

# UPgraded ICPC Notebook

## Contents

### 1 C++

#### 1.1 C++ Template

```
#include <bits/stdc++.h>
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#define ll long long
#define pb push_back
#define ld long double
#define nl '\n'
#define fast cin.tie(0), cout.tie(0), ios_base::sync_with_stdio(false)
#define fore(i,a,b) for(ll i=a;i<b;++i)
#define rofe(i,a,b) for(ll i=a-1;i>=b;--i)
#define ALL(u) u.begin(),u.end()
#define vi vector<ll>
#define vvi vector<vi>
#define sz(a) ((ll)a.size())
#define lsb(x) ((x)&(-x))
#define lsbpos(x) __builtin_ffs(x)
#define PI acos(-1.0)
#define pii pair<ll,ll>
#define fst first
#define snd second
#define RB(x) (x<n?r[x]:0)

using namespace __gnu_pbds;
using namespace std;

typedef tree<pair<int, int>, null_type, less<pair<int, int>>, rb_tree_tag, tree_order_statistics_node_update> ordered_multiset;
typedef tree<int,null_type, less<int>, rb_tree_tag, tree_order_statistics_node_update> ordered_set;

int main() {
    fast;
}
```

#### 1.2 Bits Manipulation

```
mask |= (1<<n) // prender bit-N
mask ^= (1<<n) // flippear bit-N
mask &= ~(1<<n) // apagar bit-N
```

```
if(mask&(1<<n)) // checkar bit-n
T = ((mask)&(-mask)) // LSO
__builtin_ffs(mask); // indice del LSO (indexado en 1)
// Iterate over the subsets of S.
for(int subset= S; subset; subset= (subset-1) & S)
    for (int subset=0;subset=subset-S&S;) // Increasing order
```

#### 1.3 Random

```
// Declare random number generator
mt19937_64 rng(0); // 64 bit, seed = 0
mt19937 rng(chrono::steady_clock::now().time_since_epoch().count()); // 32 bit

// Use it to shuffle a vector
shuffle(all(vec), rng);

// Create int/real uniform dist. of type T in range [l, r]
uniform_int_distribution<T> / uniform_real_distribution<T>
> dis(l, r);
dis(rng); // generate a random number in [l, r]

int rd(int l, int r) { return uniform_int_distribution<int>(l, r)(rng);}

srand(time(0)); //include this in main.
```

#### 1.4 Other

```
#pragma GCC optimize("O3")
/*(UNCOMMENT WHEN HAVING LOTS OF RECURSIONS) \
#pragma comment(linker, "/stack:200000000")
(UNCOMMENT WHEN NEEDED) */
#pragma GCC optimize("Ofast,unroll-loops,no-stack-protector,fast-math")
#pragma GCC target("sse,sse2,sse3,ssse3,sse4,popcnt,abm,mmx,avx,tune=native")

// Custom comparator for set/map
struct comp {
    bool operator()(const double& a, const double& b) const {
        return a+EPS<b;}
};
set<double,comp> w; // or map<double,int,comp>

// double inf
const double DINF=numeric_limits<double>::infinity();
```

## 2 Strings

### 2.1 Aho Corasick

```
const int MAXN = 1e6+10;
map<char, int> to[MAXN]; // if TLE change this to normal
                        // array.
string a[MAXN];
int lnk[MAXN],sz=1;
ll que[MAXN],endlink[MAXN];
vi leaf[MAXN],ans[MAXN];
void add_str(string s, int id) {
    int v = 0;
    for(char c: s) {
        if(!to[v].count(c)) to[v][c] = sz++;
        v = to[v][c];
    }
    leaf[v].pb(id); //Node in the automata where a word
                    // ends.
}
void push_links() {
    queue<int> q({0});
    while(!q.empty()) {
        int v = q.front(); q.pop();
        for(auto [c,u]: to[v])
        {
            int j = lnk[v];
            while(j && !to[j].count(c)) j=lnk[j];
            if(to[j].count(c) && to[j][c]!=u) lnk[u] = to
                [j][c];
            endlink[u] = leaf[lnk[u]].size()>0?lnk[u]:
                endlink[lnk[u]];
            q.push(u);
        }
    }
}
void walk(string s){ //KMP with multiple target patterns
    int v=0;
    for(i,0,sz(s)) {
        char c=s[i];
        while(v && !to[v].count(c)) v=lnk[v];
        if(to[v].count(c)) v=to[v][c];
        for(int u=v;u;u=endlink[u]) for(int x: leaf[u]){
            ans[x].pb(i); //pushing the index of the main
                          // string where a pattern ends.
        }
    }
}
void doit() {
    string s;
    cin>>s; //main string.
    for(i,0,n){
        cin>>a[i];
```

```
        add_str(a[i],i); //add target strings.
    }
    push_links();
    walk(s);
}
```

### 2.2 Hashing

```
const ll maxn = 1e6 + 5;
const ll M = 1e9+9; // prime modulo.
const ll B = 131; // prime number bigger than the
                    // alphabet.
string s,t;
ll pws[maxn],h[maxn],tams,tamt,hasht=0,ans=0;
ll conv(char c){
    return (c-'a'+1);
}
bool sameHash(int l1, int len1, int l2, int len2){
    int r1 = l1 + len1;
    int r2 = l2 + len2;
    ll h1 = (h[r1]-h[l1]*pws[len1]%M + M)%M;
    ll h2 = (h[r2]-h[l2]*pws[len2]%M + M)%M;
    return h1 == h2;
}
void precalc(){
    tams = sz(s), tamt = sz(t);
    pws[0] = 1;
    for(i,1,maxn) pws[i] = (pws[i-1]*B)%M;
    // Main hash.
    h[0] = conv(s[0]);
    for(i,0,tams) h[i+1] = ((h[i]*B)+conv(s[i]))%M;
    // Target hash.
    for(i,0,tamt) hasht = ((hasht*B)+conv(t[i]))%M;
}
void doit(){
    cin>>s; //main text.
    cin>>t; //pattern.
    precalc();
    //For all substrings, check if hashings of substring
    // 's' and 't' are equal:
    for(i,tamt,tams+1){
        ll cur_hash = (h[i]-h[i-tamt]*pws[tamt]%M + M)%M;
        if (cur_hash == hasht) ans++;
    }
}
```

### 2.3 KMP

```

vi kmp(string s){
    vi vs(sz(s));
    fore(i,1,sz(s)){
        int j = vs[i-1];
        while(j!=0 && s[i] != s[j]){
            j = vs[j-1];
        }
        if(s[i] == s[j]) j++;
        vs[i] = j;
    }
    return vs;
}

void doit(){
    string s,t,p;
    cin>>s; // main text.
    cin>>t; // target.
    p = t, p += "#", p += s;;
    vi res = kmp(p);
    ll ans = 0;
    for (auto au : res){
        if (au == sz(t)) ans++;
    }
}

```

## 2.4 Lyndon Factorization

*// A Lyndon word is a non-empty string that is strictly smaller than any of its non-trivial suffixes.*

```

vector<string> duval(string const& s){
    int i = 0;
    vector<string> factorization;
    while (i < sz(s)) {
        int j = i + 1, k = i;
        while (j < sz(s) && s[k] <= s[j]) {
            if (s[k] < s[j]) k = i;
            else k++;
            j++;
        }
        while (i <= k) {
            factorization.pb(s.substr(i, j - k));
            i += j - k;
        }
    }
    return factorization;
}

string duvalMinShift(string s){ // finds the minimum
    cyclic shift of a string.
    s += s;
    int i = 0, ans = 0;
    while (i < sz(s) / 2) {
        ans = i;
        int j = i + 1, k = i;

```

```

        while (j < sz(s) && s[k] <= s[j]) {
            if (s[k] < s[j]) k = i;
            else k++;
            j++;
        }
        while (i <= k) i += j - k;
    }
    return s.substr(ans, sz(s) / 2);
}

```

## 2.5 Manacher

```

const ll MAXN = 1e6+5;
int d1[MAXN]; //d1[i] = max odd palindrome centered on i
int d2[MAXN]; //d2[i] = max even palindrome centered on i

//s aabbaacaabbaa
//d1 1111117111111
//d2 0103010010301
void manacher(string& s){
    int l=0,r=-1,n=sz(s);
    fore(i,0,n){
        int k=i>r?1:min(d1[l+r-i],r-i);
        while(i+k<n&&i-k>=0&&s[i+k]==s[i-k])k++;
        d1[i]=k--;
        if(i+k>r)l=i-k,r=i+k;
    }
    l=0;r=-1;
    fore(i,0,n){
        int k=i>r?0:min(d2[l+r-i+1],r-i+1);k++;
        while(i+k<=n&&i-k>=0&&s[i+k-1]==s[i-k-1])k++;
        d2[i]=--k;
        if(i+k-1>r)l=i-k,r=i+k-1;
    }
}

```

## 2.6 Suffix Array

```

void csort(vi& sa, vi& r, int k){
    int n=sa.size();
    vi f(max(255,n),0),t(n);
    fore(i,0,n)f[RB(i+k)]++;
    int sum=0;
    fore(i,0,max(255,n))f[i]=(sum+=f[i])-f[i];
    fore(i,0,n)t[f[RB(sa[i]+k)]++] = sa[i];
    sa=t;
}

vi constructSA(string& s){
    int n=s.size(),rank;
    vi sa(n),r(n),t(n);
    fore(i,0,n)sa[i]=i,r[i]=s[i];
    for(int k=1;k<n;k*=2){

```

```

        csort(sa,r,k); csort(sa,r,0);
        t[sa[0]]=rank=0;
        fore(i,1,n){
            if(r[sa[i]]!=r[sa[i-1]]||RB(sa[i]
                ]+k)!=RB(sa[i-1]+k)) rank++;
            t[sa[i]]=rank;
        }
        r=t;
        if(r[sa[n-1]]==n-1) break;
    }
    return sa;
}

void doit(){
    string s;
    cin>>s;
    s = "$" + s; //add an extra symbol at the
                  //beginning to avoid conflicts.
    vi sa = constructSA(s);
}

```

## 2.7 Suffix Automaton

```

const ll maxn = 1e6+5;
struct state {int len,link;map<char,int> next;}; //clear
next!!
state st[maxn];
int sz,last;
string s;

void sa_init(){
    last=st[0].len=0;sz=1;
    st[0].link=-1;
}

void sa_extend(char c) {
    int cur = sz++;
    st[cur].len = st[last].len + 1;
    int p = last;
    while (p != -1 && !st[p].next.count(c)) {
        st[p].next[c] = cur;
        p = st[p].link;
    }
    if (p == -1) {
        st[cur].link = 0;
    } else {
        int q = st[p].next[c];
        if (st[p].len + 1 == st[q].len) {
            st[cur].link = q;
        } else {
            int clone = sz++;
            st[clone].len = st[p].len + 1;
            st[clone].next = st[q].next;
            st[clone].link = st[q].link;
            while (p != -1 && st[p].next[c] == q) {

```

```

                st[p].next[c] = clone;
                p = st[p].link;
            }
            st[q].link = st[cur].link = clone;
        }
        last = cur;
    }
    //Finds longest common substring in 2 substrings.
    string lcs (string S, string T) {
        sa_init();
        for (int i = 0; i < sz(S); i++) sa_extend(S[i]);
        int v = 0, l = 0, best = 0, bestpos = 0;
        for (int i = 0; i < T.size(); i++) {
            while (v && !st[v].next.count(T[i])) {
                v = st[v].link ;
                l = st[v].len;
            }
            if (st[v].next.count(T[i])) {
                v = st[v].next[T[i]];
                l++;
            }
            if (l > best) {
                best = l;
                bestpos = i;
            }
        }
        return T.substr(bestpos - best + 1, best);
    }

    ll f(ll x, vector<ll> &dp){
        if (dp[x] >= 0) return dp[x];
        ll res = 1;
        for(auto it=st[x].next.begin(); it!=st[x].next.end();
            it++) res += f(it->second,dp);
        dp[x] = res;
        return dp[x];
    }
    //Finds the total length of different substrings.
    ll get_tot_len_diff_substings(){
        ll tot = 0;
        for(int i = 1; i < sz; i++) {
            ll shortest = st[st[i].link].len + 1;
            ll longest = st[i].len;

            ll num_strings = longest - shortest + 1;
            ll cur = num_strings * (longest + shortest) / 2;
            tot += cur;
        }
        return tot;
    }
    //Finds the amount of distinct substrings.
    void distinctSubstrings(){
        cin>>s;
        int n = s.size();
        vi dp(maxn+5,-1);

```

```

sa_init();
for(i,0,n) sa_extend(s[i]);
ll ans = f(0,dp)-1;
cout<<ans<<endl;
}
void dfs(int node, ll k, vi &dp, vector<char> &path){
    if (k < 0) return;
    for(const auto &[c,signode]: st[node].next){
        if (dp[signode] <= k) k -= dp[signode];
        else{
            path.pb(c);
            dfs(signode,k-1,dp,path);
            return;
        }
    }
}
//Finds the Kth biggest substring.
void substringOrder(){
    string s;
    ll k;
    cin>>s;
    cin>>k;
    int n = s.size();
    vector<ll> dp(maxn+5,-1);
    sa_init();
    for(i,0,n) sa_extend(s[i]);
    f(0,dp);
    vector<char> path;
    dfs(0,k-1,dp,path);
    for(auto c : path) cout<<c;
    cout<<endl;
}

```

## 2.8 Trie

```

const int ALPHABET_SIZE = 26;
struct TrieNode
{
    struct TrieNode *children[ALPHABET_SIZE];
    bool isEndOfWord;
};

struct TrieNode *getNode(void){
    struct TrieNode *pNode = new TrieNode;
    pNode->isEndOfWord = false;
    for(i,0,ALPHABET_SIZE) pNode->children[i] = NULL;
    return pNode;
}

void insert(struct TrieNode *root, string key){
    struct TrieNode *pCrawl = root;
    for (int i = 0; i < key.length(); i++){
        int index = key[i] - 'a';
        if (!pCrawl->children[index])

```

```

        pCrawl->children[index] = getNode();
        pCrawl->children[index];
    }
    pCrawl->isEndOfWord = true;
}

bool search(struct TrieNode *root, string key){
    struct TrieNode *pCrawl = root;
    for(i,0,sz(key)){
        int index = key[i] - 'a';
        if (!pCrawl->children[index]) return false;
        pCrawl = pCrawl->children[index];
    }
    return (pCrawl->isEndOfWord);
}

void doit(){
    struct TrieNode *root = getNode();
}

```

## 2.9 Z-Function

```

//Z Function for strings (longest prefix from start and
//from i).
//Complexity O(n).
const ll maxn = 2e5+5;
ll z[maxn];
void z_function(string s){
    for (int i = 1, l = 0, r = 0; i < sz(s); ++i) {
        if (i <= r){
            z[i] = min(r - i + 1, z[i - l]);
        }
        while (i + z[i] < sz(s) && s[z[i]] == s[i + z[i]]){
            z[i]++;
        }
        if (i + z[i] - 1 > r){
            l = i, r = i + z[i] - 1;
        }
    }
}

```

## 3 Graph algorithms

### 3.1 2-SAT

```

const ll maxn = 1e5+100;
struct Sat2 {
    vector<vector<int>> g, rg;
    vector<int> component;
    vector<bool> ans;

```

```

int tag, n, siz;
stack<int> st;
Sat2(int n) : n(n), siz(2*n), g(vector< vector<int>
    >(2*n)), rg(vector< vector<int> >(2*n)) {}
void add_edge(int u, int v) {
    g[u].push_back(v);
    rg[v].push_back(u);
}
int neg(int u) {
    return (n+u)%siz;
}
void implication(int u, int v) {
    add_edge(neg(u), v);
}
// AND (a&b) = add(a&a), add(b&b)
void add(int u, int v) { // OR = true (u or v is
    true).
    implication(u, v);
    implication(v, u);
}
void diff(int u, int v) { //XOR = true (both u
    and v are different).
    add(u, v);
    add(neg(u), neg(v));
}
void eq(int u, int v) { //XOR = false (both u and
    v are equal).
    diff(neg(u), v);
}
void dfs(int u, vector< vector<int> > &g, bool first)
{
    component[u] = tag;
    for(int i = 0; i < g[u].size(); i++) {
        int v = g[u][i];
        if(component[v] == -1)
            dfs(v, g, first);
    }
    if(first) st.push(u);
}
bool satisfiable() {
    tag = 0;
    ans = vector<bool>(n);
    component = vector<int>(siz, -1);
    for(int i = 0; i < siz; i++) {
        if(component[i] == -1)
            dfs(i, g, true);
    }
    component = vector<int>(siz, -1);
    tag = 0;
    while(st.size()) {
        int u = st.top(); st.pop();
        if(component[u] != -1) continue;
        ++tag;
        dfs(u, rg, false);
    }
}

```

```

for(int i = 0; i < n; i++) {
    if(component[i] == component[neg(i)]) return
        false;
    ans[i] = component[i] > component[neg(i)];
}
return true;
}
};

void doit(){
    ll n;
    Sat2 sat(n);
    // insert clauses ...
    sat.satisfiable(); //run 2-SAT.
}

```

### 3.2 Bellman Ford

```

const ll maxn = 5050;
const ll mod = 1e9+7;
const ll INF = 1e17;

struct Edge {
    ll a, b, cost;
};

vector< Edge> edges;
ll n, m, ncy[maxn];

void bford(int stnode) { //When wanting to find the
    longest path, invert the signs of the costs (+ -)
    vi d(n+1, 0LL); //to find shortest paths from
    stnode: set to INF.
    //to find any negative cycle in
    the graph, set to 0.
    //d[stnode] = 0; <-- when having a starting node (
    task: find shortest paths), uncomment this.
    vi p(n+1, -1);
    int x = -1;
    fore(i, 0, n) {
        x = -1;
        for (Edge e : edges)
            if (d[e.a] < INF)
                if (d[e.b] > d[e.a] + e.cost) {
                    d[e.b] = max(-INF, d[e.a] + e.cost);
                    p[e.b] = e.a; //to keep track of the
                    path, pointing to the previous
                    node.
                    if (i+1 == n) ncy[e.b] = 1, x = e.b;
                    //e.b is part of a negative cycle.
                }
    }
    if (x == -1) cout<<"No negative cycles"<<endl;
    else{
        cout<<"Negative cycle: "<<endl;
    }
}

```

```

    fore(i,0,n) x = p[x];
    vi cycle;
    ll start = x;
    cycle.pb(x);
    x = p[x];
    while(start != x){
        cycle.pb(x);
        x = p[x];
    }
    cycle.pb(start);
    reverse(ALL(cycle));
    for(auto au : cycle) cout<<au<<" ";
    cout<<nl;
}

void doit(){
    // insert edges first.
    bford(0); // from start node.
}

```

### 3.3 Binary Lifting

```

const ll maxn = 2e5+5;
const ll loga = 20;
ll n, up[maxn][loga], dep[maxn];

void binlift(){
    // Assuming we have all direct parents for each node
    (up[node][0])
    fore(i,1,loga){
        fore(j,1,n+1) up[j][i] = up[up[j][i-1]][i-1];
    }
}

ll lca(ll x, ll y){ //calculate the depths of each node
    before.
    if (dep[x] < dep[y]) swap(x,y);
    ll dif = dep[x]-dep[y];
    rofe(i,loga,0){
        if (dif & (1ll<<i)) x = up[x][i];
    }
    if (x == y) return x;
    rofe(i,loga,0){
        if (up[x][i] != up[y][i]){
            x = up[x][i];
            y = up[y][i];
        }
    }
    return up[x][0];
}

```

### 3.4 Centroid Decomposition

```

const ll maxn = 2e5+5;
const ll loga = 20;
vi adj[maxn+5];
ll subt[maxn][loga], dep[maxn][loga], vis[maxn], cenpar[maxn];
ll n, centroids_root;

ll dfsExplore(ll anode, ll node, ll depth, ll layer, vi &
    elms){
    dep[node][layer] = depth;
    subt[node][layer] = 1;
    elms.pb(node);
    for (auto au : adj[node]){
        if (anode != au && vis[au] == 0){
            subt[node][layer] += dfsExplore(node, au, depth
                +1, layer, elms);
        }
    }
    return subt[node][layer];
}

bool check(ll node, ll layer, ll tam){
    ll sum = 1;
    for (auto au : adj[node]){
        if (dep[au][layer] > dep[node][layer]){
            sum += subt[au][layer];
            if (subt[au][layer] > tam/2) return false;
        }
    }
    if (tam-sum <= tam/2) return true;
    return false;
}

void centroidBuild(ll centroid_parent, ll node, ll layer)
{
    vi elms;
    ll tam = dfsExplore(0, node, 1, layer, elms);
    for(auto elm : elms){
        if (check(elm, layer, tam)){
            vis[elm] = 1;
            // Save each node's centroid parent.
            if (centroid_parent == -1){
                centroids_root = elm;
                cenpar[centroids_root] = 0;
            }
            else cenpar[elm] = centroid_parent;
            for(auto signode : adj[elm]){ //expand to the
                children.
                if (vis[signode] == 0){
                    centroidBuild(elm, signode, layer+1);
                }
            }
            break;
        }
    }
}

