

# Threads

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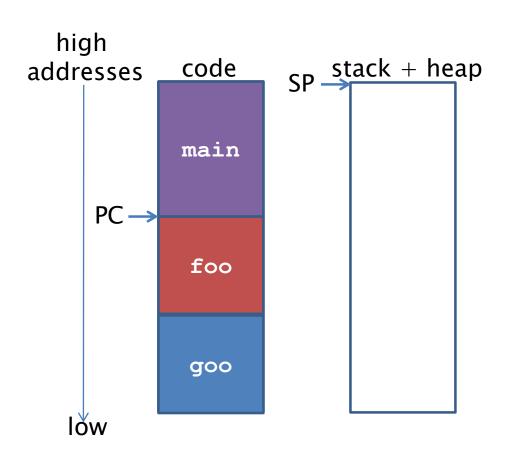
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# **Lecture Outline**

- Review on stack
- Intro to Multithreading
- Multithreading Models
- Multithreading APIs

# Stack Pointer and Program Counter



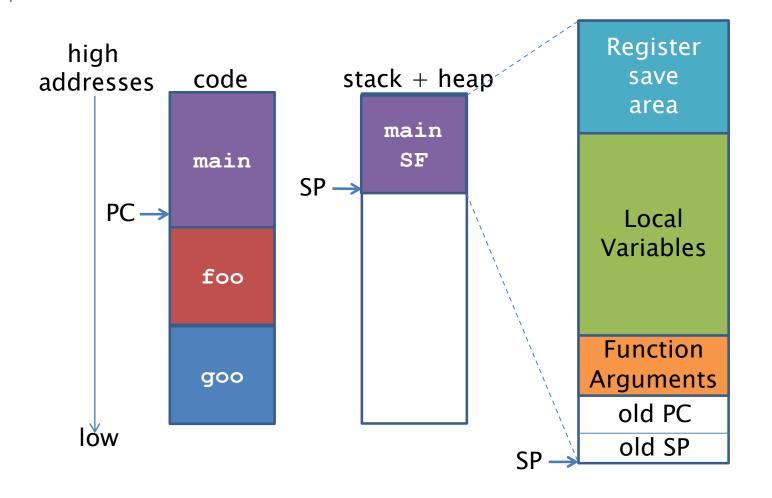
# Consider a code with the following functions:

#### Assume that the functions are called:

```
main->foo->goo
```

PC pointing to main Stack is empty

#### **Stack Frame**



# Stack Frame Organization – I

```
char *foo(int x, int y , int z)
{
    int a;
    char array[500];
    double d;
    ...
    a = x+y+goo(d,z);
    ...
}
```

Register save area

Local Variables

Function Arguments

old PC

old SP

# Stack Frame Organization - II

```
Register
                                                  save
char *foo(int x, int y , int z)
                                                  area
     int a;
     char array[500];
     double d;
                                                 Local
                                               Variables
     a = x+y+goo(d,z);
                                                Function
                                              Arguments
                                                 old PC
                                                 old SP
a and d could be in registers
```

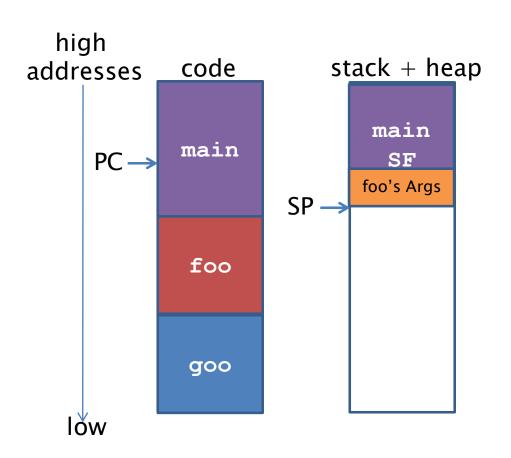
# Stack Frame Organization - III

```
Register
                                                    save
char *foo(int x, int y , int z)
                                                     area
     int a;
     char array[500]
     double d;
                                                    Local
                                                  Variables
     a = x + y + goo(\overline{d}, z);
                                                  Function
                                                 Arguments
                                                    old PC
                                                    old SP
```

