# Toward Efficient Inference for High-dimensional Latent Variable Models

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MCMSKI Lenzerheide, Switzerland. January 2016

Joint work with Yawen Guan

# Talk Summary

- Latent variable models are very widely used.
- Markov chain Monte Carlo (MCMC) is a convenient approach for fitting such models.
- ▶ In practice: MCMC is often impractical when the latent variables become high-dimensional.
- I will discuss an approach for addressing these computational challenges for a class of spatial/nonparametric regression models: generalized linear mixed models with Gaussian process priors.
- The approach is based on latent variable reparameterization and dimension reduction.

Much of this is work in progress.

#### Latent Variable Models Review

- In sciences, latent variables are often physically meaningful.
  - ► E.g. unobserved immigration/carriers of disease in a disease dynamics model
- ▶ In social sciences may be a theoretical construct.
  - E.g. latent behavioral states in a psychology experiment
- ► Can add flexibility, help a model fit data better.
  - E.g. random intercepts or random slopes model in regression. Capture heterogeneity.
  - E.g. model dependence in non-Gaussian data

#### **Spatial Count Data**

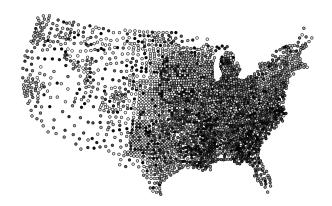
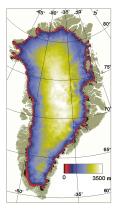


Figure: U.S. infant mortality data by county. n = 3071 Ratio of deaths to births, each averaged over 2002-2004. Darker indicates higher rate.

#### Greenland Ice Sheet Thickness



(Bamber et al., 2001). Over 60,000 locations

#### Spatial Generalized Linear Mixed Models

Example model for  $Z(\mathbf{s})$  for  $\mathbf{s} \in D \subset \mathbb{R}^d$ ,

- 1.  $Z(\mathbf{s}_i) \mid \beta, W(\mathbf{s}_i) \sim \text{Poisson}(\mu(\mathbf{s}_i))$ , conditionally independent for i = 1, ..., n.
- 2.  $\log(\mu(\mathbf{s}_i)) = X(\mathbf{s}_i)\beta + W(\mathbf{s}_i)$
- 3. Impose dependence:  $\mathbf{W} = (W(\mathbf{s}_1), \dots, W(\mathbf{s}_n))^T$  via (a) Gaussian Markov random field on a lattice,

$$p(\mathbf{W}|\theta) \propto \theta^{(n-1)/2} \exp\left(-rac{ heta}{2}\mathbf{W}'Q\mathbf{W}
ight), heta > 0,$$

(b) Gaussian process for continuous-domain spatial data,

$$p(\mathbf{W}|\theta) \sim N(0, \Sigma(\theta)).$$

**4.** Priors for  $\theta$ ,  $\beta$ 

Inference based on posterior,  $\pi(\theta, \beta, \mathbf{W} \mid \mathbf{Z})$ Key references: Besag et al. (1991), Diggle et al. (1998). Also useful for non-Gaussian nonparametric regression.

# Computational Challenges with SGLMM inference

- High-dimensionality of latent variables (W): n.
  Posterior distribution is of dimension p + k + n for p covariates, k covariance parameters, n data points.
- Strong cross-correlations make it hard to design efficient updating schemes. Too many low-dimensional updates may be slow, and result in poor mixing. High-dimensional updates may be computationally inefficient.
- Result (often): computationally expensive and slow mixing Markov chains.

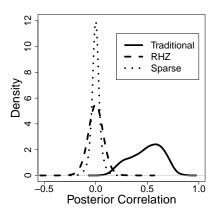
# Outline of Strategy

#### Observations:

- Reparameterization of latent variables can help "de-correlate" them, improve mixing of MCMC algorithm.
  - ▶ Not a new idea. E.g. Christensen and Roberts (2006).
- "Spatial confounding": dependence between latent variables and fixed effects (covariates) causes poor mixing.
- 3. Latent variables are merely a device for inducing dependence. May not need *n* variables for this.
  - ► #2 and #3 identified in Hughes and Haran (2013) in the context of Gaussian Markov random field models.

