



# NFA , $\epsilon$ -NFA and Moore , Mealy machines

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## Lecture 9 and 10



# Language of an NFA

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- An NFA accepts  $w$  if *there exists at least one* path from the start state to an accepting (or final) state that is labeled by  $w$
- $L(N) = \{ w \mid \hat{\delta}(q_0, w) \cap F \neq \Phi \}$



# Advantages & Caveats for NFA

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- Great for modeling regular expressions
  - String processing - e.g., grep, lexical analyzer
- Could a non-deterministic state machine be implemented in practice?
  - Probabilistic models could be viewed as extensions of non-deterministic state machines (e.g., toss of a coin, a roll of dice)
    - They are not the same though
  - A parallel computer could exist in multiple “states” at the same time

# Technologies for NFAs

- Micron's Automata Processor (introduced in 2013)
- 2D array of MISD (multiple instruction single data) fabric w/ thousands to millions of processing elements.
- 1 input symbol = fed to all states (i.e., cores)
- Non-determinism using circuits
- <http://www.micronautomata.com/>



But, DFAs and NFAs are equivalent in their power to capture languages !!

# Differences: DFA vs. NFA

## ■ DFA

1. All transitions are deterministic
  - Each transition leads to exactly one state
2. For each state, transition on all possible symbols (alphabet) should be defined
3. Accepts input if the last state visited is in F
4. Sometimes harder to construct because of the number of states
5. Practical implementation is feasible

## ■ NFA

1. Some transitions could be non-deterministic
  - A transition could lead to a subset of states
2. Not all symbol transitions need to be defined explicitly (if undefined will go to an error state – this is just a design convenience, not to be confused with “non-determinism”)
3. Accepts input if *one of* the last states is in F
4. Generally easier than a DFA to construct
5. Practical implementations limited but emerging (e.g., Micron automata processor)



# Equivalence of DFA & NFA

- Theorem:

Should be  
true for  
any L

- → A language L is accepted by a DFA if and only if it is accepted by an NFA.

- Proof:

1. If part:

- Prove by showing every NFA can be converted to an equivalent DFA (in the next few slides...)

2. Only-if part is trivial:

- Every DFA is a special case of an NFA where each state has exactly one transition for every input symbol. Therefore, if L is accepted by a DFA, it is accepted by a corresponding NFA. □



# Proof for the if-part

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- If-part: A language  $L$  is accepted by a DFA if it is accepted by an NFA
  - rephrasing...
  - Given any NFA  $N$ , we can construct a DFA  $D$  such that  $L(N)=L(D)$
- 
- How to convert an NFA into a DFA?
    - Observation: In an NFA, each transition maps to a *subset* of states
    - Idea: Represent:  
each “subset of NFA\_states”  $\rightarrow$  a single “DFA\_state”

*Subset construction*



## NFA to DFA by subset construction

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- Let  $N = \{Q_N, \Sigma, \delta_N, q_0, F_N\}$
- Goal: Build  $D = \{Q_D, \Sigma, \delta_D, \{q_0\}, F_D\}$  s.t.  
 $L(D) = L(N)$
- Construction:
  1.  $Q_D$  = all subsets of  $Q_N$  (i.e., power set)
  2.  $F_D$  = set of subsets  $S$  of  $Q_N$  s.t.  $S \cap F_N \neq \emptyset$
  3.  $\delta_D$ : for each subset  $S$  of  $Q_N$  and for each input symbol  $a$  in  $\Sigma$ :
    - $\delta_D(S, a) = \bigcup_{p \in S} \delta_N(p, a)$

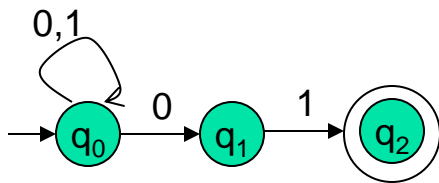


Idea: To avoid enumerating all of power set, do "lazy creation of states"

