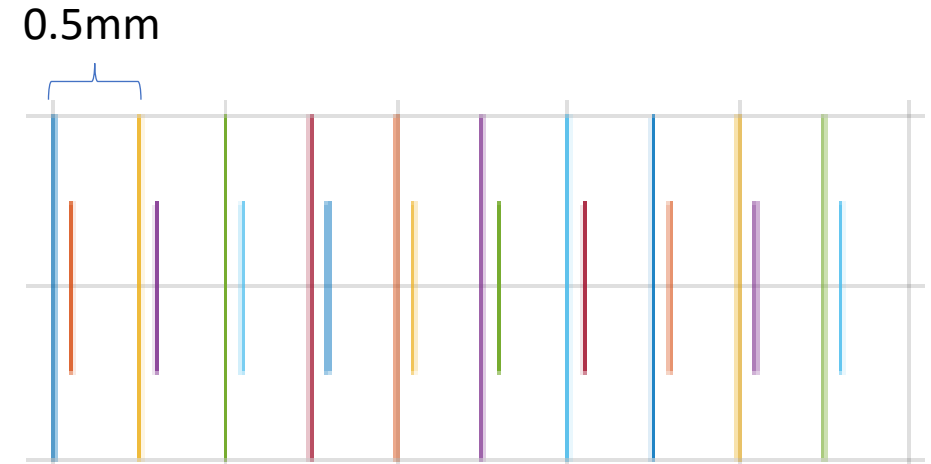


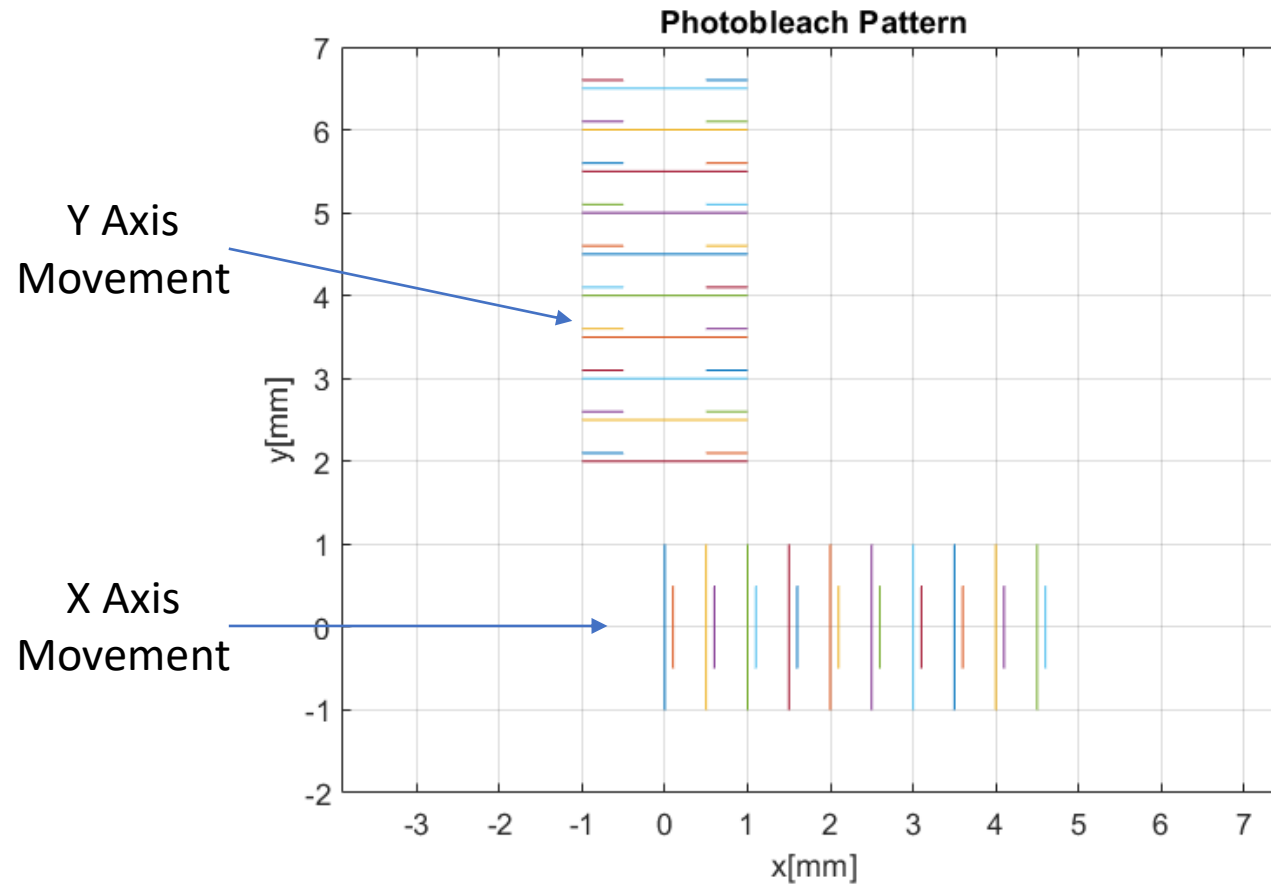
Photobleached Line Repeatability

Calibration Pattern – X Galvo

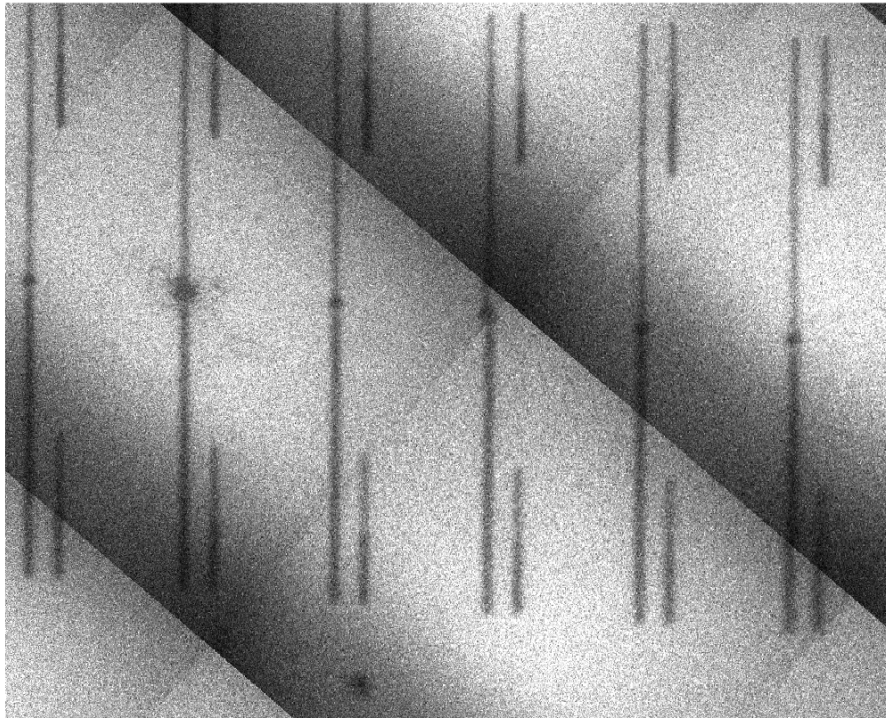
- We photobleach the pattern on the right.
- Long lines are used for calibration
- Short lines used to identify which motor is being calibrated.
- Stage moves 0.5mm between photobleaching consecutive long lines.
- By comparing requested movement to measured photobleach lines we can calibrate motor units to physical units.



Calibration Pattern – Overall

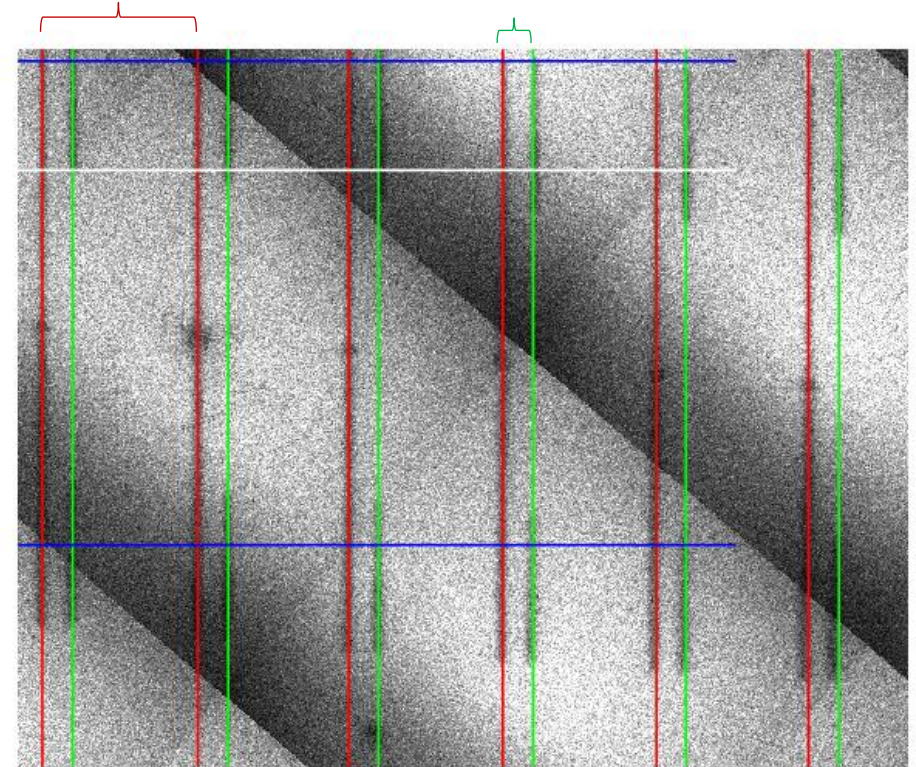


Calibration Results



Hopefully, motor translated
0.5mm (by design)

