#### Object Modeling with OMG UML Tutorial Series



# Behavioral Modeling

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UML Revision Task Force November 2000

Part 2: Statecharts
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# Behavioral Modeling

- Part 1: Interactions and Collaborations
- Part 2: Statecharts
- Part 3: Activity Diagrams



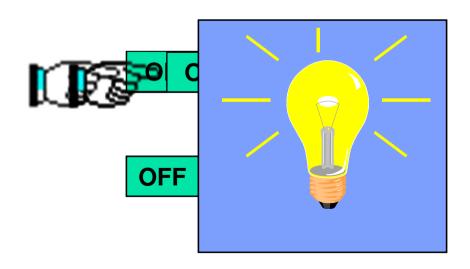
#### Overview

- Basic State Machine Concepts
- Statecharts and Objects
- Advanced Modeling Concepts
- Case Study
- Wrap Up



#### **Automata**

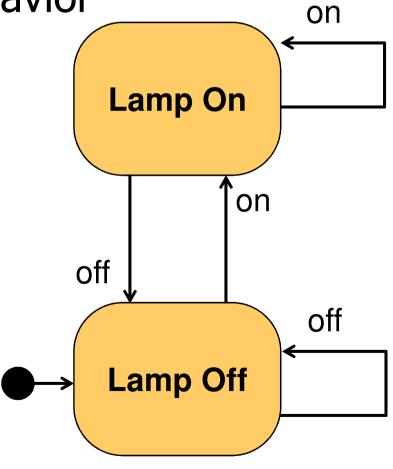
- A machine whose output behavior is not only a direct consequence of the current input, but of some past history of its inputs
- Characterized by an internal state which represents this past experience





### State Machine (Automaton) Diagram

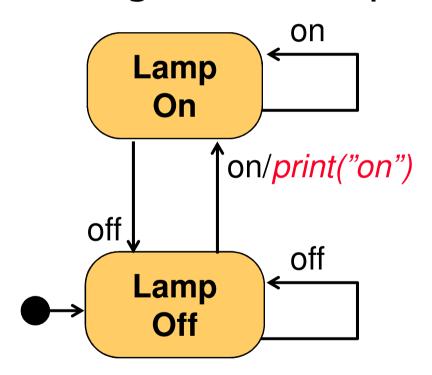
 Graphical rendering of automata behavior



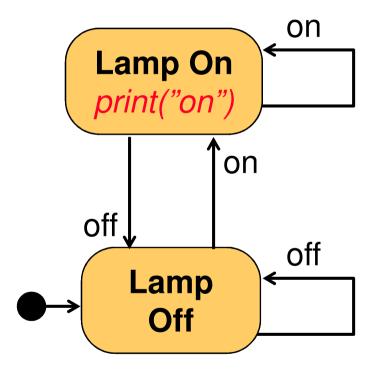


### **Outputs and Actions**

As the automaton changes state it can generate outputs:



**Mealy** automaton

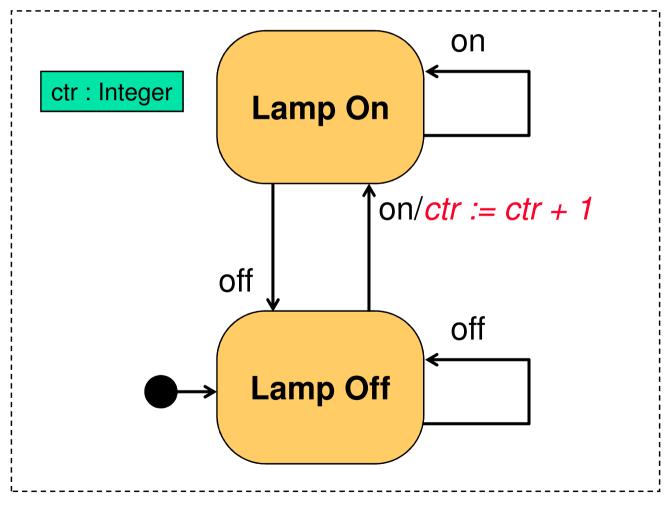


**Moore** automaton



#### **Extended State Machines**

Addition of variables ("extended state")

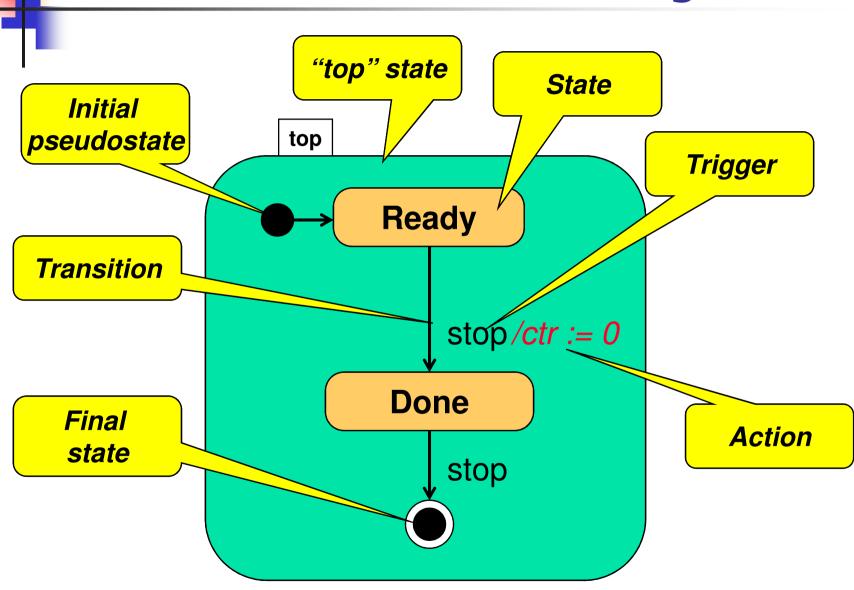




## A Bit of Theory

- An extended (Mealy) state machine is defined by:
  - a set of input signals (input alphabet)
  - a set of output signals (output alphabet)
  - a set of states
  - a set of transitions
    - triggering signal
    - action
  - a set of extended state variables
  - an initial state designation
  - a set of final states (if terminating automaton)

