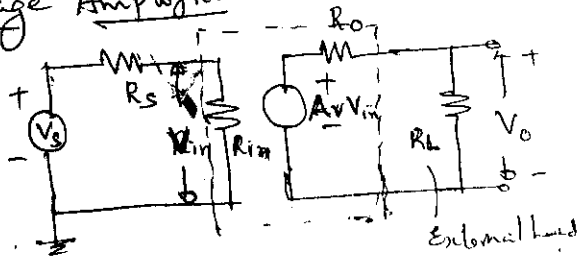


# Feedback Amplifiers

①

Classification of Amplifiers : The amplifiers can be classified as follows :  
 1. Voltage  
 2. Current  
 3. Transconductance  
 4. Transresistance amplifiers

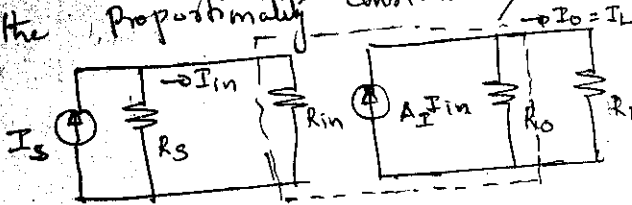
## Voltage Amplifier



The thevenin eqd ckt of a two Port network which represents an amplifier is shown in the fig. If  $R_{in} \gg R_s$ , then  $V_{in} \approx V_s$ . If the external resistor  $R_L$  is large compared with the o/p Res  $R_o$  of the amplifier, then

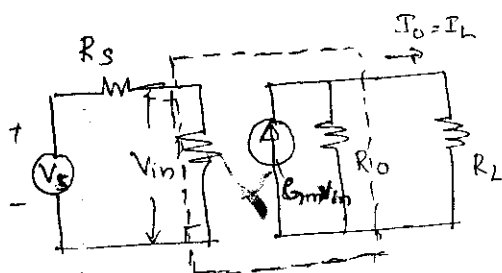
$V_o \approx A_v V_{in} \approx A_v V_s$ . The o/p voltage is proportional to i/p voltage and proportionality constant is independent of  $R_s$  and load resistance. This type of ckt is called voltage amplifier. The ideal voltage amplifiers must have infinite i/p impedances and zero o/p impedances. The voltage gain  $A_v = \frac{V_o}{V_{in}}$  with  $R_L = \infty$  and hence represents the open ckt voltage amplification or gain.

Current Amplifier : An ideal current amplifier is defined as an amplifier which provides an o/p current proportional to the signal current, and the proportionality constant is independent of  $R_s$  and  $R_L$ . An ideal current amplifier must have zero i/p impedance ( $R_{in} = 0$ ) and infinite o/p impedance ( $R_o = \infty$ ). In practice the amplifier will have low i/p impedance and high o/p impedance. (i.e.  $R_{in} \ll R_s$  &  $R_o \gg R_L$ )



The fig shows the Norton eqd of the current amplifier ckt. The short circuit current  $I_{sc} = I_L$  with  $R_L = 0$ , representing the short circuit current. If  $R_{in} \ll R_s$ ,  $I_{in} \approx I_s$  and if  $R_o \gg R_L$ ,  $I_o \approx I_{sc}$ . Hence o/p current is proportional to signal current. The current gain  $A_i = \frac{I_o}{I_{in}} \approx \frac{I_o}{I_s}$ .

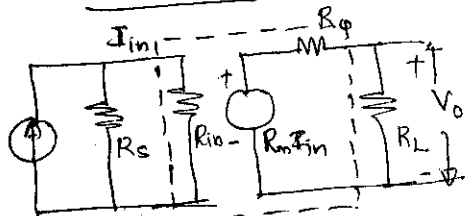
Transconductance Amplifier : In an ideal transconductance amplifier the o/p current is proportional to the signal voltage, independent of the magnitudes of  $R_s$  and  $R_L$ . The amplifier must have infinite input Res  $R_{in}$  and infinite o/p resistance  $R_o$ . A Practical Transconductance amplifier has large input resistance  $R_{in} \gg R_s$ , i.e., amplifier is driven by a low resistance source, & presents high o/p resistance ( $R_o \gg R_L$ ) and hence drives a low-resistance load. The eqd ckt of transconductance amplifier is shown below



$$R_{in} \gg R_s$$

$$R_o \gg R_L$$

### Transresistance Amplifier

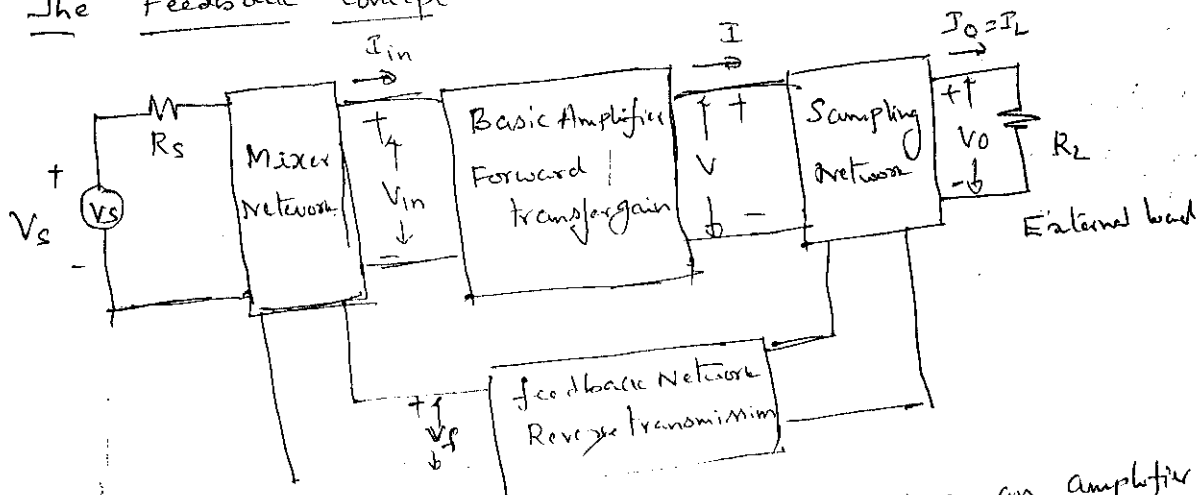


The equiv ckt of an amplifier which ideally supplies an output Voltage  $V_o$  in proportion to the signal current  $I_s$  independently of  $R_s$  and  $R_L$ .

For a practical transresistance amplifier we must have  $R_{in} \ll R_s$  and  $R_o \ll R_L$  relative to source and load resistances.

Hence the i/p and o/p resistances. Since  $R_s \gg R_{in}$   $I_{in} \approx I_s$  and if  $R_o \ll R_L$ , then  $V_o \approx R_m I_{in}$ . We note that  $R_m = \frac{V_o}{I_{in}}$  with  $R_L = \infty$ .

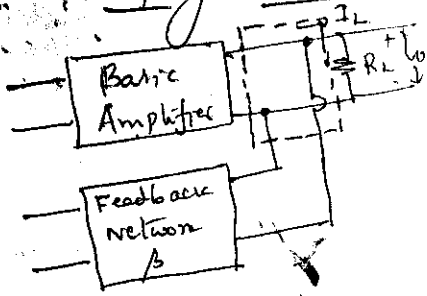
### The Feedback Concept



Any one of the above four amplifiers can be used as an amplifier. In this amplifier we may sample either current or voltage by means of a suitable sampling network and then signal is applied to the i/p. through a feedback two port network as shown in the fig. At the i/p the feedback signal is combined with the external (source) signal through a mixer network and is fed into the amplifier proper.

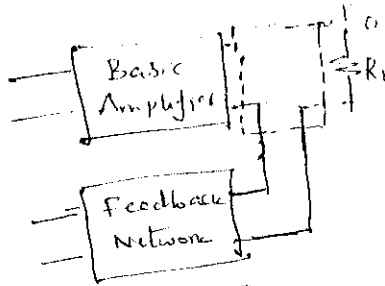
Feedback network: It is usually passive two port network which may contain resistors, capacitors and inductors. Very often it is made up of only resistive configuration.

## Sampling Network



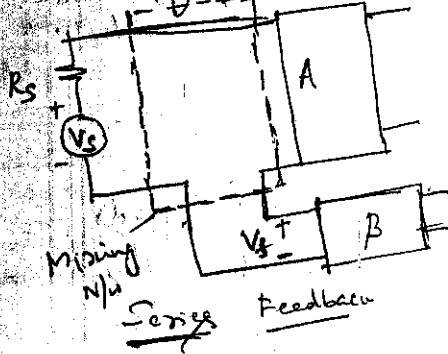
## Voltage Sampling

In the first block diagram, the output voltage is sampled by connecting the feedback network in shunt across the output. In this case it is desirable that the i/p impedance of the feedback network be much greater than  $R_L$  so that feedback N/w does not load the output of the amplifier. Another feedback connection which samples the output current is shown in current sampling case, where the feedback N/w is connected in series with the output. In this case the i/p impedance of the feedback N/w should be much smaller than  $R_L$  in order <sup>not to</sup> reduce the current gain.

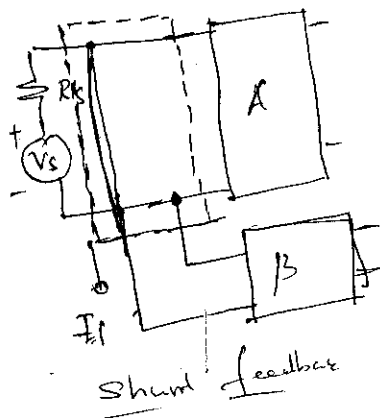


## Current Sampling

## Mixing Network



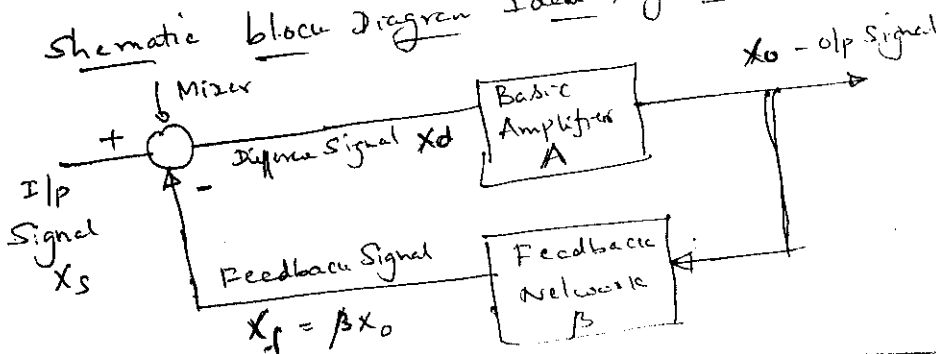
## Series Feedback



## Shunt Feedback

The fig shows simple block diagram approach of series & shunt feedback ckt. Feedback may be classified as either positive or negative. In the former case any increase in o/p signal results in a feedback into the i/p in such a way as to increase further the magnitude of the o/p signal. When the feedback results in decrease in the magnitude of the output signal, the amplifier is said to have negative feedback.

