empty
      then M[j, w] \leftarrow \text{MAX}(v_j + \text{M-KNAPSACK}(j-1, w-w_i),
4
                             M-KNAPSACK(i-1, w)
5
   return M[i, w]
```

Memoizing the recursion

```
M-KNAPSACK(i, w)
   if j = 0 or w = 0
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   elseif M[i, w] is empty
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      then M[j, w] \leftarrow \text{MAX}(v_i + M - KNAPSACK}(j-1, w-w_i),
4
                            M-KNAPSACK(i-1, w)
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   return M[i, w]
```

• Each entry in M[i, w] gets filled in only once at $\Theta(1)$ time, and there are $n + 1 \times W + 1$ entries, so M-KNAPSACK(n, W)takes $\Theta(nW)$ time.

Memoizing the recursion

```
M-KNAPSACK(j, w)

1 if j = 0 or w = 0

2 then return 0

3 elseif M[j, w] is empty

4 then M[j, w] \leftarrow \text{MAX}(v_j + \text{M-KNAPSACK}(j-1, w-w_j), \\ M-KNAPSACK}(j-1, w))

5 return M[j, w]
```

- Each entry in M[j,w] gets filled in only once at $\Theta(1)$ time, and there are $n+1\times W+1$ entries, so M-KNAPSACK(n,W) takes $\Theta(nW)$ time.
- Is this a linear-time algorithm?

Memoizing the recursion

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                            M-KNAPSACK(i-1, w)
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   return M[i, w]
```

- Each entry in M[i, w] gets filled in only once at $\Theta(1)$ time, and there are $n+1\times W+1$ entries, so M-KNAPSACK(n,W)takes $\Theta(nW)$ time.
- Is this a linear-time algorithm?
- This is an example of a pseudo-polynomial problem, since it depends on another parameter W that is independent of the problem size.

Developing a Dynamic Programming algorithm

```
KNAPSACK(n, W)
    for i \leftarrow 0 to n \rightarrow \infty no remaining capacity
            do M[i,0] \leftarrow 0
    for w \leftarrow 0 to W \rightarrow \text{no item to choose from}
            do M[0, w] \leftarrow 0
     for i \leftarrow 1 to n
 6
            do for w \leftarrow 1 to W
                      do if w_i > w
 8
                             then M[j, w] = M[j - 1, w]
 9
                             else M[j, w] \leftarrow \text{MAX}(v_i + M[j-1, w-w_i],
                                                        M[i-1,w]
10
     return M[n, W]
```

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0/1 Knapsack recursive algorithm in action

Given the following (from M. H. Alsuwaiyel, ex. 7.6):

$$W = 9$$

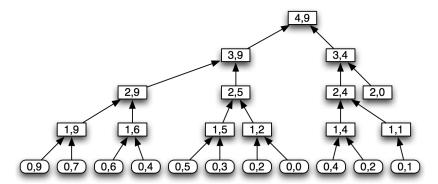
 $w_i = \{2, 3, 4, 5\}$
 $v_i = \{3, 4, 5, 7\}$

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 $w_i = \{2, 3, 4, 5\}$
 $v_i = \{3, 4, 5, 7\}$

	0	1	2	3	4	5	6	7	8	9
4	1	1	ı	•	-	-	-	-	-	•
3	-	-	-	-	-	-	-	-	-	-
2	-	-	-	-	-	-	-	-	-	-
1	-	-	-	-	-	-	-	-	-	-
0	-	1		-	-	-	-	-	-	

0/1 Knapsack DP algorithm in action

Given the following (from M. H. Alsuwaiyel, ex. 7.6):

$$W = 9$$

$$w_i = \{2, 3, 4, 5\}$$

$$v_i = \{3, 4, 5, 7\}$$



	0	1	2	3	4	5	6	7	8	9
4	0	0	3	4	5	7	8	10	11	12
3	0	0	3	4	5	7	8	9	9	12
2	0	0	3	4	4	7	7	7	7	7
1	0	0	3	3	3	3	3	3	3	3
0	0	0	0	0	0	0	0	0	0	0

Definition (Subset Sums problem)

Given a set S of n items, such that each item i has a positive weight w_i , the goal is to find the maximum-weight subset that does not exceed a given weight W.

