



Exercise Sheet 4

Autonomous Learning

June 30, 2020

The Assignment 4 is not mandatory for the exam but contains valuable exercises.

Task 1 - Policy Gradient

- A. Extend your agent with a policy gradient learning component.
- B. Use a neural network with the following layers:
 - (a) Input Layer
 - (b) 1 Hidden Layer (128 Knoten + Relu)
 - (c) 1 Hidden Layer (256 Knoten + Relu)
 - (d) 1 Output Layer (8 Knoten + Softmax)
- C. As Input use only the x- and y- distance from the marine to the beacon.
 - Normalise your input to the range $[-1, 1]$
- D. Use a learning rate of $\alpha = 0.00025$
- E. The agent receives after every action the following reward:
 - +100 if it reaches the beacon
 - -0.1 otherwise
- F. Use a gamma of $\gamma = 0.99$
- G. Use a screen size of `screen_size = 16`
- H. Visualise the learning process as usual
- I. Again implement a learning module (TrainPG.py), where the agent initialise a new neural network, and a module (RunPG.py) running the agent without learning.