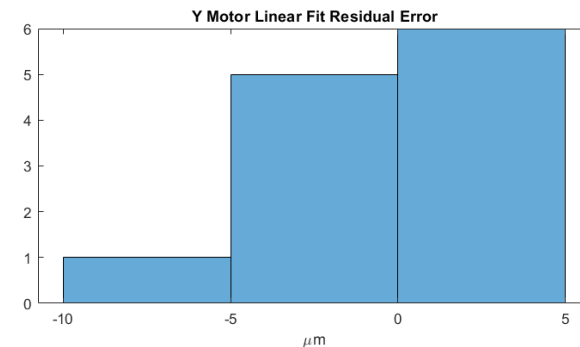
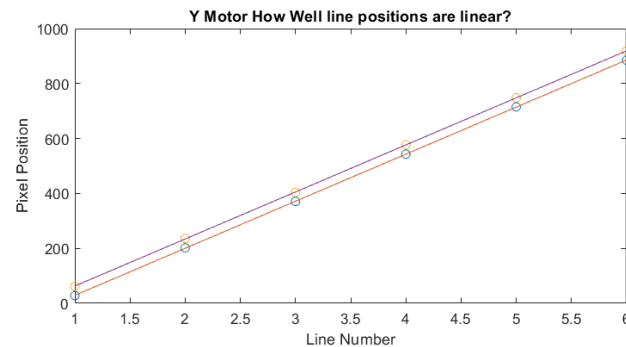
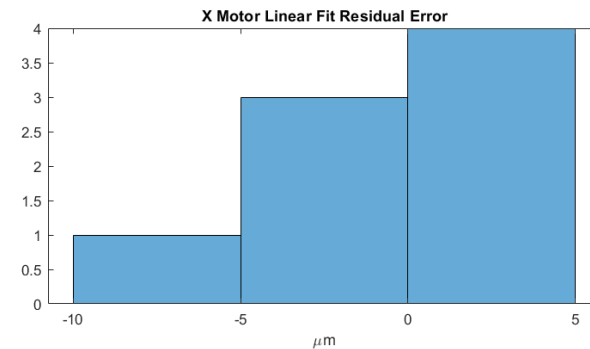
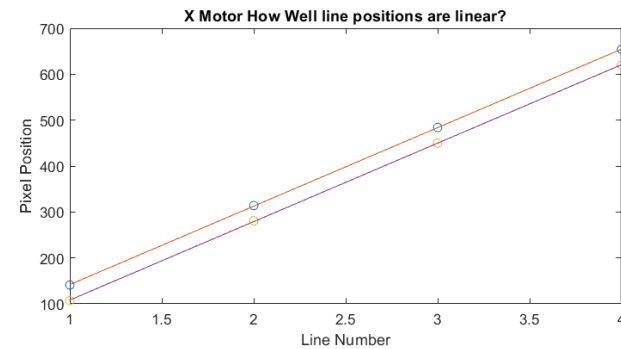
Second Line in FOV
0.1mm (Galvo Calibrated)



Linear Fit & Residual

Very good linear fit, residuals are within motor spec (see next slide)

Script outputs recommended calibration



Motorized Stage Specs (Z825B)



Specification	Value
Travel Range	25 mm (0.98")
Backlash	<8 μm
Bidirectional Repeatability	<1.5 μm
Home Location Accuracy	$\pm 1.0 \mu\text{m}$
Homing Repeatability	$\pm 1.0 \mu\text{m}$
Vertical Load Capacity	4.5 kg (Max)
Horizontal Load Capacity	9 kg (Max)
Vertical Load Capacity ^a	<4.0 kg
Horizontal Load Capacity ^a	<7.5 kg
Velocity ^b	2.6 mm/s (Max)
Acceleration	4 mm/s ² (Max)
Absolute On-axis Accuracy	130 μm
Percentage Accuracy	0.52% (Max)
Phase to Phase Resistance	33.0 Ω (Max)
Phase to Phase Inductance	0.6 mH (Max)
Motor Type ^c	6 VDC Servo
Minimum Achievable Incremental Movement	0.05 μm
Minimum Repeatable Incremental Movement	0.2 μm
Mounting Barrel	$\varnothing 3/8"$ (9.525 mm)
Weight	0.134 kg

a. Recommended

b. The nominal motor drive voltage is 6 V. Voltages up to 12 V can be used with pulse width modulation (PWM) controlled outputs.

c. At 2.6 mm/s velocity ripple and distortion of the acceleration/deceleration profile may occur. For improved control, the maximum velocity should be limited to 2.3 mm/s.

Calibration Stability

- A few runs of the script:

X Motor: Distance Between Large Lines is **5.0622** X Distance Between Large Line to Small Line.

We would like this ratio to be Please correct mmToDeviceUnits from 34304.141 to NEW VALUE: **34731.036**

Y Motor: Distance Between Large Lines is **5.0877** X Distance Between Large Line to Small Line.

We would like this ratio to be Please correct mmToDeviceUnits from 34304.141 to NEW VALUE: **34905.797**

X Motor: Distance Between Large Lines is **5.0294** X Distance Between Large Line to Small Line.

We would like this ratio to be Please correct mmToDeviceUnits from 34304.141 to NEW VALUE: **34505.93**

Y Motor: Distance Between Large Lines is **5.0794** X Distance Between Large Line to Small Line.

We would like this ratio to be Please correct mmToDeviceUnits from 34304.141 to NEW VALUE: **34849.227**

X Motor: Distance Between Large Lines is **5.0421** X Distance Between Large Line to Small Line.

We would like this ratio to be Please correct mmToDeviceUnits from 34304.141 to NEW VALUE: **34592.839**

