

Practical Parallel Computing (実践的並列コンピューティング)

Part2: GPU (2)
May 9, 2022

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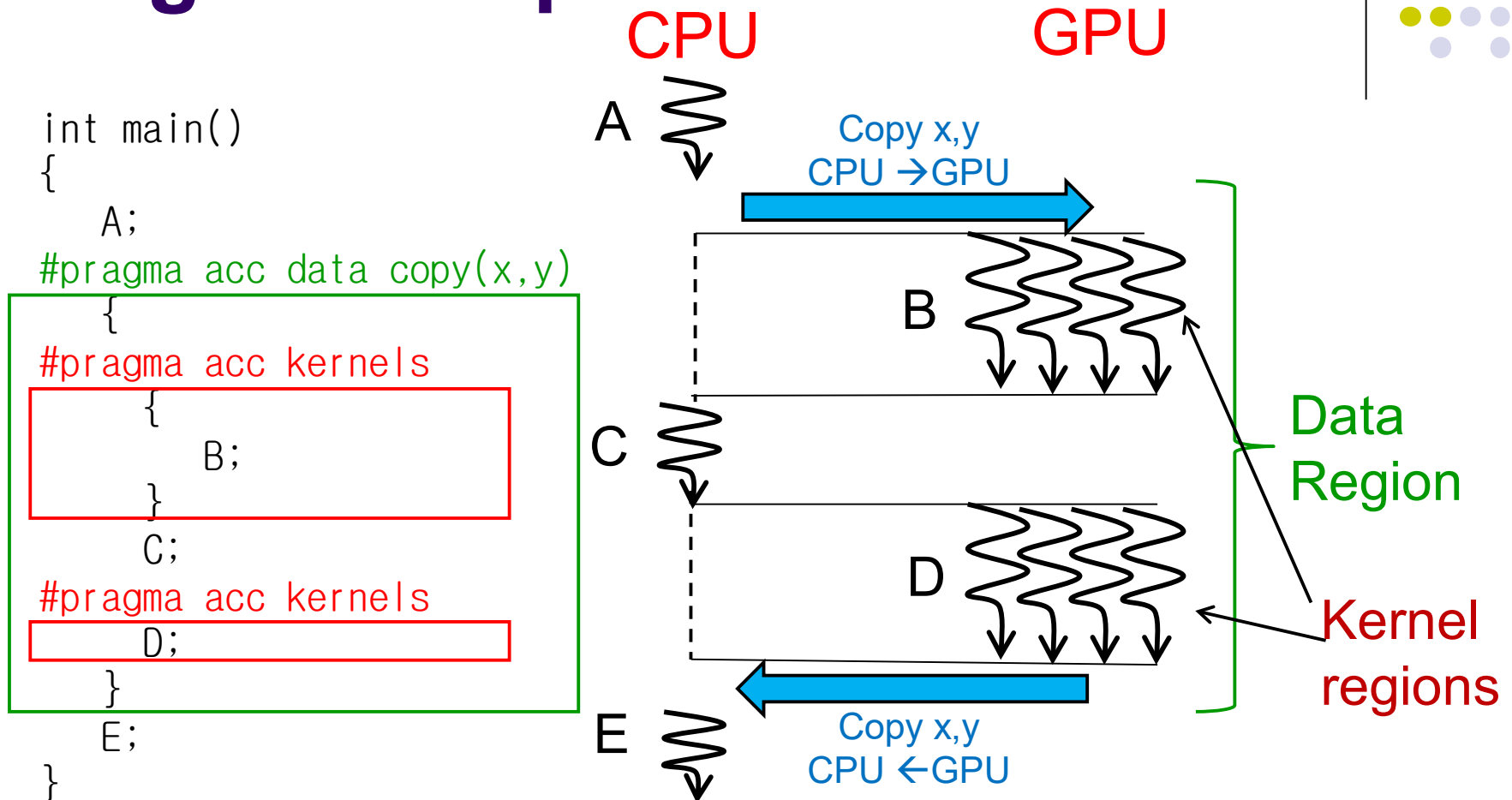
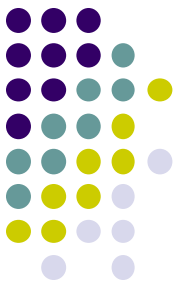




Overview of This Course

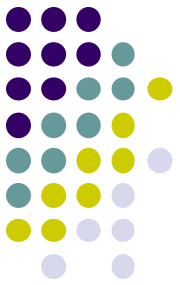
- Part 0: Introduction
 - 2 classes
- Part 1: OpenMP for shared memory programming
 - 4 classes
- Part 2: **GPU** programming
 - 4 classes **← We are here (2/4)**
 - OpenACC (1.5 classes) and CUDA (2.5 classes)
- Part 3: **MPI** for distributed memory programming
 - 3 classes

Data Region and Kernel Region in OpenACC

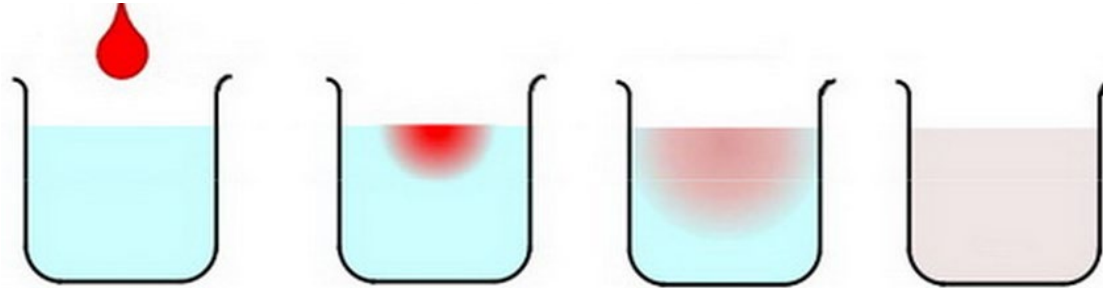


- Data movement occurs at beginning and end of data region
- Data region may contain 1 or more kernel regions