Schematic block diagram Ideal single loop feedback amplifier



## The Transfer gain with Feedback

Considering  $\beta$  as a feedback factor

the feedback signal  $X_f = \beta X_o$ .

where  $X_o$  is o/p of an amplifier (either voltage or current).  
If i/p to an amplifier is  $X_d$  and o/p is proportional to the i/p by an proportionality constant  $A$  (which independent of source & load impedances)

$$\text{then } X_o = A X_d$$

$$\text{Therefore } X_o = A(X_s - X_f) = A(X_s - \beta X_o)$$

$$X_o(1 + A\beta) = AX_s$$

$$A_f = \text{gain with feedback} = \frac{X_o}{X_s} = \frac{A}{1 + A\beta}$$

In case of negative feedback  $|A_f| < |A|$ . In case of positive feedback  $|A_f| > |A|$ . Since in negative feedback gain reduces by the factor  $|1 + A\beta|$  which is greater than one. This factor  $(1 + A\beta)$

is also called as Sensitivity factor.  
Gain Reduces with negative feedback  $A_f = \frac{A}{1 + A\beta}$   
Gain without feedback  
Gain with feedback  
feedback factor

## General Characteristics of negative feedback amplifiers

Increases the stability i.e. Stability of Gain

The transfer gain of the amplifier is not constant as it depends on the factors such as operating point, temperature etc. This lack of stability in an amplifier can be reduced by using negative feedback.

$$\text{Proof } A_f = \frac{A}{1 + A\beta}$$

Differentiating both sides w.r.t.  $A$  we get

$$\frac{dA_f}{dA} = \frac{(1 + A\beta)(1) - A(\beta)}{(1 + A\beta)^2} = \frac{1}{(1 + A\beta)^2}$$

$$dA_f = \frac{dA}{(1 + A\beta)^2}$$

Dividing both sides by  $A_f$  we get

$$\frac{dA_f}{A_f} = \frac{dA}{(1+A\beta)^2} \cdot \frac{1}{A_f} = \frac{dA}{(1+A\beta)^2} \cdot \frac{(1+A\beta)}{A}$$

$$\frac{dA_f}{A_f} = \frac{dA}{A} \left( \frac{1}{1+A\beta} \right) = \frac{dA/A}{(1+A\beta)}$$

$\frac{dA_f}{A_f}$  = change in amplification w.r.t original amplification with feedback

$\frac{dA}{A}$  = change in amplification w.r.t original amplification without feedback.

The above expression shows that the change in gain with feedback is less than change in gain without feedback by a factor  $(1+A\beta)$

Increase Bandwidth

We know that  $A_f = \frac{A}{1+A\beta}$

Using this equation we can write

$$(A_f)_{mid} = \frac{A_{mid}}{1+A_{mid}\beta}$$

$$(A_f)_{low} = \frac{A_{low}}{1+A_{low}\beta}$$

$$(A_f)_{high} = \frac{A_{high}}{1+A_{high}\beta}$$

effect of negative feedback on lower cutoff frequency

We know that

$$(A_f)_{low} = \frac{A_{low}}{1+A_{low}\beta}$$

$$\text{where } A_{low} = \frac{A_{mid}}{1 - j\frac{f_L}{f}}$$

$$(A_f)_{low} = \frac{A_{mid} \left(1 - j \frac{f_L}{f}\right)}{1 + \frac{A_{mid}}{(1 - j \frac{f_L}{f})} \beta}$$

$$(A_f)_{low} = \frac{A_{mid}}{1 - j \frac{f_L}{f} + A_{mid} \beta} = \frac{A_{mid}}{1 + A_{mid} \beta} \cdot \frac{1}{1 - j \left( \frac{f_L}{1 + A_{mid} \beta} \right) \frac{1}{f}}$$

$$\frac{(A_f)_{low}}{A_{fmid}} = \frac{1}{1 - j \left( \frac{f_{Lf}}{f} \right)}$$

$$\text{where } f_{Lf} = \frac{f_L}{1 + A_{mid} \beta}$$

Lower cutoff frequency with feedback reduces compared to without feedback.

Upper cutoff frequency

$$(A_f)_{high} = \frac{A_{high}}{1 + A_{high} \beta} = \frac{A_{mid}}{(1 + j \frac{f}{f_H})} \cdot \frac{1}{1 + \frac{A_{mid}}{(1 + j \frac{f}{f_H})} \beta}$$

$$(A_f)_{high} = \frac{A_{mid}}{1 + j \frac{f}{f_H} + A_{mid} \beta} = \frac{A_{mid}}{1 + A_{mid} \beta} \cdot \frac{1}{1 + j \left( \frac{f}{f_H (1 + A_{mid} \beta)} \right)}$$

$$f_{Hf} = f_H (1 + A_{mid} \beta)$$

Here upper cutoff frequency increases by a factor  $(1 + A_{mid}\beta)$  with feedback.

Therefore Bandwidth = Upper cutoff  $f_{cu}$  - Lower cutoff  $f_{cl}$ .

$$(BW)_f = f_{cu} - f_{cl} = (1 + A_{mid}\beta)f_H - \frac{f_L}{(1 + A_{mid}\beta)}$$

Therefore  $(f_{cu} - f_{cl}) > (f_H - f_L)$

∴ Bandwidth increases with feedback.

### Frequency Distortion

$$A_f = \frac{A}{1 + A\beta} \quad \frac{A}{A\beta} \quad \frac{1}{\beta}$$

In the above expression, if the feedback network does not contain reactive elements, the overall gain becomes independent of frequency. Thus a substantial reduction in frequency and phase distortion is obtained.

Nonlinear distortion: If large signal is applied to an amplifier, then amplifier will operate in nonlinear region along with linear region of operation. As a result of this, the output signal gets distorted. This can be reduced by using negative feedback.

To illustrate this, let us assume that a sinusoidal signal is applied as input and there is only second harmonic generated within the active device. Let second harmonic be  $B_2$  in the absence of feedback and  $B_{2f}$  in the presence of negative feedback. Now we will find relationship between  $B_2$  and  $B_{2f}$ .

Once the feedback is applied, the output contains two terms

①  $B_2$  generated within the active device and ②  $-A\beta B_{2f}$ ,

representing the effect of feedback. Hence we may write

$$B_{2f} = B_2 - A\beta B_{2f}$$

$$\therefore B_{2f} (1 + A\beta) = B_2$$

$$B_{2f} = \frac{B_2}{1 + A\beta} = \frac{B_2}{D}$$

where  $D$  = Desensitizing factor

Reduction in noise It is seen that the nonlinear distortion introduced in an amplifier gets divided by the factor  $D$  if the negative feedback is used. By similar reasoning the noise introduced in an amplifier also gets divided by the factor  $D$  on using negative feedback. By keeping  $D$  large noise can be reduced to larger extent.

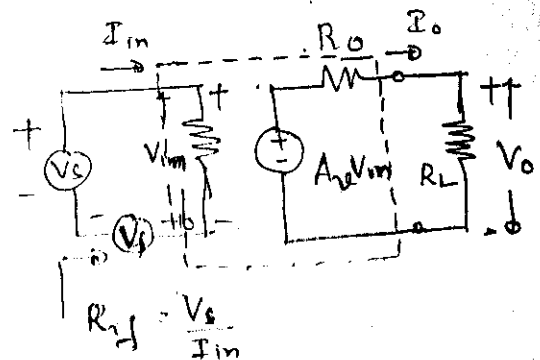
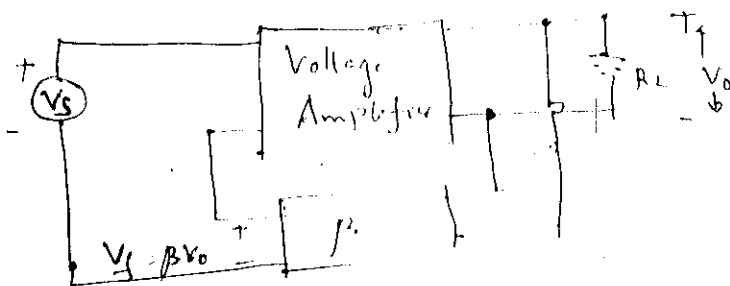
Modification of I/p and o/p Resistance The I/p & o/p resistance of the feedback amplifier get modified depending on the topology of the feedback amplifier.

We may now summarise the merits of negative feedback.

- (i) Stability of transfer gain
- (ii) Reduction in frequency & phase distortion
- (iii) Reduction in nonlinear distortion
- (iv) Reduction in noise
- (v) modification of I/p & o/p impedance
- (vi) Increase Bandwidth

Input and output Resistances

Voltage Series feedback



Eqnd Ckt of the block Diagram

Here  $A_{vs}$  is open ckt voltage gain ( $R_L = \infty$ ) with  $R_s \neq 0$ . Instead of  $A_{vs}$  we will write this as  $A_v$ .

$$(R_{in})_f = R_{in} \frac{V_s}{I_{in}}$$

Applying KVL to the I/p side we get

$$V_s - I_{in} R_{in} - V_i = 0$$



$$V_s = I_{in} R_{in} + V_f$$

$$V_s = I_{in} R_{in} + \beta V_o$$

$$V_o = \frac{A_{vo} V_{in} R_L}{R_L + R_o} = A_v V_{in}$$

Where  $A_v$  is the gain without feedback taking  $R_L$  into account

$$A_v = \frac{A_{vo} R_L}{R_L + R_o}$$

$$V_s = I_{in} R_{in} + \beta A_v V_{in}$$

$$\text{where } V_{in} = I_{in} R_{in}$$

$$V_s = I_{in} R_{in} + \beta A_v I_{in} R_{in}$$

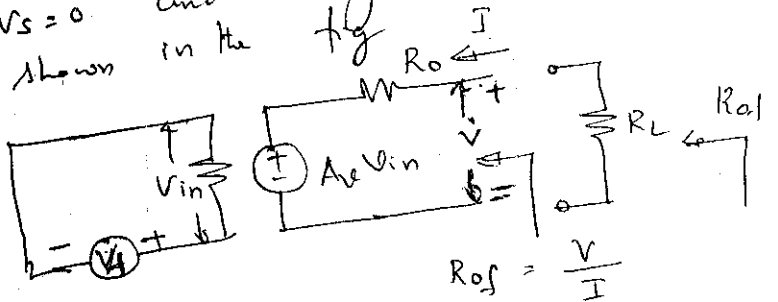
$$V_s = I_{in} R_{in} (1 + A_v \beta)$$

$$\therefore \frac{V_s}{R_{in}} = \frac{R_{in} (1 + A_v \beta)}{R_{in}} = R_{in} (1 + A_v \beta)$$