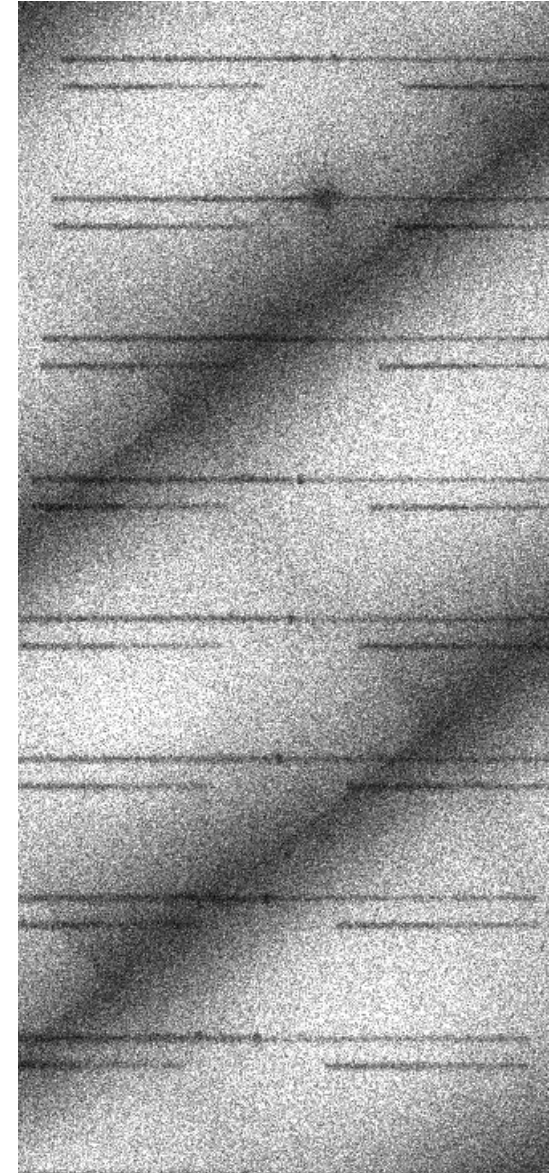
Y Motor: Distance Between Large Lines is **5.0770** X Distance Between Large Line to Small Line.

We would like this ratio to be Please correct mmToDeviceUnits from 34304.141 to NEW VALUE: **34832.678**

