

8-4

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**3 a)**

Let  $T : P_2 \rightarrow P_2$  be the linear operator defined by

$$T(a_0 + a_1x + a_2x^2) = a_0 + a_1(x - 1) + a_2(x - 1)^2$$

Find the matrix for  $T$  relative to the standard basis  $B = \{1, x, x^2\}$  for  $P_2$

**b)**

Verify that the matrix  $[T]_B$  obtained in part (a) satisfies Formula (8) for every vector  $\mathbf{x} = a_0 + a_1x + a_2x^2$  in  $P_2$

**4 a)**

Let  $T : R^2 \rightarrow R^2$  be the linear operator defined by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 - x_2 \\ x_1 + x_2 \end{bmatrix}$$

and let  $B = \{\mathbf{u}_1, \mathbf{u}_2\}$  be the basis for which

$$\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \text{a n d} \quad \mathbf{u}_2 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

Find  $[T]_B$

**b)**

Verify that Formula (8) holds for every vector  $\mathbf{x}$  in  $R^2$

**5 a)**

Let  $T : R^2 \rightarrow R^3$  be defined by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 + 2x_2 \\ -x_1 \\ 0 \end{bmatrix}$$

Find the matrix  $[T]_{B',B}$  relative to the bases  $B = \{\mathbf{u}_1, \mathbf{u}_2\}$  and  $B' = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  where

$$\mathbf{u}_1 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} -2 \\ 4 \end{bmatrix}$$
$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}$$

**b)**

Verify that Formula (5) holds for every vector in  $R^2$

**7 a)**

Let  $T : P_2 \rightarrow P_2$  be the linear operator defined by

$$\begin{aligned} T(p(x)) &= p(2x + 1), \text{ t h a t i s,} \\ T(c_0 + c_1x + c_2x^2) &= c_0 + c_1(2x + 1) + c_2(2x + 1)^2 \end{aligned}$$

Find  $[T]_B$  with respect to the basis  $B = \{1, x, x^2\}$  .

**b)**

Use the three-step procedure illustrated in Example 2 to compute  $T(2 - 3x + 4x^2)$  .

**c)**

Check the result obtained in part (b) by computing  $T(2 - 3x + 4x^2)$  directly.

**9 a)**

Let  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} -1 \\ 4 \end{bmatrix}$ , and let  $A = \begin{bmatrix} 1 & 3 \\ -2 & 5 \end{bmatrix}$  be the matrix for  $T: R^2 \rightarrow R^2$  relative to the basis  $B = \{\mathbf{v}_1, \mathbf{v}_2\}$ .  
Find  $[T(\mathbf{v}_1)]_B$  and  $[T(\mathbf{v}_2)]_B$

**b)**

Find  $T(\mathbf{v}_1)$  and  $T(\mathbf{v}_2)$

**c)**

Find a formula for  $T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right)$

**d)**

Use the formula obtained in (c) to compute  $T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right)$



### Answers

$$3. \text{ (a)} \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$5. \text{ (a)} \begin{bmatrix} 0 & 0 \\ -\frac{1}{2} & 1 \\ \frac{8}{3} & \frac{4}{3} \end{bmatrix}$$

$$7. \text{ (a)} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 4 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\text{(b),(c)} \ 3 + 10x + 16x^2$$

$$9. \text{ (a)} \ [T(\mathbf{v}_1)]_B = \begin{bmatrix} 1 \\ -2 \end{bmatrix}; [T(\mathbf{v}_2)]_B = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

$$\text{(b)} \ T(\mathbf{v}_1) = \begin{bmatrix} 3 \\ -5 \end{bmatrix}; T(\mathbf{v}_2) = \begin{bmatrix} -2 \\ 29 \end{bmatrix}$$

$$\text{(c)} \ T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} \frac{18}{7} & \frac{1}{7} \\ -\frac{107}{7} & \frac{24}{7} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\text{(d)} \ T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} \frac{19}{7} \\ -\frac{83}{7} \end{bmatrix}$$