```

```
void doit(){
    // create adjacency list first.
    centroidBuild(-1,1,0); //nodes [1,n]
}
```

### 3.5 Cycle Detection

```
const ll maxn = 2e5+5;
ll n,m,color[maxn],par[maxn];
vvi cycles;
vi adj[maxn];

void dfs_cycle(int u, int p){
    if (color[u] == 2) return;
    if (color[u] == 1) {
        vi v;
        int cur = p;
        v.pb(cur);
        while (cur != u){
            cur = par[cur];
            v.pb(cur);
        }
        //reverse(ALL(v)); //uncomment if graph
        //is directed.
        cycles.pb(v);
        return;
    }
    par[u] = p;
    color[u] = 1;
    for (int v : adj[u]) {
        if (v == par[u]) { //remove IF graph is directed.
            continue;
        }
        dfs_cycle(v, u);
    }
    color[u] = 2;
}
```

### 3.6 Dijkstra

```
const ll INF = 1e18;
const ll maxn = 2e5+5;
ll n,m,d[maxn];
vector<pii> adj[maxn]; //{adjacent node,cost}

void daikra(int stnode){
    priority_queue<pii, vector<pii>, greater<pii> > pq;
    fore(i,0,n+1) d[i]=INF;
    d[stnode]=0;
    pq.push({d[stnode],stnode});
    while(!pq.empty()){
```

```
        ll curw = pq.top().fst;
        ll node = pq.top().snd;
        pq.pop();
        if (curw != d[node]) continue;
        for(auto au : adj[node]){
            int signode = au.fst;
            ll sigw = au.snd;
            if (d[signode] > d[node] + sigw){
                d[signode] = d[node] + sigw;
                pq.push({d[signode],signode});
            }
        }
    }
}
```

### 3.7 Euler Path Directed

```
const int maxn = 1e5+5;

ll n,m,indeg[maxn],outdeg[maxn];
vi g[maxn],path;

// Hierholzer's algorithm
// Directed graph: going from node 1, passing through all
// edges without repeating and end at node n.
void dfs(int node){
    while(!g[node].empty()){
        int signode = g[node].back();
        g[node].pop_back();
        dfs(signode);
    }
    path.pb(node);
}

void doit(){
    //Have out and in degree for each node first.
    bool flag=true;
    fore(i,2,n) if (indeg[i] != outdeg[i]) flag=false;
    if (indeg[1]+1 != outdeg[1] || indeg[n]-1 != outdeg[n]
        || !flag){
        cout<<"IMPOSSIBLE"<<nl;
        return;
    }
    dfs(1);
    reverse(ALL(path));
    if (sz(path) != m+1 || path.back() != n) cout<<"
        IMPOSSIBLE"<<nl;
    else{
        for(auto node : path) cout<<node<<" ";
        cout<<nl;
    }
}
```



### 3.8 Euler Path Undirected

```

const int maxn = 1e5+5;
const int maxm = 2e5+5;
ll seen[maxn], n, m;
vi path;
vector<pii> g[maxn]; //{neighbor node, edge index}
// Hierholzer's algorithm
// Going from node 1, passing through all edges without
// repeating and come back to node 1.
void dfs(int node) {
    while(!g[node].empty()) {
        auto [signode, idx] = g[node].back();
        g[node].pop_back();
        if (seen[idx]) continue;
        seen[idx] = true;
        dfs(signode);
    }
    path.pb(node);
}

void doit() {
    // Create adjacency list.
    for(i, 0, n) {
        if (sz(g[i]) % 2) {
            cout << "IMPOSSIBLE" << endl;
            return;
        }
    }
    dfs(0);
    if (sz(path) != m+1) cout << "IMPOSSIBLE" << endl;
    else {
        for(auto node : path) cout << node+1 << " ";
        cout << endl;
    }
}

```

### 3.9 Floyd Warshall

```

struct Conn { ll a, b, c; }; //{node a, node b, cost}
const ll maxn = 1e3+5;
const ll INF = 1e18;
ll n, m, q, d[maxn][maxn];
Conn adj[maxn];

void floyd_warshall() {
    for(i, 0, n+1) for(j, 0, n+1) d[i][j] = INF;
    for(int i = 1; i <= n; i++) d[i][i] = 0;
    for(auto au : adj) { //loop through the edges
        ll nd = au.a;
        ll nd2 = au.b;
        ll cost = au.c;
        d[nd][nd2] = min(d[nd][nd2], cost);
    }
}

```

```

        d[nd2][nd] = min(d[nd2][nd], cost);
    }
    for(i, 1, n+1) {
        for(j, 1, n+1) {
            for(k, 1, n+1) {
                d[j][k] = min(d[j][k], d[j][i] + d[i][k]);
            }
        }
    } //D[j][k] = shortest distance from j --> k
}

```

### 3.10 Heavy Light Decomposition

```

const int maxn = 2e5+50;
const int neut = 0;
const int loga = 19;
int n, qrys, label_cont;
int up[maxn][loga], subt[maxn], dep[maxn], labe[maxn], arr[
    maxn], tp[maxn], revlabe[maxn], st[maxn*4], p[loga];
vi adj[maxn];

void upd(int pos, int val, int node = 1, int ini = 1, int
    fin = n) {
    if (ini == fin) {
        st[node] = val;
        return;
    }
    int mid = (ini+fin)/2;
    if (pos <= mid) upd(pos, val, 2*node, ini, mid);
    else upd(pos, val, 2*node+1, mid+1, fin);
    st[node] = max(st[2*node], st[2*node+1]); //
        operation
}

int query(int l, int r, int node = 1, int ini = 1, int
    fin = n) {
    if (fin < l || r < ini) return neut; // operation
        neutral
    if (l <= ini && fin <= r) return st[node];
    int mid = (ini+fin)/2;
    return max(query(l, r, 2*node, ini, mid), query(l, r, 2*
        node+1, mid+1, fin)); // operation
}

void init() {
    label_cont = 1;
    p[0] = 1;
    for(i, 1, loga) p[i] = (p[i-1] * 2LL);
}

int dfs_sz(int cur, int par) {
    subt[cur] = 1;
    for(int chi : adj[cur]) {
        if (chi == par) continue;
    }
}

```

```

        dep[chi] = dep[cur] + 1;
        up[chi][0] = cur;
        subt[cur] += dfs_sz(chi, cur);
    }
    return subt[cur];
}

void dfs_hld(int cur, int par, int top) {
    labe[cur] = label_cont++;
    tp[cur] = top;
    upd(labe[cur], arr[cur]); //updating the STree
    using the labeling.
    int h_chi = -1, h_sz = -1;
    for (int chi : adj[cur]) {
        if (chi == par) continue;
        if (subt[chi] > h_sz) {
            h_sz = subt[chi];
            h_chi = chi;
        }
    }
    if (h_chi == -1) return;
    dfs_hld(h_chi, cur, top); //exploring the heavy
    edge first.
    for (int chi : adj[cur]) {
        if (chi == par || chi == h_chi) continue;
        dfs_hld(chi, cur, chi); //exploring the
        light edges.
    }
}

void binaryLift() {
    fore(i, 1, loga) {
        fore(j, 1, n+1) up[j][i] = up[up[j][i-1]][i-1];
    }
}

ll lca(ll x, ll y) {
    if (x == y) return x;
    if (dep[x] > dep[y]) swap(x, y); // 'y' is deeper.
    ll dif = dep[y] - dep[x];
    rofe(i, loga, 0) {
        if (p[i] <= dif) {
            dif -= p[i];
            y = up[y][i];
        }
    }
    if (x == y) return x;
    rofe(i, loga, 0) {
        if (up[x][i] != up[y][i]) {
            x = up[x][i];
            y = up[y][i];
        }
    }
    return up[x][0];
}

```

```

int pathQuery(int chi, int par) {
    int ret = 0;
    while (chi != par) {
        if (tp[chi] == chi) { //querying for the
            top of the chain, no STree needed.
            ret = max(ret, arr[chi]);
            chi = up[chi][0];
        } else if (dep[tp[chi]] > dep[par]) { //
            queyring for the whole chain.
            ret = max(ret, query(labe[tp[chi]
                ], labe[chi]));
            chi = up[tp[chi]][0];
        } else { //querying for a part of the
            chain
            ret = max(ret, query(labe[par] +
                1, labe[chi]));
            break;
        }
    }
    return ret;
}

void doit() { //Example querying and updating for maximum
    value.
    init();
    // 1. Read initial values for each node.
    // 2. Read and create adjacency list.
    dfs_sz(1, 1);
    dfs_hld(1, 1, 1);
    binaryLift();
    // for updates:
    upd(labe[node], val);
    arr[node] = val;
    // for queries:
    ll lcan = lca(node, node2);
    ll q_ans = max({pathQuery(node, lcan), pathQuery(node2,
        lcan), arr[lcan]});
}

```

### 3.11 Kruskal

```

const int maxn = 1e5+5;

struct Edge { ll a, b, c; }; //{Node1, Node2, Cost}.

vector <Edge> edges;

bool cmp(Edge e1, Edge e2) { return e1.c < e2.c; }

void doit() {
    // Initialize Union Find.
    // Read edges.
    ll totalw = 0; // total MST weight.
    sort(ALL(edges), cmp);
    for(auto edge : edges) {

```

```

        if (bus(edge.a) != bus(edge.b)){
            join(edge.a, edge.b);
            totalw += edge.c;
        }
    }
}

```

### 3.12 Tarjan

```

const ll maxn = 2e5+10;
ll n,x,y,m,foundat=1;
ll low[maxn],disc[maxn],isArt[maxn],inStack[maxn];
vi adj[maxn];
vvi scc;
vector<pii> brid;

void dfs(int node, int antnode){ //first call antnode
    should be = -1.
    static stack<int> stk;
    low[node] = disc[node] = foundat;
    stk.push(node);
    inStack[node] = 1;
    foundat++;
    int children = 0;
    for (auto signode : adj[node]){
        if(disc[signode] == 0){
            children++;
            dfs(signode, node);
            if (low[signode] > disc[node]){
                brid.pb({node,signode});
            }
            low[node] = min(low[node], low[signode]);
            if (antnode == -1 && children > 1) isArt[node] = 1;
            if (antnode != -1 && low[signode] >= disc[node]) isArt[node] = 1;
        }
    }
    //Remove some of this IF condition according to
    //the desired function of Tarjan
    //When wanting to find SCC's:
    else if (inStack[signode] == 1){
        low[node] = min(low[node], disc[signode]);
    }
    //When wanting to find bridges or articulation
    //points:
    /*
    else if (antnode != signode){
        low[node] = min(low[node], disc[signode]);
    } */
}

if (low[node] == disc[node]){ // for SCC's
    vi scctem;
    while (true){

```

```

        ll topic = stk.top();
        stk.pop();
        scctem.pb(topic);
        inStack[topic] = 0;
        if (node == topic) break;
    }
    scc.pb(scctem);
}
}

```

### 3.13 Topo Sort

```

const int maxn = 2e5+5;
int n,m,indeg[maxn];
vi adj[maxn];
vi topo;

void topo_sort(){
    // 1. Create adjacency list with nodes' indegree.
    queue<int> q;
    for(i,0,n) if (!indeg[i]) q.push(i);
    while (!q.empty()){
        int node = q.front();
        q.pop();
        topo.pb(node);
        for(auto signode : adj[node]){
            indeg[signode]--;
            if (!indeg[signode]) q.push(signode);
        }
    }
    // If sz(topo) != n, there is a cycle in the graph.
}

```

## 4 Flows

### 4.1 Dinic

```

struct FlowEdge {
    int v, u;
    ll cap, flow = 0;
    FlowEdge(int v, int u, ll cap) : v(v), u(u), cap(
        cap) {}
};

struct Dinic {
    const ll flow_inf = 1e18;
    vector<FlowEdge> edges;
    vvi adj;
    int n, m = 0;
    int s, t;
    vi level, ptr;
    queue<int> q;
    Dinic(int n, int s, int t) : n(n), s(s), t(t){

```

```

        adj.resize(n);
        level.resize(n);
        ptr.resize(n);
    }
    void add_edge(int v, int u, ll cap){ // v -> u
        edges.emplace_back(v, u, cap);
        edges.emplace_back(u, v, 0);
        adj[v].push_back(m);
        adj[u].push_back(m + 1);
        m += 2;
    }
    bool bfs(){
        while (!q.empty()) {
            int v = q.front();
            q.pop();
            for (int id : adj[v]) {
                if (edges[id].cap - edges[id].flow < 1)
                    continue;
                if (level[edges[id].u] != -1)
                    continue;

                level[edges[id].u] =
                    level[v] + 1;
                q.push(edges[id].u);
            }
        }
        return level[t] != -1;
    }
    ll dfs(int v, ll pushed) {
        if (pushed == 0) return 0;
        if (v == t) return pushed;
        for (ll& cid = ptr[v]; cid < sz(adj[v]); cid++) {
            int id = adj[v][cid];
            int u = edges[id].u;
            if (level[v] + 1 != level[u] ||
                edges[id].cap - edges[id].flow < 1)
                continue;

            ll tr = dfs(u, min(pushed, edges[id].cap - edges[id].flow));
            if (tr == 0) continue;

            edges[id].flow += tr;
            edges[id ^ 1].flow -= tr;
            return tr;
        }
        return 0;
    }
    ll flow(){ // run the algorithm.
        ll f = 0;
        while (true) {
            fill(ALL(level), -1);
            level[s] = 0;
            q.push(s);

```

```

                if (!bfs()) break;
                fill(ALL(ptr), 0);
                while (ll pushed = dfs(s,
                    flow_inf)) {
                    f += pushed;
                }
            }
            return f;
        }
    }; // initialize dinic(size, source_index, sink_index).

```

## 4.2 Min-Cost Max-Flow Algorithm

```

const ll maxn = 600;
const ll maxm = 50000;
const ll INF = 1e18;

int n, p[maxn], edgeId=1, src, sink;
ll d[maxn], cap[maxn][maxn], cost[maxn][maxn];
bool inq[maxn], vis[maxn];
vi path, g[maxn];

struct Edge {
    int u, v;
    ll r, c;
} edges[maxn], redges[maxn];

void bellman_ford(int start = 0){
    fill(inq, inq+maxn, false);
    fill(d, d+maxn, INF);
    fill(p, p+maxn, 0);
    queue<int> Q;
    Q.push(start);
    d[start] = 0;
    inq[start] = true;
    while(!Q.empty()){
        int u = Q.front(); Q.pop();
        inq[u] = false;
        for(int i : g[u]){
            Edge e = (i < 0 ? redges[-i] : edges[i]);
            if(e.r > 0 && d[e.v] > d[u] + e.c){
                d[e.v] = d[u] + e.c;
                p[e.v] = i;
                if(!inq[e.v]){
                    inq[e.v] = true;
                    Q.push(e.v);
                }
            }
        }
    }
}

ll mcf(){
    ll flow = 0, cost = 0;

```

```

while(flow < n){ //set N equal to INF if wanting to
compute the MCMF.
    bellman_ford();
    if(d[sink] == INF) break;

    ll aug = n-flow;
    int u = sink;
    while(u != 0){
        Edge e = (p[u] < 0 ? redges[-p[u]] : edges[p[
            u]]);
        aug = min(aug, e.r);
        u = e.u;
    }

    flow += aug;
    cost += aug * d[sink];
    u = sink;
    while(u != 0){
        if(p[u] < 0){
            redges[-p[u]].r -= aug;
            edges[-p[u]].r += aug;
        } else {
            redges[p[u]].r += aug;
            edges[p[u]].r -= aug;
        }
        u = (p[u] < 0 ? redges[-p[u]].u : edges[p[u]
            ].u);
    }
    return (flow < n ? -1 : cost);
}

void dfs(int u = 0){ //look for all paths computed (flow
matches).
    if(u == sink) return;
    if(u != 0) path.pb(u);
    for(int i : g[u]){
        if(i > 0 && edges[i].r == 0 && !vis[i]){
            vis[i] = true;
            dfs(edges[i].v);
            return;
        }
    }
}

void add_edge(int u, int v, ll cost){ // u -> v
    g[u].pb(edgeId);
    g[v].pb(-edgeId);
    edges[edgeId] = {u, v, 1, cost};
    redges[edgeId] = {v, u, 0, -cost};
    edgeId++;
}

void doit(){
    // define src and sink.
    // edges src to node, and node to sink have cost 0.
    // to compute flow matches, run dfs n times (amount

```

*of left side nodes).*

## 5 Data Structures

### 5.1 Disjoint Set Union

```

struct UnionFind{
    int ran, pad, tam;
};
UnionFind uf[maxn];

int bus(int u){
    if (uf[u].pad!=u) uf[u].pad=bus(uf[u].pad);
    return uf[u].pad;
}

void unir(int u ,int v){
    u=bus(u); v=bus(v);
    if (u==v) return;
    if (uf[u].ran>uf[v].ran){
        uf[v].pad=u;
        uf[u].tam+=uf[v].tam;
    }
    else if (uf[u].ran<uf[v].ran) {
        uf[u].pad=v;
        uf[v].tam+=uf[u].tam;
    }
    else {
        uf[u].pad=v;
        uf[v].ran++;
        uf[v].tam+=uf[u].tam;
    }
    return;
}

void init(){
    for(i,0,n){
        uf[i].dad = i;
        uf[i].ran = 0;
        uf[i].tam = 1;
    }
}

```

### 5.2 DSU with Rollbacks

```

struct dsu_save {
    int v, rnkv, u, rnku;

    dsu_save() {}
    dsu_save(int v, int rnkv, int u, int rnku)
        : v(v), rnkv(rnkv), u(u), rnku(rnku) {}
}

```

```

};

struct dsu_with_rollbacks {
    vi p, rnk;
    int comps;
    stack<dsu_save> op;

    dsu_with_rollbacks() {}
    dsu_with_rollbacks(int n) {
        p.resize(n);
        rnk.resize(n);
        fore(i, 0, n) {
            p[i] = i;
            rnk[i] = 0;
        }
        comps = n;
    }

    int find_set(int v) {
        return (v == p[v]) ? v : find_set(p[v]);
    }

    bool unite(int v, int u) {
        v = find_set(v);
        u = find_set(u);
        if (v == u) return false;
        comps--;
        if (rnk[v] > rnk[u]) swap(v, u);
        op.push(dsu_save(v, rnk[v], u, rnk[u]));
        p[v] = u;
        if (rnk[u] == rnk[v]) rnk[u]++;
        return true;
    }

    void rollback() {
        if (op.empty()) return;
        dsu_save x = op.top();
        op.pop();
        comps++;
        p[x.v] = x.v;
        rnk[x.v] = x.rnk;
        p[x.u] = x.u;
        rnk[x.u] = x.rnk;
    }
};

struct query {
    int v, u;
    bool united;
    query(int _v, int _u) : v(_v), u(_u) {}
};

struct QueryTree {
    vector<vector<query>> t;
    dsu_with_rollbacks dsu;
    int T;

    QueryTree() {}
    QueryTree(int T, int n) : T(T) {
        dsu = dsu_with_rollbacks(n);
    }
};

```

```

        t.resize(4 * T + 4);
    }

    void add_to_tree(int v, int l, int r, int ul, int ur,
                    query& q) {
        if (ul > ur)
            return;
        if (l == ul && r == ur) {
            t[v].pb(q);
            return;
        }
        int mid = (l+r)/2;
        add_to_tree(2 * v, l, mid, ul, min(ur, mid), q);
        add_to_tree(2 * v + 1, mid + 1, r, max(ul, mid +
        1), ur, q);
    }

    void add_query(query q, int l, int r) {
        add_to_tree(1, 0, T - 1, l, r, q);
    }

    void dfs(int v, int l, int r, vi& ans) {
        for (query& q : t[v]) {
            q.united = dsu.unite(q.v, q.u);
        }
        if (l == r)
            ans[l] = dsu.comps;
        else {
            int mid = (l + r) / 2;
            dfs(2 * v, l, mid, ans);
            dfs(2 * v + 1, mid + 1, r, ans);
        }
        for (query q : t[v]) {
            if (q.united) dsu.rollback();
        }
    }

    vi solve() {
        vi ans(T);
        dfs(1, 0, T - 1, ans);
        return ans;
    }
};

void doit() {
    QueryTree qt(q+2, n+1); //Queries and nodes are 0-
                             //indexed.
    query edge(x, y); // Existing edge.
    // Add the living interval of an edge [l, r]. Close
    // all edges.
    qt.add_query(edge, l, r);
    // Answer queries: amount of CCs at each moment i.
    // Subtract -1 to the each answer.
    vi ans = qt.solve();
}

```

### 5.3 Fenwick Tree

```

const int maxn = 1e5+5;
int arr[maxn];
// Sum of values. (1-indexed).
void add(int x, int v){
    while (x <= maxn-5){
        arr[x] += v;
        x += lsb(x);
    }
}
// Getting to whole prefix.
int get(int x){
    int freq = 0;
    while (x > 0){
        freq += arr[x];
        x -= lsb(x);
    }
    return freq;
}