Goal: find reparameterization to achieve above for Gaussian process (continuous-domain) model.

#### **Distribution of Correlations**



Posterior distribution of correlations (example from Hughes and Haran, 2013).

# Reparameterize Random Effects

SGLMMs:

$$g\left\{ E(Z_i|oldsymbol{eta}, W_i) 
ight\} = oldsymbol{X}_ioldsymbol{eta} + W_i \ oldsymbol{W}|oldsymbol{ heta} \sim oldsymbol{N}_n(0, \Sigma(oldsymbol{ heta}))$$

Inference based on  $\pi(\boldsymbol{\theta}, \boldsymbol{\beta}, \boldsymbol{W}|\boldsymbol{Z})$ 

- 1. Let  $P^{\perp} = I P$  denote projection on orthogonal space of X, where  $P = X(X'X)^{-1}X'$ ,
- **2**. Approximate first *m* eigenvectors  $\mathbf{H}_{\theta}$  of  $P^{\perp}\Sigma(\theta)P^{\perp}$ .
- 3. Replace W with  $H_{\theta}\delta$ , where  $\delta \stackrel{approx}{\sim} N_m(\mathbf{0}, D_{\theta})$ .  $D_{\theta}$  is m-dim diagonal matrix.  $D_{ii}=i^{th}$  eigenvalue. Reduced Model:

$$g\left\{ E(Z_i|oldsymbol{eta}, W_i, oldsymbol{ heta}) 
ight\} = oldsymbol{X}oldsymbol{eta} + oldsymbol{H}_ioldsymbol{\delta} \ \delta | oldsymbol{ heta} \sim oldsymbol{N}_m(oldsymbol{0}, D_{oldsymbol{ heta}})$$

4. Inference based on  $\pi(\theta, \beta, \delta | \mathbf{Z})$ 

# Spatial Confounding and Fast Mixing

- ▶ Step 1 is not necessary before dimension reduction: can apply algorithm to  $\Sigma(\theta)$  instead of  $P^{\perp}\Sigma(\theta)P^{\perp}$ .
- ► However, 1 results in better mixing MCMC algorithm.
- (If spatial confounding issue is of interest, Step 1 addresses this as well.)

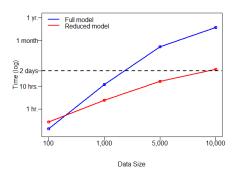
# Approximate **H** using Random Projection

- Step #2 (computing eigenvectors) of high-dimensional Σ(Θ) is expensive.
- ► Random projections (Banerjee, Dunson, Tokdar, 2012) provides fast approximation of the leading *m* eigenvectors.
- 1. Low dimensional projection from  $R^{n\times n}$  to  $R^{n\times m}$ :
  - 1.1 Simulate  $\Omega_{ij} \sim N(0, \frac{1}{\sqrt{m}}), \Omega \in R^{n \times m}$
  - 1.2 Form  $\Sigma\Omega$
- **2**. Use SVD to find basis  $\Phi^T$  (left vectors of  $\Sigma\Omega$ )
- 3. Nyström method to approximate eigen-decomposition: Approximate  $\Sigma \approx HD^2H^T$

# **Computational Benefits**

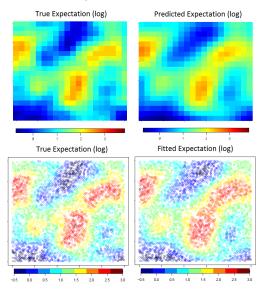
#### Win on both counts:

- ► Reduced dimensions:  $\delta$  is m vs n, e.g. m=50, n=5000. Computational complexity:  $O(m^2n)$  vs  $O(n^3)$ .
- δ are approximately de-correlated. Improves MCMC mixing, simplifies algorithm construction.
   Block updates: (i) δ | β, θ, (ii) β | δ, θ, (iii) θ | δ, β.



