

# Algorithms for Approximating the Normalizing Constant of the G-Wishart Distribution

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# Gaussian Graphical Models

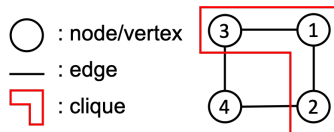
**Useful:** Understanding dependence relationship between variables.

- Let  $G=(V,E)$  be an undirected graph.
- The vertices  $V$  is associated with a  $p$ -dimensional vector  $\mathbf{X}$ ,

$$\mathbf{X} = (X_1, \dots, X_p)^\top \sim N_p(0, \Sigma), \quad \mathbf{K} = \Sigma^{-1},$$

where  $K_{ij} = 0$  if  $X_i$  and  $X_j$  are conditionally independent.

**Example:** A 4-dimensional cycle graph.



$$\mathbf{X} \sim N_5(0, \Sigma)$$
$$\mathbf{K} = \begin{pmatrix} * & * & * & 0 \\ * & * & 0 & * \\ * & 0 & * & * \\ 0 & * & * & * \end{pmatrix}$$

# The G-Wishart Distributions

$$\mathbf{X} = (X_1, \dots, X_p)^\top \sim N_p(0, \Sigma), \quad K = \Sigma^{-1},$$

**Interest:** Bayesian inference on  $K$ .

The G-Wishart distribution is a conjugate prior for  $K$ .

$$\text{(prior)} \quad K|G \sim W_G(\delta, D) \quad (1)$$

$$\text{(posterior)} \quad K|(X, G) \sim W_G(\delta^*, D^*) \quad (2)$$

**Computational challenge:** If  $K \sim W_G(\delta, D)$ ,

$$P(K|G) = \frac{1}{I_G(\delta, D)} \exp\{h_{\delta, D}(K)\}. \quad \text{Intractible!}$$

**Goal of this project:** Compare two existing methods to approximate it.

**Monte Carlo method vs. Laplace method**

# Monte Carlo Approximation (Atay-Kayis and Massam, 2005)

**Goal:** Approximate  $I_G(\delta, D) = \int e^{h_{\delta,D}(K)} dK$

**Theorem:** Atay-Kayis and Massam (2005)

$$I_G(\delta, D) = C_{\delta,D} \mathbf{E} [f_D(\psi_{\mathcal{V}})]$$

$$\psi_{ii} \sim \sqrt{\chi_{\delta, \mathcal{V}_i}^2}, \quad i = 1, \dots, p,$$

$$\psi_{ij} \sim N(0, 1), \quad (i, j) \in \{(i, j) \in \mathcal{V} : i \neq j\},$$

where  $\mathcal{V}$  is the set of indices of the free elements.

**Idea:** Use Monte Carlo method.

1. Generate  $\psi_{ii}^{(1)}, \dots, \psi_{ii}^{(N)}$  from  $\sqrt{\chi_{\delta, \mathcal{V}_i}^2}$ ,  $i = 1, \dots, p$
2. Generate  $\psi_{ij}^{(1)}, \dots, \psi_{ij}^{(N)}$  from  $N(0, 1)$ ,  $(i, j) \in \{(i, j) \in \mathcal{V} : i \neq j\}$

$$\hat{I}_G^{mc}(\delta, D) = C_{\delta,D} \frac{1}{N} \sum_{\ell=1}^N f_D(\psi_{\mathcal{V}}^{(\ell)})$$

# Laplace Approximation (Lenkoski and Dobra, 2011)

**Motivation:** In MC, the number of iterations relies on the dimension.

**Goal:** Efficiently approximate  $I_G(\delta, D) = \int e^{h_{\delta,D}(K)} \prod_{(i,j) \in \mathcal{V}} dK_{ij}$ .

**Idea:** Use Taylor's expansion and Gaussian assumption to approximate integrals of the form  $\int e^{h(x)} dx$ .

Suppose  $h(x)$  has a unique global maximum at  $\hat{x}$ .

