

## Assembler Directives for Procedures

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- Assembler provides two directives to define procedures: PROC and ENDP
- To define a NEAR procedure, use

```
proc-name    PROC    NEAR
```

  - \* In a NEAR procedure, both calling and called procedures are in the same code segment
- A FAR procedure can be defined by

```
proc-name    PROC    FAR
```

  - \* Called and calling procedures are in two different segments in a FAR procedure

## Assembler Directives for Procedures (cont'd)

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- If FAR or NEAR is not specified, NEAR is assumed (i.e., NEAR is the default)
- We focus on NEAR procedures
- A typical NAER procedure definition

```
proc-name    PROC
. . . . .
<procedure body>
. . . . .
proc-name    ENDP
```

**proc-name** should match in PROC and ENDP

## Pentium Instructions for Procedures

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- Pentium provides two instructions: **call** and **ret**
- **call** instruction is used to invoke a procedure
- The format is

**call**      **proc-name**

**proc-name** is the procedure name

- Actions taken during a near procedure call:

$SP := SP - 2$	; push return address
$(SS:SP) := IP$	;      onto the stack
$IP := IP + \textit{relative displacement}$	; update IP
	; to point to the procedure

## Pentium Instructions for Procedures (cont'd)

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- **ret** instruction is used to transfer control back to the calling procedure
- How will the processor know where to return?
  - \* Uses the return address pushed onto the stack as part of executing the **call** instruction
  - \* Important that TOS points to this return address when **ret** instruction is executed
- Actions taken during the execution of **ret** are:

$IP := (SS:SP)$	; pop return address
$SP := SP + 2$	;      from the stack

## Pentium Instructions for Procedures (cont'd)

- We can specify an optional integer in the **ret** instruction
  - \* The format is  
**ret      optional-integer**
  - \* Example:  
**ret 6**
- Actions taken on **ret** with optional-integer are:

IP := (SS:SP)  
SP := SP + 2 + optional-integer

## How Is Program Control Transferred?

Offset(hex)	machine code(hex)		
		<b>main</b>	<b>PROC</b>
		. . . . .	. . .
cs:000A	E8000C	call	sum
cs:000D	8BD8	mov	BX,AX
		. . . . .	. . .
		<b>main</b>	<b>ENDP</b>
<hr/>			
		<b>sum</b>	<b>PROC</b>
cs:0019	55	push	BP
		. . . . .	. . .
		<b>sum</b>	<b>ENDP</b>
<hr/>			
		<b>avg</b>	<b>PROC</b>
		. . . . .	. . .
cs:0028	E8FFEE	call	sum
cs:002B	8BD0	mov	DX,AX
		. . . . .	. . .
		<b>avg</b>	<b>ENDP</b>

## Parameter Passing

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- Parameter passing is different and complicated than in a high-level language
- In assembly language
  - » You should first place all required parameters in a mutually accessible storage area
  - » Then call the procedure
- Type of storage area used
  - » Registers (general-purpose registers are used)
  - » Memory (stack is used)
- Two common methods of parameter passing:
  - » Register method
  - » Stack method

## Parameter Passing: Register Method

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- Calling procedure places the necessary parameters in the general-purpose registers before invoking the procedure through the **call** instruction
- Examples:
  - \* **PROCEX1.ASM**
    - » call-by-value using the register method
    - » a simple sum procedure
  - \* **PROCEX2.ASM**
    - » call-by-reference using the register method
    - » string length procedure

## Pros and Cons of the Register Method

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- Advantages
  - \* Convenient and easier
  - \* Faster
- Disadvantages
  - \* Only a few parameters can be passed using the register method
    - Only a small number of registers are available
  - \* Often these registers are not free
    - freeing them by pushing their values onto the stack negates the second advantage

## Parameter Passing: Stack Method

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- All parameter values are pushed onto the stack before calling the procedure
- Example:

```
push    number1
push    number2
call    sum
```

TOS  
SP →