The input impedance increases with  $-$  feedback

### Output Impedance or o/p Resistance

The o/p resistance can be calculated by shorting i/p source,  $V_s = 0$  and looking into the output terminals with  $R_L$  disconnected, as shown in the fig



Applying KVL for o/p loop

$$A_v V_{in} + I R_o - V = 0$$

$$I = \frac{V - A_v V_{in}}{R_o}$$

$$V_{in} = -V_f = -\beta V$$

$$\text{because } V_s = 0 \quad (V_o = V)$$

$$\therefore I = \frac{V + A_v \beta V}{R_o} = \frac{V (1 + A_v \beta)}{R_o}$$

$$R_{of} = \frac{V}{I} = \frac{R_o}{1 + \beta A_v}$$

$$R_{of}' = R_{of} \parallel R_L$$

$$R_{ef}' = R_{ef} \parallel R_L = \frac{R_{ef} R_L}{R_{ef} + R_L} \quad (10)$$

$$R_{ef}' = \frac{\frac{R_o}{1+A_v\beta} \parallel R_L}{\frac{R_o}{1+A_v\beta} + R_L} = \frac{R_o R_L}{R_o + R_L(1+A_v\beta)}$$

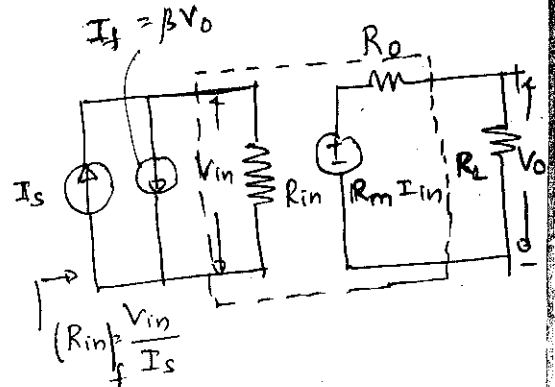
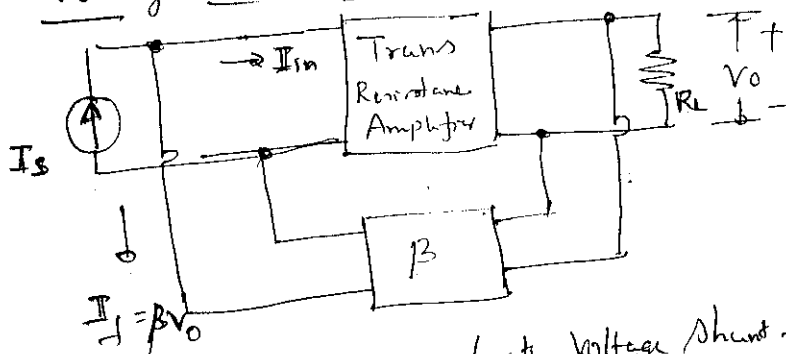
$$R_{ef}' = \frac{(R_o R_L) \parallel (R_o + R_L)}{1 + A_v \left( \frac{R_L}{R_o + R_L} \right) \beta}$$

$$R_{ef}' = \frac{R_o'}{1 + A_v \beta}$$

$$\text{where } R_o' = R_o \parallel R_L$$

where  $A_v$  is gain taking both  $R_s$  and  $R_L$  into account.

### Voltage Shunt-feedback



Transresistance Amplifier with Voltage Shunt feedback

The block diagram can be represented by an eqvt ckt as shown in the fig.

Applying KCL at the node we get

$$I_s = I_{in} + I_f$$

$$= I_{in} + \beta V_o$$

$$\text{The o/p voltage } V_o = \frac{R_m I_{in} R_L}{R_o + R_L} = R_m I_{in}$$

$$\text{where } R_m = \frac{R_m R_L}{R_o + R_L}$$

where  $R_m$  represents the open ckt transresistance without feedback and  $R_m$  represents the transresistance without feedback taking  $R_L$  into account.

Therefore  $I_s = I_{in} + \beta R_m I_{in}$

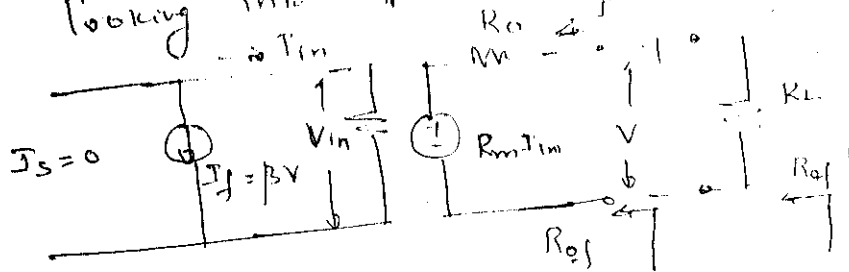
$$I_s = I_{in} (1 + \beta R_m)$$

$$R_{if} = \frac{V_{in}}{I_s} = \frac{V_{in}}{I_{in} (1 + \beta R_m)} = \frac{V_{in} / I_{in}}{(1 + \beta R_m)} = \frac{R_{in}}{1 + \beta R_m}$$

4, Input Resistance reduces with feedback.

### Output Resistance

The o/p resistance is measured by shorting the input source  $V_s = 0$  and looking into o/p terminals with  $R_L$  disconnected.



Applying KVL to the output loop

$$R_m I_{in} + I R_o - V = 0$$

$$I = \frac{V - R_m I_{in}}{R_o}$$

From the I/p side

$$\therefore I = \frac{V + R_m \beta V}{R_o}$$

$$I_{in} = -I_f = -\beta V$$

$$= \frac{V(1 + R_m \beta)}{R_o}$$

$$\therefore \boxed{\frac{V}{I} = \frac{R_o}{1 + R_m \beta} = R_{of}}$$

Taking  $R_L$  into consideration

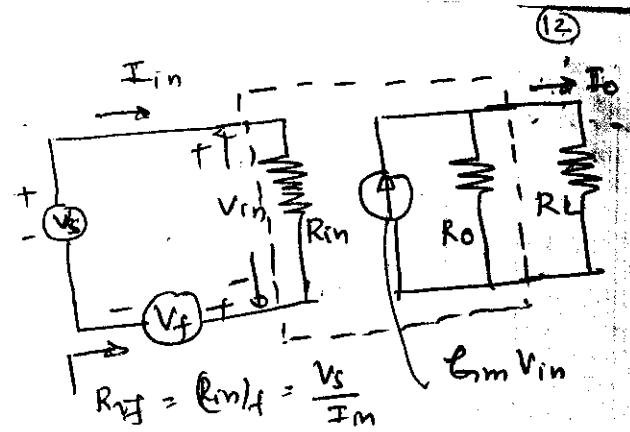
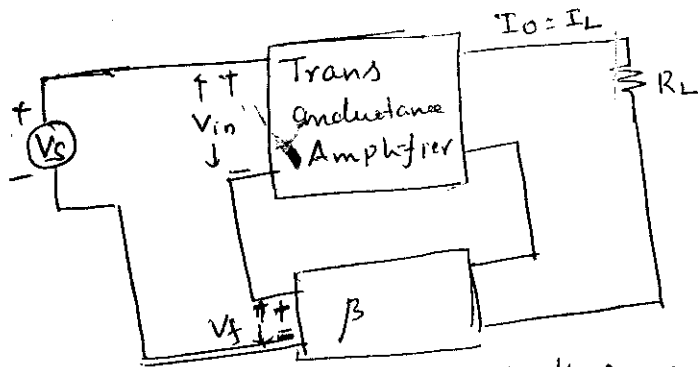
$$R_{of} = R_{of} \parallel R_L = \frac{R_{of} R_L}{R_{of} + R_L}$$

$$= \frac{\left( \frac{R_o}{1 + R_m \beta} \right) (R_L)}{\left( \frac{R_o}{1 + R_m \beta} \right) + R_L} = \frac{R_o R_L}{R_o + R_L (1 + R_m \beta)}$$

$$= \frac{\left( \frac{R_o}{1 + R_m \beta} + R_L \right)}{\left( \frac{R_o R_L}{1 + R_m \beta} \right) / (R_o + R_L)} = \frac{R_o}{1 + R_m \beta}$$

where  $R_o' = R_o \parallel R_L$

## current Series feedback



## Transconductance Amplifier with current Series feedback

Applying KVL for I/p side

$$V_s - I_{in} R_{in} - V_f = 0$$

$$V_s = I_{in} R_{in} + V_f$$

$$V_s = I_{in} R_{in} + \beta I_o$$

$$I_o = \frac{G_m V_{in} R_o}{R_o + R_L} = G_M V_{in}$$

$$\text{where } G_M = \frac{G_m R_o}{R_o + R_L}$$

$G_m$  represents transconductance without feedback and for open ckt condition, where  $G_M$  represents transconductance without feedback taking  $R_L$  into account.