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Related problem: Subset Sums problem

Definition (Subset Sums problem)

Given a set S of n items, such that each item i has a positive weight w_i , the goal is to find the maximum-weight subset that does not exceed a given weight W.

Formally, we wish to determine a subset of S that maximizes $\sum_{i \in S} w_i$, subject to $\sum_{i \in S} w_i \leq W$.

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Related problem: Subset Sums problem

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Formally, we wish to determine a subset of S that maximizes $\sum_{i \in S} w_i$, subject to $\sum_{i \in S} w_i \leq W$.

• How is this similar to the 0/1 Knapsack problem?

Related problem: Subset Sums problem

Definition (Subset Sums problem)

Given a set S of n items, such that each item i has a positive weight w_i , the goal is to find the maximum-weight subset that does not exceed a given weight W.

Formally, we wish to determine a subset of S that maximizes $\sum_{i \in S} w_i$, subject to $\sum_{i \in S} w_i \leq W$.

- How is this similar to the 0/1 Knapsack problem?
- Can you solve this using the same algorithm?

- Introduction
- Memoization
- Dynamic programming
- Weighted interval scheduling problem
- 0/1 Knapsack problem
- Coin changing problem
- What problems can be solved by DP?
- Conclusion

Definition

Given coin denominations in $C = \{c_i\}$, make change for a given amount A with the minimum number of coins.

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Given coin denominations in $C = \{c_i\}$, make change for a given amount A with the minimum number of coins.

Example

Coin denominations, $C = \{12, 5, 1\}$ Amount to change, A = 15

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Definition

Given coin denominations in $C = \{c_i\}$, make change for a given amount A with the minimum number of coins.

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Coin denominations, $C = \{12, 5, 1\}$ Amount to change, A = 15

- ① Choose 0 12 coins, so remaining is 15
- 2 Choose 3 5 coins, so remaining is 15 3 * 5 = 0

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Example

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- Choose 0 12 coins, so remaining is 15
- 2 Choose 3 5 coins, so remaining is 15 3 * 5 = 0

Solution: 3 coins.

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- Choose 0 12 coins, so remaining is 15
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Solution: 3 coins.

Questions

What is the natural search space? Does this problem have a Dynamic Programming solution? If so, how do we develop it?

Licensed under CSE 221: Algorithms 43 / 53 Coin denominations, $C = \{12, 5, 1\}$ Amount to change, A = 15

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Developing a recursive solution

Coin denominations, $C = \{12, 5, 1\}$ Amount to change, A = 15

• The best combination of coins for 15 paisa must be one of the following:

Mumit Khan Licensed under @@@@ CSE 221: Algorithms Coin denominations, $C = \{12, 5, 1\}$ Amount to change, A = 15

- The best combination of coins for 15 paisa must be one of the following:
 - **1** Best combination for 15 12 = 3 paisa, plus a 12 paisa coin.

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Coin denominations, $C = \{12, 5, 1\}$ Amount to change, A = 15

- The best combination of coins for 15 paisa must be one of the following:
 - **1** Best combination for 15 12 = 3 paisa, plus a 12 paisa coin.
 - Best combination for 15 5 = 10 paisa, plus a 5 paisa coin.

- Coin denominations, $C = \{12, 5, 1\}$ Amount to change, A = 15
 - The best combination of coins for 15 paisa must be one of the following:
 - **1** Best combination for 15 12 = 3 paisa, plus a 12 paisa coin.
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 - Best combination for 15 1 = 14 paisa, plus a 1 paisa coin.