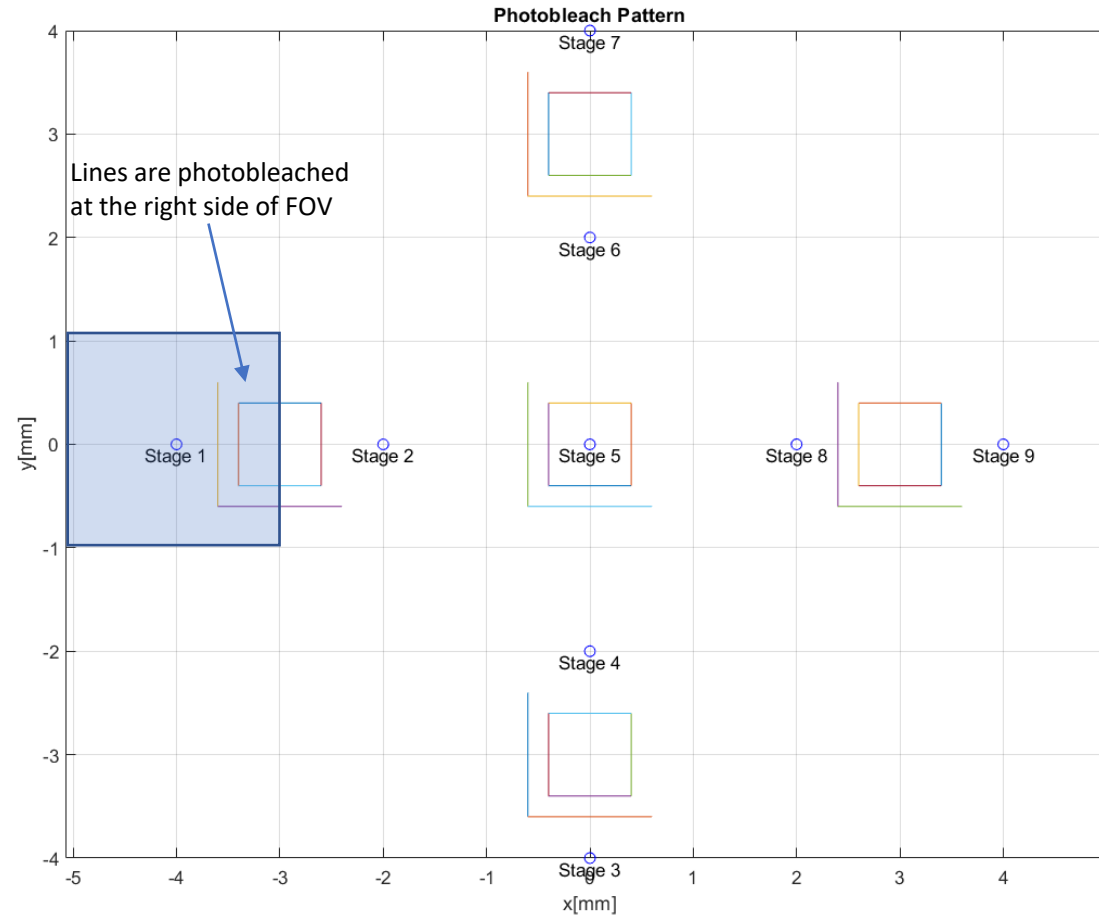
Script Error: 0.1% to 0.3%

After Calibration

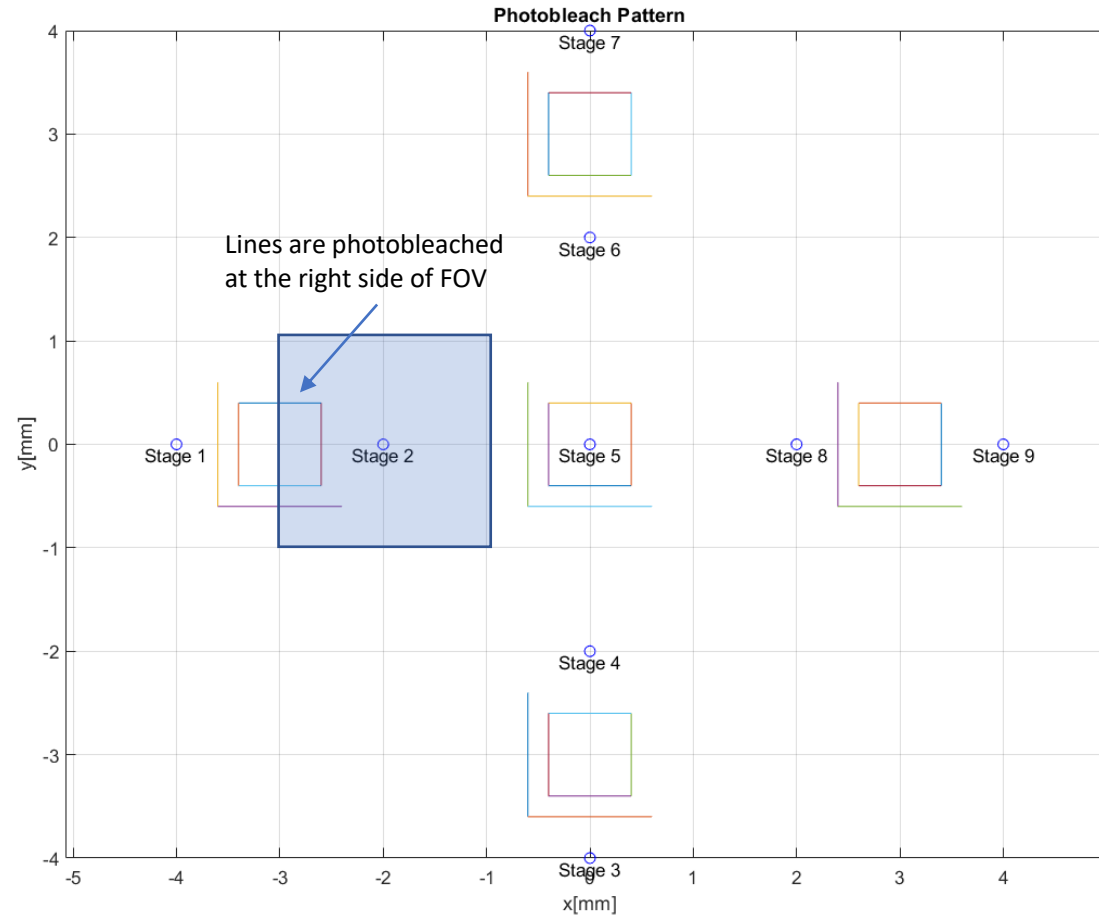
- New Calibration Values
 - X Galvo, 1 mm in device units: 34609.935
