Optical character recognition

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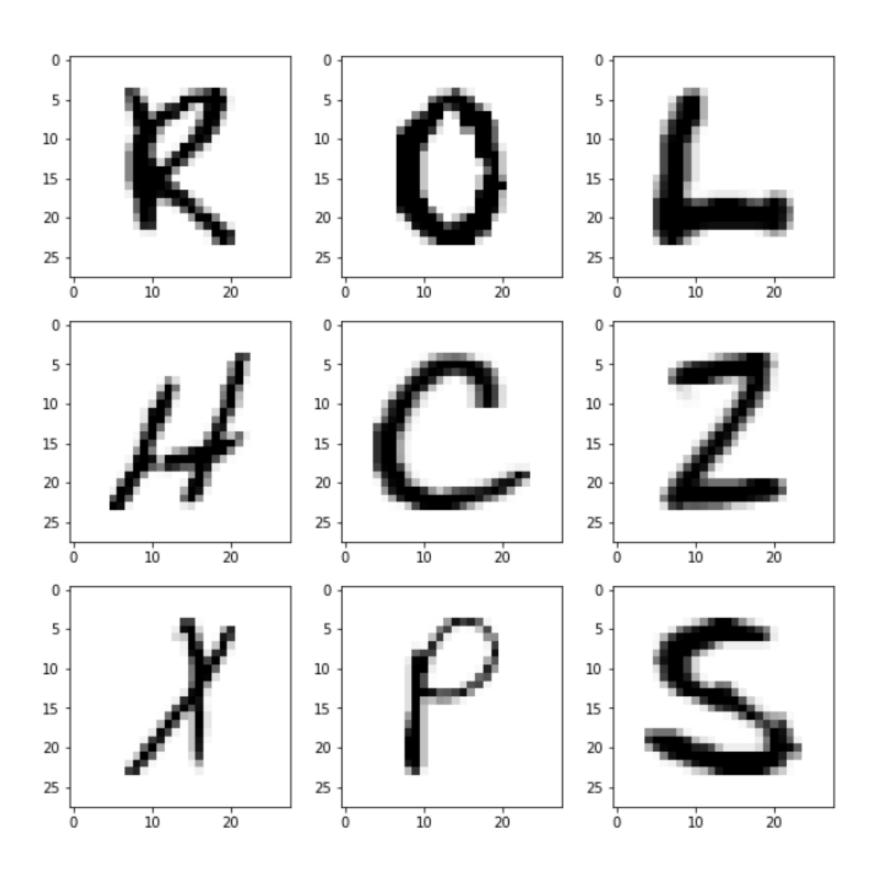


### Dataset

## A-Z Handwritten Alphabets in .csv format

The dataset contains 26 folders (A-Z) containing handwritten images in size 28x28 pixels, each alphabet in the image is centre fitted to 20x20 pixel box.



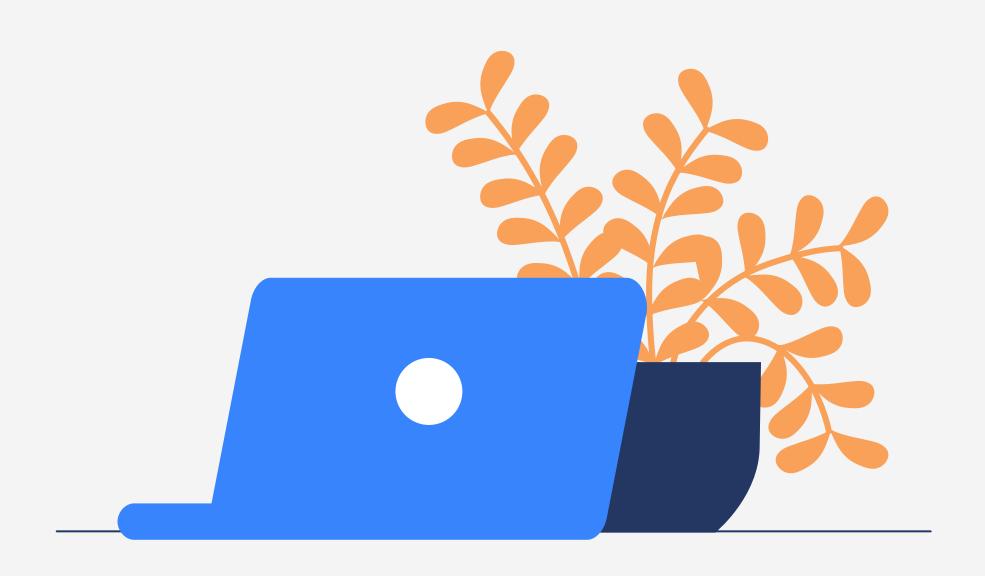


## Add data augmentation

Augmentation allows you to expand the dataset with the help of already received data