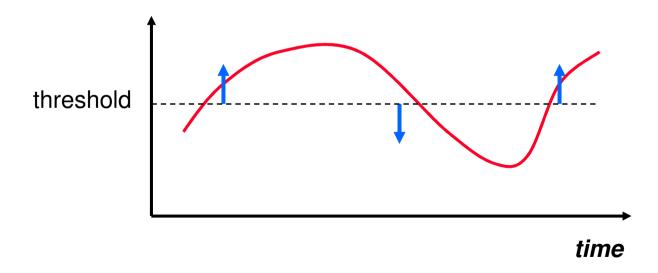
## Basic UML Statechart Diagram





#### What Kind of Behavior?

- In general, state machines are suitable for describing event-driven, discrete behavior
  - inappropriate for modeling continuous behavior





#### **Event-Driven Behavior**

- Event = a type of observable occurrence
  - interactions:
    - synchronous object operation invocation (call event)
    - asynchronous signal reception (signal event)
  - occurrence of time instants (time event)
    - interval expiry
    - calendar/clock time
  - change in value of some entity (change event)
- Event Instance = an instance of an event (type)
  - occurs at a particular time instant and has no duration



#### The Behavior of What?

- In principle, anything that manifests event-driven behavior
  - NB: there is no support currently in UML for modeling continuous behavior
- In practice:
  - the behavior of individual objects
  - object interactions
- The dynamic semantics of UML state machines are currently mainly specified for the case of active objects

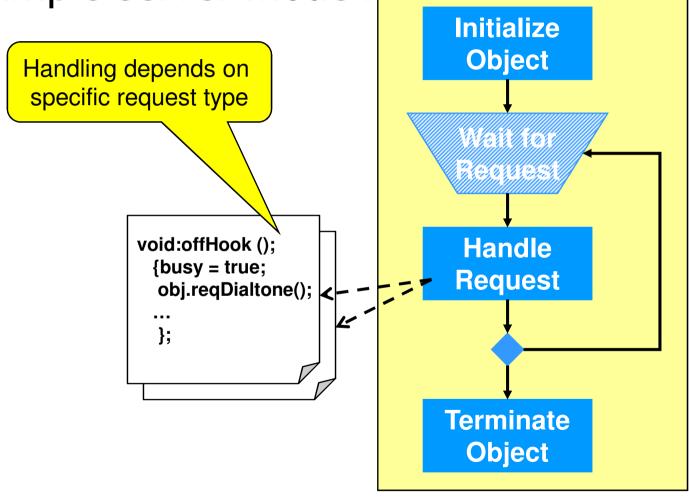


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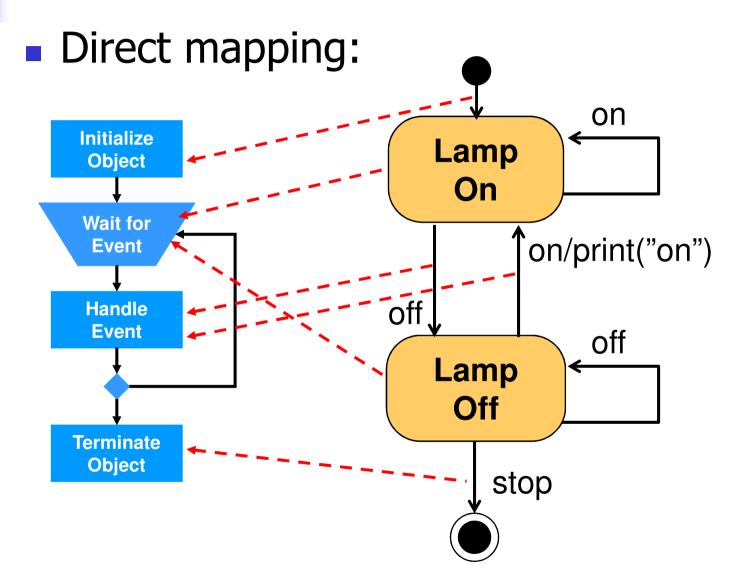
### Object Behavior - General Model

Simple server model:





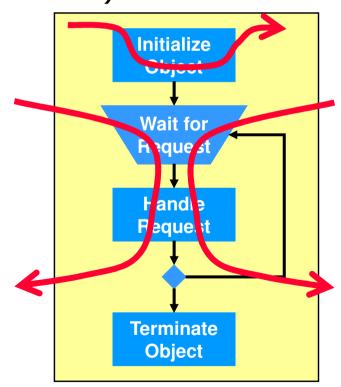
### **Object Behavior and State Machines**