# NFA to DFA construction: Example

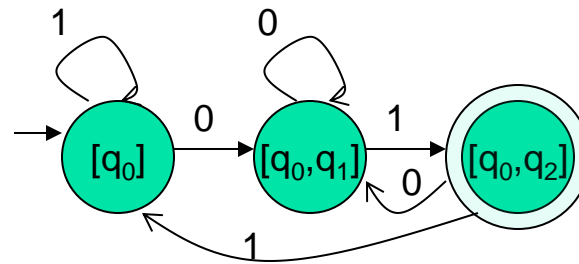
- $L = \{w \mid w \text{ ends in } 01\}$

**NFA:**



$\delta_N$	0	1
$\rightarrow q_0$	$\{q_0, q_1\}$	$\{q_0\}$
$q_1$	$\emptyset$	$\{q_2\}$
$*q_2$	$\emptyset$	$\emptyset$

**DFA:**



$\delta_D$	
<del><math>\emptyset</math></del>	
$\rightarrow [q_0]$	
<del><math>[q_1]</math></del>	
<del><math>*[q_2]</math></del>	
$[q_0, q_1]$	
$*[q_0, q_2]$	
<del><math>*[q_1, q_2]</math></del>	
<del><math>*[q_0, q_1, q_2]</math></del>	

$\delta_D$	0	1
$\rightarrow [q_0]$	$[q_0, q_1]$	$[q_0]$
$[q_0, q_1]$	$[q_0, q_1]$	$[q_0, q_2]$
$*[q_0, q_2]$	$[q_0, q_1]$	$[q_0]$

- Enumerate all possible subsets
- Determine transitions
- Retain only those states reachable from  $\{q_0\}$



# Correctness of subset construction

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*Theorem:* *If  $D$  is the DFA constructed from NFA  $N$  by subset construction, then  $L(D)=L(N)$*

■ Proof:

- Show that  $\hat{\delta}_D(\{q_0\}, w) \equiv \hat{\delta}_N(q_0, w)$  , for all  $w$
- Using induction on  $w$ 's length:
  - Let  $w = xa$
  - $\hat{\delta}_D(\{q_0\}, xa) \equiv \hat{\delta}_D(\hat{\delta}_N(q_0, x), a) \equiv \hat{\delta}_N(q_0, w)$



# Applications

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- Text indexing
  - inverted indexing
  - For each unique word in the database, store all locations that contain it using an NFA or a DFA
- Find pattern P in text T
  - Example: Google querying
- Extensions of this idea:
  - PATRICIA tree, suffix tree



# A few subtle properties of DFAs and NFAs

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- The machine never really terminates.
  - It is always waiting for the next input symbol or making transitions.
- The machine decides when to consume the next symbol from the input and when to ignore it.
  - (but the machine can never skip a symbol)
- $\Rightarrow$  A transition can happen even *without* really consuming an input symbol (think of consuming  $\varepsilon$  as a free token) – if this happens, then it becomes an  $\varepsilon$ -NFA (see next few slides).
- A single transition *cannot* consume more than one (non- $\varepsilon$ ) symbol.



# FA with $\varepsilon$ -Transitions

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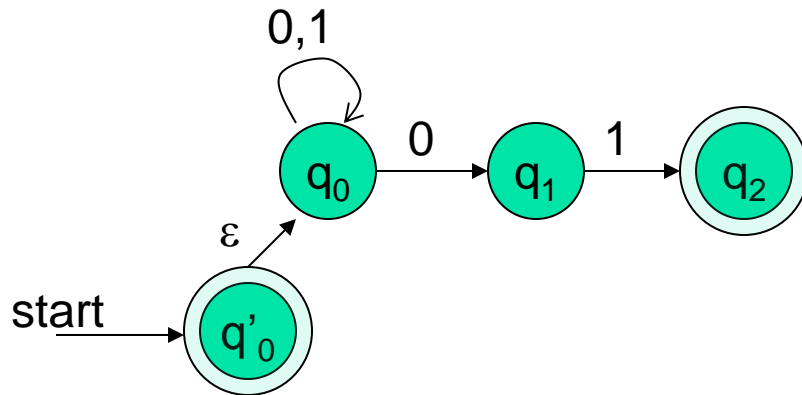
- We can allow explicit  $\varepsilon$ -transitions in finite automata
  - i.e., a transition from one state to another state without consuming any additional input symbol
  - Explicit  $\varepsilon$ -transitions between different states introduce non-determinism.
  - Makes it easier sometimes to construct NFAs