# Stack Frame Organization – IV

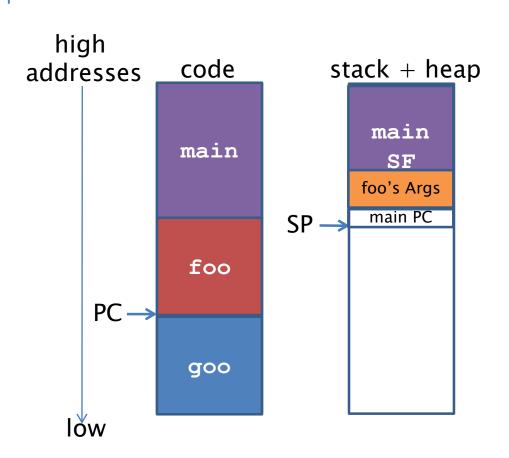
```
Register
                                                save
char *foo(int x, int y , int z)
                                                area
    int a;
    char array[500]
    double d;
                                               Local
                                             Variables
        (x+y+goo(d,z);
                                              Function
                                            Arguments
                                               old PC
                                               old SP
```

# Function Call and SF Creation - I



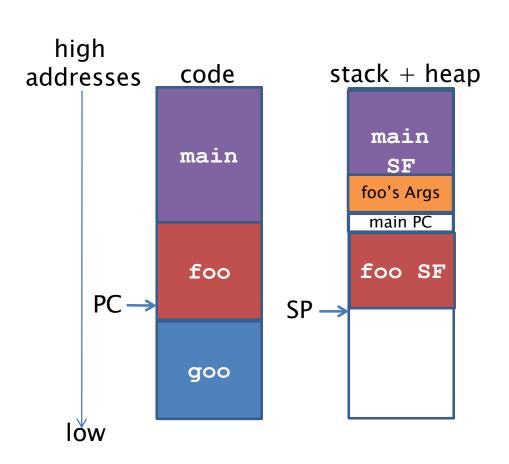
Push foo's Args

### Function Call and SF Creation - II



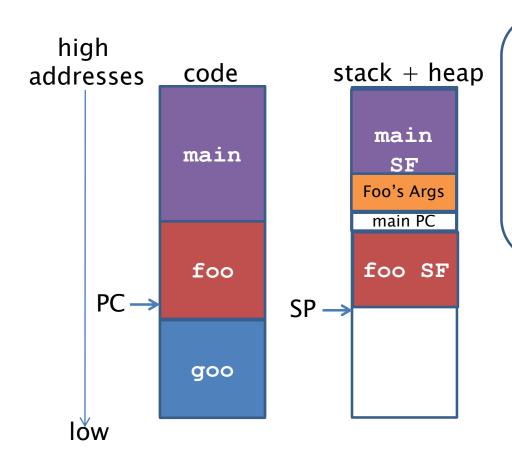
- Push foo's Args
- 2. Call foo

#### Function Call and SF Creation -III



- Push foo's Args
- 2. Call foo
- Save main SP and decrement SP

#### Function Call and SF Creation -IV



- Push foo's Args
- 2. Call foo
- Save main SP and decrement SP

Done in software i.e., done by instructions generated by the compiler!

