

7.7书后习题答案

1.

(1)

$$\left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z} \right) \Big|_{(1,1,-2)} = (yz, xz, xy) \Big|_{(1,1,-2)} = (-2, -2, 1)$$

$$\hat{l} = \left(\frac{2}{3}, -\frac{1}{3}, \frac{2}{3} \right)$$

$$\Rightarrow \frac{\partial u}{\partial \hat{l}} = (-2, -2, 1) \cdot \left(\frac{2}{3}, -\frac{1}{3}, \frac{2}{3} \right) = 0$$

(2)

$$\text{grad } u = \nabla u = (3, 2z, 2z + 2y)$$

$$\text{grad } u \Big|_{(1,-2,2)} = (3, 4, 0)$$

\Rightarrow 方向导数最大值 5 最小值为 -5

2.

(1)

$$\text{div } \vec{v} = \nabla \cdot \vec{v} = 6x + 3y^2 + z^2 + xy - 6xz$$

$$\nabla \cdot \vec{v} \Big|_M = 6 + 16 - 14 = 8$$

(2)

$$\text{div } \vec{v} \Big|_M = \nabla \cdot \vec{v} \Big|_M = 2x \sin y + 2y \sin xz - \sin z \cdot xy \cdot \cos(\cos z)$$

3.

(1)

$$\text{div} [(\vec{r} \cdot \vec{w}) \vec{w}] = \nabla \cdot [(\vec{r} \cdot \vec{w}) \vec{w}] = (\vec{r} \cdot \vec{w}) (\nabla \cdot \vec{w}) + \vec{w} \cdot \nabla (\vec{r} \cdot \vec{w}) = \vec{w} \cdot \nabla (\vec{r} \cdot \vec{w}) = \vec{w} \cdot \vec{w}$$

(2)

$$\text{div} [(\vec{r} \cdot \vec{w}) \vec{r}] = \nabla \cdot [(\vec{r} \cdot \vec{w}) \vec{r}] = (\vec{r} \cdot \vec{w}) (\nabla \cdot \vec{r}) + \vec{r} \cdot \nabla (\vec{r} \cdot \vec{w}) = 3(\vec{r} \cdot \vec{w}) + \vec{r} \cdot \vec{w} = 4\vec{r} \cdot \vec{w}$$

(3)

$$\text{div} \left(\frac{\vec{r}}{r} \right) = \frac{1}{r} \nabla \cdot \vec{r} + \left(\nabla \frac{1}{r} \right) \cdot \vec{r} = \frac{3}{r} - \frac{\hat{r}}{r^2} \cdot \vec{r} = \frac{2}{r}$$

(4)

$$\text{div} (\vec{w} \times \vec{r}) = \nabla \cdot (\vec{w} \times \vec{r}) = \vec{r} \cdot (\nabla \times \vec{w}) - \vec{w} \cdot (\nabla \times \vec{r}) = 0 - 0 = 0$$

(5)

$$\operatorname{div} (r^2 \vec{w}) = \nabla (r^2 \vec{w}) = \nabla r^2 \cdot \vec{w} + r^2 (\nabla \cdot \vec{w}) = 2\vec{r} \cdot \vec{w}$$

(6)

$$\operatorname{div} [f(r) \vec{r}] = \nabla f(r) \cdot \vec{r} + f(r) (\nabla \cdot \vec{r}) = r f'(r) + 3f(r)$$

4.

(1)

$$\nabla \cdot \nabla \varphi = \nabla^2 \varphi = 6xy^4z^2 + 12x^3y^2z^2 + 2x^3y^4$$

(2)

$$\nabla u = ((x+1)yz e^{(x+y+z)}, (y+1)xze^{(x+y+z)}, (z+1)xye^{(x+y+z)})$$

$$\nabla \cdot \nabla u = (x+2)yz e^{(x+y+z)} + (y+2)xze^{(x+y+z)} + (z+2)xye^{(x+y+z)}$$

5.

(1)

$$\operatorname{rot} \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^2 & z^2 & x^2 \end{vmatrix} = -2z\vec{i} - 2x\vec{j} - 2y\vec{k}$$

(2)

$$\operatorname{rot} \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xe^y + y & e^y + z & y + 2ze^y \end{vmatrix} = 2ze^y \vec{i} - (1 + xe^y) \vec{k}$$

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(1)

$$\begin{aligned} \operatorname{rot} (\vec{w} \times \vec{r}) &= \nabla \times (\vec{w} \times \vec{r}) = \vec{w} (\nabla \cdot \vec{r}) + (\vec{r} \cdot \nabla) \vec{w} - (\nabla \cdot \vec{w}) \vec{r} - \vec{w} \cdot \nabla \vec{r} \\ &= 3\vec{w} + 0 - 0 - \vec{w} = 2\vec{w} \end{aligned}$$