“diffusion” Sample Program related to [G1]



An example of diffusion phenomena:

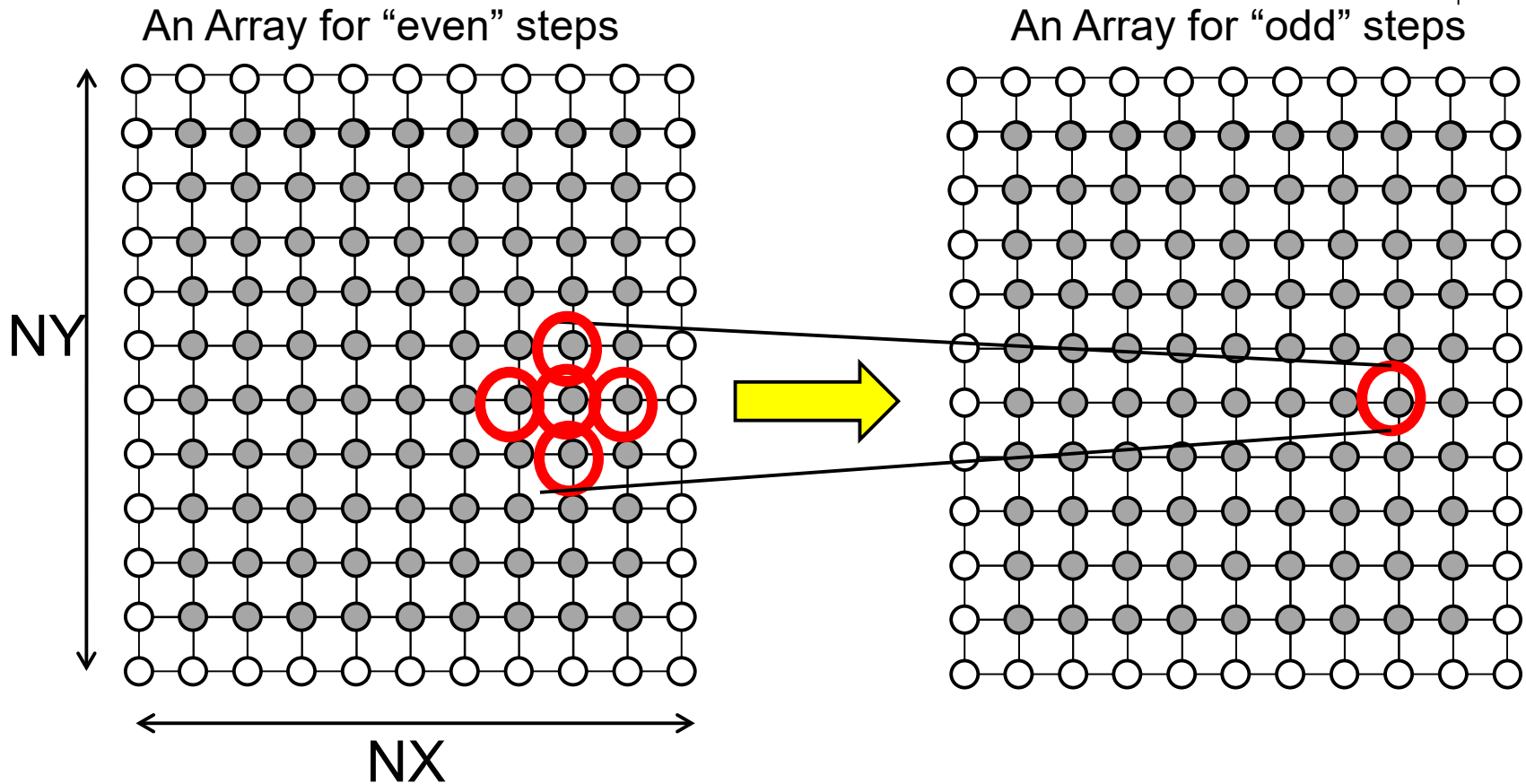
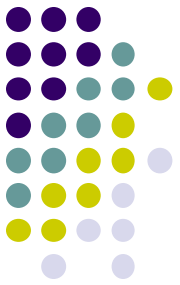


The ink spreads gradually, and finally the density becomes uniform (Figure by Prof. T. Aoki)

Available at </gs/hs1/tga-ppcomp/22/diffusion/>
You can use </gs/hs1/tga-ppcomp/22/diffusion-acc/>

- Execution : `./diffusion [nt]`
 - nt: Number of time steps

Data Structure in “diffusion”



Consideration of Parallelizing Diffusion with OpenACC related to [G1]



- x, y loops can be parallelized
 - We can use “#pragma acc loop” twice
- t loop cannot be parallelized

[Data transfer from CPU to GPU]

```
for (t = 0; t < nt; t++) {  
    for (y = 1; y < NY-1; y++) {  
        for (x = 1; x < NX-1; x++) {  
            :  
        }  
    }  
}
```

Kernel region on GPU
Parallel x, y loops

It's better to transfer data *out of* t-loop

[Data transfer from GPU to CPU]

data Clause for Multi-Dimensional arrays



`float A[2000][1000];` → an example of a 2-dimension array

.... `data copy(A)`

→ **OK**, all elements of A are copied

.... `data copy(A[0:2000][0:1000])`

→ **OK**, all elements of A are copied

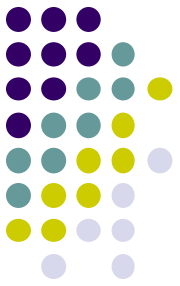
.... `data copy(A[500:600][0:1000])`

→ **OK**, rows[500,1100) are copied

.... `data copy(A[0:2000][300:400])`

→ **NG** in current OpenACC

✘ Currently, OpenACC does not support non-consecutive transfer



Notes on Assignment [G1]