$$V_s = I_{in} R_{in} + \beta G_M V_{in}$$

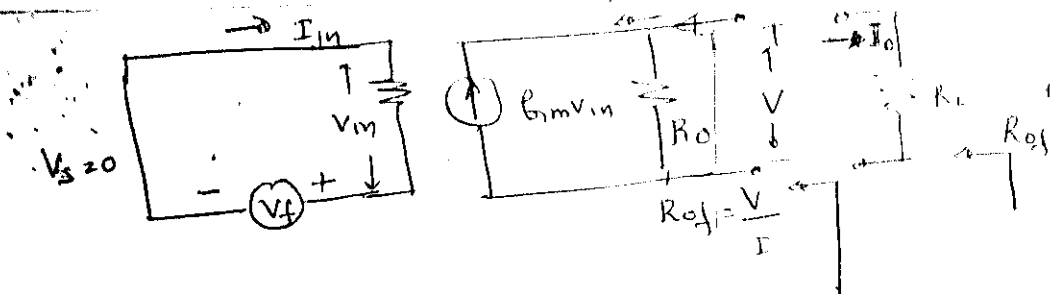
$$V_s = I_{in} R_{in} + \beta G_M I_{in} R_{in}$$

$$V_s = I_{in} R_{in} (1 + \beta G_M)$$

$$\boxed{\frac{V_s}{I_{in}} = R_{eff} = (R_{in})_f = R_{in} (1 + \beta G_M)}$$

To find o/p impedance

To find o/p impedance  $V_s = 0$  and  $R_L$  should be disconnected and



$$I = \frac{V}{R_o} - g_m V_{in}$$

where  $V_{in} = -V_f = -\beta I_o = +\beta I$

$$I = \frac{V}{R_o} - g_m \beta I$$

$$I(1 + g_m \beta) = \frac{V}{R_o}$$

$$R_o(1 + g_m \beta) = \frac{V}{I} = R_{of}$$

$$R_{of}' = R_{of} \parallel R_L$$

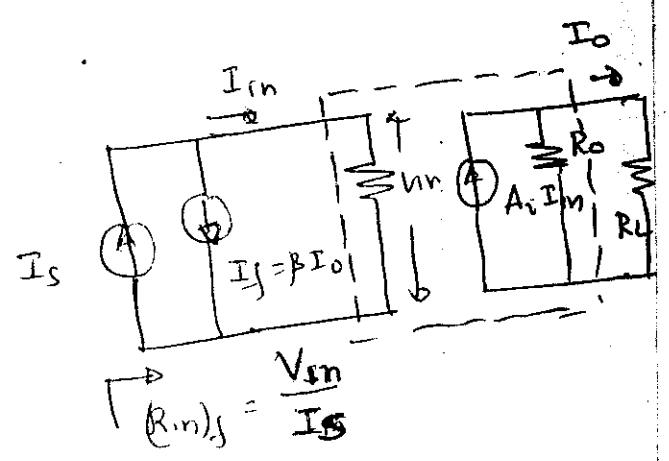
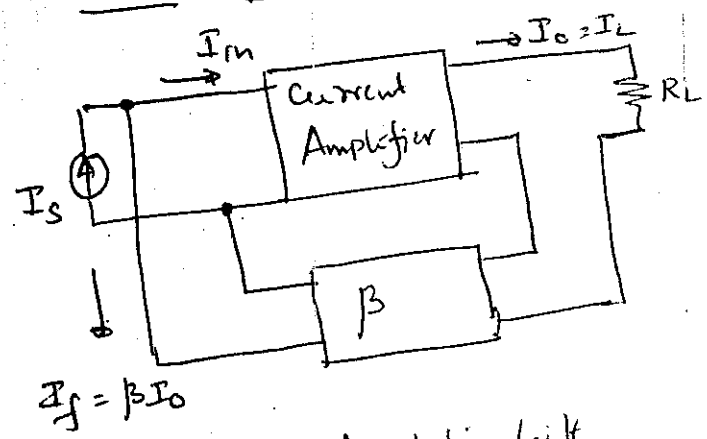
$$R_{of}' = [R_o(1 + g_m \beta)] \parallel R_L$$

$$R_{of}' = \frac{R_o R_L (1 + g_m \beta)}{R_o(1 + g_m \beta) + R_L} = \frac{\left(\frac{R_o R_L}{R_o + R_L}\right) (1 + g_m \beta)}{1 + \frac{R_o g_m \beta}{R_o + R_L}}$$

$$R_{of}' = \frac{R_o' (1 + g_m \beta)}{1 + \beta g_m}$$

Because  $g_m = \frac{g_m R_o}{R_o + R_L}$

### Current Shunt feedback



### Current Amplifier with Current Shunt feedback

Applying KCL to the  $I_p$  node we get

$$I_s = I_m + I_i$$

$$I_s = I_m + \beta I_o$$

$$\text{The o/p Voltage } V_o = \left( \frac{A_i I_m R_o}{R_o + R_L} \right) R_L$$

$$\text{And } I_o = \frac{A_i I_m R_o}{R_o + R_L} = A_I I_m$$

$$\text{Where } A_I = \frac{A_i R_o}{R_o + R_L} \text{ taking } R_L \text{ into consideration.}$$

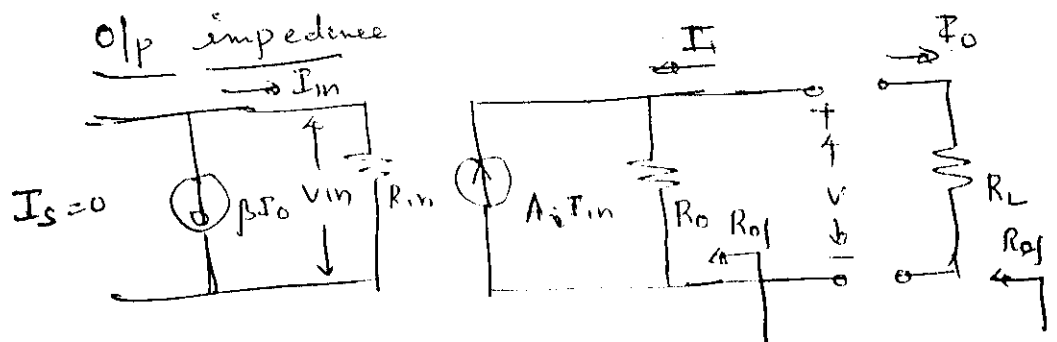
$$I_s = I_m + \beta A_I I_m$$

$$I_s = I_m (1 + A_I \beta)$$

$$I_m = \frac{V_{in}}{R_{in}}$$

$$\therefore I_s = \frac{V_{in}}{R_{in}} (1 + A_I \beta)$$

$$\boxed{\frac{V_{in}}{I_s} = (R_{in})_f = \frac{R_{in}}{1 + A_I \beta}}$$



Applying KCL to o/p side

$$I = \frac{V}{R_o} - A_i I_m$$

$$I_m = -I_f = -\beta I_o$$

$$\text{where } I_o = -I$$

$$\text{Therefore } I_m = \beta I$$

$$\text{Therefore } I = \frac{V}{R_o} - A_i \beta I$$

$$I + A_i \beta I = \frac{V}{R_o}$$

$$I(1 + A_i \beta) = \frac{V}{R_o}$$

$$\text{Therefore } \boxed{\frac{V}{I} = R_o(1 + \beta A_i) = R_{of}}$$

$$R_{of}' = R_{of} \parallel R_L$$

$$= \frac{R_o(1 + \beta A_i) R_L}{R_L + R_o(1 + \beta A_i)}$$

$$= \frac{\frac{R_o R_L}{R_o + R_L} (1 + \beta A_i)}{1 + \frac{\beta R_o A_i}{R_o + R_L}}$$

$$R_{of}' = \frac{R_o' (1 + \beta A_i)}{1 + \beta A_i}$$

$$\text{where } R_o' = R_o \parallel R_L$$

$$A_i = \frac{A_v R_o}{R_o + R_L}$$

### Method of Analysis of Feedback Amplifier

The entire feedback amplifier may be separated into two blocks, the basic amplifier  $A$  and the feedback network  $\beta$ . Then with the knowledge of  $A$  &  $\beta$ , we may calculate the characteristics of the feedback amplifier.

The procedure that is applied to obtain the basic amplifier configuration without feedback, but taking the loading of  $\beta$  network into consideration.

(A) To find the I/p ckt

(i) For Voltage Sampling

Set  $V_o = 0$  or short ckt the o/p

(ii) For Current Sampling

Set  $I_o = 0$  or o/p loop is open circuited

(B) To find the o/p ckt

(i) For Series Comparison

Set  $I_{in} = 0$  or open the I/p loop

(ii) For Shunt Comparison

Set  $V_{in} = 0$  or short the I/p node

Complete Analysis The complete analysis of a feedback amplifier may be done by carrying out the following steps.

(1) Identify the topology

(a) To find whether the feedback signal is applied in series or in shunt with external excitation.

(b) find whether the sampled signal is voltage or current

(ii) Basic amplifier ckt is drawn without feedback but taking into the effect of loading because of feedback network

(iii) If the feedback signal is a voltage the Thevenin source is used, if feedback signal is current the Norton source is used.

(iv) Each active device is replaced by its equivalent circuit.

(v)  $\beta$  is calculated

(vi) Calculate Gain A

(vii) Then finally calculate  $A, \beta, D, R_{if}, R_{of}$  &  $R_{of}'$

Analysis of Feedback Amplifier (Table)

Topology Characteristic	Voltage Series	Current Series	Current Shunt	Voltage Shunt
Feedback Signal	Voltage	Voltage	Current	Current
Sampled Signal	Voltage	Current	Current	Voltage
To find o/p loop, set	$V_o = 0$	$I_o = 0$	$I_o = 0$	$V_o = 0$
To find o/p loop, set	$I_m = 0$	$I_m = 0$	$V_m = 0$	$V_m = 0$
Signal Source form (i/p side)	Thevenin	Thevenin	Norton	Norton
$\beta$ (Feedback factor)	$V_f / V_o$	$V_f / I_o$	$I_f / I_o$	$I_f / V_o$
Transfer Gain	$A_v = \frac{V_o}{V_{in}}$	$G_m = \frac{I_o}{V_m}$	$A_i = \frac{I_o}{I_m}$	$R_m = \frac{V_o}{I_{in}}$
$D = 1 + \beta A$	$1 + \beta A_v$	$1 + \beta G_m$	$1 + \beta A_i$	$1 + \beta R_m$
$A_f$	$A_v / D$	$G_m / D$	$A_i / D$	$R_m / D$
$R_{if}$	$R_i / D$	$R_i / D$	$R_o / D$	$R_i / D$
$R_{of}$	$R_o / (1 + \beta A_v)$	$R_o (1 + \beta G_m)$	$R_o (1 + \beta A_i)$	$\frac{R_o}{1 + \beta R_m}$
$R_{of}'$	$R_o' / (R_o' / I_m)$	$[R_o' (1 + \beta G_m)] / I_m$	$R_o' (1 + \beta A_i)$	$\frac{R_o}{R_o'}$



## POWER AMPLIFIERS (Large Signal Amplifiers)

(79)

Power Amplifiers are large signal amplifiers, which raise the power level of the signals. In power amplifiers, the output voltage and current swings are so large that the amplifying device cannot be replaced by the linear model. In such case a graphical analysis is used.

