## MIDDLE EAST TECHNICAL UNIVERSITY DEPARTMENT OF MECHANICAL ENGINEERING ME 310 NUMERICAL METHODS FALL 2022 PROGRAMMING PROJECT 3

Assignment date : 12.12.2022 Due date : 26.12.2022

The programming project will be submitted through METU-Class, as described in the "Programming Project Assignment Guidelines", which is posted on METU-Class.

Given n+1 data points  $x_1, x_2, ... x_{n+1}$  and corresponding function values  $y_1, y_2, ... y_{n+1}$ , it is desired to fit a quartic spline  $S_k(x)$ , where the subscript 'k' designates the spline number in between the two consecutive data points  $[x_k, x_{k+1}]$ 

The equation of the k-th spline is defined by the following polynomial.

$$S_k(x) = S_{k,1} + S_{k,2}(x - x_k) + S_{k,3}(x - x_k)^2 + S_{k,4}(x - x_k)^3 + S_{k,5}(x - x_k)^4$$

where  $\mathbf{s} = \begin{bmatrix} S_{k,1} & S_{k,2} & S_{k,3} & S_{k,4} & S_{k,5} \end{bmatrix}^T$  are the unknown coefficients.

- Write down the necessary equations for a sample  $k^{th}$  internal point and the two end points  $x_1, x_{n+1}$
- Express the problem in matrix form as As = b where s is the unknown coefficients.
- Write a computer program that forms  $\boldsymbol{A}$  and  $\boldsymbol{b}$  matrices and solves for  $\boldsymbol{s}$ . The input of your program should be  $\boldsymbol{x} = \begin{bmatrix} x_1 & \dots & x_{n+1} \end{bmatrix}^T$  and  $\boldsymbol{y} = \begin{bmatrix} y_1 & \dots & y_{n+1} \end{bmatrix}^T$  arrays. The output should be  $n \times 5$  coefficient matrix in the form of

$$\mathbf{C} = \begin{bmatrix} S_{1,1} & S_{1,2} & S_{1,3} & S_{1,4} & S_{1,5} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ S_{k,1} & S_{k,2} & S_{k,3} & S_{k,4} & S_{k,5} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ S_{n,1} & S_{n,2} & S_{n,3} & S_{n,4} & S_{n,5} \end{bmatrix}$$

- In your computer program plot the spline obtained and its derivative, in separate figures, in between the data points  $x_{min}$  and  $x_{max}$
- Your computer program should ask for and input and print the related spline value and its derivative at that point.

## Notes:

You should use the given polynomial description; any other forms will not be graded.

In the first spline  $S_1(x)$  take, the second and third derivatives as zero. Assume the n<sup>th</sup> spline  $S_n(x)$  has a natural boundary condition with the third derivative equal to zero.

Your program should read the x and y arrays from a given "input.txt" file, output the coefficient matrix C on screen and plot the x-y points and the splines (between the end points). A sample "input.txt" is attached.

You may use readily available equation solvers.