

# Selected Problems Chapter 5

## Linear Algebra Done Right, Sheldon Axler, 3rd Edition

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**Problem Example 5.8.** Suppose  $T \in \mathcal{L}(F^2)$  is defined by  $T(w, z) = (-z, w)$ . Find the eigenvectors and eigenvalues of  $T$  if  $F = \mathbb{R}$ . Find the eigenvectors and eigenvalues of  $T$  if  $F = \mathbb{C}$

*Proof.* **Part(a).**

Assume  $T$  has eigenvectors and eigenvalues with  $F = \mathbb{R}$ . The equation  $\lambda(w, z) = (-z, w)$  holds and leads to the following system of equations:

$$\lambda w = -z$$

$$\lambda z = w.$$

Solving for  $\lambda$ , we have  $\lambda^2 = -1$ , which only has solutions in  $\mathbb{C}$ . This contradiction means  $T$  has no eigenvectors and eigenvalues.

**Part(b).**

In part(a), we showed that the eigenvalues of  $T$  must be in the complex numbers. The equation from part(a)  $\lambda^2 = -1$  has the solutions  $\lambda = i$  and  $\lambda = -i$ . The eigenvectors corresponding to  $\lambda = i$  are of the form  $(w, -iw)$  for any  $w \in \mathbb{C}$ ; the eigenvectors corresponding to  $\lambda = -i$  are of the form  $(w, iw)$ .

□

**Problem Theorem 5.10 Linearly Independent Eigenvectors.** Let  $T \in \mathcal{L}(V)$ . Suppose  $(\lambda_1, \dots, \lambda_n)$  are distinct eigenvalues of  $T$ , and  $(v_1, \dots, v_n)$  are corresponding eigenvectors. Then  $(v_1, \dots, v_n)$  is a linearly independent list.

*Proof.* For a contradiction, suppose  $(v_1, \dots, v_n)$  is a linearly dependent list. Then choose  $a_1, \dots, a_n \in F$  where not all are zero such that  $0 = a_1 v_1 + \dots + a_n v_n$ . By the linear dependence lemma, choose the smallest  $j$  such that  $v_j = \frac{a_1}{a_j} v_1 + \dots + \frac{a_{j-1}}{a_j} v_{j-1}$ . Applying  $T$ , we have

$$\lambda_j v_j = \frac{a_1 \lambda_1}{a_j} v_1 + \dots + \frac{a_{j-1} \lambda_{j-1}}{a_j} v_{j-1}.$$

Subtracting the left side, we have

$$0 = \frac{a_1(\lambda_1 - \lambda_j)}{a_j} v_1 + \dots + \frac{a_{j-1}(\lambda_{j-1} - \lambda_j)}{a_j} v_{j-1}.$$

Each  $(\lambda_k - \lambda_j) \neq 0$  because the eigenvalues are distinct. Since we chose  $j$  to be the smallest such that the  $v_j$  is in the span of the preceding vectors,  $a_k = 0$  for  $k = 1, \dots, j-1$ . Thus,  $v_j = 0$ , but that is a contradiction because  $v_j$  is an eigenvector. □

**Problem Theorem 5.13 Number of Eigenvalues.** Suppose  $V$  is finite-dimensional. Then each operator on  $V$  has at most  $\dim(V)$  distinct eigenvalues.

*Proof.* Let  $T \in \mathcal{L}(V)$ . Let  $(\lambda_1, \dots, \lambda_n)$  be a list of distinct eigenvalues in  $F$ , and let  $(u_1, \dots, u_m)$  be a corresponding list of eigenvectors. By Theorem 5.10,  $(v_1, \dots, v_n)$  is a linearly independent list. Choose a basis  $(v_1, \dots, v_n)$  of  $V$ . By Theorem 2.23,  $m \leq n = \dim(V)$ .  $\square$

**Problem 5.A.12.** Define  $T \in \mathcal{L}(P_4(\mathbb{R}))$  by

$$T(p(x)) = xp'(x)$$

for all  $x \in \mathbb{R}$ . Find all the eigenvalues and eigenvectors.

