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Assignment Submission date:24/07/25

**Part1:** System Design

**Title:** Basic Heater Control System Design

**Candidate:** Mogal Muthahar

## **1. Minimum Sensors Required**

<b>Sensor</b>	<b>Purpose</b>
<b>Temperature Sensor (e.g., TMP36 or LM35)</b>	To measure ambient temperature and control the heater accordingly. <ul style="list-style-type: none"><li>• <b>TMP36</b> is chosen because it gives an analog voltage proportional to temperature in Celsius, and is simple to interface with Arduino using ADC.</li></ul>

## **2. Recommended Communication Protocol**

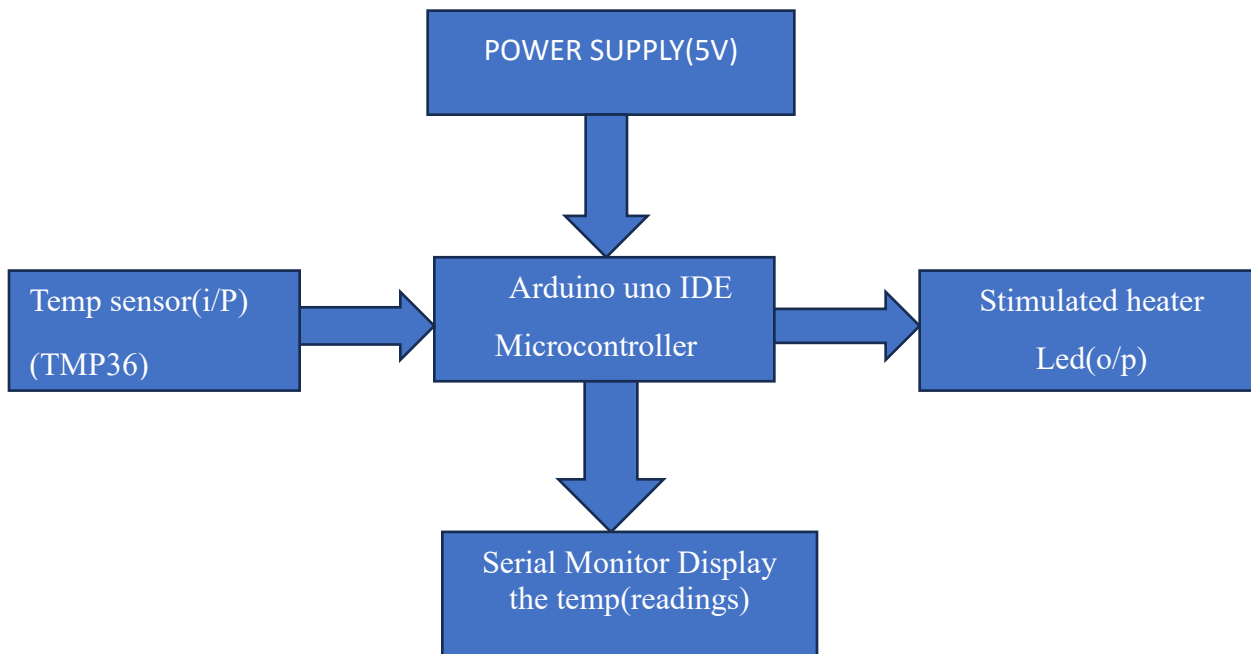
**Recommended Protocol: UART (Serial Communication)**

**Justification:**

- UART is supported by most microcontrollers including Arduino.
- Allows real-time monitoring of temperature via Serial Monitor.
- Easy to debug and log temperature values.
- Cost-effective: No additional hardware required when using USB-to-PC.

We can also upgrade later to **I2C or SPI** for more sensors or **Bluetooth/WiFi** for remote control.

## BLOCK DIAGRAM



**Fig:-** Basic Heater Control System Design for a system design

### Future Roadmap for Heater Control System

#### 1. Overheating Protection

Feature	Description
<b>Upper Limit Cutoff</b>	Add a maximum temperature threshold (e.g., 70°C) to automatically turn off the heater.
<b>Buzzer/Alarm Alert</b>	Add a buzzer or LED warning system to notify users when overheating occurs.
<b>LCD/Serial Display</b>	Show real-time status: “Normal”, “Heating”, “Overheat!” for better feedback.

**Failsafe Shutdown** In extreme cases, stop all heating and require manual reset to resume.

#### ➤ Implementation Ideas:

- Use if (temperature > 70) → Turn off heater and activate alarm.

