CSE 221: Algorithms Heapsort

Mumit Khan

Computer Science and Engineering BRAC University

References

T. H. Cormen, C. E. Leiserson, R. L. Rivest, and C. Stein, Introduction to Algorithms, Second Edition. The MIT Press, September 2001.

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Contents

- Heapsort
 - Introduction
 - Heap data structure
 - Heap algorithms
 - Heapsort algorithm
 - Priority queue
 - Conclusion



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Heapsort

• $O(n \lg n)$ in the worst case – like merge sort.

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Heapsort

- $O(n \lg n)$ in the worst case like merge sort.
- Sorts in place like insertion sort.

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Heapsort

- $O(n \lg n)$ in the worst case like merge sort.
- Sorts in place like insertion sort.
- Combines the best of both algorithms.

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- Sorts in place like insertion sort.
- Combines the best of both algorithms.
- Uses a data structure called the heap, which is also extensively used in other applications.

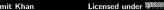


- Introduction
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Heap data structure

• A data structure that provides worst-case O(1) time access to the largest (max heap) or smallest (min heap) element.



- A data structure that provides worst-case O(1) time access to the largest (max heap) or smallest (min heap) element.
- A data structure that provides worst-case $\Theta(\lg n)$ time extract the largest (max heap) or smallest (min heap) element.

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- Heapsort is an another application, where the keys can be sorted by repeatedly extracting the largest from the heap.

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Max vs. Min Heap

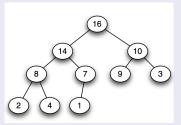
Unless explicitly stated as max heap or min heap, heap means max heap in this course.

Definition

A binary tree is heap-ordered if:

 \bullet the value at a node is \geq the value at each of its children.

Example of (max) heap



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Definition

A binary tree is heap-ordered if:

1 the value at a node is > the value at each of its children.

Heapsort

2 the tree is almost-complete.

Example of complete tree (or *not*)

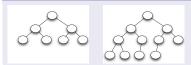


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Heap-ordered tree

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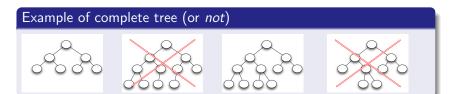
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Example of complete tree (or *not*)

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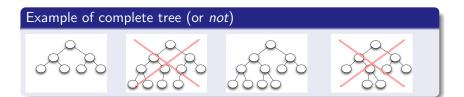
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- 2 the tree is almost-complete.



Definition

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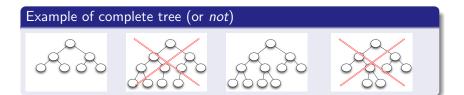
- 1 the value at a node is > the value at each of its children.
- 2 the tree is almost-complete. Height of tree is $\Theta(\lg n)$.



Definition

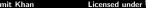
A binary tree is heap-ordered if:

- \bullet the value at a node is \geq the value at each of its children.
- 2 the tree is almost-complete. Height of tree is $\Theta(\lg n)$. Why?



Height of a heap-ordered tree

• Height h of a tree is the maximum distance of any leaf node to the root.



- Height h of a tree is the maximum distance of any leaf node to the root.
- A heap of height h has the most number of elements if the tree is complete, so *n* equals the sum of nodes at each level.

$$n \le 2^{0} + 2^{1} + 2^{2} + 2^{3} + \dots + 2^{h}$$

$$= \frac{2^{h+1} - 1}{2 - 1}$$

$$= 2^{h+1} - 1.$$

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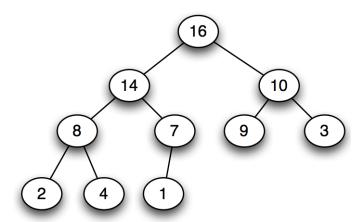
$$n \le 2^{0} + 2^{1} + 2^{2} + 2^{3} + \dots + 2^{h}$$

$$= \frac{2^{h+1} - 1}{2 - 1}$$

$$= 2^{h+1} - 1.$$

- It has the least number of elements if the lowest level has a single element and all higher levels are complete, so $n > 2^h - 1 + 1 = 2^h$.
- $2^h < n < 2^{h+1} 1 < 2^{h+1}$ \Rightarrow $h \le \lg n < h + 1$. Since h is an integer, $h = |\lg n| = \Theta(\lg n)$.