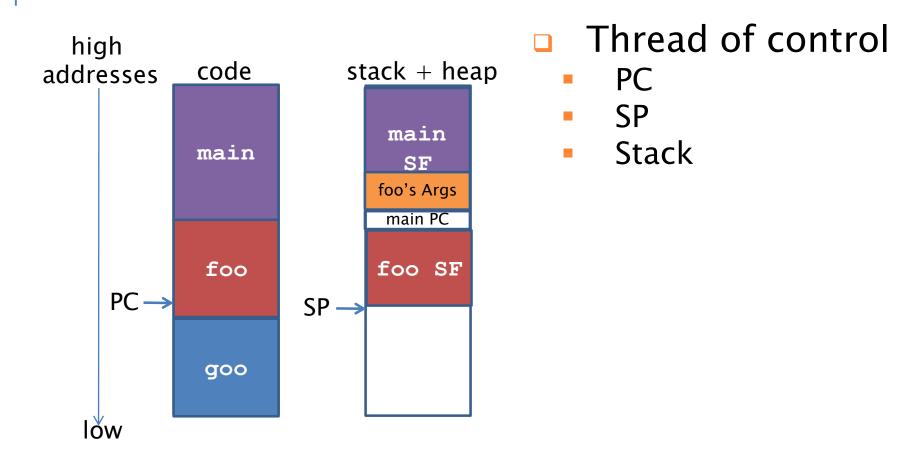
#### Q & A

- Does each function use the same stack frame size?
  - No. Depends on the size of local variables
- How and when is the size of stack frame determined?
  - Compiler determines by looking at the code.
     Compile-time.
- How is the stack frame allocated during run-time?
  - Decrementing the stack pointer

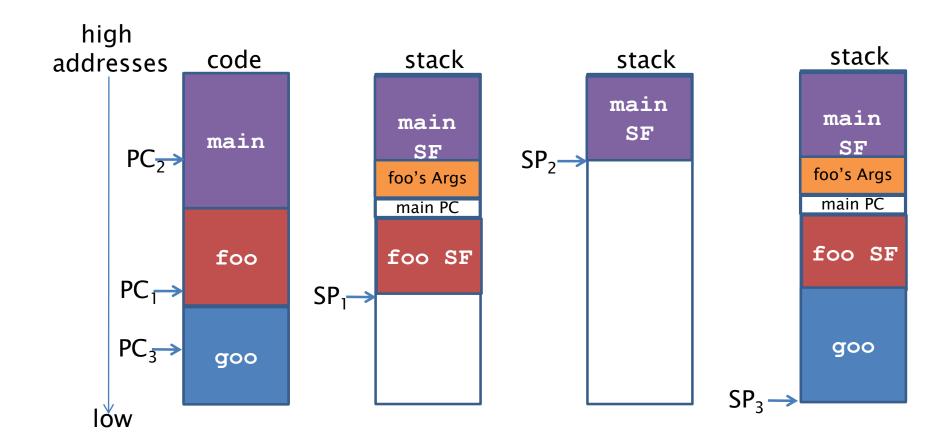
### Q & A

- What is the stack pointer?
  - A value stored in stack pointer register (x86/64: %esp (32bits), %rsp (64bits)) pointing to the beginning of the stack frame
- What is a program counter?
  - A value stored in program counter register (%eip (32bits), %rip (64bits))) pointing to a point in the text

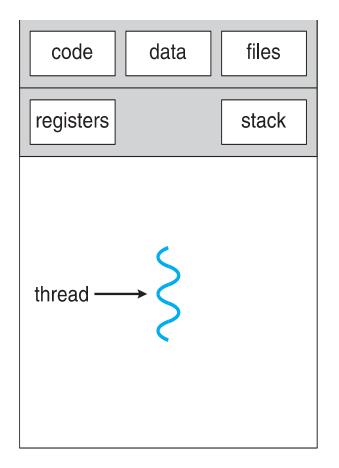
# Single-thread process

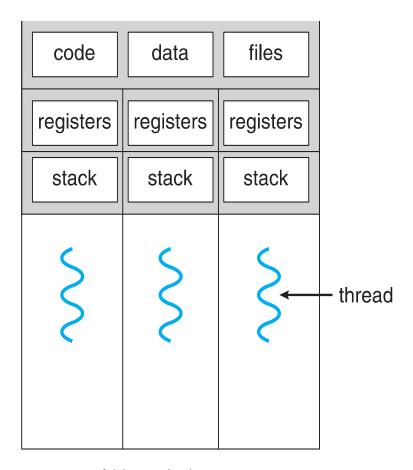


# Multi-threaded process



# Multi-threaded versus single threaded





single-threaded process

multithreaded process

# Why Multithreading?

- Responsiveness
- Resource Sharing
- Economy
- Scalability

# Matrix multiplication

$$c_{ij} = \sum_{r=1}^{n} a_{ir} \times b_{rj}$$
 How many arithmetic operations?