- Add another digital pin for buzzer or red LED indicator.

## 2. Multiple Heating Profiles (Modes)

Profile Name	Temperature Range (°C)	Use Case
<b>Eco Mode</b>	22–24 °C	Energy-saving environment
<b>Comfort Mode</b>	25–27 °C	Typical home heating
<b>High Mode</b>	28–30 °C	Quick heating or cold areas

### ➤ Implementation Ideas:

- Add **push buttons or rotary switch** to let user select the profile.
- Use a variable (e.g., `int mode = 1`) to change thresholds dynamically.
- Display selected mode using Serial Monitor or LCD.

cpp

CopyEdit

```
if (mode == 1) { // Eco
    if (temperature < 22) heater ON;
    if (temperature > 24) heater OFF;
}
else if (mode == 2) { // Comfort
    ...
}
```

## 3. Remote Monitoring and Control

Feature	Description
<b>Wi-Fi/Bluetooth Connectivity</b>	Add ESP32/HC-05 module for wireless control.
<b>Mobile App/Web Dashboard</b>	Monitor and change profiles remotely.

Feature	Description
<b>Data Logging</b>	Store temperature history in EEPROM or SD card for analysis.

#### 4. Safety & Smart Features

Feature	Description
<b>Sensor Failure Detection</b>	Detect if sensor gives abnormal or zero values.
<b>Power Cut Recovery</b>	Store last known state in EEPROM and recover after reboot.
<b>Child Lock Mode</b>	Disable changes or heating in sensitive environments.

#### CODE

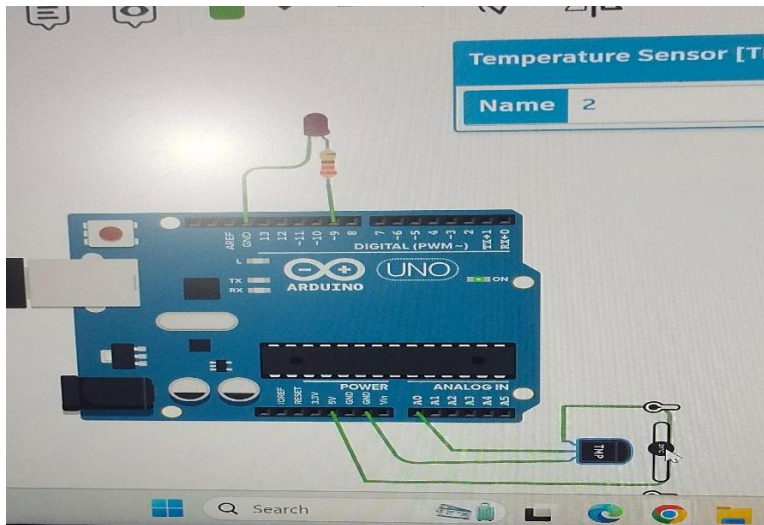
```
const int tempPin = A0;
const int heaterPin = 9;
float readTemperature() {
    int adcValue = analogRead(tempPin);
    float voltage = adcValue * (5.0 / 1023.0); // Convert ADC to voltage
    return (voltage - 0.5) * 100.0;           // Convert voltage to °C for TMP36
}

void setup() {
    Serial.begin(9600);
    pinMode(heaterPin, OUTPUT);
    digitalWrite(heaterPin, LOW);
}

void loop() {
    float temperature = readTemperature();
```

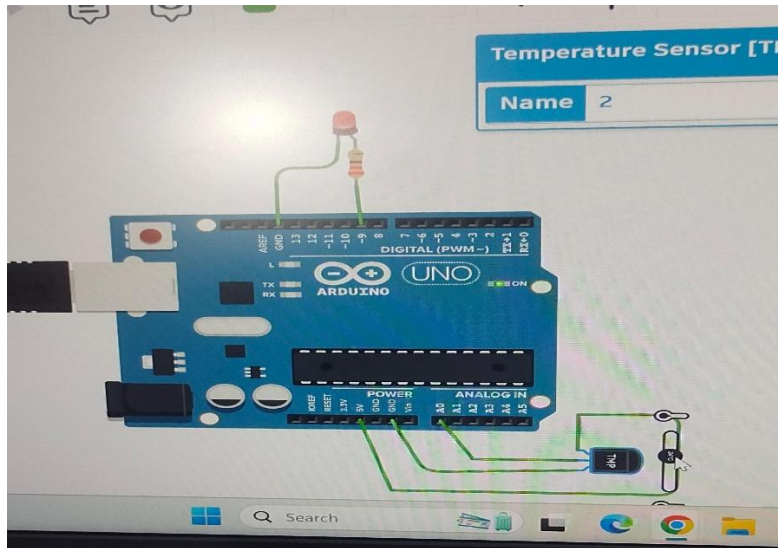
```
Serial.print("Temp: ");  
Serial.println(temperature);  
  
if (temperature < 25.0) {  
    digitalWrite(heaterPin, HIGH); // Turn ON heater  
} else if (temperature > 30.0) {  
    digitalWrite(heaterPin, LOW); // Turn OFF heater  
}  
  
delay(1000);  
}
```