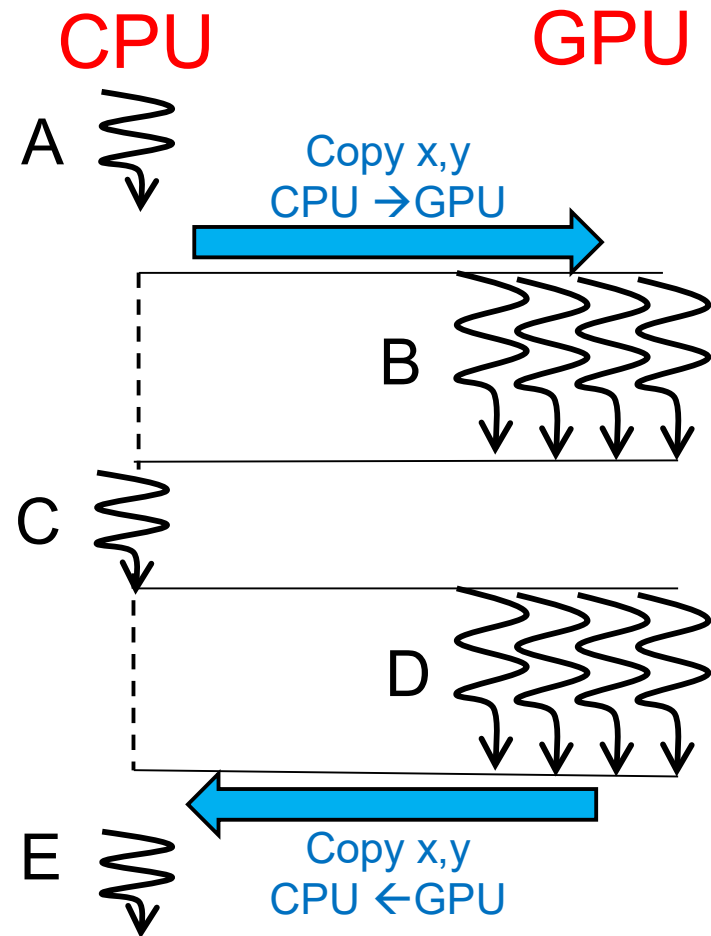
- You will need compiler options different from the [diffusion](#) directory for OpenACC
- You can use files in [diffusion-acc](#) directory as basis
 - [/gs/hs1/tga-ppcomp/22/diffusion-acc/](#)
 - “Makefile” in this directory supports compiler options for OpenACC
 - Don’t forget “[module load nvhpc](#)” before “make”

Data Transfer Costs in GPU Programming

Related to [G2]



- In GPU programming, **data transfer costs between CPU and GPU** have impacts on speed
 - Program speed may be slower than expected ☹️



Speed of GPU Programs: case of mm-acc



In mm-acc, speed in Gflops is computed by

$$S = 2mnk / T_{\text{total}}$$

T_{total} includes both computation time and transfer

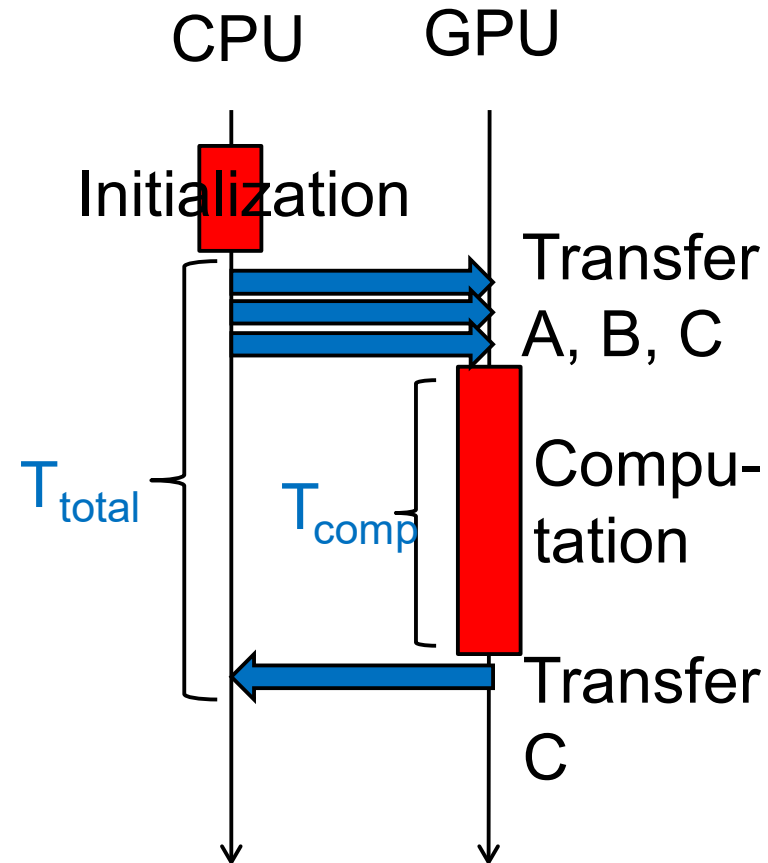
→ S counts slow-down by transfer

To see the effects, let's try another sample

[/gs/hs1/tga-ppcomp/22/mm-meas-acc](https://gs/hs1/tga-ppcomp/22/mm-meas-acc)

which outputs time for

- copyin (transfer A, B, C)
- computation
- copyout (transfer C)



