Recorded at time: 136.416 world Broadcaster: /robot2/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (136.416 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot2/robot_state_publisher Broadcaster: /robot1/robot_state_publisher Average rate: 10000.000 Hz Average rate: 100.506 Hz Most recent transform: 136.410 (0.006 sec old) Most recent transform: 0.000 (136.416 sec old) Buffer length: 0.000 sec Buffer length: 1.582 sec shoulder_link base Broadcaster: /robot1/robot_state_publisher Average rate: 100.506 Hz Most recent transform: 136.410 (0.006 sec old) Buffer length: 1.582 sec upper_arm_link Broadcaster: /robot1/robot_state_publisher Average rate: 100.506 Hz Most recent transform: 136.410 (0.006 sec old) Buffer length: 1.582 sec forearm_link Broadcaster: /robot1/robot_state_publisher Average rate: 100.506 Hz Most recent transform: 136.410 (0.006 sec old) Buffer length: 1.582 sec wrist_1_link Broadcaster: /robot1/robot_state_publisher Average rate: 100.506 Hz Most recent transform: 136.410 (0.006 sec old) Buffer length: 1.582 sec wrist_2_link Broadcaster: /robot1/robot_state_publisher Average rate: 100.506 Hz Most recent transform: 136.410 (0.006 sec old) Buffer length: 1.582 sec wrist_3_link Broadcaster: /robot2/robot_state_publisher Broadcaster: /robot2/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (136.416 sec old) Most recent transform: 0.000 (136.416 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec tool0 ee_link Broadcaster: /robot2/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (136.416 sec old) Buffer length: 0.000 sec camera_link Broadcaster: /robot2/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (136.416 sec old) Buffer length: 0.000 sec camera_link_optical

view_frames Result