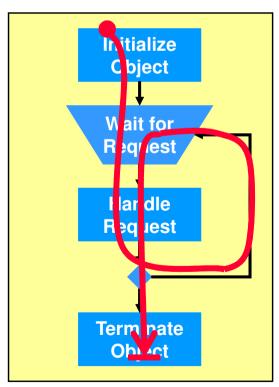




### **Object and Threads**

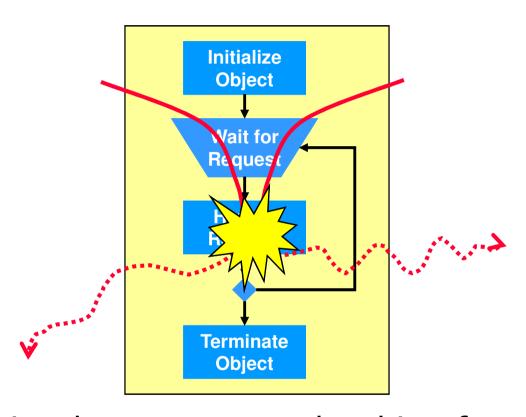
- Passive objects: depend on external power (thread of execution)
- •Active objects: self-powered (own thread of execution)







#### Passive Objects: Dynamic Semantics

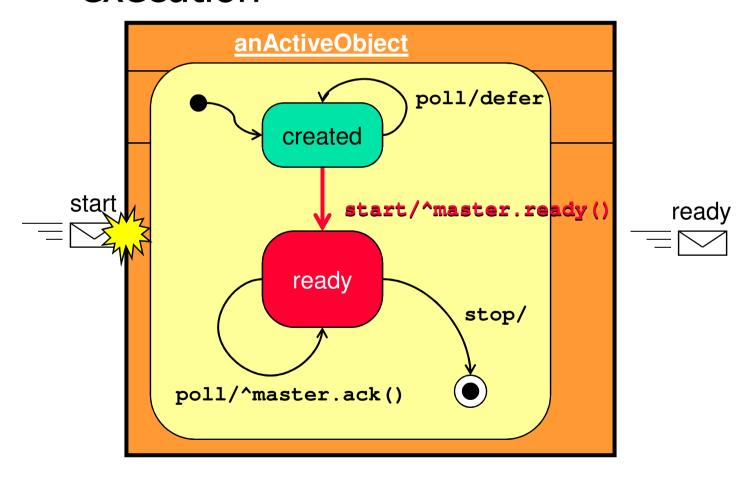


- •Encapsulation does not protect the object from concurrency conflicts!
- Explicit synchronization is still required



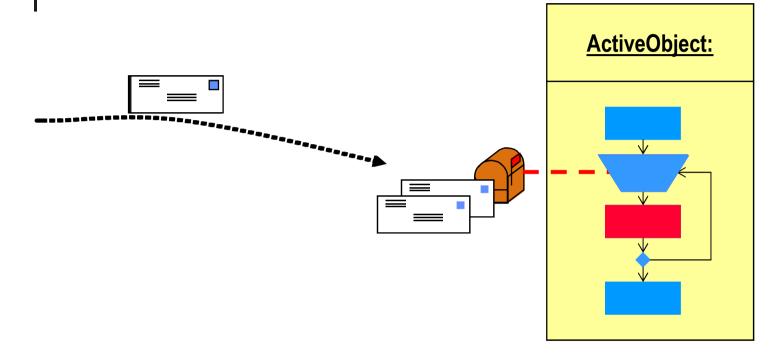
#### **Active Objects and State Machines**

Objects that encapsulate own thread of execution





#### Active Objects: Dynamic Semantics



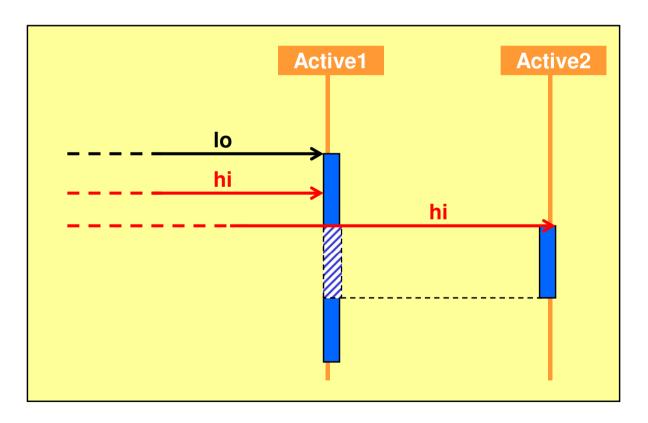
#### **Run-to-completion model:**

- serialized event handling
- eliminates internal concurrency
- minimal context switching overhead



## The Run-to-Completion Model

 A high priority event for (another) active object will preempt an active object that is handling a low-priority event





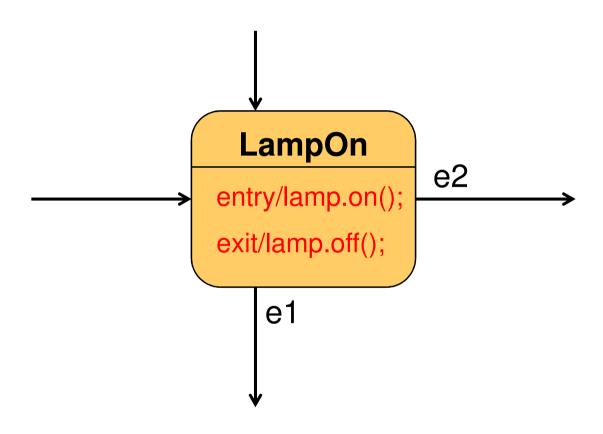
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# State Entry and Exit Actions