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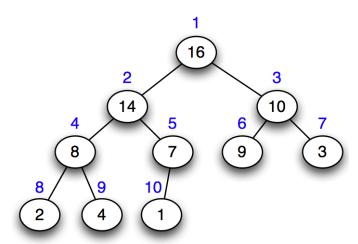
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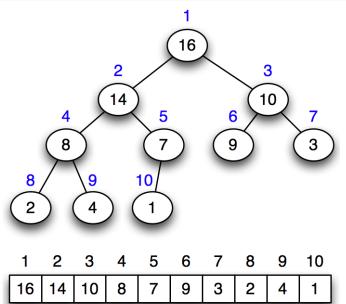
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Heap – array representation of heap-ordered tree



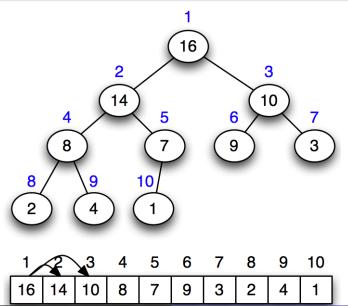
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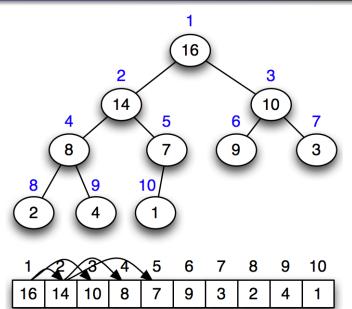


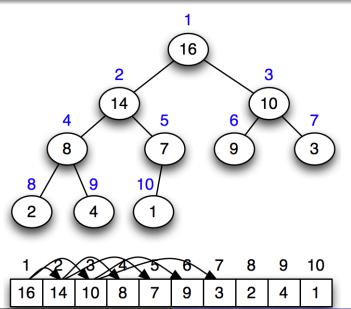
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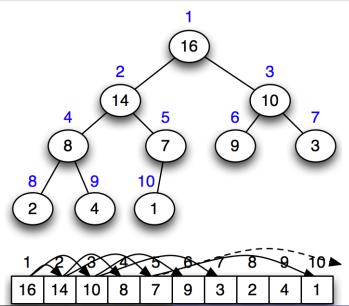
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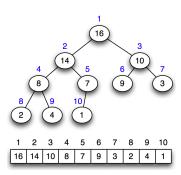
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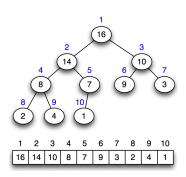
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Heap – accessing parent and children

MAXIMUM(A)return A[1]



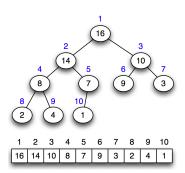
Heap – accessing parent and children



MAXIMUM(A)return A[1]

PARENT(i)return |i/2|

Heap – accessing parent and children

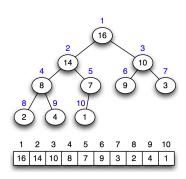


MAXIMUM(A)return A[1]

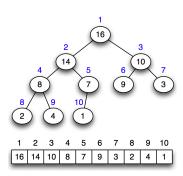
PARENT(i)return |i/2|

Question

What if PARENT(i) < 1?



```
MAXIMUM(A)
   return A[1]
PARENT(i)
   return |i/2|
LEFT(i)
   return 2i
```



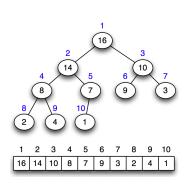
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PARENT(i)return |i/2|

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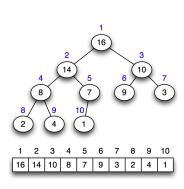
Question

What if LEFT(i) > n?



```
MAXIMUM(A)
   return A[1]
PARENT(i)
   return |i/2|
LEFT(i)
   return 2i
RIGHT(i)
```

return 2i + 1



MAXIMUM(A)return A[1]

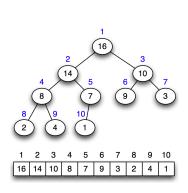
PARENT(i)return |i/2|

LEFT(i)return 2i

RIGHT(i)return 2i + 1

Question

What if RIGHT(i) > n?