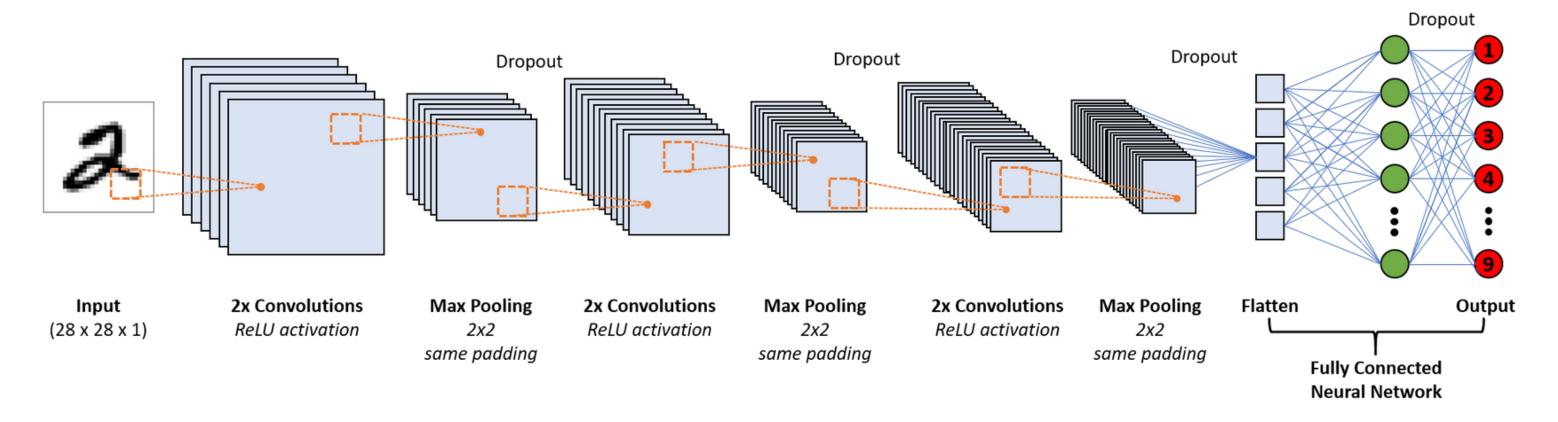
- Small rotation (prevent letter overturn)
- Changing contrast of image
- Zooming

```
data_augmentation = tf.keras.Sequential([
    layers.experimental.preprocessing.RandomRotation(0.08),
    layers.experimental.preprocessing.RandomContrast(0.12),
    layers.experimental.preprocessing.RandomZoom(height_factor=(0.05,0.1))
])
```



### CNN model

#### Convolutional Neural Network (CNN) Architecture



A Convolutional Neural Network, also known as CNN or ConvNet, is a class of neural networks that specializes in processing data that has a grid-like topology, such as an image. A digital image is a binary representation of visual data. It contains a series of pixels arranged in a grid-like fashion that contains pixel values to denote how bright and what color each pixel should be.

## CNN realization code snippet

#### (using keras)

```
model = Sequential()
model.add(data augmentation)
# input -> conv -> maxpool -> conv -> maxpool .....->flattened vector->
                          hidden layer -> hidden layer -> softmax layer
model.add(Conv2D(filters=32, kernel size=(3, 3), activation='relu', input shape=(28,28,1)))
model.add(MaxPool2D(pool size=(2, 2), strides=2))
model.add(Conv2D(filters=64, kernel size=(3, 3), activation='relu', padding = 'same'))
model.add(MaxPool2D(pool_size=(2, 2), strides=2))
model.add(Conv2D(filters=128, kernel size=(3, 3), activation='relu', padding = 'valid'))
model.add(MaxPool2D(pool size=(2, 2), strides=2))
model.add(Flatten())
model.add(Dense(64,activation ="relu"))
model.add(Dense(128,activation ="relu"))
model.add(Dense(26,activation ="softmax"))
```