 - Y Galvo, 1 mm in device units: 34862.567
- 500 micron galvo movement is:
 - 500.5 microns (X Galvo)
 - 505.2 microns (Y Galvo)



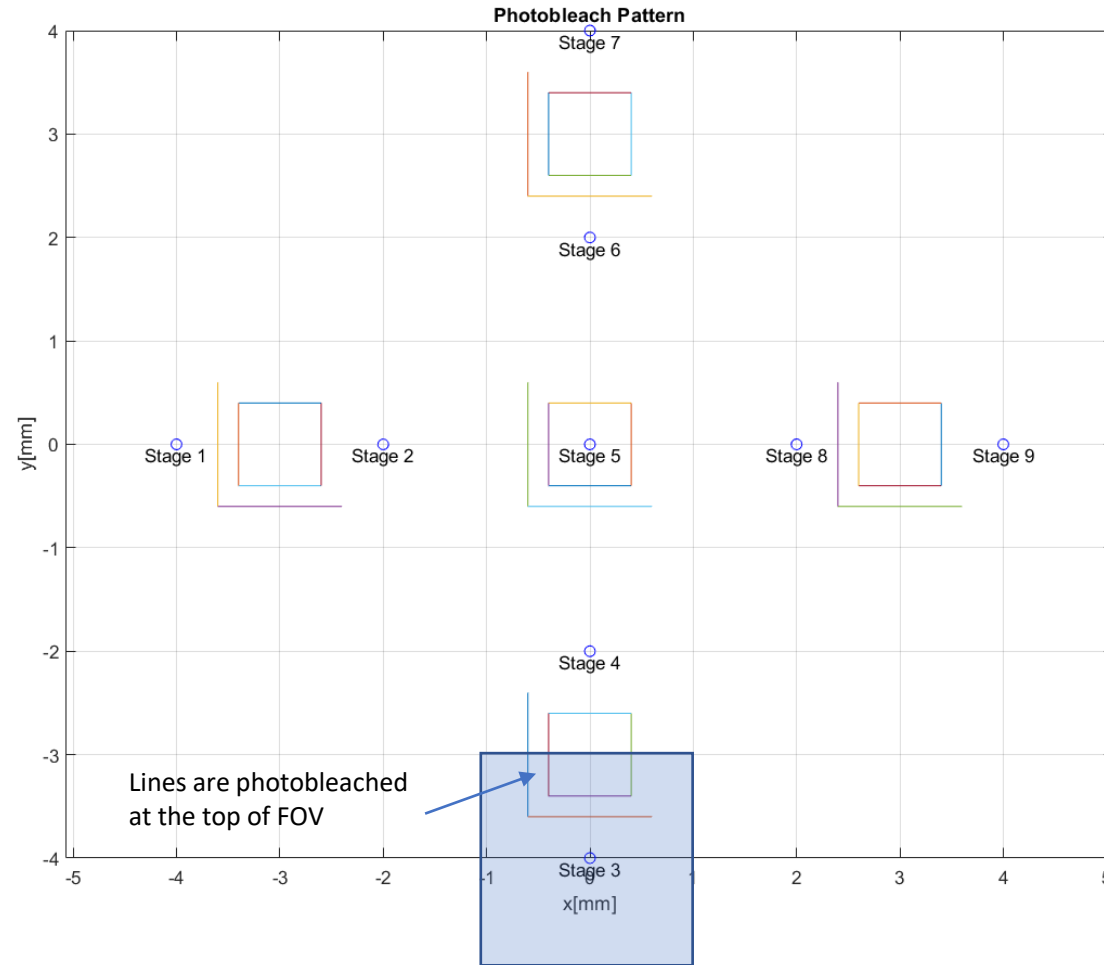
2nd Motor Calibration: Stage & FOV Repeatability



