Inferring Likelihoods and Climate System Characteristics from Climate Models and Multiple Tracers

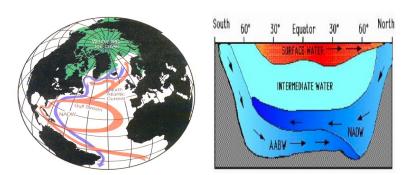
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Motivation

- Example of climate change: potential collapse of the Atlantic meridional overturning circulation (AMOC), results in disruptions in the equilibrium state of the climate.
- An AMOC collapse may result in drastic changes in temperatures and precipitation patterns.

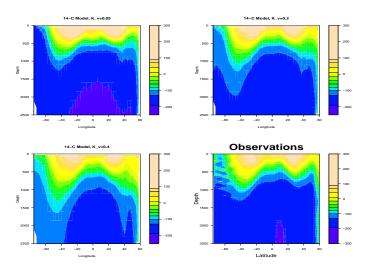


(plots: Rahmstorf (Nature, 1997) and Behl and Hovan)

Overview of Statistical Problem

- ► **Goal**: Infer important climate characteristics (parameters) that drive major climate systems, and hence AMOC.
- ▶ AMOC affected by vertical diffusivity (K_{ν}), latter cannot be measured directly.
- ▶ Two sources of (indirect) information about K_{ν}
 - ► Observations: ¹⁴C and CFC11 collected in the 1990s (latitude, longitude, depth), zonally averaged.
 - Output from complex climate models at 6 values of K_{ν} .
- Challenges
 - ▶ No direct connection between observations and climate parameter, need to rely on sparse climate model runs.
 - Large data sets: both observations and climate model output.
 - Combining information from multiple spatial fields in a flexible manner (multivariate spatial data).

¹⁴C Observations and Model Output



Bottom right: observations, Other plots: model output at different K_V values. Latitude: 80 S-60 N, depths:0-3000m.

Statistical Inference

- Notation: Z(s): physical observations, Y(s, θ): model output at location s, and calibration parameter θ. Y and Z are spatial fields.
- ► Emulation of climate model (Sacks et al, 1989): replace complex model with simple stochastic model.
- Computer model calibration: Kennedy & O'Hagan (2001), Sanso et al. (2008) in the context of climate models, etc.
- ▶ Data Sources: Observations for ¹⁴C/CFC11: Z₁, Z₂ (locations at S).
- ▶ Climate model runs at several values of θ : \mathbf{Y}_1 , \mathbf{Y}_2 .
- ▶ **Goal**: Inference for climate parameter θ .

Our Approach

- Two stage approach to obtain posterior of θ: (i) model relationship between Z and θ via model output Y and (ii) Use observations Z to infer θ.
- ▶ Model **Y** (model output) as a Gaussian process (emulator): $\mathbf{Y} \mid \beta, \boldsymbol{\xi} \sim \mathcal{N}(\mu_{\boldsymbol{\beta}}(\boldsymbol{\theta}), \Sigma(\boldsymbol{\xi})).$
- \triangleright β : regression parameters, ξ : covariance parameters.
- η(Y, θ) (a random variable) is the prediction at a new θ and locations S; obtained by using the standard kriging framework with a multivariate normal distribution.
- ▶ $\mathbf{Z} = \eta(\mathbf{Y}, \theta) + \delta(\mathbf{S}) + \epsilon$ where ϵ is observation error and $\delta(\mathbf{S})$ is model discrepancy.
- ▶ Inference on θ performed using MCMC.