(2)

$$\operatorname{rot} [f(r) \vec{r}] = \nabla f(r) \times \vec{r} + f(r) (\nabla \times \vec{r}) = 0 + 0 = 0$$

(3)

$$\operatorname{rot} [f(r) \vec{w}] = \nabla f(r) \times \vec{w} + f(r) (\nabla \times \vec{w}) = f'(r) \cdot \hat{r} \times \vec{w} = \frac{1}{r} f'(r) (\vec{r} \times \vec{w})$$

(4)

用张量做

$$\begin{aligned}
& \text{设用 } \frac{\partial}{\partial x_p} \text{ 代表 } \nabla, w_j \text{ 代表 } \vec{w}, r_i \text{ 代表 } \vec{r} \\
& \Rightarrow \nabla \times [\vec{r} \times f(r) \vec{w}] \text{ 可以用 } \varepsilon_{pkq} \frac{\partial}{\partial x_p} (\varepsilon_{kij} r_i f(r) w_j) \text{ 表示} \\
& \Rightarrow \varepsilon_{pkq} \frac{\partial}{\partial x_p} (\varepsilon_{kij} r_i f(r) w_j) = (\delta_{qi} \delta_{pj} - \delta_{qj} \delta_{pi}) \frac{\partial}{\partial x_p} (r_i f(r) w_j) \\
& = \frac{\partial}{\partial x_j} (r_q f(r) w_j) - \frac{\partial}{\partial x_p} (r_p f(r) w_q) \\
& = f(r) \frac{\partial}{\partial x_j} (r_q w_j) + r_q w_j \frac{\partial}{\partial x_j} (f(r)) - f(r) \frac{\partial}{\partial x_p} (r_p w_q) - r_p w_q \frac{\partial}{\partial x_p} (f(r)) \\
& = f(r) \left[r_q \frac{\partial w_j}{\partial x_j} + w_j \frac{\partial r_q}{\partial x_j} \right] + r_q w_j f'(r) \frac{r_j}{r} - f(r) \left[r_p \frac{\partial w_q}{\partial x_p} + w_q \frac{\partial r_p}{\partial x_p} \right] - r_p w_q f'(r) \frac{r_p}{r} \\
& \Rightarrow \nabla \times [\vec{r} \times f(r) \vec{w}] \\
& = f(r) [\vec{r} (\nabla \cdot \vec{w}) + (\vec{w} \cdot \nabla) \vec{r}] + f'(r) (\vec{w} \cdot \vec{r}) \frac{\vec{r}}{r} - f(r) [(\vec{r} \cdot \nabla) \vec{w} + \vec{w} (\nabla \cdot \vec{r})] - \vec{w} f'(r) r \\
& = f(r) [\vec{0} + \vec{w}] + f'(r) (\vec{w} \cdot \vec{r}) \frac{\vec{r}}{r} - f(r) [\vec{0} + 3\vec{w}] - \vec{w} f'(r) r \\
& = -2f(r) \vec{w} + f'(r) (\vec{w} \cdot \vec{r}) \frac{\vec{r}}{r} - \vec{w} f'(r) r
\end{aligned}$$

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$$\begin{aligned}
(1) \quad \vec{F} &= -y \vec{i} + x \vec{j} \\
l_1: w &= \int_{l_1} \vec{F} \cdot d\vec{l} = \int_{(0,0)}^{(1,0)} \vec{F} \cdot d\vec{l} + \int_{(1,0)}^{(1,1)} \vec{F} \cdot d\vec{l} = 0 + \int_0^1 (y \vec{i} + \vec{j}) \cdot \vec{j} dy = 1 \\
l_2: w &= \int_{l_2} \vec{F} \cdot d\vec{l} = \int_{l_2} (-y \vec{i} + x \vec{j}) (dx \vec{i} + 2x dx \vec{j}) = \int_0^1 x^2 dx = \frac{1}{3} \\
l_3: w &= \int_{l_3} \vec{F} \cdot d\vec{l} = \int_0^1 (-x \vec{i} + x \vec{j}) (dx \vec{i} + dx \vec{j}) = 0 \\
l_4: w &= \int_{l_4} \vec{F} \cdot d\vec{l} = \int_{(0,0)}^{(0,1)} \vec{F} \cdot d\vec{l} + \int_{(0,1)}^{(1,1)} \vec{F} \cdot d\vec{l} \\
&= \int_{(0,0)}^{(1,0)} (-y \vec{i} + x \vec{j}) \cdot \vec{j} dy + \int_{(1,0)}^{(1,1)} (-y \vec{i} + x \vec{j}) \cdot \vec{i} dx = 0 + \int_0^1 -1 dx = -1
\end{aligned}$$

沿不同路径积分积分值不等

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & x & 0 \end{vmatrix} = 2\vec{k} \neq 0$$