#### **Prediction Performance**

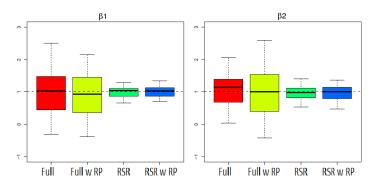
- ► Simulate n = 5000 spatial count data
- ▶ Prediction on 20 x 20 grid with *m*=50.



# Simulation Study

#### (Preliminary)

- Simulate spatial count data with:  $\beta = (1, 1)^T$ , and Matérn family $(\nu, \phi, \sigma^2) = (0.5, 0.2, 1)$
- Boxplots illustrating inference for β



# Summary

- ► Two pronged approach: (i) reducing dimensions of posterior distribution; (ii) de-correlation of latent variables.
- Speeds up computational cost per iteration, simplifies construction of algorithm, and improves Markov chain mixing.
- Caveats:
  - 1. Matrix multiplication is still expensive.
  - 2. Approach seems impractical as *n* gets large, e.g. greater than around 20,000.
  - 3. May oversmooth when true surface is rough.

# Acknowledgments and References

#### Support:

- ▶ NSF GEO-1240507 The Network for Sustainable Climate Risk Management (SCRiM)
- NSF-CDSE/DMS-1418090 Statistical Methods for Ice Sheet Projections

#### Key References:

- Hughes, J. and Haran, M. (2013), Dimension Reduction and Alleviation of Confounding for Spatial Generalized Linear Mixed Models, Journal of the Royal Statistical Society, Series B.
- Banerjee, A., Dunson, D.B., Tokdar, S.T. (2012), Efficient Gaussian process regression for large datasets, Biometrika. Projections

# Reducing Dimensions/Reparameterization

- Basic idea: reparameterize the model and reduce the dimension of the random effects (W), while preserving the desirable properties of the original model.
- Particularly worth considering when random effects are not intrinsically important, i.e., they are "nuisance parameters".
- Typical in spatial generalized linear mixed models: random effects are used to pick up residual spatial dependence, adjust for unmeasured spatially-varying covariates.

# Reparameterization for Lattice-domain Data

#### Recall model:

- ▶  $p(\mathbf{W}|\tau) \propto \tau^{(n-1)/2} \exp\left(-\frac{\tau}{2}\mathbf{W}'Q\mathbf{W}\right)$

#### Let:

- $ightharpoonup \mathbf{P} = \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$ , orthogonal projection onto  $C(\mathbf{X})$
- $P^{\perp} = I P$
- ▶ Let  $\mathbf{M} = \mathbf{P}^{\perp} \mathbf{A} \mathbf{P}^{\perp}$ , where **A** is the adjacency matrix

#### Reparameterize as follows:

- ▶  $g(\mu(\mathbf{s}_i)) = X(\mathbf{s}_i)\beta + \mathbf{M}_i\delta$ , where  $\mathbf{M}_i$  is the *i*th row of  $\mathbf{M}$
- $p(\delta \mid \tau) \propto \tau^{q/2} \exp\left(-\frac{\tau}{2} \delta' \mathbf{Q}^{**} \delta\right)$ , where  $\mathbf{Q}^{**} = \mathbf{M}' \mathbf{Q} \mathbf{M}$ .
- ▶ If we only keep the first q columns of the matrix  $\mathbf{M}$ , that is, reduce dimensions of  $\mathbf{M}_i$  to q for each i, the # random effects is reduced from n to q ( $q \ll n$ )

#### Hughes and Haran (2013)

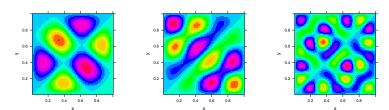
#### Comments

- ▶ Intuition: projected spatial random effects orthogonal to the predictors and in the direction specified by the graph.
- ▶ Inference is now based on  $\pi(\Theta, \beta, \delta \mid \mathbf{Z})$ q + p + 1-dimensional
- Dimension reduction works because of an ordering: highest to lowest (including negative) spatial dependence (Boots and Tiefelsdorf, 2000)

# Interpreting the Resulting Reparameterization

► "Tailored" to **X** and *G*: eigenvectors comprise all possible patterns of clustering residual to **X** and accounting for *G* 

Some selected basis vectors for the 30  $\times$  30 lattice.