MAXIMUM(A)return A[1]PARENT(i)return |i/2|

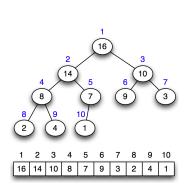
LEFT(i)return 2i

RIGHT(i)return 2i + 1

Lemma

All nodes i > |length[A]/2| (or equivalently, i > |heap-size[A]/2|) are leaf nodes. *Check Note

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MAXIMUM(A)return A[1]PARENT(i)return |i/2|LEFT(i)return 2i RIGHT(i)

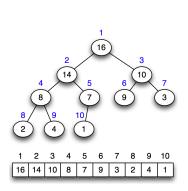
return 2i + 1

Definition (Heap property)

Heap property: For every node *i* other than the root,

$$A[PARENT(i)] \geq A[i].$$





MAXIMUM(A)return A[1]PARENT(i)return |i/2|LEFT(i)return 2i RIGHT(i)return 2i + 1

Question

Why do we insist that a heap-ordered tree be a complete binary tree? (Hint: draw the array representation of a tree that is not complete and see the gaps).

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• MAX-HEAPIFY(A, i) – Ensure the heap property of A starting at node i. Also known as "sink" operation since it sinks the lighter elements down the tree.

- **1** MAX-HEAPIFY(A, i) Ensure the heap property of A starting at node i. Also known as "sink" operation since it sinks the lighter elements down the tree.
- \bigcirc MAX-HEAP-INSERT(A, key) Insert key in the heap A, maintaining A's heap property.

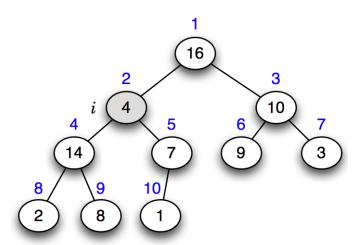
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- **3** BUILD-MAX-HEAP(A) Build a max heap given an array A.
- **1** HEAPSORT(A) Sort the elements in array A using the heap operations.
- **1** HEAP-INCREASE-KEY(A, i, key) Increase the value of element at node i to key, and ensure the heap property of A by moving larger elements upwards. Also known as "swim" operation as it moves larger elements upwards.

- MAX-HEAPIFY(A, i) Ensure the heap property of A starting at node i. Also known as "sink" operation since it sinks the lighter elements down the tree.
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- heap A.

Example of MAX-HEAPIFY ("sink") operation

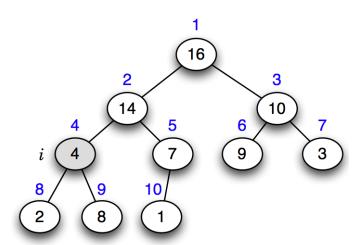


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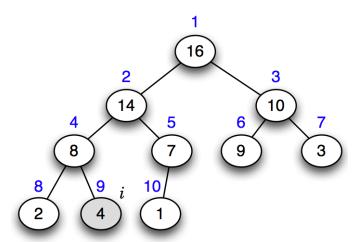
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Example of MAX-HEAPIFY ("sink") operation



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MAX-HEAPIFY algorithm

```
MAX-HEAPIFY (A, i)
  1 I \leftarrow left(i)
 2 r \leftarrow right(i)
 3 if l \le heap\text{-}size[A] and A[l] > A[i]
          then largest \leftarrow l
          else largest \leftarrow i
      if r \le heap\text{-}size[A] and A[r] > A[largest]
          then largest \leftarrow r
      if largest \neq i
 9
          then exchange A[i] \leftrightarrow A[largest]
10
                 MAX-HEAPIFY (A, largest)
```

MAX-HEAPIFY algorithm

```
MAX-HEAPIFY (A, i)
 1 I \leftarrow left(i)
 2 r \leftarrow right(i)
 3 if I < heap-size[A] and A[I] > A[i]
         then largest \leftarrow l
         else largest \leftarrow i
 6 if r < heap\text{-}size[A] and A[r] > A[largest]
          then largest \leftarrow r
      if largest \neq i
          then exchange A[i] \leftrightarrow A[largest]
                 MAX-HEAPIFY (A, largest)
10
```

Analysis - first way

Since the children's subtrees each have at most size of 2n/3 (when the last row is exactly half full), we have

$$T(n) < T(2n/3) + \Theta(1)$$
.

According to case 2 of the Master theorem, $T(n) = O(\lg n)$.