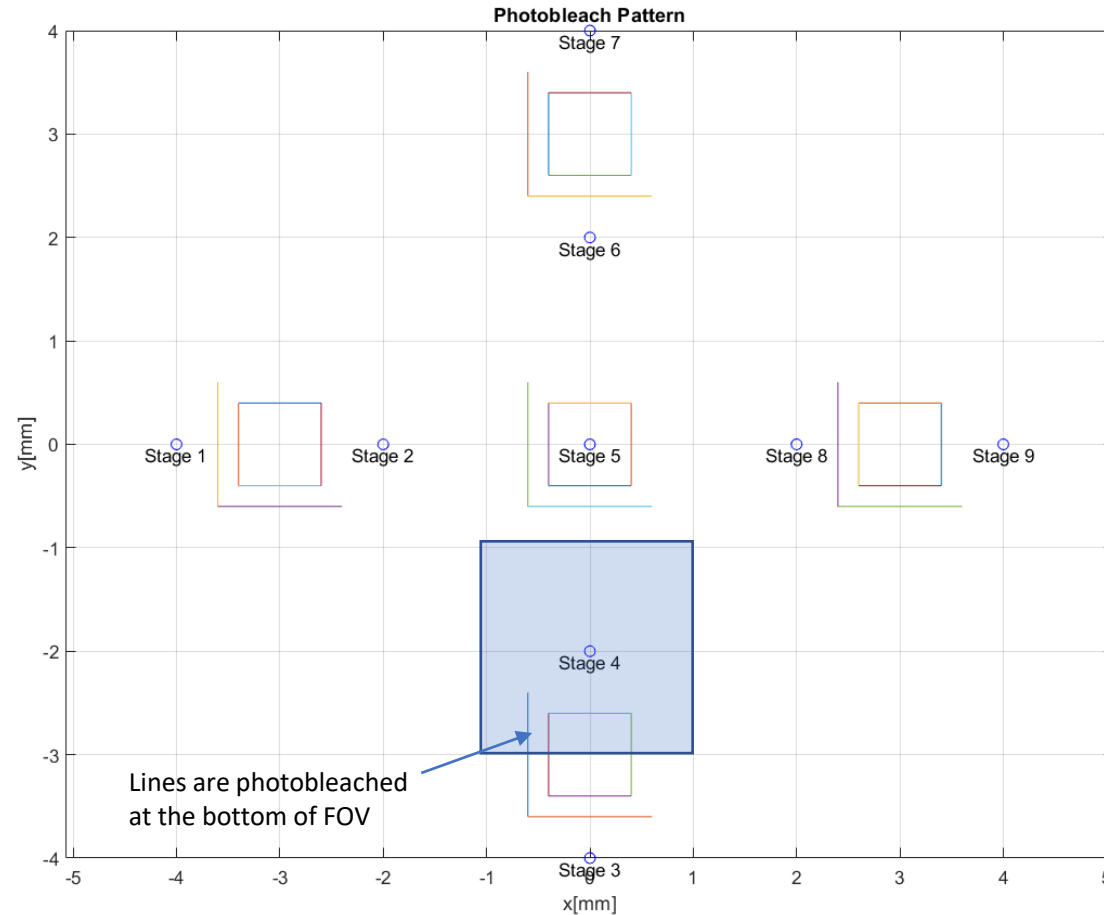
2nd Motor Calibration: Stage & FOV Repeatability



