

**PA2**

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November 5, 2018

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- **Acknowledgments:** This template takes some materials from course CSE 547/Stat 548 of Washington University:  
<https://courses.cs.washington.edu/courses/cse547/17sp/index.html>.  
If you refer to other materials in your homework, please list here.
  - **Collaborators:** I finish this homework by myself.
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2.1.(a) Firstly, we need to know the log Maximum Likelihood Estimate:

$$\begin{aligned} & \log L(\mu_1, \dots, \mu_k, \Sigma_1, \dots, \Sigma_k, \phi_1, \dots, \phi_k) \\ &= \log \prod_{i=1}^m p(x_i, y_i; \mu_1, \dots, \mu_k, \Sigma_1, \dots, \Sigma_k, \phi_1, \dots, \phi_k) \\ &= \log \prod_{i=1}^m p(x_i | y_i; \mu_{y_i}, \Sigma_{y_i}) p(y_i; \phi_{y_i}) \\ &= \log \prod_{i=1}^m \prod_{j=1}^k \mathbf{1}\{y_i = j\} \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma_j|^{\frac{1}{2}}} e^{-\frac{1}{2}(x_i - u_j)^T \Sigma_j^{-1} (x_i - u_j)} p(y_i = j; \phi_j) \\ &= \sum_{i=1}^m \sum_{j=1}^k \mathbf{1}\{y_i = j\} \left( -\frac{1}{2} (x_i - u_j)^T \Sigma_j^{-1} (x_i - u_j) - \frac{n}{2} \log(2\pi) + \frac{1}{2} \log |\Sigma_j| + \log p(y_i; \phi_{y_i}) \right) \end{aligned}$$

If we want to find the Maximum, we need to get the derivative of Sigma. If we cut the useless parts, the function will be look like this:

$$l = \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^k \mathbf{1}\{y_i = j\} (\log |\Sigma_j| - (x_i - u_j)^T \Sigma_j^{-1} (x_i - u_j))$$

I need to tell some basic rules about derivative of matrix:

$$\frac{\partial |A|}{\partial A} = |A| (A^{-1})^T \quad (1)$$

$$\frac{\partial A^{-1}}{\partial x} = -A^{-1} \frac{\partial A}{\partial x} A^{-1} \quad (2)$$

We could use the (1) to get the  $\log |\Sigma_k|$  's derivative. Because of the SPD, we could get:

$$\frac{\partial \log |\Sigma_j|}{\partial \Sigma_j} = (\Sigma_j^{-1})^T = \Sigma_j^{-1} \quad (3)$$

Then, use the rule (2). Because the  $x$  is a scalar, so we need to separate the process. First let's try to find the derivative of  $\Sigma_{k,(i,j)}$ :

$$\begin{aligned}\frac{\partial \Sigma_k^{-1}}{\partial \Sigma_{k,(i,j)}} &= \Sigma_k^{-1} \frac{\partial \Sigma_k}{\Sigma_{k,(i,j)}} \Sigma_k^{-1} \\ (x_i - u_j)^T \frac{\partial \Sigma_k^{-1}}{\partial \Sigma_{k,(i,j)}} (x_i - u_j) &= (x_i - u_j)^T \Sigma_k^{-1} \frac{\partial \Sigma_k}{\Sigma_{k,(i,j)}} \Sigma_k^{-1} (x_i - u_j)\end{aligned}$$

We noticed that  $(x_i - u_j)^T \Sigma_k^{-1} = (\Sigma_k^{-1} (x_i - u_j))^T$ . And the matrix  $\frac{\partial \Sigma_k^{-1}}{\partial \Sigma_{k,(i,j)}}$  will be like a  $n \times n$  matrix with the exception that the value of the position  $(i,j)$  will be 1.

So we could get:

$$\begin{aligned}(x_i - u_j)^T \frac{\partial \Sigma_k^{-1}}{\partial \Sigma_{k,(i,j)}} (x_i - u_j) &= (x_i - u_j)^T \Sigma_k^{-1} \frac{\partial \Sigma_k}{\Sigma_{k,(i,j)}} \Sigma_k^{-1} (x_i - u_j) \\ &= [(\Sigma_k^{-1} (x_i - u_j)) (\Sigma_k^{-1} (x_i - u_j))^T]_{(i,j)}\end{aligned}$$

So:

$$(x_i - u_j)^T \frac{\partial \Sigma_k^{-1}}{\partial \Sigma_{k,(i,j)}} (x_i - u_j) = (\Sigma_k^{-1} (x_i - u_j)) (\Sigma_k^{-1} (x_i - u_j))^T \quad (4)$$

Now use (3) and (4), we could get:

$$\begin{aligned}\frac{\partial l}{\partial \Sigma_j} &= \frac{1}{2} \sum_{i=1}^m \mathbf{1}\{y_i = j\} (\Sigma_j^{-1} - (\Sigma_k^{-1} (x_i - u_j)) (\Sigma_k^{-1} (x_i - u_j))^T) \\ &= \frac{1}{2} \sum_{i=1}^m \mathbf{1}\{y_i = j\} (\Sigma_j^{-1} - \Sigma_j^{-1} (x_i - u_j) (x_i - u_j)^T \Sigma_j^{-1})\end{aligned}$$

Because we want to let  $\frac{\partial l}{\partial \Sigma_j} = \mathbf{0}$ .

$$\begin{aligned}\frac{1}{2} \sum_{i=1}^m \mathbf{1}\{y_i = j\} (\Sigma_j^{-1} - \Sigma_j^{-1} (x_i - u_j) (x_i - u_j)^T \Sigma_j^{-1}) &= \mathbf{0} \\ \sum_{i=1}^m \mathbf{1}\{y_i = j\} (I - \Sigma_j^{-1} (x_i - u_j) (x_i - u_j)^T) &= \mathbf{0} \\ \sum_{i=1}^m \mathbf{1}\{y_i = j\} I &= \Sigma_j^{-1} \sum_{i=1}^m \mathbf{1}\{y_i = j\} (x_i - u_j) (x_i - u_j)^T\end{aligned}$$

So, for QDA, the  $\Sigma_j$  will be like this:

$$\Sigma_j = \frac{\sum_{i=1}^m \mathbf{1}\{y_i = j\} (x_i - \mu_j) (x_i - \mu_j)^T}{\sum_{i=1}^m \mathbf{1}\{y_i = j\}}$$

where  $j = 1, 2$ .

(b) The Programming assignment is attached in the zip file.