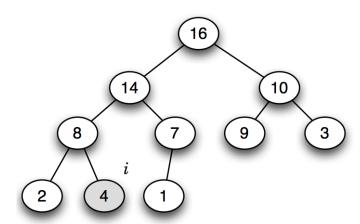
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```

Analysis – second way

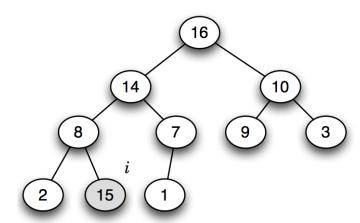
The running time of MAX-HEAPIFY on a node of height h is $T(n) = O(h) = O(\lg n).$

Example of HEAP-INCREASE-KEY ("swim") operation



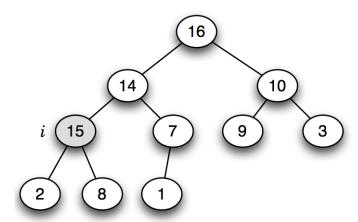
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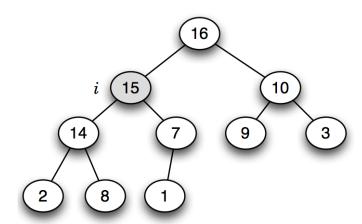
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Example of HEAP-INCREASE-KEY ("swim") operation



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HEAP-INCREASE-KEY algorithm

```
HEAP-INCREASE-KEY(A, i, key)
   if key < A[i]
       then error "new key is smaller than current key"
3
   A[i] \leftarrow key
    while i > 1 and A[PARENT(i)] < A[i]
4
          do exchange A[i] \leftrightarrow A[parent(i)]
5
6
              i \leftarrow PARENT(i)
```

HEAP-INCREASE-KEY algorithm

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Analysis

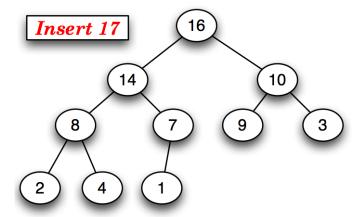
A node may move all the way from a leaf node to the root because of increased value, so $T(n) = O(h) = O(\lg n)$.

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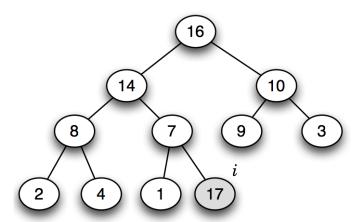
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Example of MAX-HEAP-INSERT operation

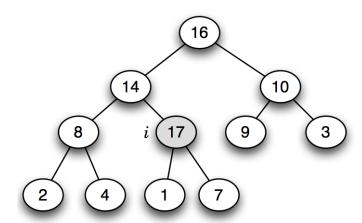


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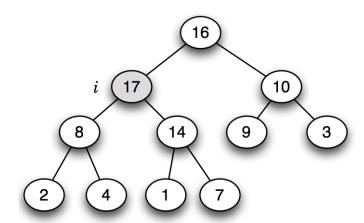
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Example of MAX-HEAP-INSERT operation



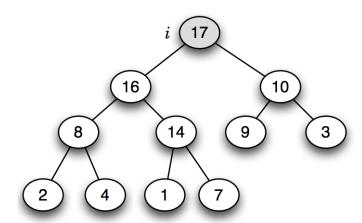
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Example of MAX-HEAP-INSERT operation



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Example of MAX-HEAP-INSERT operation



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MAX-HEAP-INSERT algorithm

```
MAX-HEAP-INSERT (A, key)
```

- heap- $size[A] \leftarrow heap$ -size[A] + 1
- $A[heap-size[A]] \leftarrow key$
- $i \leftarrow heap-size[A]$
- while i > 1 and A[PARENT(i)] < A[i]
- 5 **do** exchange $A[i] \leftrightarrow A[parent(i)]$
- $i \leftarrow A[PARENT(i)]$ 6

MAX-HEAP-INSERT algorithm

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Can also be done using HEAP-INCREASE-KEY.

MAX-HEAP-INSERT
$$(A, key)$$

- heap- $size[A] \leftarrow heap$ -size[A] + 1
- $A[heap-size[A]] \leftarrow -\infty$
- 3 HEAP-INCREASE-KEY(A, heap-size[A], key)

- MAX-HEAP-INSERT (A, key)
- heap- $size[A] \leftarrow heap$ -size[A] + 1
- $A[heap-size[A]] \leftarrow key$
- $3 \quad i \leftarrow heap\text{-}size[A]$
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- heap- $size[A] \leftarrow heap$ -size[A] + 1
- $A[heap-size[A]] \leftarrow -\infty$
- 3 HEAP-INCREASE-KEY(A, heap-size[A], key)

Analysis

$$T(n) = O(h) = O(\lg n).$$

Heapsort

```
BUILD-MAX-HEAP'(A)
   heap-size[A] \leftarrow 1
   for i \leftarrow 2 to length[A]
3
         do MAX-HEAP-INSERT(A, A[i])
```

Simple BUILD-MAX-HEAP algorithm

```
BUILD-MAX-HEAP'(A)
   heap-size[A] \leftarrow 1
   for i \leftarrow 2 to length[A]
3
         do MAX-HEAP-INSERT(A, A[i])
```

Analysis

There are n-1 calls to MAX-HEAP-INSERT, each taking $O(\lg n)$ time, so $T(n) = O(n \lg n)$.

