

## **EE 407 Homework-2**

- 1. A hydraulic system**
- 2. A biochemical reactor**
- 3. An Ecological System**

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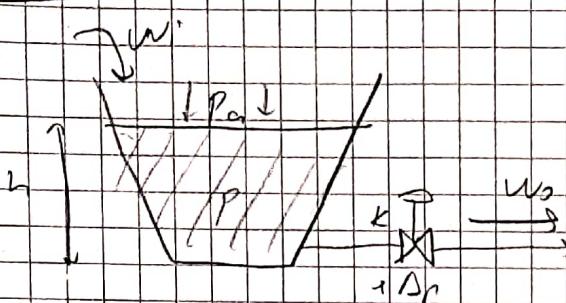
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EE-907

HW-2

Question - 1



$$w_0 = k \sqrt{P_A} \quad k: \text{constant}$$

where

$$P_A = P_A + \rho g h$$

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where  $\rho$  = liquid density

q) We assume that rate of change of cross section will be wrt  $h(A)$ . ( $A(h)$ )

$$w_0 = k \sqrt{P_A} = k \sqrt{P_A + \rho g h + \rho g} = k \sqrt{\rho g h}$$

By our assumption;

$$V = A(h) \cdot h' \quad \left( \begin{array}{l} \text{(Rate of change of volume)} \\ \text{= cross section, of change} \\ \text{when } h = h/t \\ h = h/t \end{array} \right)$$

Also,

$$V = w_1 - w_2 = w_1 - k \sqrt{\rho g h} \quad \text{(Accumulation (conservation) law)}$$

$$V = A(h) \cdot h' = w_1 - k \sqrt{\rho g h}$$

$$h' = \frac{w_1 - k \sqrt{\rho g h}}{A(h)} - \frac{k \sqrt{\rho g h}}{A(h)}$$

$$b) \Delta p = g_s h$$

$$h = \frac{\Delta p}{g_s}$$

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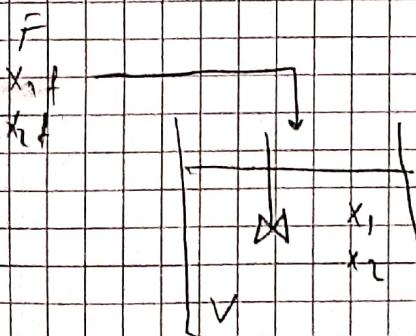
$$\Delta p = \frac{g_s \cdot g \cdot w_i(t)}{A(h)} - \frac{g_s \cdot k \cdot \sqrt{\Delta p}}{A(h)}$$

c) output constant  $\Rightarrow h = 0$ ,  $\frac{h=0}{\text{given}}$

$$0 = \frac{w_i(t)}{A(h)} - \frac{k \sqrt{g_s h}}{A(h)}$$

$$w_{i, \text{steady state}} = w_{i, \text{ss}} = \frac{k \sqrt{g_s r}}{A(h)}$$

## Question 2



Generation rate

$$r_1 = M x_1$$

Specific growth coefficient of  $x_1$

concentration of  
(mass/volume)  
substrate

flow rate  
dilution rate

Assumptions = no biomass feed stream,  $d = F/V \rightarrow \text{constant}$   
 $x_{1f} = 0$

$$Y = \frac{1}{n} \Rightarrow \text{constant}$$

$$d) \quad \dot{x}_1 = Mx_1 - x_2 \cdot \frac{F}{Y} + x_{1f} \cdot \frac{F}{Y}^d - (M-d)x_1$$

$$\dot{x}_2 = -\frac{Mx_1}{Y} - x_2 \cdot \frac{F}{Y} + x_{2f} \cdot \frac{F}{Y}^d = -\frac{M}{Y}x_1 - dx_2 + d x_{2f}$$

$$\begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \end{bmatrix} = \begin{bmatrix} M-d & 0 \\ -\frac{M}{Y} & d \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} 0 \\ d x_{2f} \end{bmatrix}$$

b) when  $M = \frac{M_m \cdot x_2}{(M_m + x_2)}$   $M_m, x_m > 0$   
 $d < M_m$

$$① \quad \dot{x}_1 = 0 = \left( \frac{M_m - x_{1eq}}{M_m + x_{1eq}} - d \right) x_{1eq}$$

$$② \quad \dot{x}_2 = 0 = -\frac{1}{Y} \left( \frac{M_m \cdot x_{1eq}}{M_m + x_{1eq}} \right) \cdot x_{1eq} - dx_{1eq} + dx_{2f}$$