**Definition:  $\varepsilon$  -NFAs are those NFAs with at least one explicit  $\varepsilon$ -transition defined.**

- $\varepsilon$  -NFAs have one more column in their transition table

# Example of an $\varepsilon$ -NFA

$L = \{w \mid w \text{ is empty, or if non-empty will end in } 01\}$



- $\varepsilon$ -closure of a state  $q$ , **ECLOSE( $q$ )**, is the set of all states (including itself) that can be *reached* from  $q$  by repeatedly making an arbitrary number of  $\varepsilon$ -transitions.

$\delta_E$	0	1	$\varepsilon$	
$\rightarrow *q'_0$	$\{\}$	$\{\}$	$\{q'_0, q_0\}$	ECLOSE( $q'_0$ )
$q_0$	$\{q_0, q_1\}$	$\{q_0\}$	$\{q_0\}$	ECLOSE( $q_0$ )
$q_1$	$\{\}$	$\{q_2\}$	$\{q_1\}$	ECLOSE( $q_1$ )
$*q_2$	$\{\}$	$\{\}$	$\{q_2\}$	ECLOSE( $q_2$ )

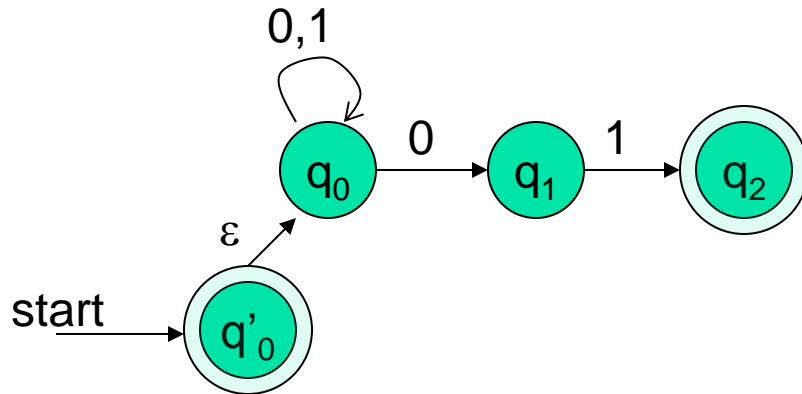
To simulate any transition:

Step 1) Go to all immediate destination states.

Step 2) From there go to all their  $\varepsilon$ -closure states as well.

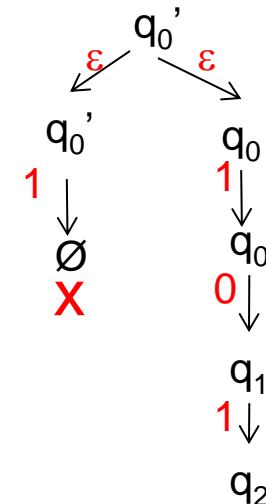
# Example of an $\varepsilon$ -NFA

$L = \{w \mid w \text{ is empty, or if non-empty will end in } 01\}$



Simulate for  $w=101$ :

$\delta_E$	0	1	$\varepsilon$	
$*q'_0$	$\{\}$	$\{\}$	$\{q'_0, q_0\}$	ECLOSE( $q'_0$ )
$q_0$	$\{q_0, q_1\}$	$\{q_0\}$	$\{q_0\}$	ECLOSE( $q_0$ )
$q_1$	$\{\}$	$\{q_2\}$	$\{q_1\}$	
$*q_2$	$\{\}$	$\{\}$	$\{q_2\}$	

