

# Introduction to Statistical Methods for Uncertainty Quantification in the Assessment of Climate Change Risk

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# What This Talk is About

- ▶ I will explain how climate change risk assessment cannot take place without language and methods from the fields of probability and statistics.
- ▶ The focus of the talk will be on climate models and the importance of uncertainty quantification when climate projections are made using models.
- ▶ As required, will review basics of Bayesian inference and Markov chain Monte Carlo.

# Our Research Group

## **SCRiM Group: Interface of Earth System Analysis and Uncertainty Quantification**

- ▶ Faculty: Chris Forest, Murali Haran, Klaus Keller, Dave Pollard
- ▶ Research associates/postdocs: Patrick Applegate, Rob Nicholas, Roman Olson
- ▶ Graduate students: Saksham Chandra, Won Chang, Yawen Guan, Josh Magerman
- ▶ Undergraduate students: Evan Bittner, Kira White

# Climate Change and Risk



Polder dyke, Netherlands (from John Elk III, [lonelyplanet.com](http://lonelyplanet.com))

# Risk

- ▶ We need probability/statistics to define and quantify risk.
- ▶ Risk associated with an action = expected cost (or “loss”) for that action, “expected” = weighted average
  - ▶ Sum over { **probability of outcome**  $\times$  cost of that outcome }
- ▶ For a particular policy, example of outcomes:
  - ▶ strength of the Atlantic Meridional overturning circulation or “AMOC”: weakening? stable?
  - ▶ global sea level rise: 2 metres? more? less ?
- ▶ To study economic impacts: relate outcome to impact.  
Example: sea level rise of  $x$  metres will cost \$ $y$ .

Summary: To be useful for decision-making, we need probabilities associated with our climate projections.

# Learning about Risk

- ▶ What is probability of sea level rise of 2m. in 2100 if:
  - (A) Carbon emissions grow at same rate ("business as usual")
  - (B) Carbon emissions are controlled by a policy
- ▶ Of particular interest: low probability-high impact events. For example sea level rise of 2 metres may be a relatively low probability event but extremely expensive. "Tails" of probability distributions are important.

How do we learn about the probability of each outcome while accounting for uncertainties?

# Learning about Risk through Statistical Methods

Risk assessment based on climate projections involves:

- (1) Combining information from climate models and observations.
- (2) Uncertainty quantification: for honest assessment of risk, critical to incorporate information about how certain or uncertain we are about various aspects of the climate projections.
- (3) Addressing technical challenges related to the size of the data sets involved.

Novel statistical methods have been/are being developed to address the above issues.

# What Do We Mean by “Uncertainties?”

Types of uncertainty:

- (1) Aleatoric: stochasticity (randomness) in the universe.  
Example: if we knew a coin was fair, still would not know if a particular toss would yield heads or tails.
- (2) Epistemic: uncertainty regarding our knowledge. Example: the weight of a particular coin (nickel/5c) is fixed but our knowledge about the weight is uncertain. If we knew the weights of 20 other coins (nickel/5c), we could make a better guess (reduced uncertainty).

Statistical models may be used to account for both.



# Climate Model Uncertainties

- ▶ Model projections are uncertain as models can never fully describe the climate system.
- ▶ Boundary or initial condition uncertainty.
- ▶ “Forcings” uncertainty, e.g. uncertainty about emissions.
- ▶ Observations may have measurement errors, may not be available everywhere (interpolation uncertainty).
- ▶ **Parameter uncertainty:** parameters (“dials” in the computer model) may be uncertain. The value of the parameter may affect climate projections.

# Quantifying Uncertainty

- ▶ Uncertainty is not the same as not knowing.
- ▶ Describing uncertainties carefully is central to the scientific enterprise. “Without uncertainty quantification, it is easy to dismiss climate (computer) models.” – A. O’Hagan.

# A Statistical Challenge in Climate Science

Focus here on one important challenge:

- ▶ Characterizing values for unknown or uncertain parameters ( $\theta$ ) of a climate model is called **calibration**.
- ▶ Informally: done by comparing climate model output (for various parameter values) to observations.
- ▶ Statistical model in two stages:
  1. Build an “emulator”,  $\eta(\theta)$  that captures relationship between  $\theta$  and model output at  $\theta$ , including for  $\theta$  values at which model runs are not available
  2. Relate observations  $Z$  to the parameters  
 $Z = \eta(\theta^*) + \delta(\theta^*) + \epsilon$ , where  $\delta$  is model-data discrepancy,  $\epsilon$  is measurement error,  $\theta^*$  is “fitted value” of parameter
- ▶ Can study  $\delta$  and  $\epsilon$ , sources of uncertainty
- ▶ Observations, model runs in the form of large spatial data

# Statistical Methods

A Bayesian approach is useful:

- ▶ **Prior distribution** plausibility of various parameter ( $\theta$ ) values: distribution  $p(\theta)$
- ▶ **Probability model** (built using climate model runs) connects parameters to observations, accounting for model-data discrepancy.
- ▶ **Posterior distribution** plausibility of various values of the parameters *given* the data, integrating all the information and sources of uncertainty