From ①

$$d \cdot k_m + d x_{1eq} = M_m \cdot x_{1eq}$$

$$x_{1eq} = \frac{d \cdot k_m}{(M_m - d)}$$

Contd...

from  $\textcircled{2}$

$$-d x_{2eq} - \frac{\gamma}{\gamma} \left( \frac{dM_m \cdot x_{2eq}}{k_m + x_{2eq}} \right) \cdot x_{1eq} + d \cdot x_{2f} = 0$$

$$x_{1eq} = \frac{\gamma \cdot d (x_{2f} - x_{2eq}) / (k_m + x_{2eq})}{dM_m - x_{2eq}}$$

where  $x_{2eq} < \frac{d \cdot k_m}{(dM_m - d)}$  (Final before.)

$$x_{1eq} = \frac{\gamma (x_{2f} - \frac{d \cdot k_m}{(dM_m - d)})}{(dM_m - d)}$$

Or as trivial solution

$$x_{1eq} = 0$$

$$x_{1eq} = x_{2f}$$

Continues

c) write in the form of

$$\begin{bmatrix} \dot{x}_1 \\ \vdots \\ \dot{x}_n \end{bmatrix} = \begin{pmatrix} ① & ② \\ ③ & ④ \end{pmatrix} \begin{bmatrix} x_1 - x_{1eq} \\ x_2 - x_{2eq} \end{bmatrix}$$

Now, find ①, ②, ③, ④

$$\dot{x}_1 = 0 + \underbrace{\frac{u_m x_{1eq} - d}{k_m - x_{1eq}}}_{①} (x_1 - x_{1eq})$$

$$+ x_1 u_m \underbrace{\left( \frac{k_m}{(k_m + x_{2eq})^2} \right)}_{②} (x_2 - x_{2eq})$$

Find ①

$$\frac{\frac{u_m (d/k_m)}{u_m \cdot d}}{k_m + \frac{d u_m}{u_m \cdot d}} - d = 0 \quad ①$$

Find ②

$$\frac{x_1 u_m \cdot k_m}{\left( k_m + \frac{d u_m}{u_m \cdot d} \right)^2} \quad ②$$

To find 3, 4 use  $x_2$

$$x_2 = 0 + \left( -\frac{1}{Y} \cdot \frac{\sqrt{m} x_{2eq}}{1km + x_{2eq}} \right) (x_1 - x_{1eq}) - 1$$

$$\left( -d - \left( \frac{1}{Y} \cdot \frac{x_{1eq} \sqrt{m} \cdot km}{(km + x_{2eq})^2} \right) (x_2 - x_{2eq}) \right)$$

Find ③

$$\textcircled{3} = \frac{-d}{Y}$$

Find ④

$$-d = (x_2 - \frac{d \text{ km}}{m - d}) \frac{m \cdot \text{km}}{(km - \frac{d \text{ km}}{m - d})^2}$$

So finally we now all unknowns

m

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \textcircled{1} & \textcircled{2} \\ \textcircled{1} & \textcircled{3} \end{bmatrix} \begin{bmatrix} x_1 - x_{1eq} \\ x_2 - x_{2eq} \end{bmatrix}$$

$$①) \mu = \frac{M_m x_2}{(k_m + x_2 + k_1 x_1^2)}$$

$$②) x_1 = 0 = -d x_{1eq} + \frac{M_m x_{2eq}}{(k_m + x_{2eq} + k_1 x_{1eq}^2)} \cdot x_{1eq}$$

$$③) x_2 = 0 = d x_{2f} - \frac{M_m x_{2eq}}{Y (k_m + x_{2eq} + k_1 x_{1eq}^2)} \cdot x_{2eq}$$

From ①

$$x_{1eq} = \frac{M_m - d}{d} \pm \sqrt{\left(\frac{d - M_m}{d}\right)^2 - 6 k_1 k_m}$$

$$x_{2eq} = \frac{(M_m - d) \mp \sqrt{d^2 M_m^2 + 2 d M_m - 4 d^2 k_1 k_m}}{2 d k_1}$$