$$\begin{pmatrix} a_{11} & \dots & a_{1n} \\ \dots & \dots & \dots \\ a_{m1} & \dots & a_{mn} \end{pmatrix} \times \begin{pmatrix} b_{11} & \dots & b_{1k} \\ \dots & \dots & \dots \\ b_{n1} & \dots & b_{nk} \end{pmatrix} = \begin{pmatrix} c_{11} & \dots & c_{1k} \\ \dots & \dots & \dots \\ c_{m1} & \dots & c_{mk} \end{pmatrix}$$

### An initial solution

```
void slow multiply (Matrix A, Matrix B, Matrix C)
    for (int i=0; i < m; i++)
        for (int j=0; j < k; j++)
             int acc = 0;
             for (int r=0; r< n; r++)
                 acc += A[i][r]*B[r][j];
             C[i][j] = acc;
```

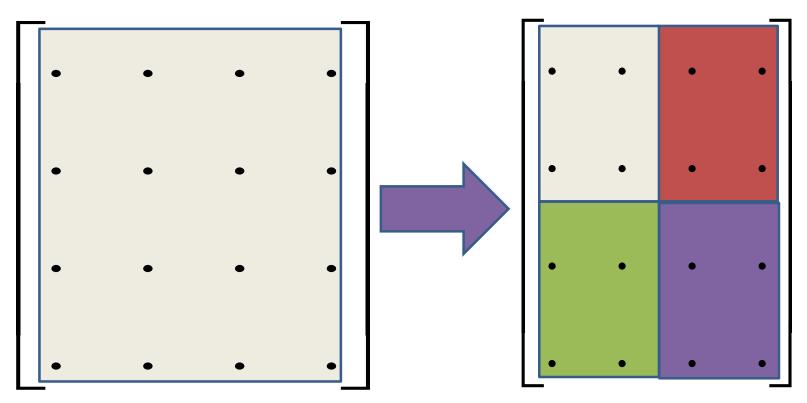
### Resources Usage

```
void
                       void slow multiply (Matrix A, Matrix
slow multiply
                       B, Matrix C)
(Matrix A,
Matrix B,
Matrix C)
                                      CPU<sub>2</sub>
       CPU<sub>1</sub>
                         CPU<sub>1</sub>
                                                  CPU<sub>3</sub>
                                                                      CPU_n
```

# Doing better

Instead of computing  $C_{00}$ ,  $C_{01}$ ,  $C_{02}$ ,  $C_{03}$ ,....

Why don't we .... split up the computation?



# Multithreads of Multiplication

#### **Procedure** multiply(*C*, *A*, *B*):

- •Base case: if n = 1, set  $c_{11} \leftarrow a_{11} \times b_{11}$  (or multiply a small block matrix).
- •Otherwise, allocate space for a new matrix T of shape  $n \times n$ , then:
  - Partition A into A<sub>11</sub>, A<sub>12</sub>, A<sub>21</sub>, A<sub>22</sub>.
  - Partition B into  $B_{11}$ ,  $B_{12}$ ,  $B_{21}$ ,  $B_{22}$ .
  - Partition C into  $C_{11}$ ,  $C_{12}$ ,  $C_{21}$ ,  $C_{22}$ .
  - Partition T into  $T_{11}$ ,  $T_{12}$ ,  $T_{21}$ ,  $T_{22}$ .
  - Parallel execution:
    - Fork multiply( $C_{11}$ ,  $A_{11}$ ,  $B_{11}$ ).
    - Fork multiply( $C_{12}$ ,  $A_{11}$ ,  $B_{12}$ ).
    - Fork multiply( $C_{21}$ ,  $A_{21}$ ,  $B_{11}$ ).
    - Fork multiply( $C_{22}$ ,  $A_{21}$ ,  $B_{12}$ ).
    - Fork multiply( $T_{11}$ ,  $A_{12}$ ,  $B_{21}$ ).
    - Fork multiply( $T_{12}$ ,  $A_{12}$ ,  $B_{22}$ ).
    - Fork multiply( $T_{21}$ ,  $A_{22}$ ,  $B_{21}$ ).
    - Fork multiply( $T_{22}$ ,  $A_{22}$ ,  $B_{22}$ ).
  - Join (wait for parallel forks to complete).
  - add(C, T).
  - Deallocate T.