A dynamic assertion mechanism





## Order of Actions: Simple Case

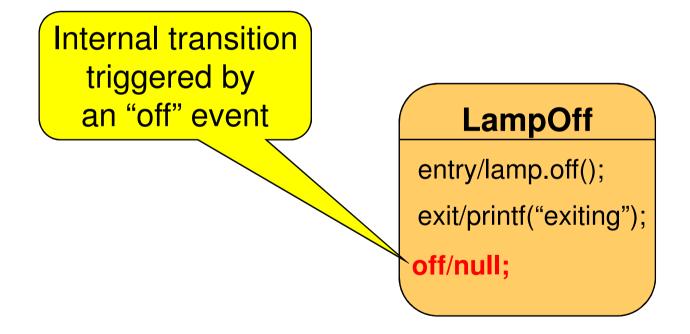
- Exit actions prefix transition actions
- Entry action postfix transition actions

```
LampOn
                                            LampOff
                    off/printf("to off");
 entry/lamp.on();
                                         entry/lamp.off();
 exit/printf("exiting");
                                         exit/printf("exiting");
Resulting action sequence:
                                      off/printf("needless");
      printf("exiting");
      printf("to off");
                                 printf("exiting");
      lamp.off();
                                 printf("needless");
                                 lamp.off();
```



#### **Internal Transitions**

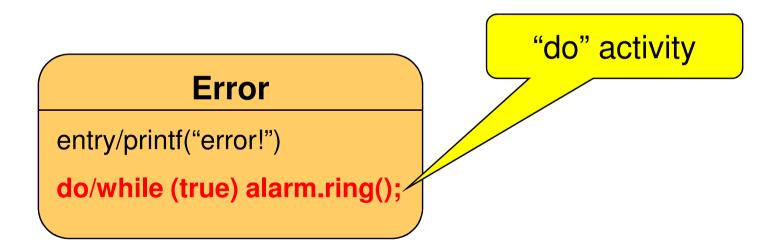
 Self-transitions that bypass entry and exit actions





## State ("Do") Activities

- Forks a concurrent thread that executes until:
  - the action completes or
  - the state is exited through an outgoing transition





#### Guards

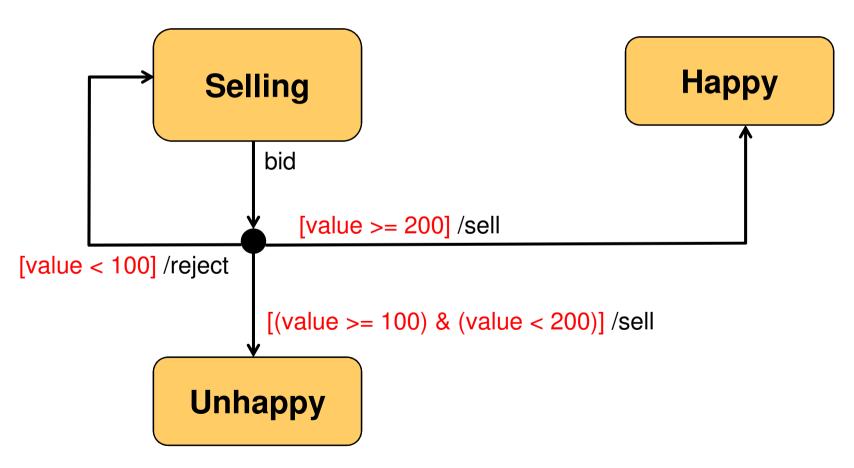
- Conditional execution of transitions
  - guards (Boolean predicates) must be side-effect free

bid [value < 100] /reject bid [value >= 200] /sell Нарру **Selling** bid [(value >= 100) & (value < 200)] /sell **Unhappy** 



## Static Conditional Branching

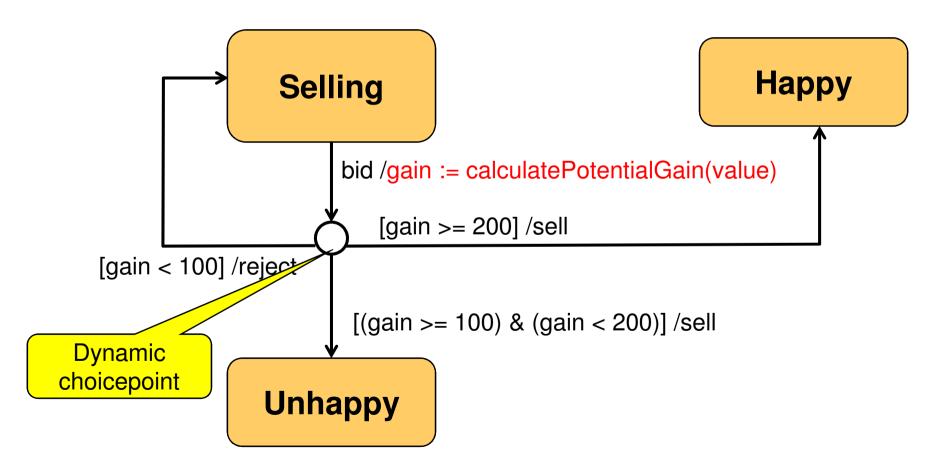
 Merely a graphical shortcut for convenient rendering of decision trees