Layer (type)	Output Shape	Param #
sequential_9 (Sequential)		0
conv2d_20 (Conv2D)	(None, 26, 26, 32)	320
max_pooling2d_19 (MaxPooli g2D)	n (None, 13, 13, 32)	0
conv2d_21 (Conv2D)	(None, 13, 13, 64)	18496
<pre>max_pooling2d_20 (MaxPooli g2D)</pre>	n (None, 6, 6, 64)	0
conv2d_22 (Conv2D)	(None, 4, 4, 128)	73856
max_pooling2d_21 (MaxPooli g2D)	n (None, 2, 2, 128)	0
flatten_7 (Flatten)	(None, 512)	0
dense_20 (Dense)	(None, 64)	32832
dense_21 (Dense)	(None, 128)	8320
dense_22 (Dense)	(None, 26)	3354

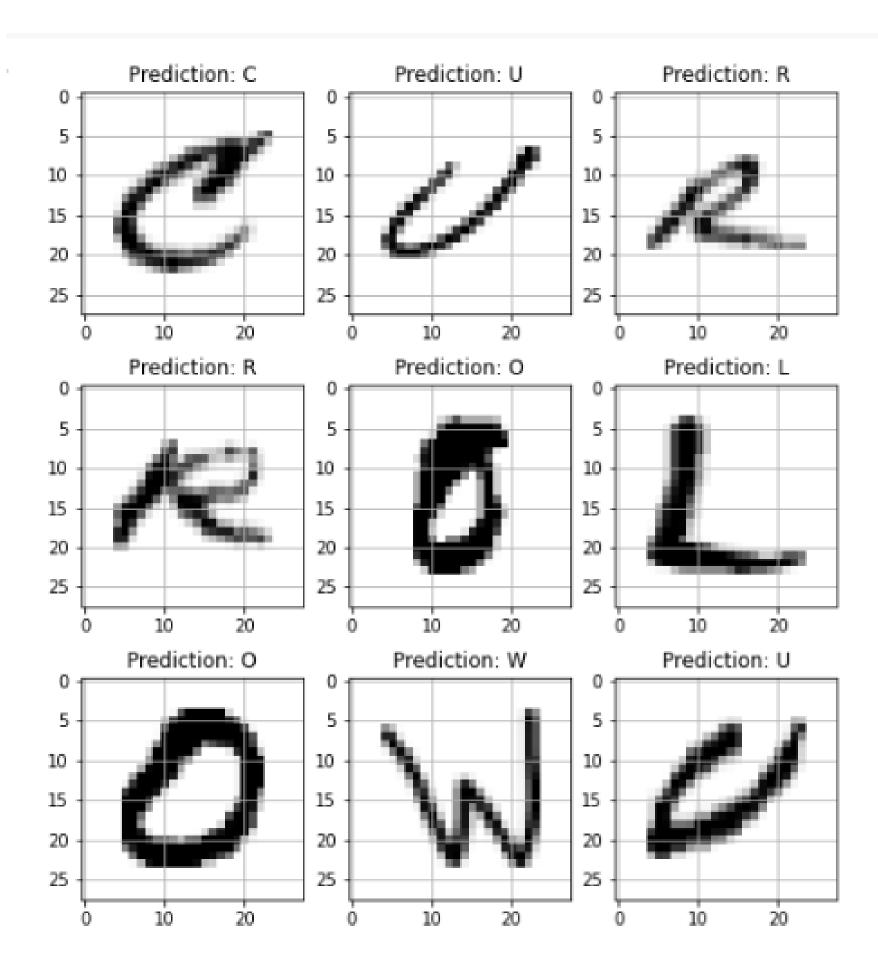
## Training results

#### Compiling the Model

```
[61] model.compile(optimizer = Adam(learning_rate=0.001), loss='categorical_crossentropy', metrics=['accuracy'])
```