```

## 5.4 Merge Sort Tree

```

struct Node{
    vi v;
    void order(){
        sort(ALL(v));
    }
    int get(int val_l, int val_r){ //nos interesa saber
        //si al menos hay 1 elemento en el rango [val_l,
        //val_r]
        return lower_bound(ALL(v), val_l) != upper_bound(ALL
        (v), val_r);
    }
};

struct MSTree{
    vector <Node> st; int n;
    MTree(int n): st(4*n + 5), n(n) {}
    void upd(int node, int ini, int fin, int pos, int val
    ){
        st[node].v.pb(val);
        if (ini == fin) return;
        int mid = (ini+fin)/2;
        if (pos <= mid) upd(2*node, ini, mid, pos, val);
        else upd(2*node + 1, mid+1, fin, pos, val);
    }
    int query(int node, int ini, int fin, int l, int r,
    int val_l, int val_r){
        if (fin < l || r < ini) return 0;
        if (l <= ini && fin <= r) return st[node].get(
        val_l, val_r);
        int mid = (ini+fin)/2;
        return (query(2*node, ini, mid, l, r, val_l, val_r) |
        query(2*node + 1, mid+1, fin, l, r, val_l, val_r));
    }
};

```

```

}
void order(){ fore(i,1,4*n + 5) st[i].order();} //
    //after all insertions, sort all nodes.
void upd(int pos, int val){ upd(1,1,n,pos,val);}
int query(int l, int r, int val_l, int val_r){ return
    query(1,1,n,l,r,val_l,val_r);}
};

```

## 5.5 Monotonic Deque

```

const ll maxn = 2e5+10;
deque <int> q; //monotonic deque keeping maximums in
    front.

void add(int x){
    while(!q.empty() && q.back() < x) q.pop_back();
    q.pb(x);
}

void remove(int x){
    if (!q.empty() && q.front() == x) q.pop_front();
}

void clear(){
    while(!q.empty()) q.pop_back();
}

int getBest(){ return q.front(); }

```

## 5.6 Mo's Algorithm

```

const int maxn = 1e6+5;
struct qu{int l,r,id;};

ll n,nq,sq,res;

bool qcomp(const qu &a, const qu &b){
    if(a.l/sq!=b.l/sq) return a.l<b.l;
    return (a.l/sq)&l?a.r<b.r:a.r>b.r;
}

qu qs[maxn];
ll a[maxn],cnt[maxn],ans[maxn];

void add(int i){
    if (cnt[a[i]] == 0) res++;
    cnt[a[i]]++;
}

void remove(int i){
    cnt[a[i]]--;
    if (cnt[a[i]] == 0) res--;
}

ll get_ans(){
    return res;
}

```

```

}
void mos() { // example amount of distinct elements in [l,
r)
    fore(i, 0, nq) qs[i].id = i;
    sq = sqrt(n) + 0.5;
    sort(qs, qs + nq, qcomp); // sort the queries.
    int l = 0, r = 0;
    res = 0;
    fore(i, 0, nq) { // Must have queries like: [l, r)
        qu = qs[i];
        while(l > qu.l) add(--l);
        while(r < qu.r) add(r++);
        while(l < qu.l) remove(l++);
        while(r > qu.r) remove(--r);
        ans[qu.id] = get_ans();
    }
}

```

## 5.7 Ordered Set

```

// Tested with: https://cses.fi/problemset/task/1076
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>

using namespace __gnu_pbds;

typedef tree<pair<int, int>, null_type, less<pair<int,
int>>, rb_tree_tag, tree_order_statistics_node_update>
ordered_multiset;
typedef tree<int, null_type, less<int>, rb_tree_tag,
tree_order_statistics_node_update> ordered_set;

ordered_multiset omst;
// find_by_order(k): finds the element that is the Kth in
the set.
// order_of_key(k): finds the number of elements strictly
smaller than k (or {k, pos} if multiset).

ll get_kth_element(ll k) { return (*omst.find_by_order(k))
.fst; } // 0-indexed.

ll get_elements_less_than_k(ll k, ll pos) { return (omst.
order_of_key({k, pos})); }

void insert(ll val, ll pos) { omst.insert({val, pos}); }

void erase(ll val, ll pos) { omst.erase(omst.find_by_order
(omst.order_of_key({val, pos}))); }

```

## 5.8 Segment Tree 2D

```

int n, m;
const int MAXN = 1e3;

```

```

int a[MAXN][MAXN], st[2*MAXN][2*MAXN];
const int NEUT = 0;

int op(int x, int y) { return x + y; }

void build() {
    fore(i, 0, n) fore(j, 0, m) st[i+n][j+m] = a[i][j];
    fore(i, 0, n) for(int j = m-1; j >= 0; --j)
        st[i+n][j] = op(st[i+n][j << 1], st[i+n][j
<< 1 | 1]);
    for(int i = n-1; i >= 0; --i) fore(j, 0, 2*m)
        st[i][j] = op(st[i << 1][j], st[i << 1 | 1][j]);
}

void upd(int x, int y, int v) { // [x, y] coordinates, and
value v.
    st[x+n][y+m] = v;
    for(int j = y+m; j > 1; j >= 1) st[x+n][j >= 1] = op(st[x+n][
j], st[x+n][j ^ 1]);
    for(int i = x+n; i > 1; i >= 1) for(int j = y+m; j >= 1)
        st[i >= 1][j] = op(st[i][j], st[i ^ 1][j]);
}

// (x0, y0) inclusive, (x1, y1) exclusive (excluding that
row and column).
int query(int x0, int y0, int x1, int y1) {
    int r = NEUT;
    for(int i0 = x0+n, i1 = x1+n; i0 < i1; i0 >= 1, i1 >= 1) {
        int t[4], q = 0;
        if(i0 & 1) t[q++] = i0++;
        if(i1 & 1) t[q++] = --i1;
        fore(k, 0, q) for(int j0 = y0+m, j1 = y1+m; j0 < j1;
j0 >= 1, j1 >= 1) {
            if(j0 & 1) r = op(r, st[t[k]][j0++]);
            if(j1 & 1) r = op(r, st[t[k]][--j1]);
        }
    }
    return r;
}

```

## 5.9 Segment Tree Beats

```

const ll maxn = 2e5 + 5;
const ll lzneut = 0;
const ll neut = 0;
const ll INF = 1e18 + 5;

struct Node {
    ll sum, max1, max2, maxc, min1, min2, minc, lazy;
};

ll a[maxn], N;

struct STBeats {
    vector<Node> st; int n;
    STBeats(int n): st(4*n + 5), n(n) {}
}

```



```

void merge(int t) {
    // sum
    st[t].sum = st[t << 1].sum + st[t << 1 | 1].sum;

    // max
    if (st[t << 1].max1 == st[t << 1 | 1].max1) {
        st[t].max1 = st[t << 1].max1;
        st[t].max2 = max(st[t << 1].max2, st[t << 1 | 1].max2);
        st[t].maxc = st[t << 1].maxc + st[t << 1 | 1].maxc;
    } else {
        if (st[t << 1].max1 > st[t << 1 | 1].max1) {
            st[t].max1 = st[t << 1].max1;
            st[t].max2 = max(st[t << 1].max2, st[t << 1 | 1].max1);
            st[t].maxc = st[t << 1].maxc;
        } else {
            st[t].max1 = st[t << 1 | 1].max1;
            st[t].max2 = max(st[t << 1].max1, st[t << 1 | 1].max2);
            st[t].maxc = st[t << 1 | 1].maxc;
        }
    }

    // min
    if (st[t << 1].min1 == st[t << 1 | 1].min1) {
        st[t].min1 = st[t << 1].min1;
        st[t].min2 = min(st[t << 1].min2, st[t << 1 | 1].min2);
        st[t].minc = st[t << 1].minc + st[t << 1 | 1].minc;
    } else {
        if (st[t << 1].min1 < st[t << 1 | 1].min1) {
            st[t].min1 = st[t << 1].min1;
            st[t].min2 = min(st[t << 1].min2, st[t << 1 | 1].min1);
            st[t].minc = st[t << 1].minc;
        } else {
            st[t].min1 = st[t << 1 | 1].min1;
            st[t].min2 = min(st[t << 1].min1, st[t << 1 | 1].min2);
            st[t].minc = st[t << 1 | 1].minc;
        }
    }
}

void push_add(int t, int tl, int tr, ll v) {
    if (v == 0) { return; }
    st[t].sum += (tr - tl + 1) * v;
    st[t].max1 += v;
    if (st[t].max2 != -INF) { st[t].max2 += v; }
    st[t].min1 += v;

```

```

    if (st[t].min2 != INF) { st[t].min2 += v; }
    st[t].lazy += v;
}

// corresponds to a chmin update
void push_max(int t, ll v, bool l) {
    if (v >= st[t].max1) { return; }
    st[t].sum -= st[t].max1 * st[t].maxc;
    st[t].max1 = v;
    st[t].sum += st[t].max1 * st[t].maxc;
    if (l) {
        st[t].min1 = st[t].max1;
    } else {
        if (v <= st[t].min1) {
            st[t].min1 = v;
        } else if (v < st[t].min2) {
            st[t].min2 = v;
        }
    }
}

// corresponds to a chmax update
void push_min(int t, ll v, bool l) {
    if (v <= st[t].min1) { return; }
    st[t].sum -= st[t].min1 * st[t].minc;
    st[t].min1 = v;
    st[t].sum += st[t].min1 * st[t].minc;
    if (l) {
        st[t].max1 = st[t].min1;
    } else {
        if (v >= st[t].max1) {
            st[t].max1 = v;
        } else if (v > st[t].max2) {
            st[t].max2 = v;
        }
    }
}

void pushdown(int t, int tl, int tr) {
    if (tl == tr) return;
    // sum
    int tm = (tl + tr) >> 1;
    push_add(t << 1, tl, tm, st[t].lazy);
    push_add(t << 1 | 1, tm + 1, tr, st[t].lazy);
    st[t].lazy = 0;

    // max
    push_max(t << 1, st[t].max1, tl == tm);
    push_max(t << 1 | 1, st[t].max1, tm + 1 == tr);

    // min
    push_min(t << 1, st[t].min1, tl == tm);
    push_min(t << 1 | 1, st[t].min1, tm + 1 == tr);
}

void build(int t = 1, int tl = 0, int tr = N - 1) {

```

```

    st[t].lazy = 0;
    if (tl == tr) {
        st[t].sum = st[t].max1 = st[t].min1 = a[tl];
        st[t].maxc = st[t].minc = 1;
        st[t].max2 = -INF;
        st[t].min2 = INF;
        return;
    }

    int tm = (tl + tr) >> 1;
    build(t << 1, tl, tm);
    build(t << 1 | 1, tm + 1, tr);
    merge(t);
}

// [l, r] ai += b
void update_add(int l, int r, ll v, int t = 1, int tl = 0, int tr = N - 1) {
    if (r < tl || tr < l) { return; }
    if (l <= tl && tr <= r) {
        push_add(t, tl, tr, v);
        return;
    }
    pushdown(t, tl, tr);

    int tm = (tl + tr) >> 1;
    update_add(l, r, v, t << 1, tl, tm);
    update_add(l, r, v, t << 1 | 1, tm + 1, tr);
    merge(t);
}

// [l, r] ai = min(ai, x)
void update_chmin(int l, int r, ll v, int t = 1, int tl = 0, int tr = N - 1) {
    if (r < tl || tr < l || v >= st[t].max1) { return; }
    if (l <= tl && tr <= r && v > st[t].max2) {
        push_max(t, v, tl == tr);
        return;
    }
    pushdown(t, tl, tr);

    int tm = (tl + tr) >> 1;
    update_chmin(l, r, v, t << 1, tl, tm);
    update_chmin(l, r, v, t << 1 | 1, tm + 1, tr);
    merge(t);
}

// [l, r] ai = max(ai, x)
void update_chmax(int l, int r, ll v, int t = 1, int tl = 0, int tr = N - 1) {
    if (r < tl || tr < l || v <= st[t].min1) { return; }
    if (l <= tl && tr <= r && v < st[t].min2) {
        push_min(t, v, tl == tr);
        return;
    }
    pushdown(t, tl, tr);

```

```

    int tm = (tl + tr) >> 1;
    update_chmax(l, r, v, t << 1, tl, tm);
    update_chmax(l, r, v, t << 1 | 1, tm + 1, tr);
    merge(t);
}

// print sum [l, r]
ll query_sum(int l, int r, int t = 1, int tl = 0, int tr = N - 1) {
    if (r < tl || tr < l) { return 0; }
    if (l <= tl && tr <= r) { return st[t].sum; }
    pushdown(t, tl, tr);

    int tm = (tl + tr) >> 1;
    return query_sum(l, r, t << 1, tl, tm) +
           query_sum(l, r, t << 1 | 1, tm + 1, tr);
}
};

```

## 5.10 Segment Tree Lazy

```

const ll maxn = 2e5+100;
const ll lzneut = 0;
const ll neut = 0;

ll a[maxn];

struct STree{ // Lazy Segment Tree with set and add
updates with sum get query.
    vi st, lzadd, lzset; int n;
    STree(int n): st(4*n + 5, neut), lzadd(4*n + 5, 0), lzset
        (4*n + 5, 0), n(n) {}

    void build(int node, int ini, int fin){
        if (ini == fin){
            st[node] = a[ini];
            return;
        }
        int mid = (ini+fin)/2;
        build(2*node, ini, mid);
        build(2*node + 1, mid+1, fin);
        st[node] = st[2*node] + st[2*node + 1];
    }

    void increment(int node, int ini, int fin, ll val){
        lzadd[node] += val;
        st[node] += (fin-ini+1)*val;
    }

    void assign(int node, int ini, int fin, ll val){
        lzset[node] = val;
        lzadd[node] = 0;
        st[node] = (fin-ini+1)*val;
    }

    void push(int node, int ini, int fin){

```

```

    int mid = (ini+fin)/2;
    if (lzset[node]){
        assign(2*node, ini, mid, lzset[node]);
        assign(2*node + 1, mid+1, fin, lzset[node]);
        lzset[node] = 0;
    }
    if (lzadd[node]){
        increment(2*node, ini, mid, lzadd[node]);
        increment(2*node + 1, mid+1, fin, lzadd[node]);
        lzadd[node] = 0;
    }
}

void setUpdate(int node, int ini, int fin, int l, int
r, ll val){
    if (fin < l || r < ini) return;
    if (l <= ini && fin <= r){
        assign(node, ini, fin, val);
        return;
    }
    push(node, ini, fin);
    ll mid = (ini+fin)/2;
    setUpdate(2*node, ini, mid, l, r, val);
    setUpdate(2*node + 1, mid+1, fin, l, r, val);
    st[node] = st[2*node] + st[2*node + 1];
}

void addUpdate(int node, int ini, int fin, int l, int
r, ll val){
    if (fin < l || r < ini) return;
    if (l <= ini && fin <= r){
        increment(node, ini, fin, val);
        return;
    }
    push(node, ini, fin);
    ll mid = (ini+fin)/2;
    addUpdate(2*node, ini, mid, l, r, val);
    addUpdate(2*node + 1, mid+1, fin, l, r, val);
    st[node] = st[2*node] + st[2*node + 1];
}

ll query(int node, int ini, int fin, int l, int r){
    if (fin < l || r < ini) return neut;
    if (l <= ini && fin <= r){
        return st[node];
    }
    push(node, ini, fin);
    int mid = (ini+fin)/2;
    ll lsum = query(2*node, ini, mid, l, r);
    ll rsum = query(2*node + 1, mid+1, fin, l, r);
    st[node] = st[2*node] + st[2*node + 1];
    return lsum + rsum;
}

void build(){ build(1,1,n); } //[1,n]
void setUpdate(int l, int r, ll val){ setUpdate(1,1,n

```

```

, l, r, val); } //[1,r]
void addUpdate(int l, int r, ll val){ addUpdate(1,1,n
, l, r, val); } //[1,r]
ll query(int l, int r){ return query(1,1,n,l,r); } //[
l,r]
};

```

## 5.11 Segment Tree

```

const ll maxn = 2e5+10;
ll a[maxn];

struct STree{
    vi st; int n;
    STree(int n): st(4*n + 5), n(n) {}

    void build(int node, int ini, int fin){
        if (ini == fin) {
            st[node] = a[ini];
            return;
        }
        int mid = (ini+fin)/2;
        build(2*node, ini, mid); //Left sohn
        build(2*node + 1, mid+1, fin); //Right sohn
        st[node] = (st[2*node] + st[2*node + 1]); //
        desired operation
        return;
    }

    ll query(int node, int ini, int fin, int l, int r){
        if (l <= ini && fin <= r) return st[node]; //
        Fully in
        if (ini > r || fin < l) return 0; //Fully out
        int mid = (ini+fin)/2;
        return (query(2*node, ini, mid, l, r) + query(2*node
+ 1, mid+1, fin, l, r));
    }

    void upd(int node, int ini, int fin, int pos, ll val){
        if (fin < pos || pos < ini) return; //Fully out
        if (ini == fin && ini == pos) {
            st[node] = val;
            return;
        }
        int mid = (ini+fin)/2;
        upd(2*node, ini, mid, pos, val);
        upd(2*node + 1, mid+1, fin, pos, val);
        st[node] = (st[2*node] + st[2*node + 1]);
        return;
    }

    void build(){ build(1,1,n); }
    void upd(int pos, ll val){ upd(1,1,n,pos,val); }
    ll query(int l, int r){ return query(1,1,n,l,r); }
};

```

## 5.12 Sparse Table

```

const ll maxn = 2e5+500;
const ll INF = 1e18;
const ll loga = 22;
ll n,k,sp[maxn][loga],a[maxn];

ll query(int l, int r){
    //Check in steps of powers of 2.
    int tam = (r-l+1);
    ll res = INF;
    rofe(i,loga,0){
        if (tam & (1ll<<i)){
            res = min(res,sp[l][i]);
            l += (1ll<<i);
        }
    }
    return res;
}

void build(){ // Minimums sparse table.
    fore(i,1,n+1) sp[i][0]=a[i];
    fore(i,1,loga){
        fore(j,1,n+1){
            if (j + (1ll<<i) - 1 <= n){ //
                sp[j][i] = min(sp[j][i-1], sp[j + (1ll<<
                    i-1)][i-1]);
            }
        }
    }
}

```

## 5.13 Sqrt Decomposition

```

const int maxn = 5e5+10;
const int block_amount = 710; // block_amount squared
    should be > maxn.
vi b[710]; //blocks of the SQRT.
int a[maxn];
int n,bsize;

void build_blocks(){
    bsize = sqrt(n)+1;
    fore(i,0,n) b[i/bsize].pb(a[i]);

    fore(i,0,bsize+1) sort(ALL(b[i])); //sort the blocks.
}

ll query(int l, int r, ll x){ // in [l,r] get amount of
    values >= x.
    int ans=0;
    int cl = l/bsize;
    int cr = r/bsize;
    if (cl == cr){
        fore(i,l,r+1){

```

```

        if (x <= a[i]) ans++;
    }
}
else{
    fore(i,l,(cl+1)*bsize){ //get prefix:
        if (x <= a[i]) ans++;
    }
    fore(i,cl+1,cr){ //mid part:
        ans += (sz(b[i]) - (lower_bound(ALL(b[i]),x)
            - b[i].begin()));
    }
    fore(i,cr*bsize,r+1){ //get suffix:
        if (x <= a[i]) ans++;
    }
}
return ans;
}

void update(int pos, ll x){ // point update in O(bsize)
    int cb = pos/bsize;
    int idx = lower_bound(ALL(b[cb]),a[pos]) - b[cb].
        begin();
    b[cb][idx] = a[pos] = x;
    sort(ALL(b[cb]));
}

```

## 5.14 Treap Implicit

```

typedef struct Node *pnode;
const ll maxn = 1e6+10;

struct Node {
    Node(ll val) : val(val), weight(rand()), size(1),
        lazy_tag(0) {}
    ll val, sum; // val -> a[i], sum = sum of all a[i]
        in subtree
    ll weight, size;
    bool rev = false; // whether this range is
        reversed
    pnode l = nullptr;
    pnode r = nullptr;
    ll lazy_tag; // neutral value is 0.
};

int size(pnode node) { return node ? node->size : 0; }
ll sum(pnode node) { return node ? node->sum : 0; }

void push(pnode node) {
    if (!node) { return; }
    if (node->rev){ // need to reverse this range
        node->rev = false;
        swap(node->l, node->r);
        if (node->l) { node->l->rev ^= true; }
        if (node->r) { node->r->rev ^= true; }
    }
}