### Difference between Voltage and Power Amplifier

Voltage Amplifier A voltage amplifier is designed to achieve maximum voltage amplification. The voltage gain is given by

$$A_v = \frac{\beta R_c}{R_{in}}$$

In order to achieve high voltage amplification, the following features are incorporated. Such as

- (i) The transistor with high  $\beta$  ( $> 100$ ) is used & the transistors have thin base.
- (ii) The i/p Resistance  $R_{in}$  should be low in comparison to collector Resistance  $R_c$ .  $R_c$  should be high.
- (iii) To achieve high gain  $R_c$  should be high.
- (iv) Usually  $R_c$  coupling is used.
- (v) i/p voltage is low and o/p power is low.
- (vi) It has only magnitude and phase distortion.

Power Amplifier : The power amplifiers are designed to obtain maximum o/p power. In order to achieve high power amplification, the following features are incorporated in such amplifiers.

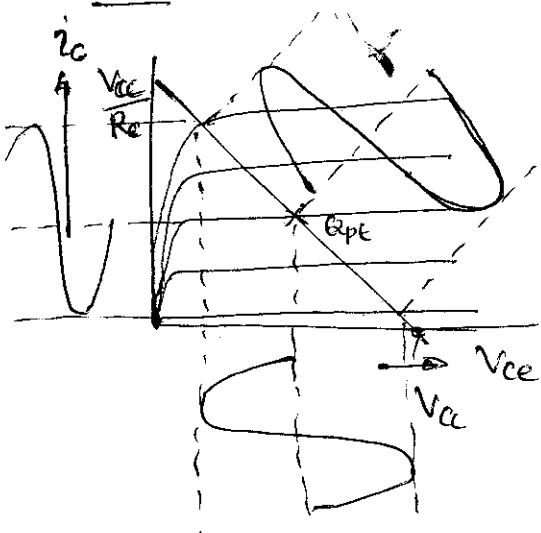
- (i) The transistor with comparatively smaller value of  $\beta$  is used because it uses power transistors. In power transistors base width is higher to handle large currents, therefore  $I_B$  is higher &  $\beta$  will be less.
- (ii) Collector Resistance is made low.
- (iii) Transformer coupled is normally used.
- (iv) Collector current is high.
- (v) i/p voltage is high & o/p power is high.

Classification of Power Amplifier : The operating point is fixed by selecting the proper dc biasing. The operating point

is selected on the dc loadline which plotted on the  $i_c$  vs  $V_{ce}$  characteristics of the transistor. The position of the Qpt decides the class of operation of the Power Amplifier. It can be Class A, Class B, Class AB, & Class C.

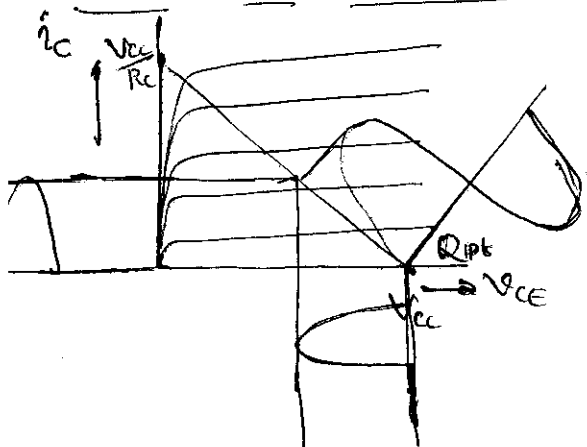
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### Class A Power Amplifier



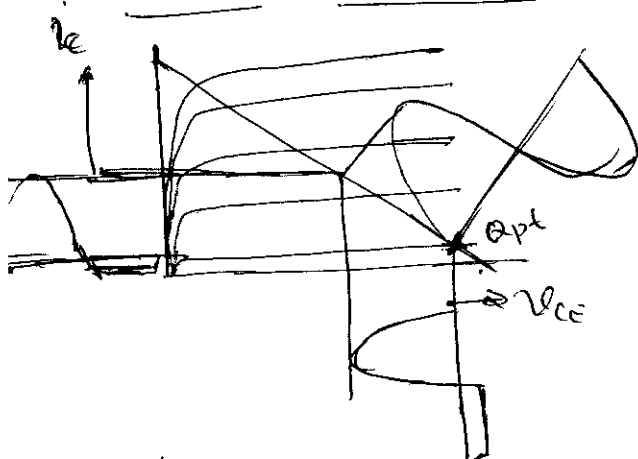
- Operating point (Qpt) is selected on the middle of the loadline. Therefore transistor conducts for entire  $360^\circ$ .
- The transistor conducts for entire  $360^\circ$ .
- The  $\% \eta$  is 25% with  $R_c$  and 50% with Transformer in the collector instead of  $R_c$ .
- It needs only one transistor to get o/p.

### Class B Power Amplifier



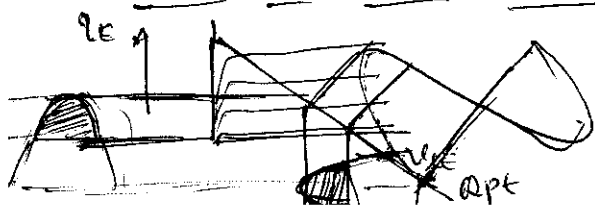
- Operating Point is selected exactly at cutoff or on  $x$  axis. Therefore transistor conducts only  $180^\circ$ .
- The  $\% \eta$  is max of 78.5%.
- It needs two transistors to get o/p.
- There is a distortion at o/p (called crossover distortion).

### Class AB Power Amplifier



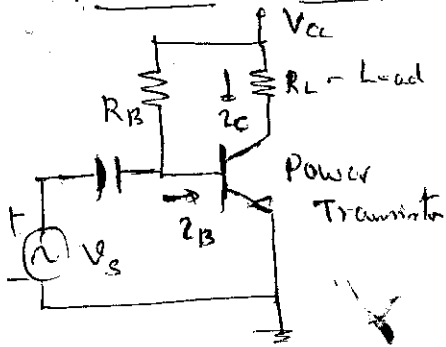
- Operating Point is selected slightly above Cutoff.
- Conduction angle is slightly greater than  $180^\circ$ .
- The  $50\% < \% \eta < 78.5\%$ .
- It needs two transistors to get o/p.
- Crossover distortion is eliminated.

### Class C Power Amplifier



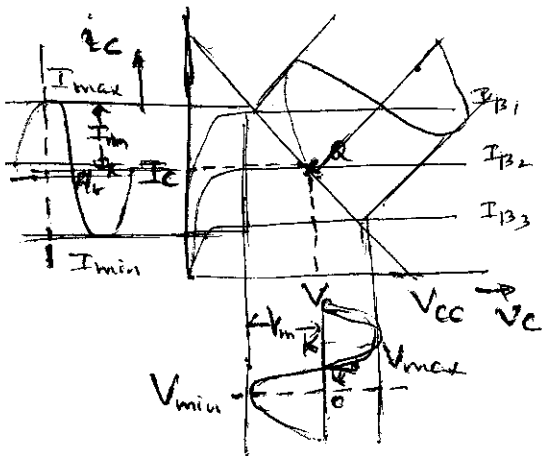
- The operating Point is fixed beyond cutoff.
- Conduction angle is less than  $180^\circ$ .
- The  $\% \eta > 78.5\%$ .
- It needs one transistor and he act in collector & act o/p.

Claim A Power Amplifier : The ckt showing simple transistor



amplifier that supplies power to a pure resistive load  $R_L$ .  $i_c$  represents the total instantaneous collector current,  $i_c$  designates the instantaneous variation from the quiescent value  $I_c$  of the collector current. Similarly  $i_B$ ,  $i_b$ ,  $I_B$  represents corresponding base currents. The total instantaneous

collector-emitter voltage is given by  $V_c$  and the instantaneous variation from the quiescent value  $V_c$  is represented by  $v_c$



Let us assume that static o/p characteristics are equidistant for equal increments of input base current  $i_b$ . Then input signal  $i_b$  is sinusoidal, then o/p current and voltage are also sinusoidal. Under these conditions nonlinear distortion is negligible.

The output power may be found graphically

as follows  $P = V_c I_c = I_c^2 R_L$

The  $V_c$  and  $I_c$  are the rms values of o/p voltage & o/p current. Can be determined graphically between the maximum and minimum voltage and current swings.

$$I_c = \frac{I_m}{\sqrt{2}} = \frac{I_{max} - I_{min}}{2\sqrt{2}}$$

$$V_c = \frac{V_m}{\sqrt{2}} = \frac{V_{max} - V_{min}}{2\sqrt{2}}$$

The total power  $P_{out} = \frac{V_m I_m}{2} = \frac{I_m^2 R_L}{2} = \frac{V_m^2}{2R_L}$

which may be also written as  $P = \frac{(V_{max} - V_{min})(I_{max} - I_{min})}{8}$

$$\therefore \eta = \frac{P_{out}}{P_{in}} = \frac{P_{ac}}{P_{dc}} = \frac{(V_{max} - V_{min})(I_{max} - I_{min})}{8 I_{dc} V_{cc}} \times 100$$

% max  $\eta$  when  $V_{min} = 0$ ,  $I_{min} = 0$

$$V_{max} = V_{cc} \quad V_{min} = 0 \quad I_{max} = 2I_c$$

$$\text{max } \% \eta = \frac{V_{cc} 2I_c}{8 (V_{cc})(I_c)} \times 100 = 25\%$$

(82) 4

Second - Harmonic Distortion. We know that the transistor is ideally not operate in perfectly as a linear device. This is true from dynamic transfer characteristic is not a straight line. This nonlinearity arises because the static o/p characteristics are not equidistant straight lines for constant increments of input excitation. If the dynamic curve is nonlinear over the operating range, the waveform of the output voltage differs from that of the i/p signal. Distorting this type is called nonlinear or amplitude distortion. To investigate this distortion we assume that the dynamic curve with respect to  $Q_{pt}$  can be represented by a parabola rather than a straight line. Therefore the incremental collector current  $i_c$  and incremental base current  $i_b$  is related by the expression

$$i_c = G_1 i_b + G_2 i_b^2 + \dots$$

where  $G_i$  is constant

If i/p  $i_b = I_m \cos \omega t$

Then  $i_c = G_1 I_m \cos \omega t + G_2 I_m^2 \cos^2 \omega t$

Since  $\cos^2 \omega t = \frac{1}{2} + \frac{1}{2} \cos 2\omega t$

Then the expression for the total instantaneous current  $i_c$  reduces to the form

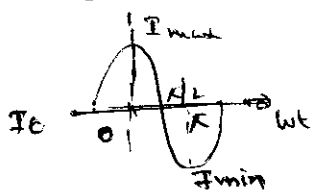
$$i_c = I_c + i_c = I_c + B_0 + B_1 \cos \omega t + B_2 \cos 2\omega t + \dots$$

where the  $B_i$  are constants which may be evaluated in terms of  $G_i$ 's. The term  $B_0$  is the dc term added after applying i/p. The term  $\cos 2\omega t$  represents second harmonic and  $\cos 3\omega t$  etc represents higher harmonic terms. The total dc component of the ckt is  $I_c + B_0$ . Parabolic nonlinear distortion introduces into the o/p a component whose frequency is twice that of the sinusoidal input excitation. Also, since a sinusoidal i/p signal changes the average value of the o/p current, rectification takes place.