\Rightarrow 场有旋, 无源, 非有势场 \Rightarrow 沿不同路径积分积分值不等

$$(2) \vec{F} = 2xy\vec{i} + x^2\vec{j}$$

$$l_1: w = \int_{l_1} \vec{F} \cdot d\vec{l} = \int_{(0,0)}^{(1,0)} \vec{F} \cdot d\vec{l} + \int_{(1,0)}^{(1,1)} \vec{F} \cdot d\vec{l} = 0 + \int_0^1 (y\vec{i} + \vec{j}) \cdot \vec{j} dy = 1$$

$$l_2: w = \int_{l_2} \vec{F} \cdot d\vec{l} = \int_0^1 (2x^3\vec{i} + x^2\vec{j}) \cdot (dx\vec{i} + 2xdx\vec{j}) = \int_0^1 4x^3 dx = 1$$

$$l_3: w = \int_{l_3} \vec{F} \cdot d\vec{l} = \int_0^1 (2x^2\vec{i} + x^2\vec{j}) \cdot (dx\vec{i} + dx\vec{j}) = \int_0^1 3x^2 dx = 1$$

$$l_4: w = \int_{l_4} \vec{F} \cdot d\vec{l} = \int_{(0,0)}^{(0,1)} \vec{F} \cdot d\vec{l} + \int_{(0,1)}^{(1,1)} \vec{F} \cdot d\vec{l} \\ = \int_{(0,0)}^{(1,0)} (2xy\vec{i} + x^2\vec{j}) \cdot \vec{j} dy + \int_{(1,0)}^{(1,1)} (2xy\vec{i} + x^2\vec{j}) \cdot \vec{i} dx = 0 + \int_0^1 2x dx = 1$$

沿不同路径积分积分值相等

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2xy & x^2 & 0 \end{vmatrix} = 0$$

\Rightarrow 场无旋，有源，是有势场 \Rightarrow 沿不同路径积分积分值相等

8.

(1)

$$\vec{F} = (2x + y)\vec{i} + (x + 4y + 2z)\vec{j} + (2y - 6z)\vec{k}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2x + y & x + 4y + 2z & 2y - 6z \end{vmatrix} = 0$$

\Rightarrow 场无旋，有源，是有势场 \Rightarrow 沿不同路径积分积分值相等

\Rightarrow 取路径: $L': y = 0, x + z = a$, 从 $(a, 0, 0) \rightarrow (0, 0, a)$

$$\Rightarrow \text{原式} = \int_0^a -(2x + y) + (2y - 6z) dz = \int_0^a -4z - 2a dz = -4a^2$$

(2)

$$\vec{F} = (x^2 - yz)\vec{i} + (y^2 - xz)\vec{j} + (z^2 - xy)\vec{k}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 - yz & y^2 - xz & z^2 - xy \end{vmatrix} = 0$$

\Rightarrow 场无旋，有源，是有势场 \Rightarrow 沿不同路径积分积分值相等

\Rightarrow 取路径: $L': x = a, y = 0$, 从 $(a, 0, 0) \rightarrow (a, 0, h)$

$$\Rightarrow \text{原式} = \int_0^h z^2 dz = \frac{1}{3}h^3$$

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(1)

$$\nabla \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2x \cos y - y^2 \sin x & 2y \cos x - x^2 \sin y & 0 \end{vmatrix} = 0$$

\Rightarrow 场无旋，有源，是有势场

设势函数为 φ

$$\Rightarrow \begin{cases} \frac{\partial \varphi}{\partial x} = 2x \cos y - y^2 \sin x \\ \frac{\partial \varphi}{\partial y} = 2y \cos x - x^2 \sin y \\ \frac{\partial \varphi}{\partial z} = 0 \end{cases}$$

$$\Rightarrow \varphi = x^2 \sin y + y^2 \cos x + c, c \text{ 为常数}$$

(2)

$$\nabla \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz(2x+y+z) & xz(2y+z+x) & xy(2z+x+y) \end{vmatrix} = 0$$

\Rightarrow 场无旋，有源，是有势场

设势函数为 φ

$$\Rightarrow \begin{cases} \frac{\partial \varphi}{\partial x} = yz(2x+y+z) \\ \frac{\partial \varphi}{\partial y} = xz(2y+z+x) \\ \frac{\partial \varphi}{\partial z} = xy(2z+x+y) \end{cases}$$

$$\Rightarrow \varphi = xyz(x+y+z) + c, c \text{ 为常数}$$

(3)

$$\nabla \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x(x^2+y^2+z^2) & y(x^2+y^2+z^2) & z(x^2+y^2+z^2) \end{vmatrix} = 0$$

