

## Exercise # 7.1 Orthogonal Matrices Date \_\_\_\_\_

Definition: A square matrix  $A$  is said to be orthogonal if its transpose is the same as its inverse. i.e if

$$A^{-1} = A^T$$

or equivalently, if

$$AA^T = A^TA = I$$

A matrix transformation  $T_A : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is said to be an orthogonal transformation or an orthogonal operator if  $A$  is an orthogonal matrix.

Example #01  $3 \times 3$  Orthogonal Matrix

$$A = \begin{bmatrix} \frac{3}{7} & \frac{2}{7} & \frac{6}{7} \\ \frac{2}{7} & \frac{3}{7} & \frac{2}{7} \\ \frac{6}{7} & \frac{2}{7} & \frac{-3}{7} \end{bmatrix} \quad \text{is orthogonal because:}$$

$$A^T \cdot A = \begin{bmatrix} \frac{3}{7} & \frac{2}{7} & \frac{6}{7} \\ \frac{2}{7} & \frac{3}{7} & \frac{2}{7} \\ \frac{6}{7} & \frac{2}{7} & \frac{-3}{7} \end{bmatrix} \begin{bmatrix} \frac{3}{7} & \frac{2}{7} & \frac{6}{7} \\ \frac{2}{7} & \frac{3}{7} & \frac{2}{7} \\ \frac{6}{7} & \frac{2}{7} & \frac{-3}{7} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Example #02: Rotation and Reflection Matrices are Orthogonal

$$A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$A^T \cdot A = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

ROW VECTORS & COL. VECTORS FORM ORTHONORMAL SETS W.R.T  
THE EUCLIDEAN INNER PRODUCT.

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Following are equivalent for an  $n \times n$  matrix A

- a) A is orthogonal.
- b) The row vectors of A form an orthonormal set in  $\mathbb{R}^n$  with the Euclidean inner product.
- c) The column vectors of A form an orthonormal set in  $\mathbb{R}^n$  with the euclidean inner product.

x                    x

- a) The transpose of an orthogonal matrix is orthogonal.
- b) The ~~trans~~ inverse of an orthogonal matrix is orthogonal.
- c) A product of orthogonal matrices is orthogonal.
- d) If A is orthogonal, then  $\det(A) = \pm 1$

Example # 03 :  $\det(A) = \pm 1$  for an Orthogonal Matrix A

$$A = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\det(A) = \frac{1}{2} + \frac{1}{2} = \frac{2}{2} = 1 \quad \text{orthogonal.}$$

Properties of Orthogonal Transformations

If A is an  $n \times n$  matrix, then following are equivalent :

- a) A is orthogonal
- b)  $\|Ax\| = \|x\|$  for all  $x$  in  $\mathbb{R}^n$
- c)  $Ax \cdot Ay = x \cdot y$  for all  $x$  and  $y$  in  $\mathbb{R}^n$ .

Exercise # 7.1

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In each part of exercise 1-4, determine whether the matrix is orthogonal, and if so find its inverse

$$1. \quad a. \quad A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \text{ orthogonal}$$

$$A^{-1} = A^T$$

$$A^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$b. \quad A = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$A^T A = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} + \frac{1}{2} & -\frac{1}{2} + \frac{1}{2} \\ -\frac{1}{2} + \frac{1}{2} & \frac{1}{2} + \frac{1}{2} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \text{ orthogonal}$$

$$A^{-1} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$2. \quad a. \quad A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1+0 & 0+0 \\ 0+0 & 0+1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \text{ orthogonal}$$

$$A^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

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$$b. \quad A = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}$$

$$\begin{aligned} A^T \cdot A &= \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix} = \begin{bmatrix} \frac{1}{5} + \frac{4}{5} & \frac{2}{5} + \frac{2}{5} \\ \frac{2}{5} + \frac{2}{5} & \frac{4}{5} + \frac{1}{5} \end{bmatrix} \\ &= \begin{bmatrix} 1 & \frac{4}{5} \\ \frac{4}{5} & 1 \end{bmatrix} \text{ not orthogonal} \end{aligned}$$

