

STAT540 Stat. Comp. Project Presentation

A Comparison between Likelihood-free MCMC & Likelihood-free Sequential Monte Carlo

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Pseudocode of ABC MCMC

- 1 Initialize $\theta_i, i = 0$
- 2 Propose θ^* according to a proposal distribution $q(\theta|\theta_i)$
- 3 Simulate a dataset x^* from $f(x|\theta^*)$
- 4 If $\rho(x_0, x^*) \leq \epsilon$, go to 5, otherwise set $\theta_{i+1} = \theta_i$ and go to 6
- 5 Set $\theta_{i+1} = \theta^*$ with probability

$$\alpha = \min \left\{ 1, \frac{\pi(\theta^*)q(\theta_i|\theta^*)}{\pi(\theta_i)q(\theta^*|\theta_i)} \right\}$$

and $\theta_{i+1} = \theta_i$ with probability $1 - \alpha$

- 6 Set $i = i + 1$, go to 2.

Potential problem of ABC MCMC

Simulation may get stuck in low probability region and the Markov chain stops moving for a really long time. For example,

proposal and prior are both chosen to be multivariate normal

- For threshold $\epsilon = 2$, the chain may stop moving for 500 steps
- For threshold $\epsilon = 0.5$, the chain may stop moving for 10,000 steps

Pseudocode of ABC SMC

- 1 Initialize threshold schedule $\epsilon_1 > \dots > \epsilon_T$
- 2 Set $t = 1$
For $i = 1, 2, \dots, N$
 - Simulate $\theta_i^{(1)} \sim p(\theta)$ and $x \sim p(x|\theta_i^{(1)})$ until $\rho(x, x_{\text{obs}}) < \epsilon_1$
 - Set $w_i = 1/N$
- 3 For $t = 2, \dots, T$
For $i = 1, 2, \dots, N$
 - Repeat:
Pick θ_i^* from the $\theta_j^{(t-1)}$'s with probabilities $w_j^{(t-1)}$, draw
 $\theta_i^{(t)} \sim K_t(\theta_i^{(t)}|\theta_i^*)$ and $x \sim p(x|\theta_i^{(t)})$; until $\rho(x, x_{\text{obs}}) < \epsilon_t$
 - Compute new weights as

$$w_i^{(t)} \propto \frac{p(\theta_i^{(t)})}{\sum_j w_j^{(t-1)} K_t(\theta_i^{(t)}|\theta_j^{(t-1)})}$$

Normalize $w_i^{(t)}$ over $i = 1, 2, \dots, N$

Pseudocode of ABC SMC with Adaptive Weights

- 1 Initialize threshold schedule $\epsilon_1 > \dots > \epsilon_T$
- 2 Set $t = 1$
 - For $i = 1, 2, \dots, N$
 - Simulate $\theta_i^{(1)} \sim p(\theta)$ and $x \sim p(x|\theta_i^{(1)})$ until $\rho(x, x_{\text{obs}}) < \epsilon_1$
 - Set $w_i = 1/N$
- 3 For $t = 2, \dots, T$
 - Compute data based weights $v_i^{(t-1)} \propto w_i^{(t-1)} K_{x,t}(x_{\text{obs}}|x_i^{(t-1)})$
 - Normalize weights $v_i^{(t-1)}$ over $i = 1, 2, \dots, N$
 - For $i = 1, 2, \dots, N$
 - Repeat:
 - Pick θ_i^* from the $\theta_j^{(t-1)}$'s with probabilities $v_j^{(t-1)}$, draw $\theta_i^{(t)} \sim K_{\theta,t}(\theta_i^{(t)}|\theta_i^*)$ and $x \sim p(x|\theta_i^{(t)})$; until $\rho(x, x_{\text{obs}}) < \epsilon_t$
 - Compute new weights as

$$w_i^{(t)} \propto \frac{p(\theta_i^{(t)})}{\sum_j v_j^{(t-1)} K_{\theta,t}(\theta_i^{(t)}|\theta_j^{(t-1)})}$$

Normalize $w_i^{(t)}$ over $i = 1, 2, \dots, N$

Different Choices of Transition Kernel

- Component-wise perturbation kernels
- Multivariate normal perturbation kernels
- local perturbation kernels
 - Multivariate normal kernel with M nearest neighbors
 - Multivariate normal kernel with optimal covariance matrix
 - Perturbation kernel based on the Fisher information for model defined by ODE/SDE

Simulation Results

Average Number of Simulation Steps per Accepted Particle:

	ϵ_1	ϵ_2	ϵ_3	ϵ_4	ϵ_5	Total
ABC SMC	54	103	1436	738	524	2855
ABC SMC AW	52	53	123	364	542	1134
ABC SMC OLCM	1	153	1479	897	467	2997

$$N = 100, \quad \epsilon = (200, 100, 10, 2, 1)^T$$

Simulation Results

Average Number of Simulation Steps per Accepted Particle:

	ϵ_1	ϵ_2	ϵ_3	ϵ_4	ϵ_5	Total
ABC SMC	265	490	9726	4112	2408	17001
ABC SMC AW	262	259	818	2356	2120	5815
ABC SMC OLCM	1	728	7482	3931	2016	14158

$$N = 500, \quad \epsilon = (200, 100, 10, 2, 1)^T$$

Simulation Results

Change the parameter setting and evaluate the performance in terms of L^2 norm error:

- True parameter: $\theta = (1, -3, 5)^T$
- Threshold schedule: $\epsilon = (2, 0.5, 0.025)^T$
- Simulate $n = 50$ independent runs with particle number $N = 100$ and compute the average L^2 -norm errors

The L^2 differences of three algorithms are:

$$\text{diff}_{SMC} = 0.862, \quad \text{diff}_{AW} = 0.853, \quad \text{diff}_{OLCM} = 0.851$$

Boxplots for Estimated Parameter Moments