# Reducing Dimensions for Continuous-Domain Processes

- Unlike in the lattice case, there is no graph/adjacency matrix to work with.
- Alternative: use an idea from Banerjee, Dunson and Tokdar (2012): "random projections" of data into a lower-dimensional subspace
- Apply a fast algorithm to obtain reduced-dimensional random effects, replacing **W** (*n*-dimensional) with *V* (*m*-dimensional) with *m* ≪ *n*.
- Same idea: we project latent variables to obtain a reduced-dimensional posterior distribution. Easier to construct efficient MCMC algorithms.

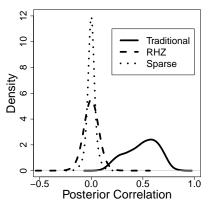
# Preliminary Results

- Prediction: reduced-dimensional approach gives similar results as regular methods
- ▶ Inference: better or worse, depending on the assumed true model. If interpreting parameters is not important, this is a non-issue. But if it is, need to think harder about spatial confounding-related issues. (Hanks et al., 2015)

(JSM 2015 poster by Yawen Guan)

#### **Pros**

- Random effects are much smaller in number.
- They are approximately "de-correlated". That is (by construction) they no longer exhibit as much dependence. Easy to construct fast mixing MCMC



#### Cons

- Highly specialized approach
- There may be scaling issues: as dimensions and complexity of the model increases, may still need a significant fraction of the latent variables.

Can improve inference while in other cases can induce problems

# Computational Strategies

- 1. Composite likelihood-based approaches
- 2. Approximate integration approaches
- Simulation-based approaches: study how the forward (probability) model generates data for different parameter settings. Then compare the simulations to the real observations.
  - Approximate Bayesian Computing (ABC)
  - Gaussian process approximations ("emulation-calibration").
     (Jandarov, Haran, Bjornstad, Grenfell, 2014)
- 4. Reduced-dimensional approximations/reparameterizations
- 5. Some combination of the above

#### Composite Likelihood

Has potential to address inferential and scaling issues

Inference with latent variables  $u_1, \ldots, u_k$ , joint posterior distribution,  $\pi(\theta, u_1, \ldots, u_k \mid \mathbf{Y})$ 

$$\propto f(\mathbf{Y} \mid u_1, \dots, u_k) f(u_1, \dots, u_k \mid \theta) p(\theta).$$

- ▶ Basic idea: replace above with  $\prod_{b=1}^{B} f(\mathbf{Y}_{b}^{C} \mid u_{b}^{C}) f(u_{b}^{C} \mid \theta) p(\theta), \text{ where } \mathbf{Y}_{b}^{C} \text{ and } u_{b}^{C}, \text{ for } b=1,\ldots,B, \text{ are each subsets (blocks) of the vectors } \mathbf{Y} \text{ and } u_{1},\ldots,u_{k} \text{ respectively}$
- Evaluating this approximation can be much more computationally efficient than evaluating the joint distribution
- Separating the latent variables into blocks suggest convenient block-MCMC schemes. Many choices for composite likelihood (e.g. Caragea and Smith, 2003)

(JSM 2015 poster by Saksham Chandra)

# Interpreting the Resulting Reparameterization

 Positive (negative) eigenvalues correspond to varying degrees of positive (negative) spatial dependence (Boots and Tiefelsdorf, 2000)

The standardized eigenvalues for the 30  $\times$  30 lattice.