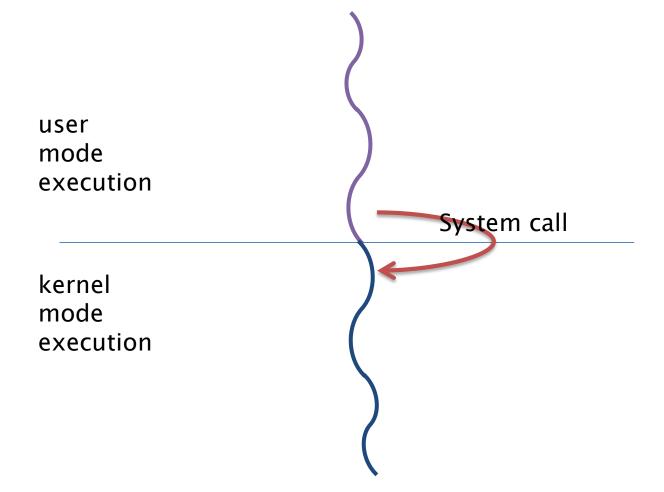
# Two kinds of stack

- User Stack
  - Used for user-level programs
- Kernel Stack
  - Used by system-calls

# User Threads and Kernel Threads

- User threads management done by user-level threads library
- Three primary thread libraries:
  - POSIX Pthreads
  - Windows threads
  - Java threads
- Kernel threads Supported by the Kernel
- Examples virtually all general purpose operating systems, including:
  - Windows
  - Linux
  - Mac OS X

# Single thread execution



# Multithreading Model

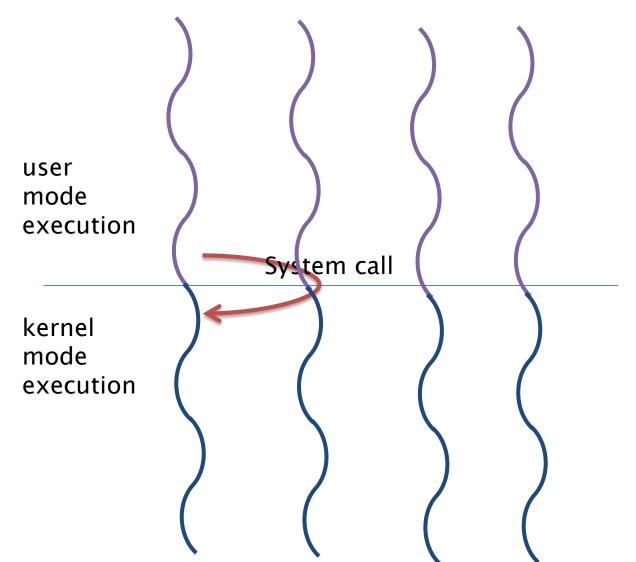
- Ratio of User Level Threads to Kernel Level Threads in a Process
  - M:1
  - 1:1
  - M:N

### M: 1 Model

user mode execution

kernel mode execution System call

#### 1:1 Thread Execution



# M:N Thread Execution user mode execution System call kernel mode execution

# Threads API

- Basic
  - Thread Creation
  - Thread Joining & Exit
- Advanced
  - ProcessorAffinity
  - Yield CPU

# **Threads Creation**

- Thread ID
- Passing Arguments to thread
- Starting function for thread
  - pthread\_create in Linux/Unix
  - CreateThread in Win32

# Threads Joining and Exit

- Linux
  - pthread\_join and pthread\_exit
- Win32
  - WaitForSingleObject
  - ExitThread