In [G2], please evaluate effects of transfer costs



To Measure Transfer Time

- Data transfer occurs at the beginning and the end of “data region”

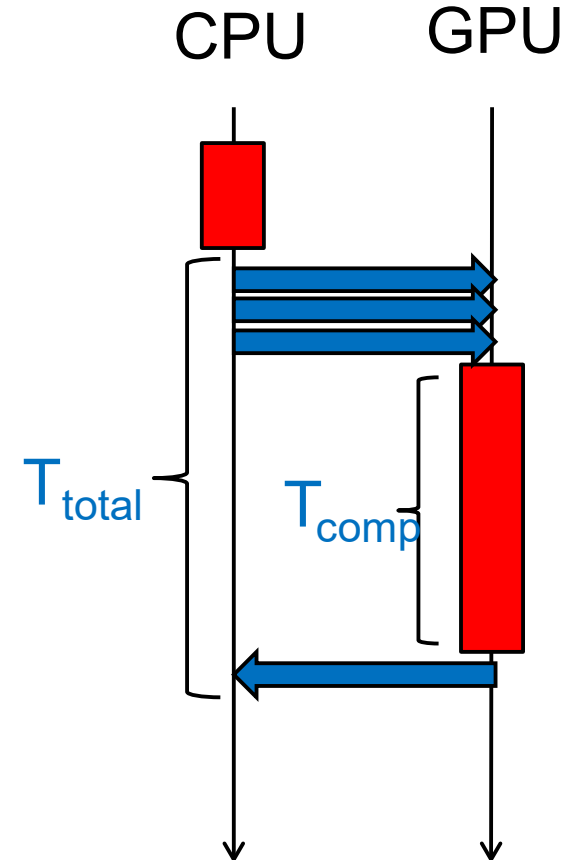
```
// A,B,C are on CPU
```

```
#pragma acc data copyin(A,B) copy(C)  
{ // copyin (CPU->GPU) here
```

```
#pragma acc kernels
```

```
{  
:  
}
```

```
} //copyout (GPU->CPU) here
```



See [mm-meas-acc/mm.c](#)

Also note that `gettimeofday()` must be called on CPU

Discussion on Data Transfer Costs



- Time for data transfer $T_{\text{trans}} \doteq M / B + L$
 - M : Data size in bytes
 - B : “Bandwidth” (speed)
 - L : “Latency” (if M is sufficiently large, we can ignore it)
 - In a P100 GPU,
 - Theoretical computation speed is 5.3TFlops
 - Theoretical bandwidth B is 16GB/s (2G double values per second)
- Transfer of values is much slower than computation ☹️

Discussion on Computation and Transfer Costs

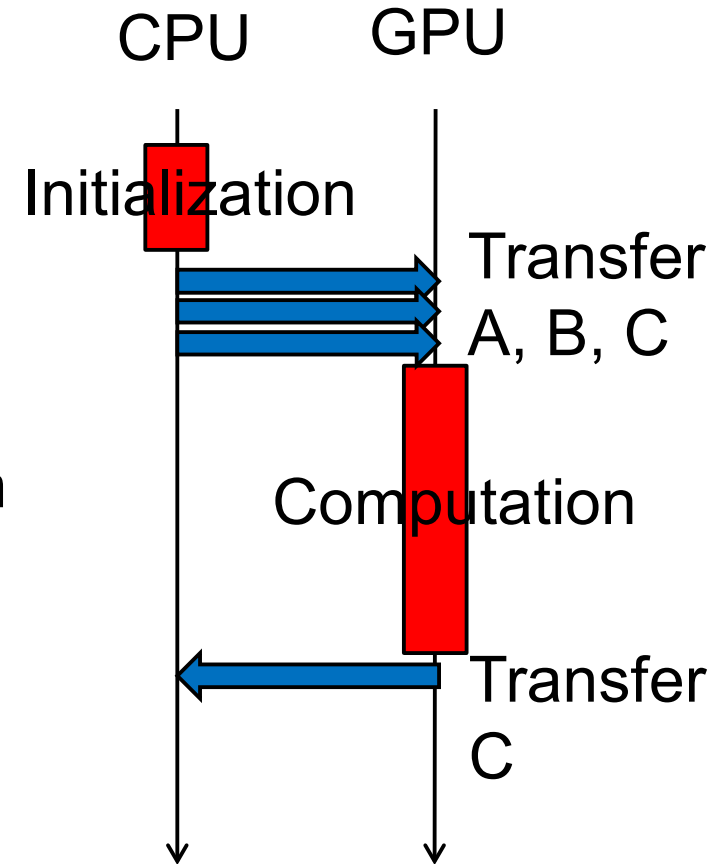


In mm-acc,

- Computation amount: $O(mnk)$
- Data transfer amount:
 - A, B, C: CPU \rightarrow GPU: $O(mk+kn+mn)$
 - C: GPU \rightarrow CPU: $O(mn)$

Transfer costs are relatively smaller with larger m , n , k

In diffusion-acc [G1], how can we reduce transfer costs?





Function Calls from GPU

- Calling functions in kernel region is ok, but we need to be careful
 - “**acc routine**” directive is required by compiler to generate GPU code

```
int main()
{
    #pragma acc kernels
    {
        ... func(A[i]) ...
    }
}

#pragma acc routine
int func(int arg)
{
    :
    :
    return ...;
}
```



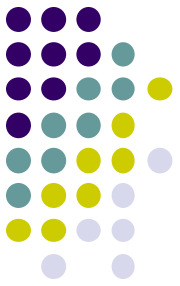
How about Library Functions?

