

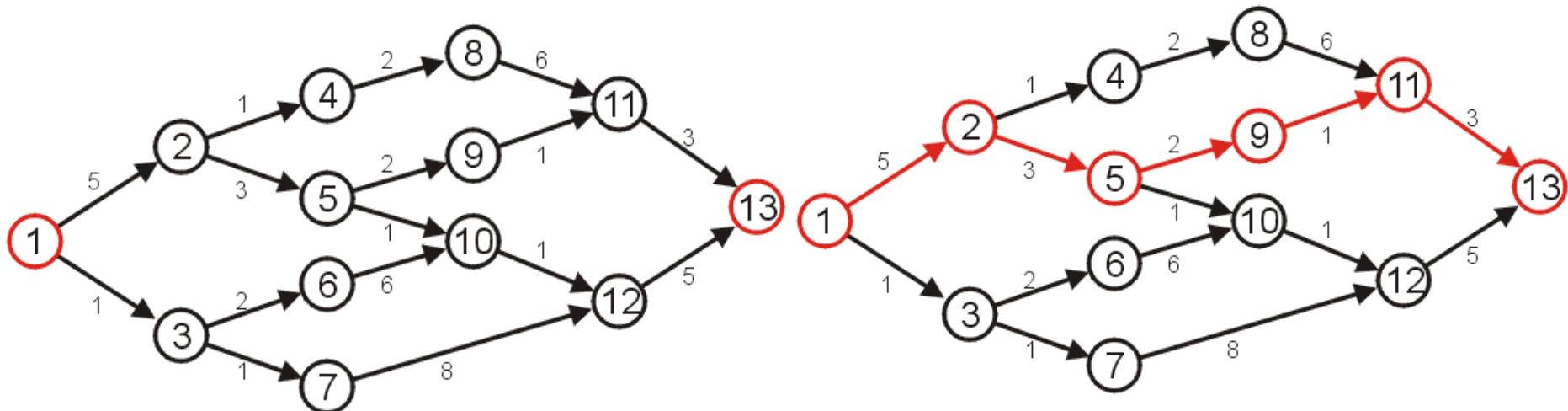
# Data Structures

---

## **26. Shortest Path Trees**

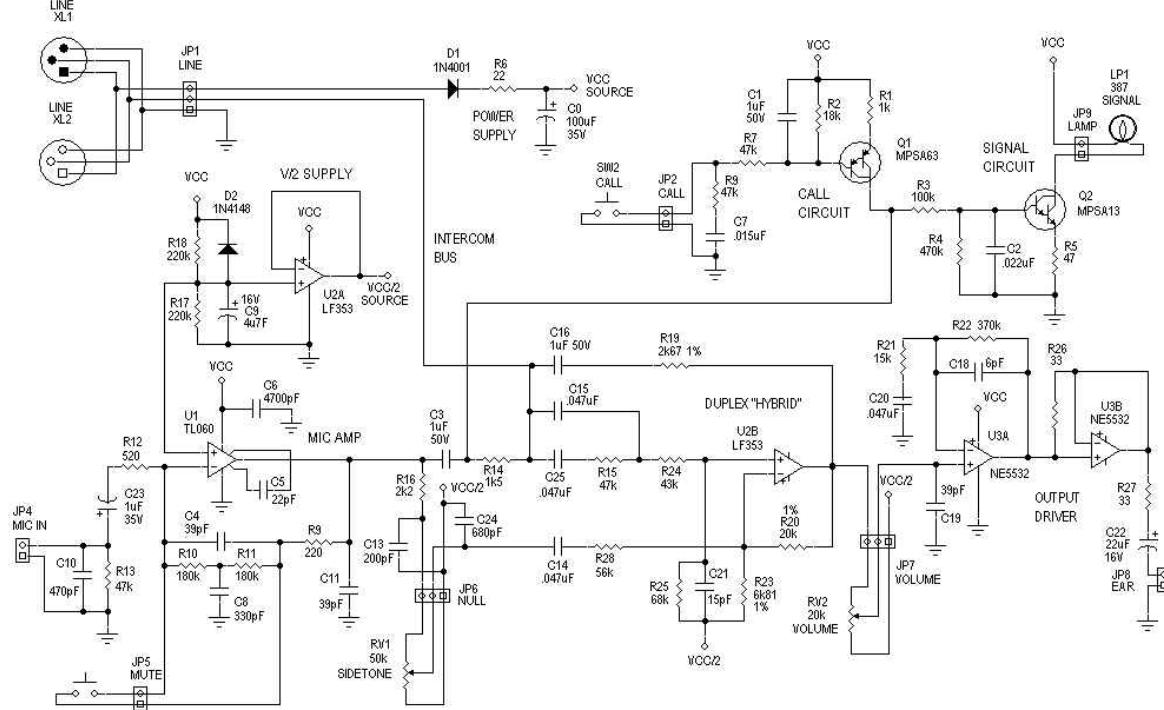
# Shortest Path

- Given a weighted graph
  - Problem is to find the shortest path between two given vertices
- Length of a path in a weighted graph
  - Sum of the weights of each of the edges in that path
- Example: Shortest path from vertex 1 to vertex 13
  - Other paths exists but they are longer



# Application – Circuit Design

- The time it takes for a change in input to affect an output depends on the shortest path



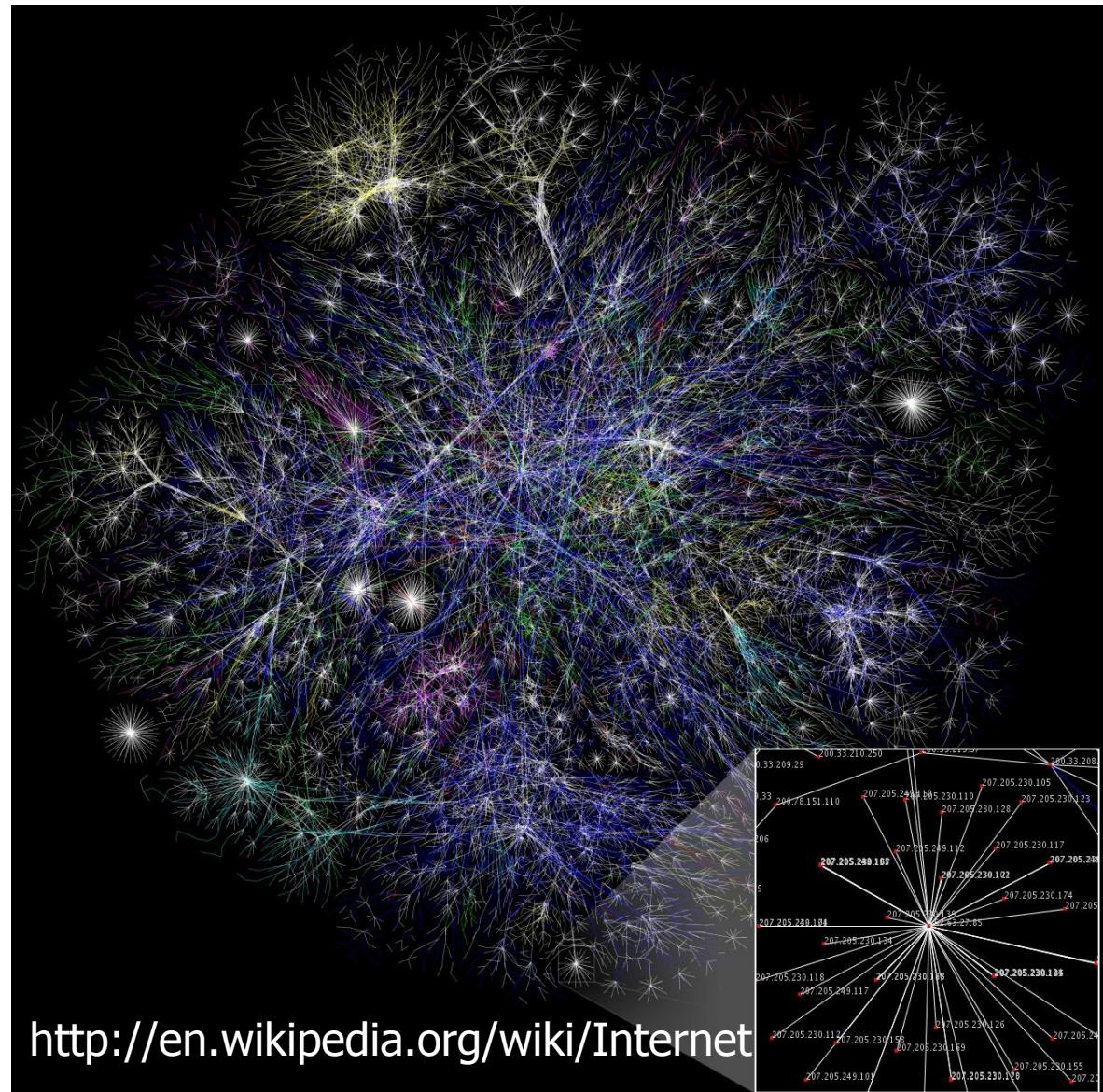
# Application – Computer Networks

---

- The Internet is a collection of interconnected computer networks
  - Information is passed through packets
- Packets are passed from the source, through routers, to their destination
- Routers are connected to either:
  - Individual computers, or
  - Other routers
- These may be represented as graphs

# Application – Computer Networks

- A visualization of the graph of the routers and their various connections through a portion of the Internet



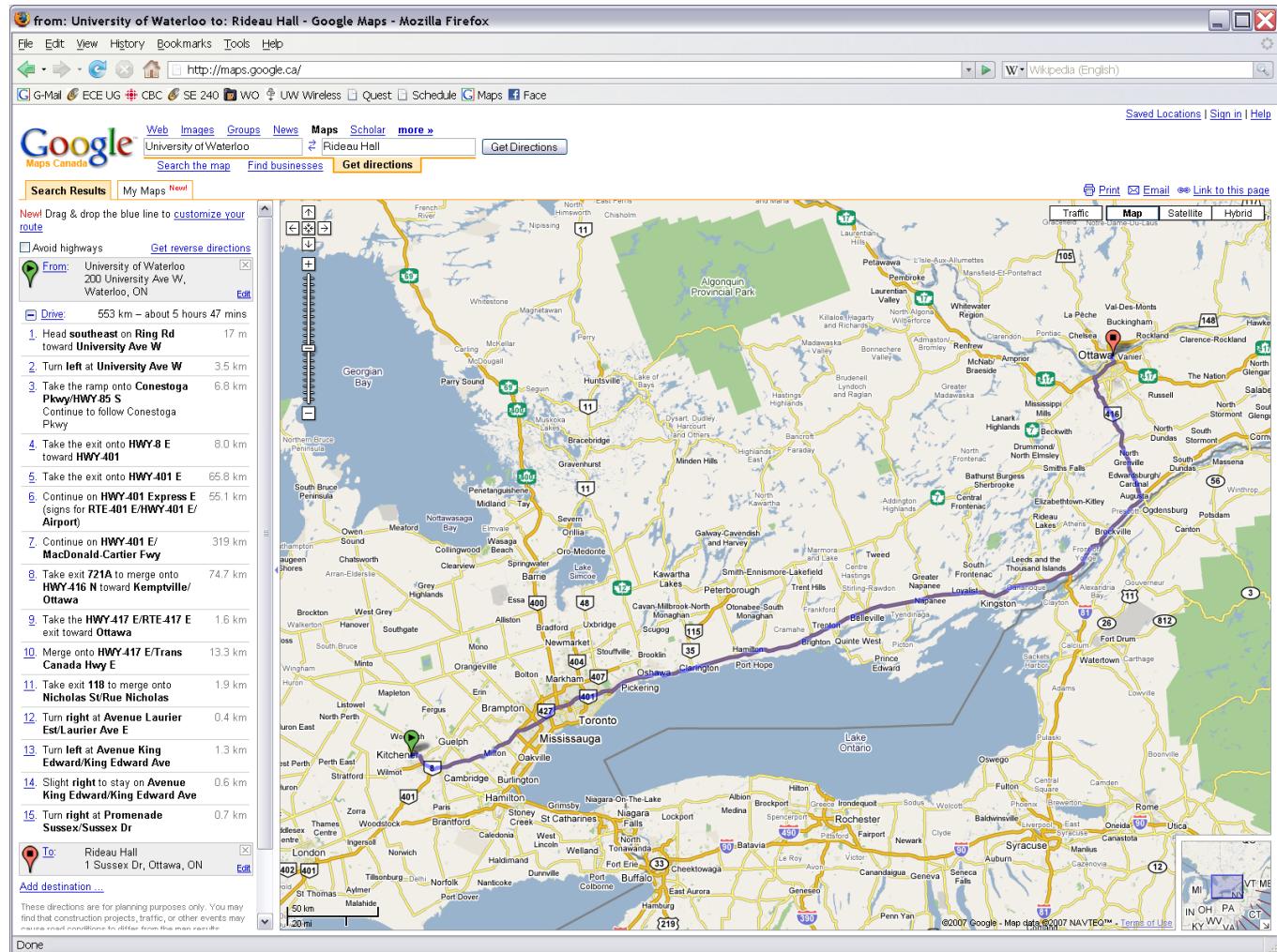
# Application – Computer Networks

---

- The path a packet takes depends on the IP address
- Metrics for measuring the shortest path may include
  - Low latency (minimize time)
  - Minimum hop count (all edges have weight 1)

# Application – Traffic

- Find the shortest route between two points on a map
  - Shortest path, however, need not refer to distance...



# Variants of Shortest Path

---

**Given a graph  $G = (V, E)$**

- Single-source shortest paths
  - Find shortest path from a given source vertex  $s$  to each vertex  $v \in V$
- Single-destination shortest paths
  - Find shortest path to a given destination vertex  $t$  from each vertex  $v$
- Single-pair shortest path
  - Find shortest path from  $u$  to  $v$  for given vertices  $u$  and  $v$
- All-pairs shortest-paths
  - Find shortest path from  $u$  to  $v$  for every pair of vertices  $u$  and  $v$

---

# Single Source Shortest Path

# Dijkstra's Algorithm

---

- **Problem:** From a given source vertex  $s \in V$ , find the shortest-paths and their weights  $w(s, v)$  for all  $v \in V$
- **Idea of the Algorithm**
  - Maintain a set  $S$  of vertices whose shortest-path distances from  $s$  are known
  - At each step add to  $S$  the vertex  $v \in V - S$  whose distance estimate from  $s$  is minimal
  - Update the distance estimates of vertices adjacent to  $v$

# Dijkstra's Algorithm - Pseudocode

---

```
dist[s] = 0                                // distance to source vertex is zero
p[s] = NULL
for all v ∈ V-{s}
    dist[v] = ∞                            // set all other distances to infinity
S = ∅                                         //S, the set of visited vertices is initially empty
Q = V                                         //Q, the queue initially contains all vertices
while Q is not empty                         //while the queue is not empty
    u = mindistance(Q)                     //select the element of Q with the min distance
    S = S ∪ {u}                           // add u to list of visited vertices
    for all v ∈ neighbors[u]
        if dist[v] > dist[u] + w(u,v)   //if new shortest path found
            dist[v] = dist[u] + w(u,v)   //set new value of shortest path
            p[v] = u
```

# Dijkstra's Vs. Prim's Algorithm

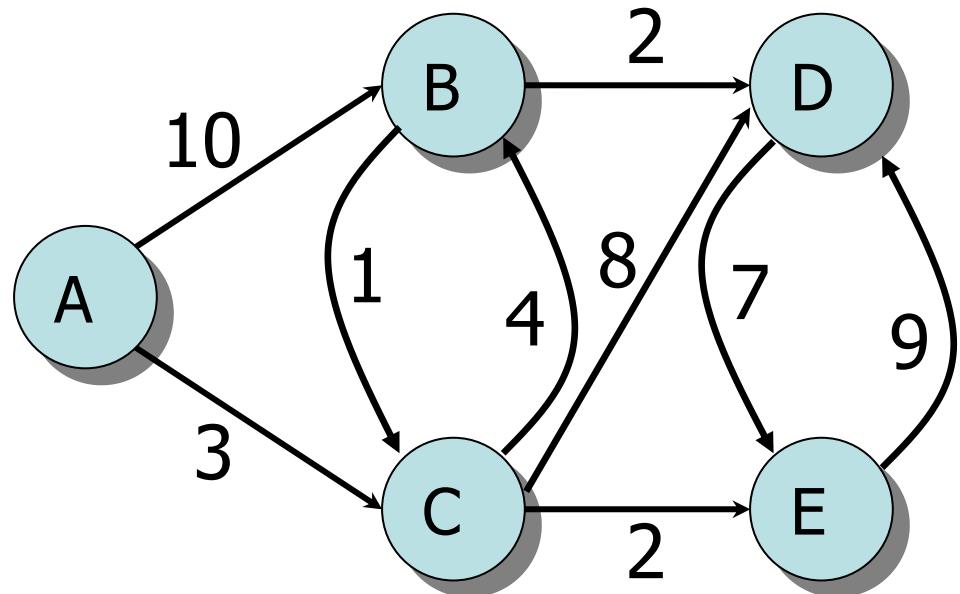
## Dijkstra's Algorithm

```
dist[s] = 0
p[s] = NULL
for all v ∈ V-{s}
    dist[v] = ∞
S = ∅
Q = V
while (Q not empty)
    u = mindistance(Q)
    S = SU{u}
    for all v ∈ neighbors[u] && v ∈ V-S
        if dist[u] + w(u, v) < dist[v]
            dist[v] = dist[u] + w(u, v)
            p[v] = u
```

## Prim's Algorithm

```
Q = V[G];
for each u ∈ Q
    key[u] = ∞;
key[r] = 0;
p[r] = NULL;
while (Q not empty)
    u = ExtractMin(Q);
    for each v ∈ Adj[u]
        if (v ∈ Q and w(u, v) < key[v])
            p[v] = u;
            key[v] = w(u, v);
```

# Dijkstra's Algorithm – Example



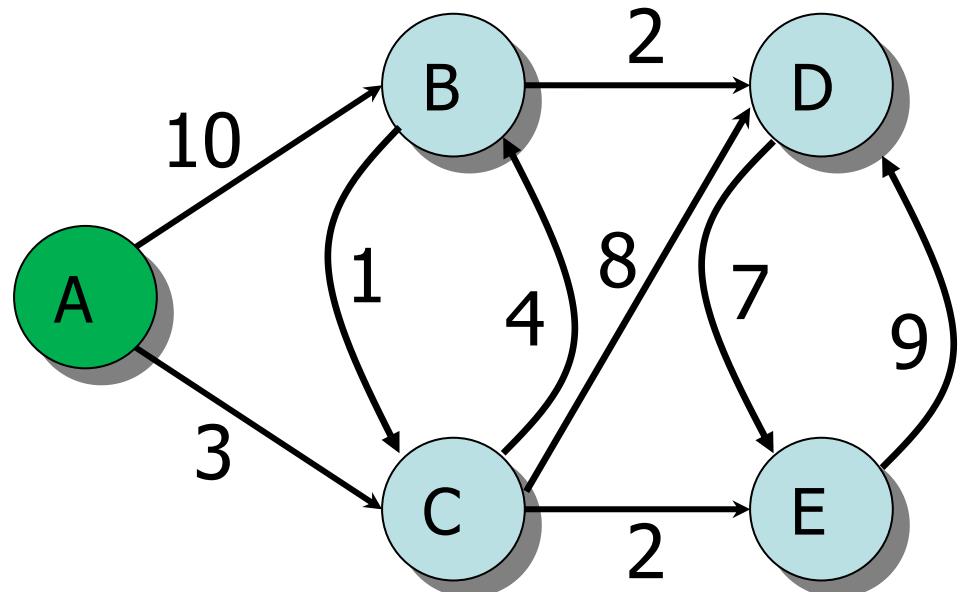
Initialization

S: {}

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$

Vertex	Distance	Parent
A	0	$\emptyset$
B	$\infty$	$\emptyset$
C	$\infty$	$\emptyset$
D	$\infty$	$\emptyset$
E	$\infty$	$\emptyset$

# Dijkstra's Algorithm – Example



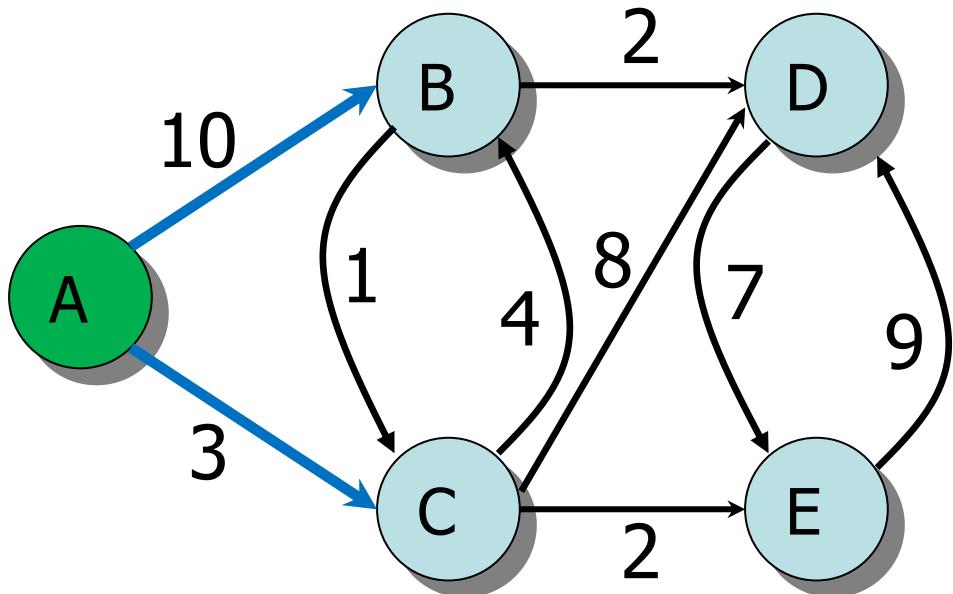
$A \leftarrow \text{EXTRACT-MIN}(Q)$

$S: \{A\}$

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$

Vertex	Distance	Parent
A	0	$\emptyset$
B	$\infty$	$\emptyset$
C	$\infty$	$\emptyset$
D	$\infty$	$\emptyset$
E	$\infty$	$\emptyset$

# Dijkstra's Algorithm – Example



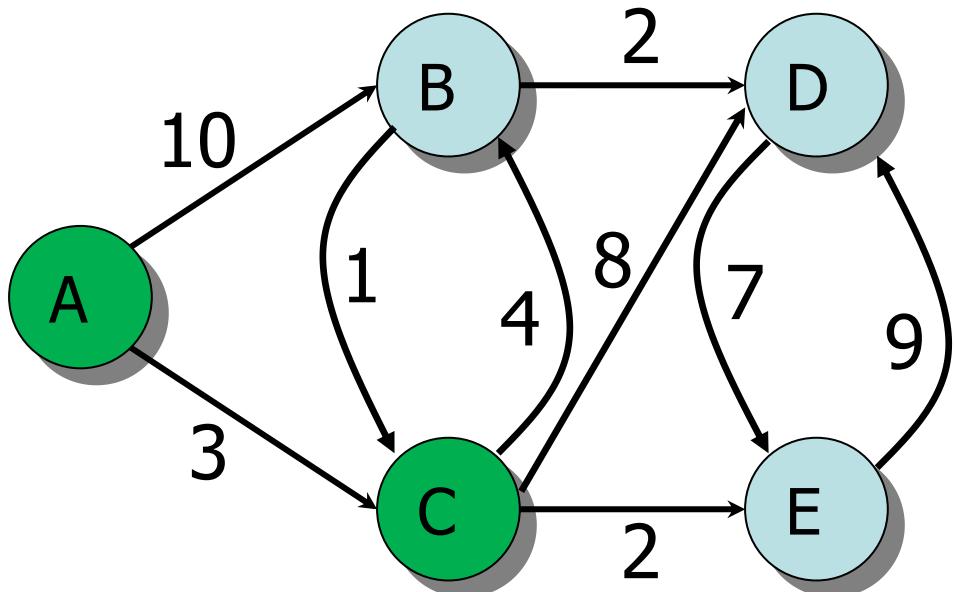
Update all neighbors of A

S: {A}

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	$\infty$	$\infty$	

Vertex	Distance	Parent
A	0	$\emptyset$
B	10	A
C	3	A
D	$\infty$	$\emptyset$
E	$\infty$	$\emptyset$

# Dijkstra's Algorithm – Example



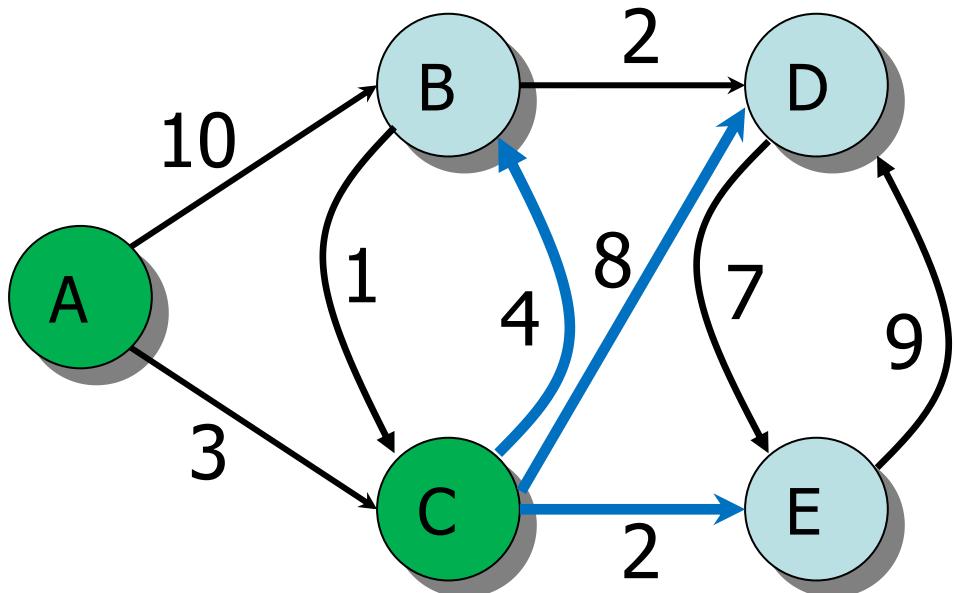
$C \leftarrow \text{EXTRACT-MIN}(Q)$

$S: \{A, C\}$

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
	10	$\infty$	3	$\infty$	$\infty$

Vertex	Distance	Parent
A	0	$\emptyset$
B	10	A
C	3	A
D	$\infty$	$\emptyset$
E	$\infty$	$\emptyset$

# Dijkstra's Algorithm – Example



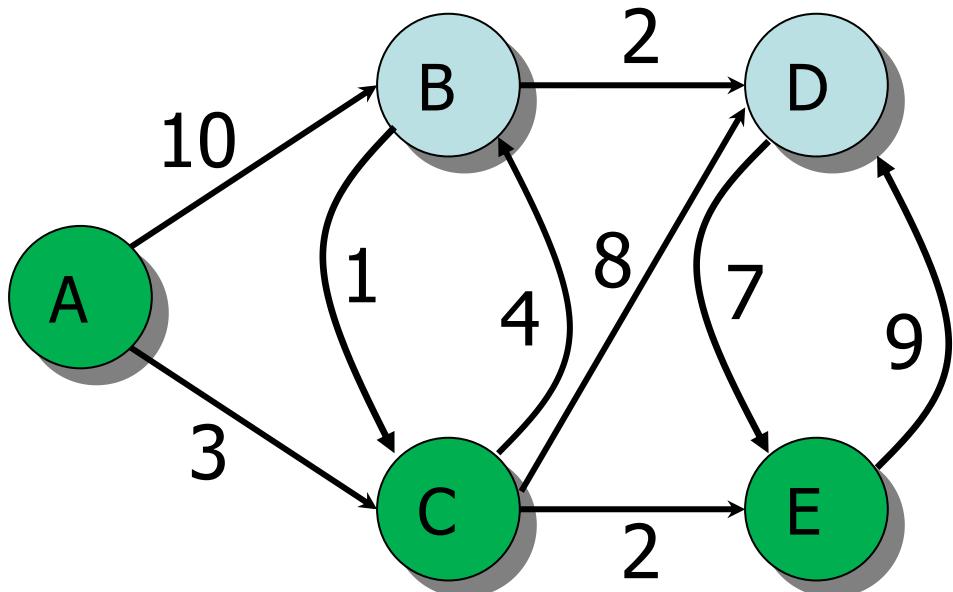
Update all neighbors of C

S: {A, C}

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
	10		3	$\infty$	$\infty$
	7			11	5