```

```

    }
    if (node->lazy_tag){ // need to update the sum of
                        this range.
        node->sum += node->lazy_tag * size(node);
        node->val += node->lazy_tag;
        if (node->l) { node->l->lazy_tag += node
                    ->lazy_tag;}
        if (node->r) { node->r->lazy_tag += node
                    ->lazy_tag;}
        node->lazy_tag = 0;
    }
}

void pull(pnode node) {
    if (!node) { return; }
    push(node->l), push(node->r);
    assert(!node->lazy_tag);
    node->size = size(node->l) + size(node->r) + 1;
    node->sum = sum(node->l) + sum(node->r) + node->
        val;
}

// merges treaps l and r into treap
void merge(pnode &node, pnode l, pnode r) {
    push(l), push(r);
    if (!l || !r) {
        node = l ? l : r;
    } else if (l->weight > r->weight) {
        merge(l->r, l->r, r), node = l;
    } else {
        merge(r->l, l, r->l), node = r;
    }
    pull(node);
}

// splits treap into l, r; l: [0, val), r: [val, )
void split(pnode node, pnode &l, pnode &r, int val) {
    if (!node) return void(l = r = nullptr);
    push(node);
    if (val > size(node->l)) {
        split(node->r, node->r, r, val - size(
            node->l) - 1), l = node;
    } else {
        split(node->l, l, node->l, val), r = node
        ;
    }
    pull(node);
}

struct Treap {
    Node *root = nullptr; // root of this treap

    void insert(int i, int x) {
        Node *l, *r;
        split(root, l, r, i);
        auto v = new Node(x);
        merge(l, l, v);
    }
}

```

```

        merge(root, l, r);
    }

    void del(int i) {
        Node *l, *r;
        split(root, l, r, i);
        split(r, root, r, l);
        merge(root, l, r);
    }

    void swap_intervals(int l1, int r1, int l2, int r2) {
        if (l1 > l2) {
            swap(l1, l2);
            swap(r1, r2);
        }
        assert(r1 <= l2);

        pnode a, b, c, d, e;
        split(root, a, b, l1);
        split(b, b, c, r1 - l1);
        split(c, c, d, l2 - r1);
        split(d, d, e, r2 - l2);

        merge(root, a, d);
        merge(root, root, c);
        merge(root, root, b);
        merge(root, root, e);
    }

    // updates the range [l, r)
    void upd(int l, int r, function<void(Node *)> f)
    {
        Node *a, *b, *c;
        split(root, a, b, l);
        split(b, b, c, r - l);
        if (b) { f(b); }
        // merge all the splits back into the
        main treap
        merge(root, a, b);
        merge(root, root, c);
    }

    // queries the range [l,r)
    template <typename R> R query(int l, int r,
        function<R(Node *)> f) {
        Node *a, *b, *c;
        split(root, a, b, l);
        split(b, b, c, r - l);
        assert(b);
        R x = f(b);
        merge(root, a, b);
        merge(root, root, c);
        return x;
    }

    void print_treap(pnode node) {
        if (!node) return;
        push(node);
    }
}

```

```

        print_treap(node->l);
        cout<<node->val<<" ";
        print_treap(node->r);
    }
    void print_all() {
        print_treap(root);
        cout << nl;
    }
};

void doit() {
    int pos, val, l, r, x;
    Treap treap;
    // insert:
    treap.insert(pos, val);
    // delete:
    treap.del(pos);
    // update [l, r] reverse:
    treap.upd(l, r, [] (Node *node) { node->rev ^= true;
    });
    // update [l, r] adding a value x:
    treap.upd(l, r, [x] (Node *node) { node->lazy_tag += x
    ; });
    // query for the sum in [l, r]
    ll range_sum = treap.query<ll>(l, r, [] (Node *node) {
        return node->sum; });
}

int main() { srand(time(0)); }

```

## 5.15 Treap

```

typedef struct item *pitem;
struct item {
    int pr, key, cnt;
    pitem l, r;
    item(int key): key(key), pr(rand()), cnt(1), l(0), r(0) {}
    item(int key, int pr): key(key), pr(pr), cnt(1), l(0), r(0) {}
};
int cnt(pitem t) { return t? t->cnt: 0; }
void upd_cnt(pitem t) { if(t) t->cnt = cnt(t->l) + cnt(t->r) + 1; }
void split(pitem t, int key, pitem& l, pitem& r) { // l: <
    key, r: >= key
    if(!t) l=r=0;
    else if(key < t->key) split(t->l, key, l, t->l), r=t;
    else split(t->r, key, t->r, r), l=t;
    upd_cnt(t);
}
void insert(pitem& t, pitem it) {
    if(!t) t=it;

```

```

    else if(it->pr > t->pr) split(t, it->key, it->l, it->r), t=it;
    else insert(it->key < t->key? t->l: t->r, it);
    upd_cnt(t);
}
void merge(pitem& t, pitem l, pitem r) {
    if(!l||!r) t=l?l:r;
    else if(l->pr > r->pr) merge(l->r, l->r, r), t=l;
    else merge(r->l, l, r->l), t=r;
    upd_cnt(t);
}
void erase(pitem& t, int key) {
    if(t->key==key) merge(t, t->l, t->r);
    else erase(key < t->key? t->l: t->r, key);
    upd_cnt(t);
}
void unite(pitem& t, pitem l, pitem r) {
    if(!l||!r) { t=l?l:r; return; }
    if(l->pr < r->pr) swap(l, r);
    pitem p1, p2; split(r, l->key, p1, p2);
    unite(l->l, l->l, p1); unite(l->r, l->r, p2);
    t=l; upd_cnt(t);
}
//Explore the treap going left or right according to the
//target value.
ll explore(pitem t, ll key) {
    if (!t) return 0;
    ll res = 0;
    if (t->key < key) {
        res += cnt(t->l) + 1;
        res += explore(t->r, key);
    }
    else { //t->key >= key
        res += explore(t->l, key);
    }
    return res;
}

void kthSmallest(pitem t, int sz, int &kth) {
    if (!t) return;
    if (cnt(t->l) + 1 == sz) {
        kth = t->key;
        return;
    }
    else if (cnt(t->l) + 1 < sz) {
        kthSmallest(t->r, sz - cnt(t->l) - 1, kth);
    }
    else kthSmallest(t->l, sz, kth);
}

void kthLargest(pitem t, int sz, ll &kth) {
    if (!t) return;
    if (cnt(t->r) + 1 == sz) {
        kth = t->key;
        return;
    }

```

```

    }
    else if (cnt(t->r) + 1 < sz){
        kthLargest(t->l, sz - cnt(t->r) - 1, kth);
    }
    else kthLargest(t->r, sz, kth);
}

void solveCrops(){ //Spoj prefix crops problem.
    map<ll, pitem> mp;
    ll n, q;
    cin>>n>>q;
    vector<ll> a(n);
    //Having individual treaps for each number.
    //The keys are the positions in the array.
    for(i, 0, n){
        cin>>a[i];
        insert(mp[a[i]], new item(i));
    }
    while(q--){
        int pos, nw;
        cin>>pos>>nw;
        erase(mp[a[pos]], pos);
        a[pos] = nw;
        insert(mp[a[pos]], new item(pos));
        //check amount of items equal to a[pos] in [0, pos
        )
        cout<<explore(mp[a[pos]], pos)<<nl;
    }
}

void solveDogs(){ //Codeforces Dogs Show problem.
    map<ll, pitem> mp;
    ll n, k, pos=0, best=0;
    cin>>n>>k;
    vector<ll> uni, a(n+1);
    for(i, 1, n+1){
        cin>>a[i];
        ll dif = max(0LL, a[i]-i);
        uni.pb(dif);
    }
    sort(ALL(uni));
    uni.erase(unique(ALL(uni)), uni.end());
    for(i, 1, n+1){
        insert(mp[max(0LL, a[i]-i)], new item(i));
    }
    for(i, 0, uni.size()){
        ll delay = uni[i];
        best = max(best, explore(mp[delay], k-delay));
        //join 2 treaps: {root, left, right};
        if (i+1<uni.size()) unite(mp[uni[i+1]], mp[uni[i]
            +1]), mp[delay]);
    }
    cout<<best<<nl;
}

```

```
int main(){ srand(time(0)); }
```

## 6 Math

### 6.1 Binary Exponentiation

```

const ll mod = 1e9+7;
ll expo(ll x, ll pw){
    ll res = 1;
    while(pw > 0){
        if(pw&1)
            res = (res*x)%mod;
        x = (x*x)%mod;
        pw >>= 1;
    }
    return res;
} // For mul-inverses: pw = mod-2

```

### 6.2 Binomial Coefficient

```

const ll maxn = 1e6 + 5;
const ll mod = 1e9+7;
ll f[maxn];

ll expo(ll x, ll pw){
    ll res = 1;
    while(pw > 0){
        if(pw&1)
            res = (res*x)%mod;
        x = (x*x)%mod;
        pw >>= 1;
    }
    return res;
}

ll nCk(ll a, ll b){ //precalculate factorials % mod.
    b = (f[b]*f[a-b])%mod;
    ll inverse = expo(b, mod-2);
    ll res = (f[a]*inverse)%mod;
    return res;
}

```

### 6.3 Bitwise AND Convolution

```

const ll mod = 998244353;

void supersetZetaTransform(vi &v){
    int n = sz(v); // n must be a power of 2.
    for(int j = 1; j<n; j <= 1){
        fore(i, 0, n){

```

```

        if (i&j) v[i^j] += v[i], v[i^j] %= mod;
    }
}

void supersetMobiusTransform(vi &v){
    int n = sz(v); // n must be a power of 2.
    for(int j = 1; j<n; j <= 1){
        fore(i,0,n){
            if (i&j) v[i^j] -= v[i], v[i^j] += mod, v[i^j]
                ] %= mod;
        }
    }
}

// c_k = Total sum where (i,j), i&j = k of a_i*b_j
vi andConvolution(vi a, vi b){
    supersetZetaTransform(a);
    supersetZetaTransform(b);
    fore(i,0,sz(a)) a[i] *= b[i], a[i] %= mod;
    supersetMobiusTransform(a);
    return a;
}

void doit(){
    n = 1<<n;
    // Then read values of a and b arrays.
    // get the answer vector.
    // apply modulo when printing answers.
}

```

## 6.4 Bitwise OR Convolution

```

const ll mod = 998244353;

void subsetZetaTransform(vi &v){
    int n = sz(v); // n must be a power of 2.
    for(int j = 1; j<n; j <= 1){
        fore(i,0,n){
            if (i&j) v[i] += v[i^j], v[i] %= mod;
        }
    }
}

void subsetMobiusTransform(vi &v){
    int n = sz(v); // n must be a power of 2.
    for(int j = 1; j<n; j <= 1){
        fore(i,0,n){
            if (i&j) v[i] -= v[i^j], v[i] += mod, v[i] %=
                mod;
        }
    }
}

// c_k = Total sum where (i,j), i|j = k of a_i*b_j
vi orConvolution(vi a, vi b){

```

```

    subsetZetaTransform(a);
    subsetZetaTransform(b);
    fore(i,0,sz(a)) a[i] *= b[i], a[i] %= mod;
    subsetMobiusTransform(a);
    return a;
}

void doit(){
    // read a and b arrays.
    // get the answer vector
    // print answers % mod.
}

```

## 6.5 Bitwise XOR Convolution

```

const int mod = 998244353;

int inverse(int x, int mod) {
    return x == 1 ? 1 : mod - mod / x * inverse(mod %
        x, mod) % mod;
}

void xormul(vi a, vi b, vi &c){
    int m = sz(a);
    c.resize(m);
    for (int n = m / 2; n > 0; n /= 2)
        for (int i = 0; i < m; i += 2 * n)
            for (int j = 0; j < n; j++) {
                int x = a[i + j], y = a[i
                    + j + n];
                a[i + j] = (x + y) % mod;
                a[i + j + n] = (x - y +
                    mod) % mod;
            }
    for (int n = m / 2; n > 0; n /= 2)
        for (int i = 0; i < m; i += 2 * n)
            for (int j = 0; j < n; j++) {
                int x = b[i + j], y = b[i
                    + j + n];
                b[i + j] = (x + y) % mod;
                b[i + j + n] = (x - y +
                    mod) % mod;
            }
    fore(i,0,m) c[i] = a[i] * b[i] % mod;
    for (int n = 1; n < m; n *= 2)
        for (int i = 0; i < m; i += 2 * n)
            for (int j = 0; j < n; j++) {
                int x = c[i + j], y = c[i
                    + j + n];
                c[i + j] = (x + y) % mod;
                c[i + j + n] = (x - y +
                    mod) % mod;
            }
    int mrev = inverse(m, mod);
}

```



```

    fore(i,0,m) c[i] = c[i] * mrev % mod;
}
// Given two arrays of size 2^N, find:
// c_k = Total_Sum of (i,j) where (i [XOR] j) == k, a_i * b_j
void doit() {
    int n;
    vi a(1<<n), b(1<<n), c; //c is answer vector of size (1<<n).
}

```

## 6.6 Catalan Numbers

```

const ll mod = 1e9+7;
const ll maxn = 1e5+5;
int catalan[maxn+5];
void init() {
    catalan[0] = catalan[1] = 1;
    for (int i=2; i<=maxn; i++) {
        catalan[i] = 0;
        for (int j=0; j < i; j++) {
            catalan[i] += (catalan[j] * catalan[i-j-1]) % mod;
            if (catalan[i] >= mod) {
                catalan[i] -= mod;
            }
        }
    }
}
/*
Formula to get the nth catalan: C_n = (1/(n+1)) * nck(2*n, n)
Applications of Catalan Numbers, where C_n is:
> Number of correct bracket sequence consisting of 'n'
  ' opening and 'n' closing brackets.
> The number of rooted full binary trees with 'n + 1'
  leaves (vertices are not numbered).
  A rooted binary tree is full if every vertex has
  either two children or no children
> The number of ways to completely parenthesize 'n +
  1' factors.
> The number of triangulations of a convex polygon
  with 'n + 2' sides (i.e. the number of
  partitions of polygon into disjoint triangles by
  using the diagonals).
> The number of ways to connect the '2n' points on a
  circle to form 'n' disjoint chords.
> The number of non-isomorphic full binary trees with
  'n' internal nodes (i.e. nodes
  having at least one son).
> The number of monotonic lattice paths from point
  (0, 0) to point (n, n) in a square lattice

```

```

of size 'n' x 'n', which do not pass above the main
diagonal (i.e. connecting '(0, 0)' to
'(n, n)')
> Number of permutations of length 'n' that can be
  stack sorted (i.e. it can be shown that the
  rearrangement is stack sorted if and only if there
  is no such index i < j < k, such that
  a_k < a_i < a_j).
> The number of non-crossing partitions of a set of '
  n' elements.
> The number of ways to cover the ladder 1...n using
  'n' rectangles (The ladder consists of
  'n' columns, where i-th column has a height i).
*/

```

## 6.7 Euler Totient

```

vector <int> phi;
//Amount of coprime numbers (gcd(a,b) == 1) for each
  number in (1 <= i <= n).
//counting the number of integers between 1 and i, which
  are coprime to i.
void euler_totient(int n) {
    phi.resize(n+1);
    for (int i = 0; i <= n; i++) phi[i] = i;
    for (int i = 2; i <= n; i++) {
        if (phi[i] == i) {
            for (int j = i; j <= n; j += i)
                phi[j] -= phi[j] / i;
        }
    }
}
//Amount of numbers 0 <= i < m such that gcd(a+i,m) ==
  gcd(a,m)
int phiFunc(int a, int m) {
    ll y = m / __gcd(a, m);
    ll ans = y;
    for (ll i = 2; i * i <= m; i++) {
        if (y % i == 0) {
            ans -= ans / i;
            while (y % i == 0) y /= i;
        }
    }
    if (y > 1) ans -= ans / y;
    return ans;
}

```

## 6.8 Extended Euclidean

```

//a * x + b * y = gcd(a,b), where a and b are given.

```

```

int gcd(int a, int b, int& x, int& y) {
    if (b == 0) {
        x = 1;
        y = 0;
        return a;
    }
    int x1, y1;
    int d = gcd(b, a % b, x1, y1);
    x = y1;
    y = x1 - y1 * (a / b);
    return d;
}

```

## 6.9 FFT

```

typedef pair<ll,ll> ii;
const ll MAXN=1<<20; //watch out with RTEs (increase MAXN)
):
typedef vector<ll> poly;
struct CD {
    double r,i;
    CD(double r=0, double i=0):r(r),i(i){}
    double real()const{return r;}
    void operator/=(const int c){r/=c, i/=c;}
};
CD operator*(const CD& a, const CD& b){
    return CD(a.r*b.r-a.i*b.i,a.r*b.i+a.i*b.r);}
CD operator+(const CD& a, const CD& b){return CD(a.r+b.r,
    a.i+b.i);}
CD operator-(const CD& a, const CD& b){return CD(a.r-b.r,
    a.i-b.i);}
const double pi=acos(-1.0);
CD cp1[MAXN+9],cp2[MAXN+9];
int R[MAXN+9];
void dft(CD* a, int n, bool inv){
    for(i,0,n)if(R[i]<i)swap(a[R[i]],a[i]);
    for(int m=2;m<=n;m*=2){
        double z=2*pi/m*(inv?-1:1);
        CD wi=CD(cos(z),sin(z));
        for(int j=0;j<n;j+=m){
            CD w(1);
            for(int k=j,k2=j+m/2;k2<j+m;k++,
                k2++){
                CD u=a[k];CD v=a[k2]*w;a[
                    k]=u+v;a[k2]=u-v;w=w*
                    wi;
            }
        }
    }
    if(inv)for(i,0,n)a[i]/=n;
}
poly multiply(poly& p1, poly& p2){
    int n=p1.size()+p2.size()+1;

```

```

    int m=1,cnt=0;
    while(m<=n)m+=m,cnt++;
    for(i,0,m){R[i]=0;for(j,0,cnt)R[i]=(R[i]<<1)|((
        i>>j)&1);}
    for(i,0,m)cp1[i]=0,cp2[i]=0;
    for(i,0,p1.size())cp1[i]=p1[i];
    for(i,0,p2.size())cp2[i]=p2[i];
    dft(cp1,m,false);dft(cp2,m,false);
    for(i,0,m)cp1[i]=cp1[i]*cp2[i];
    dft(cp1,m,true);
    poly res;
    n-=2;
    for(i,0,n)res.pb((ll)floor(cp1[i].real()+0.5));
    return res;
}

void getBigNumMulti(vector<ll> &c){ //Big numbers
    multiplication.
    vector<char> r;
    while(!c.empty()&&!c.back()) c.pop_back(); //quitar
    todos los 0 extras.
    if(c.empty()){
        cout<<0<<endl;
        return;
    }
    ll x=0;
    //Normalizar los coeficientes para representarlos
    como digitos.
    for(i,0,c.size()){
        x+=c[i];
        r.pb((char)(x%10) + '0');
        x/=10;
    }
    while(x){ //carry que sobra.
        r.pb((char)(x%10) + '0');
        x/=10;
    }
    reverse(ALL(r));
    for(i,0,r.size()) cout<<r[i];
    cout<<endl;
}

void stringMatchShift(){ //All possible scalar products
    with strings.
    string s;
    cin>>s;
    int n = s.size();
    vector<ll> a1(n,0),a2(2*n,0),b1(n,0),b2(2*n,0),
        c1(n,0),c2(2*n,0);
    vector<ll> ra,rb,rc;

    //Create binary polynomial for each letter.
    for(i,0,n){
        if (s[i] == 'a') a1[i] = 1;
        else if (s[i] == 'b') b1[i] = 1;
        else c1[i] = 1;
    }
}

```

```

}
//Make the dup for each letter to multiply:
fore(i,0,n){
    a2[i] = a2[i+n] = a1[i];
    b2[i] = b2[i+n] = b1[i];
    c2[i] = c2[i+n] = c1[i];
}
//Append the rest of the zeros (Step 1):
fore(i,0,n){
    a1.pb(0), b1.pb(0), c1.pb(0);
}
//Reverse the arrays (Step 2):
reverse(ALL(a1));
reverse(ALL(b1));
reverse(ALL(c1));
//Multiply the polynomials:
ra = multiply(a1,a2);
rb = multiply(b1,b2);
rc = multiply(c1,c2);
int shif = 1;
//Left shift match (Step 1, then Step 2):
for(int i = (2*n)-2; i>=n; i--){
    cout<<"L-shift: "<<shif<<" "<<ra[i] + rb[
        i] + rc[i]<<nl;
    shif++;
}
//Right shift match (Step 2, then Step 1):
shif = 1;
for(int i = n-2; i>=0; i--){
    cout<<"R-shift: "<<shif<<" "<<ra[i] + rb[
        i] + rc[i]<<nl;
    shif++;
}
}

//String matching with wildcards ('?')
vector<ll> string_matching(string &s, string &t) {
    int n = s.size(), m = t.size();
    vector<ll> s1(n), s2(n), s3(n);
    //assign any non zero number for non '?'s
    for(int i = 0; i < n; i++) s1[i] = s[i] == '?' ? 0 :
        s[i] - 'a' + 1;
    for(int i = 0; i < n; i++) s2[i] = s1[i] * s1[i];
    for(int i = 0; i < n; i++) s3[i] = s1[i] * s2[i];
    vector<ll> t1(m), t2(m), t3(m);
    for(int i = 0; i < m; i++) t1[i] = t[i] == '?' ? 0 :
        t[i] - 'a' + 1;
    for(int i = 0; i < m; i++) t2[i] = t1[i] * t1[i];
    for(int i = 0; i < m; i++) t3[i] = t1[i] * t2[i];
    reverse(ALL(t1));
    reverse(ALL(t2));
    reverse(ALL(t3));
    vector<ll> s1t3 = multiply(s1, t3);
    vector<ll> s2t2 = multiply(s2, t2);
    vector<ll> s3t1 = multiply(s3, t1);
}

