

Euclidean spaces

- We work in n-dimensional space $x = (x_1, x_2, \dots, x_n)$.
- 2D: $v = (x_1, x_2) = (x, y)$
- 3D: $v = (x_1, x_2, x_3) = (x, y, z)$

Scalar product

If we have $x = (x_1, \dots, x_n)$ and $y = (y_1, \dots, y_n)$, then:

$$x \cdot y = \langle x, y \rangle = x_1 y_1 + \dots + x_n y_n$$

Cross product (3D)

$$x = (x_1, x_2, x_3)$$

$$y = (y_1, y_2, y_3)$$

$$x \times y = (x_2 y_3 - x_3 y_2, x_3 y_1 - x_1 y_3, x_1 y_2 - x_2 y_1)$$

Scalar Field

A scalar field

$$F : \mathbb{R} \rightarrow \mathbb{R}, x \rightarrow F(x)$$

assigns a scalar value to every point.

Examples: temperature, chemical concentration, pressure, probability distribution.

Given a scalar field $F^n \rightarrow \mathbb{R}$, the level set of the value $c \in \mathbb{R}$ is:

$$\{x \in \mathbb{R}^n : f(x) = c\}$$

Vector Field

A vector field assigns a vector to each point in space:

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n, x \rightarrow (F_1(x), \dots, F_n(x))$$

Examples:

- $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2, (x_1, x_2) \rightarrow (-x_2, x_1)$
- $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2, (x_1, x_2) \rightarrow (2x_1, x_2 + x_3, x_1 x_2 x_3)$

How to visualize vector fields? Put one arrow for each point in space.

- constant vector field
- rotational vector field
- source vector field

Gradient, Hessian, Laplacian

If $F : \mathbb{R}^n \rightarrow \mathbb{R}$ is a scalar field, then the gradient is the vector field

$$\nabla F = (\partial x_1 f, \partial x_2 f, \dots, \partial x_n f)$$

$$\nabla = \begin{pmatrix} \partial x_1 \\ \partial x_2 \\ \dots \\ \partial x_n \end{pmatrix}$$

$$\text{grad } f = \nabla f = \begin{pmatrix} \partial x_1 f \\ \partial x_2 f \\ \dots \\ \partial x_n f \end{pmatrix}$$

Example:

$$f(x_1, x_2) = x_1^3 + x_1 x_2^5$$

$$\nabla f(x_1, x_2) = (3x_1^2 + x_2^5, x_1 \cdot 5x_2^4)$$

- Geometrically, ∇f points in the direction of the steepest increase of f
- The directional derivative of f in direction $v \in \mathbb{R}^n$ is:

$$D_v f = \nabla f \cdot v = \partial x_1 f \cdot v + \dots + \partial x_n f \cdot v_n$$

The value $D_v f$ tells us how f changes as we move in direction v .

- Along any level set line, the gradient is orthogonal.

Example:

$$f(x_1, x_2) = x_1^2 + x_2^2$$

$$\nabla f(x_1, x_2) = (2x_1, 2x_2)$$

Level set of $c = 1$.

If $F : \mathbb{R}^n \rightarrow \mathbb{R}$ is a scalar field, then the Hessian of f is a matrix field:

$$\nabla^2 f = \begin{pmatrix} \partial_1 \partial_1 f & \partial_1 \partial_2 f & \dots & \partial_1 \partial_n f \\ \dots & \dots & \dots & \dots \\ \partial_n \partial_1 f & \dots & \dots & \partial_n \partial_n f \end{pmatrix}$$

- The Hessian is symmetric if all 2nd derivatives are continuous
- Physical/geometric interpretation contains information on the curvature of the scalar field

If $F : \mathbb{R}^n \rightarrow \mathbb{R}$ is a scalar field, then the Laplacian of f is the scalar field:

$$\Delta f = \sum_{i=1}^n \partial_i \partial_i f = \partial_1 \partial_1 f + \partial_2 \partial_2 f + \dots + \partial_n \partial_n f$$

- Sum of the diagonal entries of the Hessian
- Physically relevant in modeling diffusion

Poisson problem : $-\Delta u = f$ (u is an unknown scalar field, while f is known, it's a differential equation).

Example:

$$f(x, y, z) = xy^3e^z$$

$$\nabla f(x) = (y^3e^z, 3xy^2e^z, xy^3e^z)$$

$$\partial x \partial x f = 0$$

$$\partial x \partial y f = 3y^2e^z$$

$$\partial x \partial z f = y^3e^z$$

$$\partial y \partial y f = 6xye^z$$

$$\partial y \partial z f = 3xy^2e^z$$

$$\partial z \partial z f = xy^3e^z$$

$$\nabla^2 f = \begin{pmatrix} 0 & 3y^2e^z & y^3e^z \\ 3y^2e^z & 6xye^z & 3xy^2e^z \\ y^3e^z & 3xy^2e^z & xy^3e^z \end{pmatrix}$$

$$\Delta f = 0 + 6xye^z + xy^3e^z = e^z xy(6 + y^2)$$

Example:

$$F(x) = \|x\| = \sqrt{\sum_{i=1}^n x_i^2}, x \in \mathbb{R}^n$$

First derivatives:

$$\partial_i F(x) = \partial_i \left(\sum_{i=1}^n x_i^2 \right)^{\frac{1}{2}} = \frac{1}{2} \left(\sum_{i=1}^n x_i^2 \right)^{-\frac{1}{2}} \cdot 2x_i = \frac{1}{\|x\|} x_i = \frac{x_i}{\|x\|}$$

Notice the singularity at $x = 0$. It looks like the gradient is not defined but in fact it can be removed by continuous extension of the first derivatives.