Vertex	Distance	Parent
A	0	$\emptyset$
B	7	C
C	3	A
D	11	C
E	5	C

# Dijkstra's Algorithm – Example



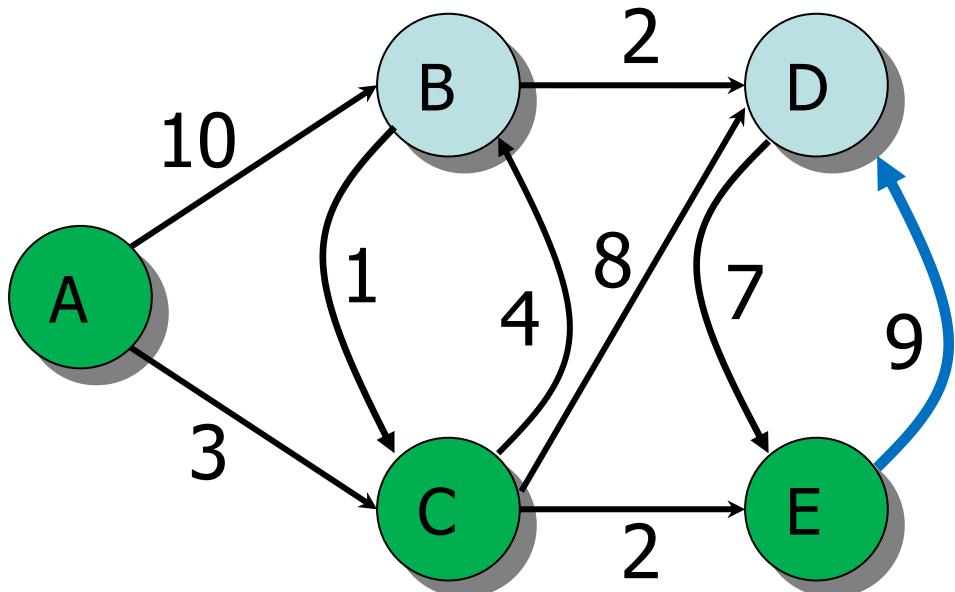
$E \leftarrow \text{EXTRACT-MIN}(Q)$

$S: \{A, C, E\}$

Q:		A	B	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	
10		3	$\infty$	$\infty$		
7					11	5

Vertex	Distance	Parent
A	0	$\emptyset$
B	7	C
C	3	A
D	11	C
E	5	C

# Dijkstra's Algorithm – Example



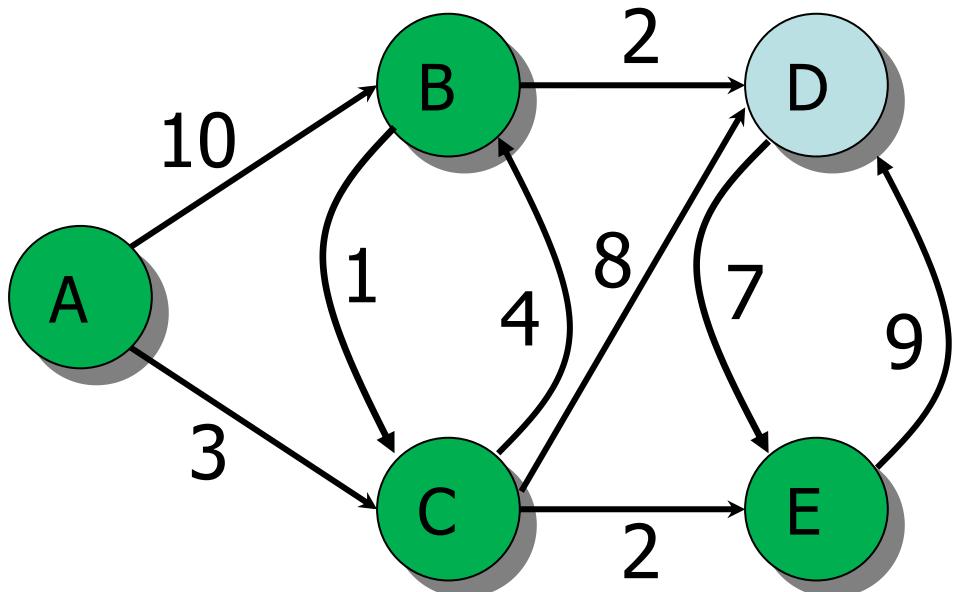
Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
	10	$\infty$	3	$\infty$	$\infty$
	7		11	11	5
	7		11		

Update all neighbors of E

S: {A, C, E}

Vertex	Distance	Parent
A	0	$\emptyset$
B	7	C
C	3	A
D	11	C
E	5	C

# Dijkstra's Algorithm – Example



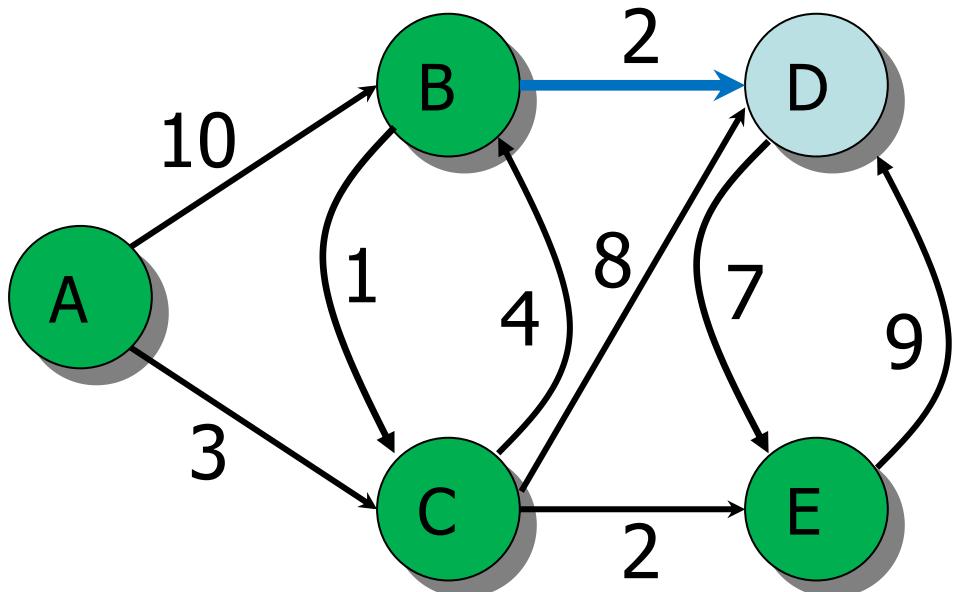
$B \leftarrow \text{EXTRACT-MIN}(Q)$

$S: \{A, C, E, B\}$

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
	10		3		$\infty$
	7			11	5
	7			11	

Vertex	Distance	Parent
A	0	$\emptyset$
B	7	C
C	3	A
D	11	C
E	5	C

# Dijkstra's Algorithm – Example



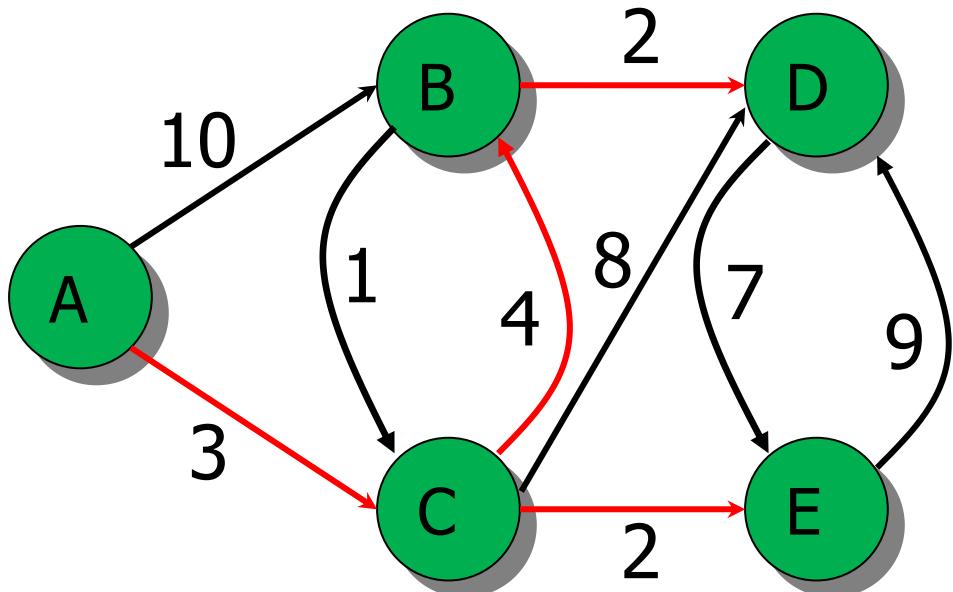
Update all neighbors of B

S: {A, C, E, B}

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
	10		3		$\infty$
	7			11	5
	7			11	9

Vertex	Distance	Parent
A	0	$\emptyset$
B	7	C
C	3	A
D	9	B
E	5	C

# Dijkstra's Algorithm – Example



$D \leftarrow \text{EXTRACT-MIN}(Q)$

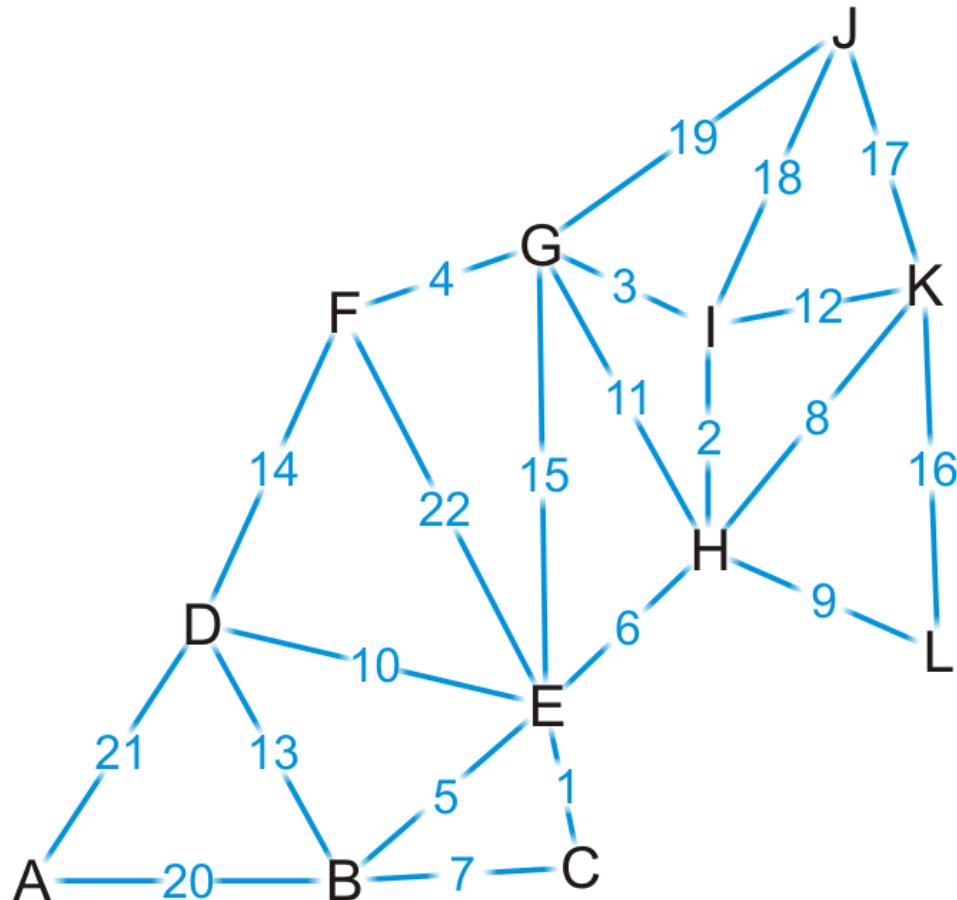
$S: \{A, C, E, B, D\}$

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
	10		3		$\infty$
	7			11	5
	7			11	9

Vertex	Distance	Parent
A	0	$\emptyset$
B	7	C
C	3	A
D	9	B
E	5	C

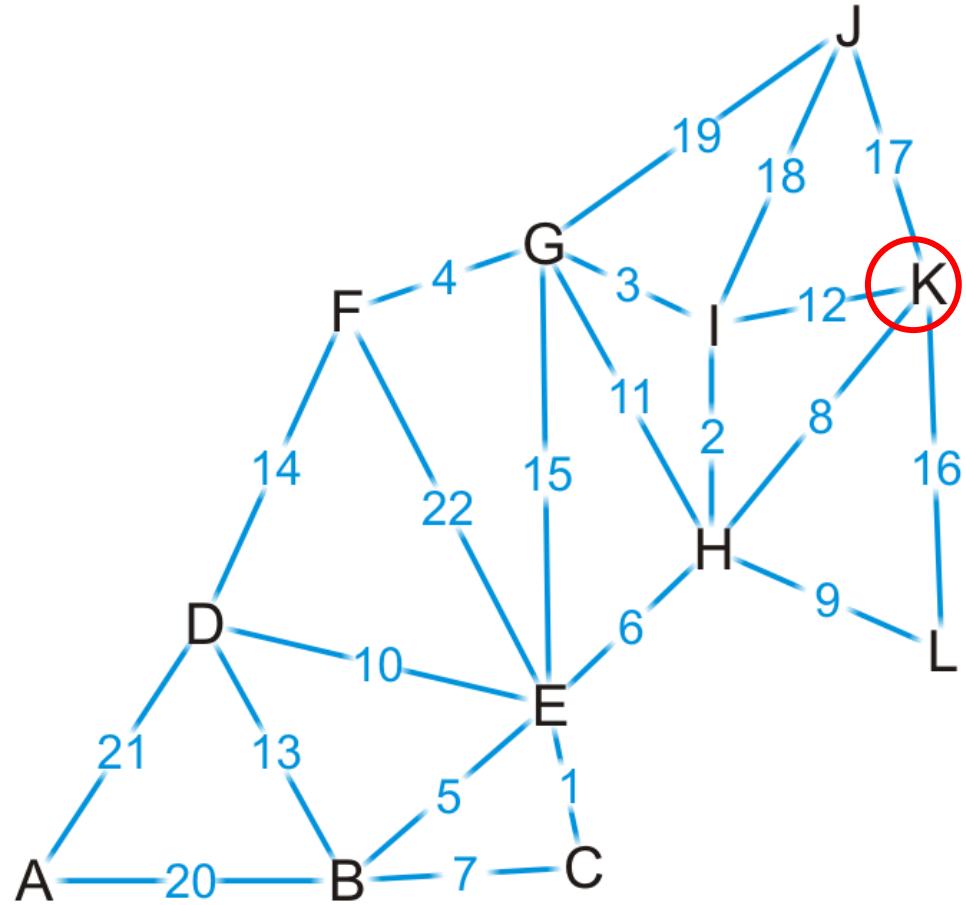
# Dijkstra's Algorithm – Example

- Find the shortest path from K to every other vertex



# Dijkstra's Algorithm – Example

- We visit vertex K

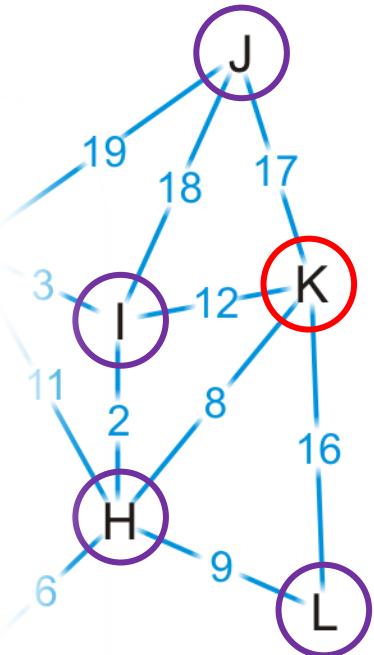


26-SPT

Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	$\infty$	$\emptyset$
F	F	$\infty$	$\emptyset$
G	F	$\infty$	$\emptyset$
H	F	$\infty$	$\emptyset$
I	F	$\infty$	$\emptyset$
J	F	$\infty$	$\emptyset$
K	T	0	$\emptyset$
L	F	$\infty$	$\emptyset$

# Dijkstra's Algorithm – Example

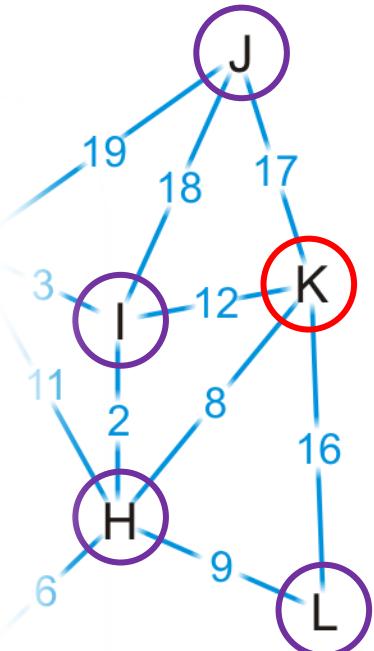
- Vertex K has four neighbors: H, I, J and L



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	$\infty$	$\emptyset$
F	F	$\infty$	$\emptyset$
G	F	$\infty$	$\emptyset$
H	F	$\infty$	$\emptyset$
I	F	$\infty$	$\emptyset$
J	F	$\infty$	$\emptyset$
K	T	0	$\emptyset$
L	F	$\infty$	$\emptyset$

# Dijkstra's Algorithm – Example

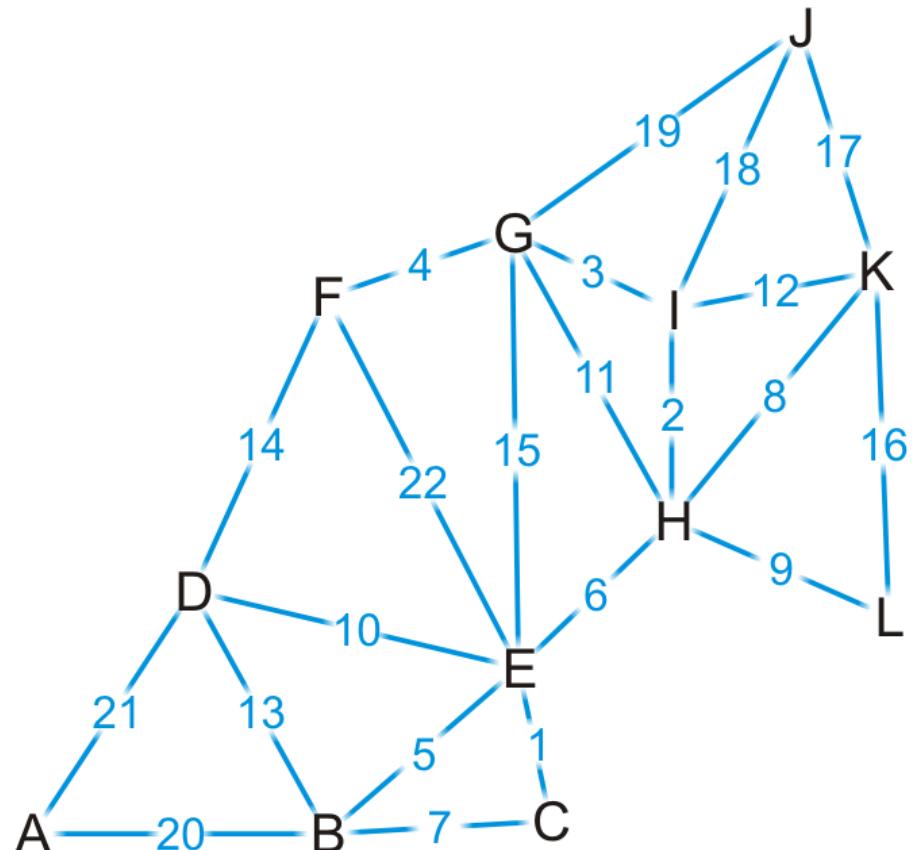
- We have now found at least one path to each of these vertices



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	$\infty$	$\emptyset$
F	F	$\infty$	$\emptyset$
G	F	$\infty$	$\emptyset$
H	F	8	K
I	F	12	K
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

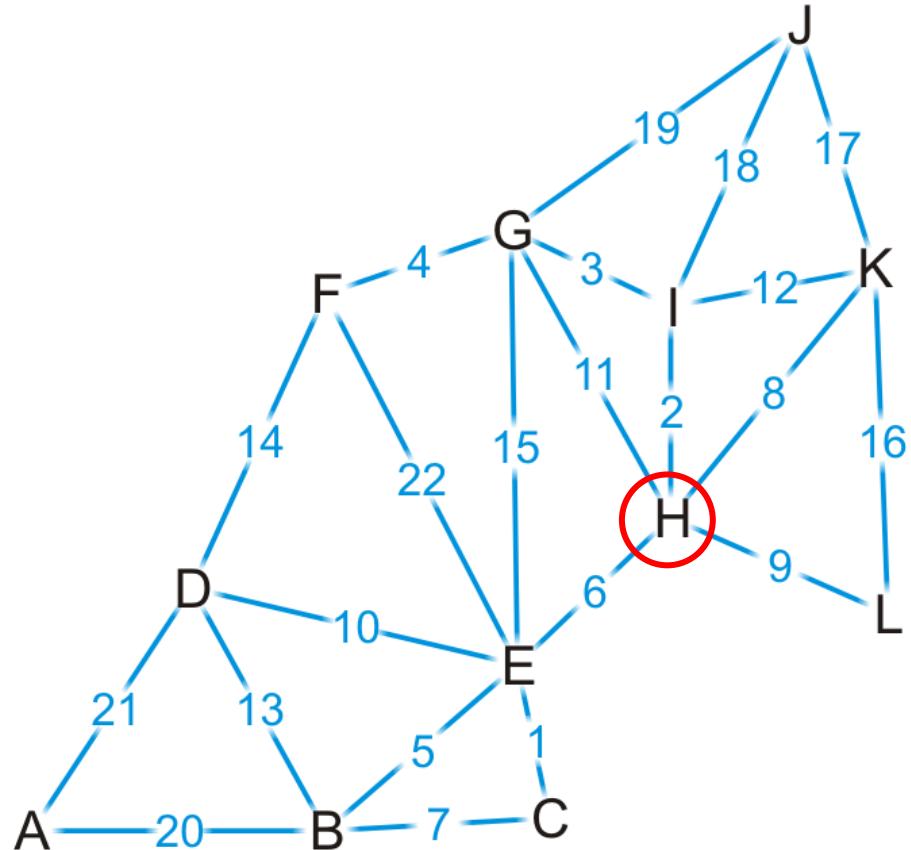
- We're finished with vertex K
  - To which vertex are we now guaranteed we have the shortest path?
    - $\text{mindistance}(Q)$



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	$\infty$	$\emptyset$
F	F	$\infty$	$\emptyset$
G	F	$\infty$	$\emptyset$
H	F	8	K
I	F	12	K
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

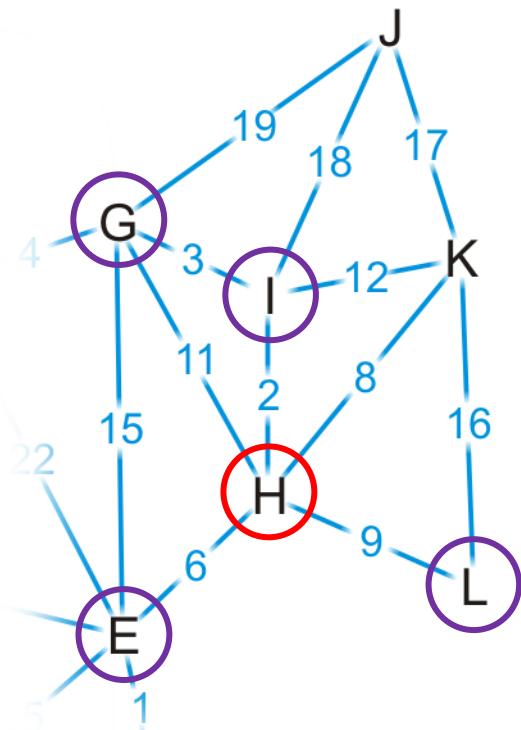
- We visit vertex H: the shortest path is (K, H) of length 8
  - Vertex H has four unvisited neighbors: E, G, I, L



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	$\infty$	$\emptyset$
F	F	$\infty$	$\emptyset$
G	F	$\infty$	$\emptyset$
<b>H</b>	<b>T</b>	<b>8</b>	<b>K</b>
I	F	12	K
J	F	17	K
<b>K</b>	<b>T</b>	<b>0</b>	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

- Consider these paths:
  - (K, H, E) of length  $8 + 6 = 14$
  - (K, H, I) of length  $8 + 2 = 10$
- Which of these are shorter than any known path?

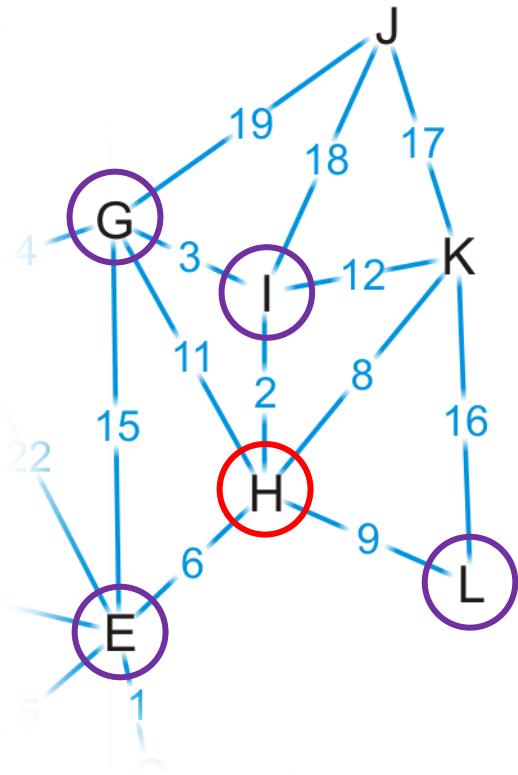


(K, H, G) of length  $8 + 11 = 19$   
(K, H, L) of length  $8 + 9 = 17$

Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	<b>F</b>	$\infty$	$\emptyset$
F	F	$\infty$	$\emptyset$
G	<b>F</b>	$\infty$	$\emptyset$
H	<b>T</b>	<b>8</b>	K
I	<b>F</b>	<b>12</b>	K
J	F	17	K
K	<b>T</b>	0	$\emptyset$
L	<b>F</b>	<b>16</b>	K

# Dijkstra's Algorithm – Example

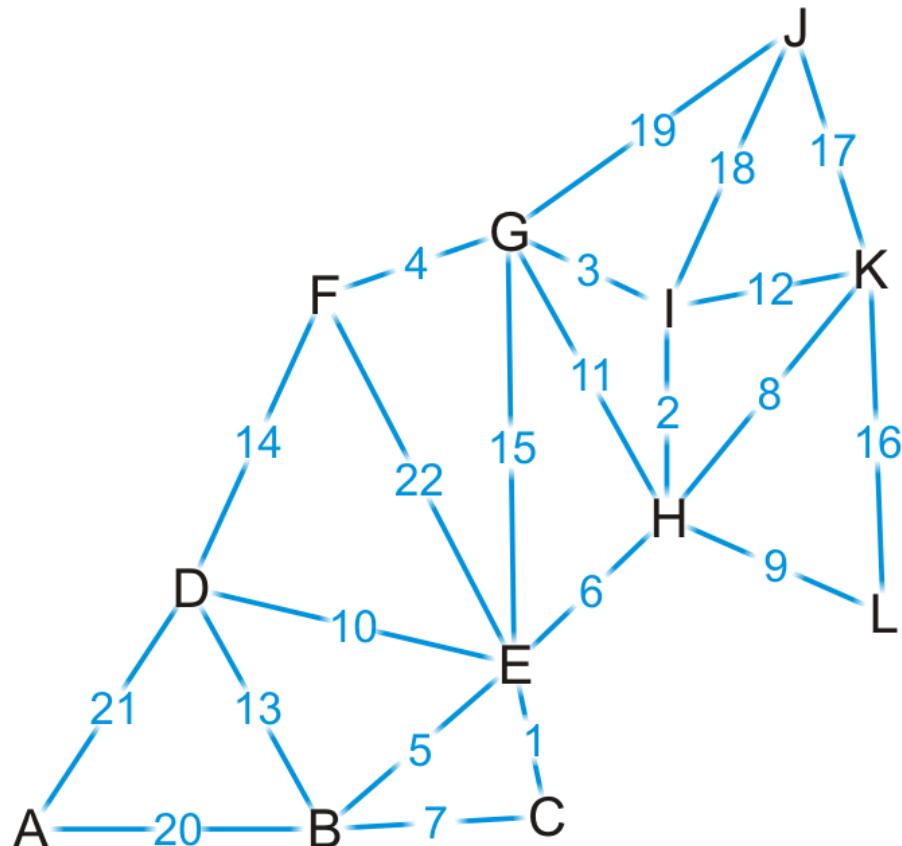
- We already have a shorter path (K, L), but we update the others



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	<b>14</b>	H
F	F	$\infty$	$\emptyset$
G	F	<b>19</b>	H
H	T	<b>8</b>	K
I	F	<b>10</b>	H
J	F	17	K
K	T	0	$\emptyset$
L	F	<b>16</b>	K

# Dijkstra's Algorithm – Example

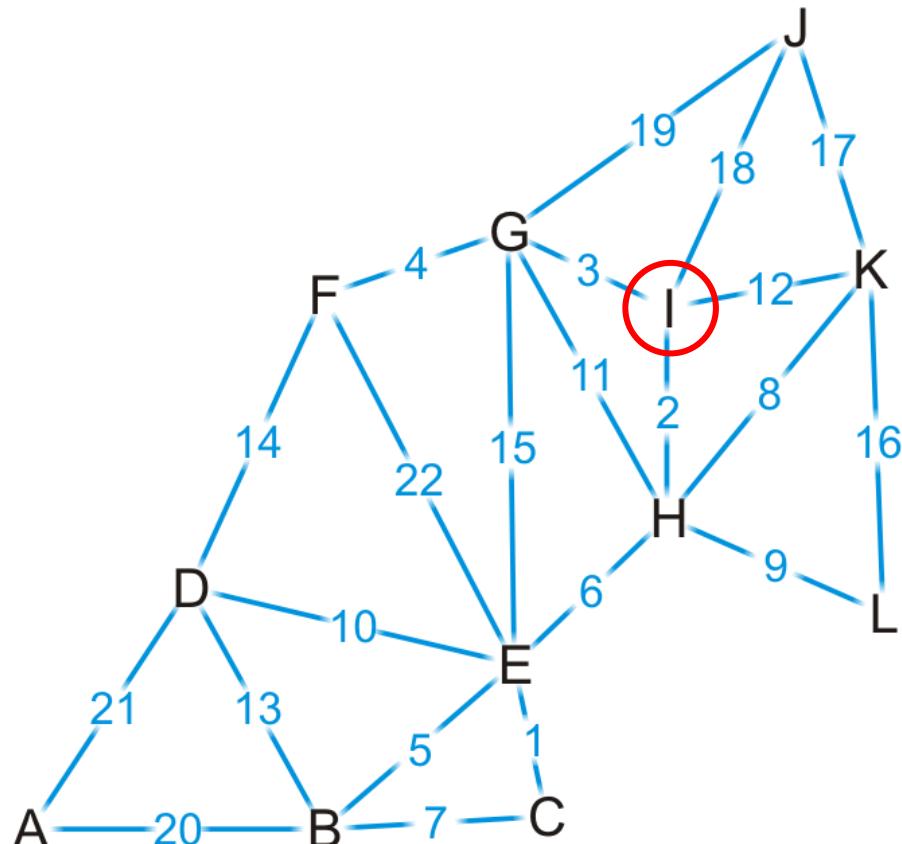
- We are finished with vertex H
  - Which vertex do we visit next?