Assume  $T$  has an eigenvalue  $\lambda$ . Choose a non-zero  $p(x) = a_0 + a_1x + \cdots + a_4x^4 \in P_4(\mathbb{R})$  such that  $T(p(x)) = \lambda p(x)$ . This is equivalent to the system of equations

$$\begin{aligned}\lambda a_0 &= 0 \\ \lambda a_1 &= a_1 \\ \lambda a_2 &= 2a_2 \\ \lambda a_3 &= 3a_3 \\ \lambda a_4 &= 4a_4\end{aligned}$$

This is equivalent to

$$\begin{aligned}\lambda a_0 &= 0 \\ a_1(\lambda - 1) &= 0 \\ a_2(\lambda - 2) &= 0 \\ a_3(\lambda - 3) &= 0 \\ a_4(\lambda - 4) &= 0\end{aligned}$$

Let  $\lambda \in \{0, 1, 2, 3, 4\}$ . Then for each  $j \neq \lambda$

$$\begin{aligned}a_j(\lambda - j) &= 0 \\ a_j &= 0\end{aligned}$$

by dividing by  $(\lambda - j)$ . The corresponding eigenvector for  $\lambda$  is then  $p(x) = a_\lambda x^\lambda$ . Let  $\lambda \notin \{0, 1, 2, 3, 4\}$ . By dividing the coefficient  $(\lambda - j)$  for  $j = 0, 1, 2, 3, 4$ , we have  $a_j = 0$  for each  $j$ . Thus,  $p(x) = 0$ , which is not an eigenvector.

We've shown that the eigenvalues are  $\lambda = 0, 1, 2, 3, 4$  with the corresponding eigenvectors  $c, cx, cx^2, cx^3, cx^4$  for  $c \in \mathbb{R}$ .

**Problem 5.A.15.** Suppose  $T \in \mathcal{L}(V)$ . Suppose  $S \in \mathcal{L}(V)$  is invertible.

- (a) Prove that  $T$  and  $S^{-1}TS$  have the same eigenvalues
- (b) What is the relationship between the eigenvectors of  $T$  and the eigenvectors of  $S^{-1}TS$ ?

*Proof.* **Part(a)**

We must show that  $\lambda$  is an eigenvalue of  $T$  if and only if  $\lambda$  is an eigenvalue of  $S^{-1}TS$ . For the forward direction, assume  $\lambda$  is an eigenvalue of  $T$ . Choose  $v \in V$  such that  $Tv = \lambda v$ . Since  $S$  is invertible,  $S$  is also injective and surjective. We can choose  $u \in V$  such that  $Su = v$ . We have

$$\begin{aligned}(S^{-1}TS)u &= (S^{-1}T)(Su) \\ &= (S^{-1}T)(v) \\ &= (S^{-1})(\lambda v) \\ &= \lambda u.\end{aligned}$$

For the backward direction, assume  $\lambda$  is an eigenvalue of  $S^{-1}TS$ . Choose  $u \in V$  such that  $(S^{-1}TS)u = \lambda u$ . Applying  $S$  to  $(S^{-1}TS)u$ , we have

$$\begin{aligned}(TS)u &= T(Su) \\ &= \lambda(Su)\end{aligned}$$

,

as desired.

**Part(b)**

If  $v$  is an eigenvector of  $T$ , then  $S^{-1}v$  is an eigenvector of  $S^{-1}TS$ . if  $v$  is an eigenvector of  $S^{-1}TS$ ,  $Sv$  is an eigenvector of  $T$ .

□

**Problem 5.A.18.** Show that the operator  $T \in \mathcal{L}(C^\infty)$  defined by

$$T(z_1, z_2, \dots) = (0, z_1, z_2, \dots)$$

has no eigenvalues.

*Proof.* Assume that  $T(z_1, z_2, \dots) = \lambda(z_1, z_2, \dots)$ . This is equivalent to the following system of equations

$$\lambda z_1 = 0$$

$$\lambda z_2 = z_1$$

$$\lambda z_3 = z_2$$

$$\dots$$

The first equation implies  $\lambda = 0$  or  $z_1 = 0$ . If  $\lambda = 0$ , then  $(z_1, z_2, \dots)$  is the zero vector. If  $z_1 = 0$  each  $z_j = 0$ , and thus  $(z_1, z_2, \dots)$  is the zero vector. We have that  $(z_1, z_2, \dots)$  is the zero vector, which can't be associated with any eigenvalue by definition.

□

**Problem 5.A.20.** Find all eigenvalues and eigenvectors of the backward shift operator  $T \in \mathcal{L}(F^\infty)$  defined by

$$T(z_1, z_2, \dots) = (z_2, z_3, \dots)$$

Assume  $T(z_1, z_2, \dots) = \lambda(z_1, z_2, \dots)$  with  $(z_1, z_2, \dots)$  being non-zero. The previous relation is equivalent to the system of equations

$$\lambda z_1 = z_2$$

$$\lambda z_2 = z_3$$

$$\lambda z_3 = z_4$$

...

By substitution of variables, another equivalent form is

$$\lambda z_1 = z_2$$

$$\lambda^2 z_1 = z_3$$

$$\lambda^3 z_1 = z_4$$

...

Thus, all eigenvectors are of the form  $(z_1, z_2, z_3, \dots) = (z_1, \lambda z_1, \lambda^2 z_1, \dots)$  with  $z_1 \neq 0$ . Each  $\lambda \in F$  is an eigen vector.