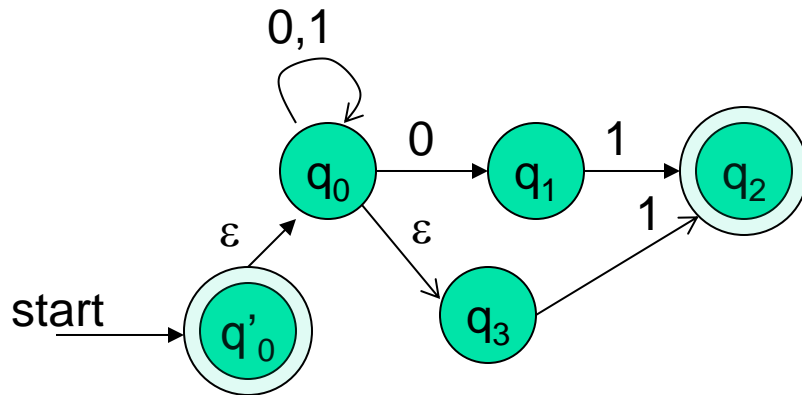


To simulate any transition:

Step 1) Go to all immediate destination states.

Step 2) From there go to all their  $\varepsilon$ -closure states as well.

## Example of another $\varepsilon$ -NFA



Simulate for  $w=101$ :

?

$\delta_E$	0	1	$\varepsilon$
$\rightarrow *q'_0$	$\{\}$	$\{\}$	$\{q'_0, q_0, q_3\}$
$q_0$	$\{q_0, q_1\}$	$\{q_0\}$	$\{q_0, q_3\}$
$q_1$	$\{\}$	$\{q_2\}$	$\{q_1\}$
$*q_2$	$\{\}$	$\{\}$	$\{q_2\}$
$q_3$	$\{\}$	$\{q_2\}$	$\{q_3\}$





# Equivalency of DFA, NFA, $\epsilon$ -NFA

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- Theorem: A language  $L$  is accepted by some  $\epsilon$ -NFA if and only if  $L$  is accepted by some DFA
- Implication:
  - $\text{DFA} \equiv \text{NFA} \equiv \epsilon\text{-NFA}$
  - (all accept Regular Languages)



# Eliminating $\varepsilon$ -transitions

Let  $E = \{Q_E, \Sigma, \delta_E, q_0, F_E\}$  be an  $\varepsilon$ -NFA

Goal: To build DFA  $D = \{Q_D, \Sigma, \delta_D, \{q_D\}, F_D\}$  s.t.  $L(D) = L(E)$

Construction:

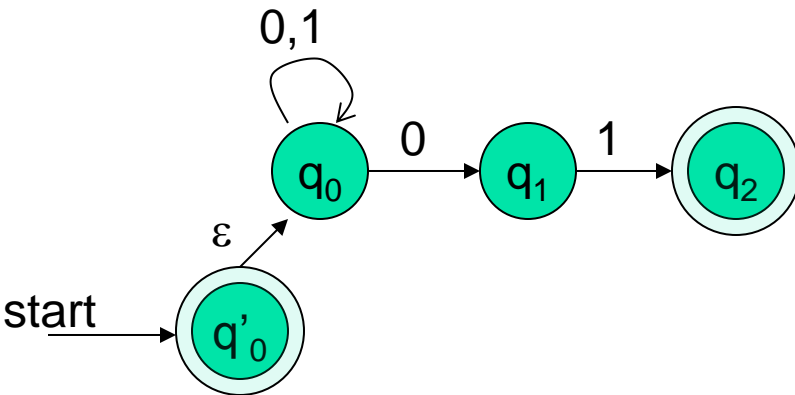
1.  $Q_D$  = all reachable subsets of  $Q_E$  factoring in  $\varepsilon$ -closures
2.  $q_D = \text{ECLOSE}(q_0)$
3.  $F_D$  = subsets  $S$  in  $Q_D$  s.t.  $S \cap F_E \neq \emptyset$
4.  $\delta_D$ : for each subset  $S$  of  $Q_E$  and for each input symbol  $a \in \Sigma$ :
  - Let  $R = \bigcup_{p \in S} \delta_E(p, a)$  // go to destination states
  - $\delta_D(S, a) = \bigcup_{r \in R} \text{ECLOSE}(r)$  // from there, take a union of all their  $\varepsilon$ -closures

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Reading: Section 2.5.5 in book