$$3. \quad a. \quad A = \begin{vmatrix} 0 & 1 & \frac{1}{\sqrt{2}} \\ 1 & 0 & 0 \\ 0 & 0 & \frac{1}{\sqrt{2}} \end{vmatrix}$$

$$A^T \cdot A = \begin{vmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{vmatrix} \begin{vmatrix} 0 & 1 & \frac{1}{\sqrt{2}} \\ 1 & 0 & 0 \\ 0 & 0 & \frac{1}{\sqrt{2}} \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$A^{-1} = A^T \quad \text{orthogonal.}$$

$$A^{-1} = \begin{vmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{vmatrix}$$

$$b. \quad A = \begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} & -\frac{1}{2} & 0 \\ 0 & \frac{1}{\sqrt{3}} & 0 & 1 \\ 0 & \frac{1}{\sqrt{3}} & \frac{1}{2} & 0 \end{vmatrix}$$

$$A^T \cdot A = \begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ 0 & -\frac{1}{2} & 0 & \frac{1}{2} \\ 0 & 0 & 1 & 0 \end{vmatrix} \begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} & -\frac{1}{2} & 0 \\ 0 & \frac{1}{\sqrt{3}} & 0 & 1 \\ 0 & \frac{1}{\sqrt{3}} & \frac{1}{2} & 0 \end{vmatrix}$$

not orthogonal.

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

not orthogonal matrix.

So,  $A^{-1} = A^T =$

Q5. In exercise 5-6, show that the matrix is orthogonal three ways,  
first by calculating  $A^T A$ , then by using part (b) and (c) of  
Theorem 7.1.1

$$A = \begin{bmatrix} \frac{4}{5} & 0 & -\frac{3}{5} \\ -\frac{9}{25} & \frac{4}{5} & -\frac{12}{25} \\ \frac{12}{25} & \frac{3}{5} & \frac{16}{25} \end{bmatrix}$$

$$A^T A = \begin{bmatrix} \frac{4}{5} & 0 & -\frac{3}{5} \\ -\frac{9}{25} & \frac{4}{5} & -\frac{12}{25} \\ \frac{12}{25} & \frac{3}{5} & \frac{16}{25} \end{bmatrix} \begin{bmatrix} \frac{4}{5} & -\frac{9}{25} & \frac{12}{25} \\ 0 & \frac{4}{5} & \frac{3}{5} \\ -\frac{3}{5} & -\frac{12}{25} & \frac{16}{25} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$r_1 = \left[ \frac{4}{5}, 0, -\frac{3}{5} \right], r_2 = \left[ \frac{9}{25}, \frac{4}{5}, -\frac{12}{25} \right]$$

$$r_3 = \left[ \frac{12}{25}, \frac{3}{5}, \frac{16}{25} \right]$$

$$\langle r_1, r_2 \rangle = \frac{4}{5} \times \frac{9}{25} + 0 \times \frac{4}{5} + \left( -\frac{3}{5} \right) \left( -\frac{12}{25} \right) = 0$$

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$$\langle r_1, r_3 \rangle = 0 \quad \langle r_2, r_3 \rangle = 0$$

$$\text{and } \|r_1\| = \|r_2\| = \|r_3\| = 1$$

column vectors :

$$c_1 = \begin{bmatrix} 4/5 \\ -9/25 \\ 12/25 \end{bmatrix} \quad c_2 = \begin{bmatrix} 0 \\ 4/5 \\ 3/5 \end{bmatrix} \quad c_3 = \begin{bmatrix} -3/5 \\ -12/25 \\ 16/25 \end{bmatrix}$$

$$\langle c_1, c_2 \rangle = \frac{4}{5} \times 0 + \frac{4}{5} \times \frac{-9}{25} + \frac{3}{5} \times \frac{12}{25} = 0$$

$$\langle c_2, c_3 \rangle = 0 \quad \langle c_1, c_3 \rangle = 0$$

$$\text{and } \|c_1\| = \|c_2\| = \|c_3\| = 1$$

Q7. Let  $T_A : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be multiplication by the orthogonal matrix in exercise 5. Find  $T_A(x)$  for the vector  $x = (-2, 3, 5)$  and confirm that  $\|T_A(x)\| = \|x\|$  relative to the euclidean inner product.