From ②

$$x_{1eq} = Y (x_{2f} - x_{2eq}) (k_m + x_{2eq} + k_1 x_{1eq}^2)$$

$$\text{put } x_{2eq}$$

$$x_{1eq} = Y (x_{2f} - \frac{M_m - d}{d} \pm \sqrt{\frac{d^2 M_m^2 + 2 d M_m - 4 d^2 k_1 k_m}{d^2}})$$

As trivial,  $x_{1eq} = 0$   $x_{2eq} = x_{2f}$

### 3. An Ecological System

a)

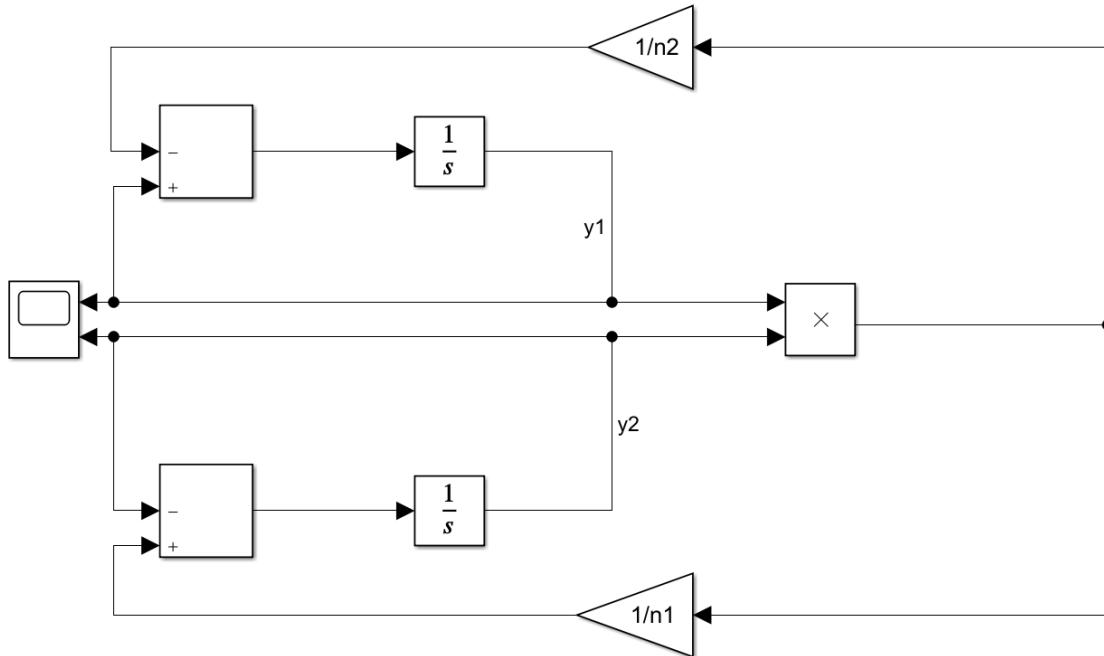


Figure.1: Prey-Predator Simulink Model

b)