## **Dynamic Conditional Branching**

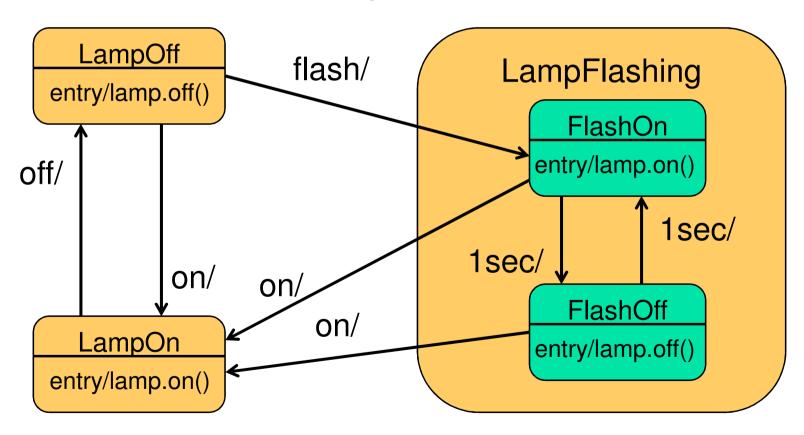
 Choice pseudostate: guards are evaluated at the instant when the decision point is reached





#### **Hierarchical State Machines**

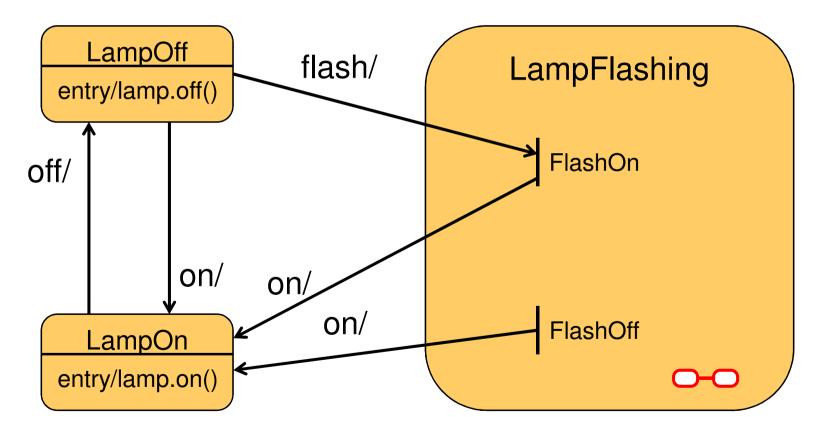
- Graduated attack on complexity
  - states decomposed into state machines





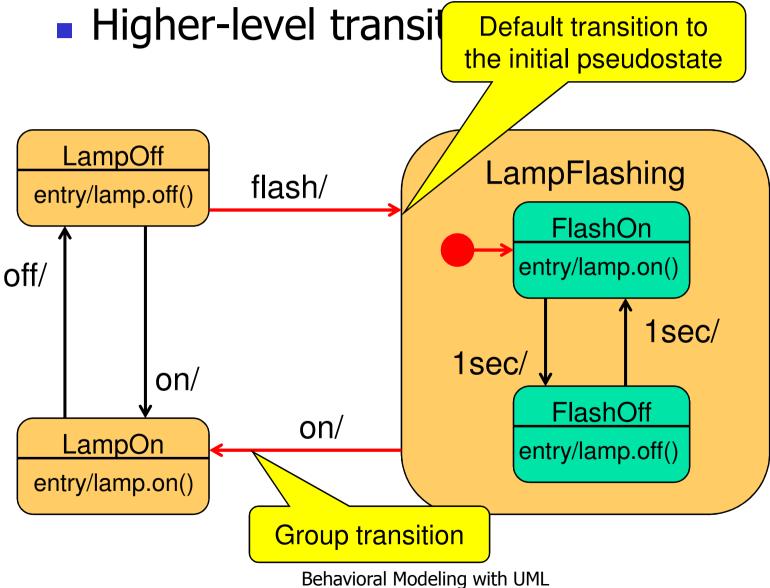
#### "Stub" Notation

Notational shortcut: no semantic significance





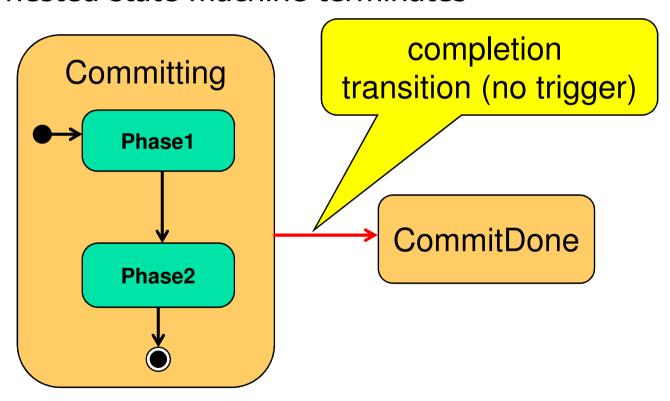
## **Group Transitions**





### **Completion Transitions**

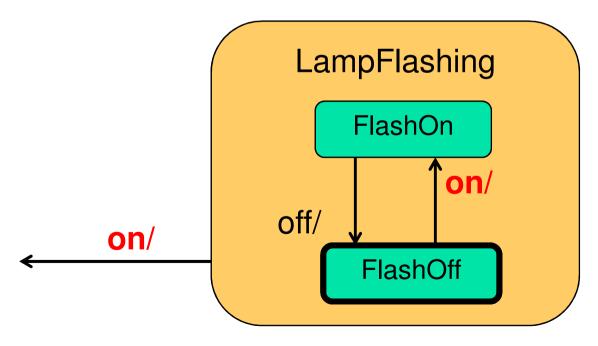
- Triggered by a completion event
  - generated automatically when an immediately nested state machine terminates