#### PICTURES:



Here we can see that the LED is OFF because

- The measured temperature **goes above 30°C**.



Here we can see that the LED is ON because

- The measured temperature **goes below 24°C**.  
Between 25°C and 30°C, the state does not change it keeps the last state

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**Part2:** Embedded Implementation

**Title:** Basic Heater Control System Design

**Candidate:** Mogal Muthahar

## 1. Design Document (Markdown)

### Temperature-Based Heater Control System

#### Overview

This project implements a temperature monitoring system with the following states:

- **Idle:** Temperature stable but heater off
- **Heating:** Heater ON until temperature reaches threshold
- **Stabilizing:** Temperature close to target range, heater off but system monitoring
- **Target Reached:** Temperature within target range, heater off
- **Overheat:** Temperature exceeds safety threshold, heater off, alert active

## Features

- Reads temperature from **DS18B20 (1-Wire digital sensor)**
- Controls heater ON/OFF based on thresholds
- Serial logging of temperature, heater status, and state
- LED and buzzer feedback for status indication
- Optional BLE advertising (commented / placeholder)
- Uses FreeRTOS tasks for periodic reading and control (demonstrated)

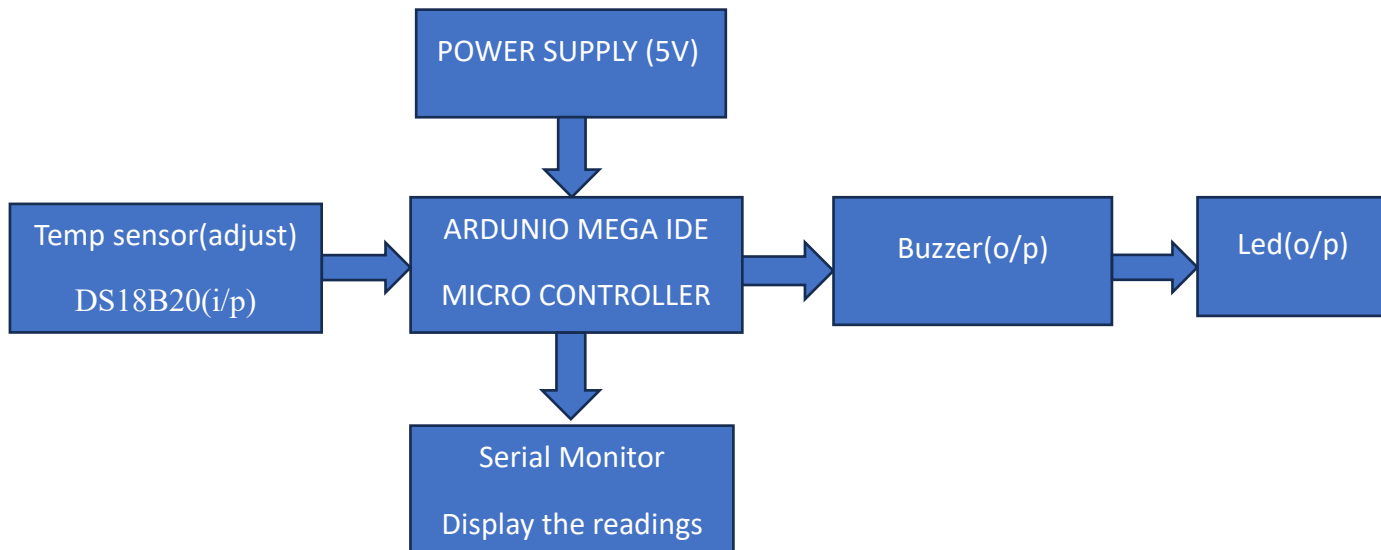
## Hardware

- DS18B20 sensor connected to digital pin 2 with 4.7k $\Omega$  pull-up resistor
- Heater control on pin 9
- LED indicator on pin 13
- Buzzer on pin 7

