Problem 1 (10 points). Let $S[1 \cdots n]$ be an *sorted* array with *n distinct* integers in ascending order. We select an integer *k* uniformly at random from $\{1, 2, \dots, n\}$.

- 1. What is the probability that S[k] is no less than the *i*-th smallest number in S and no larger than the *j*-th smallest number in S (assume that i < j)?
- 2. What is the probability that S[k] is no larger than the *i*-th smallest number in S or no less than the j-th smallest number in S (assume that i < j)?

Solution.

- 1. (j-i+1)/n.
- 2. (i+n-j+1)/n.

Problem 2 (10 points). Let $S[1 \cdots n]$ be an array with *n distinct* integers. We select an integer *k* uniformly at random from $\{1, 2, \dots, n\}$.

- 1. What is the probability that S[k] is no less than the *i*-th smallest number in S and no larger than the *j*-th smallest number in S (assume that i < j)?
- 2. What is the probability that S[k] is no larger than the *i*-th smallest number in S or no less than the j-th smallest number in S (assume that i < j)?

Solution.

- 1. (j-i+1)/n.
- 2. (i+n-j+1)/n.

Problem 3 (20 points). You are given two lists A and B, each of which is sorted in ascending order. It is guaranteed that all numbers in A and B are distinct. Given an integer k with $1 \le k \le |A| + |B|$, design an $O(\log |A| + \log |B|)$ time algorithm for computing the k-th smallest element in the union of A and B.

Solution. Without loss of generality, assume that $|A| \le k$ and $|B| \le k$, otherwise we can only keep the first k elements of A or B. (This is only true in the beginning but not during the recursion anymore.) We will again use the idea of binary search (refer to Problem 3 of Homework 2). Consider the middle elements of A[m/2] and B[n/2], where m = |A| and n = |B|. We show that we can discard half numbers in one of the two arrays by comparing A[m/2] and B[n/2]. Suppose that we have A[m/2] < B[n/2]. We consider two cases.

The first case is when we have k < m/2 + n/2, and we can claim that we can discard the second half of array B, i.e., the k-th smallest element must be not in $B[n/2 \cdots n]$. To see this, consider how many numbers are *guaranteed to be smaller than* B[n/2]. Clearly, the first n/2 - 1 numbers in B are smaller than B[n/2]. In array A, the first m/2 numbers are also guaranteed to be smaller than B[n/2] as we have A[m/2] < B[n/2]. So the numbers in $A \cup B$ that can are guaranteed to be smaller than B[n/2] is at least $m/2 + n/2 - 1 \ge k$, as we have m/2 + n/2 > k. This implies that B[n/2] is at least the (k+1)-th smallest number in $A \cup B$. Hence, we can discard all numbers in $B[n/2 \cdots n]$, and the k-th smallest number in $A \cup B$ will be exactly the k-th smallest number in the union of A and $B[1 \cdots n/2 - 1]$.

The second case is when we have $k \ge m/2 + n/2$, then we can safely discard the first half of array A, i.e., the k-th smallest element must be not in $A[1 \cdots m/2]$. To see this, consider how many numbers might be smaller than A[m/2]. Clearly, the first m/2 - 1 numbers in A are smaller than A[m/2]. In array B, the first n/2 - 1 numbers might be smaller than A[m/2], as all numbers in $B[n/2 \cdots n]$ are larger than A[m/2]. So the maximum numbers in $A \cup B$ that can be smaller than A[m/2] is m/2 - 1 + n/2 - 1 = 1

 $m/2 + n/2 - 2 \le k - 2$. This implies that A[m/2] is at most the (k-1)-th smallest number in $A \cup B$. Hence, we can discard the first m/2 numbers in A, and the k-th smallest number in $A \cup B$ will be exactly the (k-m/2)-th smallest number in the union of A[m/2+1,m] and B. Symmetric results can be obtained if we have A[m/2] > B[n/2].

We define that the recursion function select-in-two-sorted-arrays $(A, a_1, a_2, B, b_1, b_2, k)$ return the k-th smallest element in the union of $A[a_1 \cdots a_2]$ and $B[b_1 \cdots b_2]$. There are 2 possible base cases: if $a_1 > a_2$ (resp. $b_1 > b_2$) then it means that A is empty (resp. B is empty), and we can immediately locate the desired element in B (resp. in A); if we have k = 1, then we can compare the first elements of the arrays and return the smaller one.

```
function select-in-two-sorted-arrays (A, a_1, a_2, B, b_1, b_2, k)
     if a_1 > a_2: return B[b_1 + k - 1];
     if b_1 > b_2: return A[a_1 + k - 1];
     if k = 1: return the smaller one between A[a_1] and B[b_1];
     let a = (a_1 + a_2)/2;
     let b = (b_1 + b_2)/2;
     m = a_2 - a_1 + 1;
     n = b_2 - b_1 + 1;
     if A[a] < B[b]:
        if k < m/2 + n/2: return select-in-two-sorted-arrays (A, a_1, a_2, B, b_1, b - 1, k);
        if k \ge m/2 + n/2: return select-in-two-sorted-arrays (A, a+1, a_2, B, b_1, b_2, k-a+a_1-1);
     else:
        if k < m/2 + n/2: return select-in-two-sorted-arrays (A, a_1, a - 1, B, b_1, b_2, k);
        if k \ge m/2 + n/2: return select-in-two-sorted-arrays (A, a_1, a_2, B, b+1, b_2, k-b+b_1-1);
     end if
end function
```

We can call select-in-two-sorted-arrays (A, 1, |A|, B, 1, |B|, k) to compute the k-th smallest element in $A \cup B$.