## Triggering Rules

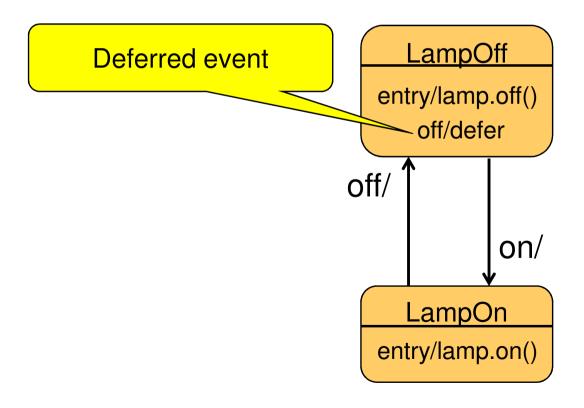
- Two or more transitions may have the same event trigger
  - innermost transition takes precedence
  - event is discarded whether or not it triggers a transition





#### **Deferred Events**

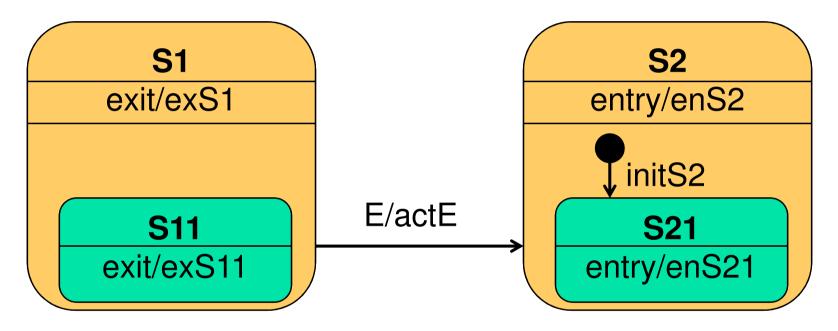
 Events can be retained if they do not trigger a transition





## Order of Actions: Complex Case

Same approach as for the simple case



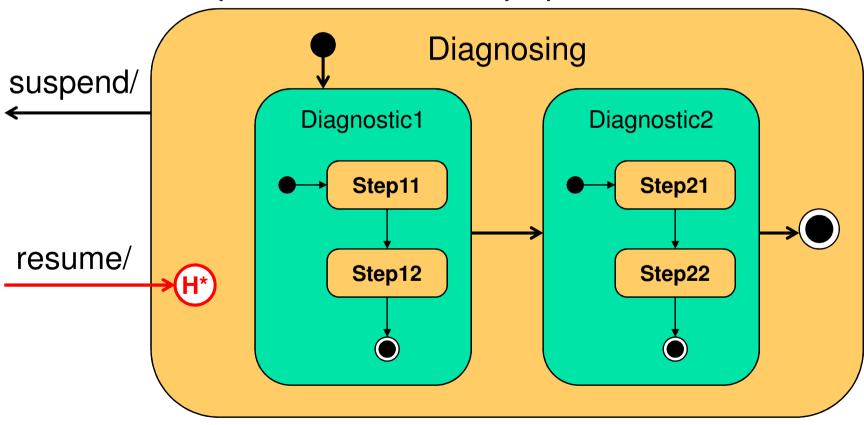
#### **Actions execution sequence:**

exS11 ⇒ exS1 ⇒ actE ⇒ enS2 ⇒ initS2 ⇒ enS21



### History

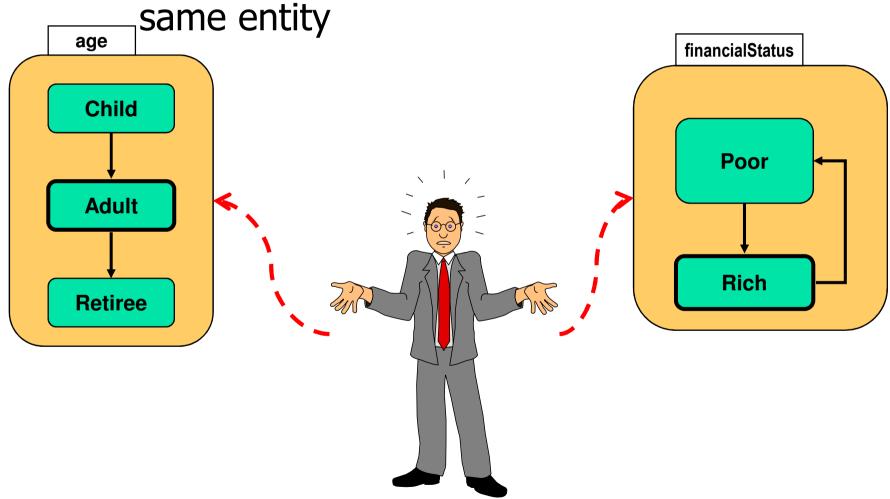
- Return to a previously visited hierarchical state
  - deep and shallow history options