Bivariate Conditional Hierarchical Model

- ► How can we combine information from multiple tracers (14 C, CFC11) in a flexible manner to infer K_V ?
- Model (Y₁, Y₂) as a hierarchical model: Y₁|Y₂ and Y₂ as Gaussian processes. (following Royle and Berliner (1999)).

$$\mathbf{Y}_1 \mid \mathbf{Y}_2, \boldsymbol{\beta}_1, \boldsymbol{\xi}_1, \boldsymbol{\gamma} \sim \textit{N}(\boldsymbol{\mu}_{\boldsymbol{\beta}_1}(\boldsymbol{\theta}) + \mathbf{B}(\boldsymbol{\gamma})\mathbf{Y}_2, \boldsymbol{\Sigma}_{1.2}(\boldsymbol{\xi}_1))$$

▶
$$\mathbf{B}(\gamma)$$
 is a matrix to describe relationship between \mathbf{Y}_1 and

Y₂, we assume a piecewise linear relationship.
Use predictive distribution η(Y, θ) (for Y = (Y₁ Y₂)) to

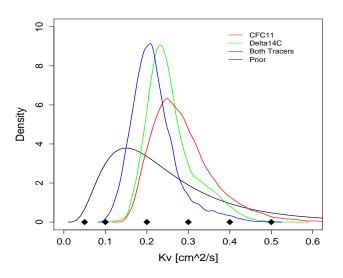
 $\mathbf{Y}_2 \mid \boldsymbol{\beta}_2, \boldsymbol{\xi}_2 \sim \mathcal{N}(\boldsymbol{\mu}_{\boldsymbol{\beta}_2}(\boldsymbol{\theta}), \boldsymbol{\Sigma}_2(\boldsymbol{\xi}_2))$

- obtain probability model connecting $\mathbf{Z} = (\mathbf{Z}_1 \ \mathbf{Z}_2)$ to θ . $\mathbf{Z} = \eta(\mathbf{Y}, \theta) + \delta(\mathbf{S}) + \epsilon$, confounding between δ and θ .
- ▶ We need to model $\delta(\mathbf{S})$ appropriately, not doing so may result in overfitting θ . Use GP model for unknown δ .

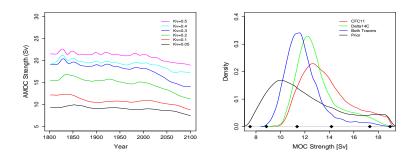
Computational Issues

- Matrix computations are O(N³), where N is the number of observations (Data size: 3706(observations); 5926(model) per tracer, could be much larger).
- Used reduced rank approach based on kernel mixing (Higdon, 1998): continuous process created by convolving a discrete white noise process with a kernel function.
- ▶ Write covariance matrix as: (A + KCK^T), K kernel matrix with rank J=196 (Cressie and Johannesson, 2008).
- ▶ Special structure + Sherman-Woodbury-Morrison identity used to reduce matrix computations to dimension $J \times J$.
- Unlike Higdon (1998), we do not estimate the knot process. Parameter space is therefore greatly reduced, and computations are simplified.

Inference Based on Both Tracers



AMOC Strength Projections for K_{ν} Values



Left: AMOC strength projections in Sv, increasing with K_v . Right: Distribution of projected AMOC strength(Sv) in 2100 (left) given posterior distributions of K_v for both single tracers and multiple tracers.

Discussion

- Advantages of our approach:
 - Statistical inferential approach to solve an important climate science problem.
 - Flexible bivariate model to combine information from multiple tracers.
 - Improve computational tractability enabling analysis of larger data sets.
 - Modularization (e.g. Liu et al., 2009): reduce computational issues and identifiability problems.

Potential issues:

- Possible over-fitting in first stage (ML estimation).
- Confounding between calibration parameter and model discrepancy.
- May be difficult to extend to more than two spatial fields.

Key References

- ▶ Royle, J. A. and Berliner, L.M. (1999), A Hierarchical Approach to Multivariate Spatial Modeling and Prediction, Journal of Agricultural, Biological, and Environmental Statistics.
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- Sanso, B. and Forest, C.E. and Zantedeschi, D. (2008), Inferring Climate System Properties Using a Computer Model, *Bayesian Analysis*.
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