To analyze the running time, notice that in each iteration, either $a_2 - a_1$ is reduced by half, or of $b_2 - b_1$ is reduced by half. Therefore, the running time is $O(\log |A| + \log |B|)$.

Problem 4 (20 points). Let $S[1 \cdots n]$ be an array with *n distinct* integers. Given an integer k with $1 \le k \le n$, design an algorithm to partition S into S_L (integers in S that are smaller than S[k]), S[k], and S_R (integers in S that are larger than S[k]) using at most constant amount of extra memory.

Solution. We maintain two pointers, k_1 and k_2 , pointing to the first and last elements in the beginning, i.e., $k_1 = 1$ and $k_2 = n$. We will move k_1 right and move k_2 left until we find that $S[k_1] > S[k]$, and $S[k_2] < S[k]$. When this happens, we swap $S[k_1]$ and $S[k_2]$. To avoid handling multiple cases when k_1 or k_2 equals to k, we can first swap S[1] and S[k] to protect S[k] and swap them again in the end. The pseudo-code is as follows.

```
function partition-in-place (S,k) let k_1=1; let k_2=n; swap S[1] and S[k]; /* now S[1] is the pivot */ while (k_1 < k_2) while (S[k_1] < S[1]) k_1 = k_1 + 1; while (S[k_2] > S[1]) k_2 = k_2 - 1; if (k_1 < k_2): swap S[k_1] and S[k_2]; end while; swap S[k_2] and S_1; /*S[1 \cdots k_2 - 1], S[k_2], and S[k_2 + 1 \cdots n] will be the desired partition*/ end function
```

The above algorithm takes linear time and only uses constant number of memory units.

Problem 5 (20 points). Let $S[1 \cdots n]$ be an array with n distinct integers. We say two indices (i, j) form an inversion if we have i < j and S[i] > S[j]. Design an divide-and-conquer algorithm that counts the number of inversions in S. Your algorithm should run in $O(n \cdot \log n)$ time. For example, if you are given S = (3, 8, 5, 2, 9), then your algorithm should return 4. The 4 inversions are (3, 2), (8, 5), (8, 2), (5, 2).

Solution. We can design a divide-and-conquer algorithm to count the number of inversions. Define recursive function count-inversions (S) returns (S',N), where S' is the sorted list of S, and N is the number of inversions in array S. We can recursively call (S_1,N_1) = count-inversions ($S[1\cdots n/2]$), and (S_2,N_2) = count-inversions ($S[n/2+1\cdots n]$). To compute the total number of inversions in S, we need to add up S_1 and S_2 , and also the inversions between the two halves of S. Since now we have the sorted lists of the two halves, which are stored in S_1 and S_2 , we can use them to count inversions. Similar to the merge-two-sorted-arrays function, we can maintain two pointers and scan both arrays, once we have that $S_1[i] > S_2[j]$, then we know all numbers in S_1 that are at index $S_2[i]$ are larger than $S_2[i]$, i.e., we have $S_1[i] = i + 1$ inversions by comparing all elements in S_1 to $S_2[i]$. The pseudo-code for counting the number of inversions between two sorted arrays is below.

```
function count-inversions-between-two-sorted-lists (S_1, S_2) /* merge S_1 \& S_2, and count cross inversions
      let k_1 = 1, k_2 = 1, k_3 = 1, N = 0;
      init list S_3; /* S_3 will store the merged list of S_1 and S_2;
      while (k_1 \le |S_1| \text{ and } k_2 \le |S_2|)
        if (S_1[k_1] < S_2[k_2])
            S_3[k_3] = S[k_1];
           k_1 = k_1 + 1;
           k_3 = k_3 + 1;
         else
            N = N + (|S_1| - k_1) + 1;
            S_3[k_3] = S[k_2];
            k_2 = k_2 + 1;
           k_3 = k_3 + 1;
         end if
     end while
      while (k_1 \leq |S_1|)
        S_3[k_3] = S[k_1];
        k_1 = k_1 + 1;
        k_3 = k_3 + 1;
      end while
      while (k_2 \le |S_1|)
        S_3[k_3] = S[k_2];
        k_2 = k_2 + 1;
        k_3 = k_3 + 1;
     end while
      return S_3, N;
end function
```

The entire divide-and-conquer algorithm for computing inversions with array S is below.

```
function count-inversions (S)

if (|S|=1): return 0;

let n=|S|;

(S_1,N_1) = count-inversion (S[1\cdots n/2]);

(S_2,N_2) = count-inversion (S[n/2+1\cdots n]);

(S_3,N_3) = count-inversions-between-two-sorted-arrays (S_1,S_2);

return (S_3,N_1+N_2+N_3);
end function
```

The merge-step of count-inversions-between-two-sorted-arrays takes linear time. Hence, the recursion for the above algorithm is $T(n) = 2 \cdot T(n/2) + O(n)$. Therefore the running time is $O(n \cdot \log n)$.