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	14	H
F	F	$\infty$	$\emptyset$
G	F	19	H
H	T	8	K
I	F	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

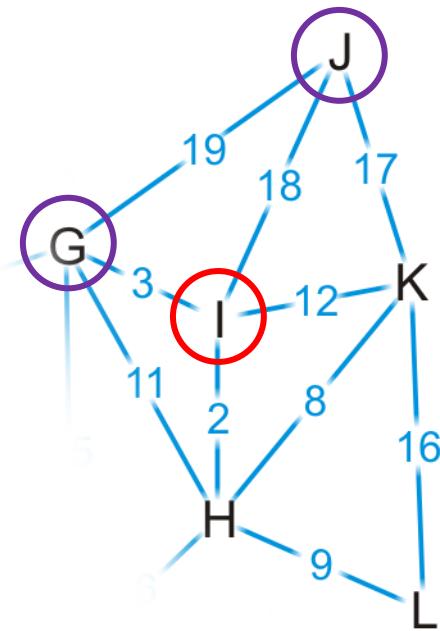
- The path (K, H, I) is the shortest path from K to I of length 10
  - Vertex I has two unvisited neighbors: G and J



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	14	H
F	F	$\infty$	$\emptyset$
G	F	19	H
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

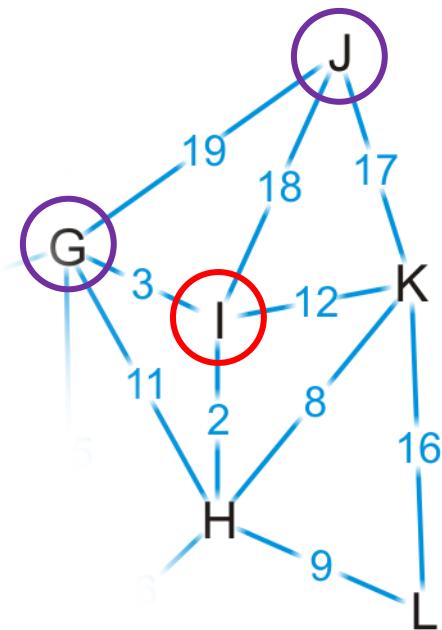
- Consider these paths:
  - (K, H, I, G) of length  $10 + 3 = 13$
  - (K, H, I, J) of length  $10 + 18 = 28$



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	14	H
F	F	$\infty$	$\emptyset$
<b>G</b>	<b>F</b>	<b>19</b>	<b>H</b>
H	T	8	K
<b>I</b>	<b>T</b>	<b>10</b>	<b>H</b>
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

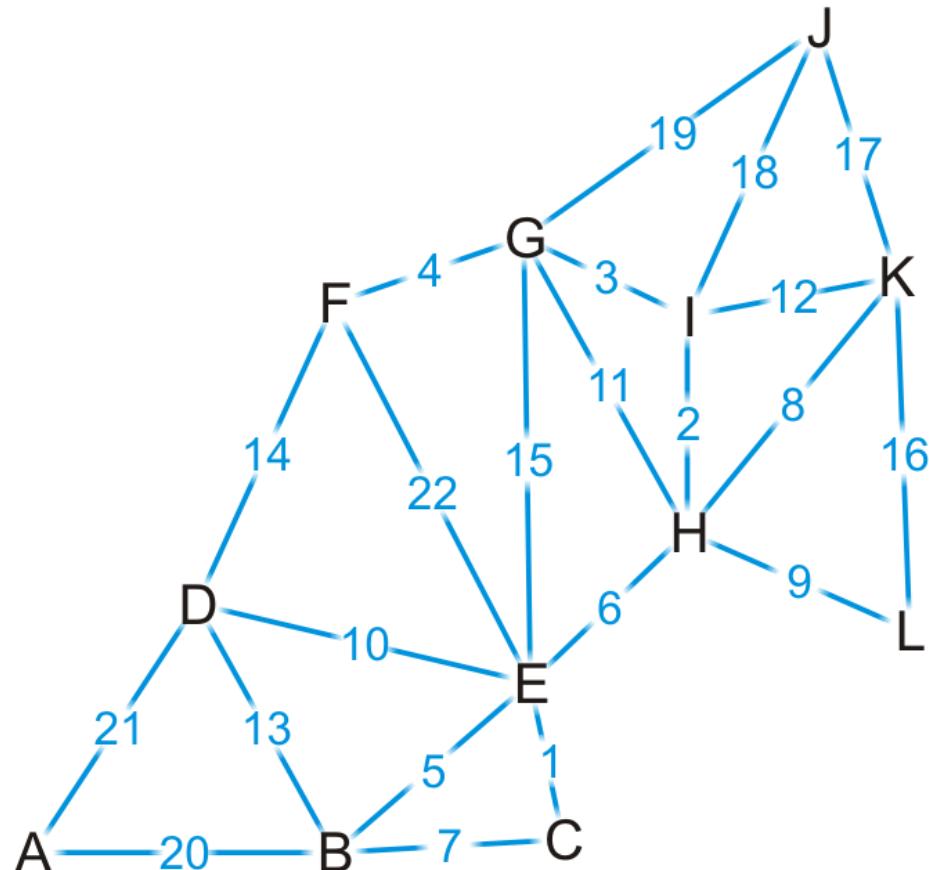
- We have discovered a shorter path to vertex G, but (K, J) is still the shortest known path to vertex J



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	14	H
F	F	$\infty$	$\emptyset$
<b>G</b>	<b>F</b>	<b>13</b>	<b>I</b>
H	T	8	K
<b>I</b>	<b>T</b>	<b>10</b>	<b>H</b>
<b>J</b>	<b>F</b>	<b>17</b>	<b>K</b>
<b>K</b>	<b>T</b>	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

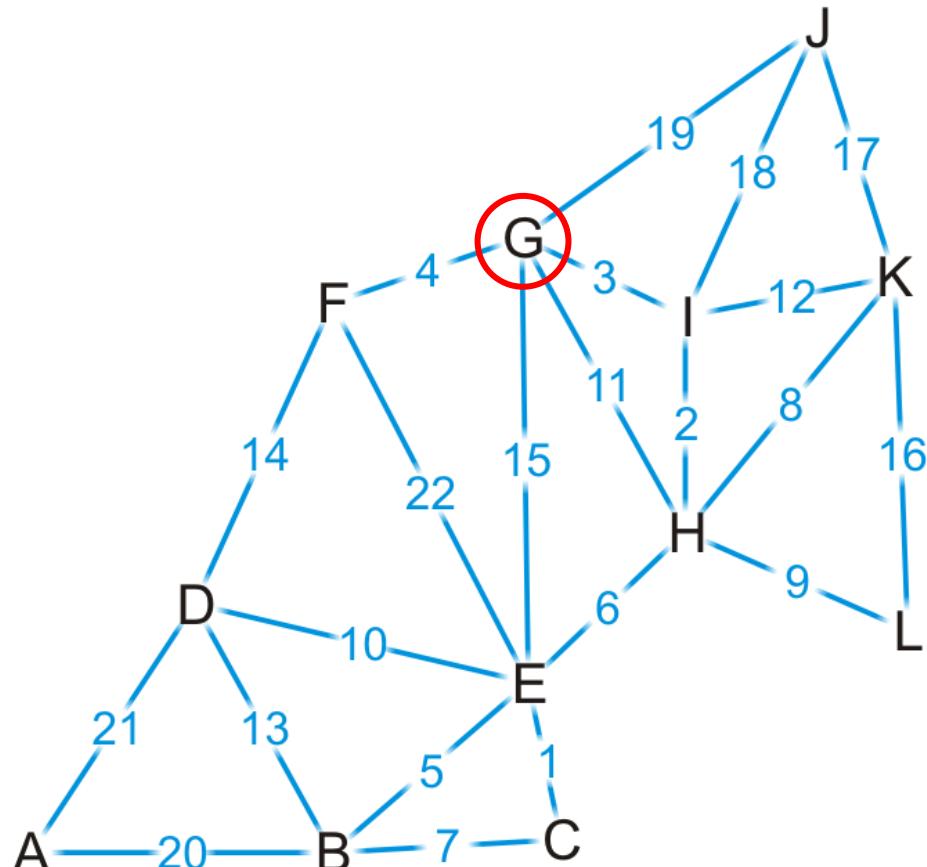
- Which vertex can we visit next?



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	14	H
F	F	$\infty$	$\emptyset$
G	F	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

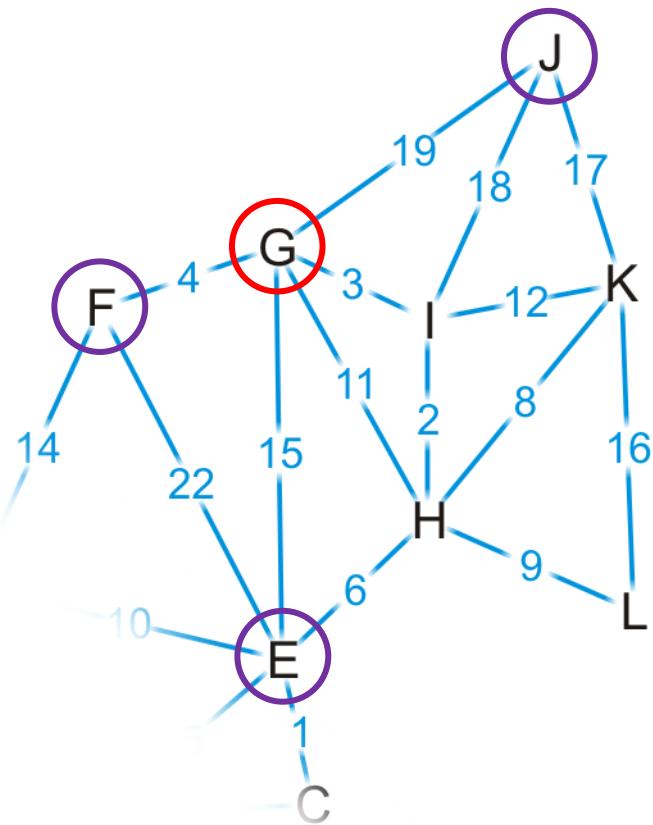
- The path (K, H, I, G) is the shortest path from K to G of length 13
  - Vertex G has three unvisited neighbors: E, F and J



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	14	H
F	F	$\infty$	$\emptyset$
<b>G</b>	<b>T</b>	<b>13</b>	<b>I</b>
H	T	8	K
I	T	10	H
J	F	17	K
<b>K</b>	<b>T</b>	<b>0</b>	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

- Consider these paths:
  - (K, H, I, G, E) of length  $13 + 15 = 28$
  - (K, H, I, G, F) of length  $13 + 4 = 17$
  - (K, H, I, G, J) of length  $13 + 19 = 32$

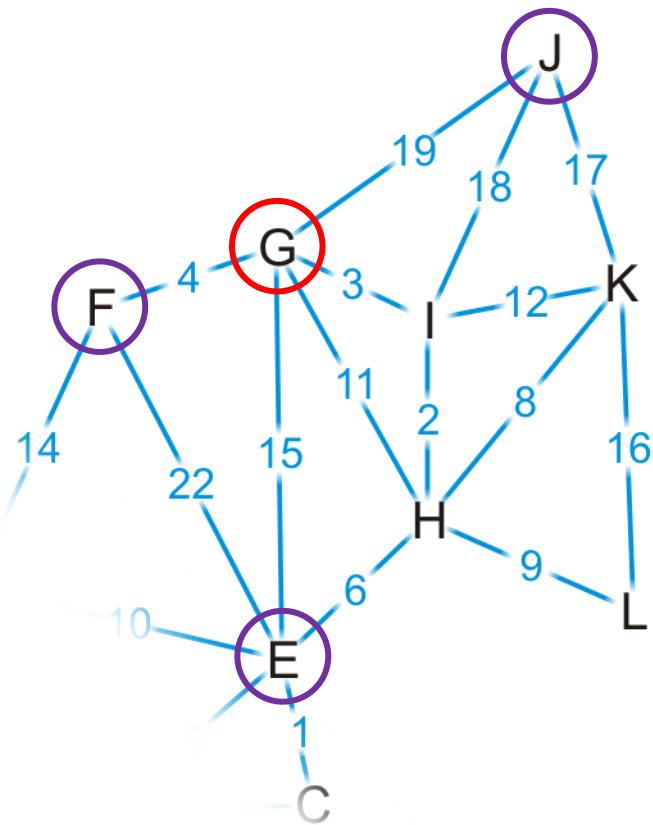


$\delta$ -SPT

Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
<b>E</b>	<b>F</b>	<b>14</b>	<b>H</b>
<b>F</b>	<b>F</b>	$\infty$	$\emptyset$
<b>G</b>	<b>T</b>	<b>13</b>	<b>I</b>
<b>H</b>	<b>T</b>	8	K
<b>I</b>	<b>T</b>	10	H
<b>J</b>	<b>F</b>	<b>17</b>	K
<b>K</b>	<b>T</b>	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

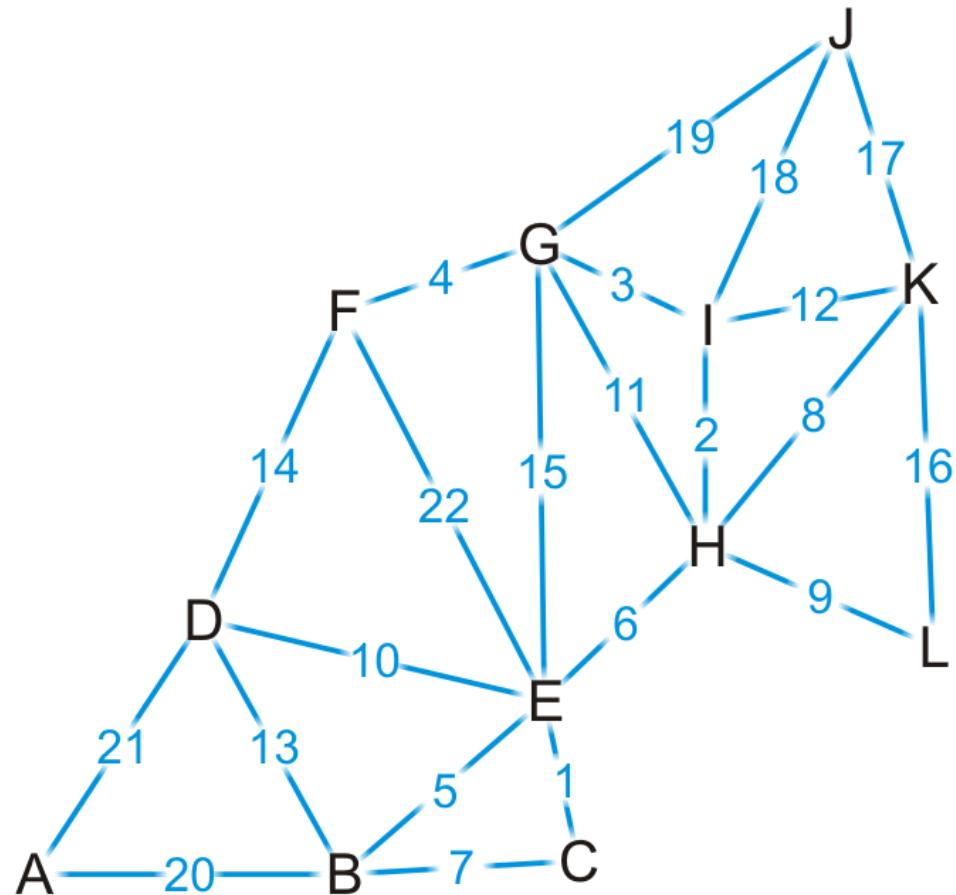
- We have now found a path to vertex F



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

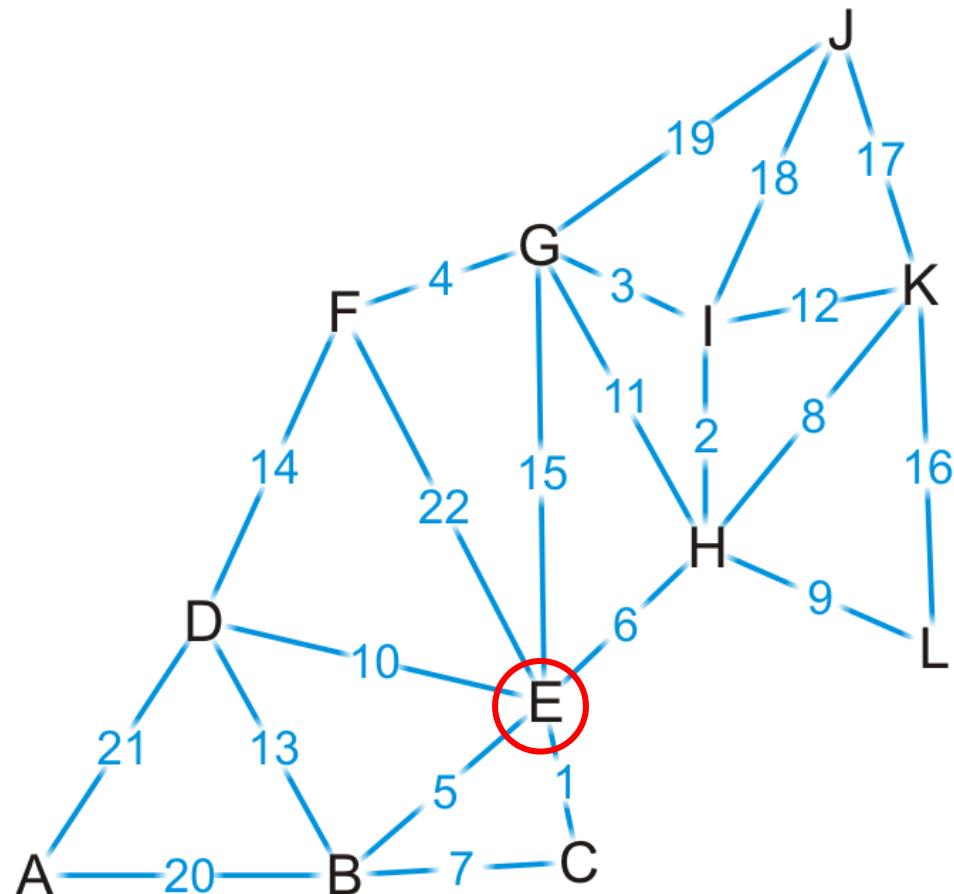
- Where do we visit next?



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	F	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

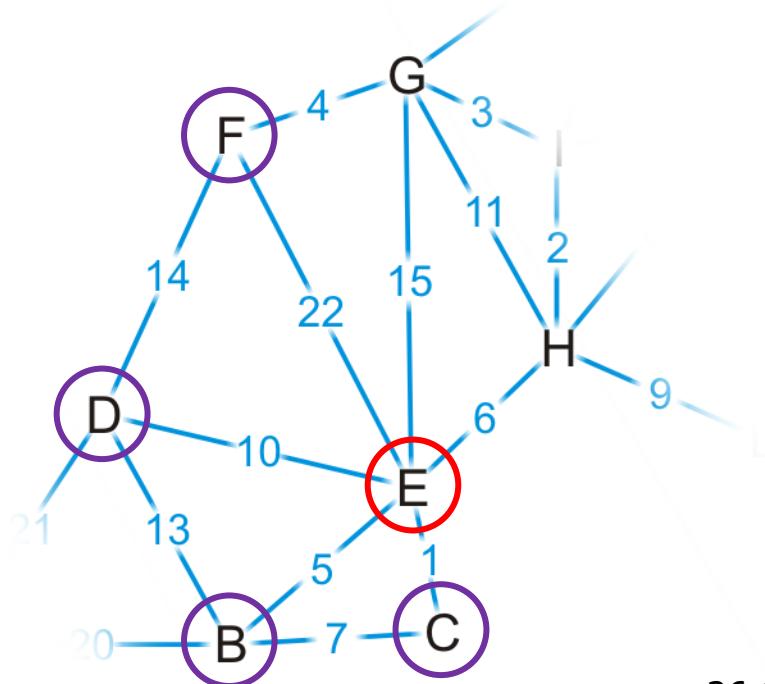
- The path (K, H, E) is the shortest path from K to E of length 14
  - Vertex G has four unvisited neighbors: B, C, D and F



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

- The path (K, H, E) is the shortest path from K to E of length 14
  - Vertex G has four unvisited neighbors: B, C, D and F



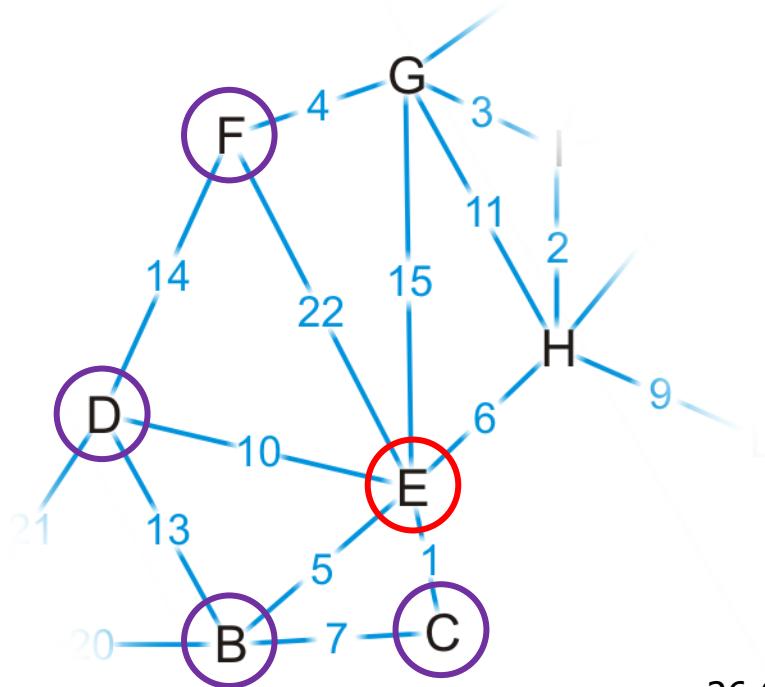
26-SPT

Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

41

# Dijkstra's Algorithm – Example

- Consider these paths:
  - (K, H, E, B) of length  $14 + 5 = 19$
  - (K, H, E, C) of length  $14 + 1 = 15$
  - (K, H, E, D) of length  $14 + 10 = 24$
  - (K, H, E, F) of length  $14 + 22 = 36$

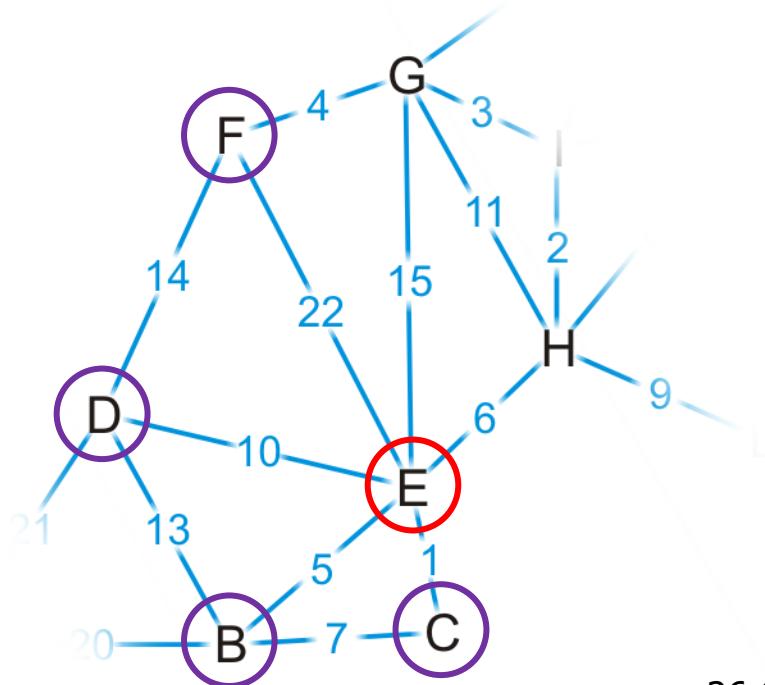


26-SPT

Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	$\infty$	$\emptyset$
C	F	$\infty$	$\emptyset$
D	F	$\infty$	$\emptyset$
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

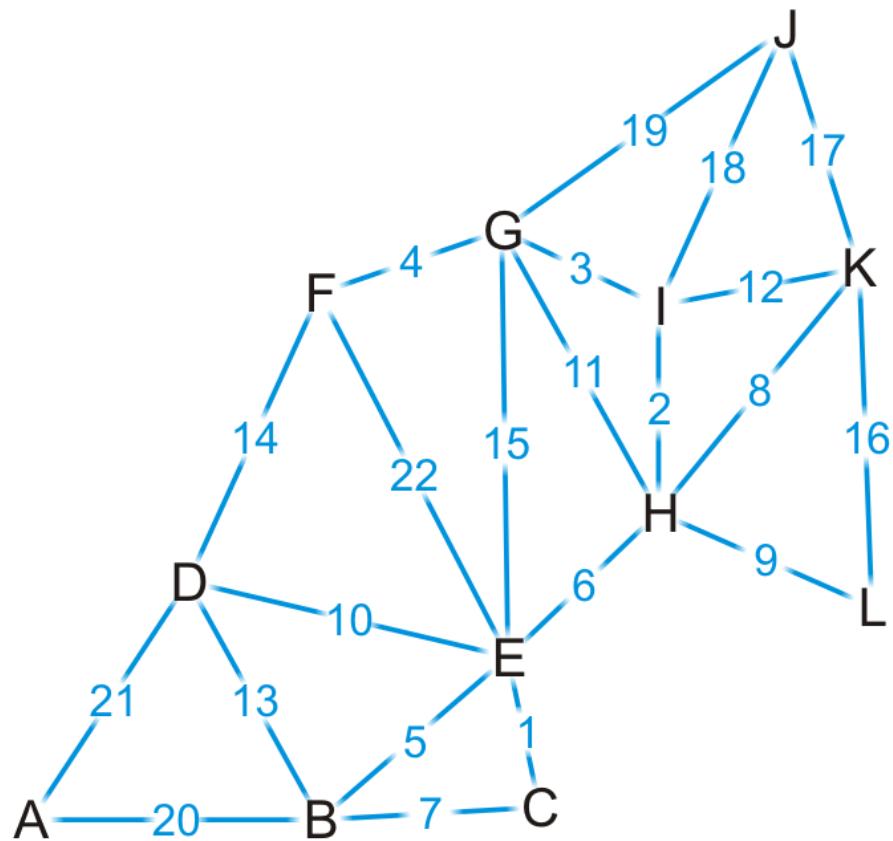
- We've discovered paths to vertices B, C, D



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	F	15	E
D	F	24	E
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

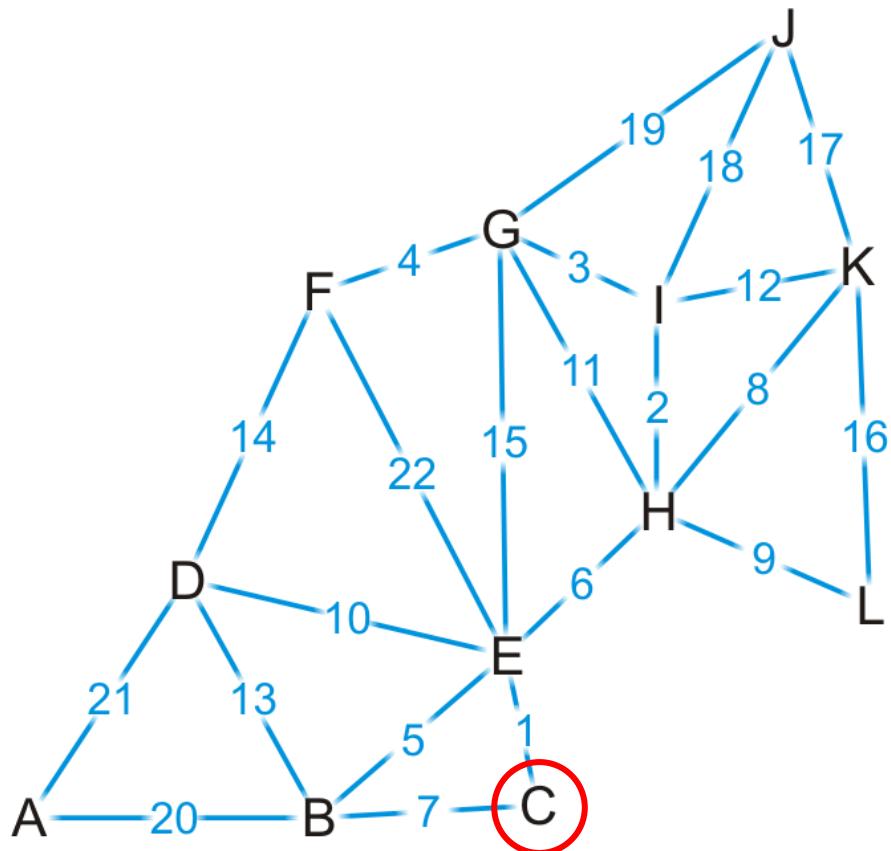
- Which vertex is next?