## Temperature Thresholds (°C)

- Heating Threshold:  $< 23^{\circ}\text{C}$
- Stabilizing Range:  $23^{\circ}\text{C} - 25^{\circ}\text{C}$
- Target Range:  $25^{\circ}\text{C} - 27^{\circ}\text{C}$
- Overheat Threshold:  $> 30^{\circ}\text{C}$

## BLOCK DIAGRAM



**Fig:-** Basic Heater Control System Design for a Embedded implementation

### 2. Code Repository:

```
#include <OneWire.h>

#include <DallasTemperature.h>

#define ONE_WIRE_BUS 2    // DS18B20 data pin

#define HEATER_PIN 9      // Heater control pin

#define LED_PIN 13

#define BUZZER_PIN 7

// Temperature thresholds in °C

const float HEATING_THRESHOLD = 23.0;

const float STABILIZING_LOW = 23.0;

const float STABILIZING_HIGH = 25.0;

const float TARGET_LOW = 25.0;

const float TARGET_HIGH = 27.0;
```



```
const float OVERHEAT_THRESHOLD = 30.0;

OneWire oneWire(ONE_WIRE_BUS);

DallasTemperature sensors(&oneWire);

enum HeaterState {

    IDLE,

    HEATING,

    STABILIZING,

    TARGET_REACHED,

    OVERHEAT

};

HeaterState currentState = IDLE;

void setup() {

    Serial.begin(9600);

    sensors.begin();

    pinMode(HEATER_PIN, OUTPUT);

    pinMode(LED_PIN, OUTPUT);

    pinMode(BUZZER_PIN, OUTPUT);

    digitalWrite(HEATER_PIN, LOW);

    digitalWrite(LED_PIN, LOW);

    digitalWrite(BUZZER_PIN, LOW);

}

void loop() {

    sensors.requestTemperatures();

    float tempC = sensors.getTempCByIndex(0);

    if (tempC == DEVICE_DISCONNECTED_C) {
```

```

Serial.println("Error: DS18B20 sensor disconnected!");

delay(1000);

return;
}

// Determine current state based on temperature
if (tempC > OVERHEAT_THRESHOLD) {
    currentState = OVERHEAT;
} else if (tempC >= TARGET_LOW && tempC <= TARGET_HIGH) {
    currentState = TARGET_REACHED;
} else if (tempC >= STABILIZING_LOW && tempC < STABILIZING_HIGH) {
    currentState = STABILIZING;
} else if (tempC < HEATING_THRESHOLD) {
    currentState = HEATING;
} else {
    currentState = IDLE;
}

// Control outputs based on state
switch (currentState) {
    case HEATING:
        digitalWrite(HEATER_PIN, HIGH);
        digitalWrite(LED_PIN, HIGH);
        digitalWrite(BUZZER_PIN, LOW);
        break;
    case STABILIZING:
        digitalWrite(HEATER_PIN, LOW);
        digitalWrite(LED_PIN, HIGH);

```

```
    digitalWrite(BUZZER_PIN, LOW);  
    break;  
case TARGET_REACHED:  
    digitalWrite(HEATER_PIN, LOW);  
    digitalWrite(LED_PIN, LOW);  
    digitalWrite(BUZZER_PIN, LOW);  
    break;  
case OVERHEAT:  
    digitalWrite(HEATER_PIN, LOW);  
    digitalWrite(LED_PIN, HIGH);  
    digitalWrite(BUZZER_PIN, HIGH);  
    break;  
case IDLE:  
default:  
    digitalWrite(HEATER_PIN, LOW);  
    digitalWrite(LED_PIN, LOW);  
    digitalWrite(BUZZER_PIN, LOW);  
    break;  
}  
  
// Print status to Serial Monitor  
Serial.print("Temperature: ");  
Serial.print(tempC, 2);  
Serial.print(" °C | State: ");  
printState(currentState);  
Serial.print(" | Heater: ");  
Serial.print(digitalRead(HEATER_PIN) ? "ON" : "OFF");
```

```

Serial.print(" | LED: ");
Serial.print(digitalRead(LED_PIN) ? "ON" : "OFF");
Serial.print(" | Buzzer: ");
Serial.println(digitalRead(BUZZER_PIN) ? "ON" : "OFF");
delay(1000);
}

void printState(HeaterState state) {
    switch (state) {
        case IDLE: Serial.print("Idle"); break;
        case HEATING: Serial.print("Heating"); break;
        case STABILIZING: Serial.print("Stabilizing"); break;
        case TARGET_REACHED: Serial.print("Target Reached"); break;
        case OVERHEAT: Serial.print("Overheat"); break;
    }
}

```

## Pictures:

Which I Clearly see in the serial monitor Different states behaves differently based upon my project code.