# Example: $\varepsilon$ -NFA $\rightarrow$ DFA

$L = \{w \mid w \text{ is empty, or if non-empty will end in } 01\}$

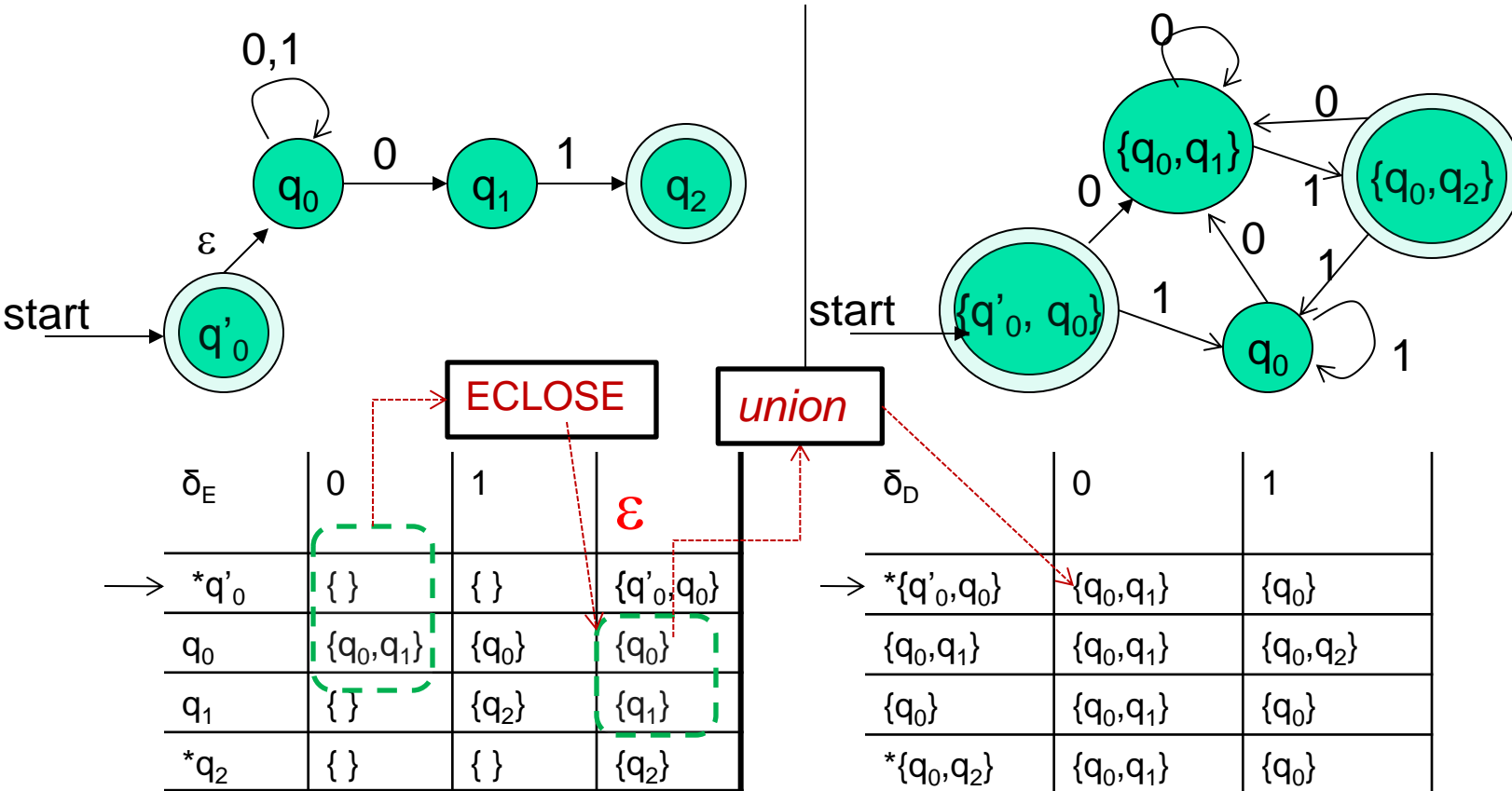


$\delta_E$	0	1	$\varepsilon$
$\rightarrow *q'_0$	$\{\}$	$\{\}$	$\{q'_0, q_0\}$
$q_0$	$\{q_0, q_1\}$	$\{q_0\}$	$\{q_0\}$
$q_1$	$\{\}$	$\{q_2\}$	$\{q_1\}$
$*q_2$	$\{\}$	$\{\}$	$\{q_2\}$