When  $\omega t = 0$   $i_c = I_{max}$

$\omega t = \pi/2$   $i_c = I_c$

$\omega t = \pi$   $i_c = I_{min}$



Substituting the values in the above expression

$$I_{max} = I_c + B_0 + B_1 + B_2$$

$$I_c = I_c + B_0 - B_2$$

$$I_{min} = I_c + B_0 - B_1 + B_2$$

from the second expression  $B_0 = B_2$   
 from the first & third expression

$$B_1 = \frac{I_{max} - I_{min}}{2}$$

Substituting the value  $B_1$  in first expression it yields

$$B_2 = B_0 = \frac{I_{max} + I_{min} - 2I_c}{4}$$

The second harmonic distortion  $D_2 = \left| \frac{B_2}{B_1} \right|$

Higher-order Harmonic distortion : In earlier case we assume Parabolic dynamic characteristics considering the o/p swing is small. Since in power amplifier o/p swing is very large, then it is necessary to express the dynamic transfer characteristic by a power series of the form

$$i_c = G_1 v_b + G_2 v_b^2 + G_3 v_b^3 + G_4 v_b^4 + \dots$$

Replacing  $v_b = I_m \cos \omega t$ , then by proper trigonometric transformation we can write

$$i_c = I_c + B_0 + B_1 \cos \omega t + B_2 \cos 2\omega t + B_3 \cos 3\omega t + \dots$$

It clearly says that the o/p waveform possess even symmetry  
 $i(\omega t) = i(-\omega t)$

Power output : If the distortion is not negligible, the power delivered at the fundamental frequency is

$$P_1 = \frac{B_1^2 R_L}{2}$$

However the total o/p power is

$$P = (B_1^2 + B_2^2 + B_3^2 + B_4^2 + \dots) \frac{R_L}{2}$$

$$= \frac{B_1^2 R_L}{2} \left[ 1 + \left( \frac{B_2}{B_1} \right)^2 + \left( \frac{B_3}{B_1} \right)^2 + \left( \frac{B_4}{B_1} \right)^2 + \dots \right]$$

$$\text{or } P = P_1 [1 + D^2]$$

where the total distortion or distortion factor is defined as

$$D = \sqrt{D_2^2 + D_3^2 + D_4^2 + D_5^2 + \dots}$$

## The Transformer Coupled Audio power Amplifier

(84)

If the load resistance is connected directly in the o/p of the power stage, then the A/C current passes through the load resistance, this current represents a considerable wastage of power because it does not contribute to AC component of power. Furthermore, it is not advisable to pass dc through the load resistance, because load Res may be speaker also. For these reasons usually an arrangement with output transformer is employed.

Impedance matching: To transfer a significant amount of power to a load such as loudspeaker with voice coil impedance of  $5\Omega$  to  $15\Omega$ , it is necessary to use an o/p matching transformer. This is required because the internal resistance of the device is more when compared to load Res, therefore most of the power is lost in the active device.

The impedance matching property says

$$\frac{V_1}{V_2} = \frac{N_1}{N_2} \quad \text{and} \quad \frac{I_1}{I_2} = \frac{N_2}{N_1}$$

where  $V_1, V_2$  are Primary (secondary) voltage

$I_1, I_2$  are Primary (secondary) current

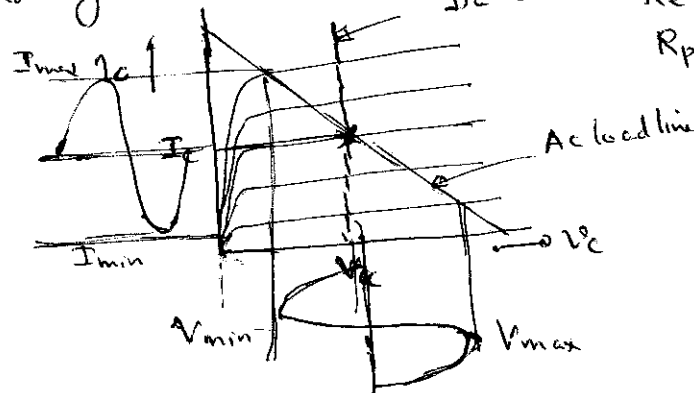
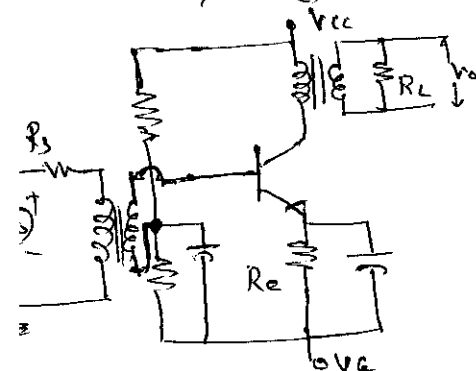
$N_1, N_2$  are number of Primary (secondary) turns

If  $N_2 < N_1$  then the transformer reduces the voltage in proportion to turns ratio  $n = N_2/N_1$  and steps up the current in the same ratio because o/p power = i/p power.

$$\therefore \frac{V_1}{I_1} = \frac{1}{n^2} \frac{V_2}{I_2}$$

where the  $\frac{V_1}{I_1} = R_L'$  is reflected load res in the Primary because of secondary load Res  $R_L$

Dc loadline  $R_e \approx 0$  (very small)  
 $R_p \approx 0$  (Primary Res of Transformer)



We will now examine various components of power. Suppose that the stage is supplying power to a pure resistive load. The average power  $I_p$  from the dc supply is  $V_{cc} I_c$ . The power absorbed by the o/p ckt is  $I_c^2 R_L + I_c V_c$ , where  $I_c$ ,  $V_c$  are the rms o/p current and voltage, respectively and where  $R_L$  is the static load resistance. If  $P_D$  is the average power dissipated by the active device, then

$$V_{cc} I_c = I_c^2 R_L + I_c V_c + P_D$$

$$\text{Since } V_{cc} = V_c + I_c R_L$$

$$P_D = V_c I_c - V_c I_c \cos \theta$$

$P_D$  may be written as

If load is not pure resistive then  $V_c I_c$  is replaced by  $V_c I_c \cos \theta$  where  $\cos \theta$  is the power factor of the load.

This clearly says that if signal is not applied then the transistor is capable of withstanding entire power  $V_{cc} I_c$ .

Conversion Efficiency: A measure of the ability of an active device to convert the dc power into the ac (signal) power delivered to the load is called the conversion efficiency or theoretical efficiency. The figure of merit, designated  $\eta$ , is also called the collector-circuit efficiency for a transistor amplifier.

$$\eta = \frac{\text{Signal Power delivered to load}}{\text{dc Power supplied to o/p ckt}} \times 100$$

$$\text{In general } = \frac{\frac{1}{2} B_1 R_L}{V_{cc} (I_c + B_0)} \times 100$$

$$\text{If distortion is negligible then } \eta = \frac{\frac{1}{2} V_m I_m}{V_{cc} I_c} \times 100$$

$$V_m = \frac{V_{\max} - V_{\min}}{2}$$

$$I_m = \frac{I_{\max} - I_{\min}}{2}$$

$$\therefore \% \eta = \frac{(V_{\max} - V_{\min})(I_{\max} - I_{\min})}{8 V_{cc} I_c} \times 100$$

$$\text{Max } \% \eta \quad V_{\max} = 2V_{cc} \quad V_{\min} = 0 \quad I_{\max} = 2I_c$$

$$I_{\min} = 0$$

$$\therefore \% \eta = \frac{2V_{cc} \cdot 2I_c}{8(V_{cc} I_c)} \times 100 = 50\%$$

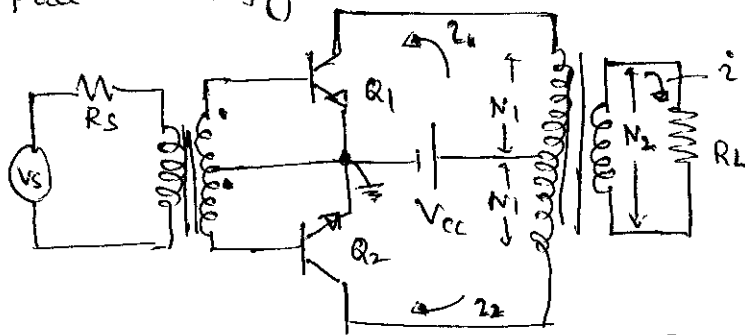
We know that generalized formula for

$$\% \eta = \left( \frac{V_{max} - V_{min}}{V_{max} + V_{min}} \right) 50$$

$$\therefore V_{cc} = \frac{V_{max} + V_{min}}{2}$$

2)  $V_{min} \ll V_{max}$ , then  $\% \eta$  approach to 50%.

Push-Pull Amplifier: The distortion introduced by the nonlinearity of the dynamic transfer characteristic may be eliminated by using Push Pull Configuration.



The push pull amplifier uses center tap transformer, if they make  $Q_1$  base +ve, then it make  $Q_2$  base -ve by the same amount.

By considering  $i_{b1} = I_m \cos \omega t$  applied to  $Q_1$ , then

$$i_{b1} = I_c + B_0 + B_1 \cos \omega t + B_2 \cos 2\omega t + B_3 \cos 3\omega t + \dots$$

Corresponding to  $Q_2$   $i_{b2} = -i_{b1} = -I_m \cos(\omega t + \pi)$

$$i_{b2}(\omega t) = i_b(\omega t + \pi)$$

$$\therefore i_{b2} = I_c + B_0 + B_1 \cos(\omega t + \pi) + B_2 \cos 2(\omega t + \pi) + \dots$$

$$i_{b2} = I_c + B_0 - B_1 \cos \omega t + B_2 \cos 2\omega t + B_3 \cos 3\omega t + B_4 \cos 4\omega t + \dots$$

$$\therefore \text{o/p current } i = K(i_{b1} - i_{b2}) = 2K(B_1 \cos \omega t + B_3 \cos 3\omega t + \dots)$$

In this expression we can see that all even harmonics are eliminated. This will be applicable only if the transistors are identical. Since o/p current does not contain even harmonic terms, we can say that the pushpull system possess both "half wave" or "mirror" symmetry in addition to the zero axis symmetry.

