Real-Time Object Detection and Multi-Object Tracking for Autonomous Vehicle

Final Dissertation System Audit

Date: 2026-02-09

Hardware: Tesla T4

1. MODEL & TRAINING CONFIGURATION

Architecture	: YOLOv8n (Nano)
Total Parameters	: 3,012,408
Training Epochs	: 50
Batch Size	: 16
Optimizer	: auto
Initial Learning Rate	: 0.01
Input Resolution	: 640x640 px

2. DATASET INFORMATION

Dataset Name	: KITTI Vision Benchmark Suite
Source URL	: https://github.com/ultralytics/assets/releases/download/v0.0.0/kitti.zip
More details about KITTI	: http://www.cvlibs.net/datasets/kitti/
Training Samples	: 5985
Validation Samples	: 1496

3. LEARNING DYNAMICS (Validation)

mAP @ 50% IoU	: 0.8367
mAP @ 50-95% IoU	: 0.6002
Precision	: 0.8497
Recall	: 0.7602

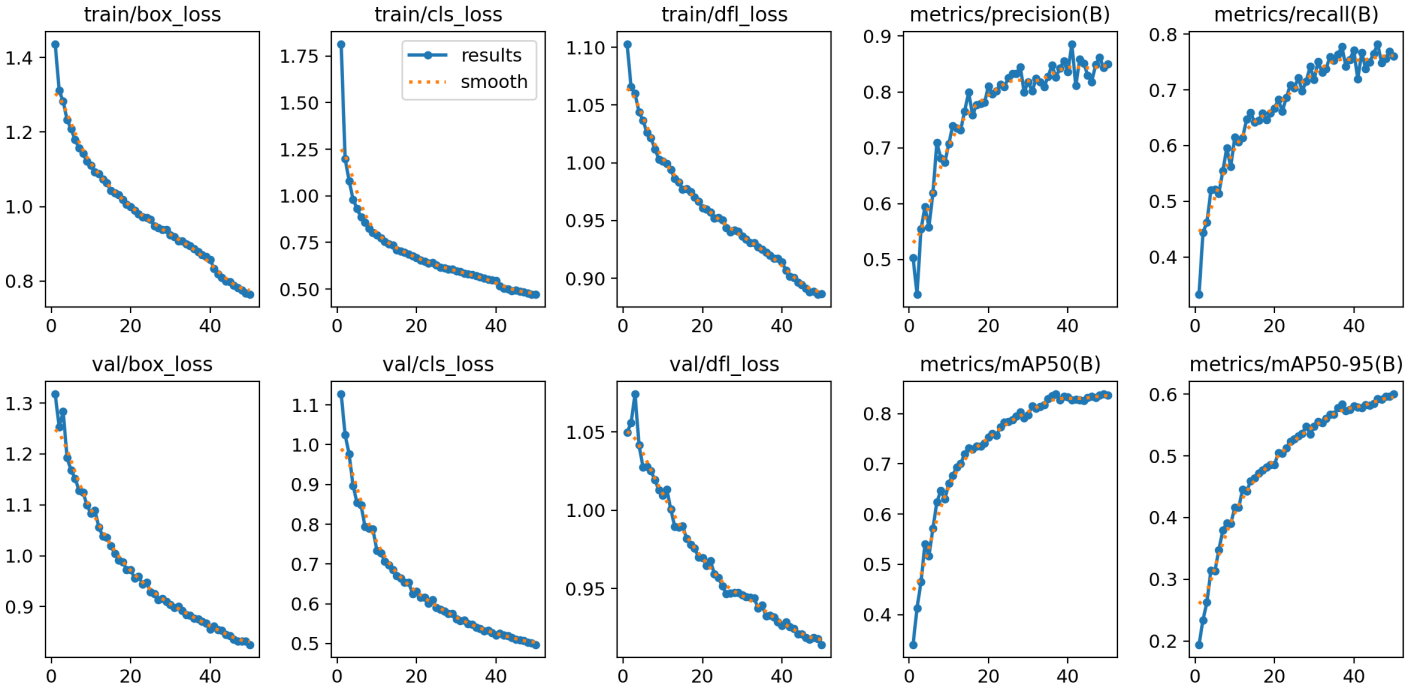
4. OPERATIONAL LATENCY

Average FPS	: 91.73 Hz
Mean Latency	: 10.90 ms
P95 Latency (Jitter)	: 16.95 ms

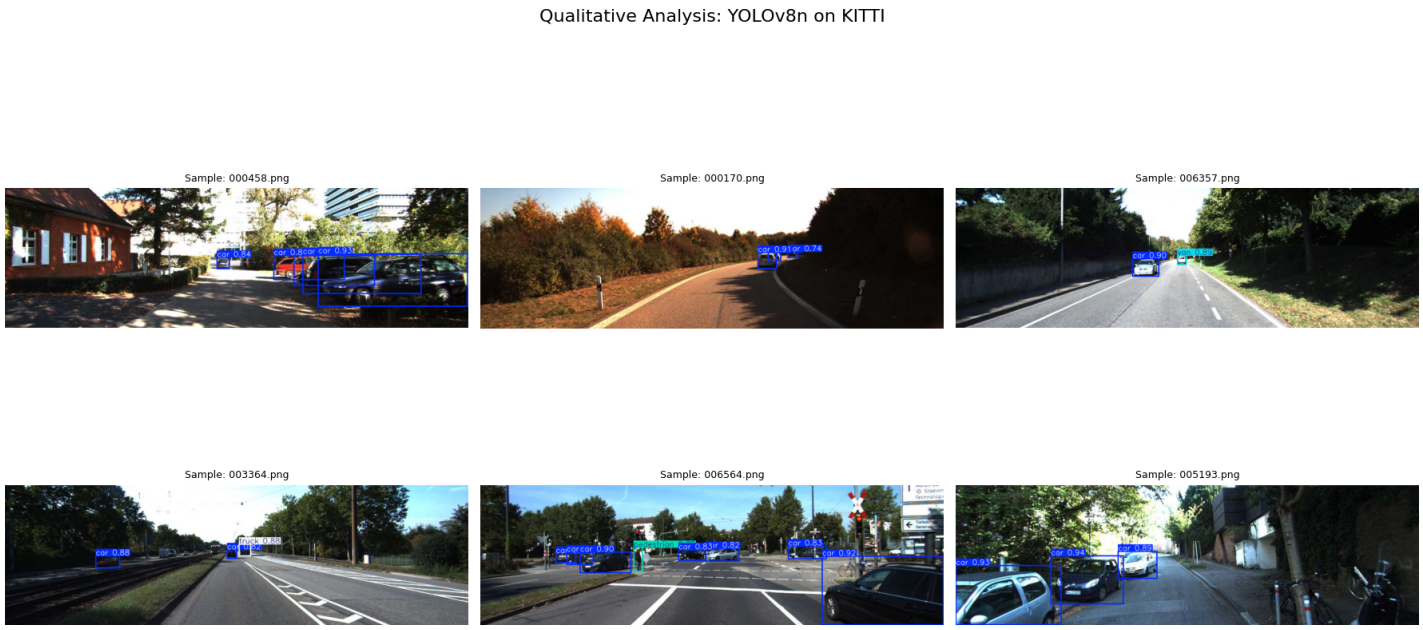
5. DEPLOYMENT ARTIFACTS

PyTorch (.pt)	: 5.93 MB
ONNX (Universal)	: 11.79 MB
TFLite (Edge)	: 5.90 MB
Interface	: Flask Web App + Ngrok Tunnel