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	F	15	E
D	F	24	E
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

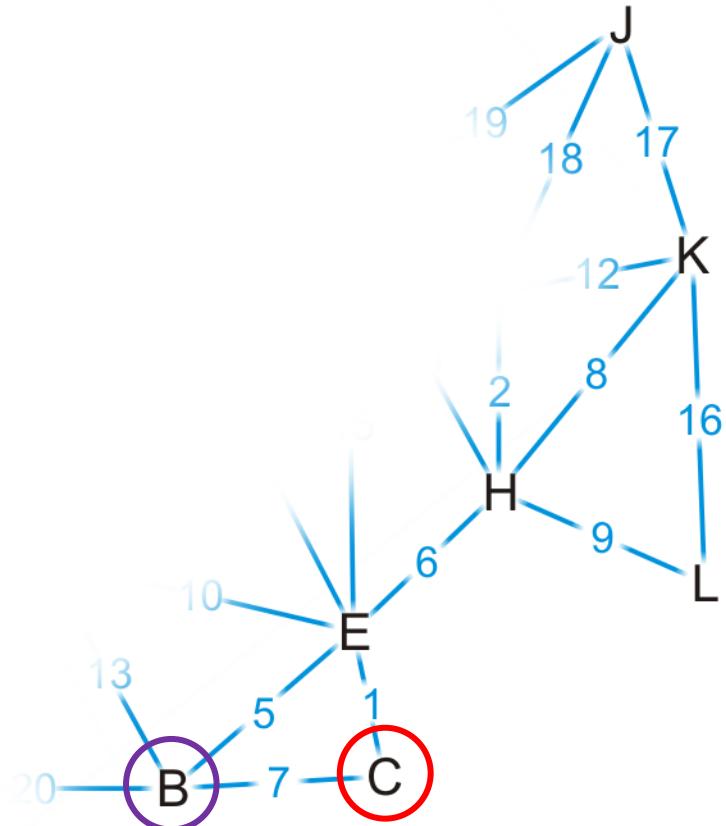
- We've found that the path (K, H, E, C) of length 15 is the shortest path from K to C
  - Vertex C has one unvisited neighbor, B



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	T	15	E
D	F	24	E
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

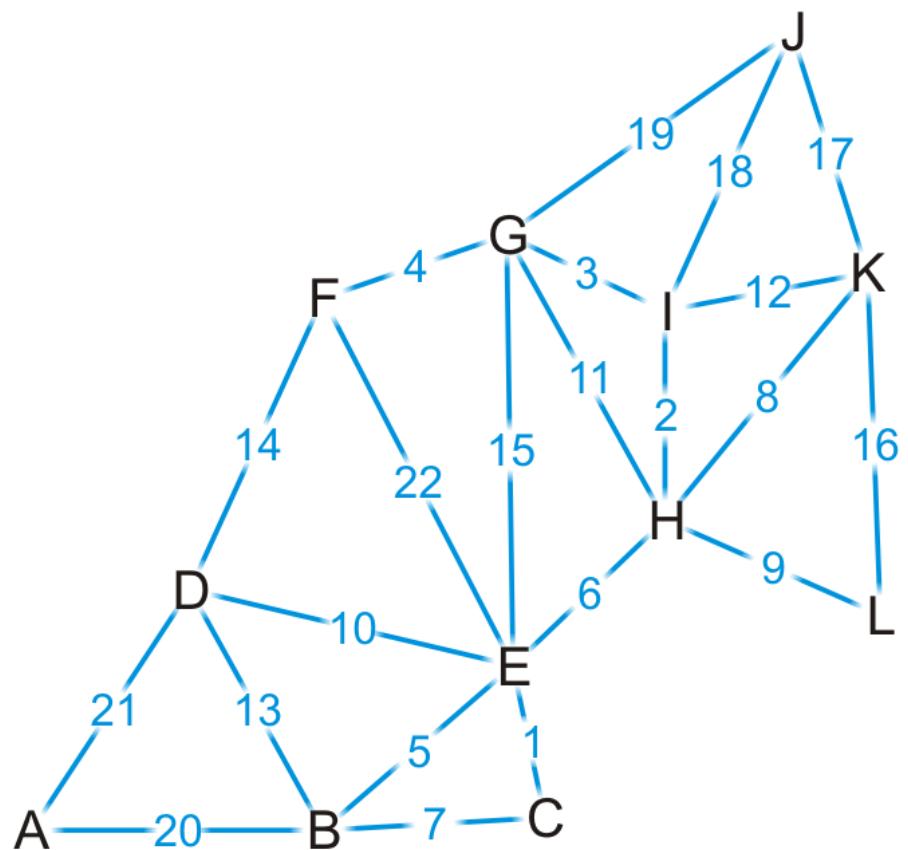
- The path (K, H, E, C, B) is of length  $15 + 7 = 22$ 
  - We have already discovered a shorter path through vertex E



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	T	15	E
D	F	24	E
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

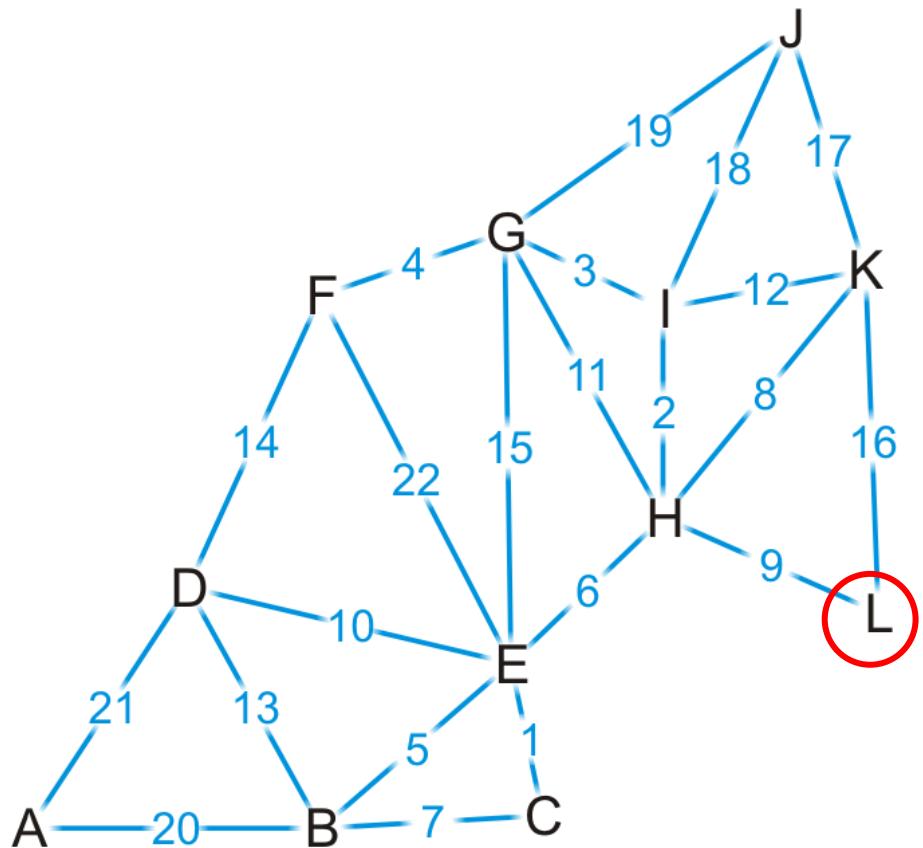
- Where to next?



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	T	15	E
D	F	24	E
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	F	16	K

# Dijkstra's Algorithm – Example

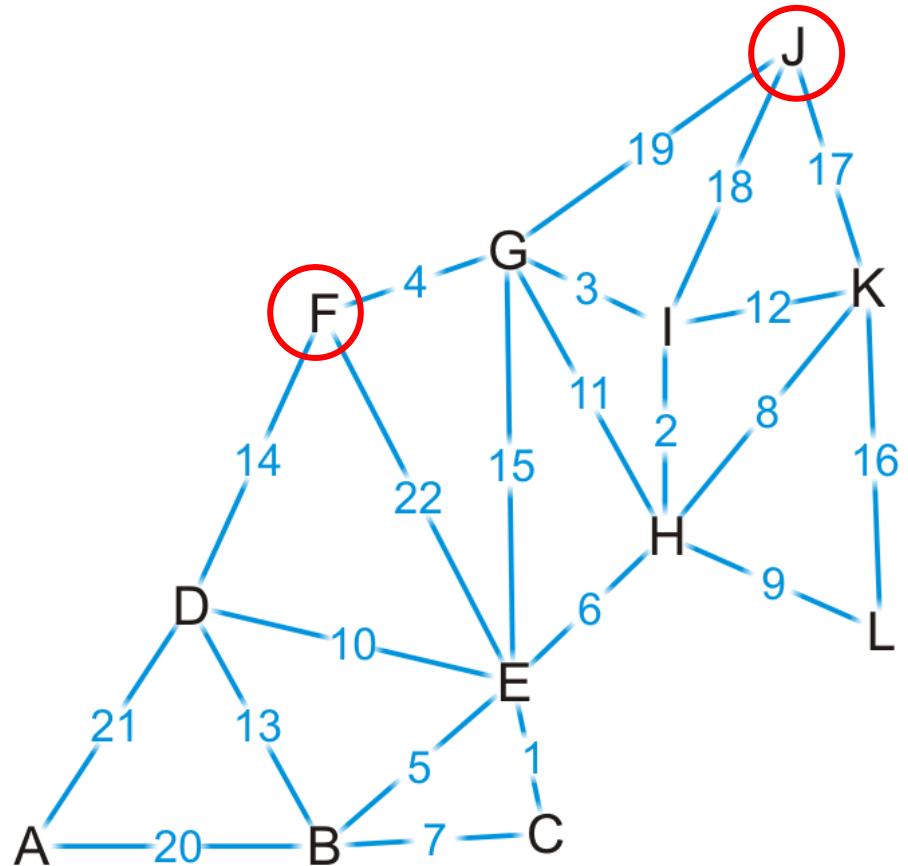
- We now know that (K, L) is the shortest path between these two points
  - Vertex L has no unvisited neighbors



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	T	15	E
D	F	24	E
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	T	16	K

# Dijkstra's Algorithm – Example

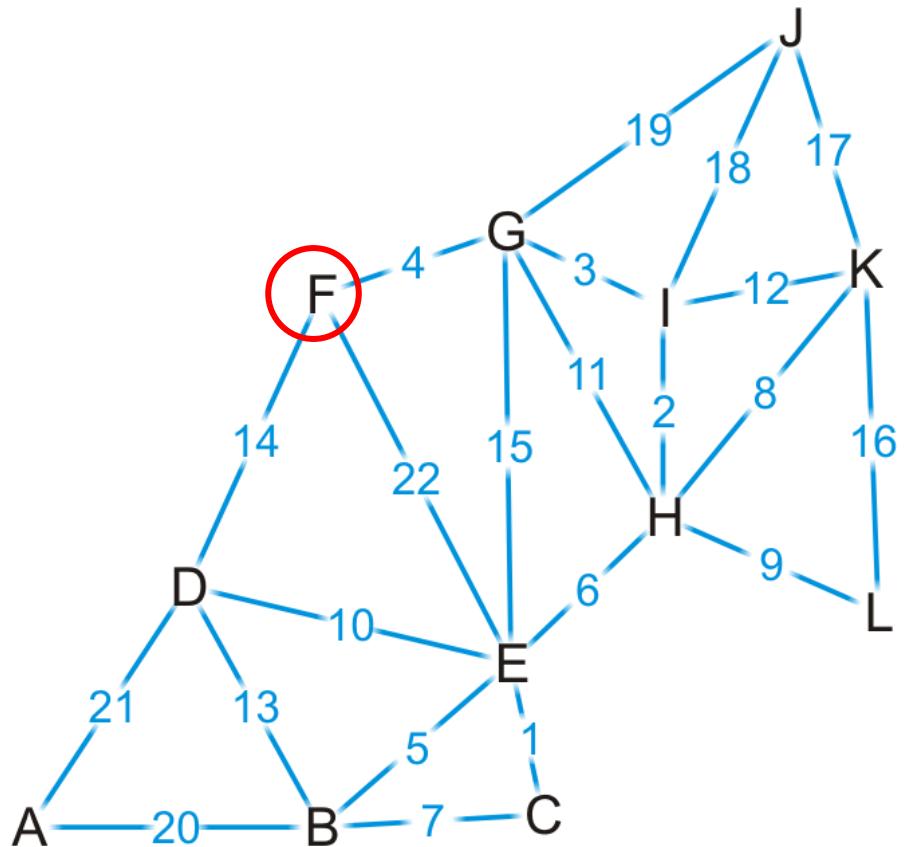
- Where to next?
  - Does it matter if we visit vertex F first or vertex J first?



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	T	15	E
D	F	24	E
E	T	14	H
F	F	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	T	16	K

# Dijkstra's Algorithm – Example

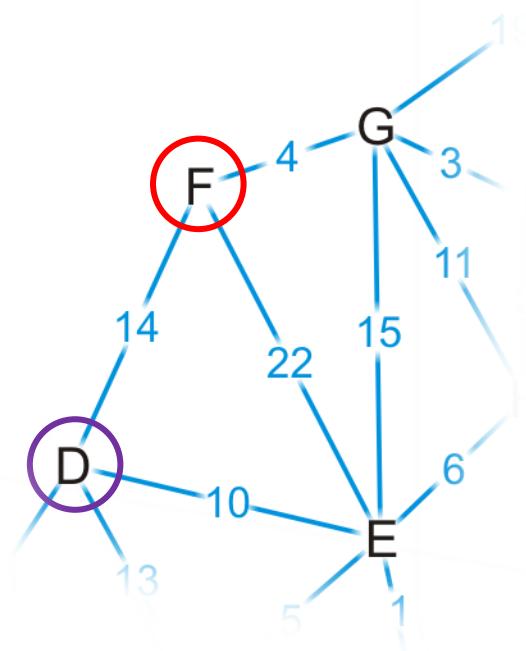
- Let's visit vertex F first
  - It has one unvisited neighbor, vertex D



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	T	15	E
D	F	24	E
E	T	14	H
F	T	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	T	16	K

# Dijkstra's Algorithm – Example

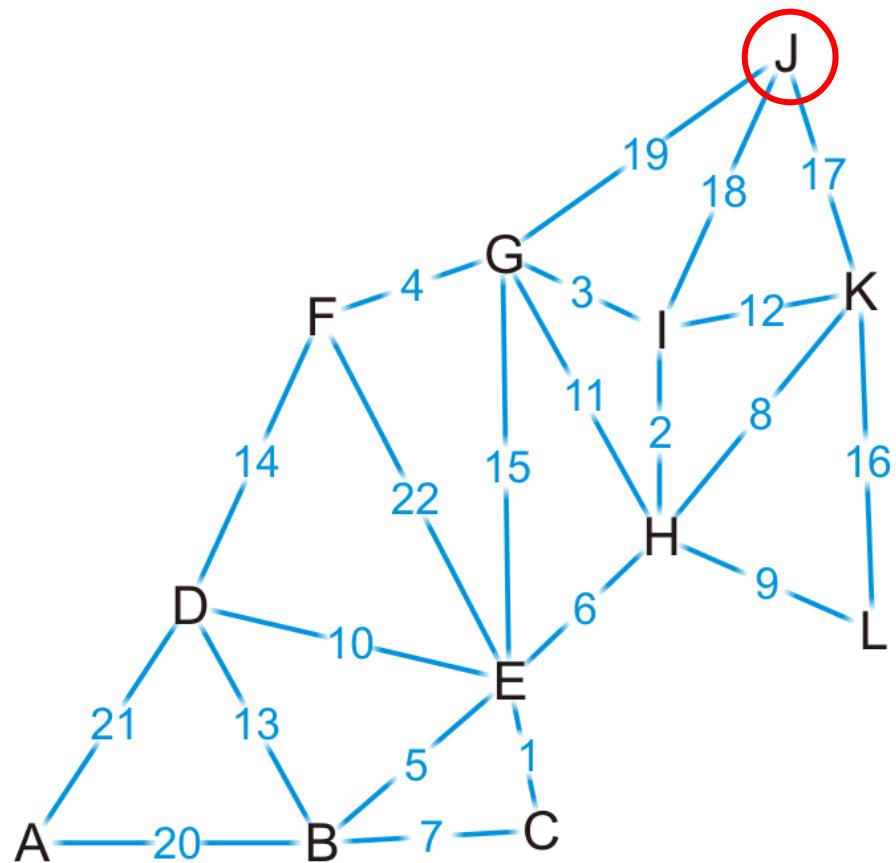
- The path (K, H, I, G, F, D) is of length  $17 + 14 = 31$ 
  - This is longer than the path we've already discovered



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	T	15	E
D	F	24	E
E	T	14	H
F	T	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	F	17	K
K	T	0	$\emptyset$
L	T	16	K

# Dijkstra's Algorithm – Example

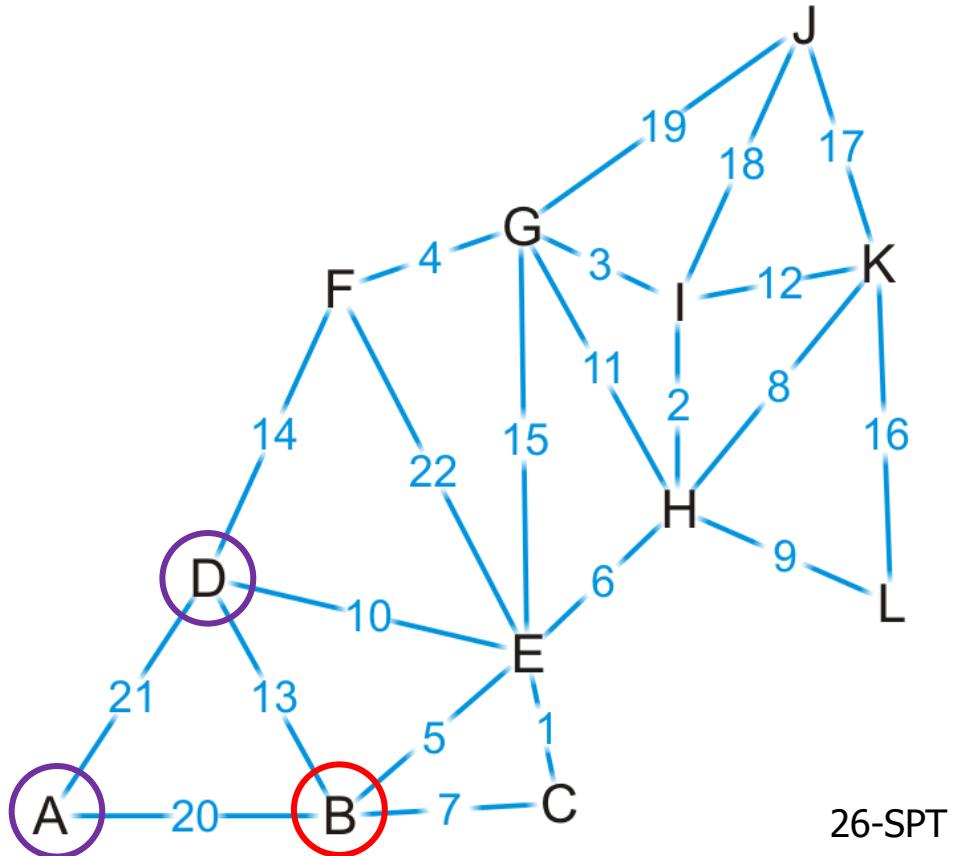
- Now we visit vertex J
  - It has no unvisited neighbors



Vertex	S	Distance	Parent
A	F	$\infty$	$\emptyset$
B	F	19	E
C	T	15	E
D	F	24	E
E	T	14	H
F	T	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	T	17	K
K	T	0	$\emptyset$
L	T	16	K

# Dijkstra's Algorithm – Example

- Next we visit vertex B, which has two unvisited neighbors:
  - (K, H, E, B, A) of length **19** + 20 = 39
  - (K, H, E, B, D) of length **19** + 13 = 32
- We update the path length to A



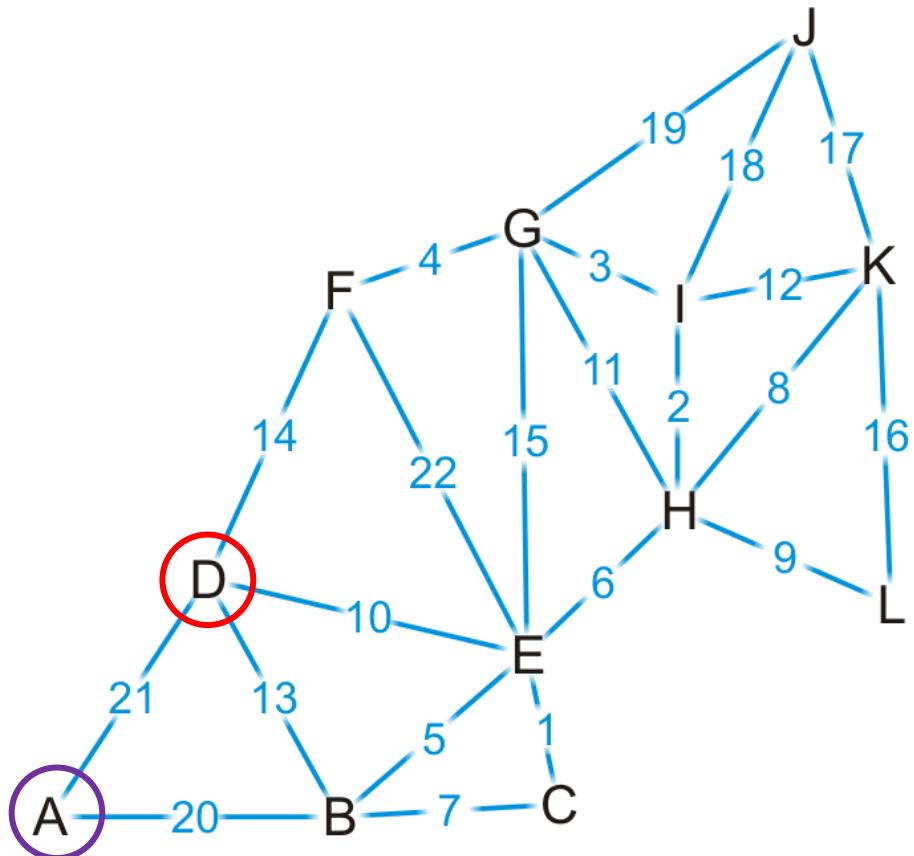
26-SPT

Vertex	S	Distance	Parent
A	F	<b>39</b>	B
B	T	<b>19</b>	E
C	T	15	E
D	F	<b>24</b>	E
E	T	14	H
F	T	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	T	17	K
K	T	0	Ø
L	T	16	K

53

# Dijkstra's Algorithm – Example

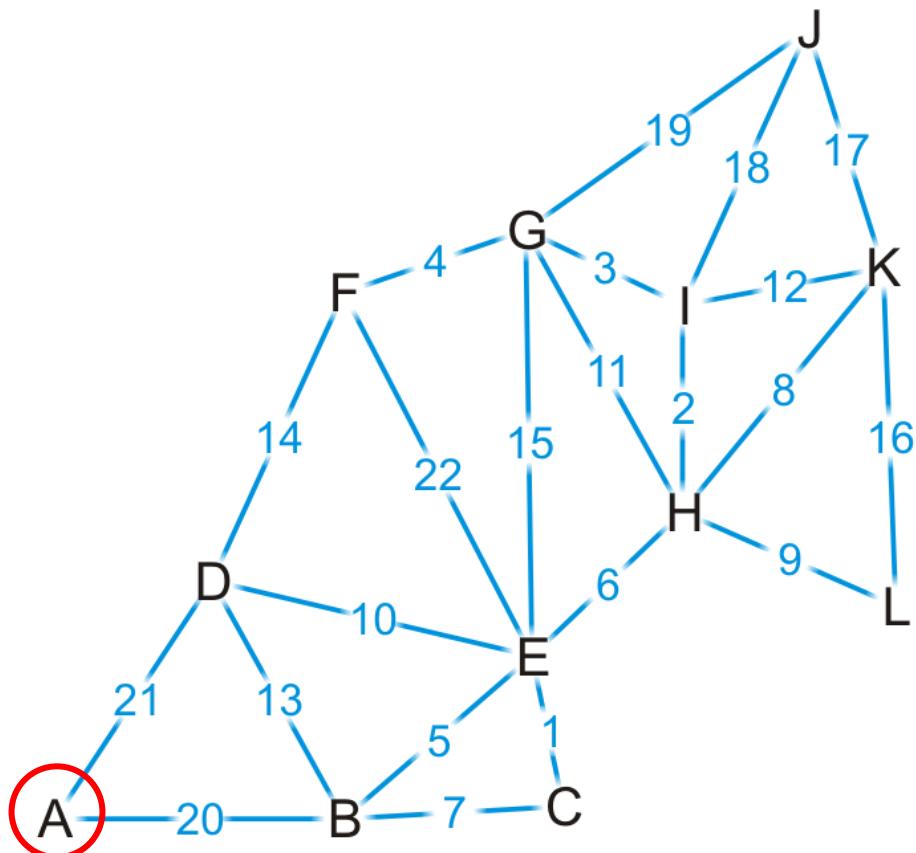
- Next we visit vertex D
  - The path (K, H, E, D, A) is of length  $24 + 21 = 45$
  - We don't update A



Vertex	S	Distance	Parent
A	F	39	B
B	T	19	E
C	T	15	E
D	T	24	E
E	T	14	H
F	T	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	T	17	K
K	T	0	Ø
L	T	16	K

# Dijkstra's Algorithm – Example

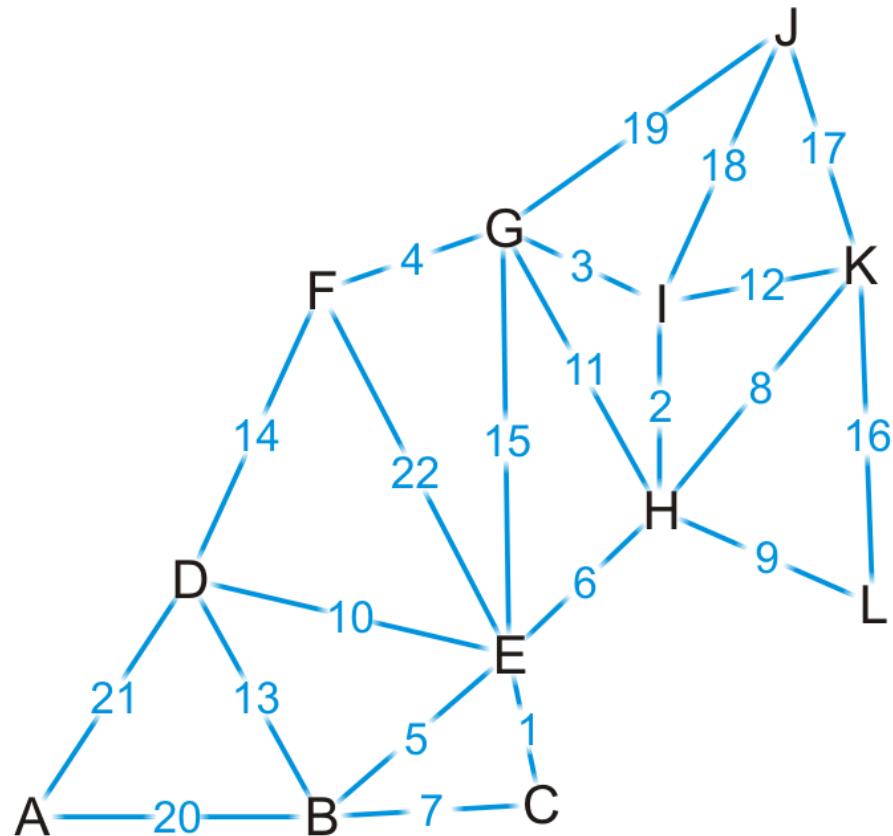
- Finally, we visit vertex A
  - It has no unvisited neighbors and there are no unvisited vertices left
  - We are done