Advantages (i) Because it avoids even harmonics in the o/p, the o/p power per active device is more for a given amount of distortion.

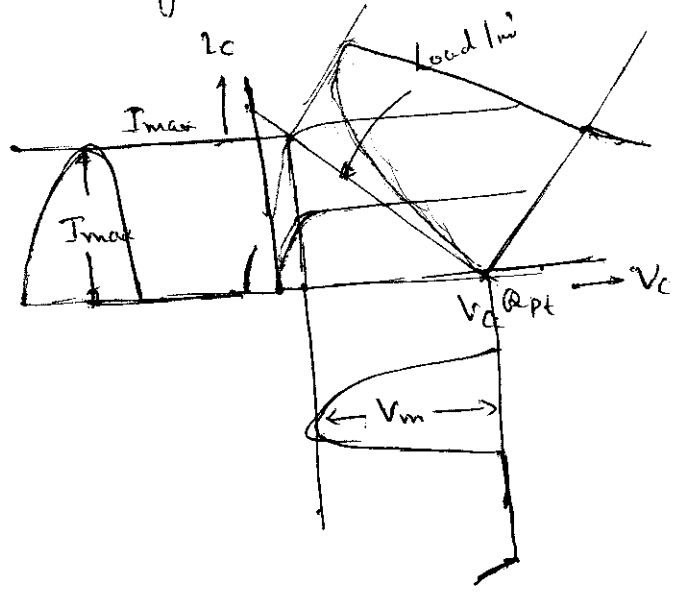
(ii) Since current flows in the transformer is equal & opposite, there is no problem of dc saturation in the transformer.

(iii) The ripple in the power supply will affect the load because its error is canceled because current flows in the o/p direction in the transformer.



# Class B Amplifier

The ckt in class B push pull amplifier is the same as in class A except that the device is biased at cutoff. Class B is preferred over because of higher efficiency, greater o/p power and negligible power loss when there is no signal. The disadvantage is harmonic distortion is higher, therefore self bias cannot be used and the supply must have good regulation.



The waveform shows only for one transistor \$Q\_1\$ and the o/p for other transistor \$Q\_2\$ is of same type with \$180^\circ\$ phase shift. The load current is because of two transistors are ideal. Perfect sinusoidal if transistors are ideal.

$$\therefore P_{out} = \frac{I_m}{\sqrt{2}} \frac{V_m}{\sqrt{2}} = \frac{I_m V_m}{2}$$

(Considering the both the transistors & o/p is sine wave \$\therefore I\_{rms} = \frac{I\_m}{\sqrt{2}}\$)

$$P_{out} = \frac{I_m}{2} (V_{max} - V_{min}) = \frac{I_m}{2} (V_{CC} - V_{min})$$

Since the transistor conducts only after applying i/p signal, the initial current is zero, then once the transistor conducts then \$I\_{dc} = \frac{I\_m}{\pi}\$ for one transistor. But the total dc current drawn because of two transistors is given by

$$P_{dc} = P_{in} = \frac{2 I_m}{\pi} V_{CC}$$

\$\therefore\$ Collector ckt efficiency  $\eta = \frac{P}{P_i} \times 100 = \frac{\pi V_m}{4 V_{CC}} \times 100$

$$\therefore \eta = \frac{\pi}{4} \left( 1 - \frac{V_{min}}{V_{CC}} \right) 100$$

\$\therefore\$ Max efficiency will be when \$V\_{min} = 0\$, 78.5% for Class B when compared to 50% for Class A.

The collector dissipation \$P\_c\$ (in both transistors) is the difference between the power i/p to the collector ckt and the power delivered to the load.

$$P_c = P_{in} - P_{out} = \frac{2 I_m V_{CC}}{\pi} - \frac{I_m V_m}{2} = \frac{2}{\pi} \frac{V_{CC} V_m}{R_L} - \frac{V_m^2}{2 R_L}$$

(\$\because I\_m = \frac{V\_m}{R\_L}\$)

This above equation shows that collector power dissipation

is Zero at no signal ( $V_m = 0$ ), rises as  $V_m$  increases, & reaches a max at  $V_m = \frac{2V_{cc}}{\pi}$  (10) (88)

$$\therefore \frac{dP_c}{dV_m} = \frac{2}{\pi} \frac{V_{cc}}{R_L} - \frac{2V_m}{2R_L} = 0$$

$$\frac{V_m}{R_L} = \frac{2V_{cc}}{\pi R_L} \quad \therefore V_m = \frac{2V_{cc}}{\pi}$$

$\therefore$  Peak Power dissipation

$$P_c = (P_c)_{max} = \frac{2}{\pi} \left( \frac{V_{cc}}{R_L} \right) \left( \frac{2V_{cc}}{\pi} \right) - \left( \frac{2V_{cc}}{\pi} \right)^2 \left( \frac{1}{2R_L} \right) = \frac{2V_{cc}^2}{\pi^2 R_L}$$

$$(P_{out})_{max} = \frac{I_m}{2} (V_m - V_{min}) \quad \text{when } V_m = V_{cc} \quad I_m = \frac{V_m}{R_L} = \frac{V_{cc}}{R_L}$$

$$V_{min} = 0$$

$$(P_{out})_{max} = \frac{V_{cc}^2}{2R_L}$$

$$\therefore (P_c)_{max} = \frac{4}{\pi^2} (P_{out})_{max}$$

1. The two transistors dissipate 40% of its output power is each transistor dissipates 20% of its total o/p power. If the total o/p power is 10W and then each transistor dissipates max power of 2W.

2. Power dissipation is max, then  $\eta$  reduces to 50%.

$$\eta = \frac{P_{out}}{P_{in}} = \frac{\frac{I_m}{2} (V_{max} - V_{min})}{\frac{2 I_m V_{cc}}{\pi}} \times 100 = \frac{V_m}{4(V_{cc}/\pi)} \times 100$$

$$\eta = \frac{2V_{cc}/\pi}{4(V_{cc}/\pi)} \times 100 = 50\% \quad \left[ \text{when } (P_c)_{max} \right. \\ \left. V_m = \frac{2V_{cc}}{\pi} \right]$$

Difference between Class A & Class B Power Amplifier

① The max Conversion  $\eta$  is 78.5% in Class B System

Compared with 50% in Class A operation.

② There is no collector current in Class B System if there is no excitation, whereas there is a drain from the power supply in Class A System even at Zero Signal.

③ We also note that in Class B amplifier the dissipation at the collector is zero in the quiescent state and increases with the excitation, whereas the heating of the collector in Class A system is a maximum at zero i/p & decreases

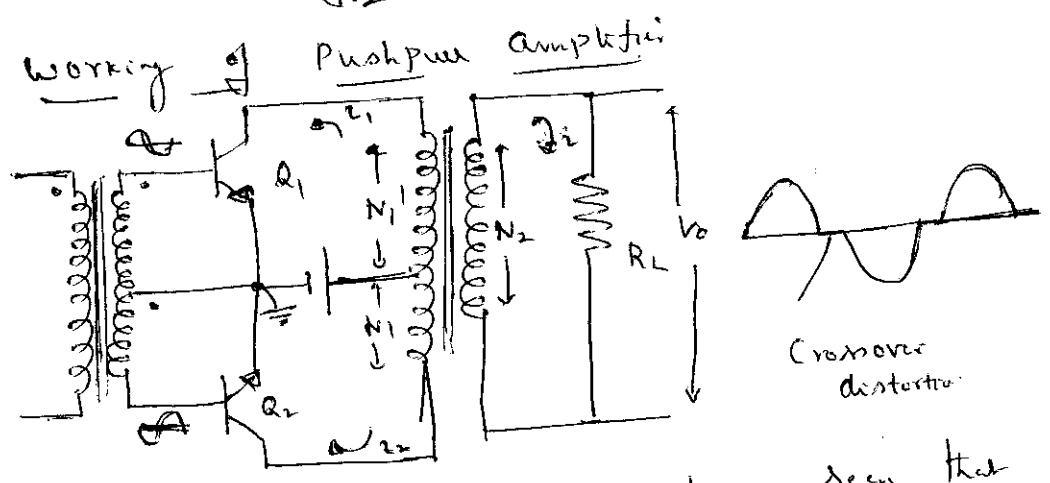
(89)

- as the signal increases.
- (4) Since the direct current increases with the signal in a class B amplifier, the power supply must have good regulation.
  - (5) The power dissipation across each transistor in Class A system is higher when compared to Class B system.

Distortion in Class B Power Amplifier: The principal contribution to distortion is the third harmonic (because all even harmonics are canceled out because of push-pull operation), given by

$$D_3 = \frac{|B_3|}{|B_1|} \cdot \text{Therefore } P = \frac{(1 + D^2) B_1^2 R_L}{2} = \frac{(1 + D_3^2) B_1^2 R_L}{2}$$

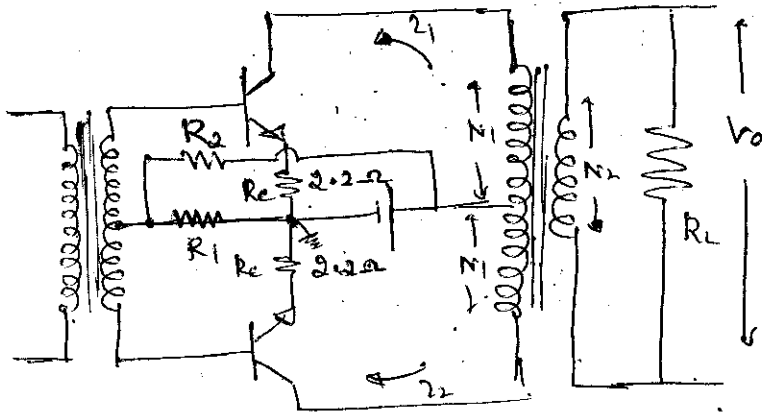
where  $R_L' = \left(\frac{N_1}{N_2}\right)^2 R_L$