\Rightarrow 场无旋，有源，是有势场

设势函数为 φ

$$\Rightarrow \begin{cases} \frac{\partial \varphi}{\partial x} = x(x^2+y^2+z^2) \\ \frac{\partial \varphi}{\partial y} = y(x^2+y^2+z^2) \\ \frac{\partial \varphi}{\partial z} = z(x^2+y^2+z^2) \end{cases}$$

$$\Rightarrow \varphi = \frac{1}{4}(x^4 + y^4 + z^4) + \frac{1}{2}(x^2y^2 + y^2z^2 + x^2z^2) + c, c \text{ 为常数}$$

10.

$$\vec{F} = (x^2 + 5ay + 3yz)\vec{i} + (5x + 3axz - 2)\vec{j} + [(a+2)xy - 4z]\vec{k}$$

$$\begin{aligned}\nabla \times \vec{F} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 + 5ay + 3yz & 5x + 3axz - 2 & (a+2)xy - 4z \end{vmatrix} \\ &= (5 + 3az - 5a - 3z)\vec{k} - [(a+2)y - 3y]\vec{j} + [(a+2)x - 3ax]\vec{i}\end{aligned}$$

$\therefore \vec{F}$ 为有势场

$$\therefore \begin{cases} 5 + 3az - 5a - 3z = 0 \\ (a+2)y - 3y = 0 \\ (a+2)x - 3ax = 0 \end{cases}$$

$$\Rightarrow a = 1$$

$$\Rightarrow \vec{F} = (x^2 + 5y + 3yz)\vec{i} + (5x + 3xz - 2)\vec{j} + (3xy - 4z)\vec{k}$$

设势函数为 φ

$$\Rightarrow \begin{cases} \frac{\partial \varphi}{\partial x} = x^2 + 5y + 3yz \\ \frac{\partial \varphi}{\partial y} = 5x + 3xz - 2 \\ \frac{\partial \varphi}{\partial z} = 3xy - 4z \end{cases}$$

$$\Rightarrow \varphi = \frac{1}{3}x^3 + 3xyz + 5yz - 2y - 2z^2 + c, c \text{ 为常数}$$

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(1)

$$\begin{cases} \frac{\partial u}{\partial x} = 3x^2 + 6xy^2 \\ \frac{\partial u}{\partial y} = 6x^2y - 4y^3 \end{cases}$$

$$\Rightarrow u = x^3 + 3x^2y^2 - y^4 + c, c \text{ 为常数}$$

(2)

$$\begin{cases} \frac{\partial u}{\partial x} = x^2 - 2yz \\ \frac{\partial u}{\partial y} = y^2 - 2xz \\ \frac{\partial u}{\partial z} = z^2 - 2xy \end{cases}$$

$$\Rightarrow u = \frac{1}{3}(x^3 + y^3 + z^3) - 2xyz + c, c \text{ 为常数}$$

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(1)

$$\vec{F} = (x - y)\vec{i} + (y - x)\vec{j}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x - y & y - x & 0 \end{vmatrix} = 0$$

⇒场无旋，有源，是有势场 ⇒ 沿不同路径积分积分值相等

⇒取路径: $L': x = y$, 从 $(0, 0) \rightarrow (1, 1)$

⇒原式 = 0

(2)

$$\vec{F} = \left(\frac{1}{y} \sin \frac{x}{y} - \frac{y}{x^2} \cos \frac{y}{x} + 1 \right) \vec{i} + \left(\frac{1}{x} \cos \frac{x}{y} - \frac{x}{y^2} \sin \frac{x}{y} + \frac{1}{y^2} \right) \vec{j}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{1}{y} \sin \frac{x}{y} - \frac{y}{x^2} \cos \frac{y}{x} + 1 & \frac{1}{x} \cos \frac{x}{y} - \frac{x}{y^2} \sin \frac{x}{y} + \frac{1}{y^2} & 0 \end{vmatrix} = 0$$

⇒场无旋，有源，是有势场 ⇒ 沿不同路径积分积分值相等

⇒取路径: $L': x = y$, 从 $(1, 1) \rightarrow (2, 2)$

$$\Rightarrow \text{原式} = \int_1^2 \frac{1}{x} \sin 1 - \frac{1}{x} \cos 1 + 1 + \frac{1}{x} \cos 1 - \frac{1}{x} \sin 1 + \frac{1}{x^2} dx = \frac{3}{2}$$

(3)

$$\vec{F} = \frac{x}{\sqrt{x^2 + y^2}} \vec{i} + \frac{y}{\sqrt{x^2 + y^2}} \vec{j}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{x}{\sqrt{x^2 + y^2}} & \frac{y}{\sqrt{x^2 + y^2}} & 0 \end{vmatrix} = 0$$

⇒场无旋，有源，是有势场 ⇒ 沿不同路径积分积分值相等

⇒取路径: $L_1: y = 0$, $(1, 0) \rightarrow (6, 0)$; $L_2: x = 6$, $(6, 0) \rightarrow (6, 3)$

$$\Rightarrow \text{原式} = \int_1^6 1 dx + \int_0^3 \frac{y}{\sqrt{36 + y^2}} dy = 6 + \frac{1}{2} (\sqrt{45} - \sqrt{36}) = \frac{3}{2} \sqrt{5} + 3$$