Vertex	S	Distance	Parent
A	T	39	B
B	T	19	E
C	T	15	E
D	T	24	E
E	T	14	H
F	T	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	T	17	K
K	T	0	Ø
L	T	16	K

# Dijkstra's Algorithm – Example

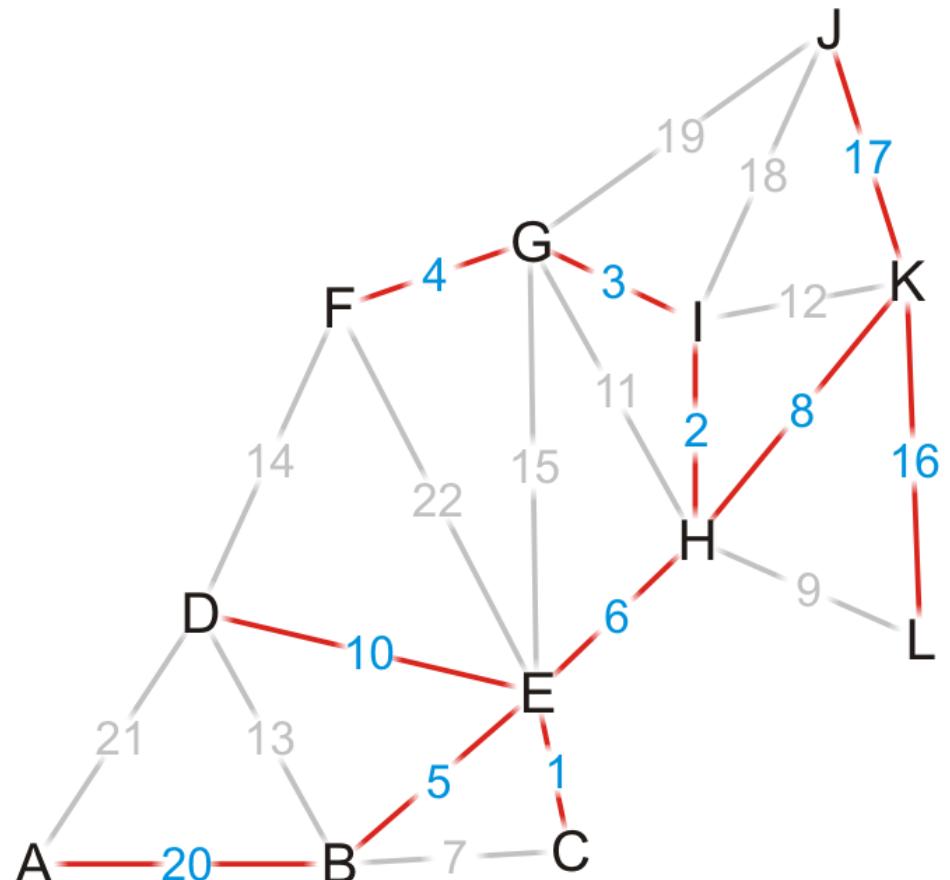
- Thus, we have found the shortest path from vertex K to each of the other vertices



Vertex	S	Distance	Parent
A	T	39	B
B	T	19	E
C	T	15	E
D	T	24	E
E	T	14	H
F	T	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	T	17	K
K	T	0	Ø
L	T	16	K

# Dijkstra's Algorithm – Example

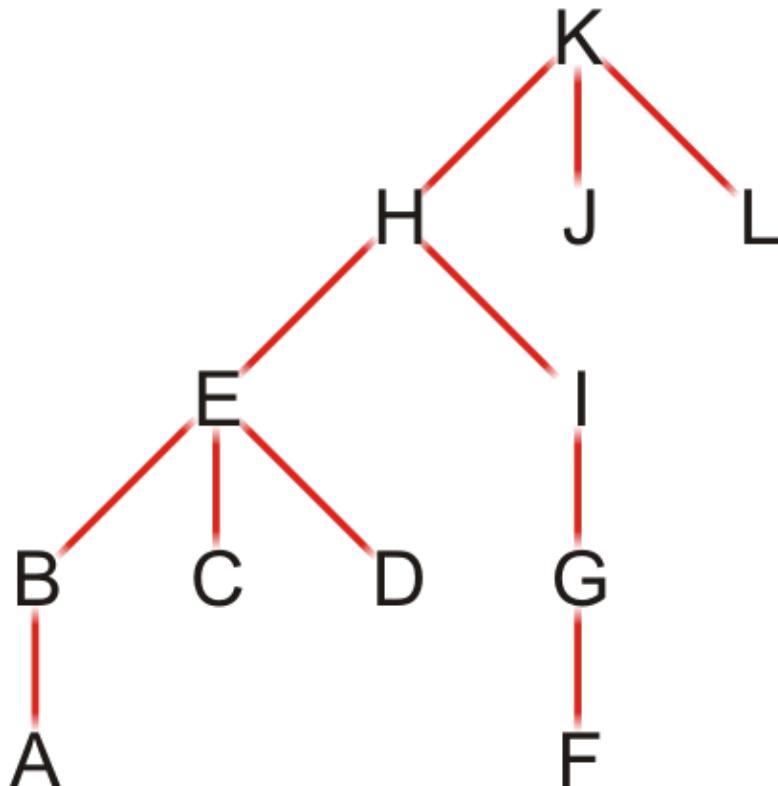
- Using the previous pointers, we can reconstruct the paths



Vertex	S	Distance	Parent
A	T	39	B
B	T	19	E
C	T	15	E
D	T	24	E
E	T	14	H
F	T	17	G
G	T	13	I
H	T	8	K
I	T	10	H
J	T	17	K
K	T	0	Ø
L	T	16	K

# Dijkstra's Algorithm – Example

- The table defines a rooted parental tree
  - The source vertex K is at the root
  - The previous pointer is the parent of the vertex in the tree



Vertex	Previous
A	B
B	E
C	E
D	E
E	H
F	G
G	I
H	K
I	H
J	K
K	∅
L	K

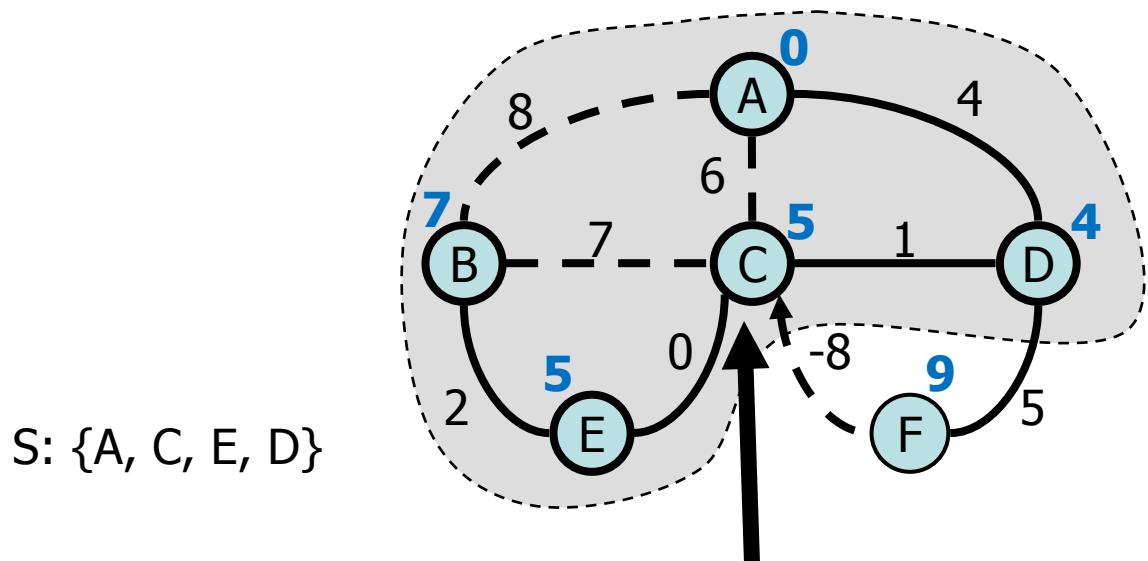
# Comments on Dijkstra's Algorithm

---

- If at some point, all unvisited vertices have a distance  $\infty$ ?
  - This means that the graph is unconnected
  - We have found the shortest paths to all vertices in the connected subgraph containing the source vertex
- To find the shortest path between vertices  $v_j$  and  $v_k$ ?
  - Apply the same algorithm, but stop when visiting vertex  $v_k$
- Does the algorithm change if graph is directed?
  - No

# Negative Edges

- Dijkstra's algorithm is based on the greedy method
  - It adds vertices by increasing distance
- If a node with a negative incident edge is visited late
  - It could mess up distances for vertices already in the set S



C's true distance is 1, but it is  
already in the set S with  
 $\text{dist}(C)=5$ !

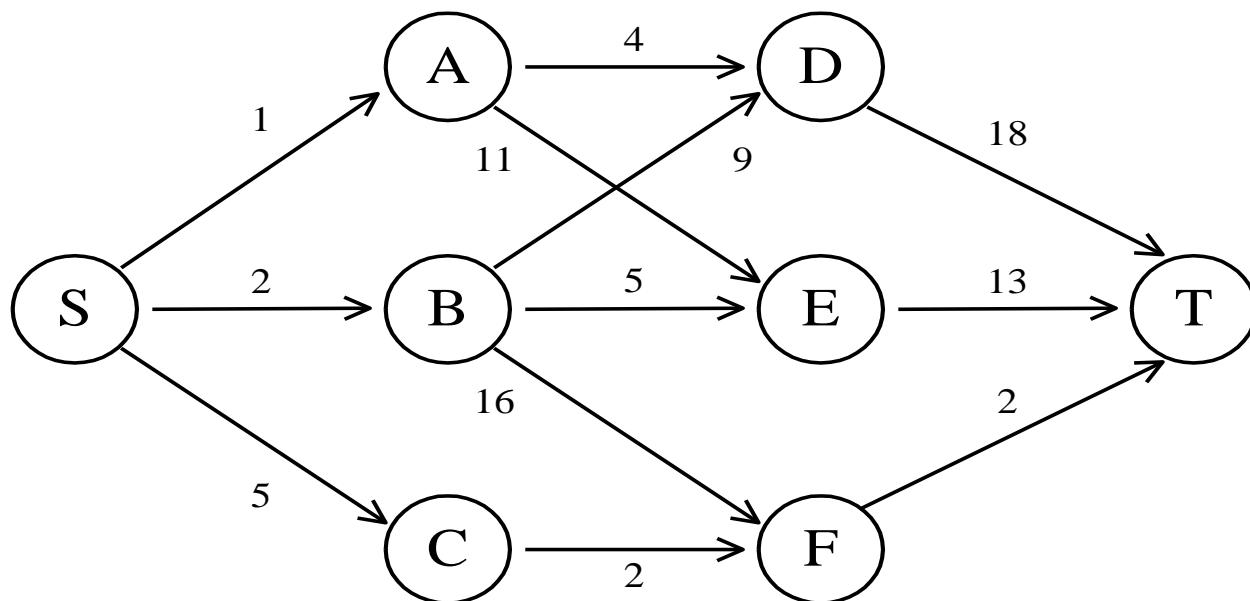
---

## All Pairs Shortest Path

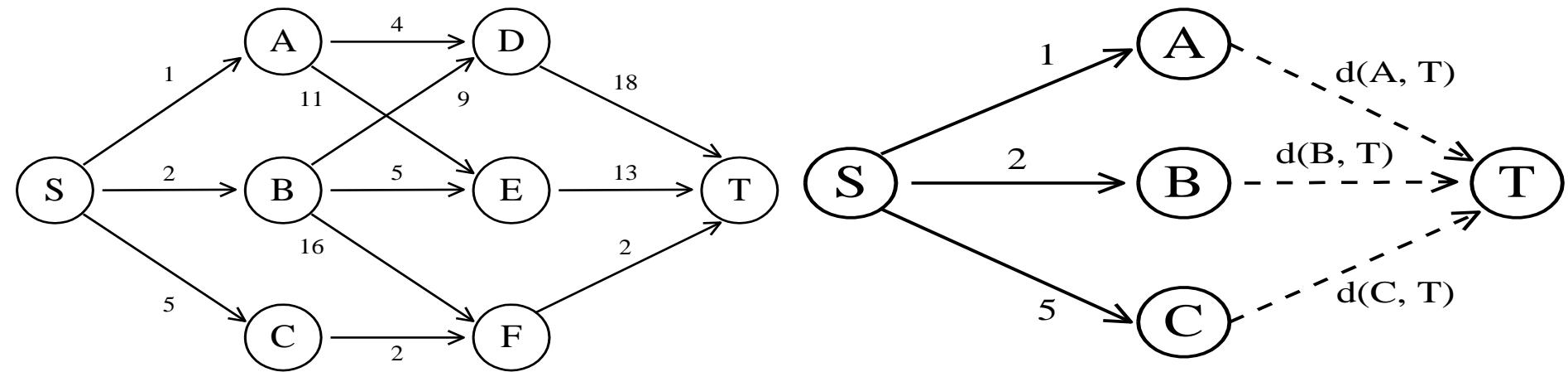
# Dynamic Programming

---

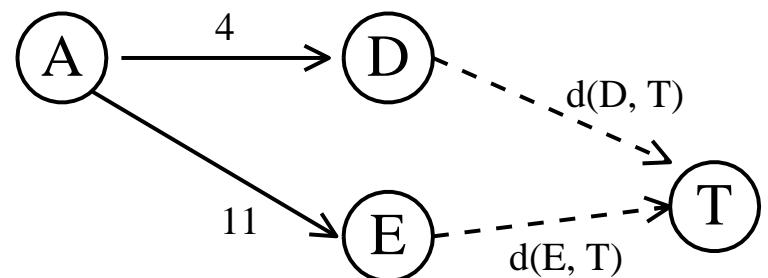
- Algorithm design method that can be used when the solution to a problem may be viewed as the result of a sequence of decisions
- Example: How to find shortest path from S to T?



# Dynamic Programming – Backward Reasoning

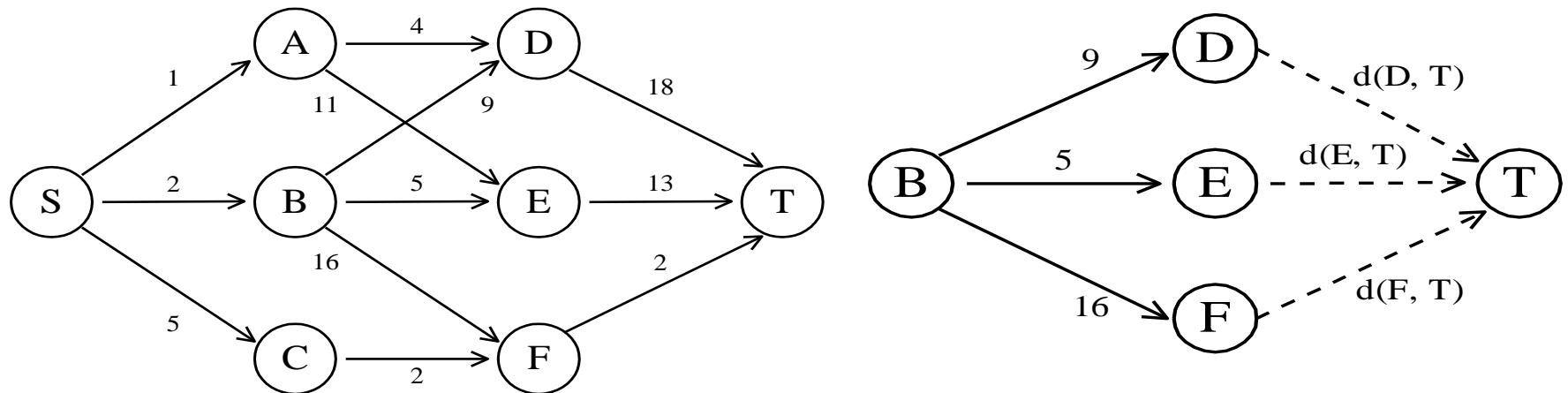


- $d(S, T) = \min\{1+d(A, T), 2+d(B, T), 5+d(C, T)\}$
- $d(A, T) = \min\{4+d(D, T), 11+d(E, T)\} = \min\{4+18, 11+13\} = 22$



# Dynamic Programming – Backward Reasoning

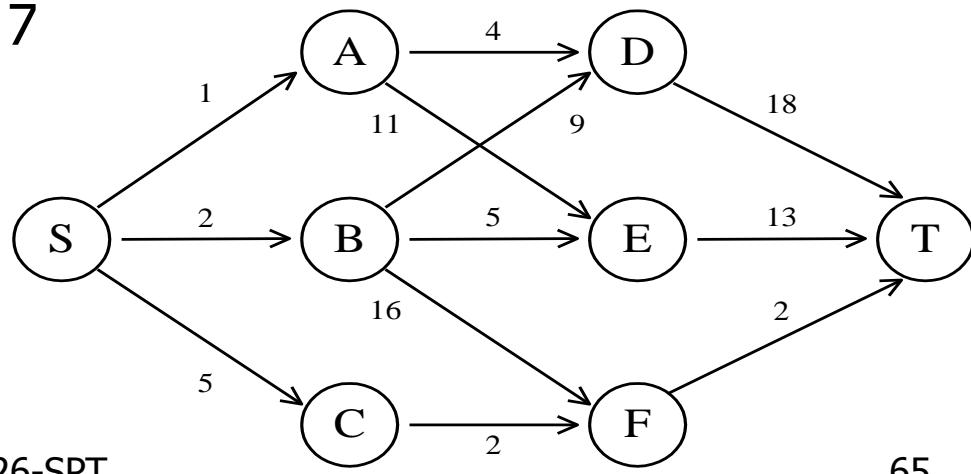
- $d(B, T) = \min\{9+d(D, T), 5+d(E, T), 16+d(F, T)\}$   
 $= \min\{9+18, 5+13, 16+2\} = 18$



- $d(C, T) = \min\{ 2+d(F, T) \} = 2+2 = 4$
- $d(S, T) = \min\{1+d(A, T), 2+d(B, T), 5+d(C, T)\}$   
 $= \min\{1+22, 2+18, 5+4\} = 9$

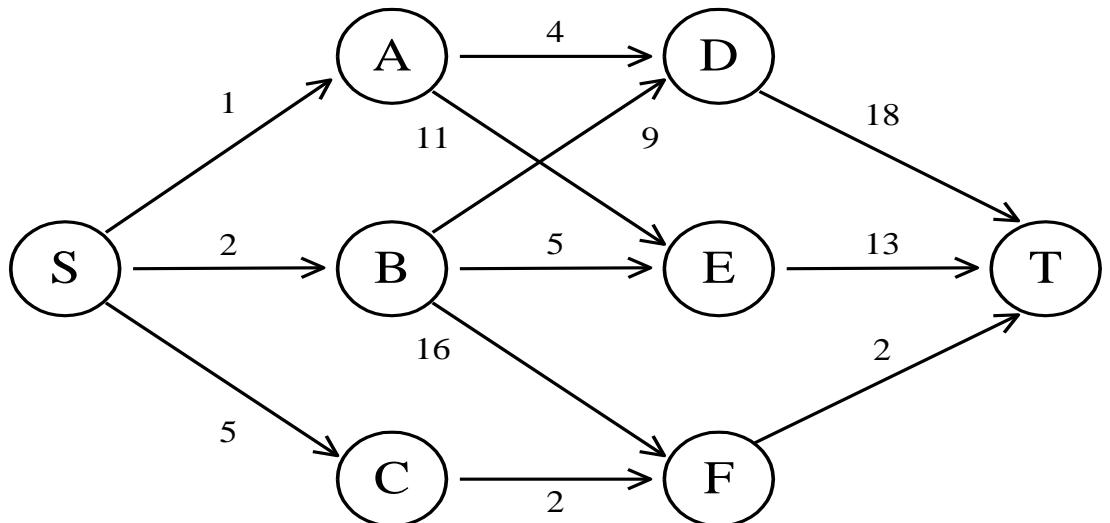
# Dynamic Programming – Forward Reasoning

- $d(S, A) = 1$
- $d(S, B) = 2$
- $d(S, C) = 5$
- $d(S,D) = \min\{d(S,A)+d(A,D), d(S,B)+d(B,D)\}$   
 $= \min\{ 1+4, 2+9 \} = 5$
- $d(S,E) = \min\{d(S,A)+d(A,E), d(S,B)+d(B,E)\}$   
 $= \min\{ 1+11, 2+5 \} = 7$
- $d(S,F) = \min\{d(S,B)+d(B,F), d(S,C)+d(C,F)\}$   
 $= \min\{ 2+16, 5+2 \} = 7$



# Dynamic Programming – Forward Reasoning

- $d(S, T) = \min\{d(S, D)+d(D, T), d(S, E) + d(E, T), d(S, F)+d(F, T)\}$   
 $= \min\{ 5+18, 7+13, 7+2 \}$   
 $= 9$



# All Pairs Shortest Path

---

- Find the shortest path between every pair of vertices of a graph
- Graph may contain negative edges but no negative cycles
- Can we use Dijkstra's algorithm for this purpose? How?
  - Set each vertex as source and call Dijkstra's algorithm
- We will discuss an algorithm By Floyd

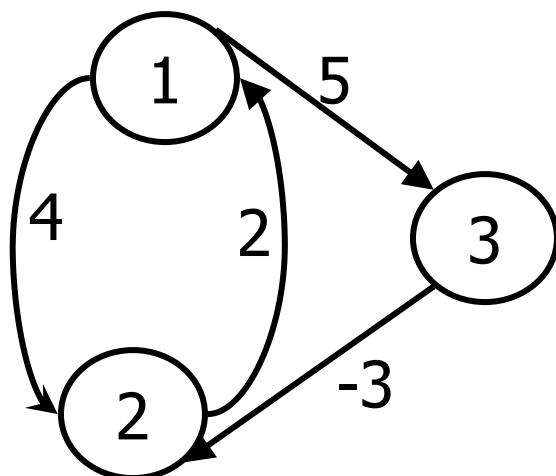
# Floyd's Algorithm – Basics and Notation

---

- Assume vertices are numbered as  $1, 2, 3, \dots, n = |V|$  for simplicity
- Uses  $n \times n$  matrix  $D$  ( $n$  is the number of vertices in the graph  $G$ )
- Shortest paths are computed in matrix  $D$
- We make  $n = |V|$  iterations over matrix  $D$ 
  - $D^k$  denotes the value of the matrix after  $k^{\text{th}}$  iterations
  - $D^k[i, j]$  indicates minimum weight path between vertices  $i$  and  $j$ 
    - That does not pass through a vertex numbered higher than  $k$

# Initialization

- $D^0$  considers only edges that connect vertices directly
  - $D^0[i,j] = 0$  if  $i==j$
  - $D^0[i,j] = w(i,j)$  if there is an edge from  $i$  to  $j$
  - $D^0[i,j] = \infty$  Otherwise
- In C++, we would define a two-dimensional array
  - `double D[num_vertices][num_vertices];`



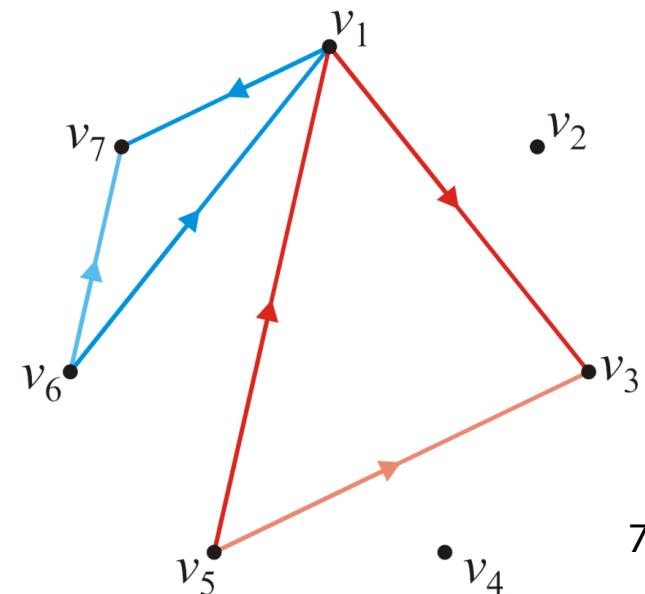
$$W = D^0 =$$

	1	2	3
1	0	4	5
2	2	0	$\infty$
3	$\infty$	-3	0

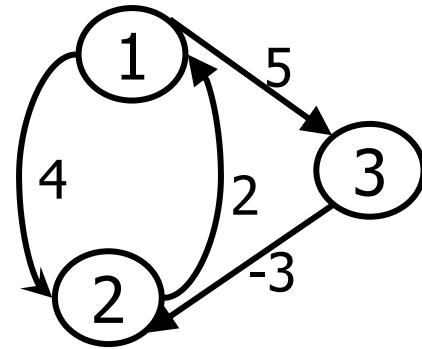
# First Iteration

- For each pair of vertices, we will define  $D^1[i, j]$  by calculating
  - $D^1[i, j] = \min(D^0[i, j], D^0[i, 1] + D^0[1, j])$

```
for ( int i = 0; i < num_vertices; ++i ) {
    for ( int j = 0; j < num_vertices; ++j ) {
        D[i][j] = std::min( D[i][j], D[i][0] + D[0][j] );
    }
}
```



## First Iteration – Example

$$D^0 = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 4 & 5 \\ 2 & 2 & 0 & \infty \\ 3 & \infty & -3 & 0 \end{array}$$

$$D^1 = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 4 & 5 \\ 2 & 2 & 0 & 7 \\ 3 & \infty & -3 & 0 \end{array}$$

Vertex 1 can be intermediate node

$$\begin{aligned} D^1[2,3] &= \min( D^0[2,3], D^0[2,1]+D^0[1,3] ) \\ &= \min( \infty, 7 ) \\ &= 7 \end{aligned}$$

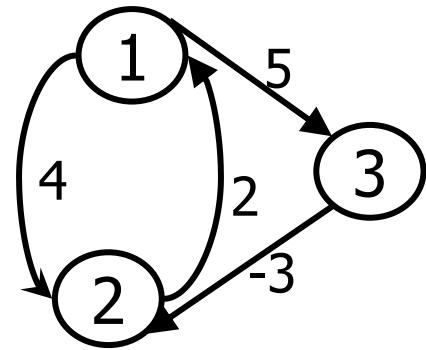
$$\begin{aligned} D^1[3,2] &= \min( D^0[3,2], D^0[3,1]+D^0[1,2] ) \\ &= \min( -3, \infty ) \\ &= -3 \end{aligned}$$

## Second Iteration

---

- With vertex 1 as intermediate we have found the shortest paths from  $i$  to  $j$ ,  $i$  to 2 and 2 to  $j$ 
  - The only possible shorter path including vertex 2 would be the path from  $i$  to 2 continuing from there to  $j$
- Thus, calculate
  - $D^2[i,j] = \min(D^1[i,j], D^1[i,2] + D^1[2,j])$

## Second Iteration – Example

$$D^1 = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 4 & 5 \\ 2 & 2 & 0 & 7 \\ 3 & \infty & -3 & 0 \end{array}$$

$$D^2 = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 4 & 5 \\ 2 & 2 & 0 & 7 \\ 3 & -1 & -3 & 0 \end{array}$$