Summary: Statistical models (Gaussian processes), data reduction (principal components), matrix theory (patterned covariances), inferential algorithms (Markov chain Monte Carlo)

# Computing for Bayesian Inference

1. Statistical model is fit to  $\mathbf{Y} = (Y(\theta_1), \dots, Y(\theta_p))$ .
  - ▶ Maximum likelihood: optimize parameters ( $\xi$ ) of Gaussian process model likelihood function,  $\mathcal{L}(\mathbf{Y}; \xi)$ . Result:  $\hat{\xi}$
2. Denote observations by  $\mathbf{Z}$ . Obtain a probability model from above + discrepancy. Result: likelihood  $\mathcal{L}_{\hat{\xi}}(\mathbf{Z}; \theta, \gamma)$ 
  - ▶  $\theta$ : calibration parameters,  $\gamma$ : discrepancy parameters
  - ▶ Bayesian inference based on posterior distribution,  
$$\pi(\theta \mid \mathbf{Z}) \propto \mathcal{L}_{\hat{\xi}}(\mathbf{Z}; \theta, \gamma)p(\theta, \gamma),$$
  - ▶ Above conditional distribution contains all information about  $\theta, \gamma$ , incorporating uncertainties
  - ▶ Markov chain Monte Carlo methods: sampling approach used to learn about complicated distribution  $\pi(\theta, \gamma \mid \mathbf{Z})$ .
  - ▶ Learn about climate model parameters  $\theta$  and discrepancy.

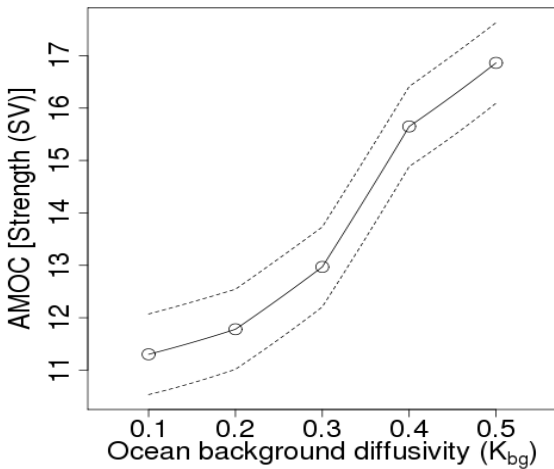
# The AMOC and Climate Change

One concrete example:

- ▶ Atlantic Meridional Overturning Circulation (AMOC):  
AMOC heat transport makes a substantial contribution to the moderate climate of Europe (cf. Bryden et al., 2005)
- ▶ Any slowdown in the overturning circulation may have major implications for climate change
- ▶ AMOC projections from climate models.

A major source of uncertainty about the AMOC is due to uncertainty about  $K_{bg}$ : model parameter that quantifies the intensity of vertical mixing in the ocean.

## AMOC and Model Parameter $K_{bg}$



## Learning about $K_{bg}$

- ▶ Two sources of indirect information:
  - ▶ **Observations** of ocean temperatures.
  - ▶ **Climate model output** at different values of  $K_{bg}$  from University of Victoria (**UVic**) Earth System Climate Model (Weaver et. al., 2001).
- ▶ Models with different  $K_{bg}$  values result in markedly different ocean temperatures. Comparing observations to model output allows us to learn about  $K_{bg}$ .

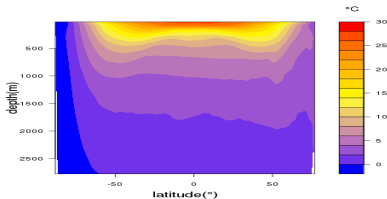


# Computational/technical challenges

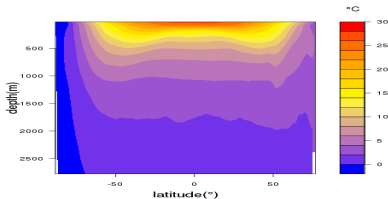
- ▶ We have 3D spatial observations and climate model output.
- ▶ Using rigorous statistical methods can be prohibitively expensive for such data. Previous methods rely on aggregation. The effect of aggregation on uncertainties is not well understood.
- ▶ Our contributions:
  1. New statistical methods and algorithms that allow us to work with the entire 3D data set without relying on aggregation.
  2. Comparison of results with unaggregated versus aggregated data: we can reduce uncertainties by using unaggregated data.