Inside kernel regions (`#pragma acc kernel`),

- Available library functions is very limited 😞
- We cannot use `strlen()`, `memcpy()`, `fopen()`, `fflush()`... 😞
- We cannot use `gettimeofday()` 😞
- Exceptionally, some mathematical functions are ok 😊
 - `fabs`, `sqrt`, `fmax`...
 - `#include <math.h>` is needed
- Recently, `printf()` in kernel regions is ok! 😊



Now explanation of OpenACC is finished; we will go to CUDA



OpenACC and CUDA for GPUs

- **OpenACC**

- C/Fortran + directives (`#pragma acc ...`), Easier programming
 - NVIDIA HPC SDK compiler works
 - `module load nvhpc`
 - `pgcc -acc ... XXX.c`
 - Basically for data parallel programs with for-loops
- Only for limited types of algorithms ☹️

- **CUDA**

- Most popular and suitable for higher performance
- Use “nvcc” command for compile
 - `module load cuda`
 - `nvcc ... XXX.cu`

Programming is harder, but more general



An OpenACC Program Look Like

```
int A[100], B[100];  
int i;  
#pragma acc data copy(A,B)  
#pragma acc kernels  
#pragma acc loop independent
```

```
    for (i = 0; i < 100; i++) {  
        A[i] += B[i];  
    }
```

Executed on GPU
in parallel

```
// After kernel region finishes,  
CPU can access to A[i],B[i]
```



A CUDA Program Look Like

Sample:

</gs/hs1/tga-ppcomp/22/add-cuda/>

```
int A[100], B[100];
int *DA, *DB;
int i;
cudaMalloc(&DA, sizeof(int)*100);
cudaMalloc(&DB, sizeof(int)*100);
cudaMemcpy(DA,A,sizeof(int)*100,
           cudaMemcpyHostToDevice);
cudaMemcpy(DB,B,sizeof(int)*100,
           cudaMemcpyHostToDevice);
```

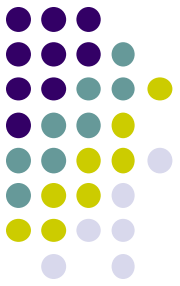
```
add<<<20, 5>>>(DA, DB);
```

```
cudaMemcpy(A,DA,sizeof(int)*100,
           cudaMemcpyDeviceToHost);
```

```
__global__ void add
(int *DA, int *DB)
{
    int i = blockIdx.x*blockDim.x
          + threadIdx.x;
    DA[i] += DB[i];
}
```

Executed on GPU
(called a *kernel function*)

We have to separate code regions executed on CPU and GPU



Using add-cuda Sample

```
[make sure that you are at a interactive node (r7i7nX) ]  
module purge    [If you have loaded nvhpc, delete it]  
module load cuda    [Do once after login]  
cd ~/t3workspace    [Example in web-only route]  
cp -r /gs/hs1/tga-ppcomp/22/add-cuda .  
cd add-cuda  
make  
[An executable file “add” is created]  
./add
```

- ※ [\[Standard route\]](#) A log-in node does not have a GPU
→ You can compile the sample there, but the program does not work!

Preparing Data on Device Memory

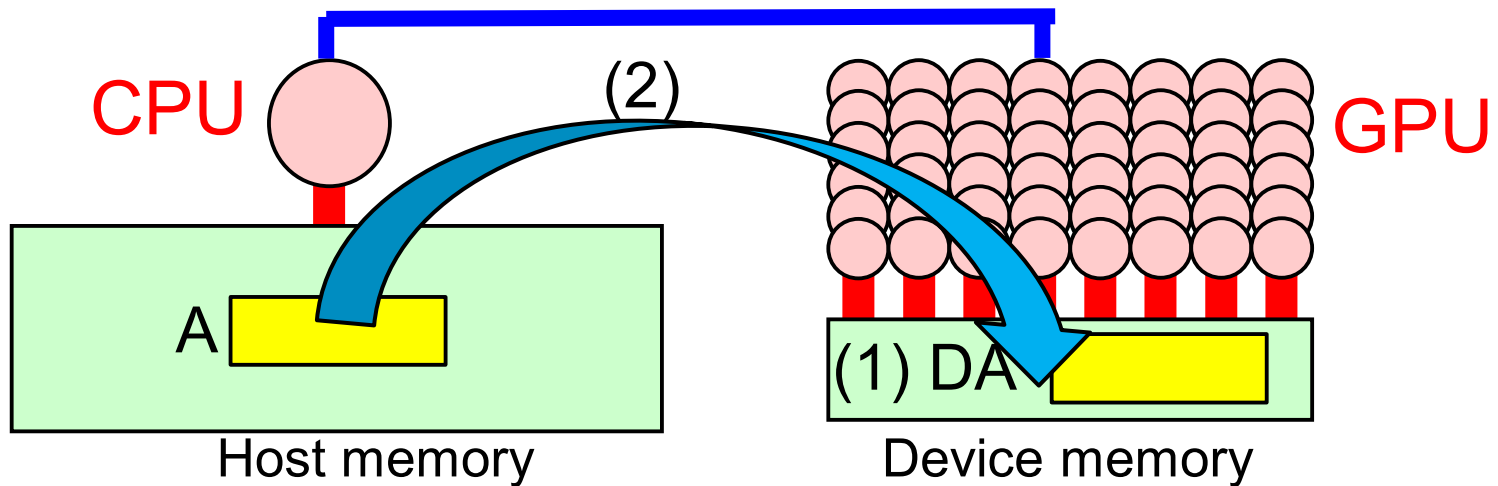


(1) Allocate a region on device memory

cf) `cudaMalloc((void**)&DA, size);`

(2) Copy data from host to device

cf) `cudaMemcpy(DA, A, size, cudaMemcpyDefault);`



Note: `cudaMalloc` and `cudaMemcpy` must be called on CPU, NOT on GPU

Comparing OpenACC and CUDA



OpenACC

Both allocation and copy are done by **acc data copyin**

One variable name A may represent both

- A on host memory
- A on device memory

```
int A[100]; ← on CPU
#pragma acc data copy(A)
#pragma acc kernels
```

```
{
  ... A[i] ...
}
```