```

```

vector<ll> res(n);
for(int i = 0; i < n; i++) res[i] = s1t3[i] - s2t2[i]
    * 2 + s3t1[i];
vector<ll> oc;
for(int i = m - 1; i < n; i++) if(res[i] == 0) oc.pb(
    i - m + 1);
return oc;
}

```

## 6.10 Fractions

```

struct frac{
    ll num, den;
    frac(){}
    frac(ll num, ll den):num(num), den(den){
        if(!num) den = 1;
        if(num > 0 && den < 0) num = -num, den = -den;
        simplify();
    }
    void simplify(){
        ll g = __gcd(abs(num), abs(den));
        if(g) num /= g, den /= g;
    }
    frac operator+(const frac& b){ return {num*b.den + b.
        num*den, den*b.den};}
    frac operator-(const frac& b){ return {num*b.den - b.
        num*den, den*b.den};}
    frac operator*(const frac& b){ return {num*b.num, den
        *b.den};}
    frac operator/(const frac& b){ return {num*b.den, den
        *b.num};}
    bool operator<(const frac& b)const{ return num*b.den
        < den*b.num; }
};

```

## 6.11 GCD Convolution

```

const ll mod = 998244353;
vi primeEnumerate(int n){
    vi p;
    vector<bool> b(n+1,1);
    fore(i,2,n+1){
        if(b[i]) p.pb(i);
        for(int j : p){
            if(i*j>n) break;
            b[i*j]=0;
            if(i%j == 0) break;
        }
    }
    return p;
}

```

```

void multipleZetaTransform(vi &v){
    const int n = sz(v)-1;
    for(int p : primeEnumerate(n)){
        for (int i = n/p; i; i--){
            v[i] = (v[i]+v[i*p])%mod;
        }
    }
}

void multipleMobiusTransform(vi &v){
    const int n = sz(v)-1;
    for(int p : primeEnumerate(n)){
        for(int i = 1; i*p <= n; i++){
            v[i] = (v[i]-v[i*p]+mod)%mod;
        }
    }
}

// c_k = TotalSum where gcd(i,j)=k of a_i*b_j modulo mod.
vi gcdConvolution(vi a, vi b){
    multipleZetaTransform(a);
    multipleZetaTransform(b);
    fore(i,0,sz(a)) a[i] = (a[i]*b[i])%mod;
    multipleMobiusTransform(a);
    return a;
}

void doit(){
    //insert elements between [1,n].
    // answers [1,n].
}

```

## 6.12 LCM Convolution

```

const ll mod = 998244353;
vi primeEnumerate(int n){ //Linear sieve.
    vi p;
    vector<bool> b(n+1,1);
    fore(i,2,n+1){
        if (b[i]) p.pb(i);
        for(int j : p){
            if (i*j>n) break;
            b[i*j]=0;
            if (i%j == 0) break;
        }
    }
    return p;
}

void divisorZetaTransform(vi &v){
    const int n = sz(v)-1;
    for(int p : primeEnumerate(n)){
        for (int i = 1; i*p <= n; i++){
            v[i*p] = (v[i*p]+v[i])%mod;
        }
    }
}

```

```

}
}

void divisorMobiusTransform(vi &v){
    const int n = sz(v)-1;
    for(int p : primeEnumerate(n)){
        for(int i = n/p; i; i--){
            v[i*p] = (v[i*p]-v[i]+mod)%mod;
        }
    }
}

// c_k = TotalSum where lcm(i,j)=k of a_i*b_j modulo mod.
vi lcmConvolution(vi a, vi b){
    divisorZetaTransform(a);
    divisorZetaTransform(b);
    fore(i,0,sz(a)) a[i] = (a[i]*b[i])%mod;
    divisorMobiusTransform(a);
    return a;
}

void doit(){
    //insert elements between [1,n].
    // answers [1,n].
}

```

## 6.13 Matrix Exponentiation Kth Term

```

const ll mod = 1e9+7;
ll tc,n,m,k;

vvi mul(vvi a, vvi b) {
    vvi c(sz(a), vi(sz(b[0])));
    for (int i = 0; i < sz(a); i++)
        for (int j = 0; j < sz(b); j++)
            for (int k = 0; k < sz(a); k++)
                (c[i][j] += a[i][k]*b[k][j]%mod)%=mod;
    return c;
}

vvi exp( vvi x, ll y) {
    vvi r(sz(x), vi(sz(x)));
    bool flag = false;
    while (y>0){
        if (y&1) {
            if (!flag) r = x, flag = true;
            else r = mul(r,x);
        }
        y=y>>1;
        x = mul(x,x);
    }
    return r;
}

void doit(){
}

```

```

// define base cases and solve directly.
// example f(0)=1, f(1)=2, f(2)=3.
// Function: F(n) = 3*F(n-1) + 2*F(n-2) + F(n-3) + 3.
mat[0] = {3,2,1,3};
mat[1] = {1,0,0,0};
mat[2] = {0,1,0,0};
mat[3] = {0,0,0,1}; //to keep the +3 constant.
vi iniv = {3,2,1,1}; //Initial vector.

mat = exp(mat,k-2); //subtract (dims-2) to k.
ll ans = 0;
fore(i,0,4){
    ll aux = (mat[0][i]*iniv[i])%mod;
    ans = (ans + aux)%mod;
}
}

```

## 6.14 Matrix Exponentiation

```

const ll mod = 1e9+7;
ll tc,n,m,k;

vvi mul(vvi a, vvi b) {
    vvi c(sz(a), vi(sz(b[0])));
    for (int i = 0; i < sz(a); i++)
        for (int j = 0; j < sz(b); j++)
            for (int k = 0; k < sz(a); k++)
                (c[i][j] += a[i][k]*b[k][j]%mod)%=mod; //
                //for amount of paths.
                //c[i][j] = min(c[i][j], a[i][k] + b[k][j]
                //); //for shortest path.
    return c;
}

vvi exp( vvi x, int y) { // matrix and desired power.
    vvi r(sz(x), vi(sz(x),0ll)); //0ll: amount of paths.
    INF: shortest path
    for (int i = 0; i < sz(x); i++) r[i][i] = 1; //1ll:
    amount of paths. 0ll: shortest path.
    while (y>0){
        if (y&1) {
            r = mul(r,x);
        }
        y=y>>1;
        x = mul(x,x);
    }
    return r;
}

void doit(){
    // build adjacency (or costs) matrix of size(n*n).
    // after exponentiating mat[i][j] denotes the path
    // from i to j.
}

```

## 6.15 Miller Rabin

```

ll mulmod(ll a, ll b, ll m){
    ll x = 0, y = a % m;
    while (b > 0) {
        if (b % 2 == 1) {
            x = (x + y) % m;
        }
        y = (y * 2) % m;
        b /= 2;
    }
    return x % m;
}

ll modulo(ll base, ll e, ll m) {
    ll x = 1;
    ll y = base;
    while (e > 0) {
        if (e % 2 == 1)
            x = (x * y) % m;
        y = (y * y) % m;
        e = e / 2;
    }
    return x % m;
}

bool Miller(ll p, int iteration) { //number and amount of
    iterations.
    if (p < 2) {
        return false;
    }
    if (p != 2 && p % 2 == 0) {
        return false;
    }
    ll s = p - 1;
    while (s % 2 == 0) {
        s /= 2;
    }
    for (int i = 0; i < iteration; i++) {
        ll a = rand() % (p - 1) + 1, temp = s;
        ll mod = modulo(a, temp, p);
        while (temp != p - 1 && mod != 1 && mod != p - 1) {
            mod = mulmod(mod, mod, p);
            temp *= 2;
        }
        if (mod != p - 1 && temp % 2 == 0) {
            return false;
        }
    }
    return true;
}

```

## 6.16 Mobius Function

```

const ll maxn = 1e7+1;
ll mobius[maxn], sum[maxn];
/* Mobius function: mu(n)
   mu(n) = 1, if n = 1.
   mu(n) = 0, if n has a squared prime factor.
   mu(n) = (-1)^k, if n is a product of k distinct prime
               factors.
*/
void computeMobius() {
    mobius[1] = -1;
    for (int i = 1; i < maxn; i++) {
        if (mobius[i]) {
            mobius[i] = -mobius[i];
            for (int j = 2 * i; j < maxn; j += i) {
                mobius[j] += mobius[i];
            }
        }
    }
}

```

## 6.17 Modular Int

```

struct mint {
    const static int M = 998244353;
    ll v = 0;
    mint() {}
    mint(ll v) { this->v = (v % M + M) % M; }
    mint operator+(const mint &o) const { return v +
        o.v; }
    mint &operator+=(const mint &o) {
        v = (v + o.v) % M;
        return *this;
    }
    mint operator*(const mint &o) const { return v *
        o.v; }
    mint operator-(const mint &o) const { return v -
        o.v; }
    mint &operator-=(const mint &o) {
        mint t = v - o.v;
        v = t.v;
        return *this;
    }
    mint operator^(int y) const {
        mint r = 1, x = v;
        for (y <= 1; y >= 1; x = x * x)
            if (y & 1) r = r * x;
        return r;
    }
    mint inv() const {
        assert(v);
        return *this ^ M - 2;
    }
    friend istream &operator>>(istream &s, mint &v) {
        return s >> v.v;
    }
    friend ostream &operator<<(ostream &s, const mint
        &v) { return s << v.v; }
}

```

```

}
friend ostream &operator<<(ostream &s, const mint
    &v) { return s << v.v; }
mint operator/(mint o) { return *this * o.inv();
}
};

```

## 6.18 NTT

```

// MAXN must be power of 2 !!
// MOD-1 needs to be a multiple of MAXN !!
// big mod and primitive root for NTT:
const int MOD=998244353, RT=3, MAXN=1<<21;
const int loga = 17;
typedef vector<ll> poly;

int mulmod(ll a, ll b) {return a*b%MOD;}
int addmod(int a, int b) {int r=a+b; if(r>=MOD) r-=MOD;
    return r;}
int submod(int a, int b) {int r=a-b; if(r<0) r+=MOD; return r
    ;}
int pm(ll a, ll e) {
    int r=1;
    while(e) {
        if(e&1) r=mulmod(r, a);
        e>>=1; a=mulmod(a, a);
    }
    return r;
}
int inv(int a) {return pm(a, MOD-2);}

struct CD {
    int x;
    CD(int x) : x(x) {}
    CD() {}
    int get() const {return x;}
};
CD operator*(const CD& a, const CD& b) {return CD(mulmod(a
    .x, b.x));}
CD operator+(const CD& a, const CD& b) {return CD(addmod(a
    .x, b.x));}
CD operator-(const CD& a, const CD& b) {return CD(submod(a
    .x, b.x));}
vector<int> rts(MAXN+9, -1);
CD root(int n, bool inv) {
    int r=rts[n]<0?rts[n]=pm(RT, (MOD-1)/n):rts[n];
    return CD(inv?pm(r, MOD-2):r);
}
CD cp1[MAXN+9], cp2[MAXN+9];
int R[MAXN+9];
void dft(CD* a, int n, bool inv) {
    fore(i, 0, n) if(R[i]<i) swap(a[R[i]], a[i]);
    for(int m=2; m<=n; m*=2) {
        CD wi=root(m, inv);
    }
}

```

```

        for(int j=0; j<n; j+=m) {
            CD w(1);
            for(int k=j, k2=j+m/2; k2<j+m; k++,
                k2++) {
                CD u=a[k]; CD v=a[k2]*w; a[
                    k]=u+v; a[k2]=u-v; w=w*
                    wi;
            }
        }
    }
    if(inv) {
        CD z(pm(n, MOD-2));
        fore(i, 0, n) a[i]=a[i]*z;
    }
}

poly multiply(poly& p1, poly& p2) {
    int n=p1.size()+p2.size()+1;
    int m=1, cnt=0;
    while(m<=n) m+=m, cnt++;
    fore(i, 0, m) { R[i]=0; fore(j, 0, cnt) R[i]=(R[i]<<1) | ((
        i>>j)&1); }
    fore(i, 0, m) cp1[i]=0, cp2[i]=0;
    fore(i, 0, p1.size()) cp1[i]=p1[i];
    fore(i, 0, p2.size()) cp2[i]=p2[i];
    dft(cp1, m, false); dft(cp2, m, false);
    fore(i, 0, m) cp1[i]=cp1[i]*cp2[i];
    dft(cp1, m, true);
    poly res;
    n-=2;
    fore(i, 0, n) res.pb(cp1[i].x);
    return res;
}

```

## 6.19 Pascal Triangle

```

const ll maxn = 1005;
const ll mod = 1e9+7;
ll c[maxn][maxn];

void pascal() {
    c[0][0] = 1;
    fore(i, 1, maxn) {
        c[i][0]=c[i][i]=1;
        fore(j, 1, i) c[i][j]=(c[i-1][j-1]+c[i-1][j])%mod;
    }
}

```

## 6.20 Sieve Linear

```

const ll maxn = 1e6+5;
ll lp[maxn];
vi primes;

```

```

void sieve_linear() {
    fore(i, 2, maxn) {
        if (!lp[i]) {
            lp[i]=i;
            primes.pb(i);
        }
        for (int j=0; j < sz(primes) && pr[j]<=lp[i] && i
            *pr[j]<maxn; j++) {
            lp[i * pr[j]] = pr[j];
        }
    }
}

```

## 6.21 Sieve

```

const ll maxn = 1e6+5;
bool c[maxn];

void sieve() {
    c[1]=true;
    fore(i, 1, maxn) {
        if (!c[i]) {
            for (int j = 2; i*j<maxn; j++) {
                criba[i*j] = true;
            }
        }
    }
}

```

## 6.22 Sieve Segmented

```

// Complexity  $O((R-L+1) * \log(\log(R)) + \sqrt{R} * \log(\log(R)))$ 
//  $R-L+1$  roughly  $1e7$   $R-- 1e12$ 
vector<bool> segmentedSieve(ll L, ll R) {
    // generate all primes up to  $\sqrt{R}$ 
    ll lim = sqrt(R);
    vector<bool> mark(lim + 1, false);
    vi primes;
    fore(i, 2, lim+1) {
        if (!mark[i]) {
            primes.emplace_back(i);
            for (ll j = i * i; j <= lim; j += i)
                mark[j] = true;
        }
    }
    vector<bool> isPrime(R - L + 1, true);
    for (ll i : primes)
        for (ll j = max(i * i, (L + i - 1) / i * i); j <= R;
            j += i)
            isPrime[j - L] = false;
}

```

```

if (L == 1)
    isPrime[0] = false;
return isPrime;
}

```

## 7 Dynamic Programming

### 7.1 Convex Hull Trick

```

const ll maxn = 1e5+5;
struct CHT { //For Optimizing DPs that can be modeled as
    y = mx + b.
    //This code is made to find the minimums. Maximums
    can also be found.
    //Use When slopes are in decreasing order for
    minimums: m1 > m2 > ... > mk
    //Use when slopes are in increasing order for
    maximums: m1 < m2 < ... < mk
    struct Line {
        ll slope, yIntercept;
        Line(ll slope, ll yIntercept) : slope(slope),
            yIntercept(yIntercept) {}
        ll val(ll x) {
            return slope * x + yIntercept;
        }
        ll intersect(Line y) {
            return (y.yIntercept - yIntercept + slope - y
                .slope - 1) / (slope - y.slope);
        }
    };
    deque<pair<Line, ll>> dq;
    void insert(ll slope, ll yIntercept) {
        Line newLine(slope, yIntercept);
        //Pop lines until all lines become useful.
        //Popping the lines that become irrelevant.
        // For minimums >=
        // For maximums <=
        while (!dq.empty() && dq.back().second >= dq.back()
            ().first.intersect(newLine)) dq.pop_back();

        if (dq.empty()) {
            dq.emplace_back(newLine, 0);
            return;
        }
        dq.emplace_back(newLine, dq.back().first.
            intersect(newLine));
    }
}

```

```

ll query(ll x) { //When x values are given in
    ascending order: x1 < x2 < .. xk.
    //Just need to use a deque, no need to use Binary
    Search.
    while (sz(dq) > 1) {
        if (dq[1].second <= x) dq.pop_front();
        else break;
    }
    return dq[0].first.val(x);
}

ll query2(ll x) { //Use Binary Search when x values
    are given without a specific order.
    auto qry = *lower_bound(dq.rbegin(), dq.rend(),
        make_pair(Line(0, 0), x),
        [&](const pair<Line, ll>
            &a, const pair<Line, ll>
            &b) {
            return a.second > b.
                second;
        });
    return qry.first.val(x);
}

};

ll dp[maxn], a[maxn], b[maxn];
void doit() {
    CHT cht;
    cht.insert(b[1], dp[1]); //slope and yIntercept.
    dp[2] = cht.query(a[2]);
    //...
}

```

### 7.2 Edit Distance

```

// O(m*n) donde cada uno es el tamaño de cada string
int editDist(string &s1, string &s2) {
    int m = sz(s1), n = sz(s2);
    int dp[m+1][n+1];
    for (i, 0, m+1)
        for (j, 0, n+1) {
            if (i==0) dp[i][j] = j;
            else if (j==0) dp[i][j] = i;
            else if (s1[i-1] == s2[j-1]) dp[i][j] = dp[i-1][j-1];
            else dp[i][j] = 1 + min({dp[i][j-1], // Insert
                dp[i-1][j], // Remove
                dp[i-1][j-1]}); // Replace
        }
    return dp[m][n];
}

```



}

## 7.3 Knapsack 01 Optimization

```

/* 0/1 Knapsack optimization where sum of all items is ~
   N
   There will be at most sqrt(N) different items.
   Array 'cnt' represents the count of a specific item.
*/
const ll maxn = 1e5+50;
const ll maxnsq = 400;

ll n,m,cnt[maxn],dp[maxnsq][maxn];
vi c;
void calculateDp(){ //DP in O(N*sqrt(N))
    dp[0][0]=0;
    fore(i,1,n+5) dp[0][i] = -1;
    fore(i,1,sz(c)){ // c is the array of unique items.
        fore(j,1,n+1){
            if(dp[i-1][j] >= 0)
                dp[i][j] = 0;
            else if(j-c[i] >= 0 && dp[i][j-c[i]] >= 0
                and dp[i][j-c[i]] < cnt[c[i]])
                dp[i][j] = dp[i][j-c[i]] + 1;
            else
                dp[i][j] = -1;
        }
    }
}

```

## 7.4 Longest Common Subsequence

```

const int maxn = 1005;
int dp[maxn][maxn];
int lcs(const string &s, const string &t){
    int n = sz(s), m = sz(t);
    fore(j,0,m+1) dp[0][j] = 0;
    fore(i,0,n+1) dp[i][0] = 0;
    fore(i,1,n+1){
        fore(j,1,m+1){
            dp[i][j] = max(dp[i-1][j], dp[i][j-1]);
            if (s[i-1] == t[j-1]){
                dp[i][j] = max(dp[i][j], dp[i-1][j-1] + 1);
            }
        }
    }
    return dp[n][m];
}

```

## 7.5 Longest Increasing Subsequence

```

// Longest increasing subsequence O(nlogn)
const ll INF = 1e18;
int lis(const vi &a) {
    int n = sz(a);
    vi d(n+1, INF);
    d[0] = -INF;

    for (int i = 0; i < n; i++) {
        int j = upper_bound(ALL(d), a[i]) - d.begin();
        if (d[j-1] < a[i] && a[i] < d[j]) d[j] = a[i];
    }

    int ans = 0;
    fore(i,0,n+1) if (d[i]<INF) ans = i;
    return ans;
}

```

## 7.6 Sum Over Subsets

```

const ll maxbit = 20;
const ll maxn = 1<<20;
ll dp[maxn][maxbit+1]; //{mask,last bit}
ll n,sos[maxn],a[maxn];

void sum_over_subsets(){
    fore(mask,0,maxn){
        dp[mask][0] = a[mask];
        fore(x,0,maxbit){
            dp[mask][x+1] = dp[mask][x];
            if (mask & (1<<x)){
                dp[mask][x+1] += dp[mask
                    - (1<<x)][x];
            }
        }
        sos[mask] = dp[mask][maxbit];
    }
}

```

## 8 Geometry

### 8.1 Template

```

const ld EPS = 1e-6;
const ll INF = 1e18;

struct Point {
    ld x, y; //cambiar tipo de dato de acuerdo al
    problema
    void read(){ cin>>x>>y; }
}

