



Exercise Sheet 2

Autonomous Learning

May 22, 2019

Task 1 - SARSA

- A. Extend the agent of the previous worksheet with a SARSA learning component.
- (a) The agent is supposed to walk as far as possible per step.
 - (b) For modelling the state space, only the x- and y-distance from marine to beacon shall be used. Apart from that, divide the state space into sections:

$$x_1 < s_1 < x_2$$

$$y_1 < s_1 < y_2$$

This helps to reduce the state space.

- B. Research another non- ϵ -greedy exploration strategy.
- (a) Which one did you choose?
 - (b) How does it work?
 - (c) Implement the exploration strategy into the framework.
- C. Visualise the learning progress analogously to Q-learning.
- D. The trained SARSA agent shall be started with the python file (`RunSARSA.py`). The agent is supposed to read the trained Q-table and use it without further learning.
- E. You should be able to start the SARSA agent training via the python file (`TrainSARSA.py`). By this, the agent should generate a new Q-table.

Task 2 - Deep Q-Network

- A. Extend the agent with a DQN learning component.
- B. For modelling the state space, no further research is needed.
- C. Implement a Neural Network with *keras*:
- (a) 1 input layer
 - (b) 1 hidden layer (16 nodes + ReLu)
 - (c) 1 hidden layer (32 nodes + ReLu)

- (d) 1 output layer (8 nodes + linear)
- D. Save the trained weights as `hdf5`-format.
- E. Apply replay memory under the following conditions:
 - (a) Total number: 100.000
 - (b) The replay memory has to be filled with at least 6000 entries before learning starts.
- F. Use all ϵ -greedy exploration strategies under the following conditions:
 - (a) $\epsilon_{start} = 1$
 - (b) $\epsilon_{min} = 0.05$
 - (c) linearly decreasing until episode 1.000
- G. Visualise the learning process as usual.
- H. The trained DQN-agent shall be started with the python file (`RunDQN.py`). The agent is supposed to read the trained weights and use them without further learning.
- I. You should be able to start the training of the DQN-agent via python file (`TrainDQN.py`). By this, the agent should learn new weights.