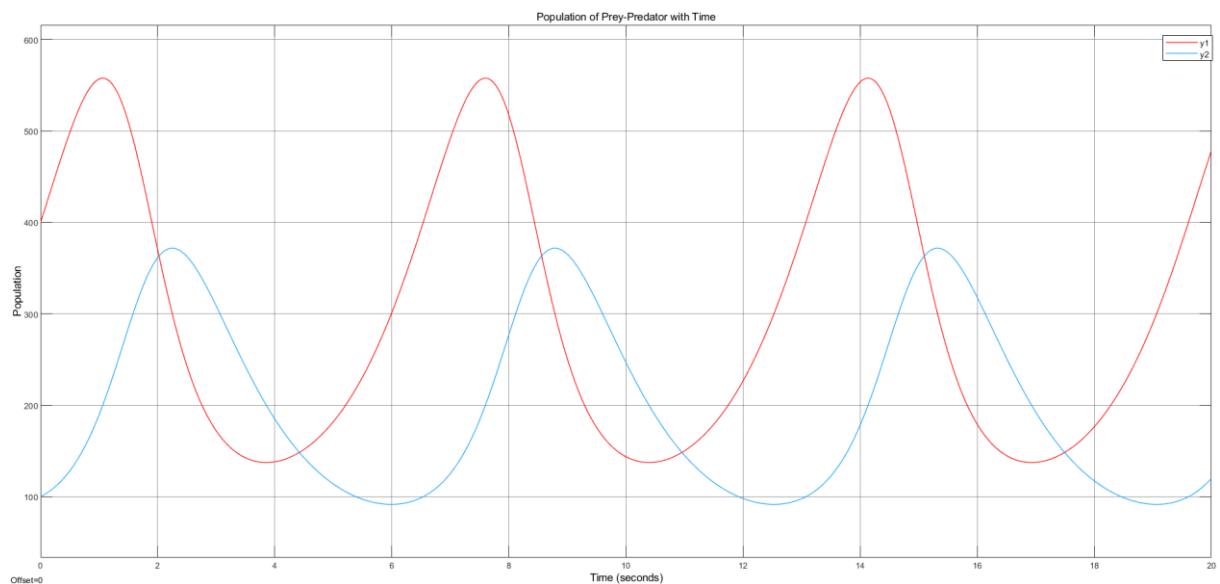


Figure.2: Prey-Predator Plot for  $y_1, i=400$ ,  $y_2, i=100$ ,  $n_1=300$ ,  $n_2=200$

c) Periodicity is 6.5s and both populations are increasing. They are living in harmony. Lions and plants are an example of this situation. They have similar properties.

e) For the equilibrium point, derivatives of them should be zero. So,  $y_1, i=n_1=300$ ,  $y_2, i=n_2=200$ . They reach equilibrium and doesn't change. Oscillations stop and periods are nearly zero and they have constant population.

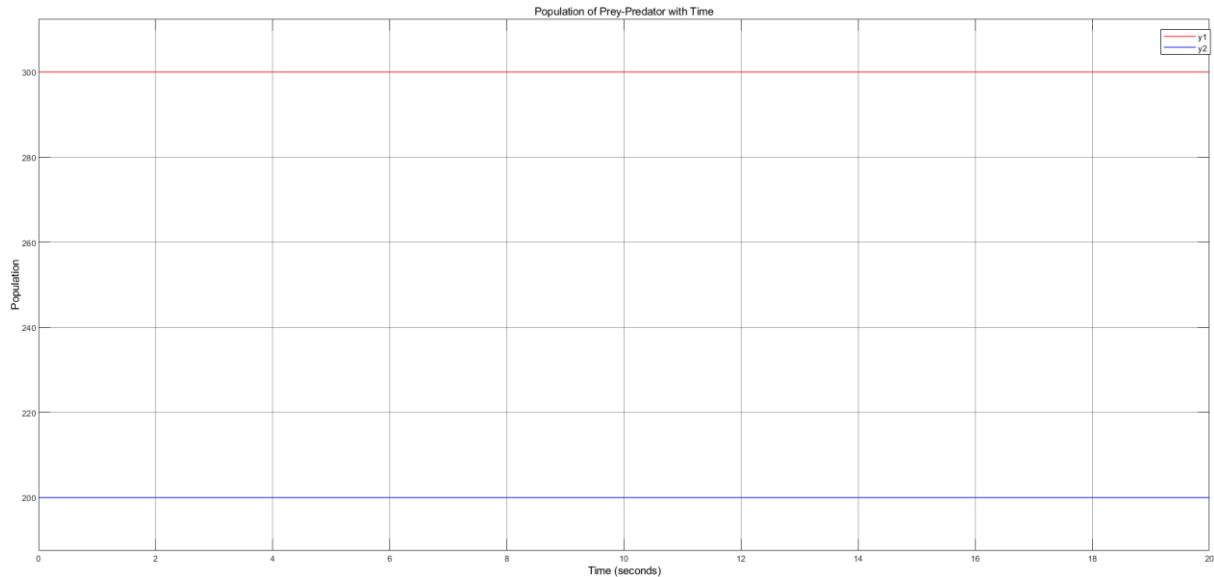


Figure.3: Prey-Predator Plot for  $y_1, i=n_1=300$ ,  $y_2, i=n_2=200$

f)

