# GLMM Lasso for Highdimensional Data

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#### GLMM – problem definition

Likelihood for GLM is:

$$f(y_i|\theta_i,\phi) = \exp\left(\phi^{-1}(y_i\cdot\theta_i - \xi(\theta_i)) + c(y_i,\phi)\right)$$

where  $\phi$  and  $\theta_i$  are model parameters. For GLMM:

$$h(\theta_i) = \mu_i = \mathbb{E}[y_i|b_i] = g^{-1}(x_i\beta + z_ib_i)$$
 where  $b_i \sim N(0, Q^{-1})$ 

For GLMM, since we have unobserved random effect, the augmented likelihood is:

$$f(y_i; \theta_i, \phi, Q) = \int f(y_i | \theta_i, \phi, b_i) \cdot f(b_i | Q) db_i$$

This is intractable because we have no close form solution to the integral!

#### GLMM – solutions

#### Bayesian inference:

- Variational Bayesian Inference (a.k.a. Variational Bayes) (VBI)
- MCMC with auxiliary variables (MCMC)

#### ML estimation:

- Monte Carlo EM (MC-EM)
- Laplace approximation (LA)

#### Variational Bayesian Inference

- We want to know  $f(\theta|y) = \frac{f(y|\theta)f(\theta)}{f(y)}$ , but:
  - $\circ$  don't know the normalizing constant f(y)
  - $\circ$  Computing  $f(y|\theta)$  is also very difficult (e.g., GLMM)
- Let's use a proposal distribution  $q(\theta)$  to approximate  $f(\theta|y)$ .
- A good proposal distribution would be to minimize the KL divergence

$$q^*(\boldsymbol{\theta}) = \min_{q(\boldsymbol{\theta})} KL(q(\boldsymbol{\theta})||f(\boldsymbol{\theta}|y))$$

- The best solution is when  $q(\theta) = f(\theta|y)$ .
- Simplifying the KL divergence, we find that

$$q^*(\boldsymbol{\theta}) = \min_{q(\boldsymbol{\theta})} KL(q(\boldsymbol{\theta})||f(\boldsymbol{\theta}|y)) = \min_{q(\boldsymbol{\theta})} KL(q(\boldsymbol{\theta})||f(\boldsymbol{\theta},y))$$

• Therefore, the best solution is converted to when  $q(\theta) = f(y|\theta)f(\theta)$ , but this is still intractable.

## Variational Bayesian Inference (cont.)

- What if we assume  $q(\theta) = \prod_i q(\theta_i)$  (mean field theory)
- Then we have

$$q^*(\theta_i) = \min_{q(\theta_i)} KL(q(\boldsymbol{\theta})||f(\boldsymbol{\theta}, y))$$

where:

$$\begin{split} & \min_{q(\theta_i)} KL\big(q(\boldsymbol{\theta})||f(\boldsymbol{\theta},y)\big) \\ &= \min_{q(\theta_i)} \int \prod_i q(\theta_i) \log \frac{\prod_i q(\theta_i)}{f(\boldsymbol{\theta},y)} d\boldsymbol{\theta} \\ &= \min_{q(\theta_i)} \int \prod_i q(\theta_i) \log \prod_i q(\theta_i) d\boldsymbol{\theta} - \int \prod_i q(\theta_i) \log f(\boldsymbol{\theta},y) d\boldsymbol{\theta} \\ &= \min_{q(\theta_i)} \int q(\theta_i) \log q(\theta_i) d\theta_i - \int q(\theta_i) \mathbb{E}_{q(\theta_{-i})} [\log f(\boldsymbol{\theta},y)] d\theta_i \\ &= \min_{q(\theta_i)} KL\big(q(\theta_i)||\exp\big(\mathbb{E}_{q(\theta_{-i})}[\log f(\boldsymbol{\theta},y)]\big)\big) \end{split}$$

Therefore, following the mean field theory, we want to find  $\theta_i$ ,  $i=1,...,|\theta|$ :  $q(\theta_i) \propto \exp\left(\mathbb{E}_{q(\theta_{-i})}[\log f(\boldsymbol{\theta},y)]\right)$ 

where  $q(\theta_i)$  should be a valid distribution.

## Variational Bayesian Inference (cont.)

General guidance for finding  $q(\theta_i)$ :

- Following  $q^*(\theta_i) = \min_{q(\theta_i)} KL(q(\theta)||f(\theta,y))$ . Find  $q^*(\theta_i)$  directly using conjugate distribution.
- Following  $q^*(\theta_i) \propto \exp(\mathbb{E}_{q(\theta_{-i})}[\log f(\boldsymbol{\theta}, y)])$ . Find  $q^*(\theta_i)$  using some tricks.
- In BI framework for GLMM, [1] gives a graphical model:

$$q^*(\lambda,\beta,Q,b) = \min_{q} KL(q(\lambda,\beta,Q,b)||f(\lambda,\beta,Q,b,y))$$

del:  $\alpha_{\lambda}$   $\beta_{\lambda}$   $s_{Q}$   $V_{Q}$  Wishart Q  $u \times u$   $MVN(\mathbf{0}, Q^{-1})$  b  $m \times u$  Exponential Family

[1] D. T. Tung, M.-N. Tran, and T. M. Cuong, "Bayesian adaptive lasso with variational Bayes for variable selection in high-dimensional generalized linear mixed models," *Commun. Stat.-Simul. Comput.*, pp. 1–14, 2018.