← on GPU

CUDA

cudaMalloc and **cudaMemcpy** are separated

Programmer have to prepare two pointers, such as A and DA

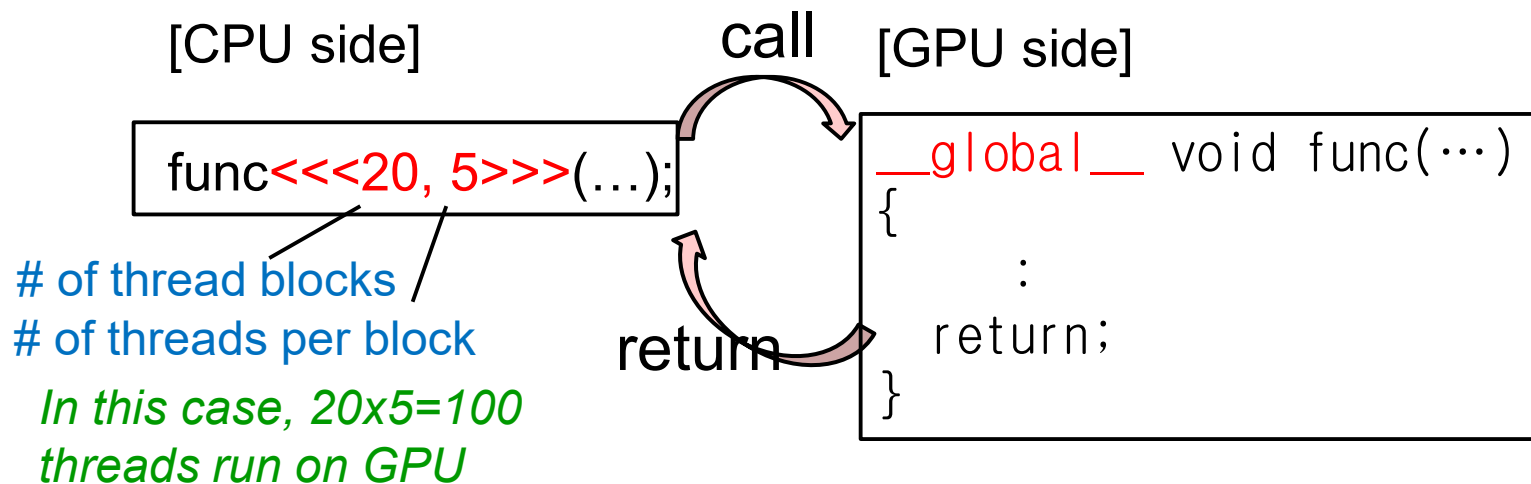
```
int A[100];
int *DA;
cudaMalloc(&DA, ...);
cudaMemcpy(DA, A, ..., ...);
// Here CPU cannot access DA[i]

func<<<..., ...>>>(DA, ...);
```

Calling A GPU Kernel Function from CPU



- A region executed by GPU must be a distinct function
 - called a GPU kernel function

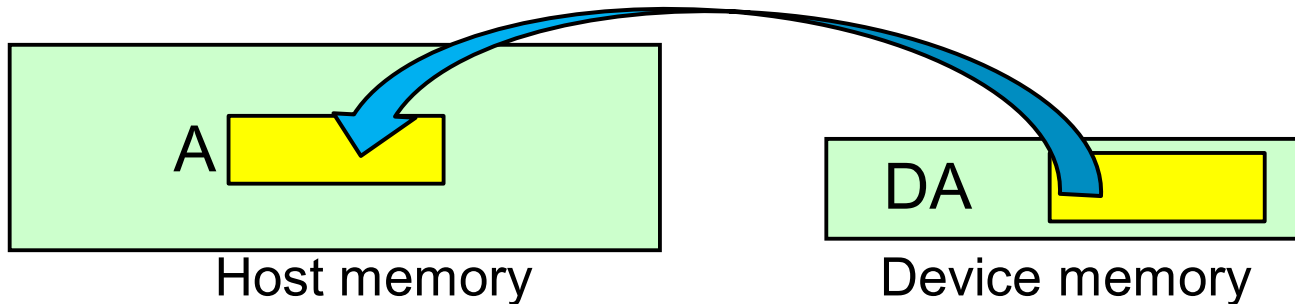


A GPU kernel function (called from CPU)

- needs **__global__** keyword
- can take parameters
- can **NOT** return value; return type must be void