- Coin denominations, $C = \{12, 5, 1\}$ Amount to change, A = 15
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 - Since we're minimizing the number of coins, the best combination would be the minimum of these three choices.

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 - By recursively solving for the best combination, this can be generalized to |C| denominations to make change for any amount A.

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- Since we're minimizing the number of coins, the best combination would be the minimum of these three choices.
- By recursively solving for the best combination, this can be generalized to |C| denominations to make change for any amount A.
- What are the subproblems?

If OPT(p) is the minimum number of coins needed to make change for amount p with denominations $C = \{c_1, c_2, \dots, c_k\}$, then:

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If OPT(p) is the minimum number of coins needed to make change for amount p with denominations $C = \{c_1, c_2, \dots, c_k\}$, then:

• The coin c_i chosen at any step must be smaller than p, the amount left at that point.

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If OPT(p) is the minimum number of coins needed to make change for amount p with denominations $C = \{c_1, c_2, \dots, c_k\}$, then:

- The coin c_i chosen at any step must be smaller than p, the amount left at that point.
- Once we choose $c_i \leq p$, $OPT(p) = 1 + OPT(p c_i)$, since we have to find the best combination for the remaining amount (picking a coin smaller than the amount at each step).

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- Since we don't know which coin would be chosen, we have to search all |C| denominations and find the minimum.

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If OPT(p) is the minimum number of coins needed to make change for amount p with denominations $C = \{c_1, c_2, \dots, c_k\}$, then:

- The coin c_i chosen at any step must be smaller than p_i the amount left at that point.
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- The number of coins for 0 amount is 0.

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- Since we don't know which coin would be chosen, we have to search all |C| denominations and find the minimum.
- The number of coins for 0 amount is 0.

Recurrence

$$OPT(p) = \left\{ egin{array}{ll} 0 & \mbox{if } p = 0 \ min_{i:c_i \leq p} \{1 + OPT(p - c_i)\} & \mbox{if } p > 0 \end{array}
ight.$$

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```
CHANGE(n, C)
    if n=0
        then return 0
3
        else min \leftarrow \infty
               for i \leftarrow 1 to |C|
5
                    do if c_i \leq n and 1 + \text{CHANGE}(n - c_i, C) < min
6
                           then min \leftarrow 1 + \text{CHANGE}(n - c_i, C)
```

```
CHANGE(n, C)
    if n=0
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3
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```

The initial call is CHANGE(A, C).

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- The initial call is CHANGE(A, C).
- The tree grows very rapidly, leading to exponential running time.

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                    do if c_i \leq n and 1 + \text{CHANGE}(n - c_i, C) < min
                           then min \leftarrow 1 + \text{CHANGE}(n - c_i, C)
6
```

- The initial call is CHANGE(A, C).
- The tree grows very rapidly, leading to exponential running time.
- There are many overlapping subproblems, so the obvious choice is to memoize the recursion.

```
M-Change(n, C)
   if n=0
       then return 0
       else if M[n] is empty
4
                 then min \leftarrow \infty
5
                        for i \leftarrow 1 to |C|
6
                             do if c_i \leq n and
                                       1 + \text{M-CHANGE}(n - c_i, C) < min
                                    then min \leftarrow 1 + \text{M-CHANGE}(n - c_i, C)
                        M[n] \leftarrow min
9
              return M[n]
```

Memoizing the recursion

```
M-Change(n, C)
   if n=0
       then return 0
3
       else if M[n] is empty
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                 then min \leftarrow \infty
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                       for i \leftarrow 1 to |C|
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                            do if c_i \le n and
                                      1 + M-CHANGE(n - c_i, C) < min
                                   then min \leftarrow 1 + \text{M-CHANGE}(n - c_i, C)
                       M[n] \leftarrow min
9
              return M[n]
```

• Each entry in M[n] gets filled in only once at $\Theta(|C|)$ time, and there are n+1 entries, so $\operatorname{M-CHANGE}(n)$ takes $\Theta(n|C|)$ time.

Memoizing the recursion