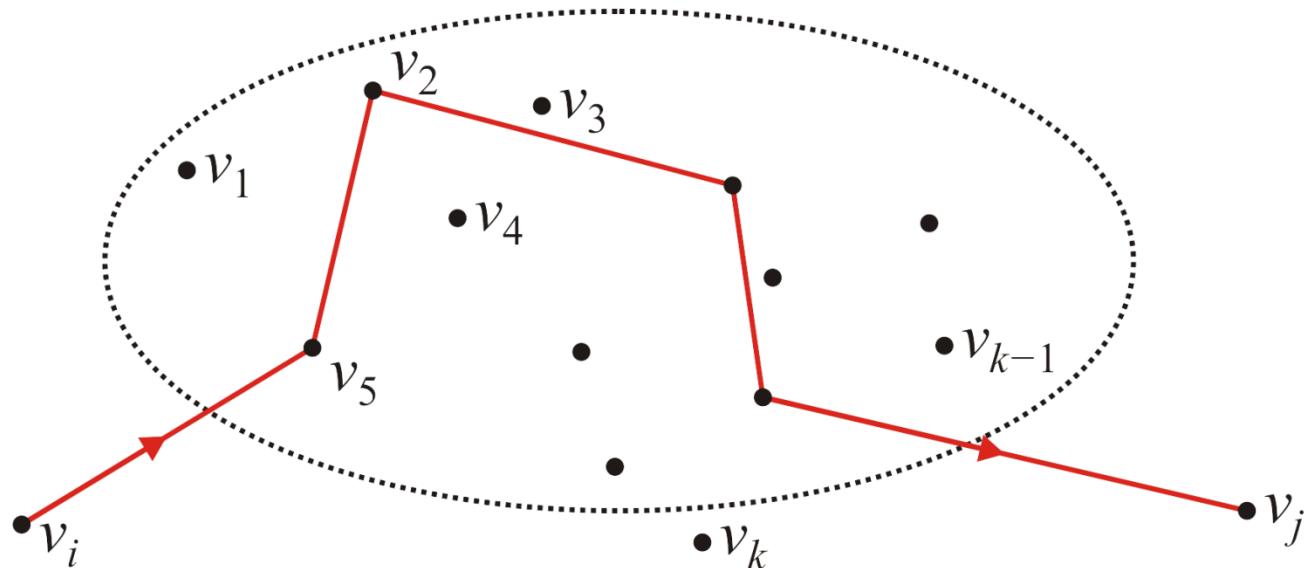
Vertex 1, 2 can be intermediate nodes

$$\begin{aligned} D^2[1,3] &= \min( D^1[1,3], D^1[1,2]+D^1[2,3] ) \\ &= \min( 5, 4+7 ) \\ &= 5 \end{aligned}$$

$$\begin{aligned} D^2[3,1] &= \min( D^1[3,1], D^1[3,2]+D^1[2,1] ) \\ &= \min( \infty, -3+2 ) \\ &= -1 \end{aligned}$$

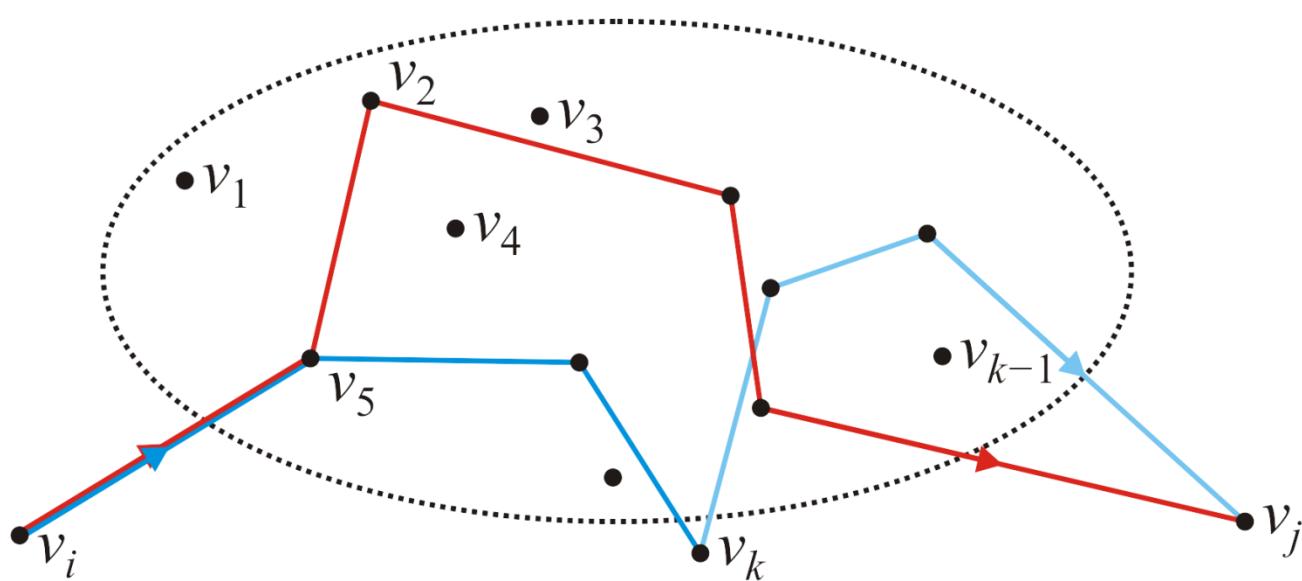
# Generalization to K<sup>th</sup> Iteration

- With vertices 1, 2, ... k-1 as intermediate we have found the shortest paths from i to j, i to k and k to j
  - The only possible shorter path including vertex k would be the path from i to k continuing from there to j



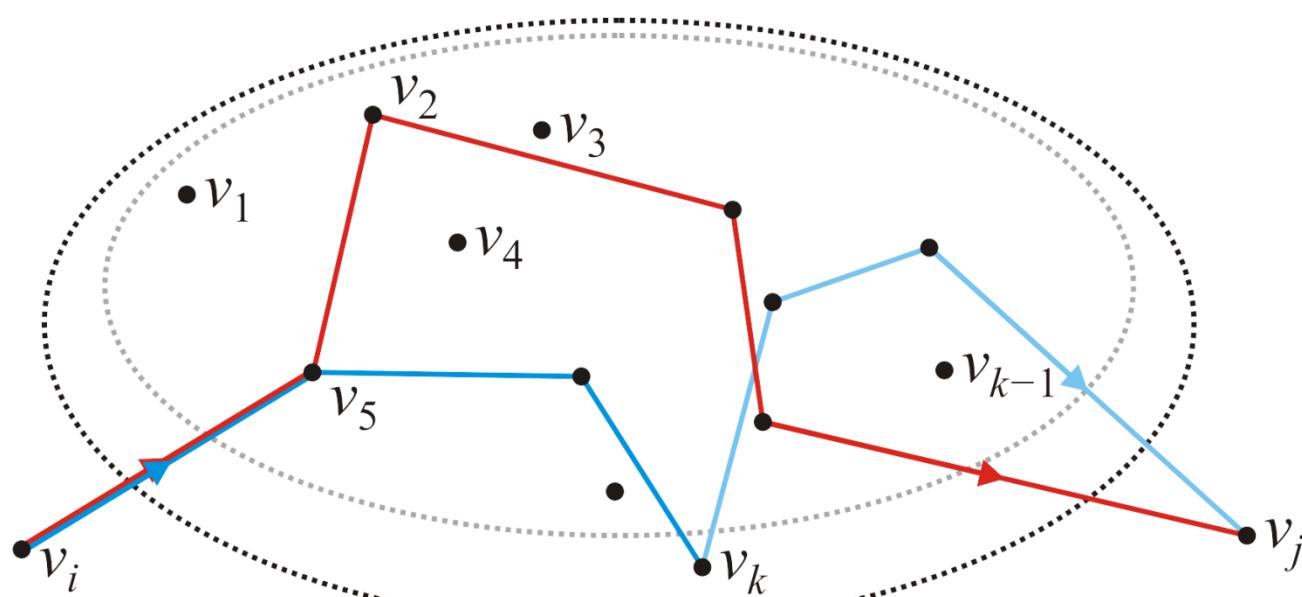
# Generalization to K<sup>th</sup> Iteration

- With vertices 1, 2, ... k-1 as intermediate we have found the shortest paths from i to j, i to k and k to j
  - The only possible shorter path including vertex k would be the path from i to k continuing from there to j
- Calculate:  $D^k[i, j] = \min (D^{k-1}[i, j], D^{k-1}[i, k] + D^{k-1}[k, j])$



# Generalization to K<sup>th</sup> Iteration

- With vertices 1, 2, ... k-1 as intermediate we have found the shortest paths from i to j, i to k and k to j
  - The only possible shorter path including vertex k would be the path from i to k continuing from there to j
- Calculate:  $D^k[i, j] = \min (D^{k-1}[i, j], D^{k-1}[i, k] + D^{k-1}[k, j])$



# Floyd's Algorithm – Pseudocode

---

```
double D[num_vertices][num_vertices];

// Initialize the matrix d
// ...

// Run Floyd-Algorithm
for ( int k = 0; k < num_vertices; ++k ) {
    for ( int i = 0; i < num_vertices; ++i ) {
        for ( int j = 0; j < num_vertices; ++j ) {
            D[i][j] = std::min( D[i][j], D[i][k] + D[k][j] );
        }
    }
}
```

# Floyd's Algorithm – Pseudocode

```
double D[num_vertices][num_vertices];  
  
// Initialize the matrix d  
// ...  
  
// Run Floyd-Algorithm  
for ( int k = 0; k < num_vertices; ++k ) {  
    for ( int i = 0; i < num_vertices; ++i ) {  
        for ( int j = 0; j < num_vertices; ++j ) {  
            D[i][j] = std::min( D[i][j], D[i][k] + D[k][j] );  
        }  
    }  
}
```

```
if( D[i][j] > D[i][k] + D[k][j] ){  
    D[i][j] = D[i][k] + D[k][j];  
}
```

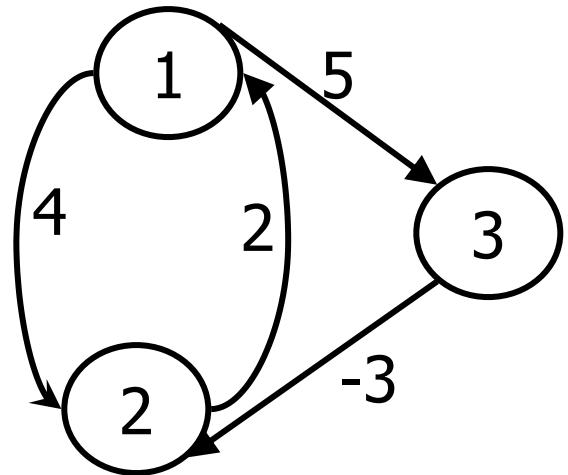
- Runtime  $O(|V|^3)$
- This algorithm finds the shortest distances, but what are the paths corresponding to those shortest distances?

# Tracking Shortest Paths

- Use another matrix  $P$
- $P[i, j]$  holds the vertex  $k$  that led to the smallest value of  $D[i, j]$
- If  $P[i, j] = 0$  there is no intermediate edge involved
  - Shortest path is direct edge between  $i$  and  $j$

```
// Run Floyd-Algorithm
for ( int k = 0; k < num_vertices; ++k ) {
    for ( int i = 0; i < num_vertices; ++i ) {
        for ( int j = 0; j < num_vertices; ++j ) {
            if( D[i][j] > D[i][k] + D[k][j] ){
                D[i][j] = D[i][k] + D[k][j];
                P[i][j] = k;
            }
        }
    }
}
```

# Floyd's Algorithm – Example Revisited

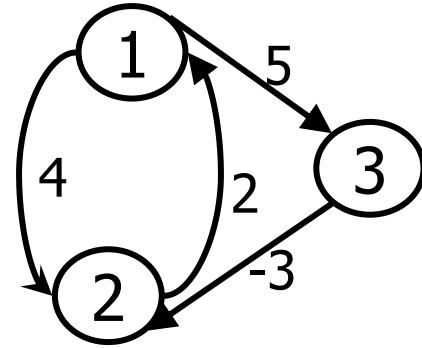
$$W = D^0 = \begin{matrix} & \begin{matrix} 1 & 2 & 3 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{matrix} 0 & 4 & 5 \\ 2 & 0 & \infty \\ \infty & -3 & 0 \end{matrix} \end{matrix}$$

$$P = \begin{matrix} & \begin{matrix} 1 & 2 & 3 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{matrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{matrix} \end{matrix}$$

# Floyd's Algorithm – Example Revisited

	1	2	3
1	0	4	5
2	2	0	$\infty$
3	$\infty$	-3	0

	1	2	3
1	0	4	5
2	2	0	7
3	$\infty$	-3	0

	1	2	3
1	0	0	0
2	0	0	1
3	0	0	0

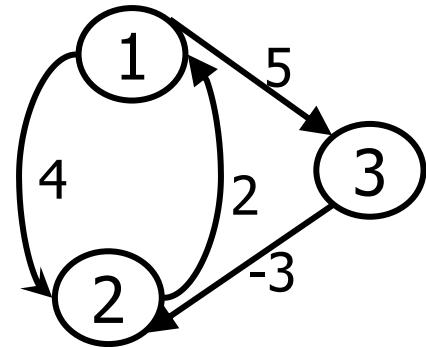


Vertex 1 can be intermediate node

$$\begin{aligned}
 D^1[2,3] &= \min(D^0[2,3], D^0[2,1]+D^0[1,3]) \\
 &= \min(\infty, 7) \\
 &= 7
 \end{aligned}$$

$$\begin{aligned}
 D^1[3,2] &= \min(D^0[3,2], D^0[3,1]+D^0[1,2]) \\
 &= \min(-3, \infty) \\
 &= -3
 \end{aligned}$$

# Floyd's Algorithm – Example Revisited

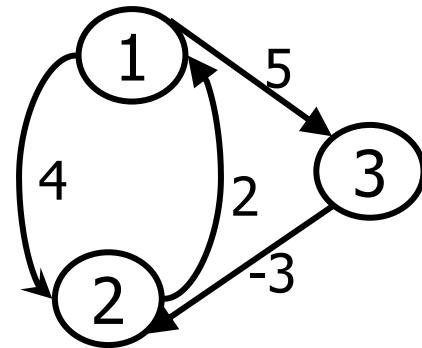
$$D^1 = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 4 & 5 \\ 2 & 2 & 0 & 7 \\ 3 & \infty & -3 & 0 \end{array}$$
$$D^2 = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 4 & 5 \\ 2 & 2 & 0 & 7 \\ 3 & -1 & -3 & 0 \end{array}$$
$$P = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 0 & 0 \\ 2 & 0 & 0 & 1 \\ 3 & 2 & 0 & 0 \end{array}$$


Vertex 1, 2 can be intermediate nodes

$$\begin{aligned} D^2[1,3] &= \min( D^1[1,3], D^1[1,2]+D^1[2,3] ) \\ &= \min( 5, 4+7 ) \\ &= 5 \end{aligned}$$

$$\begin{aligned} D^2[3,1] &= \min( D^1[3,1], D^1[3,2]+D^1[2,1] ) \\ &= \min( \infty, -3+2 ) \\ &= -1 \end{aligned}$$

# Floyd's Algorithm – Example Revisited

$$D^2 = \begin{array}{c} \begin{array}{ccc} 1 & 2 & 3 \\ \hline 1 & 0 & 4 & 5 \\ 2 & 2 & 0 & 7 \\ 3 & -1 & -3 & 0 \end{array} \end{array}$$
$$D^3 = \begin{array}{c} \begin{array}{ccc} 1 & 2 & 3 \\ \hline 1 & 0 & 2 & 5 \\ 2 & 2 & 0 & 7 \\ 3 & -1 & -3 & 0 \end{array} \end{array}$$
$$P = \begin{array}{c} \begin{array}{ccc} 1 & 2 & 3 \\ \hline 1 & 0 & 3 & 0 \\ 2 & 0 & 0 & 1 \\ 3 & 2 & 0 & 0 \end{array} \end{array}$$


Vertex 1, 2, 3 can be intermediate nodes

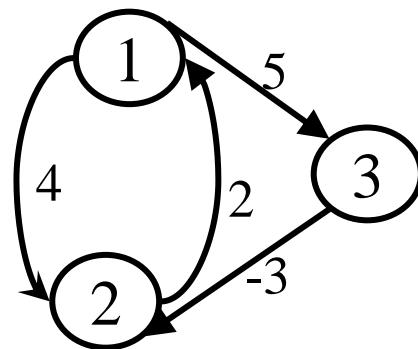
$$\begin{aligned} D^3[1,2] &= \min(D^2[1,2], D^2[1,3]+D^2[3,2]) \\ &= \min(4, 5+(-3)) \\ &= 2 \end{aligned}$$

$$\begin{aligned} D^3[2,1] &= \min(D^2[2,1], D^2[2,3]+D^2[3,1]) \\ &= \min(2, 7+ (-1)) \\ &= 2 \end{aligned}$$

# Printing Intermediate Vertices

- To print the intermediate nodes on shortest path from vertex i to j

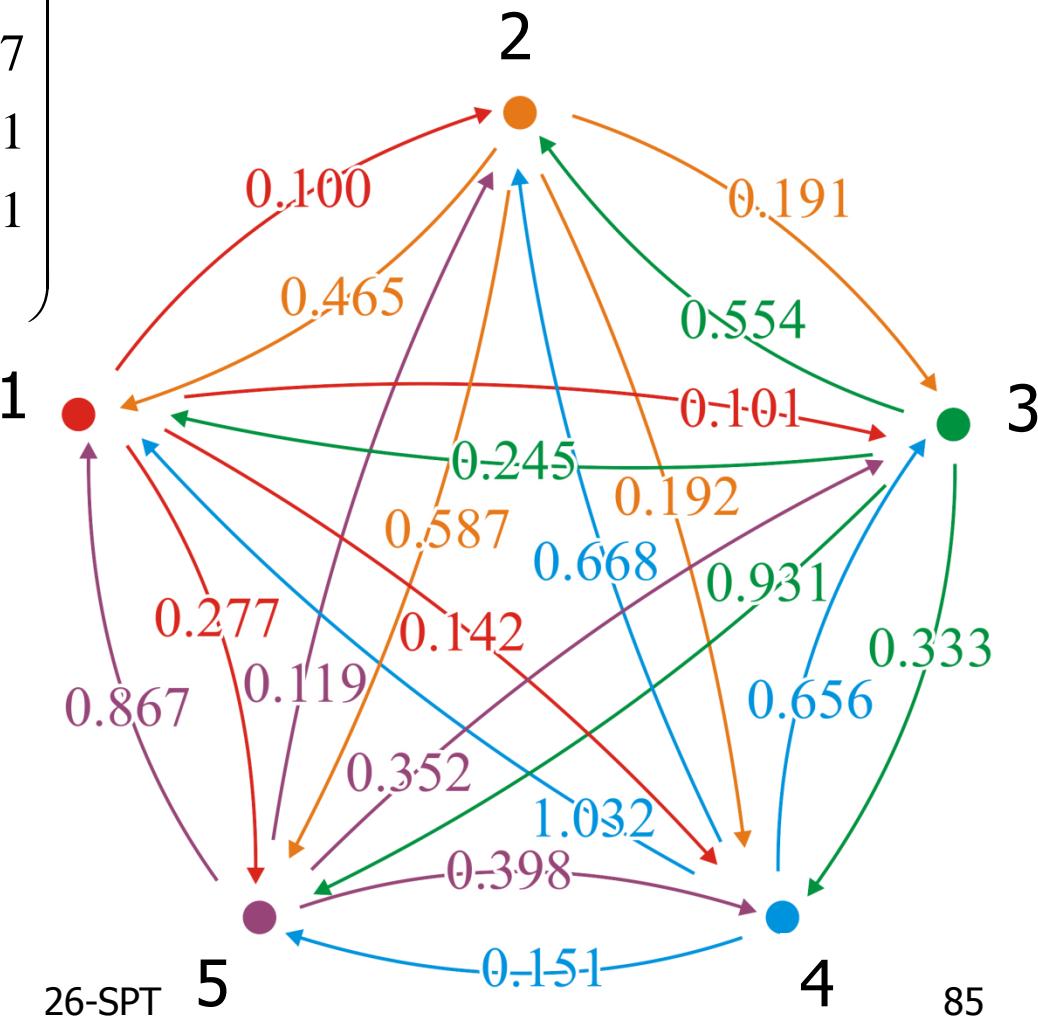
```
Path (i, j)
{
    k= P[ i, j ];
    if (k == 0) {
        return;
    }
    Path (i , k);
    print( k );
    Path (k, j);
}
```


$$P = \begin{array}{c|ccc} & & 1 & 2 & 3 \\ \hline 1 & & 0 & 3 & 0 \\ \hline 2 & & 0 & 0 & 1 \\ \hline 3 & & 2 & 0 & 0 \end{array}$$

# Floyd's Algorithm – Another Example

The D<sup>0</sup> matrix

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.554	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0



# Floyd's Algorithm – Another Example

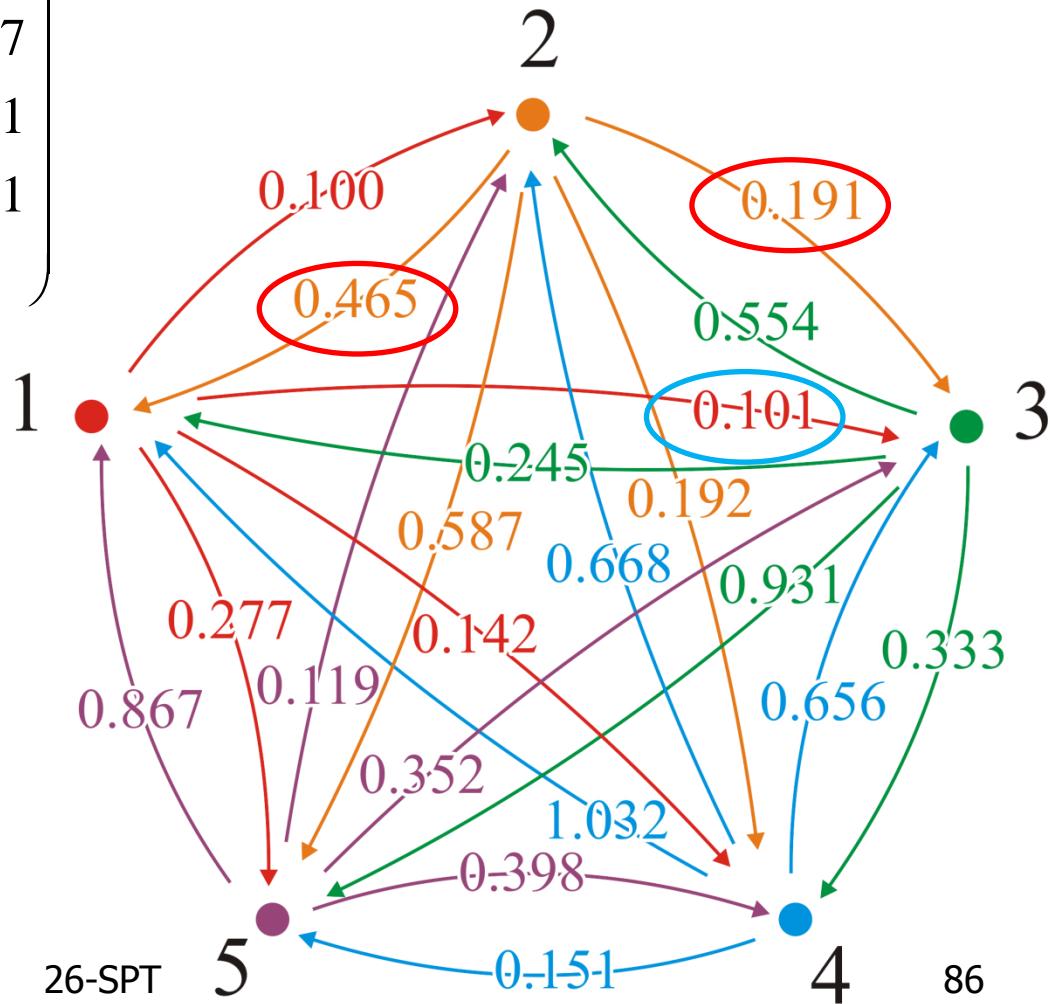
First attempt passing through vertex 1

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.554	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

We can check:

$$(2, 3) \rightarrow (2, 1, 3)$$

$$0.191 \not> 0.465 + 0.101$$



# Floyd's Algorithm – Another Example

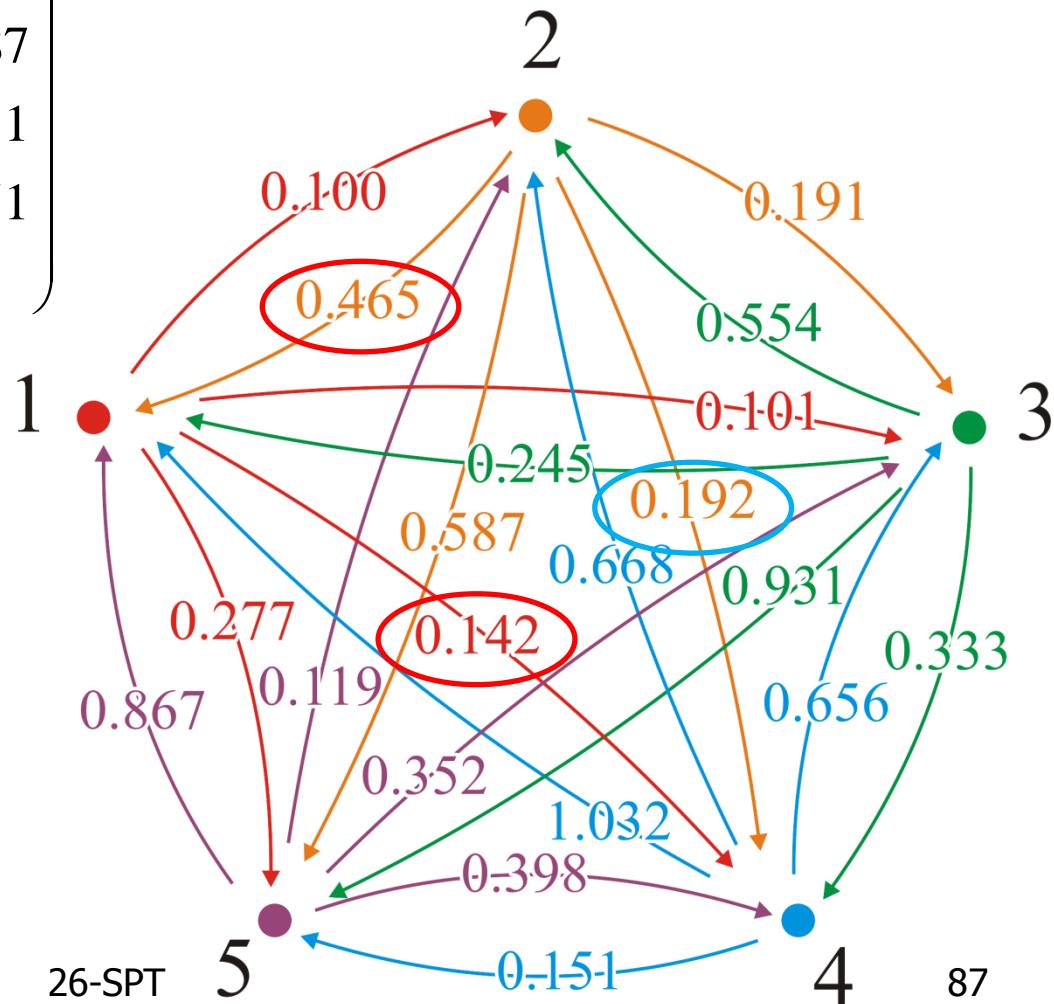
First attempt passing through vertex 1

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.554	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

We can check:

$$(2, 4) \rightarrow (2, 1, 4)$$

$$0.192 \not> 0.465 + 0.142$$



# Floyd's Algorithm – Another Example

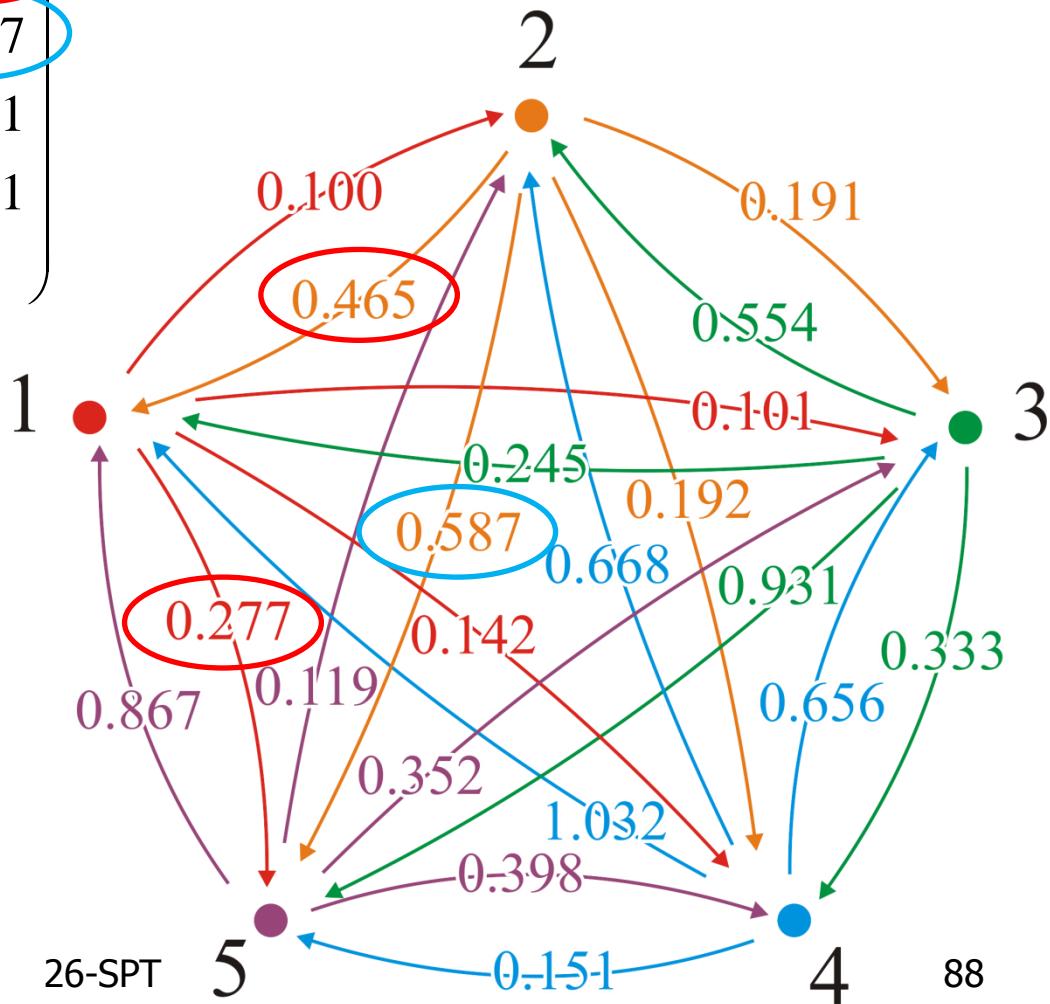
First attempt passing through vertex 1

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.554	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