```

```

Point operator +(const Point& b) const { return Point
    {x+b.x, y+b.y}; } //suma de puntos
Point operator -(const Point& b) const { return Point
    {x-b.x, y-b.y}; } //resta de puntos
ll operator *(const Point& b) const { return (ll) x *
    b.y - (ll) y * b.x; }
bool operator <(const Point& b) const { return x == b
    .x ? y < b.y : x < b.x; }
void operator +=(const Point& b) { x += b.x; y += b.y
    ; }
void operator -=(const Point &b) { x -= b.x; y -= b.y
    ; }
void operator *=(const int k) { x *= k; y *= k; }
bool operator ==(const Point &b){
    if (b.x == (*this).x && b.y == (*this).y) return
        true;
    return false;
}
ld magnitude() const { return sqrt((x*x) + (y*y)); }
//longitud hipotenusa
ld dot (const Point &b){ return (x * b.x) + (y * b.y)
    ; } //producto punto.
// Si es el producto punto es positivo, el angulo
// entre los vectores es menor a 90 grados, igual a
// 0 los vectores son perpendiculares y si es
// negativo el angulo es obtuso.
ld dist (const Point &b){ return (*this - b).
    magnitude(); } //distancia entre 2 puntos.
ll cross(const Point& b, const Point& c) const { //
    Producto cruz
    ll cruz = (b - *this) * (c - *this);
    if (cruz < 0) return -1; //Clockwise (right)
    if (cruz > 0) return +1; //Counter-clockwise (
        left)
    return 0; //Collinear.
}
ld rawCross(const Point &a, const Point &b) const {
    return (a - *this) * (b - *this);
}
bool onSegment(Point p, Point r){ //checa si un punto
    esta en el segmento entre dos puntos (delimitado
    como si fuera un rectangulo)
    if ((*this).x <= max(p.x, r.x) && (*this).x >=
        min(p.x, r.x) && (*this).y <= max(p.y, r.y) &&
        (*this).y >= min(p.y, r.y)) return true;

    return false;
}
ld angleBetweenVectors(const Point &b){ //this: (b-a)
    , Point b: (c-a).
    ld ang = acos((*this).dot(b)/((*this).magnitude()
        * b.magnitude()));
    ang = (ang * 180.0) / PI;
    return ang; //return angle in degrees.
}

```

```

};
struct LineToPoint{ //calcula la distancia entre un punto
    y una recta.
    Point p1,p2;
    ld dist(Point refPoint){
        return abs((refPoint - p1) * (refPoint - p2)) /
            p1.dist(p2);
    }
};
ld degreesToRadians(ld degrees) {
    return degrees * PI / 180.0;
}
ld radiansToDegrees(ld radians){
    return radians * (180.0 / PI);
}
signed main(){}

```

## 8.2 Formulas

```

// Volume of a sphere.
ld volumeSphere(ld rad){
    return (4.0/3.0)*PI*rad*rad*rad;
}
// Volume of a sphere cap.
ld volumeCap(ld h, ld rad){
    return PI*h*h*(rad-(h/3.0));
}
// Area of a triangle given vertices A, B, and C
ld areaTriangle(Point A, Point B, Point C) {
    return fabs((A.x * (B.y - C.y) + B.x * (C.y - A.y) +
        C.x * (A.y - B.y)) / 2.0);
}
// Area of a circle
ld areaCircle(ld radius) {
    return PI * radius * radius;
}
// Area of a trapezoid given bases and height
ld areaTrapezoid(ld base1, ld base2, ld height) {
    return 0.5 * (base1 + base2) * height;
}
// Volume of a cone
ld volumeCone(ld radius, ld height) {
    return (PI * radius * radius * height) / 3.0;
}
// Volume of a cylinder
ld volumeCylinder(ld radius, ld height) {
    return PI * radius * radius * height;
}

```

```

}
// Volume of a rectangular prism
ld volumeRectPrism(ld length, ld width, ld height) {
    return length * width * height;
}

// Volume of a pyramid with a rectangular base
ld volumePyramid(ld length, ld width, ld height) {
    return (length * width * height) / 3.0;
}

// Area of a parallelogram given two vectors (base and height)
ld areaParallelogram(Point base, Point heightVec) {
    return fabs(base * heightVec);
}

// Perimeter of a polygon given vertices (assuming vertices are in order)
ld perimeterPolygon(vector<Point> &vertices) {
    ld perimeter = 0.0;
    fore(i, 0, sz(vertices)) {
        perimeter += vertices[i].dist(vertices[(i + 1) % sz(vertices)]);
    }
    return perimeter;
}

// Volume of a prism with base area and height
ld volumePrism(ld baseArea, ld height) {
    return baseArea * height;
}

// Surface area of a sphere
ld surfaceAreaSphere(ld radius) {
    return 4 * PI * radius * radius;
}

// Surface area of a cylinder
ld surfaceAreaCylinder(ld radius, ld height) {
    return 2 * PI * radius * (radius + height);
}

```

### 8.3 Angular Sweep

```

struct Point{
    ll x,y,nume,denom,idx,typ,quad;
};

ll quadrantLocation(Point p){ //4 quadrants in 2D space.
    if (p.x == 0 || p.y == 0){
        if (p.x == 0 && p.y == 0) return 0; //origin.
        else if (p.y == 0){
            if (p.x > 0) return 1;
            else return 3;
        }
    }
}

```

```

    }
    else{
        if (p.y > 0) return 2;
        else return 4;
    }
}
else{
    if (p.x > 0 && p.y > 0) return 1;
    else if (p.x < 0 && p.y > 0) return 2;
    else if (p.x < 0 && p.y < 0) return 3;
    else return 4;
}
}

ll n;
vector <Point> a,q1,q2,q3,q4;
vi active;

void init(){
    a.clear(), a.resize(0);
    q1.clear(), q1.resize(0);
    q2.clear(), q2.resize(0);
    q3.clear(), q3.resize(0);
    q4.clear(), q4.resize(0);
    active.clear(), active.resize(n+1);
}

bool cmp(Point p1, Point p2){
    ll f1 = p1.nume*p2.denom;
    ll f2 = p1.denom*p2.nume;
    if (f1 == f2){
        return p1.typ < p2.typ;
    }
    return f1 < f2;
}

void toqVector(Point &p){
    if (p.quad == 1) q1.pb(p);
    else if (p.quad == 2) q2.pb(p);
    else if (p.quad == 3) q3.pb(p);
    else q4.pb(p);
}

ld findXIntercept(Point p1, Point p2) {
    // Calculate the slope
    ld m = (ld) (p2.y - p1.y) / (ld) (p2.x - p1.x);

    // Calculate the y-intercept (b) using one of the points
    ld b = p1.y - m * p1.x;

    // Calculate the x-coordinate where y = 0
    ld xIntercept = -b / m;

    return xIntercept;
}

void angularSort(){

```

```

sort(ALL(q1), cmp);
sort(ALL(q2), cmp);
sort(ALL(q3), cmp);
sort(ALL(q4), cmp);
for(auto elm : q1) a.pb(elm);
for(auto elm : q2) a.pb(elm);
for(auto elm : q3) a.pb(elm);
for(auto elm : q4) a.pb(elm);
}

void angularSweep() { // go through the max amount of
    points from the origin [0,0]
    ll pos = 0;
    ll cnt = 0;
    ll cur = 0;
    ll ans = 0;
    while(cnt < 2*n) { //pass through all points twice.
        if (a[pos].typ == 1) { //activate
            cur++;
            active[a[pos].idx] = 1;
            ans = max(ans, cur);
        }
        else { //deactivate
            if (active[a[pos].idx] == 1) {
                cur--;
                active[a[pos].idx] = 0;
                cnt++;
            }
        }
        pos = (pos+1)%(2*n);
    }
    cout<<ans<<endl;
}

void lineSettings() {
    cin>>n;
    fore(i, 0, n) {
        Point p1, p2;
        cin>>p1.x>>p1.y>>p2.x>>p2.y;
        p1.idx = p2.idx = i;
        ll g1 = __gcd(abs(p1.x), abs(p1.y));
        ll g2 = __gcd(abs(p2.x), abs(p2.y));
        p1.nume = p1.y/g1;
        p1.denom = p1.x/g1;
        p2.nume = p2.y/g2;
        p2.denom = p2.x/g2;
        p1.quad = quadrantLocation(p1);
        p2.quad = quadrantLocation(p2);
        if (p1.quad > p2.quad) swap(p1, p2); //p1 estara
        en un cuadrante mas chico siempre.

        if (p1.quad == 1 && p2.quad == 3) {
            ld xInt = findXIntercept(p1, p2);
            if (xInt > 0.0) {
                p2.typ = 1;
                p1.typ = 2;
            }
        }
    }
}

```

```

        else {
            p1.typ = 1;
            p2.typ = 2;
        }
    }
    else if (p1.quad == 1 && p2.quad == 4) {
        p1.typ = 2;
        p2.typ = 1;
    }
    else if (p1.quad == 2 && p2.quad == 4) {
        ld xInt = findXIntercept(p1, p2);
        if (xInt > 0.0) {
            p2.typ = 1;
            p1.typ = 2;
        }
        else {
            p1.typ = 1;
            p2.typ = 2;
        }
    }
    else {
        if (p1.quad == p2.quad) {
            vector<Point> aux;
            aux.pb(p1);
            aux.pb(p2);
            sort(ALL(aux), cmp);
            p1 = aux[0];
            p2 = aux[1];
            p1.typ = 1;
            p2.typ = 2;
        }
        else if (p1.quad < p2.quad) {
            p1.typ = 1;
            p2.typ = 2;
        }
    }
    toqVector(p1);
    toqVector(p2);
}

void doit() {
    lineSettings();
    angularSort();
    angularSweep();
}

```

## 8.4 Check Parallelism

```

bool checkParallelism(Point p1, Point p2, Point p3, Point
p4) { //(p1 -- p2) es una linea (p3 -- p4) es la otra
linea.
    Point pr1 = {p2.x-p1.x, p2.y-p1.y};
    Point pr2 = {p4.x-p3.x, p4.y-p3.y};
    double cp = (pr1*pr2);
}

```

```

    return abs(cp) < EPS; //son paralelas si su producto
    cruz = 0.
}

```

## 8.5 Check Perpendicularity

```

bool checkPerpendicular(Point p1, Point p2, Point p3,
    Point p4) //(p1 -- p2) es una linea (p3 -- p4) es la
    otra linea.
    Point pr1 = {p2.x-p1.x,p2.y-p1.y};
    Point pr2 = {p4.x-p3.x,p4.y-p3.y};
    double dotp = pr1.dot(pr2);
    return abs(dotp) < EPS; // son perpendiculares si su
    producto punto = 0;
}

```

## 8.6 Circle-Line Intersection

```

vector <Point> circleLineIntersection(double a, double b,
    double c, double r){
    //Dados los coeficientes de la ecuacion de la recta y
    el radio del circulo con centro en el origen
    vector <Point> pts;
    double x0 = -a*c/(a*a+b*b), y0 = -b*c/(a*a+b*b);
    if (c*c > r*r*(a*a+b*b)+EPS){} // 0 points.
    else if (abs (c*c - r*r*(a*a+b*b)) < EPS) pts.pb({x0,
        y0}); // 1 point.
    else{ // 2 points.
        double d = r*r - c*c/(a*a+b*b);
        double mult = sqrt (d / (a*a+b*b));
        double ax, ay, bx, by;
        ax = x0 + b * mult;
        bx = x0 - b * mult;
        ay = y0 - a * mult;
        by = y0 + a * mult;
        pts.pb({ax,ay});
        pts.pb({bx,by});
    }
    return pts;
}

```

## 8.7 Closest Pair

```

ll closestPair(vector <pii> pts){
    //Calcula el par de puntos en 2D mas cercanos entre
    si, retorna su distancia euclidiana.
    int n = sz(pts);
    sort (ALL(pts));
    set<pii> s;

    ll ans = INF;

```

```

    int pos = 0;
    for(i,0,n){
        ll d = ceil(sqrt(ans));
        while (pts[i].first - pts[pos].first >= d) {
            s.erase({pts[pos].second, pts[pos].first});
            pos++;
        }

        auto it1 = s.lower_bound({pts[i].second - d, pts[
            i].first});
        auto it2 = s.upper_bound({pts[i].second + d, pts[
            i].first});

        for (auto it = it1; it != it2; it++) {
            ll dx = pts[i].first - it->second;
            ll dy = pts[i].second - it->first;
            if (ans > 1LL * dx * dx + 1LL *
                dy * dy){
                ans = 1LL * dx * dx + 1LL *
                    * dy * dy;
            }
        }
        s.insert({pts[i].second, pts[i].first});
    }
    return ans;
}

```

## 8.8 Convex Hull

```

vector <Point> calculateHull(vector <Point> &p, int n){
    //Calculo del Convex Hull
    if (n <= 2) return p;
    vector<Point> hull;
    int tam = 0;
    sort (ALL(p));
    for(t,0,2){
        for(i,0,n){
            while(sz(hull)-tam >= 2){
                Point p1 = hull[sz(hull)-2];
                Point p2 = hull[sz(hull)-1];
                //Producto cruz: P1 ---> P2 ---> P3
                //agregar (<=) si tambien se quieren
                incluir los puntos colineales, sino
                solo (<)
                if(p1.cross(p2, p[i]) <= 0) break;
                hull.pop_back();
            }
            hull.pb(p[i]);
        }
        hull.pop_back();
        tam = sz(hull);
        reverse (ALL(p));
    }
    return hull;
}

```

## 8.9 Equation of Line

```
// Dados 2 puntos de una recta, devuelve los coeficientes
// de Ax + By + C = 0
vector<ld> equation_of_line(Point p1, Point p2){
    ld a = p1.y-p2.y;
    ld b = p2.x-p1.x;
    ld c = -(a*p1.x) - (b*p1.y);
    return {a,b,c};
}
```

## 8.10 Line Intersection

```
bool doIntersect(Point p1, Point q1, Point p2, Point q2){
    //Checa si 2 lineas se intersectan o no.
    int o1 = p1.cross(q1, p2);
    int o2 = p1.cross(q1, q2);
    int o3 = p2.cross(q2, p1);
    int o4 = p2.cross(q2, q1);

    if (o1 != o2 && o3 != o4) return true;
    if (o1 == 0 && p2.onSegment(p1, q1)) return true;
    if (o2 == 0 && q2.onSegment(p1, q1)) return true;
    if (o3 == 0 && p1.onSegment(p2, q2)) return true;
    if (o4 == 0 && q1.onSegment(p2, q2)) return true;

    return false;
}
```

## 8.11 Planar Graph

```
// Sort the points counterclockwise around a reference
// point
bool sort_ccw(const Point& p, const Point& a, const Point
& b) {
    return atan2(a.y - p.y, a.x - p.x) < atan2(b.y - p.y,
        b.x - p.x);
}

// Find a face of the graph
vector<Point> find_face(map<Point, vector<Point>>&
    neighbors, const Point& u, const Point& v) {
    vector<Point> face;
    Point current = v, previous = u;
    face.pb(previous);
    while (true) {
        face.pb(current);
        vector<Point>& current_neighbors = neighbors[
            current];
```

```
        auto index = find(ALL(current_neighbors),
            previous) - current_neighbors.begin();
        int next_index = (index + 1) % sz(
            current_neighbors);
        Point next_vertex = current_neighbors[next_index
            ];
        if (next_vertex.x == u.x && next_vertex.y == u.y)
            break;
        previous = current;
        current = next_vertex;
    }
    face.pb(u);
    return face;
}

// Find the outer edge of the graph
pair<Point, Point> find_outer_edge(map<Point, vector<
    Point>>& mp) {
    auto leftmost = min_element(ALL(mp), [](const pair<
        Point, vector<Point>>& a, const pair<Point, vector
        <Point>>& b) {
        return tie(a.first.x, a.first.y) < tie(b.first.x,
            b.first.y);
    })->first;

    vector<Point>& N_leftmost = mp[leftmost];
    sort(ALL(N_leftmost), [&leftmost](const Point& a,
        const Point& b) {
        return sort_ccw(leftmost, a, b);
    });

    Point u = N_leftmost[0];
    return {leftmost, u};
}

void doit(){
    int n; // n points.
    map<Point, vector<Point>> mp; //adjacency list.
    set<pair<Point, Point>> seen; //seen edges.

    for (int i = 0; i < n; ++i) {
        ll x1, y1, x2, y2;
        cin >> x1 >> y1 >> x2 >> y2;
        Point p1 = {x1,y1}, p2 = {x2,y2};
        mp[p1].pb(p2);
        mp[p2].pb(p1);
    }

    for (auto& p : mp) {
        //Sort each adjacency list in counter-clockwise
        //order.
        sort(ALL(p.second), [&p](const Point& a, const
            Point& b) {
            return sort_ccw(p.first, a, b);
        });
    }
}
```

```

auto [p, q] = find_outer_edge(mp);
vector<Point> outer = find_face(mp, p, q);

for(i, 0, sz(outer)-1) seen.insert({outer[i], outer[(i+1)%sz(outer)]});

for (const auto& p : mp) { // find inner faces of the planar graph:
    for (const auto& q : p.second) {
        if (seen.count({p.first, q})) continue;
        seen.insert({p.first, q});
        vector<Point> face = find_face(mp, p.first, q);
        for(i, 0, sz(face)-1) seen.insert({face[i], face[(i+1)%sz(face)]});
    }
}
}

```

## 8.12 Point Inside Polygon Linear

```

// Checa si un punto dado esta DENTRO, FUERA o en FRONTERA con un poligono
string checkPointInsidePolygon(vector<Point> P, Point point, int n){
    P[0] = point;
    ll count = 0;
    if (n < 3) return "OUTSIDE";
    for(i, 1, n+1){
        int j = (i == n ? 1 : i+1);
        if(P[i].x <= P[0].x && P[0].x < P[j].x && P[0].cross(P[i], P[j]) < 0) count++;
        else if(P[j].x <= P[0].x && P[0].x < P[i].x && P[0].cross(P[j], P[i]) < 0) count++;

        if ((min(P[i].x, P[j].x) <= point.x && point.x <= max(P[i].x, P[j].x)) && (min(P[i].y, P[j].y) <= point.y && point.y <= max(P[i].y, P[j].y)) && point.cross(P[i], P[j]) == 0){
            return "BOUNDARY";
        }
    }
    if (count%2 == 1) return "INSIDE";
    return "OUTSIDE";
}

```

## 8.13 Point Inside Polygon Optimized

```

int sgn(ll val) { return val > 0 ? 1 : (val == 0 ? 0 : -1); }

bool pointInTriangle(Point a, Point b, Point c, Point point){

```

```

    ll s1 = abs(a.rawCross(b, c));
    ll s2 = abs(point.rawCross(a, b)) + abs(point.rawCross(b, c)) + abs(point.rawCross(c, a));
    return s1 == s2;
}

//Precalculation for queries to know if a point lies inside of a convex polygon.
void prepareConvexPolygon(int &n, vector<Point> &points, vector<Point> &seq, Point &translation){ //seq and translation are empty here.
    n = points.size();
    int pos = 0;
    for (int i = 1; i < n; i++) {
        if (points[i] < points[pos]) pos = i;
    }
    rotate(points.begin(), points.begin() + pos, points.end());
    n--;
    seq.resize(n);
    for (int i = 0; i < n; i++) seq[i] = points[i + 1] - points[0];
    translation = points[0];
}

//Know if a point lies inside of a convex polygon in O(logN)
bool pointInConvexPolygon(Point point, int &n, vector<Point> &seq, Point &translation) {
    point = point - translation;
    if (seq[0]*point != 0 && sgn(seq[0]*point) != sgn(seq[0]*seq[n-1])) return false;
    if (seq[n-1]*point != 0 && sgn(seq[n-1]*point) != sgn(seq[n-1]*seq[0])) return false;
    if (seq[0]*point == 0) return seq[0].dot(seq[0]) >= point.dot(point);
    int l = 0, r = n - 1;
    while (r - l > 1) {
        int mid = (l + r) / 2;
        int pos = mid;
        if (seq[pos]*point >= 0) l = pos;
        else r = pos;
    }
    int pos = l;
    return pointInTriangle(seq[pos], seq[pos + 1], Point{0, 0}, point);
}

void doit(){
    int n;
    vector<Point> poly; //with input.
    vector<Point> seq; //empty.
    Point translation;
    prepareConvexPolygon(n, poly, seq, translation);
}

```



```

    // then call pointInConvexPolygon() for queries.
}

```

## 8.14 Polygon Area

```

ld getPolygonArea(vector <Point> poly){ //Calculo de area
    de poligono
    ll ans = 0;
    poly.pb(poly.front());
    fore(i,1,sz(poly)) ans += (poly[i-1]*poly[i]);
    return abs(ans)/2.0;
}

```

## 9 Miscellaneous

### 9.1 Coordinate Compression

```

vi a;
map <ll,ll> mp;
int pos = 0;
sort(ALL(a));
st.erase(unique(ALL(a)),a.end());
for (auto au : a){
    mp[au] = pos;
    pos++;
}