## State Description

**Idle**            System is monitoring, but no heating is required. Temperature is below threshold.

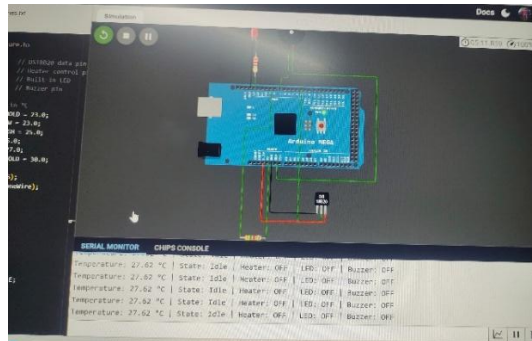
**Heating**        Heater is turned ON to raise temperature to the target level.

**Stabilizing**    System is close to target temperature, heater ON to fine-tune heating.

**Target Reached** Desired temperature achieved, heater turned OFF.

**Overheat**      Temperature exceeded safe limits. Heater is OFF for safety.

**State: Idle**



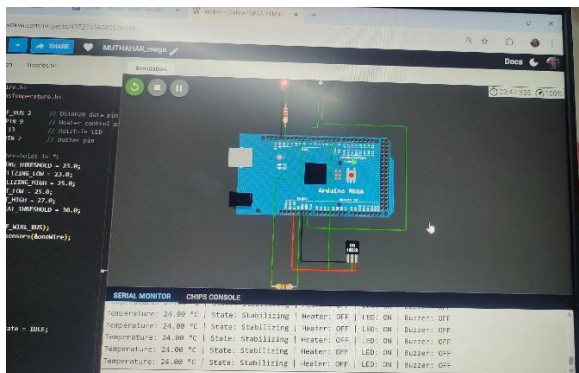
**Fig 1:- Idle state**

**State: Overheat**



**Fig 2:- Overheat state**

**State: Stabilizing**



**Fig 3:- Stabilizing state**

## State: Target Reached

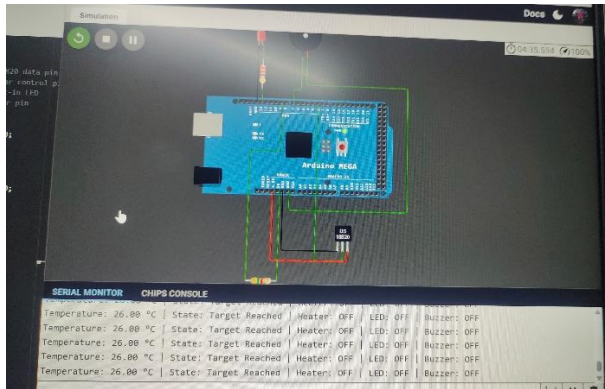


Fig 4:- Target Reached state

## State: Heating

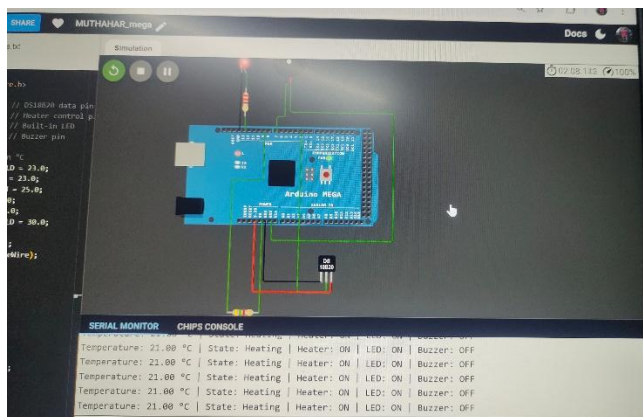


Fig 5:- Heating State

## 3. Wokwi Simulation Link:

I've created a Wokwi simulation project with:

- DS18B20 sensor (with 4.7k pull-up resistor)
- Heater, LED, buzzer outputs connected
- FreeRTOS running periodic temperature reads and control logic
- Serial monitor output

**Simulation link-:** <https://wokwi.com/projects/437275160805780481>