(4)

$$\vec{F} = x\vec{i} + y\vec{j} + z^3\vec{k}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z^3 \end{vmatrix} = 0$$

⇒场无旋，有源，是有势场 ⇒ 沿不同路径积分积分值相等

⇒取路径: $L_1: y = 0, z = 2$, $(0, 0, 2) \rightarrow (2, 0, 2)$; $L_2: x = z = 2$, $(2, 0, 2) \rightarrow (2, 3, 2)$

$L_3: x = 2, y = 3$, $(2, 3, 2) \rightarrow (2, 3, -4)$

$$\Rightarrow \text{原式} = \int_0^2 x dx + \int_0^3 y^2 dy - \int_2^{-4} z^3 dz = 2 + 9 - \frac{1}{4} (4^4 - 2^4) = 2 + 9 - 60 = -49$$

(5)

$$\vec{F} = \left(1 - \frac{1}{y} + \frac{y}{z} \right) \vec{i} + \left(\frac{x}{z} + \frac{x}{y^2} \right) \vec{j} - \frac{xy}{z^2} \vec{k}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 1 - \frac{1}{y} + \frac{y}{z} & \frac{x}{z} + \frac{x}{y^2} & \frac{xy}{z^2} \end{vmatrix} = 0$$

\Rightarrow 场无旋，有源，是有势场 \Rightarrow 沿不同路径积分积分值相等

\Rightarrow 取路径: $L': x = y = z$, 从 $(1, 1, 1) \rightarrow (2, 2, 2)$

$$\Rightarrow \text{原式} = \int_1^2 1 - \frac{1}{x} + 1 + 1 + \frac{1}{x} - 1 \, dx = \int_1^2 2 \, dx = 2$$

(6)

$$\vec{F} = \frac{x}{\sqrt{x^2 + y^2 + z^2}} \vec{i} + \frac{y}{\sqrt{x^2 + y^2 + z^2}} \vec{j} + \frac{z}{\sqrt{x^2 + y^2 + z^2}} \vec{k}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{x}{\sqrt{x^2 + y^2 + z^2}} & \frac{y}{\sqrt{x^2 + y^2 + z^2}} & \frac{z}{\sqrt{x^2 + y^2 + z^2}} \end{vmatrix} = 0$$

\Rightarrow 场无旋，有源，是有势场 \Rightarrow 沿不同路径积分积分值相等

\Rightarrow 取路径: $L_1: y = y_1, z = z_1, (x_1, y_1, z_1) \rightarrow (x_2, y_1, z_1)$;

$L_2: x = x_2, z = z_1, (x_2, y_1, z_1) \rightarrow (x_2, y_2, z_1)$

$L_3: x = x_2, y = y_2, (x_2, y_2, z_1) \rightarrow (x_2, y_2, z_2)$

$$\begin{aligned} \Rightarrow \text{原式} &= \int_{x_1}^{x_2} \frac{x}{\sqrt{x^2 + y_1^2 + z_1^2}} \, dx + \int_{y_1}^{y_2} \frac{y}{\sqrt{x_2^2 + y^2 + z_1^2}} \, dy - \int_{z_1}^{z_2} \frac{z}{\sqrt{x_2^2 + y_2^2 + z^2}} \, dz \\ &= \sqrt{x_2^2 + y_1^2 + z_1^2} - \sqrt{x_1^2 + y_1^2 + z_1^2} + \sqrt{x_2^2 + y_2^2 + z_1^2} - \sqrt{x_2^2 + y_1^2 + z_1^2} + \\ &\quad \sqrt{x_2^2 + y_2^2 + z_2^2} - \sqrt{x_2^2 + y_2^2 + z_1^2} \\ &= \sqrt{x_2^2 + y_2^2 + z_2^2} - \sqrt{x_1^2 + y_1^2 + z_1^2} \end{aligned}$$

由题目可知: $\sqrt{x_2^2 + y_2^2 + z_2^2} = \sqrt{x_1^2 + y_1^2 + z_1^2}$

\Rightarrow 原式 = 0

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(1)

即证: $\vec{h} = x f(x^2 + y^2) \vec{i} + y f(x^2 + y^2) \vec{j}$ 有对应的势函数, 设势函数为 φ

$$\begin{cases} \frac{\partial \varphi}{\partial x} = x f(x^2 + y^2) & 1 \\ \frac{\partial \varphi}{\partial y} = y f(x^2 + y^2) & 2 \end{cases}$$