Simple BUILD-MAX-HEAP algorithm

```
BUILD-MAX-HEAP'(A)
```

- heap- $size[A] \leftarrow 1$
- for $i \leftarrow 2$ to length[A]
- 3 **do** MAX-HEAP-INSERT(A, A[i])

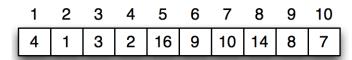
Analysis

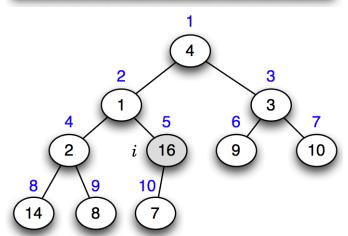
There are n-1 calls to MAX-HEAP-INSERT, each taking $O(\lg n)$ time, so $T(n) = O(n \lg n)$.

Better way?

A better way is to build up the heap from the smaller trees. See next.

Example of BUILD-MAX-HEAP ("heapify") operation

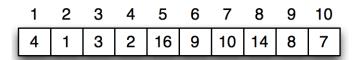


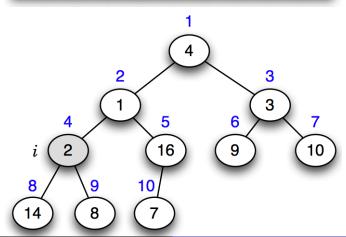


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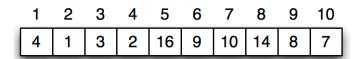
Example of BUILD-MAX-HEAP ("heapify") operation

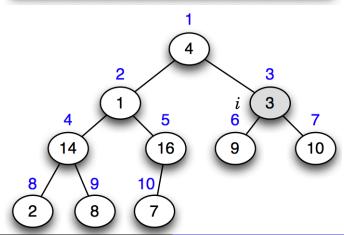




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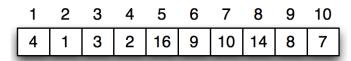


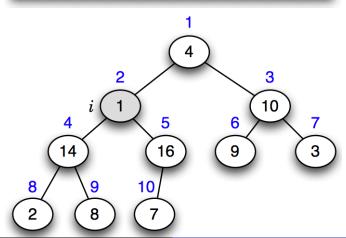


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Example of BUILD-MAX-HEAP ("heapify") operation

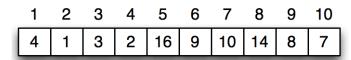


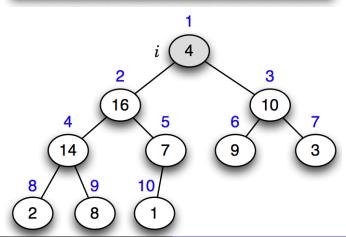


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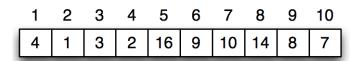
Example of BUILD-MAX-HEAP ("heapify") operation

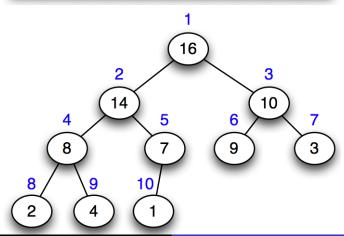




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BUILD-MAX-HEAP algorithm

```
BUILD-MAX-HEAP(A)
   heap-size[A]] \leftarrow length[A]
   for i \leftarrow |length[A]/2| downto 1
         do MAX-HEAPIFY(A, i)
3
```

BUILD-MAX-HEAP algorithm

```
BUILD-MAX-HEAP(A)
```

- heap- $size[A]] \leftarrow length[A]$
- for $i \leftarrow |length[A]/2|$ downto 1
- **do** MAX-HEAPIFY(A, i)

Analysis

$$T(n) = O(n)$$
 (see textbook for details)