$$T_A(x) = \begin{bmatrix} \frac{4}{5} & 0 & \frac{-3}{5} \\ \frac{-9}{25} & \frac{4}{5} & \frac{-12}{25} \\ \frac{12}{25} & \frac{3}{5} & \frac{16}{25} \end{bmatrix} \begin{bmatrix} -2 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} \frac{-23}{5} \\ \frac{18}{25} \\ \frac{101}{25} \end{bmatrix}$$

$$\|T_A(x)\| = \sqrt{\frac{529}{25} + \frac{324}{625} + \frac{10201}{625}} = \sqrt{38}$$

$$\|x\| = \sqrt{4 + 9 + 25} = \sqrt{38}$$

## QUADRATIC FORMS

$$a_1 x_1^2 + a_2 x_2^2 + 2a_3 x_1 x_2$$

$$a_1 x_1^2 + a_2 x_2^2 + a_3 x_3^2 + 2a_4 x_1 x_2 + 2a_5 x_1 x_3 + 2a_6 x_2 x_3$$

$$a_1 x_1^2 + a_2 x_2^2 + \dots + a_n x_n^2 + (\text{all possible terms } a_k x_i x_j \text{ in which } i \neq j)$$

The terms of the form  $a_k x_i x_j$  in which  $i \neq j$  are called cross product terms.

## ASSOCIATED QUADRATIC FORM

$$x^T A x = x \cdot A x = Ax \cdot x$$

$$x^T A x = [x_1, x_2, \dots, x_n] \begin{bmatrix} x_1 & 0 & 0 & \cdots & x_1 \\ 0 & x_2 & & & x_2 \\ 0 & & \ddots & & \vdots \\ 0 & & & \ddots & x_n \end{bmatrix}$$

$$= \lambda_1 x_1^2 + \lambda_2 x_2^2 + \dots + \lambda_n x_n^2$$

Example #01: Expressing Quadratic forms in Matrix Notation  
 In each part, express the quadratic form in the matrix notation  $x^T A x$ , where A is symmetric.

$$(a) 2x^2 + 6xy - 5y^2$$

The diagonal entries of A are the coefficients of the squared terms and the off-diagonal entries are half the coefficients of the cross product terms, so

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$$2x^2 + 6xy - 5y^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 3 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

(b)  $x_1^2 + 7x_2^2 - 3x_3^2 + 4x_1x_2 - 2x_1x_3 + 8x_2x_3$

$$= \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \left[ \begin{array}{ccc|c} 1 & 2 & -1 & x_1 \\ 2 & 7 & 4 & x_2 \\ - & 4 & -3 & x_3 \end{array} \right]$$

Exercise # 7.3

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Q. 1-2: Express the quadratic form in the matrix notation  $x^T A x$ , where A is a symmetric matrix.

1. a.  $3x_1^2 + 7x_2^2$

$$= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

b.  $4x_1^2 - 9x_2^2 - 6x_1x_2$

$$= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 4 & -3 \\ -3 & -9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

c.  $9x_1^2 - x_2^2 + 4x_3^2 + 6x_1x_2 - 8x_1x_3 + x_2x_3$

$$= \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 9 & 3 & -4 \\ 3 & -1 & \frac{1}{2} \\ -4 & \frac{1}{2} & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

2. a.  $5x_1^2 + 5x_1x_2 = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 5 & \frac{5}{2} \\ \frac{5}{2} & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

b.  $-7x_1x_2 = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 0 & -\frac{7}{2} \\ -\frac{7}{2} & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

c.  $x_1^2 + x_2^2 - 3x_3^2 - 5x_1x_2 + 9x_1x_3$

$$= \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 1 & \frac{5}{2} & \frac{9}{2} \\ \frac{5}{2} & 1 & 0 \\ \frac{9}{2} & 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

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Q 3-4: Find a formula for the quadratic form that does not use matrices.

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 2 & -3 \\ -3 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 2x_1^2 + 5x_2^2 - 6xy$$

$$\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} -2 & 1/2 & 1 \\ 1/2 & 0 & 6 \\ 1 & 6 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = -2x_1^2 + 3x_3^2 + 7x_1x_2 + 2x_1x_3 + 12x_2x_3$$