```

### 9.2 Isomorphism Rooted

```

const ll maxn = 2e5+100;
map <vector <ll>, ll> mp;
ll idx=1;

int dfs(int anode, int node, vector < vector <ll> > &adj)
{
    vector <ll> v;
    for(auto au : adj[node]){
        if (anode != au) v.pb(dfs(node,au,adj));
    }
    sort(ALL(v));
    if (!mp.count(v)) mp[v] = idx, idx++;
    return mp[v];
}

void doit(){
    ll tree1 = dfs(1,1,adj);
    ll tree2 = dfs(1,1,adj2);
    cout<<(tree1 == tree2 ? "Same" : "Diff")<<nl;
}

```

### 9.3 Isomorphism Unrooted

```

vi center(int n, vvi &adj) {
    int deg[n+1] = {0};
    virtual v;
    for (int i = 1; i <= n; i++) {
        deg[i] = sz(adj[i]);
        if (deg[i] == 1)
            v.pb(i), deg[i]--;
    }
    int m = sz(v);
    while(m < n) {
        vi vv;
        for (auto i: v) {
            for (auto j: adj[i]) {
                deg[j]--;
                if (deg[j] == 1)
                    vv.pb(j);
            }
        }
        m += sz(vv);
        v = vv;
    }
    return v;
}

map<vi, ll> mp;
int idx = 0;

int dfs(int s, int p, vvi &adj) {
    vi v;
    for (auto i: adj[s]) {
        if (i != p)
            v.pb(dfs(i, s, adj));
    }
    sort(ALL(v));
    if (!mp.count(v)) mp[v] = idx++;
    return mp[v];
}

void doit(){
    // build adjacency lists (1-indexed nodes).
    vi v1 = center(n,adj), v2 = center(n,adj2);
    bool flag = false;
    int s1 = dfs(v1[0], -1, adj);
    for(auto s : v2){
        int s2 = dfs(s, -1, adj2);
        if (s1 == s2){
            flag=true;
            break;
        }
    }
    cout<<(flag ? "YES" : "NO")<<nl;
}

```



## 9.4 Max Subarray Sum

```

const ll maxn = 2e5+100;
ll a[maxn];

struct Node{
    ll max_sum, sumL, sumR, sum;
    Node operator+(Node b) {
        return {max(max(max_sum, b.max_sum), sumR + b.
                    sumL),
                max(sumL, sum + b.sumL), max(b.sumR,
                    sumR + b.sum),
                sum + b.sum};
    }
};

struct STree{
    vector<Node> st; int n;
    STree(int n): st(4*n + 5), n(n){}

    void build(int node, int ini, int fin){
        if (ini == fin){
            st[node] = {max(0ll, a[ini]), max(0ll, a[ini]
                )), max(0ll, a[ini]), a[ini]};
            return;
        }
        int mid = (ini+fin)/2;
        build(2*node, ini, mid);
        build(2*node + 1, mid+1, fin);
        st[node] = st[2*node] + st[2*node + 1];
    }

    void update(int node, int ini, int fin, int pos, ll
        val){
        if (fin < pos || pos < ini) return;
        if (ini == fin && ini == pos){
            st[node] = {max(0ll, val), max(0ll, val), max
                (0ll, val), val};
            return;
        }
        ll mid = (ini+fin)/2;
        update(2*node, ini, mid, pos, val);
        update(2*node + 1, mid+1, fin, pos, val);
        st[node] = st[2*node] + st[2*node + 1];
    }

    void build(){ build(1, 1, n); }
    void update(int pos, ll val){ update(1, 1, n, pos, val); }
};

void doit(){
    // read values and build ST.
    // queries: st.st[1].max_sum
}

```

## 9.5 Small to Large

```

const ll maxn = 2e5+5;
ll n, res[maxn];
vi adj[maxn];
set<ll> colors[maxn];

void dfs(int anode, int node){ //amount of distinct
    elements in a subtree.
    for(auto au : adj[node]){
        if (anode != au){
            dfs(node, au);
            //current node's set should always be the
            larger one.
            if (sz(colors[node]) < sz(colors[au])){
                swap(colors[node], colors[au]);
            }
            for(auto elm : colors[au]) colors[node].
                insert(elm);
        }
    }
    res[node] = sz(colors[node]);
}

```

## 9.6 Ternary Search 2D

```

const ld INF = 1e4+100;
const ld eps = 1e-5;

struct Point{ld x, y;};

ld costf(Point p){return 0;}

ld get_y(ld x){ // looking for minimums.
    ld l = -INF;
    ld r = INF;
    while(r - l > eps){
        ld m1 = l + (r - l) / 3;
        ld m2 = r - (r - l) / 3;
        Point p1, p2;
        p1 = {x, m1}, p2 = {x, m2};
        ld f1 = costf(p1)*(-1);
        ld f2 = costf(p2)*(-1);
        if (f1 < f2) l = m1;
        else r = m2;
    }
    return costf({x, (l+r)/2});
}

ld get_xy(){ // looking for minimums.
    ld l = -INF;
    ld r = INF;
    while(r - l > eps){
        ld m1 = l + (r - l) / 3;
        ld m2 = r - (r - l) / 3;
    }
}

```

```

        ld f1= get_y(m1)*(-1);
        ld f2 = get_y(m2)*(-1);
        if (f1 < f2) l = m1;
        else r = m2;
    }
    return get_y((l+r)/2);
}

void doit() {
    cout<<fixed<<setprecision(10)<<get_xy()<<nl;
}

```

---

## 9.7 Ternary Search

```

double f(double x){ return x; }

double ternary_search(double l, double r) { //use long
    doubles (ld) for more precision.

```

```

double eps = 1e-9;
while (r - l > eps) {
    double m1 = l + (r - l) / 3;
    double m2 = r - (r - l) / 3;
    double f1 = f(m1);
    double f2 = f(m2);
    if (f1 < f2)
        l = m1;
    else
        r = m2;
}
return f(l);
} //to find the minimum of a function, invert the sign
(-1) of the result of f(x)

```

---

## 10 Fin

## 11 Theory

### DP Optimization Theory

Name	Original Recurrence	Sufficient Condition	From	To
CH 1	$dp[i] = \min_{j < i} \{dp[j] + b[j] * a[i]\}$	$b[j] \geq b[j+1]$ Optionally $a[i] \leq a[i+1]$	$O(n^2)$	$O(n)$
CH 2	$dp[i][j] = \min_{k < j} \{dp[i-1][k] + b[k] * a[j]\}$	$b[k] \geq b[k+1]$ Optionally $a[j] \leq a[j+1]$	$O(kn^2)$	$O(kn)$
D&Q	$dp[i][j] = \min_{k < j} \{dp[i-1][k] + C[k][j]\}$	$A[i][j] \leq A[i][j+1]$	$O(kn^2)$	$O(kn \log n)$
Knuth	$dp[i][j] = \min_{i < k < j} \{dp[i][k] + dp[k][j]\} + C[i][j]$	$A[i, j-1] \leq A[i, j] \leq A[i+1, j]$	$O(n^3)$	$O(n^2)$

Notes:

- $A[i][j]$  - the smallest  $k$  that gives the optimal answer, for example in  $dp[i][j] = dp[i-1][k] + C[k][j]$
- $C[i][j]$  - some given cost function
- We can generalize a bit in the following way  $dp[i] = \min_{j < i} \{F[j] + b[j] * a[i]\}$ , where  $F[j]$  is computed from  $dp[j]$  in constant time

### Combinatorics

#### Sums

$$\begin{aligned}
 \sum_{k=0}^n k &= n(n+1)/2 & \binom{n}{k} &= \frac{n!}{(n-k)!k!} \\
 \sum_{k=a}^b k &= (a+b)(b-a+1)/2 & \binom{n}{k} &= \binom{n-1}{k} + \binom{n-1}{k-1} \\
 \sum_{k=0}^n k^2 &= n(n+1)(2n+1)/6 & \binom{n+1}{k} &= \frac{n+1}{n-k+1} \binom{n}{k} \\
 \sum_{k=0}^n k^3 &= n^2(n+1)^2/4 & \binom{n}{k+1} &= \frac{n-k}{k+1} \binom{n}{k} \\
 \sum_{k=0}^n k^4 &= (6n^5 + 15n^4 + 10n^3 - n)/30 & \binom{n}{k} &= \frac{n}{n-k} \binom{n-1}{k} \\
 \sum_{k=0}^n k^5 &= (2n^6 + 6n^5 + 5n^4 - n^2)/12 & \binom{n}{k} &= \frac{n-k+1}{k} \binom{n}{k-1} \\
 \sum_{k=0}^n x^k &= (x^{n+1} - 1)/(x - 1) & 12! &\approx 2^{28.8} \\
 \sum_{k=0}^n kx^k &= (x - (n+1)x^{n+1} + nx^{n+2})/(x-1)^2 & 20! &\approx 2^{61.1} \\
 1 + x + x^2 + \dots &= 1/(1-x)
 \end{aligned}$$

- Hockey-stick identity  $\sum_{i=r}^n \binom{i}{r} = \binom{n+1}{r+1}$
- Number of ways to color  $n$ -objects with  $r$ -colors if all colors must be used at least once  $\sum_{k=0}^r \binom{r}{k} (-1)^{r-k} k^n = \sum_{k=0}^r \binom{r}{r-k} (-1)^k (r-k)^n$

#### Binomial coefficients

Number of ways to pick a multiset of size  $k$  from  $n$  elements:  $\binom{n+k-1}{k}$

Number of  $n$ -tuples of non-negative integers with sum  $s$ :  $\binom{s+n-1}{n-1}$ , at most  $s$ :  $\binom{s+n}{n}$

Number of  $n$ -tuples of positive integers with sum  $s$ :  $\binom{s-1}{n-1}$

Number of lattice paths from  $(0,0)$  to  $(a,b)$ , restricted to east and north steps:  $\binom{a+b}{a}$

**Multinomial theorem.**  $(a_1 + \dots + a_k)^n = \sum \binom{n}{n_1, \dots, n_k} a_1^{n_1} \dots a_k^{n_k}$ , where  $n_i \geq 0$  and  $\sum n_i = n$ .

$$\binom{n}{n_1, \dots, n_k} = M(n_1, \dots, n_k) = \frac{n!}{n_1! \dots n_k!}$$

$$M(a, \dots, b, c, \dots) = M(a + \dots + b, c, \dots) M(a, \dots, b)$$

#### Catalan numbers.

- $C_n = \frac{1}{n+1} \binom{2n}{n} = \frac{(2n)!}{(n+1)!n!}$  con  $n \geq 0$ ,  $C_0 = 1$  y  $C_{n+1} = \frac{2(2n+1)}{n+2} C_n$   
 $C_n = \sum_{i=0}^{n-1} C_i C_{n-1-i}$
- 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, 208012, 742900, 2674440, 9694845, 35357670
- $C_n$  is the number of: properly nested sequences of  $n$  pairs of parentheses; rooted ordered binary trees with  $n+1$  leaves; triangulations of a convex  $(n+2)$ -gon.

**Derangements.** Number of permutations of  $n = 0, 1, 2, \dots$  elements without fixed points is 1, 0, 1, 2, 9, 44, 265, 1854, 14833, ... Recurrence:  $D_n = (n-1)(D_{n-1} + D_{n-2}) = nD_{n-1} + (-1)^n$ . Corollary: number of permutations with exactly  $k$  fixed points is  $\binom{n}{k} D_{n-k}$ .

**Stirling numbers of 1<sup>st</sup> kind.**  $s_{n,k}$  is  $(-1)^{n-k}$  times the number of permutations of  $n$  elements with exactly  $k$  permutation cycles.  $|s_{n,k}| = |s_{n-1,k-1}| + (n-1)|s_{n-1,k}|$ .  $\sum_{k=0}^n s_{n,k} x^k = x^n$

**Stirling numbers of 2<sup>nd</sup> kind.**  $S_{n,k}$  is the number of ways to partition a set of  $n$  elements into exactly  $k$  non-empty subsets.  $S_{n,k} = S_{n-1,k-1} + kS_{n-1,k}$ .  $S_{n,1} = S_{n,n} = 1$ .  $x^n = \sum_{k=0}^n S_{n,k} x^k$

**Bell numbers.**  $B_n$  is the number of partitions of  $n$  elements.  $B_0, \dots = 1, 1, 2, 5, 15, 52, 203, \dots$   
 $B_{n+1} = \sum_{k=0}^n \binom{n}{k} B_k = \sum_{k=1}^n S_{n,k}$ . Bell triangle:  $B_r = a_{r,1} = a_{r-1,r-1}$ ,  $a_{r,c} = a_{r-1,c-1} + a_{r,c-1}$ .

**Bernoulli numbers.**  $\sum_{k=0}^{m-1} k^n = \frac{1}{n+1} \sum_{k=0}^n \binom{n+1}{k} B_k m^{n+1-k}$ .  
 $\sum_{j=0}^m \binom{m+1}{j} B_j = 0$ .  $B_0 = 1$ ,  $B_1 = -\frac{1}{2}$ .  $B_n = 0$ , for all odd  $n \neq 1$ .

**Eulerian numbers.**  $E(n, k)$  is the number of permutations with exactly  $k$  descents ( $i : \pi_i < \pi_{i+1}$ ) / ascents ( $\pi_i > \pi_{i+1}$ ) / excedances ( $\pi_i > i$ ) /  $k+1$  weak

excedances ( $\pi_i \geq i$ ).

Formula:  $E(n, k) = (k + 1)E(n - 1, k) + (n - k)E(n - 1, k - 1)$ .  $x^n = \sum_{k=0}^{n-1} E(n, k) \binom{x+k}{n}$ .

**Burnside's lemma.** The number of orbits under group  $G$ 's action on set  $X$ :  $|X/G| = \frac{1}{|G|} \sum_{g \in G} |X_g|$ , where  $X_g = \{x \in X : g(x) = x\}$ . ("Average number of fixed points.")

Let  $w(x)$  be weight of  $x$ 's orbit. Sum of all orbits' weights:  $\sum_{o \in X/G} w(o) = \frac{1}{|G|} \sum_{g \in G} \sum_{x \in X_g} w(x)$ .

## Number Theory

**Linear diophantine equation.**  $ax + by = c$ . Let  $d = \gcd(a, b)$ . A solution exists iff  $d|c$ . If  $(x_0, y_0)$  is any solution, then all solutions are given by  $(x, y) = (x_0 + \frac{b}{d}t, y_0 - \frac{a}{d}t)$ ,  $t \in \mathbb{Z}$ . To find some solution  $(x_0, y_0)$ , use extended GCD to solve  $ax_0 + by_0 = d = \gcd(a, b)$ , and multiply its solutions by  $\frac{c}{d}$ .

Linear diophantine equation in  $n$  variables:  $a_1x_1 + \dots + a_nx_n = c$  has solutions iff  $\gcd(a_1, \dots, a_n)|c$ . To find some solution, let  $b = \gcd(a_2, \dots, a_n)$ , solve  $a_1x_1 + by = c$ , and iterate with  $a_2x_2 + \dots = y$ .

### Extended GCD

```
// Finds g = gcd(a,b) and x, y such that ax+by=g.
// Bounds: |x|<=b+1, |y|<=a+1.
void gcdext(int &g, int &x, int &y, int a, int b)
{ if (b == 0) { g = a; x = 1; y = 0; }
  else      { gcdext(g, y, x, b, a % b); y = y - (a / b) * x; } }
```

Multiplicative inverse of  $a$  modulo  $m$ :  $x$  in  $ax + my = 1$ , or  $a^{\phi(m)-1} \pmod{m}$ .

**Chinese Remainder Theorem.** System  $x \equiv a_i \pmod{m_i}$  for  $i = 1, \dots, n$ , with pairwise relatively-prime  $m_i$  has a unique solution modulo  $M = m_1m_2 \dots m_n$ :  $x = a_1b_1\frac{M}{m_1} + \dots + a_nb_n\frac{M}{m_n} \pmod{M}$ , where  $b_i$  is modular inverse of  $\frac{M}{m_i}$  modulo  $m_i$ .

System  $x \equiv a \pmod{m}$ ,  $x \equiv b \pmod{n}$  has solutions iff  $a \equiv b \pmod{g}$ , where  $g = \gcd(m, n)$ . The solution is unique modulo  $L = \frac{mn}{g}$ , and equals:  $x \equiv a + T(b - a)m/g \equiv b + S(a - b)n/g \pmod{L}$ , where  $S$  and  $T$  are integer solutions of  $mT + nS = \gcd(m, n)$ .

**Prime-counting function.**  $\pi(n) = |\{p \leq n : p \text{ is prime}\}|$ .  $n/\ln(n) < \pi(n) < 1.3n/\ln(n)$ .  $\pi(1000) = 168$ ,  $\pi(10^6) = 78498$ ,  $\pi(10^9) = 50\,847\,534$ .  $n$ -th prime  $\approx n \ln n$ .

**Miller-Rabin's primality test.** Given  $n = 2^r s + 1$  with odd  $s$ , and a random integer  $1 < a < n$ .

If  $a^s \equiv 1 \pmod{n}$  or  $a^{2^j s} \equiv -1 \pmod{n}$  for some  $0 \leq j \leq r - 1$ , then  $n$  is a probable prime. With bases 2, 7 and 61, the test identifies all composites below  $2^{32}$ . Probability of failure for a random  $a$  is at most  $1/4$ .

**Pollard- $\rho$ .** Choose random  $x_1$ , and let  $x_{i+1} = x_i^2 - 1 \pmod{n}$ . Test  $\gcd(n, x_{2^k+i} - x_{2^k})$  as possible  $n$ 's factors for  $k = 0, 1, \dots$ . Expected time to find a factor:  $O(\sqrt{m})$ , where  $m$  is smallest prime power in  $n$ 's factorization. That's  $O(n^{1/4})$  if you check  $n = p^k$  as a special case before factorization.

**Fermat primes.** A Fermat prime is a prime of form  $2^{2^n} + 1$ . The only known Fermat primes are 3, 5, 17, 257, 65537. A number of form  $2^n + 1$  is prime only if it is a Fermat prime.

**Fermat's Theorem.** Let  $m$  be a prime and  $x$  and  $m$  coprimes, then:

- $x^{m-1} \equiv 1 \pmod{m}$
- $x^k \pmod{m} = x^{k \pmod{m-1}} \pmod{m}$
- $x^{\phi(m)} \equiv 1 \pmod{m}$

**Perfect numbers.**  $n > 1$  is called perfect if it equals sum of its proper divisors and 1. Even  $n$  is perfect iff  $n = 2^{p-1}(2^p - 1)$  and  $2^p - 1$  is prime (Mersenne's). No odd perfect numbers are yet found.

**Carmichael numbers.** A positive composite  $n$  is a Carmichael number ( $a^{n-1} \equiv 1 \pmod{n}$  for all  $a$ :  $\gcd(a, n) = 1$ ), iff  $n$  is square-free, and for all prime divisors  $p$  of  $n$ ,  $p - 1$  divides  $n - 1$ .

**Number/sum of divisors.**  $\tau(p_1^{a_1} \dots p_k^{a_k}) = \prod_{j=1}^k (a_j + 1)$ .  $\sigma(p_1^{a_1} \dots p_k^{a_k}) = \prod_{j=1}^k \frac{p_j^{a_j+1} - 1}{p_j - 1}$ .

**Product of divisors.**  $\mu(n) = n^{\frac{\tau(n)}{2}}$

• if  $p$  is a prime, then:  $\mu(p^k) = p^{\frac{k(k+1)}{2}}$

• if  $a$  and  $b$  are coprimes, then:  $\mu(ab) = \mu(a)^{\tau(b)} \mu(b)^{\tau(a)}$

**Euler's phi function.**  $\phi(n) = |\{m \in \mathbb{N}, m \leq n, \gcd(m, n) = 1\}|$ .

•  $\phi(mn) = \frac{\phi(m)\phi(n)\gcd(m, n)}{\phi(\gcd(m, n))}$ .

•  $\phi(p) = p - 1$  si  $p$  es primo

•  $\phi(p^a) = p^a(1 - \frac{1}{p}) = p^{a-1}(p - 1)$

•  $\phi(n) = n(1 - \frac{1}{p_1})(1 - \frac{1}{p_2}) \dots (1 - \frac{1}{p_k})$  donde  $p_i$  es primo y divide a  $n$

**Euler's theorem.**  $a^{\phi(n)} \equiv 1 \pmod{n}$ , if  $\gcd(a, n) = 1$ .

**Wilson's theorem.**  $p$  is prime iff  $(p - 1)! \equiv -1 \pmod{p}$ .

**Mobius function.**  $\mu(1) = 1$ .  $\mu(n) = 0$ , if  $n$  is not squarefree.  $\mu(n) = (-1)^s$ , if  $n$  is the product of  $s$  distinct primes. Let  $f, F$  be functions on positive integers. If for all  $n \in \mathbb{N}$ ,  $F(n) = \sum_{d|n} f(d)$ , then  $f(n) = \sum_{d|n} \mu(d)F(\frac{n}{d})$ , and vice versa.  $\phi(n) = \sum_{d|n} \mu(d)\frac{n}{d}$ .  $\sum_{d|n} \mu(d) = 1$ .