```
M-Change(n, C)
   if n=0
       then return 0
       else if M[n] is empty
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                then min \leftarrow \infty
5
                       for i \leftarrow 1 to |C|
6
                            do if c_i \le n and
                                      1 + M-CHANGE(n - c_i, C) < min
                                   then min \leftarrow 1 + \text{M-CHANGE}(n - c_i, C)
                       M[n] \leftarrow min
9
              return M[n]
```

- Each entry in M[n] gets filled in only once at $\Theta(|C|)$ time, and there are n + 1 entries, so M-CHANGE(n) takes $\Theta(n|C|)$ time.
- Another pseudo-polynomial problem!

Developing a Dynamic Programming algorithm

```
CHANGE(n, C)
     \triangleright M = [0..n], S = [0..n]
 1 M[0] \leftarrow 0 no amount to change
 2 for p \leftarrow 1 to n
 3
            do min \leftarrow \infty
                for i \leftarrow 1 to |C|
 5
                      do if c_i \leq p and 1 + M[p - c_i] < min
                             then min \leftarrow 1 + M[p - c_i]
 6
                                    coin ← i
 8
                M[p] \leftarrow min
                S[p] \leftarrow coin
 9
10
     return M and S
```

Developing a Dynamic Programming algorithm

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                             then min \leftarrow 1 + M[p - c_i]
 6
                                    coin ← i
 8
                M[p] \leftarrow min
                S[p] \leftarrow coin
 9
10
     return M and S
```

- M[p] for all $0 \le p \le n$ minimum number of coins needed to change for p paisa.
- S[p] for all $0 \le p \le n$ the first coin chosen in computing an optimal solution for making change for p paise.

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- The S array in the algorithm "remembers" the first coin we use when computing an optimal value for a given amount.
- We go backwards using S[n] until n=0 and find the coin that was added at each step.

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Computing a solution in addition to its values

- The S array in the algorithm "remembers" the first coin we use when computing an optimal value for a given amount.
- We go backwards using S[n] until n=0 and find the coin that was added at each step.

```
Coins(S, C, n)
   while n > 0
          do Output C[S[n]]
3
              n \leftarrow n - C_{S[n]}
```

- Introduction
- Memoization
- Dynamic programming
- Weighted interval scheduling problem
- 0/1 Knapsack problem
- Coin changing problem
- What problems can be solved by DP?
- Conclusion

Problem types solved by Dynamic Programming

 The most important part of DP is to set up the subproblem structure.

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 - Polynomially many subproblems The total number of subproblems should be a polynomial, or else DP may not provide an efficient solution.
 - Subproblem optimality If the optimal solution to the entire problem contain optimal solution to the subproblems, then it has the subproblem optimality property. Also called the principle of optimality.

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Dynamic Programming highlights

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- Developing a Dynamic Programming solution often requires some thought into the subproblems, especially how to find the natural order in which to solve the subproblems.
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- Dynamic Programming is a bottom-up techniques, and finds the solution by starting from the base case(s) and works its way upwards.
- Developing a Dynamic Programming solution often requires some thought into the subproblems, especially how to find the natural order in which to solve the subproblems.
- Unlike Memoization, which solves only the needed subproblems, DP solves all the subproblems, because it does it bottom-up.
- Dynamic Programming on the other hand may be much more efficient because its iterative, whereas Memoization must pay for the (often significant) overhead due to recursion.

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Conclusion

- Memoization is the top-down technique, and dynamic programming is a bottom-up technique.
- The key to Dynamic programming is in "intelligent" recursion (the hard part), not in filling up the table (the easy part).
- Dynamic Programming has the potential to transform exponential-time brute-force solutions into polynomial-time algorithms.
- Greed does not pay, Dynamic Programming does!