Copying Back Data from GPU

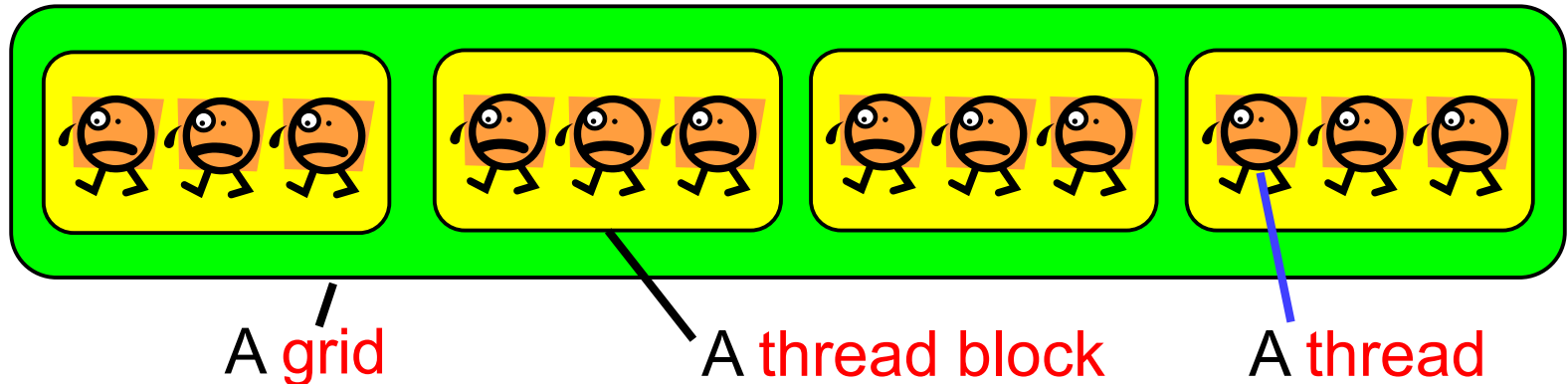


- Copy data using `cudaMemcpy`
 - cf) `cudaMemcpy(A, DA, size, cudaMemcpyDefault);`
 - 4th argument is one of
 - `cudaMemcpyHostToDevice`, `cudaMemcpyDeviceToHost`
 - `cudaMemcpyDeviceToDevice`, `cudaMemcpyHostToHost`
 - `cudaMemcpyDefault` ← Detect memory type automatically 😊
- When a memory area is unnecessary, free it
 - cf) `cudaFree(DA);`

Threads in CUDA



When calling a GPU kernel function, specify 2 numbers (at least) for number of threads



cf) func <<< 4, 3 >>> (); → 12 threads

Number of thread blocks
= gridDim

Number of threads per block
= blockDim

The reason is related to GPU hardware
Thread block \Leftrightarrow SMX, Thread \Leftrightarrow CUDA core

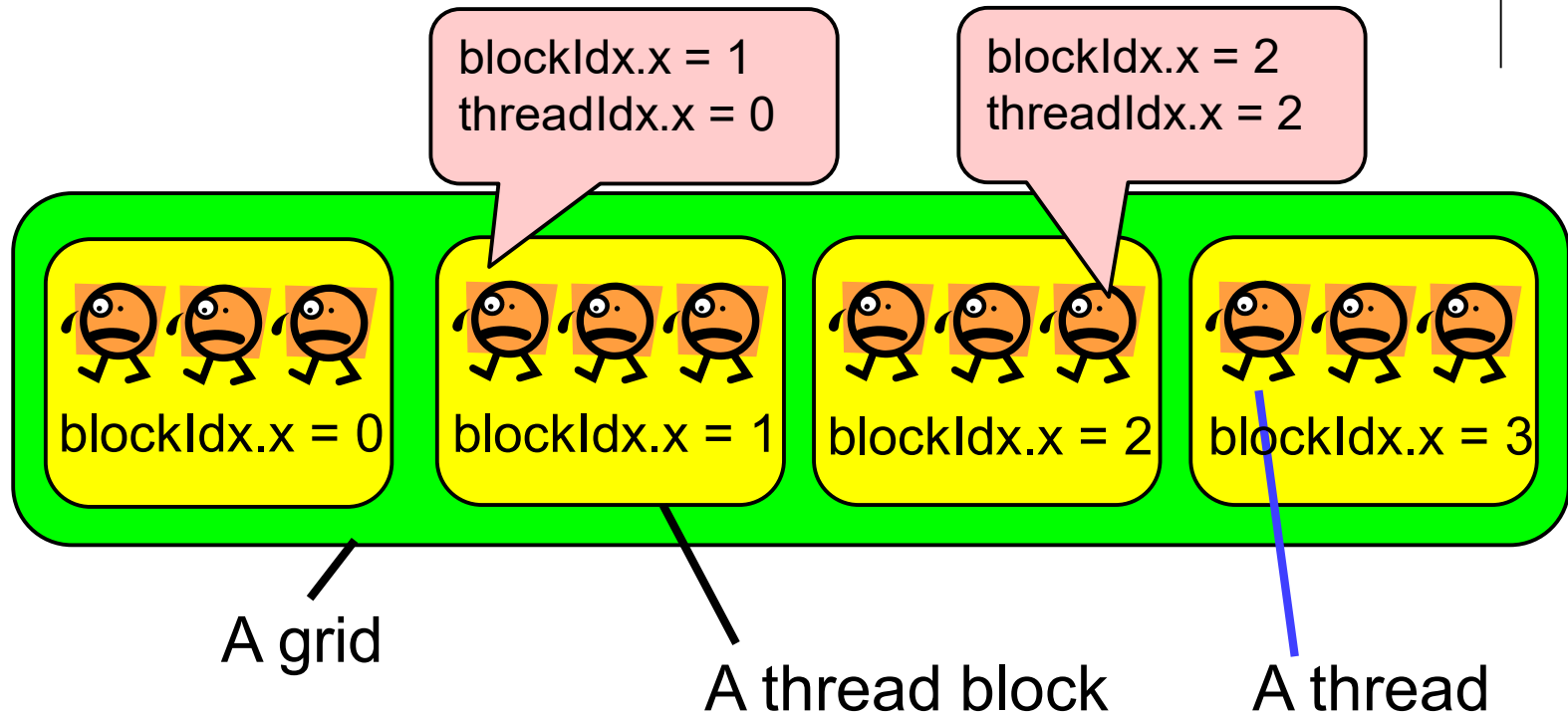


To See Who am I

- By reading the following special variables, each thread can see its thread ID in GPU kernel function
- My ID
 - blockIdx.x: Index of the block the thread belong to (≥ 0)
 - threadIdx.x: Index of the thread (**inside the block**) (≥ 0)
- Number of thread/blocks
 - blockDim.x: How many threads (**per block**) are running



