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| **FACTS** | **IDEAS** | **LEARNING ISSUES** | **ACTION** | **DATELINE** |
| What we know about the task | What do we need to find out? | | Who is going to do it? |  |
| GUI | User Access Level  Task Creation  Feedback  Camera – OpenCV, Websocket | | Yulin | Week 11 |
| Arduino Code | Integration with GUI  Calibration issue  X,y,z to angle inverse Kinetic library testing  G clamp | | Hafiidz, Chong Chia Hsing | Week 11 |
| Robotic Arm Testing | To implement the Arduino code and calibrate the robotic arm | | Hafiidz, Gary, Chong Chia Hsing | Week 11 |
| Test Case Implementation | To implement the test cases with SE team | | Chong Chia Hsing, Yulin, Gary, Hafiidz | Week 12 |
| SRS Version 2 | To rectify and update the SRS | | All team | Week 12 |
| Optimization – Genetic Algorithm | Aim is to optimize number of robotic arms based on task completion. | | Sarah | Week 12 |
| Test Cases | SRS modification,  Test plan  Static Test Report | | SE Team, Gary | Week 12 |
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