# Ocean Temperatures

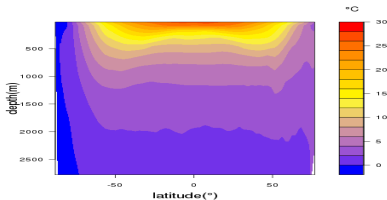
$K_{bg}$  of 0.1



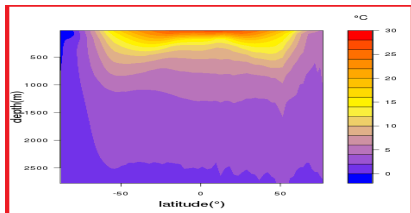
$K_{bg}$  of 0.2



$K_{bg}$  of 0.3

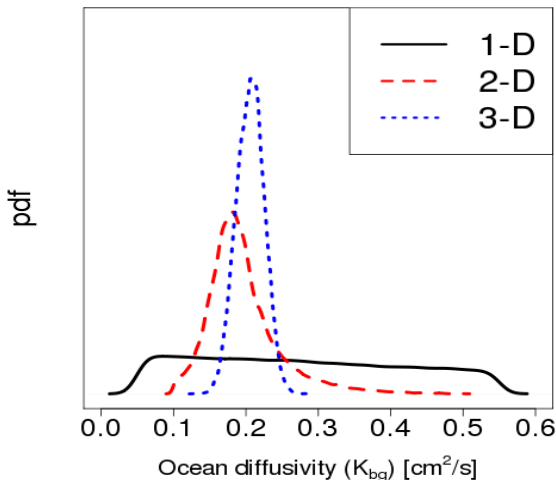


Observations



(2D versions of 3D data)

## Results for $K_{bg}$ Inference



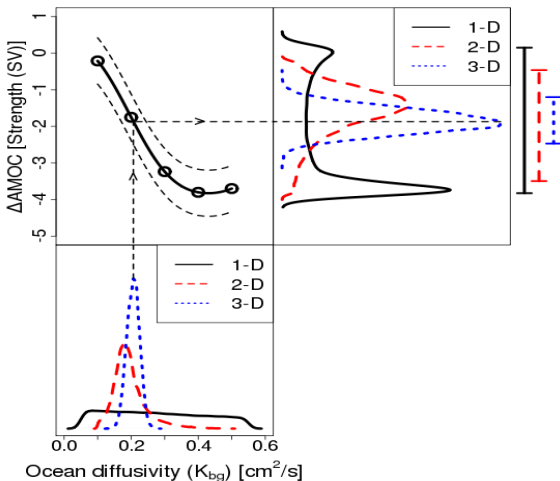
(from Chang, Haran, Olson and Keller, 2013)

## Results for $K_{bg}$ Inference: Conclusions

- ▶ Our computationally efficient methods allow us to compare results from using aggregated (1D versus 2D) versus unaggregated (3D) data. Clear value:
  - ▶ Sharpest inference is based on unaggregated (3D) data.
  - ▶ Inference with 3D data is also robust to varying prior information; not so robust when using 2D or 1D data.
  - ▶ This results in sharper and more robust projections . . .

Chang, Haran, Olson, Keller (2013)

# MOC Projections for 2100 Using Inferred $K_{bg}$



(from Chang, Haran, Olson and Keller, 2013)

## Concluding Thoughts

- ▶ Without probability and statistics, it is not possible to quantify risk. Uncertainty quantification is central for science and policy
- ▶ General statistical tools we have developed: useful for projections of the AMOC using unaggregated data and *reduced* uncertainties. Ongoing: Greenland ice sheet volume projections.
- ▶ We can study model-data discrepancies (structural uncertainties): a term in the statistics model
- ▶ We can also learn about (complicated) interactions among model parameters.

# Open Questions and Ongoing Research

- ▶ Usual caveats apply, e.g. about error structure assumptions, the fact that we are using one data set and one model; not all uncertainties are accounted for.
- ▶ We are working on several other statistical challenges in climate change risk. Examples:
  - ▶ calibration methods for non-Gaussian “zero-inflated” data
  - ▶ local impacts
  - ▶ utilizing multiple models for projections
  - ▶ using long time series tide gauge data to estimate the probability of extreme storm surges
  - ▶ estimating long term ice thinning rates in Antarctica from cosmogenic exposure dates

## Collaborators

- ▶ Won Chang, Statistics, Penn State University
- ▶ Roman Olson, Earth and Environmental Systems Institute (EESI), Penn State University
- ▶ Klaus Keller, Geosciences, Penn State University
- ▶ Patrick Applegate, EESI, Penn State University

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## Relevant Manuscripts

- ▶ Chang, W., M. Haran, R. Olson, and K. Keller (2013): Fast dimension-reduced climate model calibration, *Annals of Applied Statistics (accepted)*
- ▶ Chang, W., Haran, M., Olson, R., and Keller, K. (2013) A composite likelihood approach to computer model calibration with high-dimensional spatial data, *Statistica Sinica (accepted)*
- ▶ Chang, W., Applegate, P., Haran, M. and Keller, K. (2013) Probabilistic calibration of a Greenland Ice Sheet model using spatially-resolved synthetic observations: toward projections of ice mass loss with uncertainties
- ▶ Olson, R., R. Sriver, M. Haran, W. Chang, N. M. Urban, and K. Keller (2013): What is the effect of unresolved internal climate variability on climate sensitivity estimates? *Journal of Geophysical Research*, 118