We can check:

$$(2, 5) \rightarrow (2, 1, 5)$$

$$0.587 \not> 0.465 + 0.277$$



# Floyd's Algorithm – Another Example

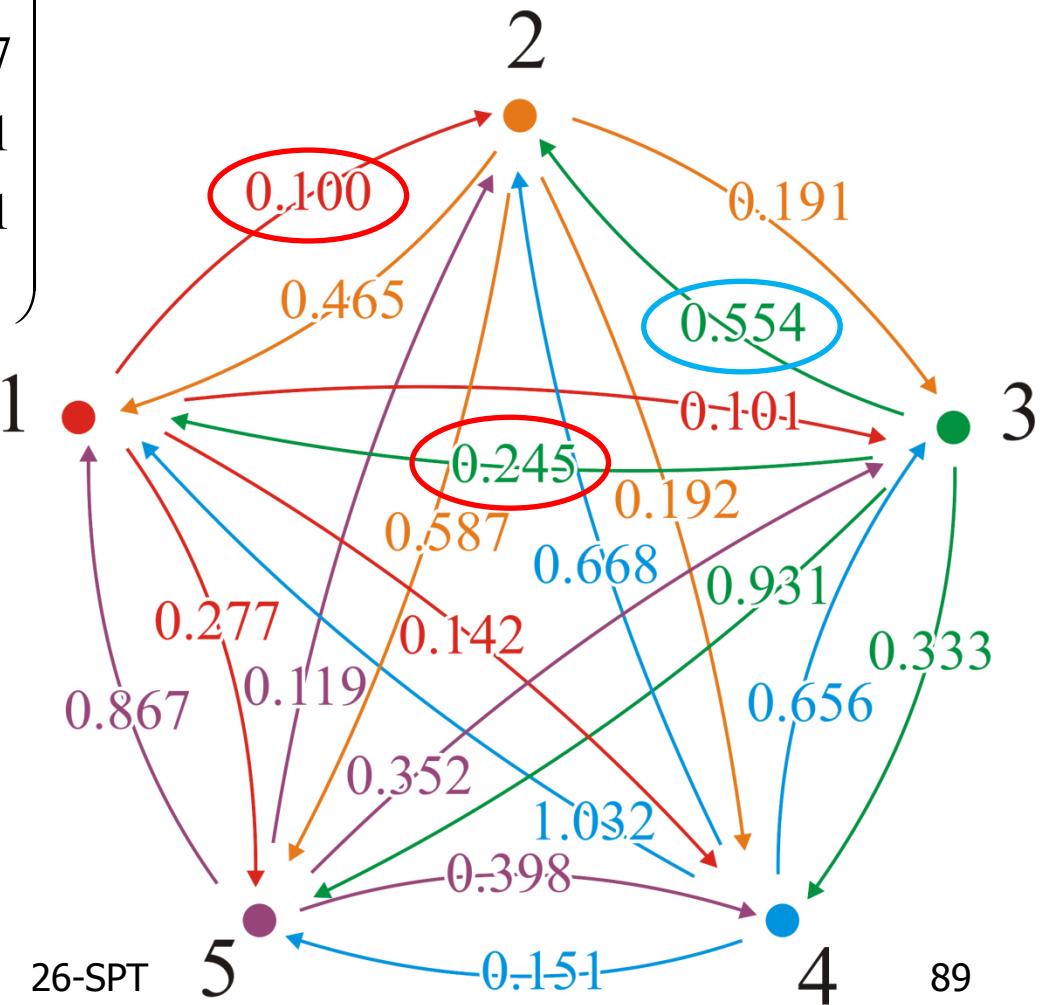
First attempt passing through vertex 1

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.554	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

Here is a shorter path:

$$(3, 2) \rightarrow (3, 1, 2)$$

$$0.554 > 0.245 + 0.100 = 0.345$$



# Floyd's Algorithm – Another Example

First attempt passing through vertex 1

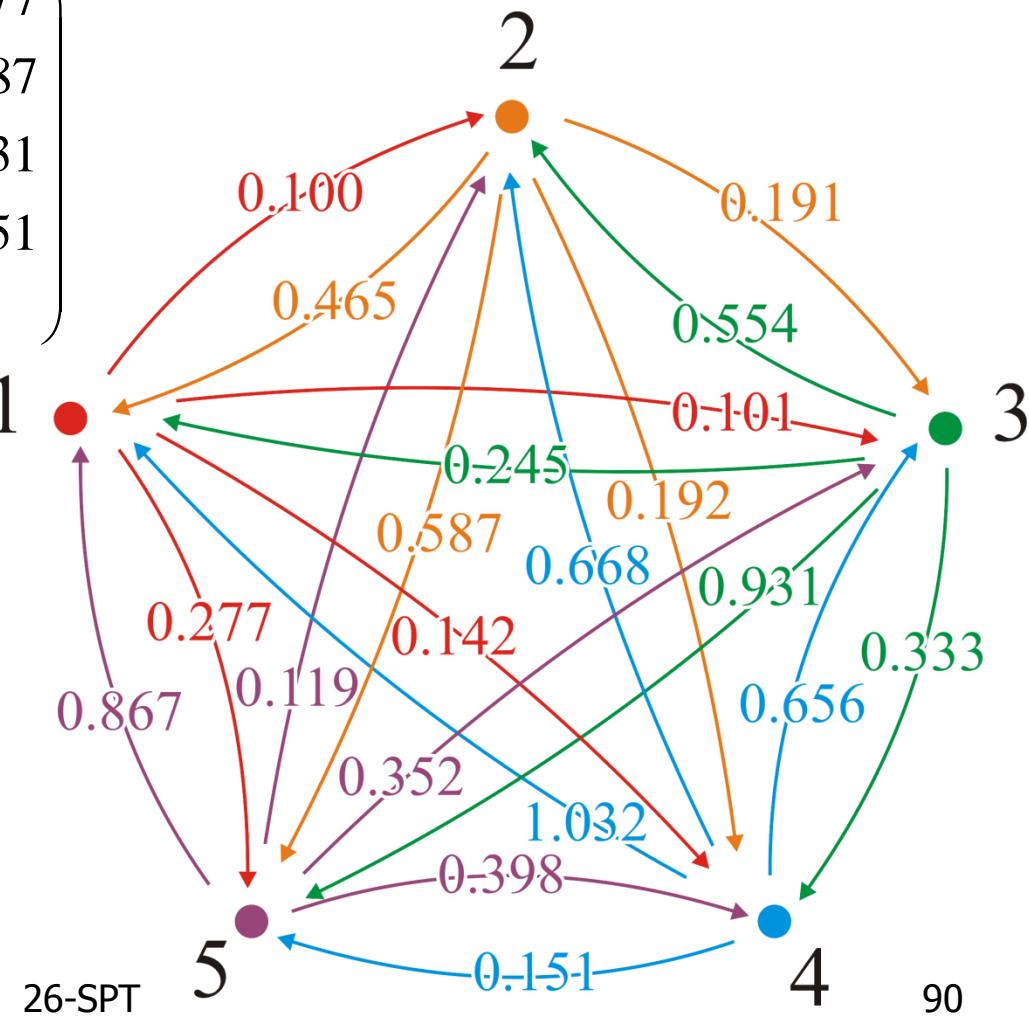
0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

Here is a shorter path:

$$(3, 2) \rightarrow (3, 1, 2)$$

$$0.554 > 0.245 + 0.100 = 0.345$$

**We can update matrix!**



# Floyd's Algorithm – Another Example

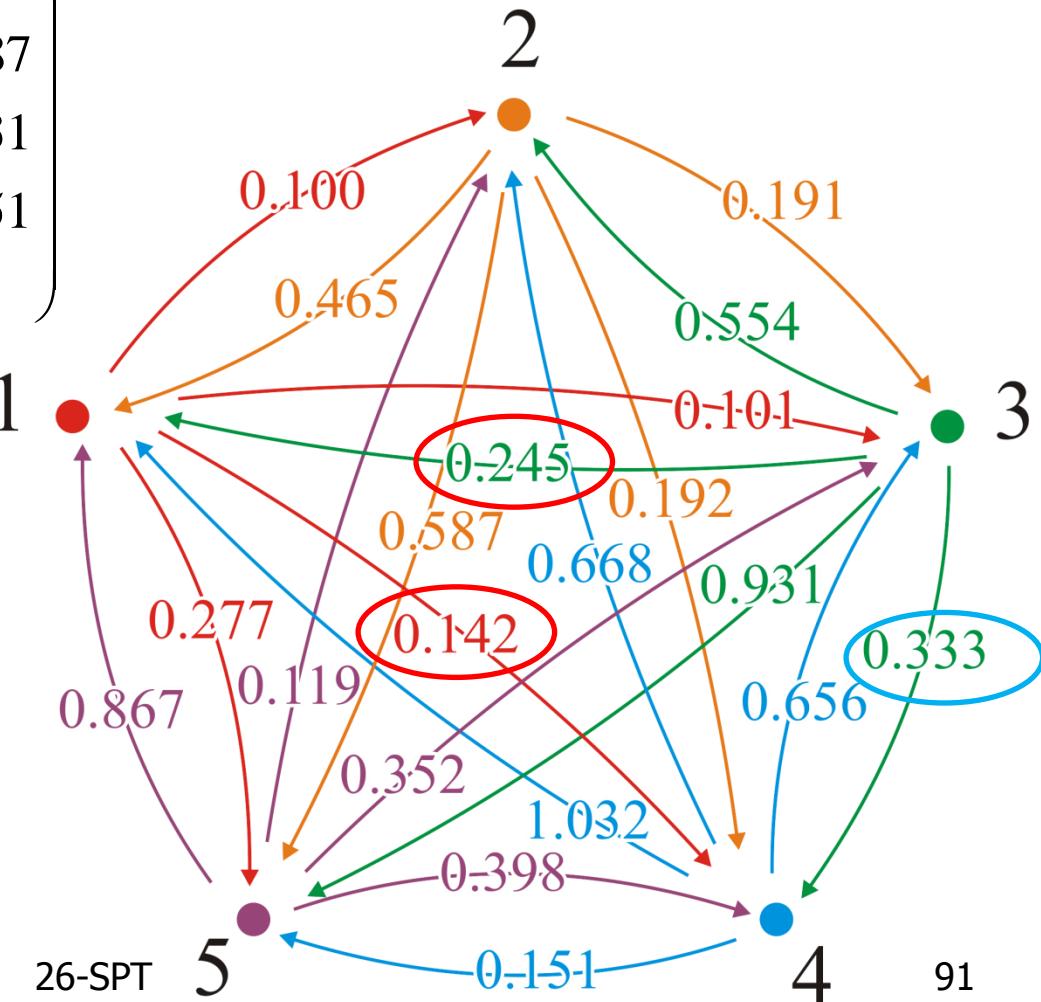
First attempt passing through vertex 1

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

We can check:

$$(3, 4) \rightarrow (3, 1, 4)$$

$$0.333 \not> 0.245 + 0.142$$



# Floyd's Algorithm – Another Example

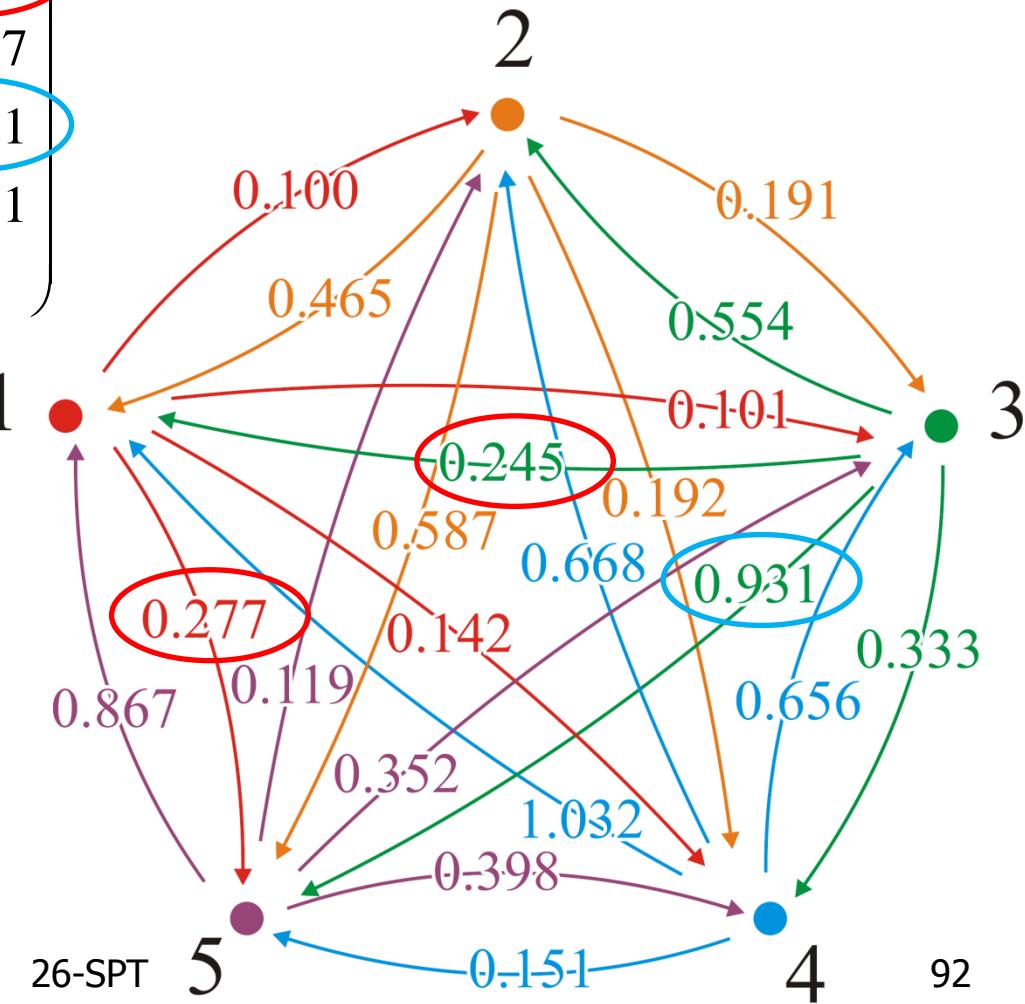
First attempt passing through vertex 1

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

Another shorter path:

$$(3, 5) \rightarrow (3, 1, 5)$$

$$0.931 > 0.245 + 0.277 = 0.522$$



# Floyd's Algorithm – Another Example

First attempt passing through vertex 1

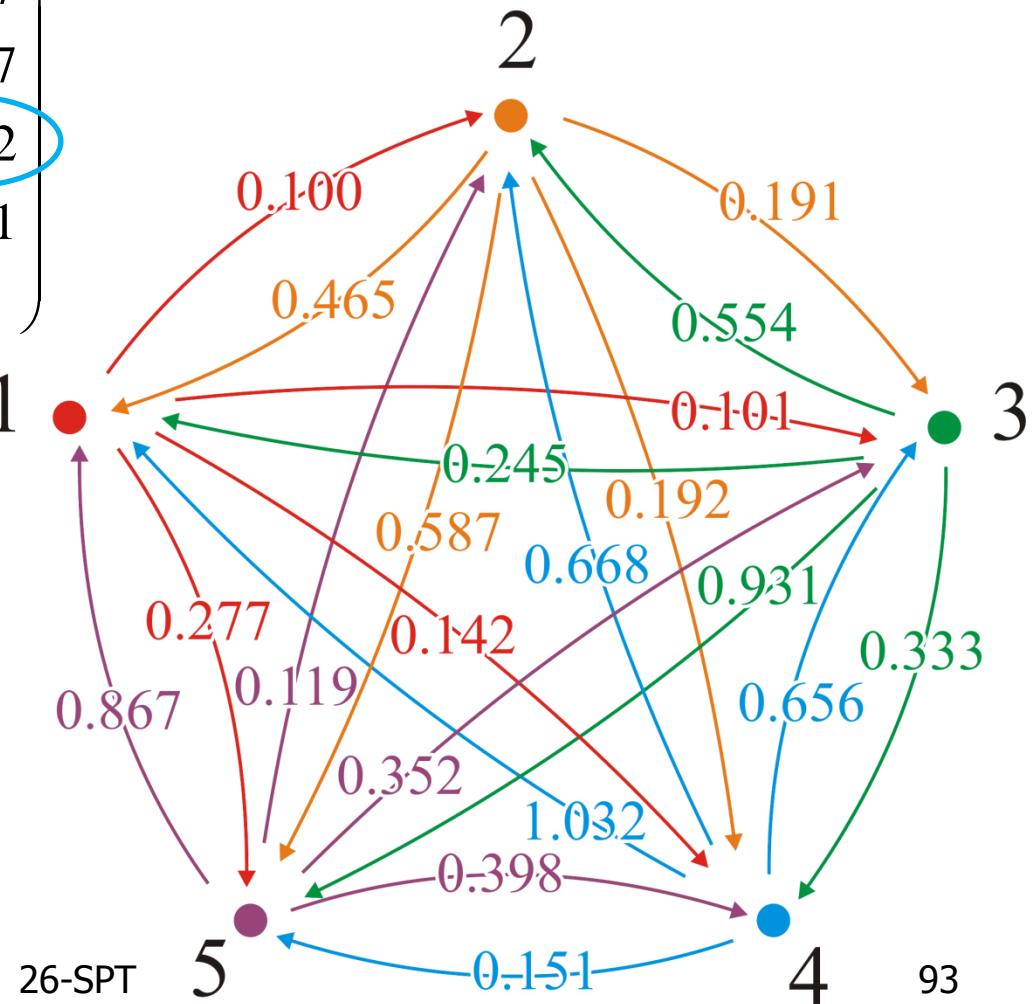
0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.522
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

Another shorter path:

$$(3, 5) \rightarrow (3, 1, 5)$$

$$0.931 > 0.245 + 0.277 = 0.522$$

**We can update matrix!**



# Floyd's Algorithm – Another Example

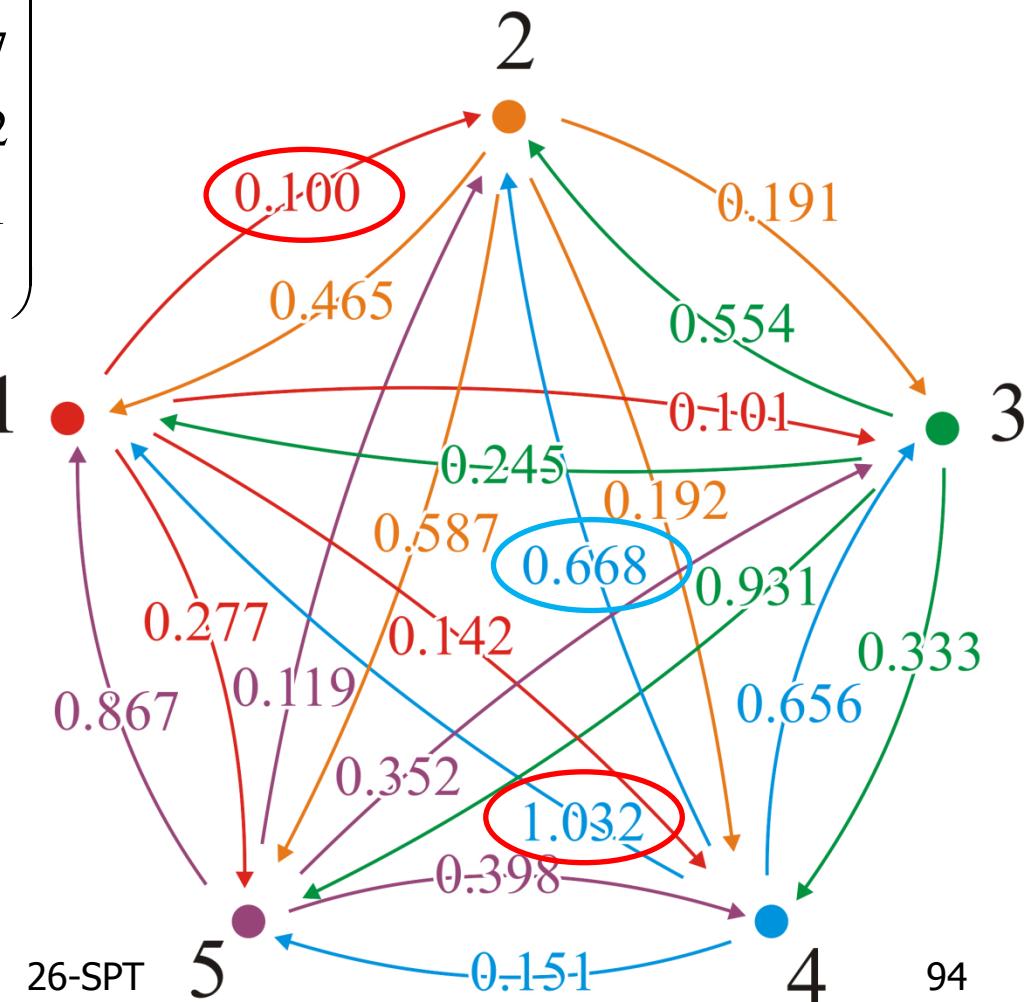
# First attempt passing through vertex 1

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.522
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

## Continuing:

$$(4, 2) \rightarrow (4, 1, 2)$$

**In fact, no other shorter paths through vertex 1 exist!**



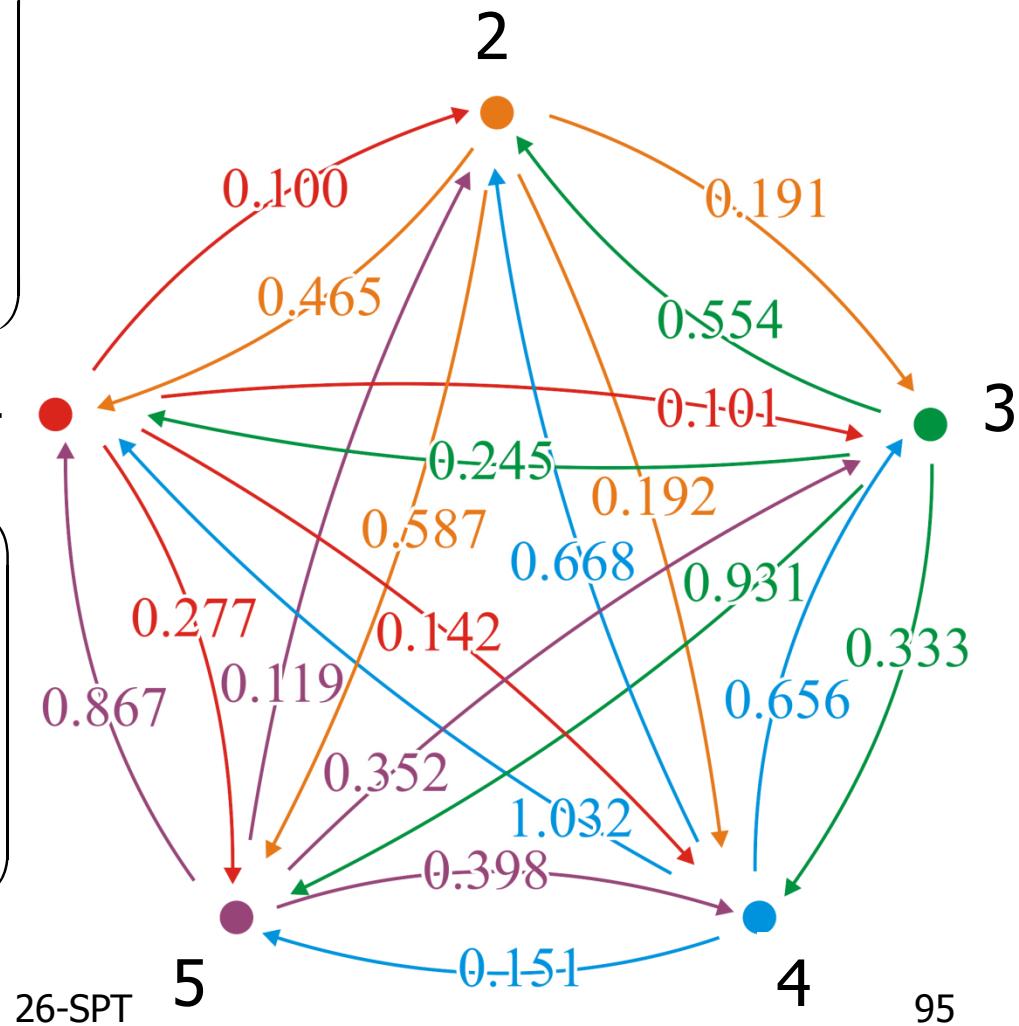
# Floyd's Algorithm – Another Example

The D<sup>0</sup> matrix

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.554	0	0.333	0.931
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

The D<sup>1</sup> matrix

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.522
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0



# Floyd's Algorithm – Another Example

Now attempt passing through vertex 2

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.522
1.032	0.668	0.656	0	0.151
0.867	0.119	0.352	0.398	0