If  $f$  is multiplicative, then  $\sum_{d|n} \mu(d)f(d) = \prod_{p|n} (1 - f(p))$ ,  $\sum_{d|n} \mu(d)^2 f(d) =$

$$\prod_{p|n} (1 + f(p)).$$

$$\sum_{d|n} \mu(d) = e(n) = [n == 1].$$

$$S_f(n) = \prod_{p=1} (1 + f(p_i) + f(p_i^2) + \dots + f(p_i^{e_i})), \text{ p - primes}(n).$$

**Legendre symbol.** If  $p$  is an odd prime,  $a \in \mathbb{Z}$ , then  $\left(\frac{a}{p}\right)$  equals 0, if  $p|a$ ; 1 if  $a$  is a quadratic residue modulo  $p$ ; and  $-1$  otherwise. Euler's criterion:  $\left(\frac{a}{p}\right) = a^{\left(\frac{p-1}{2}\right)} \pmod{p}$ .

**Jacobi symbol.** If  $n = p_1^{a_1} \cdots p_k^{a_k}$  is odd, then  $\left(\frac{a}{n}\right) = \prod_{i=1}^k \left(\frac{a}{p_i}\right)^{a_i}$ .

**Primitive roots.** If the order of  $g$  modulo  $m$  ( $\min n > 0: g^n \equiv 1 \pmod{m}$ ) is  $\phi(m)$ , then  $g$  is called a primitive root. If  $Z_m$  has a primitive root, then it has  $\phi(\phi(m))$  distinct primitive roots.  $Z_m$  has a primitive root iff  $m$  is one of 2, 4,  $p^k$ ,  $2p^k$ , where  $p$  is an odd prime. If  $Z_m$  has a primitive root  $g$ , then for all  $a$  coprime to  $m$ , there exists unique integer  $i = \text{ind}_g(a)$  modulo  $\phi(m)$ , such that  $g^i \equiv a \pmod{m}$ .  $\text{ind}_g(a)$  has logarithm-like properties:  $\text{ind}(1) = 0$ ,  $\text{ind}(ab) = \text{ind}(a) + \text{ind}(b)$ .

If  $p$  is prime and  $a$  is not divisible by  $p$ , then congruence  $x^n \equiv a \pmod{p}$  has  $\gcd(n, p-1)$  solutions if  $a^{(p-1)/\gcd(n, p-1)} \equiv 1 \pmod{p}$ , and no solutions otherwise. (Proof sketch: let  $g$  be a primitive root, and  $g^i \equiv a \pmod{p}$ ,  $g^u \equiv x \pmod{p}$ .  $x^n \equiv a \pmod{p}$  iff  $g^{nu} \equiv g^i \pmod{p}$  iff  $nu \equiv i \pmod{p}$ .)

**Discrete logarithm problem.** Find  $x$  from  $a^x \equiv b \pmod{m}$ . Can be solved in  $O(\sqrt{m})$  time and space with a meet-in-the-middle trick. Let  $n = \lceil \sqrt{m} \rceil$ , and  $x = ny - z$ . Equation becomes  $a^{ny} \equiv ba^z \pmod{m}$ . Precompute all values that the RHS can take for  $z = 0, 1, \dots, n-1$ , and brute force  $y$  on the LHS, each time checking whether there's a corresponding value for RHS.

**Pythagorean triples.** Integer solutions of  $x^2 + y^2 = z^2$ . All relatively prime triples are given by:  $x = 2mn$ ,  $y = m^2 - n^2$ ,  $z = m^2 + n^2$  where  $m > n$ ,  $\gcd(m, n) = 1$  and  $m \not\equiv n \pmod{2}$ . All other triples are multiples of these. Equation  $x^2 + y^2 = 2z^2$  is equivalent to  $\left(\frac{x+y}{2}\right)^2 + \left(\frac{x-y}{2}\right)^2 = z^2$ .

- Given an arbitrary pair of integers  $m$  and  $n$  with  $m > n > 0$ :  
 $a = m^2 - n^2$ ,  $b = 2mn$ ,  $c = m^2 + n^2$
- The triple generated by Euclid's formula is primitive if and only if  $m$  and  $n$  are coprime and not both odd.
- To generate all Pythagorean triples uniquely:  
 $a = k(m^2 - n^2)$ ,  $b = k(2mn)$ ,  $c = k(m^2 + n^2)$
- If  $m$  and  $n$  are two odd integer such that  $m > n$ , then:  
 $a = mn$ ,  $b = \frac{m^2 - n^2}{2}$ ,  $c = \frac{m^2 + n^2}{2}$
- If  $n = 1$  or  $2$  there are no solutions. Otherwise  
 $n$  is even:  $\left(\left(\frac{n^2}{4} - 1\right)^2 + n^2 = \left(\frac{n^2}{4} + 1\right)^2\right)$   
 $n$  is odd:  $\left(\left(\frac{n^2 - 1}{2}\right)^2 + n^2 = \left(\frac{n^2 + 1}{2}\right)^2\right)$

**Postage stamps/McNuggets problem.** Let  $a, b$  be relatively-prime integers. There are exactly  $\frac{1}{2}(a-1)(b-1)$  numbers *not* of form  $ax + by$  ( $x, y \geq 0$ ), and the largest is  $(a-1)(b-1) - 1 = ab - a - b$ .

**Fermat's two-squares theorem.** Odd prime  $p$  can be represented as a sum of two squares iff  $p \equiv 1 \pmod{4}$ . A product of two sums of two squares is a sum of two squares. Thus,  $n$  is a sum of two squares iff every prime of form  $p = 4k + 3$  occurs an even number of times in  $n$ 's factorization.

**RSA.** Let  $p$  and  $q$  be random distinct large primes,  $n = pq$ . Choose a small odd integer  $e$ , relatively prime to  $\phi(n) = (p-1)(q-1)$ , and let  $d = e^{-1} \pmod{\phi(n)}$ . Pairs  $(e, n)$  and  $(d, n)$  are the public and secret keys, respectively. Encryption is done by raising a message  $M \in Z_n$  to the power  $e$  or  $d$ , modulo  $n$ .

## String Algorithms

**Burrows-Wheeler inverse transform.** Let  $B[1..n]$  be the input (last column of sorted matrix of string's rotations.) Get the first column,  $A[1..n]$ , by sorting  $B$ . For each  $k$ -th occurrence of a character  $c$  at index  $i$  in  $A$ , let  $\text{next}[i]$  be the index of corresponding  $k$ -th occurrence of  $c$  in  $B$ . The  $r$ -th row of the matrix is  $A[r]$ ,  $A[\text{next}[r]]$ ,  $A[\text{next}[\text{next}[r]]]$ , ...

**Huffman's algorithm.** Start with a forest, consisting of isolated vertices. Repeatedly merge two trees with the lowest weights.

## Graph Theory

**Euler's theorem.** For any planar graph,  $V - E + F = 1 + C$ , where  $V$  is the number of graph's vertices,  $E$  is the number of edges,  $F$  is the number of faces in graph's planar drawing, and  $C$  is the number of connected components. Corollary:  $V - E + F = 2$  for a 3D polyhedron.

**Vertex covers and independent sets.** Let  $M, C, I$  be a max matching, a min vertex cover, and a max independent set. Then  $|M| \leq |C| = N - |I|$ , with equality for bipartite graphs. Complement of an MVC is always a MIS, and vice versa. Given a bipartite graph with partitions  $(A, B)$ , build a network: connect source to  $A$ , and  $B$  to sink with edges of capacities, equal to the corresponding nodes' weights, or 1 in the unweighted case. Set capacities of the original graph's edges to the infinity. Let  $(S, T)$  be a minimum  $s$ - $t$  cut. Then a maximum(-weighted) independent set is  $I = (A \cap S) \cup (B \cap T)$ , and a minimum(-weighted) vertex cover is  $C = (A \cap T) \cup (B \cap S)$ .

**Matrix-tree theorem.** Let matrix  $T = [t_{ij}]$ , where  $t_{ij}$  is the number of multiedges between  $i$  and  $j$ , for  $i \neq j$ , and  $t_{ii} = -\deg_i$ . Number of spanning trees of a graph is equal to the determinant of a matrix obtained by deleting any  $k$ -th row and  $k$ -th column from  $T$ .

**Euler tours.** Euler tour in an undirected graph exists iff the graph is connected and each vertex has an even degree. Euler tour in a directed graph exists

iff in-degree of each vertex equals its out-degree, and underlying undirected graph is connected. Construction:

```
doit(u):
    for each edge e = (u, v) in E, do: erase e, doit(v)
    prepend u to the list of vertices in the tour
```

**Stable marriages problem.** While there is a free man  $m$ : let  $w$  be the most-preferred woman to whom he has not yet proposed, and propose  $m$  to  $w$ . If  $w$  is free, or is engaged to someone whom she prefers less than  $m$ , match  $m$  with  $w$ , else deny proposal.

**Stoer-Wagner's min-cut algorithm.** Start from a set  $A$  containing an arbitrary vertex. While  $A \neq V$ , add to  $A$  the most tightly connected vertex ( $z \notin A$  such that  $\sum_{x \in A} w(x, z)$  is maximized.) Store cut-of-the-phase (the cut between the last added vertex and rest of the graph), and merge the two vertices added last. Repeat until the graph is contracted to a single vertex. Minimum cut is one of the cuts-of-the-phase.

**Tarjan's offline LCA algorithm.** (Based on DFS and union-find structure.)

```
DFS(x):
    ancestor[Find(x)] = x
    for all children y of x:
        DFS(y); Union(x, y); ancestor[Find(x)] = x
    seen[x] = true
    for all queries {x, y}:
        if seen[y] then output "LCA(x, y) is ancestor[Find(y)]"
```

**Strongly-connected components.** Kosaraju's algorithm.

1. Let  $G^T$  be a transpose  $G$  (graph with reversed edges.)
1. Call  $\text{DFS}(G^T)$  to compute finishing times  $f[u]$  for each vertex  $u$ .
3. For each vertex  $u$ , in the order of decreasing  $f[u]$ , perform  $\text{DFS}(G, u)$ .
4. Each tree in the 3rd step's DFS forest is a separate SCC.

**2-SAT.** Build an implication graph with 2 vertices for each variable – for the variable and its inverse; for each clause  $x \vee y$  add edges  $(\bar{x}, y)$  and  $(\bar{y}, x)$ . The formula is satisfiable iff  $x$  and  $\bar{x}$  are in distinct SCCs, for all  $x$ . To find a satisfiable assignment, consider the graph's SCCs in topological order from sinks to sources (i.e. Kosaraju's last step), assigning 'true' to all variables of the current SCC (if it hasn't been previously assigned 'false'), and 'false' to all inverses.

**Randomized algorithm for non-bipartite matching.** Let  $G$  be a simple undirected graph with even  $|V(G)|$ . Build a matrix  $A$ , which for each edge  $(u, v) \in E(G)$  has  $A_{i,j} = x_{i,j}$ ,  $A_{j,i} = -x_{i,j}$ , and is zero elsewhere. Tutte's theorem:  $G$  has a perfect matching iff  $\det G$  (a multivariate polynomial) is identically zero. Testing the latter can be done by computing the determinant for a few random values of  $x_{i,j}$ 's over some field. (e.g.  $Z_p$  for a sufficiently large prime  $p$ )

**Prufer code of a tree.** Label vertices with integers 1 to  $n$ . Repeatedly remove the leaf with the smallest label, and output its only neighbor's label, until

only one edge remains. The sequence has length  $n - 2$ . Two isomorphic trees have the same sequence, and every sequence of integers from 1 and  $n$  corresponds to a tree. Corollary: the number of labelled trees with  $n$  vertices is  $n^{n-2}$ .

**Erdos-Gallai theorem.** A sequence of integers  $\{d_1, d_2, \dots, d_n\}$ , with  $n - 1 \geq d_1 \geq d_2 \geq \dots \geq d_n \geq 0$  is a degree sequence of some undirected simple graph iff  $\sum d_i$  is even and  $d_1 + \dots + d_k \leq k(k-1) + \sum_{i=k+1}^n \min(k, d_i)$  for all  $k = 1, 2, \dots, n-1$ .

## Games

**Grundy numbers.** For a two-player, normal-play (last to move wins) game on a graph  $(V, E)$ :  $G(x) = \text{mex}(\{G(y) : (x, y) \in E\})$ , where  $\text{mex}(S) = \min\{n \geq 0 : n \notin S\}$ .  $x$  is losing iff  $G(x) = 0$ .

**Sums of games.**

- *Player chooses a game and makes a move in it.* Grundy number of a position is xor of Grundy numbers of positions in summed games.
- *Player chooses a non-empty subset of games (possibly, all) and makes moves in all of them.* A position is losing iff each game is in a losing position.
- *Player chooses a proper subset of games (not empty and not all), and makes moves in all chosen ones.* A position is losing iff Grundy numbers of all games are equal.
- *Player must move in all games, and loses if can't move in some game.* A position is losing if any of the games is in a losing position.

**Misère Nim.** A position with pile sizes  $a_1, a_2, \dots, a_n \geq 1$ , not all equal to 1, is losing iff  $a_1 \oplus a_2 \oplus \dots \oplus a_n = 0$  (like in normal nim.) A position with  $n$  piles of size 1 is losing iff  $n$  is odd.

## Bit tricks

Clearing the lowest 1 bit:  $x \& (x - 1)$ , all trailing 1's:  $x \& (x + 1)$

Setting the lowest 0 bit:  $x | (x + 1)$

Enumerating subsets of a bitmask  $m$ :

```
x=0; do { ...; x=(x+1)&m; } while (x!=0);
```

`__builtin_ctz`/`__builtin_clz` returns the number of trailing/leading zero bits.

`__builtin_popcount`(unsigned  $x$ ) counts 1-bits (slower than table lookups).

For 64-bit unsigned integer type, use the suffix 'll', i.e. `__builtin_popcountll`.

**XOR** Let's say  $F(L, R)$  is XOR of subarray from  $L$  to  $R$ .

Here we use the property that  $F(L, R) = F(1, R) \text{ XOR } F(1, L-1)$

## Math

**Stirling's approximation**  $z! = \Gamma(z+1) = \sqrt{2\pi} z^{z+1/2} e^{-z} (1 + \frac{1}{12z} + \frac{1}{288z^2} - \frac{139}{51840z^3} + \dots)$

**Taylor series.**  $f(x) = f(a) + \frac{x-a}{1!} f'(a) + \frac{(x-a)^2}{2!} f^{(2)}(a) + \dots + \frac{(x-a)^n}{n!} f^{(n)}(a) + \dots$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$$

$$\ln x = 2(a + \frac{a^3}{3} + \frac{a^5}{5} + \dots), \text{ where } a = \frac{x-1}{x+1}. \ln x^2 = 2 \ln x.$$

$$\arctan x = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots, \arctan x = \arctan c + \arctan \frac{x-c}{1+xc} \text{ (e.g } c=.2)$$

$$\pi = 4 \arctan 1, \pi = 6 \arcsin \frac{1}{2}$$

**Fibonacci Period** Si p es primo,  $\pi(p^k) = p^{k-1} \pi(p)$

$$\pi(2) = 3 \quad \pi(5) = 20$$

Si n y m son coprimos  $\pi(n * m) = lcm(\pi(n), \pi(m))$

### List of Primes

1e5	3	19	43	49	57	69	103	109	129	151	153
1e6	33	37	39	81	99	117	121	133	171	183	
1e7	19	79	103	121	139	141	169	189	223	229	
1e8	7	39	49	73	81	123	127	183	213		

### 2-SAT Rules

$$p \rightarrow q \equiv \neg p \vee q$$

$$p \rightarrow q \equiv \neg q \rightarrow \neg p$$

$$p \vee q \equiv \neg p \rightarrow q$$

$$p \wedge q \equiv \neg(p \rightarrow \neg q)$$

$$\neg(p \rightarrow q) \equiv p \wedge \neg q$$

$$(p \rightarrow q) \wedge (p \rightarrow r) \equiv p \rightarrow (q \wedge r)$$

$$(p \rightarrow q) \vee (p \rightarrow r) \equiv p \rightarrow (q \vee r)$$

$$(p \rightarrow r) \wedge (q \rightarrow r) \equiv (p \wedge q) \rightarrow r$$

$$(p \rightarrow r) \vee (q \rightarrow r) \equiv (p \vee q) \rightarrow r$$

$$(p \wedge q) \vee (r \wedge s) \equiv (p \vee r) \wedge (p \vee s) \wedge (q \vee r) \wedge (q \vee s)$$

### Summations

$$\bullet \sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6}$$

$$\bullet \sum_{i=1}^n i^3 = \left(\frac{n(n+1)}{2}\right)^2$$

$$\bullet \sum_{i=1}^n i^4 = \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}$$

$$\bullet \sum_{i=1}^n i^5 = \frac{(n(n+1))^2(2n^2+2n-1)}{12}$$

$$\bullet \sum_{i=0}^n x^i = \frac{x^{n+1}-1}{x-1} \text{ para } x \neq 1$$

### Compound Interest

- $N$  is the initial population, it grows at a rate of  $R$ . So, after  $X$  years the population will be  $N \times (1+R)^X$

### Great circle distance or geographical distance

- $d$  = great distance,  $\phi$  = latitude,  $\lambda$  = longitude,  $\Delta$  = difference (all the values in radians)

- $\sigma$  = central angle, angle form for the two vector

$$\bullet d = r * \sigma, \sigma = 2 * \arcsin(\sqrt{\sin^2(\frac{\Delta\phi}{2}) + \cos(\phi_1) \cos(\phi_2) \sin^2(\frac{\Delta\lambda}{2})})$$

### Theorems

- There is always a prime between numbers  $n^2$  and  $(n+1)^2$ , where  $n$  is any positive integer

- There is an infinite number of pairs of the form  $\{p, p+2\}$  where both  $p$  and  $p+2$  are primes.

- Every even integer greater than 2 can be expressed as the sum of two primes.

- Every integer greater than 2 can be written as the sum of three primes.

- $a^d \equiv a^{d \bmod \phi(n)} \bmod n$   
if  $a \in \mathbb{Z}^{n*}$  or  $a \notin \mathbb{Z}^{n*}$  and  $d \bmod \phi(n) \neq 0$

- $a^d \equiv a^{\phi(n)} \bmod n$   
if  $a \notin \mathbb{Z}^{n*}$  and  $d \bmod \phi(n) = 0$

- thus, for all  $a, n$  and  $d$  (with  $d \geq \log_2(n)$ )  
 $a^d \equiv a^{\phi(n)+d \bmod \phi(n)} \bmod n$

### Law of sines and cosines

- $a, b, c$ : lengths,  $A, B, C$ : opposite angles,  $d$ : circumcircle

$$\bullet \frac{a}{\sin(A)} = \frac{b}{\sin(B)} = \frac{c}{\sin(C)} = d$$

$$\bullet c^2 = a^2 + b^2 - 2ab \cos(C)$$

### Heron's Formula

$$\bullet s = \frac{a+b+c}{2}$$

$$\bullet Area = \sqrt{s(s-a)(s-b)(s-c)}$$

- $a, b, c$  there are the lengths of the sides

**Legendre's Formula** Largest power of  $k$ ,  $x$ , such that  $n!$  is divisible by  $k^x$

- If  $k$  is prime,  $x = \frac{n}{k} + \frac{n}{k^2} + \frac{n}{k^3} + \dots$

- If  $k$  is composite  $k = k_1^{p_1} * k_2^{p_2} \dots k_m^{p_m}$   
 $x = \min_{1 \leq j \leq m} \left\{ \frac{a_j}{p_j} \right\}$  where  $a_j$  is Legendre's formula for  $k_j$
- Divisor Formulas of  $n!$  Find all prime numbers  $\leq n$   $\{p_1, \dots, p_m\}$  Let's define  $e_j$  as Legendre's formula for  $p_j$
- Number of divisors of  $n!$  The answer is  $\prod_{j=1}^m (e_j + 1)$
- Sum of divisors of  $n!$  The answer is  $\prod_{j=1}^m \frac{p_j^{e_j+1} - 1}{p_j - 1}$

**Max Flow with Demands** Max Flow with Lower bounds of flow for each edge

- feasible flow in a network with both upper and lower capacity constraints, no source or sink: capacities are changed to upper bound — lower bound. Add a new source and a sink. let  $M[v] = (\text{sum of lower bounds of ingoing edges$

to  $v$ ) — (sum of lower bounds of outgoing edges from  $v$ ). For all  $v$ , if  $M[v] < 0$  then add edge  $(S, v)$  with capacity  $M$ , otherwise add  $(v, T)$  with capacity  $-M$ . If all outgoing edges from  $S$  are full, then a feasible flow exists, it is the flow plus the original lower bounds. maximum flow in a network with both upper and lower capacity constraints, with source  $s$  and sink  $t$ : add edge  $(t, s)$  with capacity infinity. Binary search for the lower bound, check whether a feasible exists for a network WITHOUT source or sink (B).

### Pick's Theorem

- $A = i + \frac{b}{2} - 1$
- $A$  : area of the polygon.
- $i$  : number of interior integer points.
- $b$  : number of integer points on the boundary.