# Orth

# Orthogonality

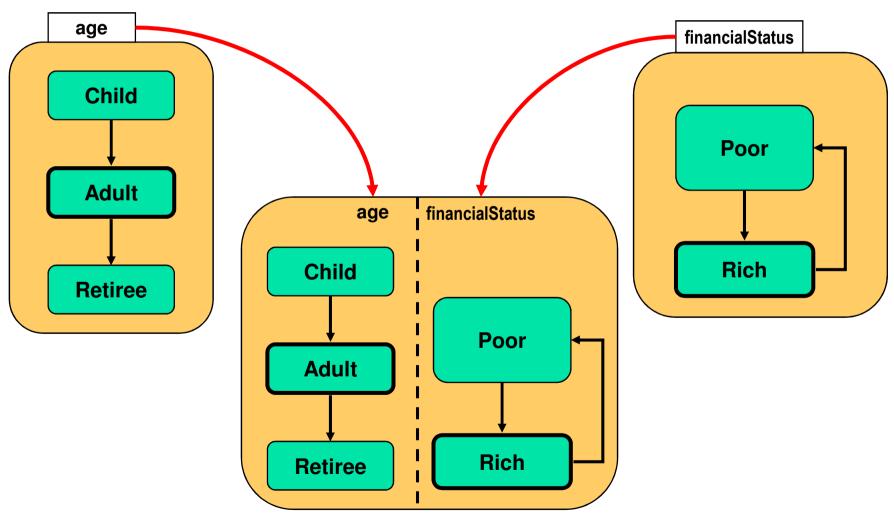
Multiple simultaneous perspectives on the
 same entity





# **Orthogonal Regions**

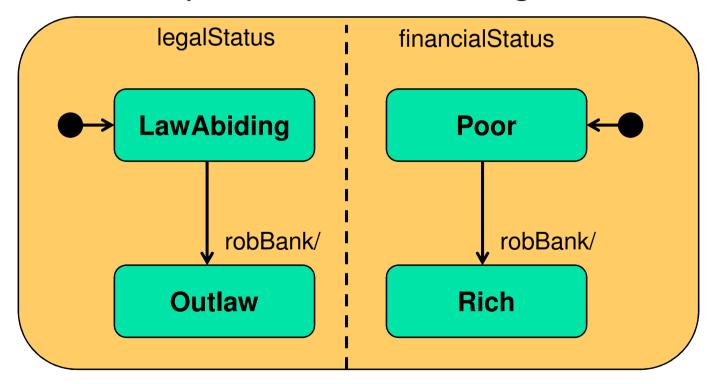
Combine multiple simultaneous descriptions





### Orthogonal Regions - Semantics

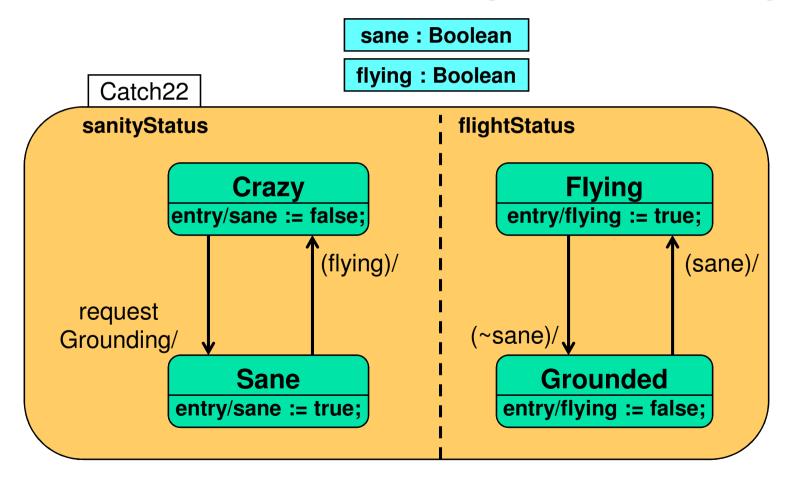
- All mutually orthogonal regions detect the same events and respond to them "simultaneously"
  - usually reduces to interleaving of some kind





### Interactions Between Regions

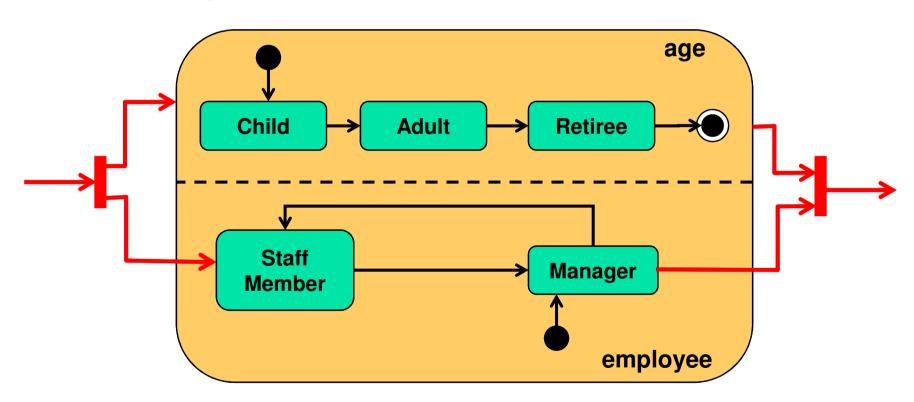
 Typically through shared variables or awareness of other regions' state changes