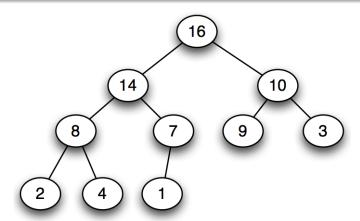


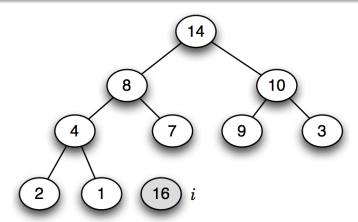
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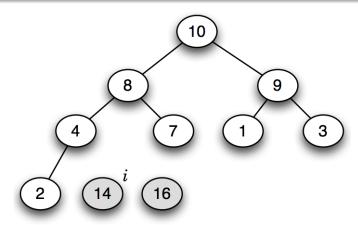


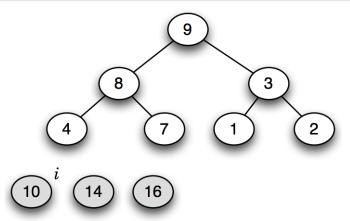
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- Heap data structure
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- Heapsort algorithm
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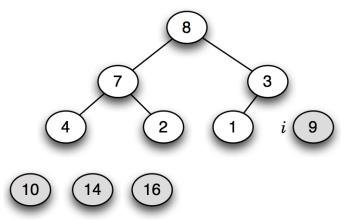


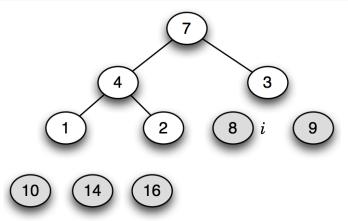


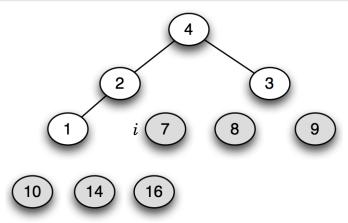


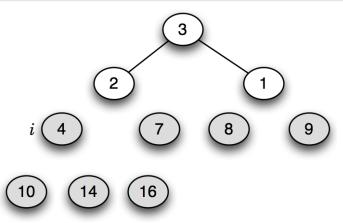


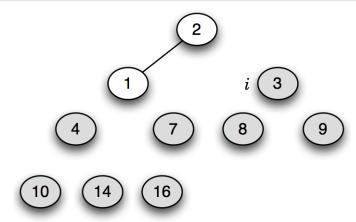


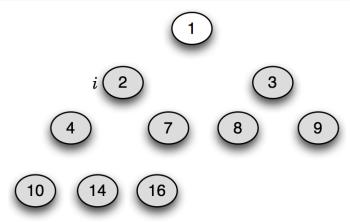




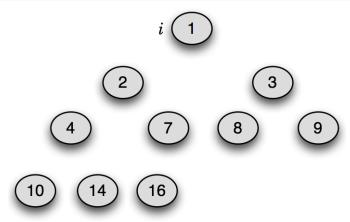


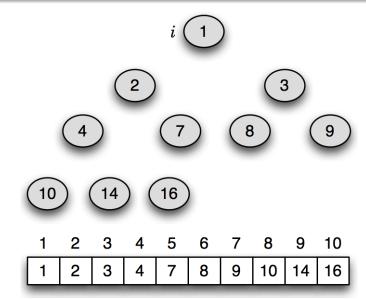






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HEAPSORT algorithm

HEAPSORT(A)

```
times
                                                       cost
    BUILD-MAX-HEAP(A)
    for i \leftarrow length[A] downto 2
3
          do exchange A[1] \leftrightarrow A[i]
              heap-size[A] \leftarrow heap-size[A] - 1
4
              MAX-HEAPIFY (A, 1)
5
```

```
times
                                                        cost
    BUILD-MAX-HEAP(A)
                                                       \Theta(n)
2
    for i \leftarrow length[A] downto 2
3
          do exchange A[1] \leftrightarrow A[i]
              heap-size[A] \leftarrow heap-size[A] - 1
4
              MAX-HEAPIFY (A, 1)
5
```

```
HEAPSORT(A)
```

```
times
                                                         cost
    BUILD-MAX-HEAP(A)
                                                        \Theta(n)
2
    for i \leftarrow length[A] downto 2
                                                        \Theta(1)
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          do exchange A[1] \leftrightarrow A[i]
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HEAPSORT algorithm

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```
times
                                                        cost
    BUILD-MAX-HEAP(A)
                                                       \Theta(n)
2
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                                                        \Theta(1)
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          do exchange A[1] \leftrightarrow A[i]
                                                       \Theta(1) n-1
              heap-size[A] \leftarrow heap-size[A] - 1
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```