There are three shorter paths:

$$(5, 1) \rightarrow (5, 2, 1)$$

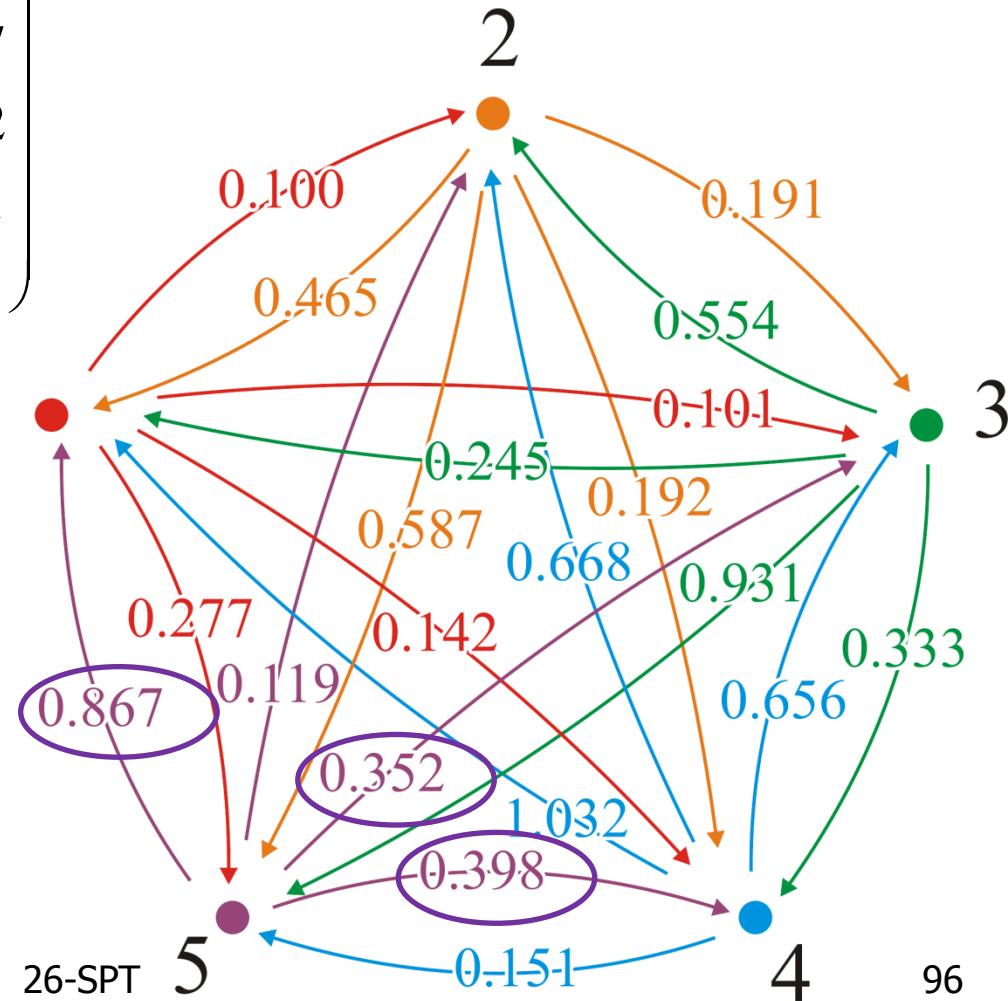
$$0.867 > 0.119 + 0.465 = 0.584$$

$$(5, 3) \rightarrow (5, 2, 3)$$

$$0.352 > 0.119 + 0.191 = 0.310$$

$$(5, 4) \rightarrow (5, 2, 4)$$

$$0.398 > 0.119 + 0.192 = 0.311$$

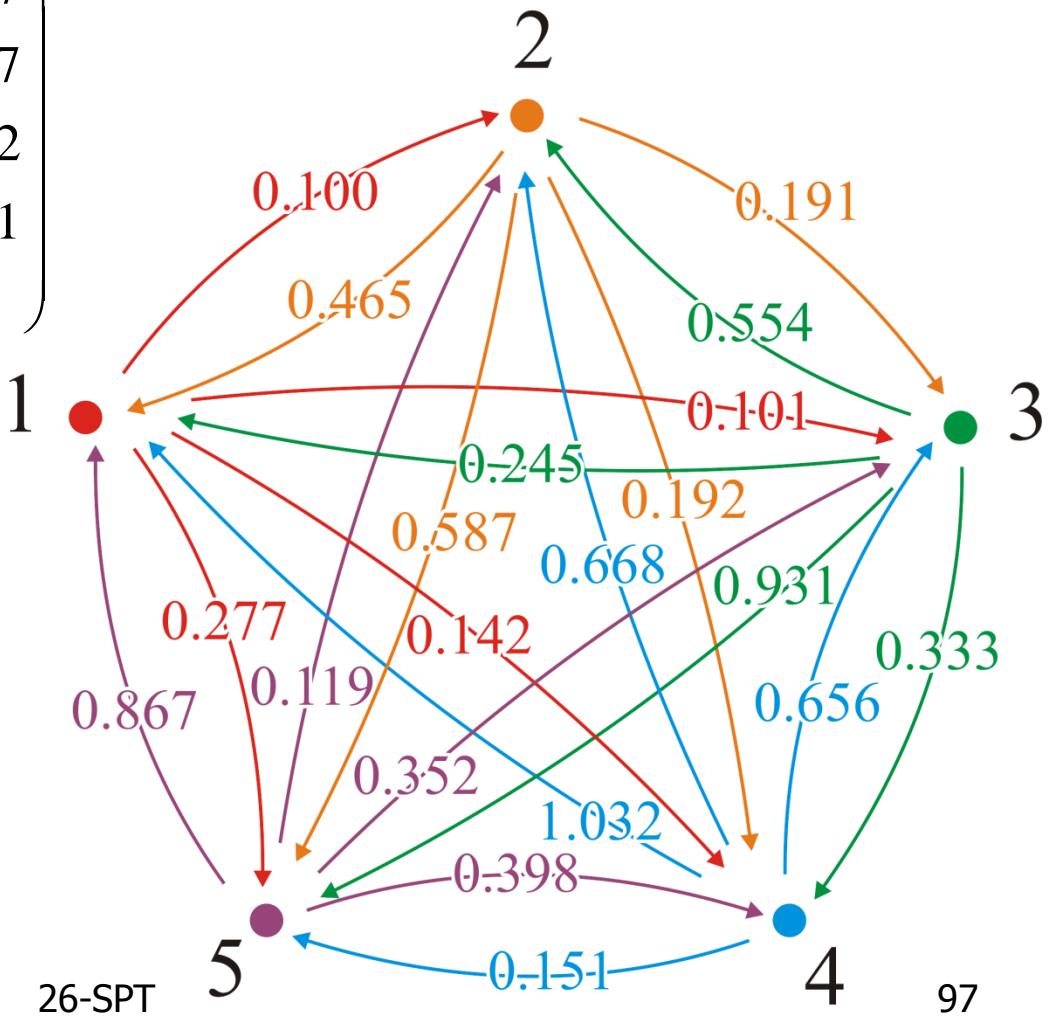


# Floyd's Algorithm – Another Example

Now attempt passing through vertex 2

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.522
1.032	0.668	0.656	0	0.151
0.584	0.119	0.310	0.311	0

We can update matrix  
to get  $D^2$



# Floyd's Algorithm – Another Example

Now attempt passing through vertex 3

0	0.100	0.101	0.142	0.277
0.465	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.522
1.032	0.668	0.656	0	0.151
0.584	0.119	0.310	0.311	0

There are three shorter paths:

$$(2, 1) \rightarrow (2, 3, 1)$$

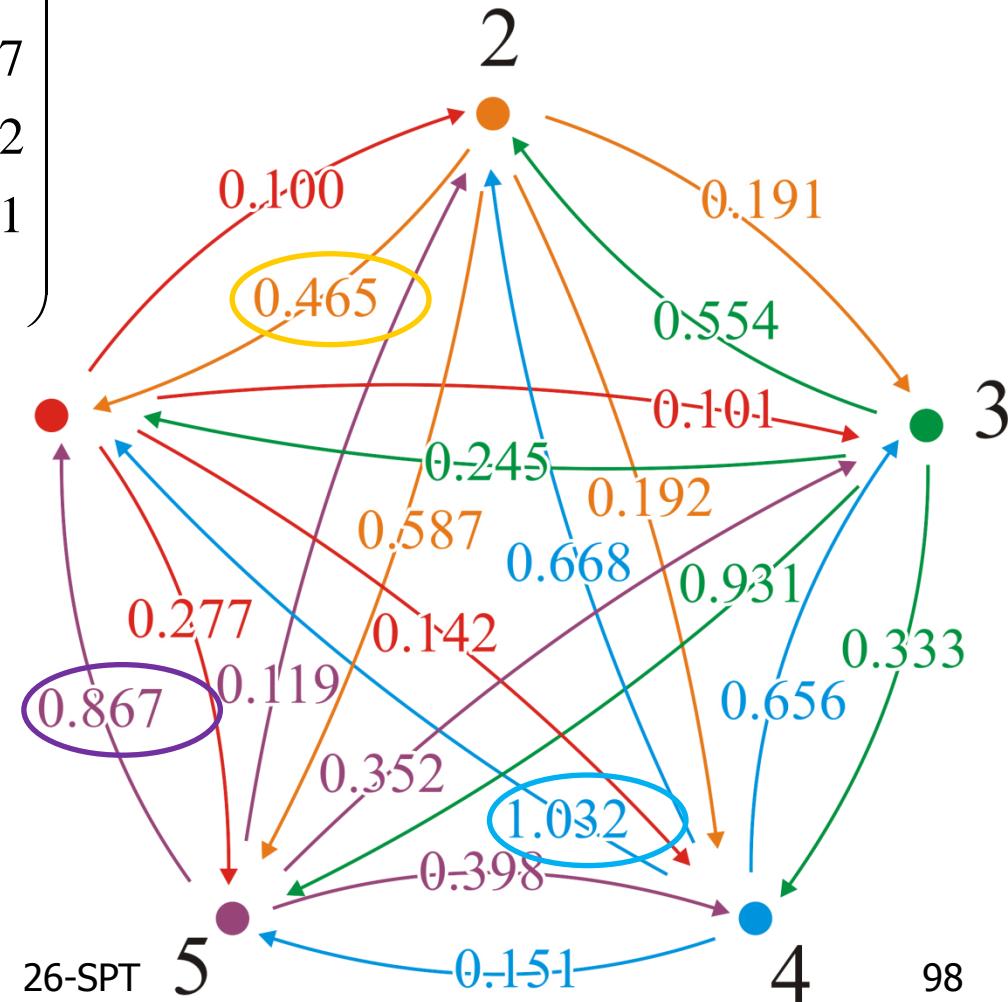
$$0.465 > 0.191 + 0.245 = 0.436$$

$$(4, 1) \rightarrow (4, 3, 1)$$

$$1.032 > 0.656 + 0.245 = 0.901$$

$$(5, 1) \rightarrow (5, 3, 1)$$

$$0.584 > 0.310 + 0.245 = 0.555$$

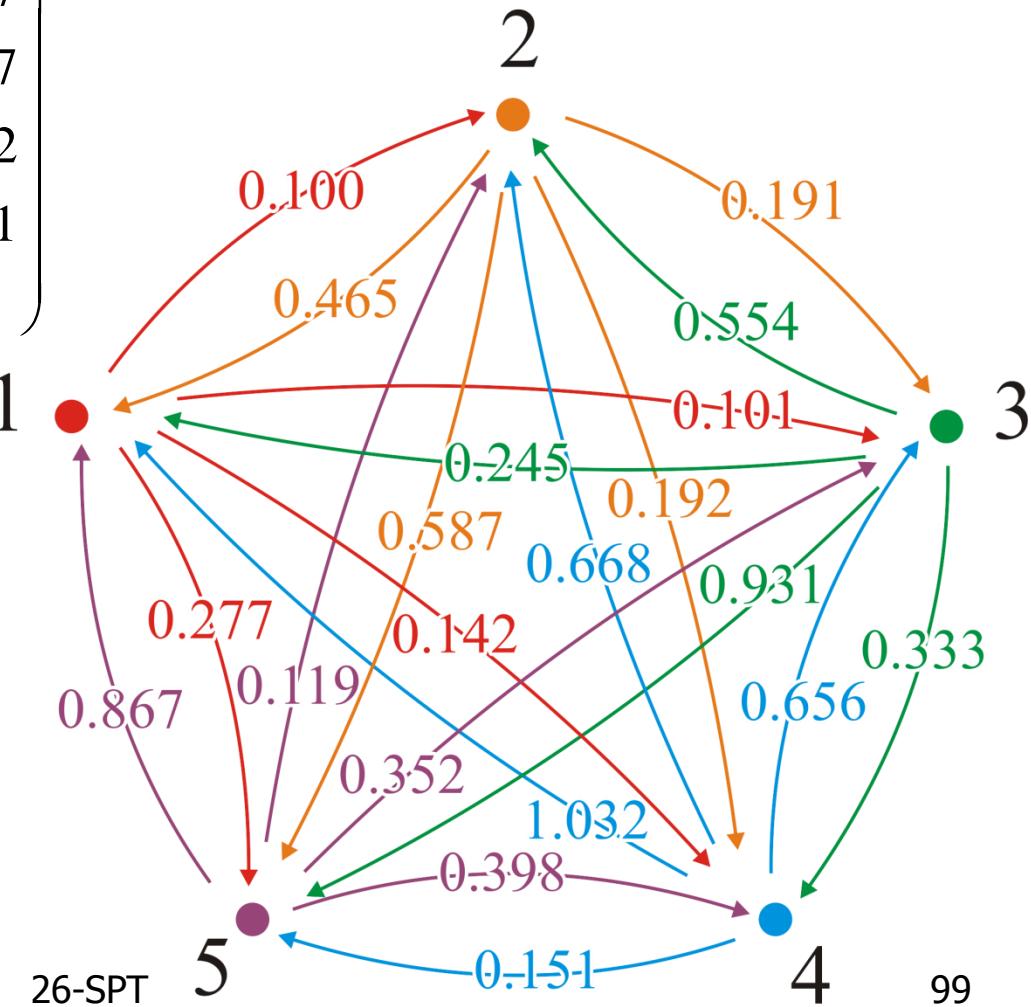


# Floyd's Algorithm – Another Example

Now attempt passing through vertex 3

0	0.100	0.101	0.142	0.277
0.436	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.522
0.901	0.668	0.656	0	0.151
0.555	0.119	0.310	0.311	0

We can update matrix  
to get  $D^3$



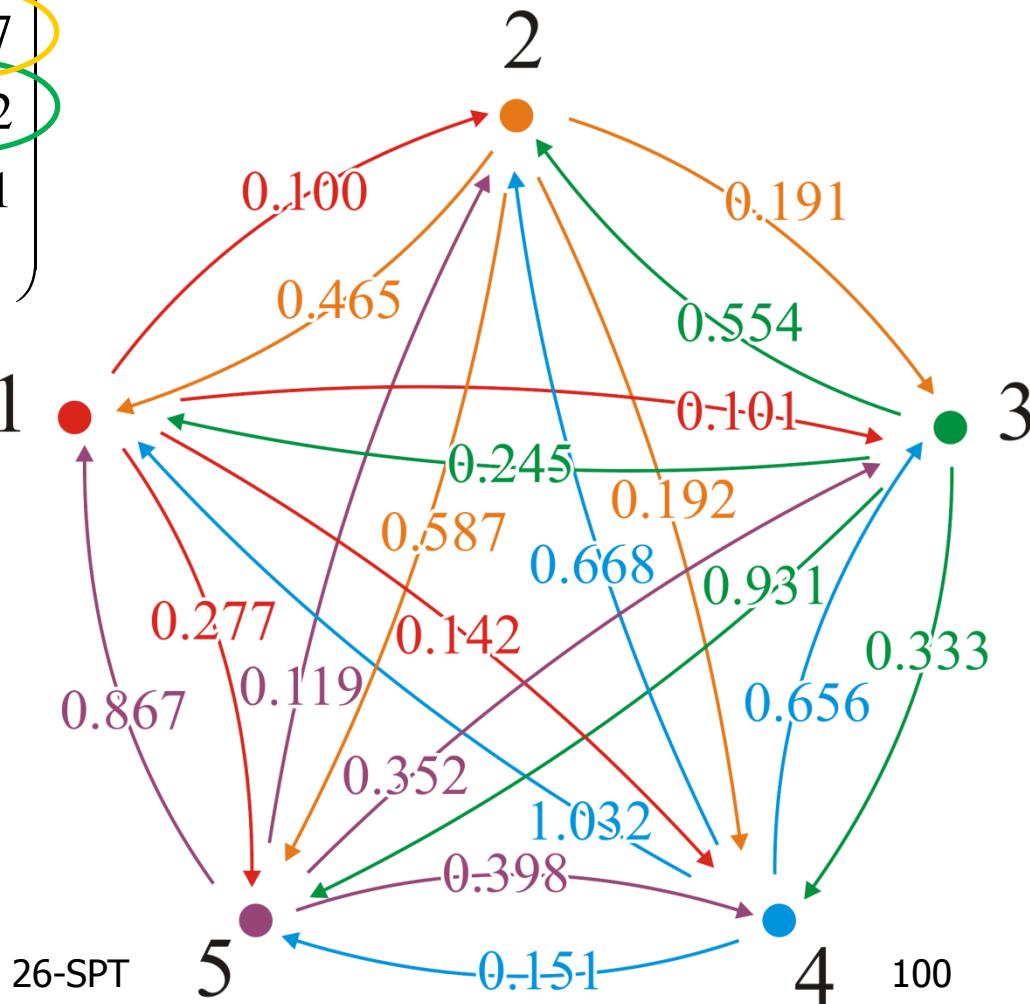
# Floyd's Algorithm – Another Example

Now attempt passing through vertex 4

0	0.100	0.101	0.142	0.277
0.436	0	0.191	0.192	0.587
0.245	0.345	0	0.333	0.522
0.901	0.668	0.656	0	0.151
0.555	0.119	0.310	0.311	0

There are two shorter paths:  
 $(2, 5) \rightarrow (2, 4, 5)$   
 $0.587 > 0.192 + 0.151$

$(3, 5) \rightarrow (3, 4, 5)$   
 $0.522 > 0.333 + 0.151$

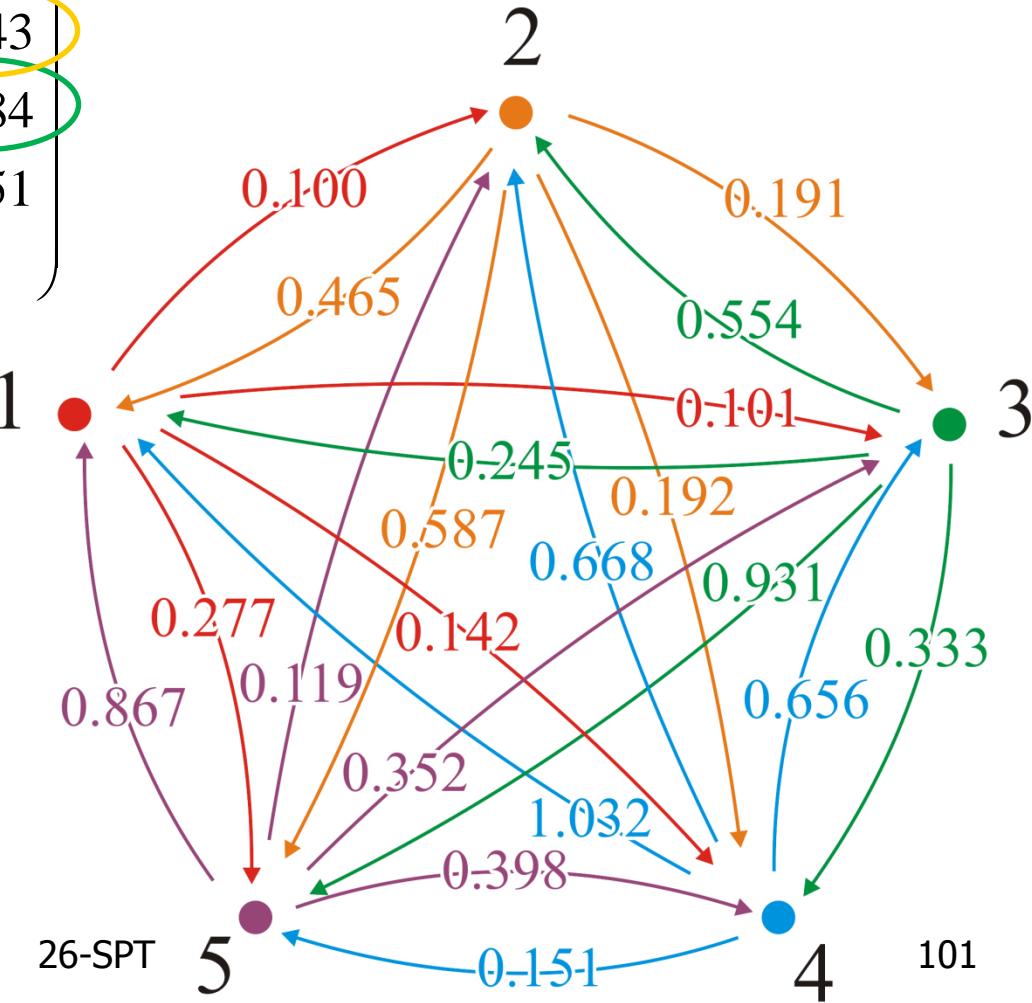


# Floyd's Algorithm – Another Example

Now attempt passing through vertex 4

0	0.100	0.101	0.142	0.277
0.436	0	0.191	0.192	0.343
0.245	0.345	0	0.333	0.484
0.901	0.668	0.656	0	0.151
0.555	0.119	0.310	0.311	0

We can update matrix  
to get  $D^4$



# Floyd's Algorithm – Another Example

Now attempt passing through vertex 5

0	0.100	0.101	0.142	0.277
0.436	0	0.191	0.192	0.343
0.245	0.345	0	0.333	0.484
0.901	0.668	0.656	0	0.151
0.555	0.119	0.310	0.311	0

There are two shorter paths:

$$(4, 1) \rightarrow (4, 5, 1)$$

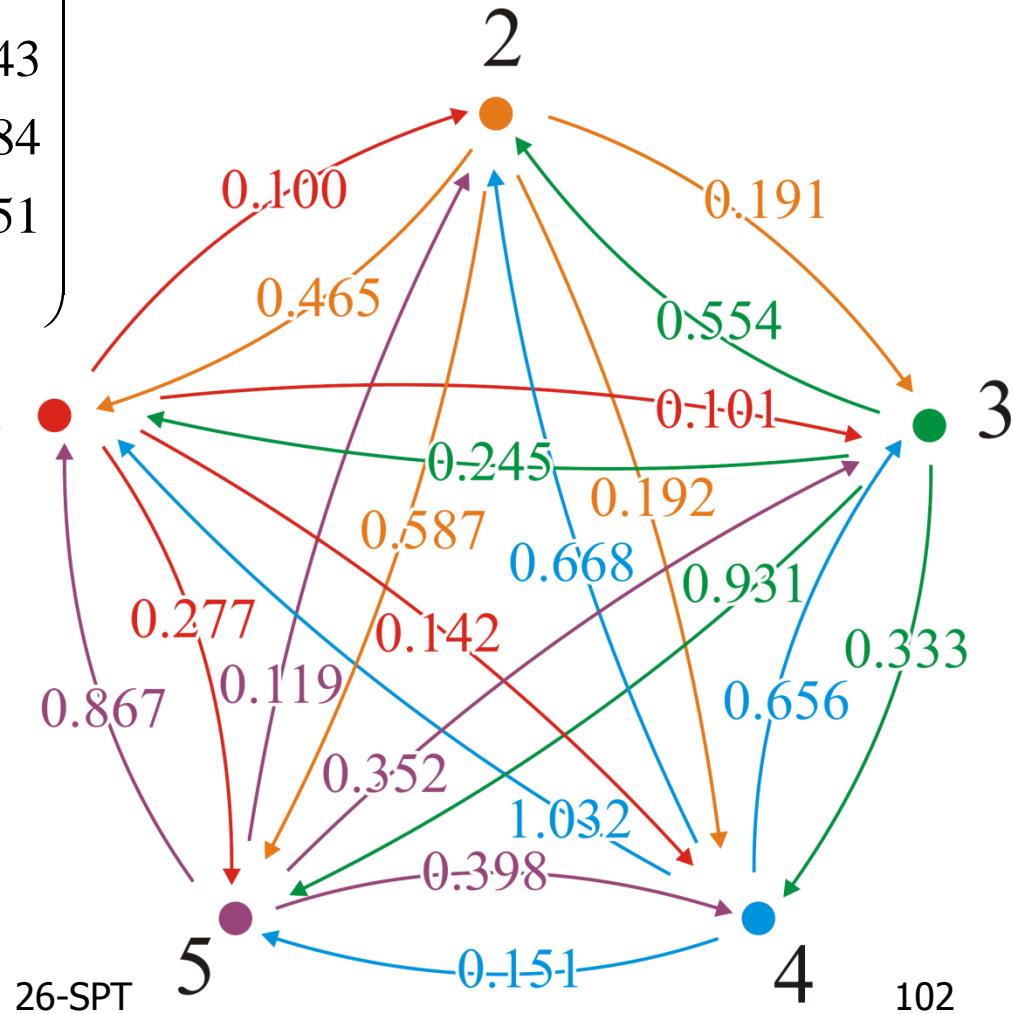
$$0.901 > 0.151 + 0.555 = 0.706$$

$$(4, 2) \rightarrow (4, 5, 2)$$

$$0.668 > 0.151 + 0.119 = 0.270$$

$$(4, 3) \rightarrow (4, 5, 3)$$

$$0.656 > 0.151 + 0.310 = 0.461$$



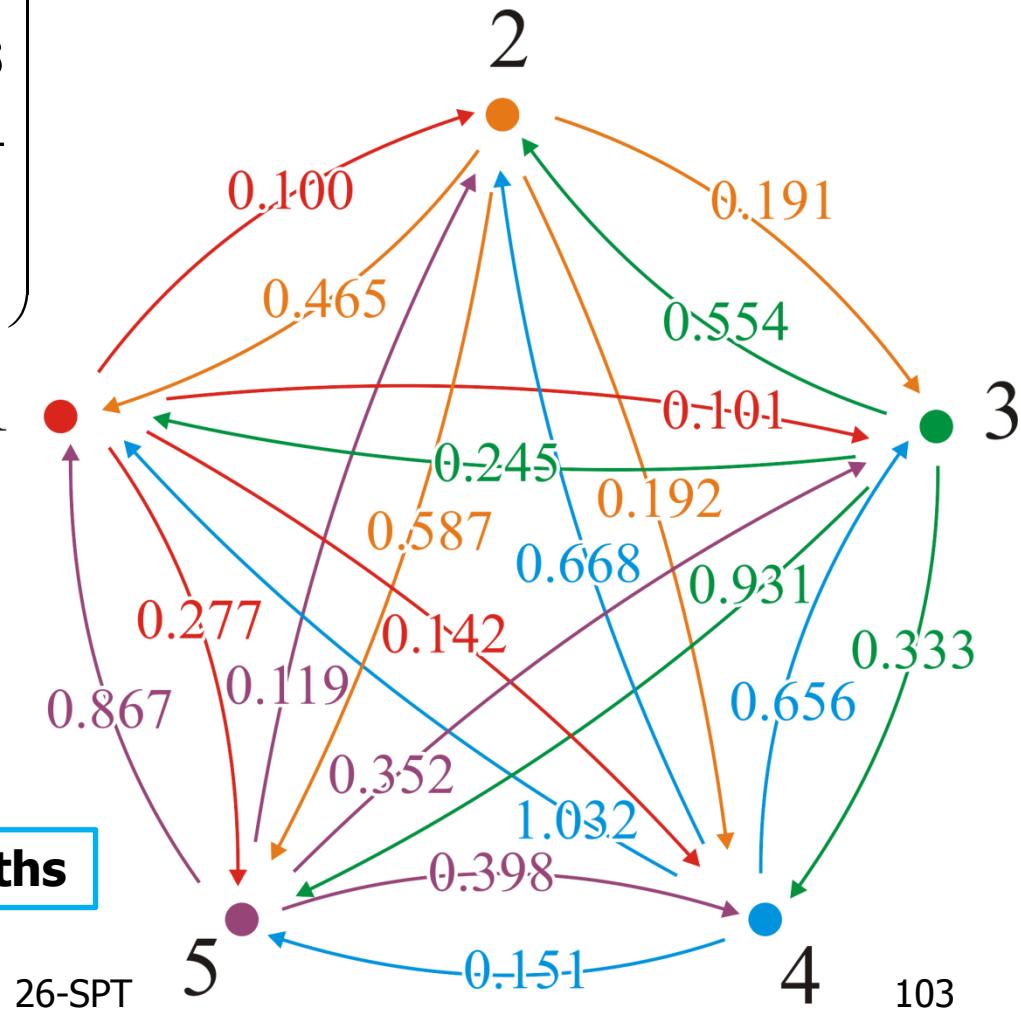
# Floyd's Algorithm – Another Example

Now attempt passing through vertex 5

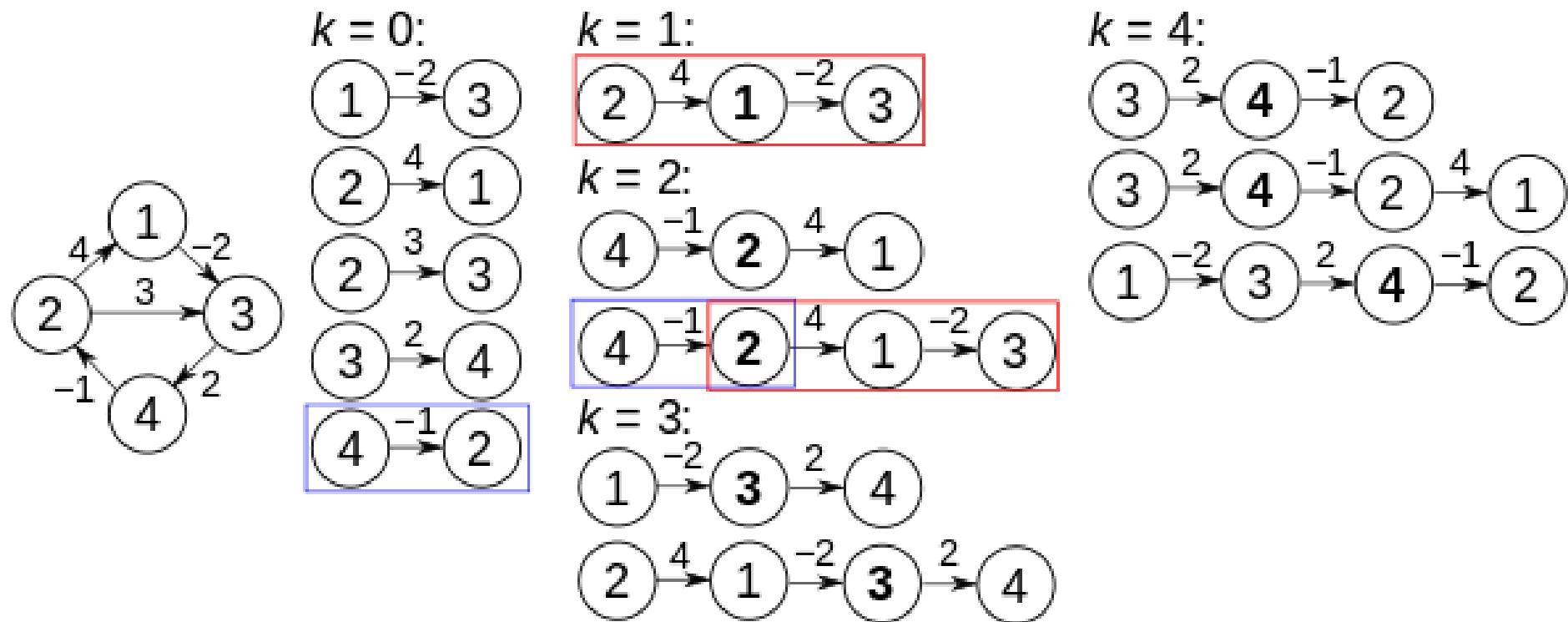
0	0.100	0.101	0.142	0.277
0.436	0	0.191	0.192	0.343
0.245	0.345	0	0.333	0.484
0.706	0.270	0.461	0	0.151
0.555	0.119	0.310	0.311	0

We can update matrix  
to get  $D^5$

Thus, we have all pairs shortest paths



# All Pairs Shortest Paths – Yet Another Example



# Any Question So Far?

---