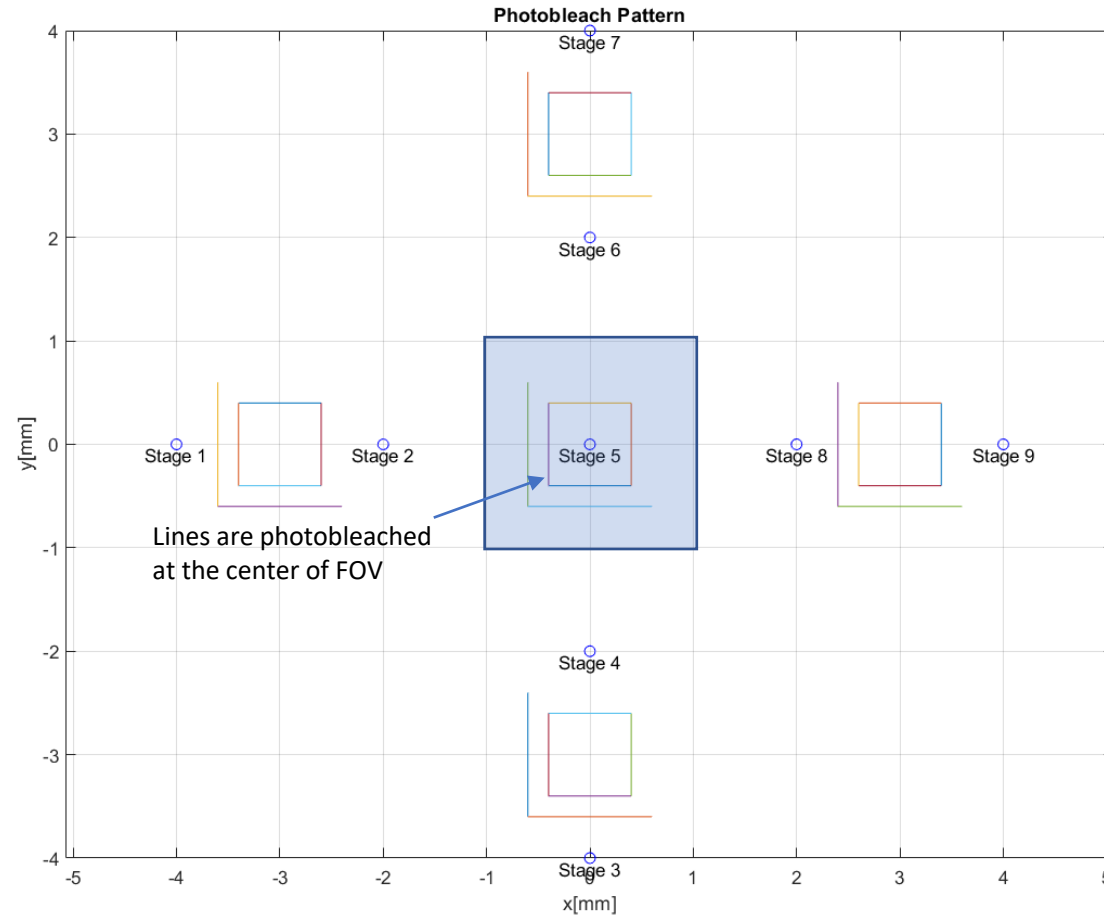
2nd Motor Calibration: Stage & FOV Repeatability



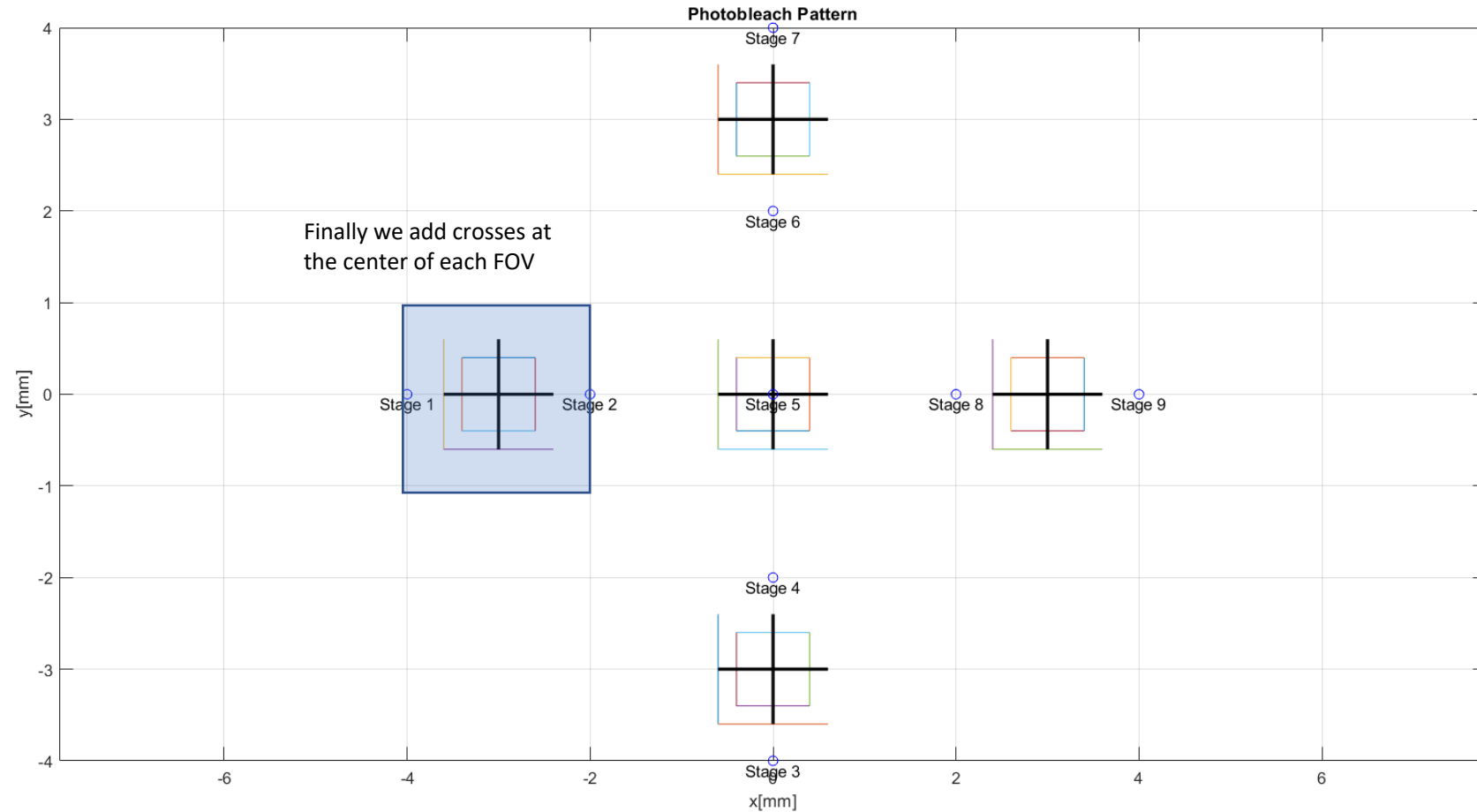
2nd Motor Calibration: Stage & FOV Repeatability