```
times
                                                        cost
    BUILD-MAX-HEAP(A)
                                                       \Theta(n)
2
    for i \leftarrow length[A] downto 2
                                                       \Theta(1)
3
          do exchange A[1] \leftrightarrow A[i]
                                                       \Theta(1) n-1
              heap-size[A] \leftarrow heap-size[A] - 1 \Theta(1) n - 1
4
              MAX-HEAPIFY (A, 1)
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```

```
times
                                                           cost
    BUILD-MAX-HEAP(A)
                                                          \Theta(n)
                                                          \Theta(1) n
2
    for i \leftarrow length[A] downto 2
3
           do exchange A[1] \leftrightarrow A[i]
                                                          \Theta(1) n-1
               heap-size[A] \leftarrow heap-size[A] - 1 \quad \Theta(1) \quad n-1
4
               MAX-HEAPIFY (A, 1)
                                                       \Theta(\lg n) \quad n-1
5
```

```
times
                                                            cost
    BUILD-MAX-HEAP(A)
                                                          \Theta(n)
2
    for i \leftarrow length[A] downto 2
                                                           \Theta(1)
3
           do exchange A[1] \leftrightarrow A[i]
                                                          \Theta(1) n-1
               heap-size[A] \leftarrow heap-size[A] - 1 \quad \Theta(1) \quad n-1
4
               MAX-HEAPIFY (A, 1)
                                                        \Theta(\lg n) \quad n-1
5
```

Worst-case analysis

$$T(n) = \Theta(n \lg n)$$

Contents



- Introduction
- Heap data structure
- Heap algorithms
- Heapsort algorithm
- Priority queue
- Conclusion



Definition (Priority Queue)

A priority queue is a data structure for maintaining a set S of elements, each with an associated value called a key. A max-priority queue supports the following operations.

- **1** INSERT(S, x) inserts the element x into the set S. This operation could be written as $S \leftarrow S \cup \{x\}$.
- \bigcirc MAXIMUM(S) returns the element of S with the largest key.
- \odot EXTRACT-MAX(S) removes and returns the element of S with the largest key.
- 4 INCREASE-KEY(S, x, k) increases the value of element x's key to k. Assume $k \ge x$'s current value.

Heap use - priority queue

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- Used in many scheduling applications where jobs or tasks are scheduled according to priority.

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 - Used in many scheduling applications where jobs or tasks are scheduled according to priority.
 - A FIFO queue is a priority queue where the priority is inversely proportional to time of arrival.

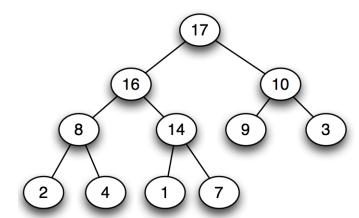
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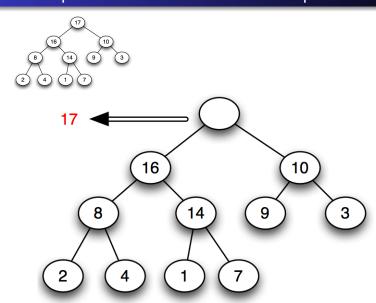
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 - Used in many scheduling applications where jobs or tasks are scheduled according to priority.
 - A FIFO queue is a priority queue where the priority is inversely proportional to time of arrival.
- A LIFO stack is a priority queue where the priority is proportional to time of arrival.

Example of HEAP-EXTRACT-MAX operation



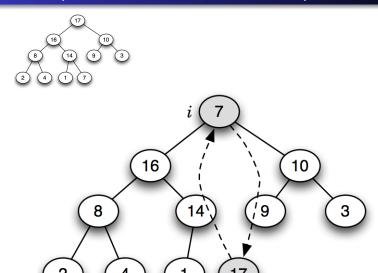
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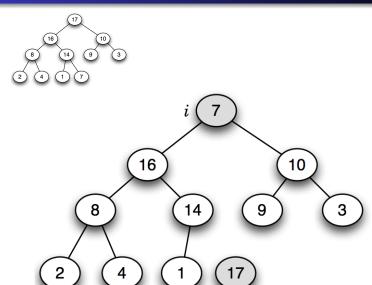