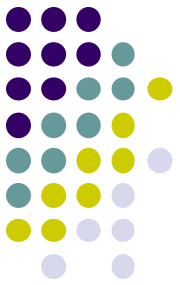
Thread Block ID, Thread ID



For every thread, `gridDim.x = 4`, `blockDim.x = 3`

Note: In order to see the entire sequential ID, we should compute
`blockIdx.x * blockDim.x + threadIdx.x`

The Case of add-cuda Sample



- </gs/hs1/tga-ppcomp/22/add-cuda>
- We want to do

```
for (i = 0; i < 100; i++) { DA[i] += DB[i]; }
```

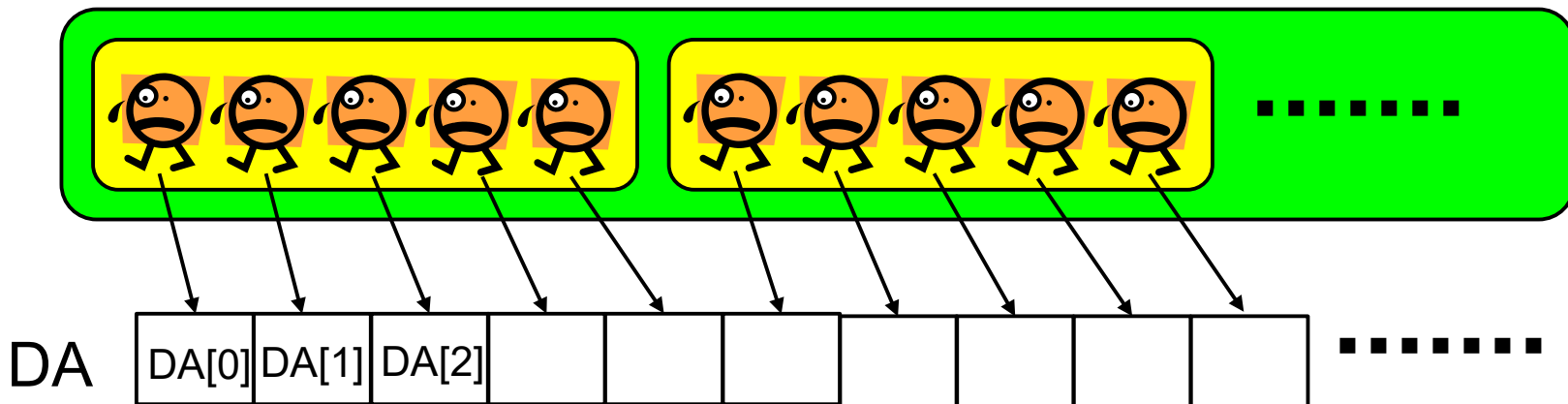
[CPU side]

```
add<<<20, 5>>>(...);
```

*20x5=100 threads
will execute add function*

[GPU side]

```
__global__ void add(int *DA, int *DB)
{
    int i = blockIdx.x * blockDim.x + threadIdx.x;
    DA[i] += DB[i];
    return;
}
```



How is Number of Threads Determined? (1)



On CUDA, a different strategy is required from on OpenMP

- On OpenMP, number of threads (OMP_NUM_THREADS) should be \leq CPU cores (or hyper threads)
 - The number is basically determined by hardware
 - ≤ 14 on q_node node, ≤ 56 on f_node
- On CUDA, it is better to use number of thread \geq GPU cores
 - ≥ 3584 on TSUBAME3's P100 GPU
 - You can use >1,000,000 threads!

How is Number of Threads Determined? (2)



We have to decide 2 numbers
<<<block number, block size>>>

A better way would be

- (1) We decide **total** number of threads P
- (2) We tune each block size BS
 - Good candidates are 32, 64, ... 1024
- (3) Then block number is P/BS
 - We consider indivisible cases later



Comparing OpenMP/OpenACC/CUDA



	OpenMP	OpenACC	CUDA
Processors	CPU	CPU+GPU	
File extension	.c, .cc		.cu
To start parallel (GPU) region	#pragma omp parallel	#pragma acc kernels	func<<<..., ...>>>()
To specify # of threads	export OMP_NUM_THREADS=...	(num_gangs, vector_length etc)	
Desirable # of threads	# of CPU cores or less	# of GPU cores or “more”	
To get thread ID	omp_thread_num()	-	blockIdx, threadIdx
Parallel for loop	#pragma omp for	#pragma acc loop	-
Task parallel	#pragma omp task	-	-
To allocate device memory	-	#pragma acc data	cudaMalloc()
To copy to/from device memory	-	#pragma acc data #pragma acc update	cudaMemcpy()
Functions on GPU	-	#pragma acc routine	__global__, __device__

※ “# of XXX” = “The number of XXX”

Assignments in GPU Part (Abstract)



Choose one of [G1]—[G3], and submit a report

Due date: May 26 (Thursday)

[G1] Parallelize “diffusion” sample program by OpenACC or CUDA

[G2] Evaluate speed of “mm-acc” or “mm-cuda” in detail

[G3] (Freestyle) Parallelize *any* program by OpenACC or CUDA.

Notes in Report Submission (1)



- Submit the followings via **T2SCHOLA**
 - (1) **A report document**
 - PDF, MS-Word or text file
 - 2 pages or more
 - in English or Japanese (日本語もok)
 - (2) **Source code files** of your program
 - Try “zip” to submit multiple files

Notes in Report Submission (2)



The report document should include:

- Which problem you have chosen
 - Also, which you have used, OpenACC or CUDA
- How you parallelized
 - It is even better if you mention efforts for high performance or new functions
- Performance evaluation on TSUBAME
 - With varying number of threads
 - With varying problem sizes
 - Discussion with your findings
 - Other machines than TSUBAME are ok, if available



Next Class:

- GPU Programming (3) on May 12
 - mm sample on CUDA
- Also please note due date of OpenMP assignment is May 12