#### Starting the Training

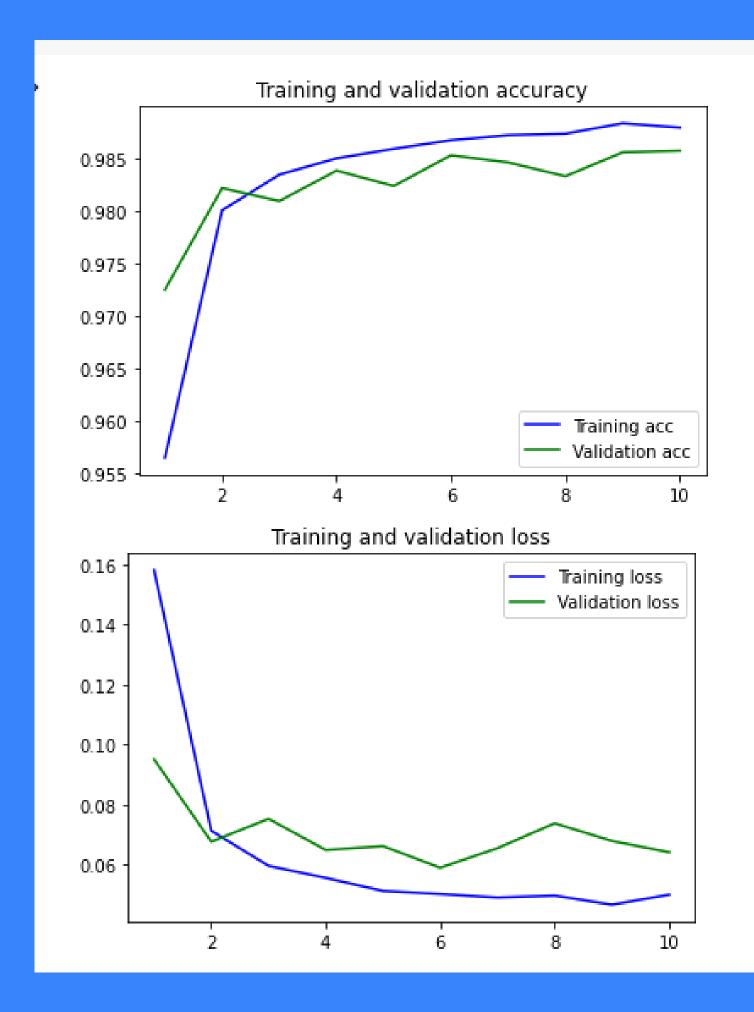
```
[62] history = model.fit(X_train, train_yOHE, epochs=10, validation_data = (X_test,test_yOHE))
Epoch 1/10
Epoch 3/10
Epoch 4/10
Epoch 5/10
Epoch 6/10
Epoch 8/10
Epoch 10/10
```