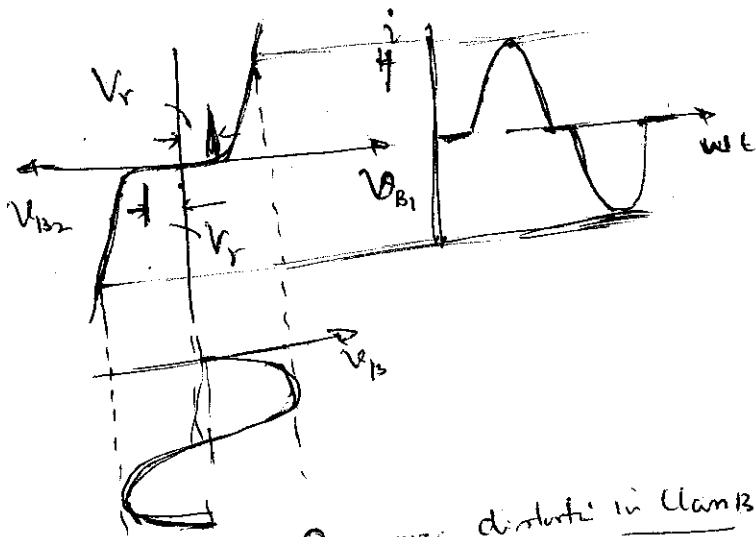
In the above circ we have seen that in the positive cycle transistor  $Q_1$  conducts, but it conducts only after the  $I_p$  voltage exceeds the cut-in voltage of BE junction diode. Till then  $o/p = 0$ . Similarly when the  $I_p$  is  $-ve$  cycle the base of transistor  $Q_2$  will be  $+ve$   $\therefore$  the transistor  $Q_2$  will be pushed into conduction and transistor  $Q_1$  is pulled out of conduction because the name Push-Pull operation. But  $Q_2$  conducts only if  $I_p$  becomes more negative compared to  $-0.6V$  because, the transistor  $Q_2$  base exceeds  $0.6V$  Till transistor  $Q_2$  conducts  $o/p$  is zero. Therefore the  $o/p$  voltage zero when  $I_p$  is crossing over from  $0.6V$  to  $-0.6V$ . This type of distortion in the  $o/p$  is called Crossover distortion. The  $o/p$  is obtained because current flowing at  $(I_1 - I_2)$ . Hence the problem of dc saturation

of the transformer is eliminated because the current flows <sup>(12)</sup> in opposite direction in the primary winding. The even harmonics are eliminated therefore distortion is low. The ripple in the power supply is eliminated. The power dissipation across each transistor is 20% of the max o/p power. The  $\eta$  is 78.5%. <sup>(90)</sup> The  $\eta$  reduces to 50% if the power dissipation is max.

### Class AB operation



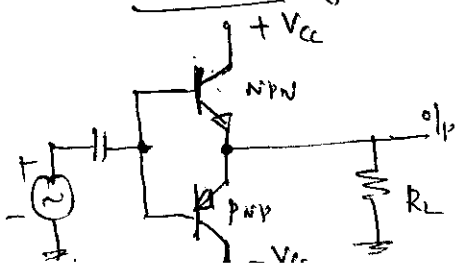
until emitter junction is forward biased. Under these conditions, the sinusoidal base excitation will not result in sinusoidal o/p current. We have seen that o/p is zero



Crossover distortion in Class B

The crossover distortion is avoided in Class AB compared to Class B with low in efficiency & standby power. The Resistor  $R_E$  provides stability for the ckt.

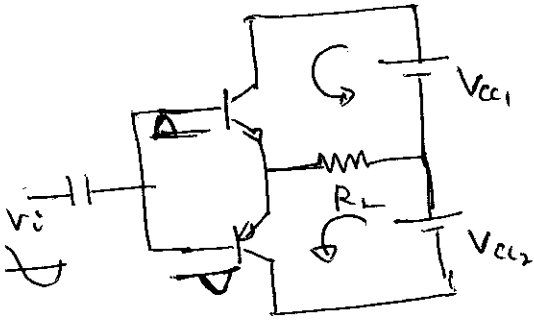
### Complementary Symmetry (one n-p-n & one p-n-p type) Power Amplifier



The ckt eliminates both I/p & o/p transform. It uses npn & pnp transistors so it is called as Complementary Symmetry. It will be difficult to get identical transistors. Here even harmonics will not be canceled out. Very often it uses negative feedback. It also leads to crossover distortion.

## Complementary - Symmetry Circuit.

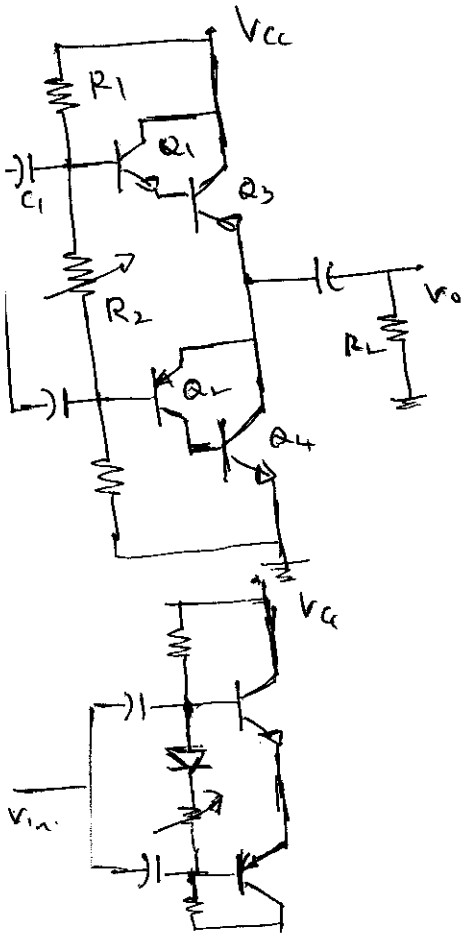
Using Complementary - Transistors (npn & pnp) it is possible to obtain a full cycle o/p across a load using half-cycle operation from each Transistor, whereas a single 3p signal is applied to the base of both transistors, the transistors being of opposite type, will conduct on opposite half cycles of the 3p. For positive half cycle npn transistor will conduct and it will result in the o/p across the load & for negative half cycle pnp transistor will conduct and results in the o/p across the load.



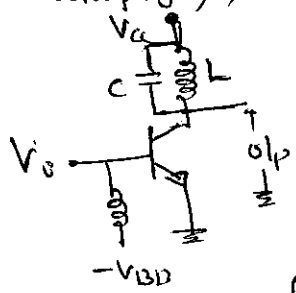
During a complete cycle of the 3p, a complete cycle of o/p signal is developed across the load. one disadvantage of the circuit is the need of two separate voltage supplies. Another, less obvious disadvantage is crossover distortion. It refers to the fact that during the signal crossover from

positive to negative (or vice versa), there is some nonlinearity in the o/p signal. During crossing over of the 3p, both the transistors will not conduct, because of this o/p voltage is zero. Biasing the transistors in class AB improves the operation by biasing both transistors to be on for more than half cycles.

Quasi - Complementary Push-Pull Amplifier. In Practical Power Amplifier ckt, it is preferable to use npn transistors for both high current - o/p devices. Since the push-pull operation requires complementary devices, a pnp high power transistor must be used. A practical means of obtaining complementary operation while using the same matched npn transistor for the o/p provided by a quasi-complementary ckt. The push-pull operation is achieved by using complementary transistors before the matched npn o/p transistors. When Q1 & Q3 form a Darlington Pair and Q2 & Q4 form a feedback pair. Both provide a low impedance drive to the load. The resistor R2 can be adjustable to minimize the crossover distortion. The 3p signal by adjusting the dc bias condition. The 3p signal is applied to the push-pull stage results in a full cycle o/p to the load. It is commonly used Power Amplifier.



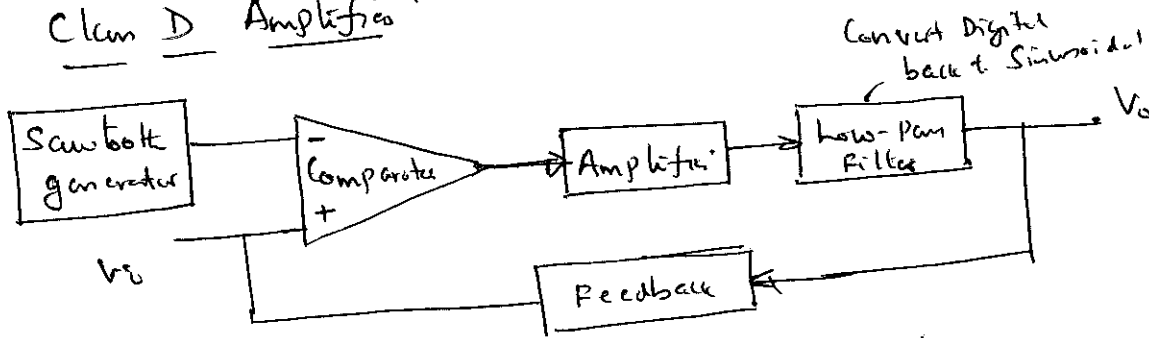
Class C and Class D Amplifiers: Class D Amplifier is Popular because of their very high efficiency. Class C Amplifier, although not used as audio amplifier, but it is used in tuned circuit as in Communication.



Class C Amplifier: Here the transistor is biased to operate for less than  $180^\circ$  of the I/P signal cycle. The tuned ckt in o/p, however will provide a full cycle of the o/p signal for the fundamental resonance frequency of the tuned ckt.

(Class C ckt) of the o/p. This type of operation is therefore limited to use at one fixed frequency, as occurs in Communication circuit.

### Class D Amplifier



### Block Diagram Class D Amplifier

A class D amplifier is designed to operate with digital or pulse type signals. An efficiency of over 90% is achieved using this type of circuit, making it quite desirable in power amplifiers. It is necessary, however, to convert any I/P signal into pulse-type waveform before using it to drive a large power load & to convert the signal back into a sinusoidal type signal to recover the original signal. The Fig shows how a sinusoidal signal may be converted into pulse type signal using some form of sawtooth or chopping waveform to be applied with the I/P into a comparator type opamp ckt so that a representative pulse type signal is produced. Although it is used to describe the next type of large operation after class, the D could also be considered to stand for 'Digital' since that is the nature of the signals provided to the class D amplifier.

The above block diagram needed to amplify the class D signal & then convert back into the sinusoidal-type signal using a low pass filter. Since the amplifier's transistor devices used to provide the o/p are basically either off or on, they provide current only when they turned on, with little power loss due to their low "on" voltage. Since most of the power applied to the amplifier is transferred to the load, the efficiency of the ckt is typically very high. Power MOSFET devices have been quite popular for the driver device for the class D amplifier.