#### **Transition Forks and Joins**

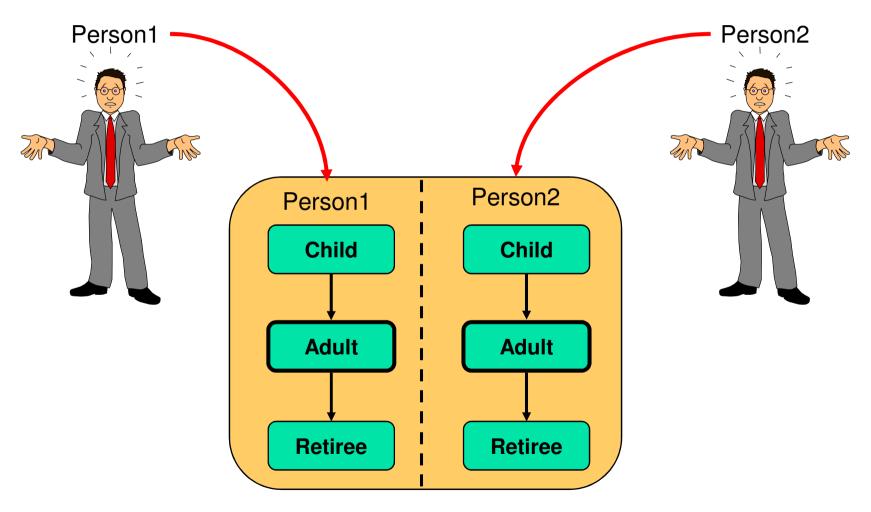
For transitions into/out of orthogonal regions:



# Common

Common Misuse of Orthogonality

Using regions to model independent objects





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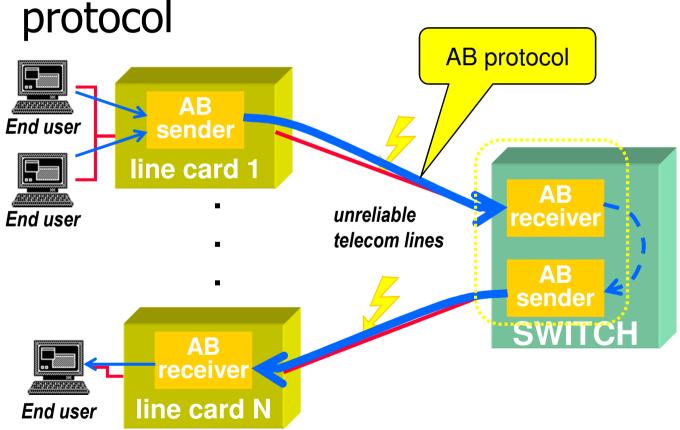
Wrap Up

Behavioral Modeling with UML



### Case Study: Protocol Handler

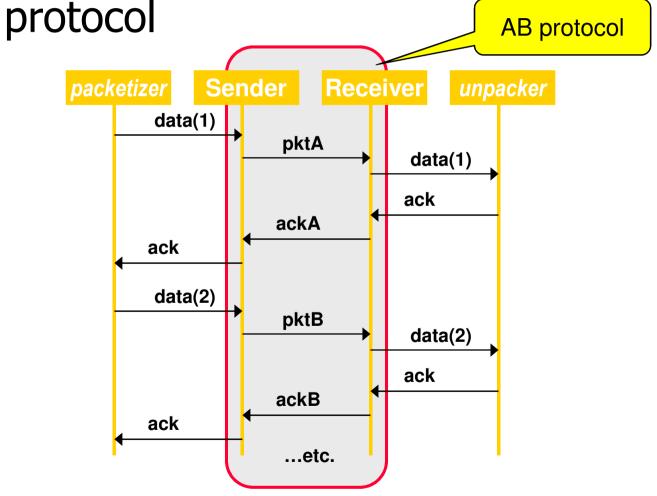
 A multi-line packet switch that uses the alternating-bit protocol as its link





## Alternating Bit Protocol (1)

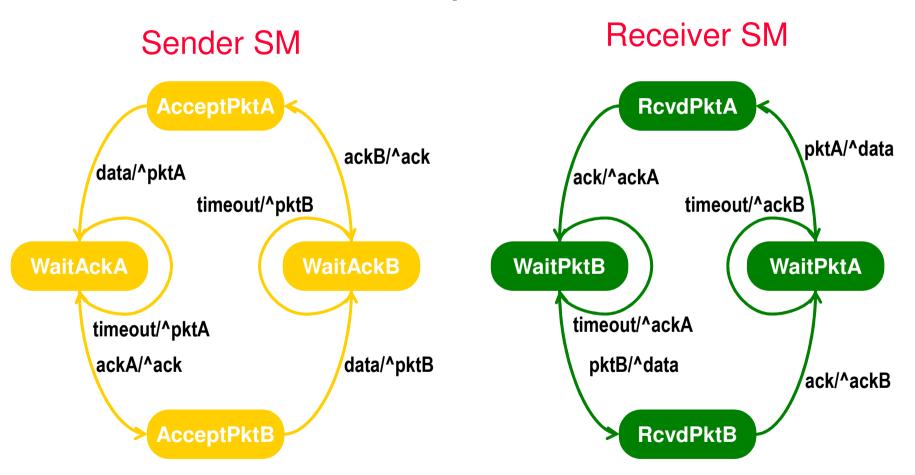
A simple one-way point-to-point packet





# Alternating Bit Protocol (2)

State machine specification





#### Wrap Up: Statecharts

- UML uses an object-oriented variant of Harel's statecharts
  - adjusted to software modeling needs
- Used to model event-driven (reactive) behavior
  - well-suited to the server model inherent in the object paradigm
- Primary use for modeling the behavior of active event-driven objects
  - systems modeled as networks of collaborating state machines
  - run-to-completion paradigm significantly simplifies concurrency management



### Wrap Up: Statecharts (cont'd)

- Includes a number of sophisticated features that realize common state-machine usage patterns:
  - entry/exit actions
  - state activities
  - dynamic and static conditional branching
- Also, provides hierarchical modeling for dealing with very complex systems
  - hierarchical states
  - hierarchical transitions
  - orthogonality