## Test on validation set

Accuracy result: 0.9857

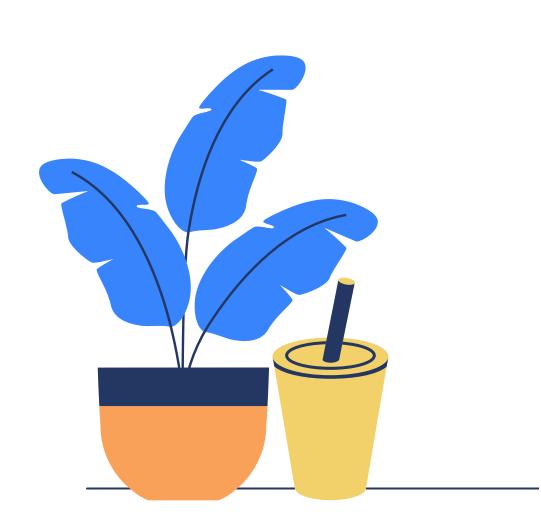
#### Making Predictions

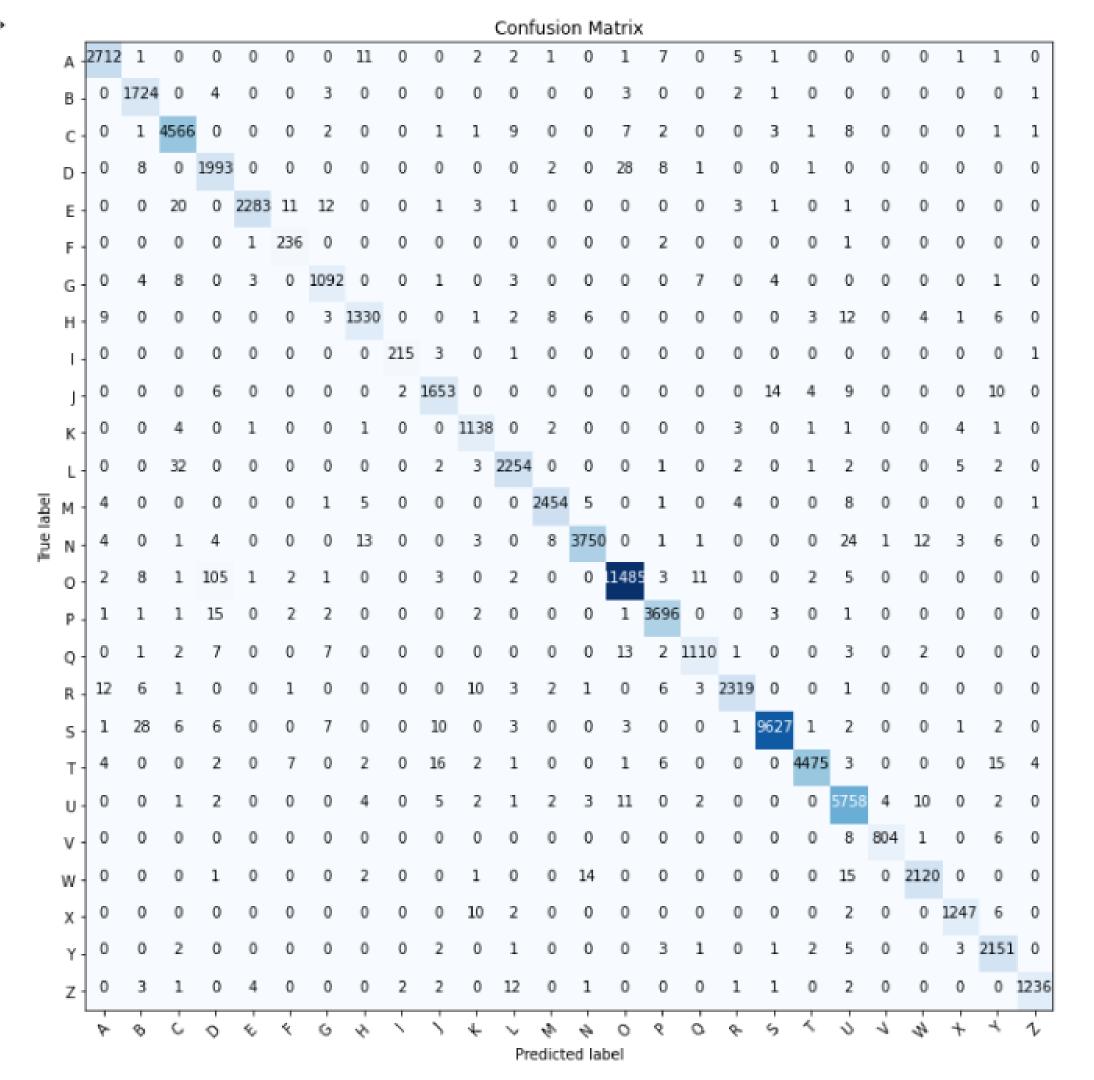


## Training and validation accuracy and loss trend



## Confusion Matrix





- 10000

- 8000

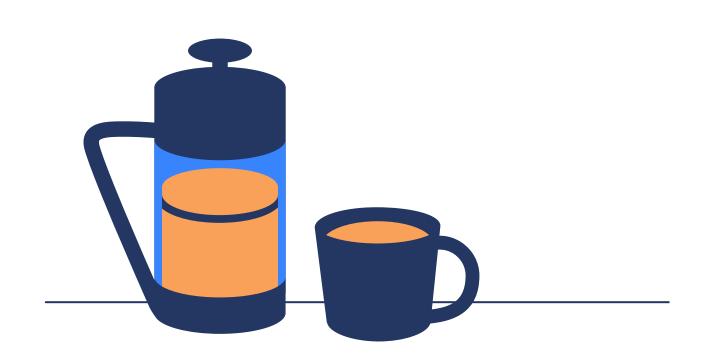
- 6000

- 4000

- 2000

### Typicall errors

We can notice that the model is trained well enough, that's why there are not many errors. But still there are enough cases where there were mix-ups O-D and N-H





# Thanks for attention!