设 $F(u)$ 为 $f(u)$ 的原函数

$$\Rightarrow \varphi = \frac{1}{2}F(x^2 + y^2) + C \quad C \text{ 为常数}$$

$\therefore \varphi$ 存在

$$\Rightarrow \int_L x f(x^2 + y^2) dx + y f(x^2 + y^2) dy = 0$$

(2)

$$\int_L f(\sqrt{x^2 + y^2 + z^2}) (x dx + y dy + z dz) = \frac{1}{2} \int_L f(\sqrt{x^2 + y^2 + z^2}) d(x^2 + y^2 + z^2)$$

$$\text{令 } \sqrt{x^2 + y^2 + z^2} = u,$$

$$\text{原式} = \int_L f(u) u du = 0$$

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$$\Gamma = \oint_L \vec{B} \cdot d\vec{l} = \oint_S (\nabla \times \vec{B}) \cdot \vec{n} dS$$

$$\vec{B} = \frac{-2I_y}{x^2 + y^2} dx + \frac{2I_x}{x^2 + y^2} dy$$

$$\nabla \times \vec{B} = 0$$

$$\Rightarrow \Gamma = 0$$

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即证: $\vec{h} = (f'(x) + 6f(x) + e^{-2x})y\vec{i} + f'(x)\vec{j}$ 有对应的势函数, 设势函数为 φ

$$\begin{cases} \frac{\partial \varphi}{\partial x} = (f'(x) + 6f(x) + e^{-2x})y & 1 \\ \frac{\partial \varphi}{\partial y} = f'(x) & 2 \end{cases}$$

设 $F(x)$ 为 $f(x)$ 的原函数

$$1 \Rightarrow \varphi = f(x)y + 6yF(x) - \frac{1}{2}e^{-2x}y + g(y)$$

$$\Rightarrow \frac{\partial \varphi}{\partial y} = f(x) + 6F(x) - \frac{1}{2}e^{-2x} + g'(y) = f'(x)$$

$$\Rightarrow g'(y) \text{ 为常数, 设 } g'(y) = C_1$$

$$\Rightarrow f(x) + 6F(x) - \frac{1}{2}e^{-2x} + C_1 = f'(x)$$

$$\Rightarrow F(x) = C_2 e^{3x} + C_3 e^{-2x} + \frac{1}{6}C_1 + \frac{1}{10}x e^{-2x}, \text{ 其中 } C_1, C_2, C_3 \text{ 为常数。}$$

$$\Rightarrow f(x) = F'(x) = 3C_2 e^{3x} - 2C_3 e^{-2x} + \left(\frac{1}{10} - \frac{1}{5}x\right) e^{-2x}$$

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(1)

因为线积分与路径无关, 所以存在势函数 φ , 设 $A(x)$ 为 $\alpha'(x)$ 的原函数

$$\begin{cases} \frac{\partial \varphi}{\partial x} = P = [2x\alpha'(x) + \beta'(x)]y^2 - 2y\beta(x)\tan 2x & 1 \\ \frac{\partial \varphi}{\partial y} = Q = [\alpha'(x) + 4x\alpha'(x)]y + \beta(x) & 2 \end{cases}$$

$$\text{由2知} \Rightarrow \varphi = \frac{1}{2}[\alpha'(x) + 4x\alpha'(x)]y^2 + \beta(x)y + f(x)$$

$$\text{由1知} \Rightarrow \varphi = y^2[2x\alpha(x) - 2A(x) + \beta(x)] - 2y\int \beta(x)\tan 2x dx + g(y)$$

$$\Rightarrow \begin{cases} 2x\alpha(x) - 2A(x) + \beta(x) = \frac{1}{2}[\alpha'(x) + 4x\alpha'(x)] \\ \beta(x) = 2\int \beta(x)\tan 2x dx + C \quad C \text{为常数} \end{cases}$$

$$\Rightarrow \begin{cases} \beta(x) = 2\cos 2x + C_1 & C_1 \text{为常数} \\ \alpha(x) = (1+x)\sin 2x + C_1 & C_1 \text{为常数} \end{cases}$$

$$\because \alpha(0) = 0, \alpha'(0) = 2, \beta(0) = 2$$

$$\Rightarrow \begin{cases} \beta(x) = 2\cos 2x \\ \alpha(x) = (1+x)\sin 2x \end{cases}$$

(2)

$$\alpha'(x) = 2(1+x)\cos 2x + \sin 2x$$

$$\Rightarrow P = y^2(2x(1+x)\cos 2x + 2\cos 2x + \sin x \cdot 2x) - 4y\sin 2x$$

$$= y^2[(2x^2 + 2x + 2)\cos 2x + 2x\sin x] - 4y\sin 2x$$

$$Q = [2(1+x)\cos 2x + (4x+5)\sin 2x]y + 2\cos 2x$$

取积分路径 L : 沿 y 轴从 $(0, 0)$ 到 $(0, 2)$

$$\Rightarrow \text{原式} = \int_0^2 2y + 2 dy = 4 + 4 = 8$$

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$\because \int_L 2xy dx + Q(x, y) dy$ 与路径无关