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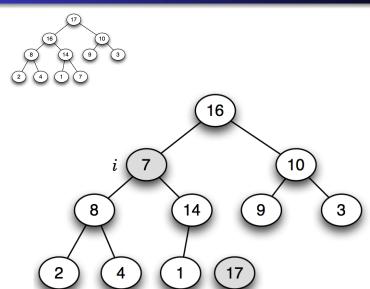


Example of HEAP-EXTRACT-MAX operation



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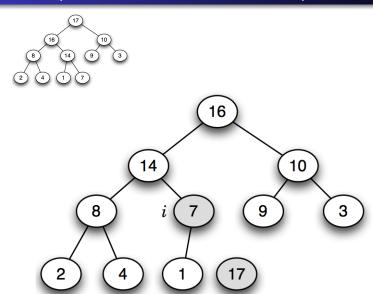
Example of HEAP-EXTRACT-MAX operation



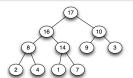
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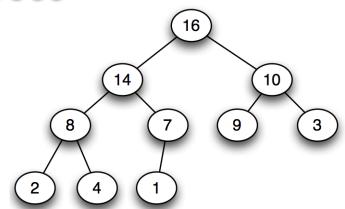
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Example of HEAP-EXTRACT-MAX operation



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cost

EXTRACT-MAX(A)

```
if heap-size[A] < 1
       then error "heap underflow"
3
    max \leftarrow A[1]
   A[1] \leftarrow A[heap-size[A]]
5
   heap-size[A]] \leftarrow heap-size[A] - 1
6
   MAX-HEAPIFY (A, 1)
```

cost

EXTRACT-MAX(A)

```
if heap-size[A] < 1
                                                       \Theta(1)
       then error "heap underflow"
3
    max \leftarrow A[1]
   A[1] \leftarrow A[heap-size[A]]
5
   heap-size[A]] \leftarrow heap-size[A] - 1
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   MAX-HEAPIFY (A, 1)
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cost

EXTRACT-MAX(A)

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if heap-size[A] < 1
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```

cost

EXTRACT-MAX(A)

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if heap-size[A] < 1
                                                        \Theta(1)
                                                        \Theta(1) 1
        then error "heap underflow"
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                                                        \Theta(1) 1
    max \leftarrow A[1]
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    MAX-HEAPIFY (A, 1)
```

HEAP-EXTRACT-MAX algorithm

EXTRACT-MAX(A)

```
times
                                                         cost
    if heap-size[A] < 1
                                                        \Theta(1)
                                                        \Theta(1)
        then error "heap underflow"
3
                                                        \Theta(1) 1
    max \leftarrow A[1]
   A[1] \leftarrow A[heap-size[A]]
                                                        \Theta(1) 1
5
    heap-size[A]] \leftarrow heap-size[A] - 1
6
    MAX-HEAPIFY (A, 1)
```

EXTRACT-MAX(A)

```
times
                                                          cost
    if heap-size[A] < 1
                                                         \Theta(1)
        then error "heap underflow"
                                                         \Theta(1)
3
                                                         \Theta(1)
    max \leftarrow A[1]
    A[1] \leftarrow A[heap-size[A]]
                                                         \Theta(1) 1
5
    heap-size[A]] \leftarrow heap-size[A] - 1
                                                         \Theta(1) 1
6
    MAX-HEAPIFY (A, 1)
```

HEAP-EXTRACT-MAX algorithm

EXTRACT-MAX(A)

```
times
                                                           cost
                                                          \Theta(1)
    if heap-size[A] < 1
                                                          \Theta(1)
        then error "heap underflow"
3
                                                          \Theta(1)
    max \leftarrow A[1]
                                                          \Theta(1)
   A[1] \leftarrow A[heap-size[A]]
5
   heap-size[A]] \leftarrow heap-size[A] -1
                                                          \Theta(1) 1
6
    MAX-HEAPIFY (A, 1)
                                                       \Theta(\lg n)
```

Worst-case analysis

$$T(n) = \Theta(\lg n)$$

Conclusion

- Heap plays a very important role in many algorithms, either used directly or as part of a priority queue implementation.
- If the size of a queue is known in advance, then an array representation (using a fixed size array) provides compact storage coupled with fast operations.
- Even if the size of the heap is not known in advance, "intelligent" resizing can still provide good benefits.
- Heapsort is a natural application of Heap with two very important properties $\Theta(n \lg n)$ complexity, and in-place sorting.