### Solving GLMM with VBI

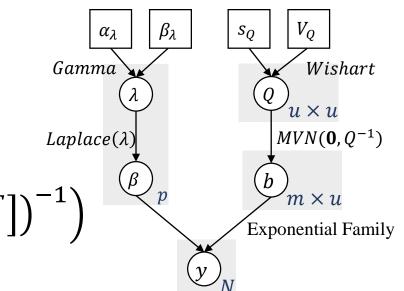
Following mean field theory, we have:

• 
$$q^*(Q) \sim Wishart \left( s_Q + m, \left( V_Q^{-1} + \sum_{i=1}^m \mathbb{E}_{q(b)} [b_i \cdot b_i^T] \right)^{-1} \right)$$

- $q^*(\lambda) \sim Gamma(\alpha_{\lambda} + 1, \beta_{\lambda} + \mathbb{E}_{q(\beta)}[|\beta|])$
- $q^*(b) \propto \exp \mathbb{E}_{-q(b)}[\log f(y|b,\beta)f(b|Q)]$
- $q^*(\beta) \propto \exp \mathbb{E}_{-q(\beta)}[\log P(y|b,\beta)P(\beta|\lambda)]$

For q(b) and  $q(\beta)$ , I use gaussian approximation, thus:

$$\begin{split} &q(b_i) \sim MVN\left(b_i^*, -\left(Z_i^T \cdot \operatorname{Diag}\{\zeta''\left(\eta_i(b_i^*)\right) \times_e \eta_i''(b_i^*)\} \cdot Z_i - \mathbb{E}_{q(Q)}[Q]\right)^{-1}\right) \\ &q(\beta) \sim MVN\left(\beta^*, -\left(X^T \cdot \operatorname{Diag}\{\zeta''\left(\eta_i(\beta^*)\right) \times_e \eta_i''(\beta^*)\} \cdot X\right)^{-1}\right) \end{split}$$



#### Generalized EM algorithm

In EM algorithm, for iteration t, we do the following:

$$f(y|\theta^{(t)}) = \int f(y,z|\theta^{(t)})dz = \int \frac{f(y,z|\theta^{(t)})}{q^{(t)}(z)}q^{(t)}(z)dz$$

where  $q^{(t)}(z) = f(z|y, \theta^{(t)})$ . Let's continue to use q(z), then we have:

$$f(y|\theta^{(t)}) = \mathbb{E}_{q^{(t)}(z)} \left[ \frac{f(y,z|\theta^{(t)})}{q^{(t)}(z)} \right]$$

Assume that we want to maximize the log-likelihood, then:

$$l(\theta^{(t)}; y) = \max_{\theta} \log f(y|\theta^{(t)}) \ge \mathbb{E}_{q^{(t)}(z)} \left[ \log \frac{f(y, z|\theta^{(t)})}{q^{(t)}(z)} \right]$$

$$= \int q^{(t)}(z) \log \frac{f(z|y, \theta^{(t)})f(y|\theta^{(t)})}{q^{(t)}(z)} dz$$

$$= \log f(y|\theta^{(t)}) - KL(q^{(t)}(z)||f(z|y, \theta^{(t)}))$$

Therefore, when  $q^{(t)}(z) = f(z|y, \theta^{(t)})$ , we have  $KL(q^{(t)}(z)||f(z|y, \theta^{(t)})) = 0$ , which is the optimal solution.

#### Generalized EM algorithm

For the E-step, what we exactly want is to compute:

$$f(y|\theta^{(t)}) = \mathbb{E}_{q^{(t)}(z)} \left[ \frac{f(y, z|\theta^{(t)})}{q^{(t)}(z)} \right]$$

This can be achieved by two ways:

- If we can draw samples from  $q^{(t)}(z)$ , then we don't need to know the form of  $q^{(t)}(z)$ . This results in MC-EM algorithm.
- If we need the close form distribution of  $q^{(t)}(z)$ , then our goal is:

$$q^{(t)}(z) = \min_{q(z)} KL\left(q(z)||f(z|y,\theta^{(t)})\right)$$

This results in VBI.