左式取路径 L : 沿 $x=0$. 从 $(0, 0)$ 到 $(0, 1)$, 沿 $y=1$, 从 $(0, 1)$ 到 $(t, 1)$

$$\Rightarrow \int_{(0,0)}^{(t,1)} 2xy dx + Q(x, y) dy = \int_0^1 Q(0, y) dy + \int_0^t 2x dx = \int_0^1 Q(0, y) dy + t^2$$

右式取路径 L : 沿 $x=0$. 从 $(0, 0)$ 到 $(0, t)$, 沿 $y=t$, 从 $(0, t)$ 到 $(1, t)$

$$\Rightarrow \int_{(0,0)}^{(1,t)} 2xy dx + Q(x, y) dy = \int_0^t Q(0, y) dy + \int_0^1 2tx dx = \int_0^t Q(0, y) dy + t$$

$$\Rightarrow \int_0^t Q(0, y) dy + t = \int_0^1 Q(0, y) dy + t^2$$

$\because \int_L 2xy \, dx + Q(x, y) \, dy$ 与路径无关

$$\Rightarrow \frac{\partial Q}{\partial x} = 2x$$

$$\Rightarrow Q = x^2 + f(y)$$

$$\Rightarrow \int_0^t f(y) \, dy + t = \int_0^1 f(y) \, dy + t^2$$

$$\Rightarrow \int_1^t f(y) \, dy = t^2 - t$$

$$\Rightarrow f(y) = 2y - 1$$

$$\Rightarrow Q = x^2 + 2y - 1$$

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(1)

$$\text{原式} = d\left(\frac{1}{2}x^2y^2 + 2xy - 2y \sin x + y \cos x\right) = 0$$

$$\Rightarrow \frac{1}{2}x^2y^2 + 2xy - 2y \sin x + y \cos x = C \quad , \quad C \text{ 为常数}$$

(2)

$$2xy \, dx + (y^2 - x^2) \, dy = 0$$

设 $y \neq 0$

$$\Rightarrow \frac{2x}{y} \, dx + \left(1 - \frac{x^2}{y^2}\right) \, dy = 0$$

$$\Rightarrow d\left(y + \frac{x^2}{y}\right) = 0$$

$$\Rightarrow y + \frac{x^2}{y} = C$$

$$\Rightarrow x^2 + y^2 = Cy \quad (y \neq 0), \quad C \text{ 为常数}$$

若 $y = 0$ 则 $x = 0$

满足 $x^2 + y^2 = Cy$, C 为常数

\Rightarrow 综上 $x^2 + y^2 = Cy$, C 为常数

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\because 全微分

$$\Rightarrow \frac{\partial}{\partial x} [f'(x) + e^x \cos y + 2x] = \frac{\partial}{\partial y} [e^x \sin y + x^2 y + f(x, y)]$$

$$\begin{aligned}
&\Rightarrow f''(x) + e^x \cos y + 2 - e^x \cos y - x^2 - f(x) = 0 \\
&\Rightarrow f''(x) - f(x) = x^2 - 2 \\
&\because f(0) = 0, f'(0) = 2 \\
&\Rightarrow f(x) = e^x - e^{-x} - x^2 \\
&\Rightarrow f'(x) = e^x + e^{-x} - 2x \\
&\Rightarrow \text{全微分: } [e^x \sin y + e^x y - e^{-x} y] dx + [e^x + e^{-x} + e^x \cos y] dy = 0 \\
&\Rightarrow d[e^x \sin y + e^x y + e^{-x} y] = 0 \\
&\Rightarrow e^x \sin y + e^x y + e^{-x} y = C \quad C \text{ 为常数}
\end{aligned}$$

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$$\begin{cases} \frac{\partial u}{\partial x} = 2xy(x^4 + y^2)^\lambda \\ \frac{\partial u}{\partial y} = -x^2(x^4 + y^2)^\lambda \end{cases}$$

因为 \vec{v} 是梯度

$$\begin{aligned}
&\Rightarrow \nabla \times \vec{v} = 0 \\
&\Rightarrow -\frac{\partial}{\partial x}[x^2(x^4 + y^2)^\lambda] - \frac{\partial}{\partial y}[2xy(x^4 + y^2)^\lambda] = 0 \\
&\Rightarrow 4x(x^4 + y^2)^\lambda + \lambda \cdot 4x(x^4 + y^2)^\lambda = 0 \\
&\Rightarrow \lambda = -1 \\
&\Rightarrow \begin{cases} \frac{\partial u}{\partial x} = \frac{2xy}{x^4 + y^2} \\ \frac{\partial u}{\partial y} = -\frac{x^2}{x^4 + y^2} \end{cases} \\
&\Rightarrow u = \arctan\left(\frac{x^2}{y}\right) + C, C \text{ 为常数。}
\end{aligned}$$