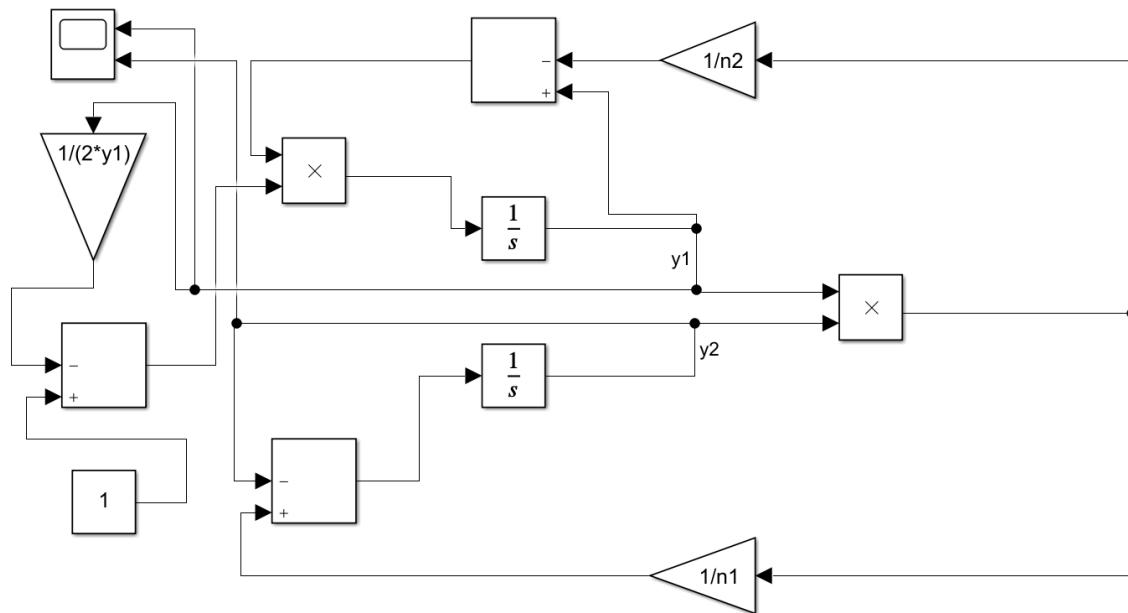


Figure.4: Prey-Predator Simulink Model for part(f)

g)

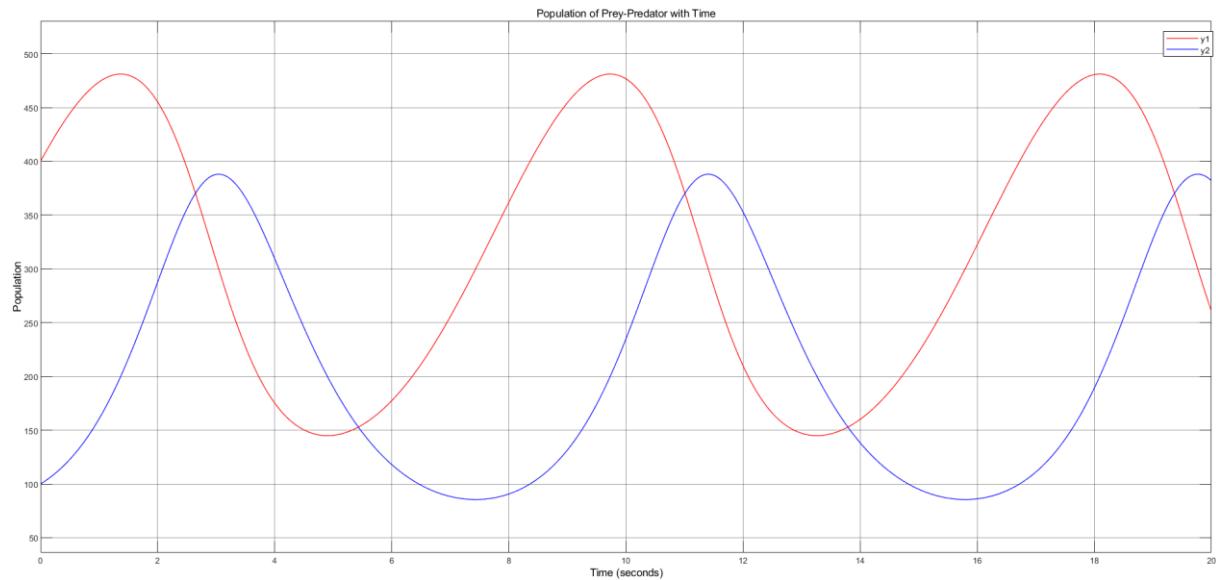


Figure.4: Prey-Predator Plot for part(g)

Oscillations happen and peak of prey decreased, mean is same. Predator is changed very little. Period are increased as nearly 8.5 since derivative of prey decreased.