$$h(x) \approx h(\hat{x}) - \frac{1}{2}|h''(\hat{x})|(x - \hat{x})^2 \quad \because \text{Taylor's theorem} \quad (3)$$

$$\int e^{h(x)} dx \approx e^{h(\hat{x})} \int e^{-\frac{1}{2}|h''(\hat{x})|(x - \hat{x})^2} dx \quad (4)$$

$$\approx (2\pi)^{1/2}|h''(\hat{x})|^{-1/2}e^{h(\hat{x})} \quad \because x \sim N(\hat{x}, |h''(\hat{x})|^{-1}) \quad (5)$$

**Approximation to  $I_G(\delta, D)$ :**

$$\hat{I}_G^{lap}(\delta, D) = (2\pi)^{|\mathcal{V}|/2} [\det |H_{\delta}(\hat{\mathbf{K}})|]^{-1/2} e^{h_{\delta,D}(\hat{\mathbf{K}})} = J_{\delta,D}(\hat{\mathbf{K}})$$

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$$\hat{I}_G^{lap}(\delta, D) = (2\pi)^{|\mathcal{V}|/2} [\det |H_\delta(\hat{\mathbf{K}})|]^{-1/2} e^{h_{\delta,D}(\hat{\mathbf{K}})} = J_{\delta,D}(\hat{\mathbf{K}}),$$

where  $\hat{\mathbf{K}}$  is the mode of  $h_{\delta,D}(K)$  (i.e., the mode of  $W_G(\delta, D)$ ) and is obtained by an iterative algorithm called “iterative proportional algorithm”.

Properties of the Laplace approximation:

- The accuracy of the approximation depends on the degree to which the density resembles a Gaussian distribution.

- We assumed that  $\mathbf{K} \sim N(\hat{\mathbf{K}}, |H_\delta(\hat{\mathbf{K}})|^{-1})$ .
- As  $\delta$  increases, the variance for each  $K_{ij}$  decreases.

- The number of iterations does not depend on the dimension,  $p$ .

# Simulation Study

Simulation settings: Approximation to  $I_G(\delta, D)$

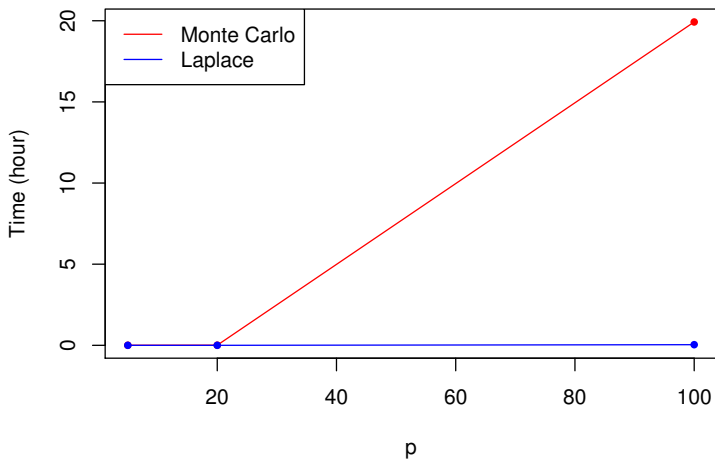
- $\delta \in \{3, 10, 25, 50, 100\}$
- $p \in \{5, 20, 100, 200, 500\}$
- $G$  is a  $p$ -dimensional cycle graph
- $D$  is an arbitrary matrix that allows the normalizing constant to be finite.
- $N = 25,000$  (MC sample size)

As  $\delta$  increases: when  $p = 5$

	$\delta$					Time (sec)
	3	10	25	50	100	
$\log \hat{I}_G^{mc}(\delta, D)$	14.201 (8e-04)	50.570 (3e-04)	166.236 (9e-06)	407.693 (3e-08)	975.966 (2e-14)	14.104
$\log \hat{I}_G^{lap}(\delta, D)$	11.068	50.044	166.149	407.618	977.033	0.069

# Simulation Study

As  $p$  increases:





# Conclusion

## Based on the simulation study:

- The Monte Carlo method is accurate but computationally demanding for a high-dimensional dataset.
- The Laplace method is computationally efficient even for the high dimension.
- The Laplace method approximates  $I_G(\delta, D)$  better for larger values of  $\delta$ .

## Recommendation:

- For small  $\delta$ , Monte Carlo method.
- For large  $\delta$  or very high-dimensional data, Laplace method.