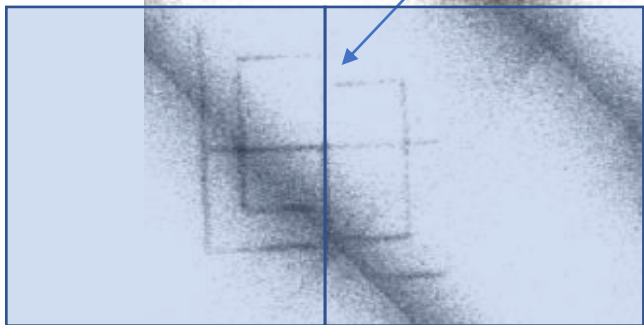
2nd Motor Calibration: Stage & FOV Repeatability

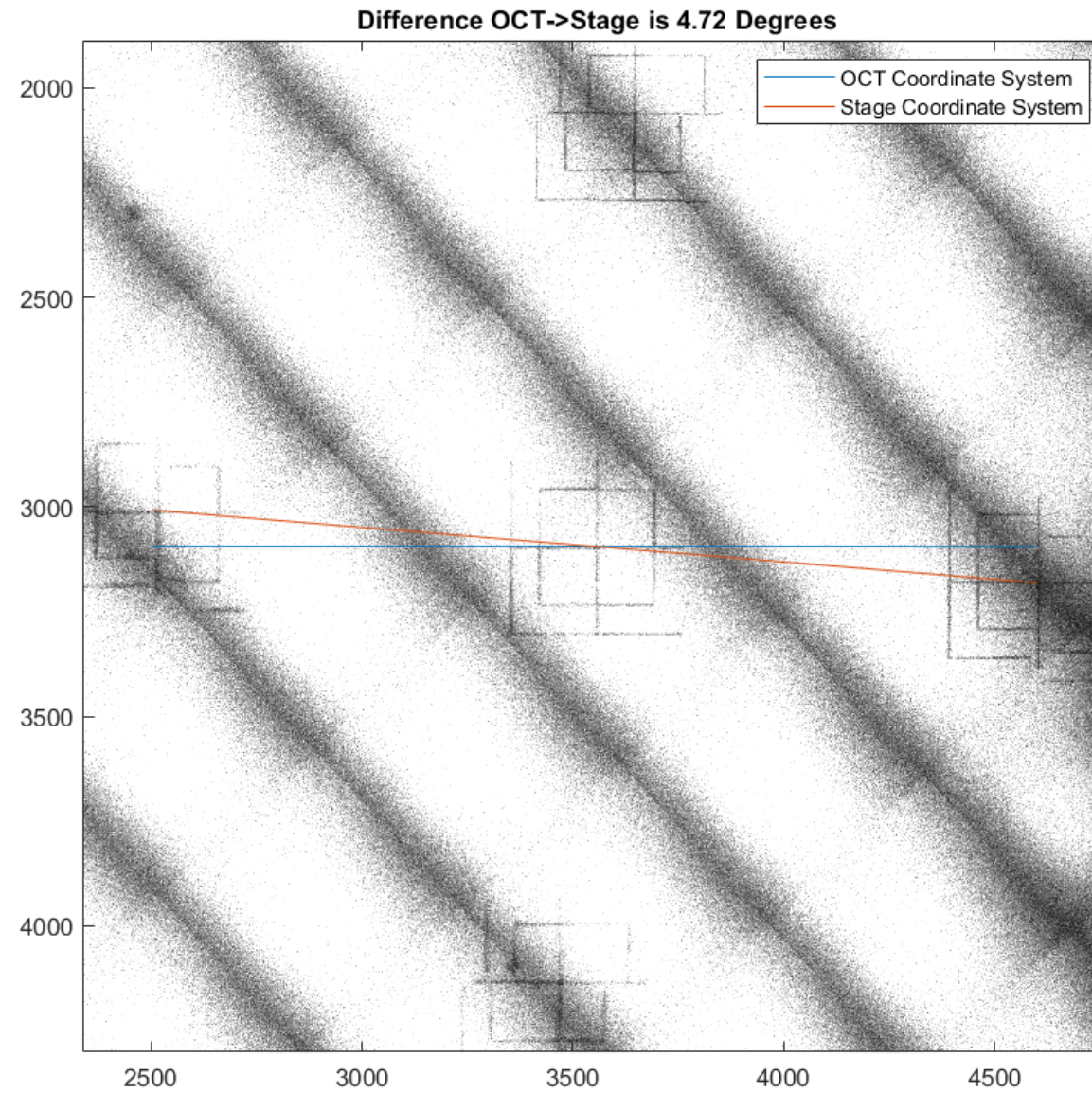


2nd Motor Calibration: Stage & FOV Repeatability



Off by $130 - 150\mu m$





After Rotation Alignment