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$$\begin{aligned}
&(1) \\
&\nabla[\vec{w} \cdot f(x) \vec{r}] = \vec{w} \cdot \nabla(f(r) \vec{r}) + f(r) \vec{r} \cdot \nabla \vec{w} = f(r) \vec{w} \cdot \nabla \vec{r} + (\vec{w} \cdot \vec{r}) \nabla f(r) \\
&= f(r) \vec{w} + (\vec{w} \cdot \vec{r}) f'(r) \frac{\vec{r}}{r}
\end{aligned}$$

用张量做

设用 $\frac{\partial}{\partial x_i}$ 代表 ∇ , w_j 代表 \vec{w} , r_j 代表 \vec{r}

$$\begin{aligned}\frac{\partial}{\partial x_i}(w_j f(r) r_j) &= w_j \frac{\partial}{\partial x_i}(f(r) r_j) + f(r) r_j \frac{\partial w_j}{\partial x_i} = w_j f(r) \frac{\partial r_j}{\partial x_i} + w_j r_j \frac{\partial f(r)}{\partial x_i} \\ &= w_j r_j \frac{\partial f(r)}{\partial x_i} + f(r) w_j \frac{\partial r_j}{\partial x_i} = w_j r_j \frac{\partial f(r)}{\partial x_i} + f(r) w_i\end{aligned}$$

(2)

$$\begin{aligned}\nabla \cdot [\vec{w} \times f(r) \vec{r}] &= f(r) \nabla \cdot [\vec{w} \times \vec{r}] + (\vec{w} \times \vec{r}) \cdot \nabla (f(r)) \\ &= f(r) \nabla \cdot [\vec{w} \times \vec{r}] + (\vec{w} \times \vec{r}) \cdot f'(r) \frac{\vec{r}}{r} = f(r) \vec{w} \cdot (\nabla \times \vec{r}) + (\vec{w} \times \vec{r}) \cdot f'(r) \frac{\vec{r}}{r} \\ &\because (\vec{w} \times \vec{r}) \cdot \vec{r} = 0, \nabla \times \vec{r} = \vec{0} \\ &\therefore \nabla \cdot [\vec{w} \times f(r) \vec{r}] = 0\end{aligned}$$

(3)

用张量做

设用 $\frac{\partial}{\partial x_p}$ 代表 ∇ , w_i 代表 \vec{w} , r_j 代表 \vec{r}

$$\begin{aligned}\Rightarrow \nabla \times [\vec{w} \times f(r) \vec{r}] &\text{ 可以用 } \varepsilon_{pkq} \frac{\partial}{\partial x_p} (\varepsilon_{kij} w_i f(r) r_j) \text{ 表示} \\ \Rightarrow \varepsilon_{pkq} \frac{\partial}{\partial x_p} (\varepsilon_{kij} w_i f(r) r_j) &= (\delta_{qi} \delta_{pj} - \delta_{qj} \delta_{pi}) \frac{\partial}{\partial x_p} (w_i f(r) r_j) \\ &= \frac{\partial}{\partial x_j} (w_q f(r) r_j) - \frac{\partial}{\partial x_p} (w_p f(r) r_q) \\ &= f(r) \frac{\partial}{\partial x_j} (w_q r_j) + w_q r_j \frac{\partial}{\partial x_j} (f(r)) - f(r) \frac{\partial}{\partial x_p} (w_p r_q) - w_p r_q \frac{\partial}{\partial x_p} (f(r)) \\ &= f(r) \left[w_q \frac{\partial r_j}{\partial x_j} + r_j \frac{\partial w_q}{\partial x_j} \right] + w_q r_j f'(r) \frac{r_j}{r} - f(r) \left[w_p \frac{\partial r_q}{\partial x_p} + r_q \frac{\partial w_p}{\partial x_p} \right] - w_p r_q f'(r) \frac{r_p}{r} \\ \Rightarrow \nabla \times [\vec{w} \times f(r) \vec{r}] &= f(r) [\vec{w} (\nabla \cdot \vec{r}) + (\vec{r} \cdot \nabla) \vec{w}] + \vec{w} f'(r) r - f(r) [(\vec{w} \cdot \nabla) \vec{r} + \vec{r} (\nabla \cdot \vec{w})] - (\vec{w} \cdot \vec{r}) f'(r) \frac{\vec{r}}{r} \\ &= 3 \vec{w} f(r) + 0 + \vec{w} r f'(r) - \vec{w} f(r) + 0 - (\vec{w} \cdot \vec{r}) f'(r) \frac{\vec{r}}{r} \\ &= 2 \vec{w} f(r) + \vec{w} r f'(r) - (\vec{w} \cdot \vec{r}) f'(r) \frac{\vec{r}}{r}\end{aligned}$$

（完结）

撒花！！