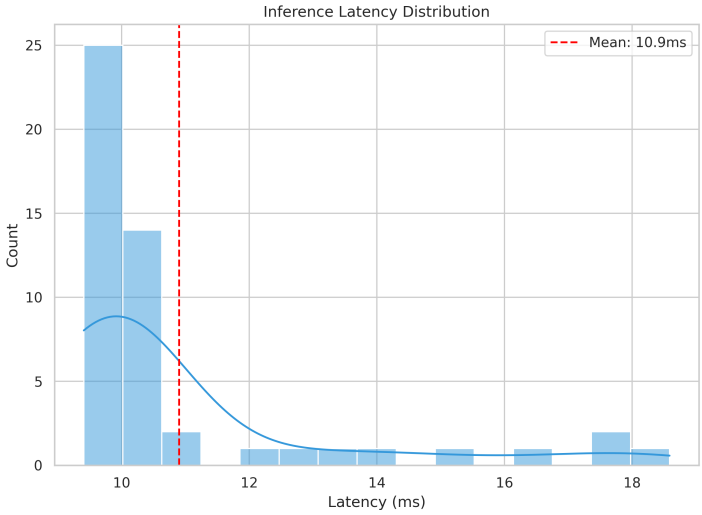
6. Training Convergence Graphs

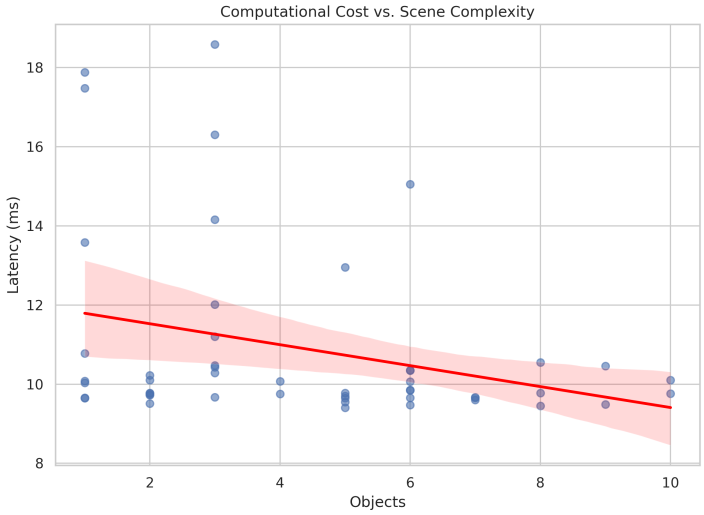


7. Qualitative Analysis

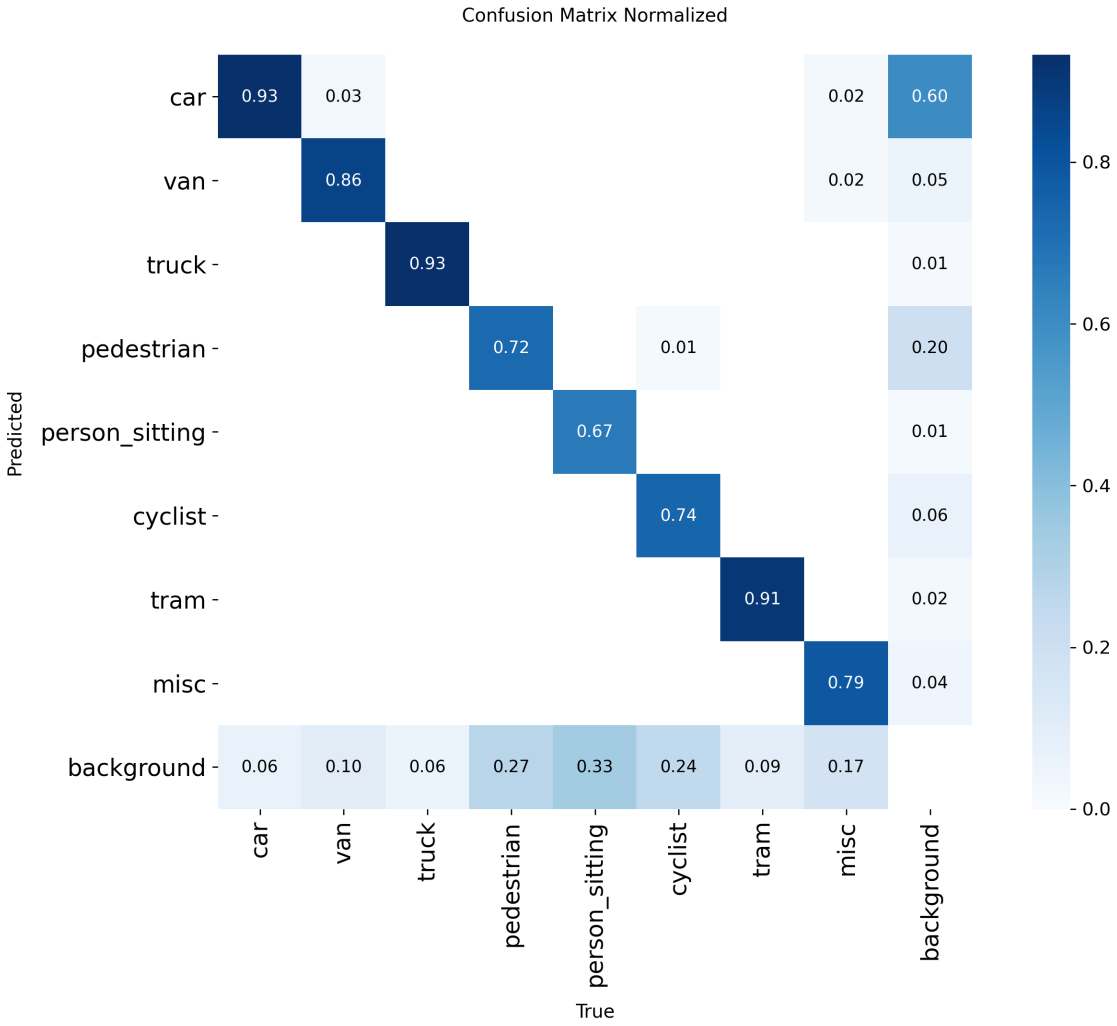


8. Latency Distribution Profile





9. Confusion Matrix



10. Artifact Size Comparison