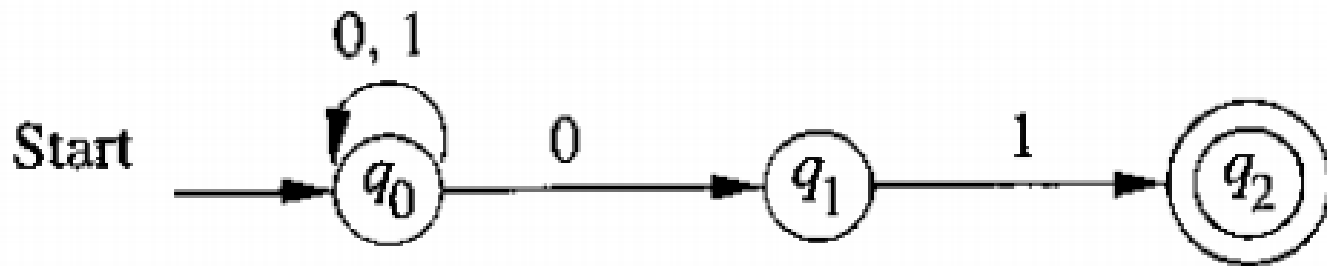
$\delta_D$	0	1
$\rightarrow * \{q'_0, q_0\}$		
...		

# Example: $\varepsilon$ -NFA $\rightarrow$ DFA

$L = \{w \mid w \text{ is empty, or if non-empty will end in } 01\}$

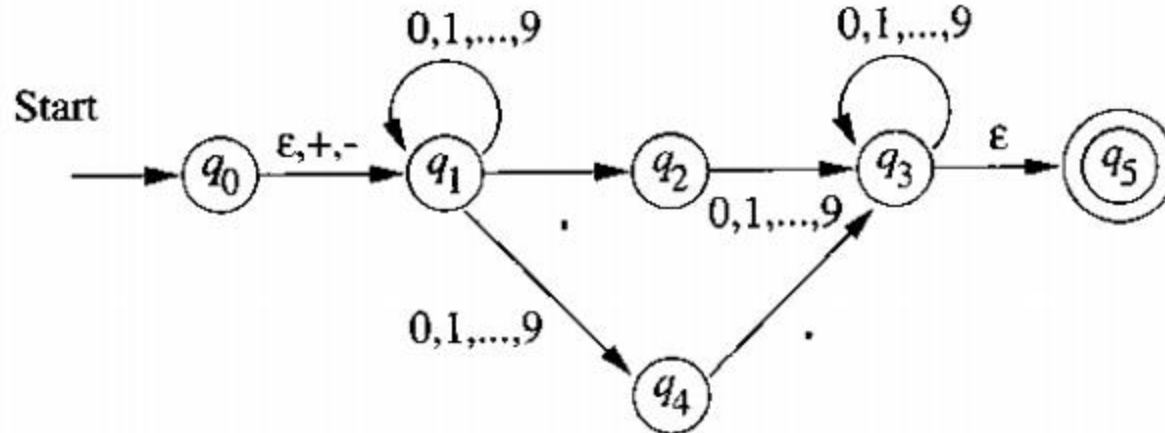


# Extended Transition Function for NFAs



- For above NFA process string 00101??

# Extended Function for $\epsilon$ -NFA



- Let compute  $\delta(q_0, 5.6) = ??$



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# Moore and Mealy Machines

Definition and example will be demonstrate in class



# Summary

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- DFA
  - Definition
  - Transition diagrams & tables
- Regular language
- NFA
  - Definition
  - Transition diagrams & tables
- DFA vs. NFA
- NFA to DFA conversion using subset construction
- Equivalency of DFA & NFA
- Removal of redundant states and including dead states
- $\epsilon$ -transitions in NFA
- Extended Transition function
- Moorey and Melay machine
- Text searching applications