Generalized EM algorithm:

E-step: solve 
$$q^{(t)}(z) = \min_{q(z)} KL\left(q(z)||f(z|y,\theta^{(t)})\right)$$
  
M-step: solve  $\theta^{(t+1)} = \max_{\theta} \mathbb{E}_{q^{(t)}(z)} \left[\frac{f(y,z|\theta^{(t)})}{q^{(t)}(z)}\right]$ 

M-step: solve 
$$\theta^{(t+1)} = \max_{\theta} \mathbb{E}_{q^{(t)}(z)} \left[ \frac{f(y,z|\theta^{(t)})}{q^{(t)}(z)} \right]$$

# Solving GLMM with MCEM [2]

We want to optimize the following objective function:

$$\hat{\theta} = \max_{\theta} \sum_{i=1}^{m} \log \int_{\mathbb{R}^{q}} f(y_{i}|\beta, b_{i}, Q) f(b_{i}|Q) \mathrm{d}b_{i} - \lambda \big| |\beta| \big|_{1}$$
 E-step: we want to solve 
$$\mathbb{E}_{b_{i}} \left[ \log \frac{f(y_{i}|\theta_{i}, b_{i}) f(b_{i}|Q)}{f(b_{i}|\theta_{i}^{(t)}, y_{i})} |\theta_{i}^{(t)}, y_{i} \right]$$
 M-step: 
$$\hat{\theta}^{(t+1)} = \max_{\theta} \sum_{i=1}^{m} \mathbb{E}_{b_{i}} \left[ \log \frac{f(y_{i}|\theta_{i}, b_{i}) f(b_{i}|Q)}{f(b_{i}|\theta_{i}^{(t)}, y_{i})} |\theta_{i}^{(t)}, y_{i} \right] - \lambda \big| |\beta| \big|_{1}$$

For E step, I apply the Metropolis-Hasting algorithm, where

$$f(b_i|\beta^{(t)}, Q^{(t)}, y_i) = \frac{f(y_i|b_i, \beta^{(t)})f(b_i|Q^{(t)})f(\beta^{(t)})}{f(y_i, \beta^{(t)}, Q^{(t)})}$$

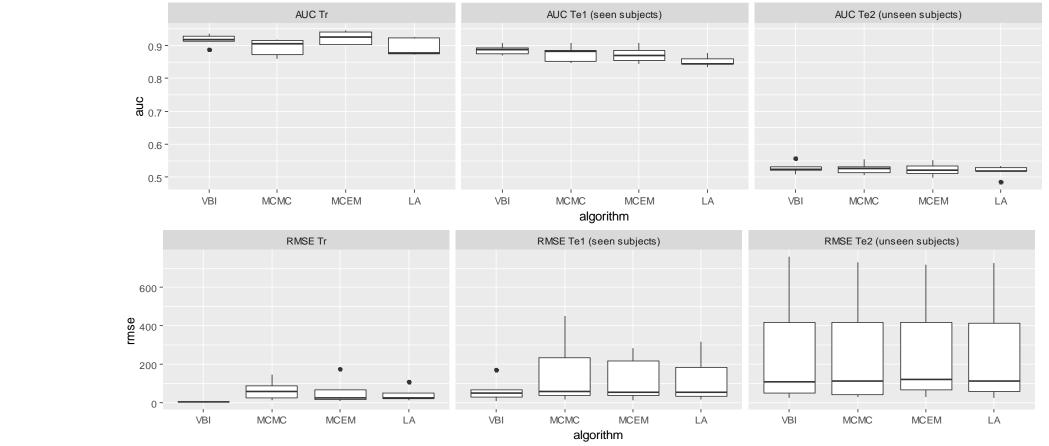
C. E. McCulloch, "Maximum likelihood algorithms for generalized linear mixed models," *J. Am. Stat. Assoc.*, vol. 92, no. 437, pp. 162–170, 1997.

#### Simulation study

- Logistic regression and Poisson regression.
- BI: VBI and MCMC; MLE: MC-EM and LA
- Simulation process:
  - Generate  $\beta$ , X, Z.
  - For each subject, generate  $b_i \sim N(0, Q^{-1})$
  - Compute  $\mu_{it} = g^{-1}(x_{it}\beta + z_{it}b_i)$
  - Simulate  $y_{it}$  with mean  $\mu_{it}$
  - Simulate two test sets. One is to reuse  $b_i$ , assuming predicting the outcome for existing subjects; one is only reusing  $\beta$  and re-simulate  $b_i$ , assuming predicting the outcome for new subjects.
- Evaluation metrics:
  - AUC for Logistic Reg, RMSE for Poisson Reg
  - Runtime
  - Overall coverage rate/coverage rate for sparsity

#### Results

Algorithm	Runtime/ iteration	AUC for $Tr$	AUC for $Te_1$	AUC for $Te_2$	Coverage	Coverage sparse
VBI	93.03	0.977	0.824	0.572	0.397	1.000
МСМС	224.74/100	1.000	0.879	0.573	0.064	0.089
MCEM	215.23	1.000	0.825	0.536	1.000	1.000
LA	932.46	0.962	0.801	0.550	1.000	1.000



#### Conclusion

- In all cases, algorithms based on BI model is faster than MLE
- For low-dimensional case, VBI > MC-EM > MCMC > LA
- For high-dimensional case, algorithms based on BI model outperform MLE
- MLE usually has larger variance.
- Difficulty of derivation and implementation: