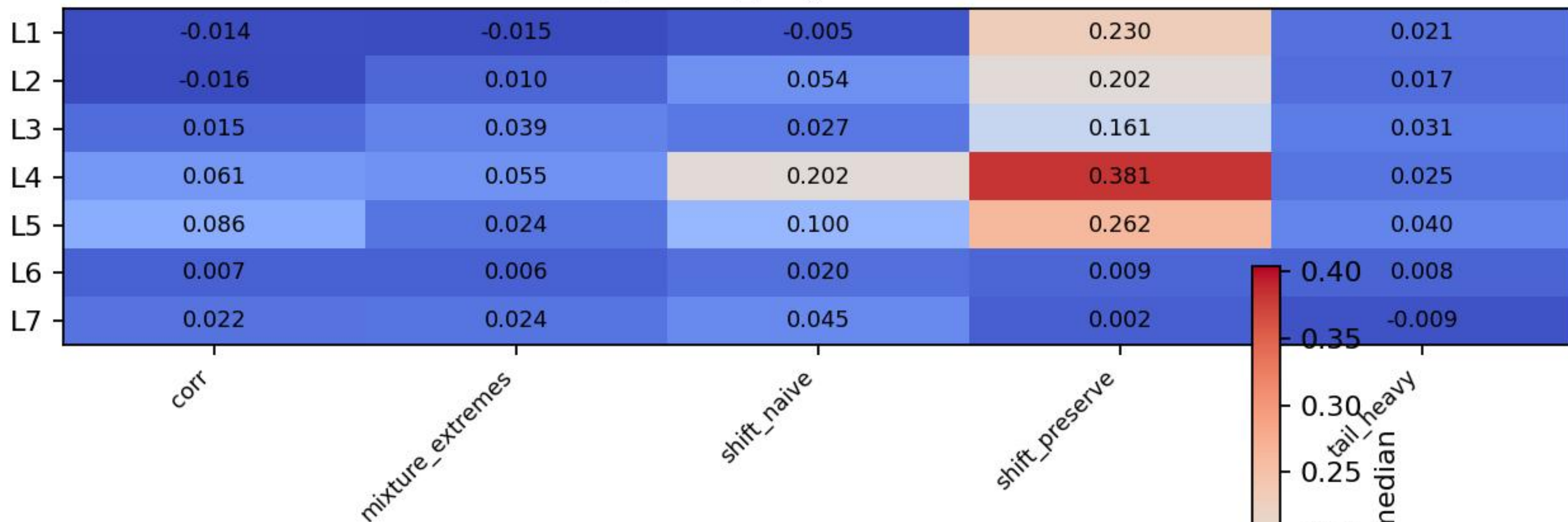
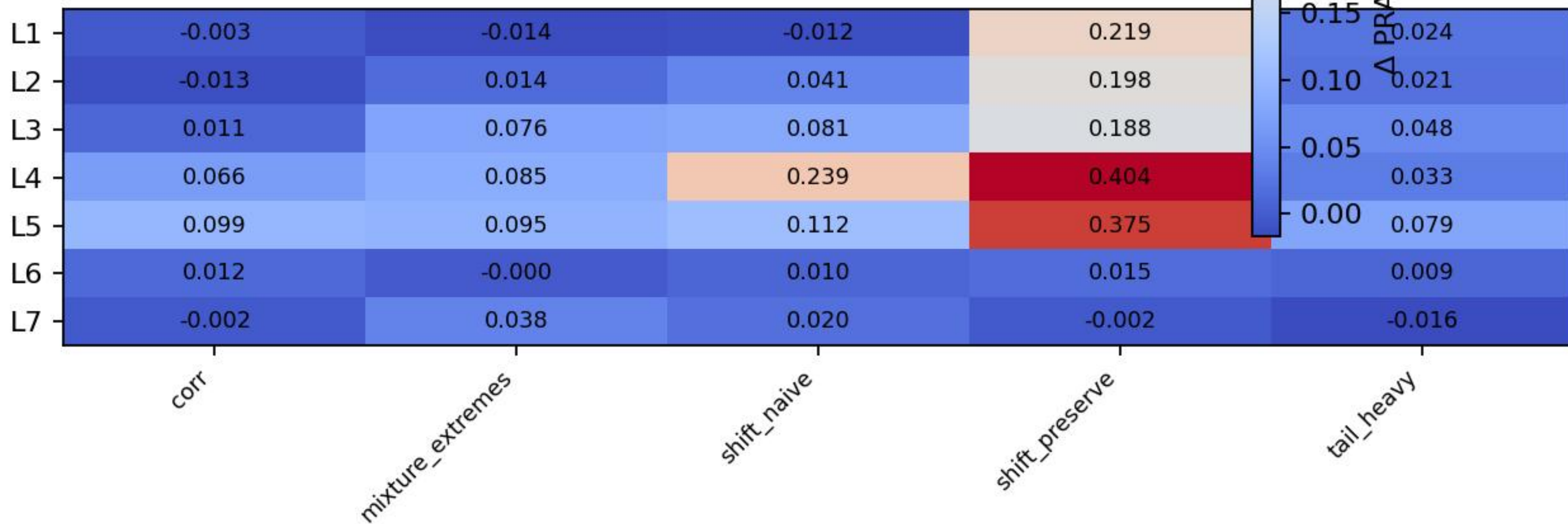


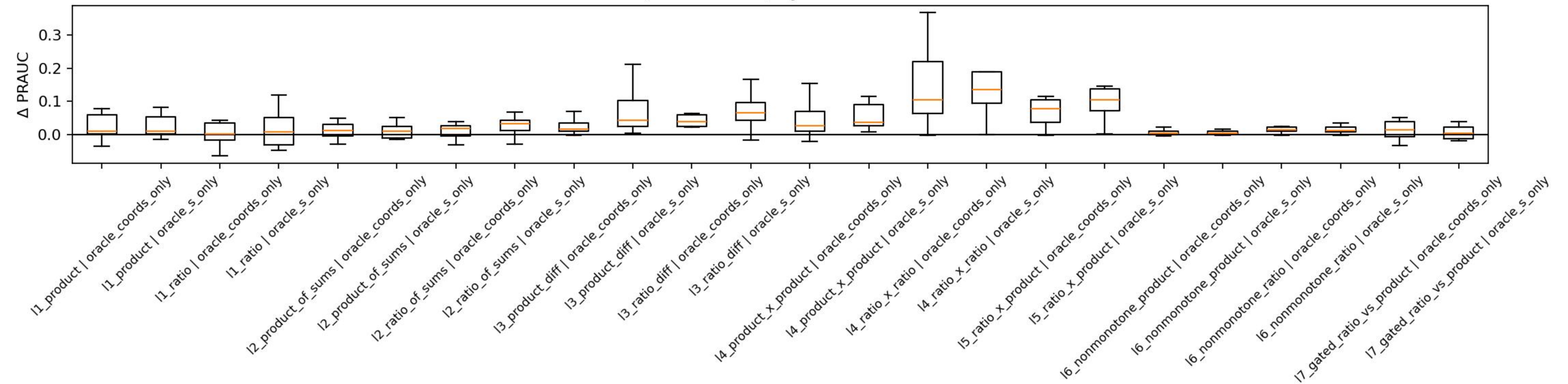
oracle_coords_only: Δ PRAUC median



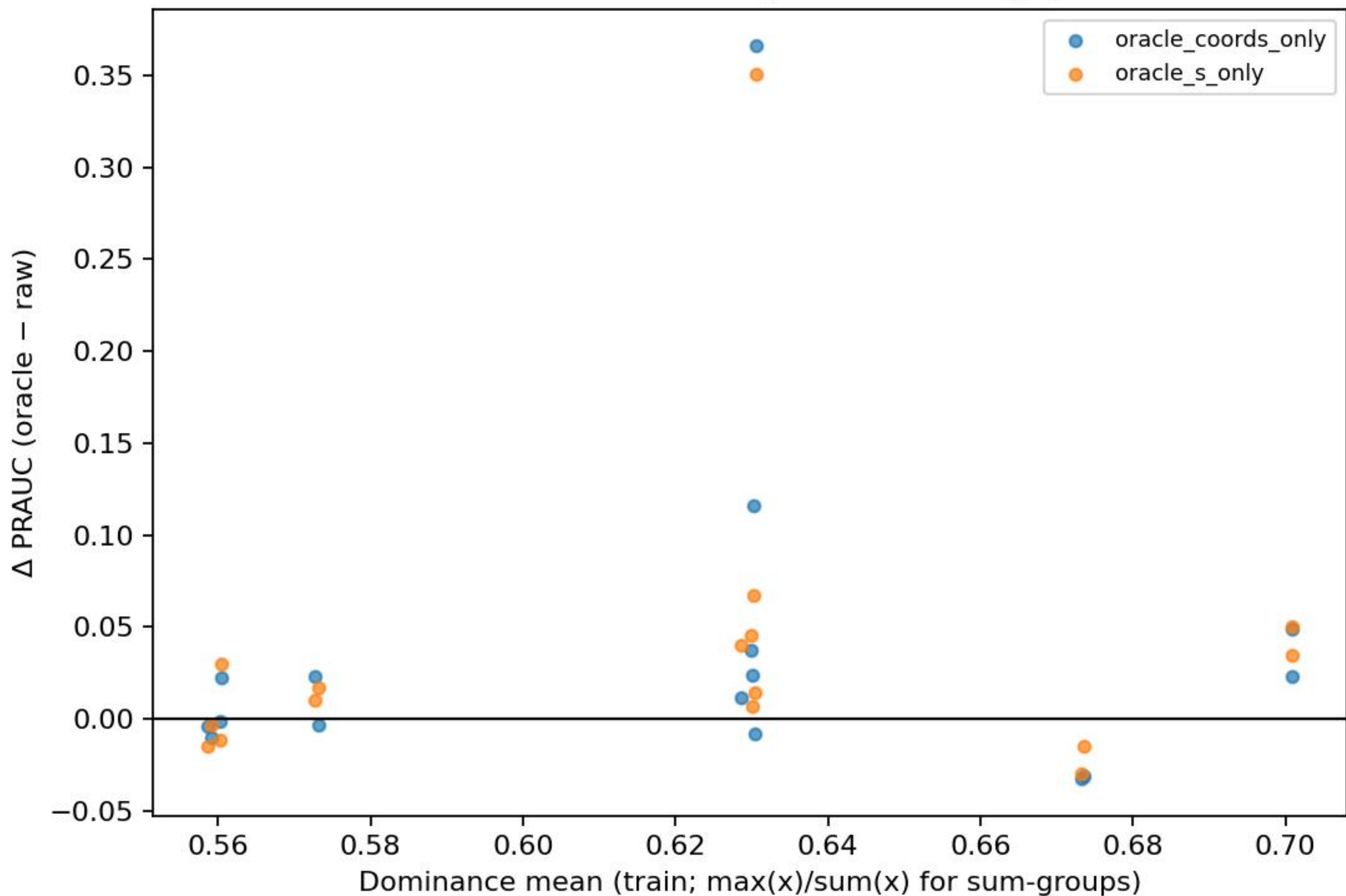
oracle_s_only: Δ PRAUC median



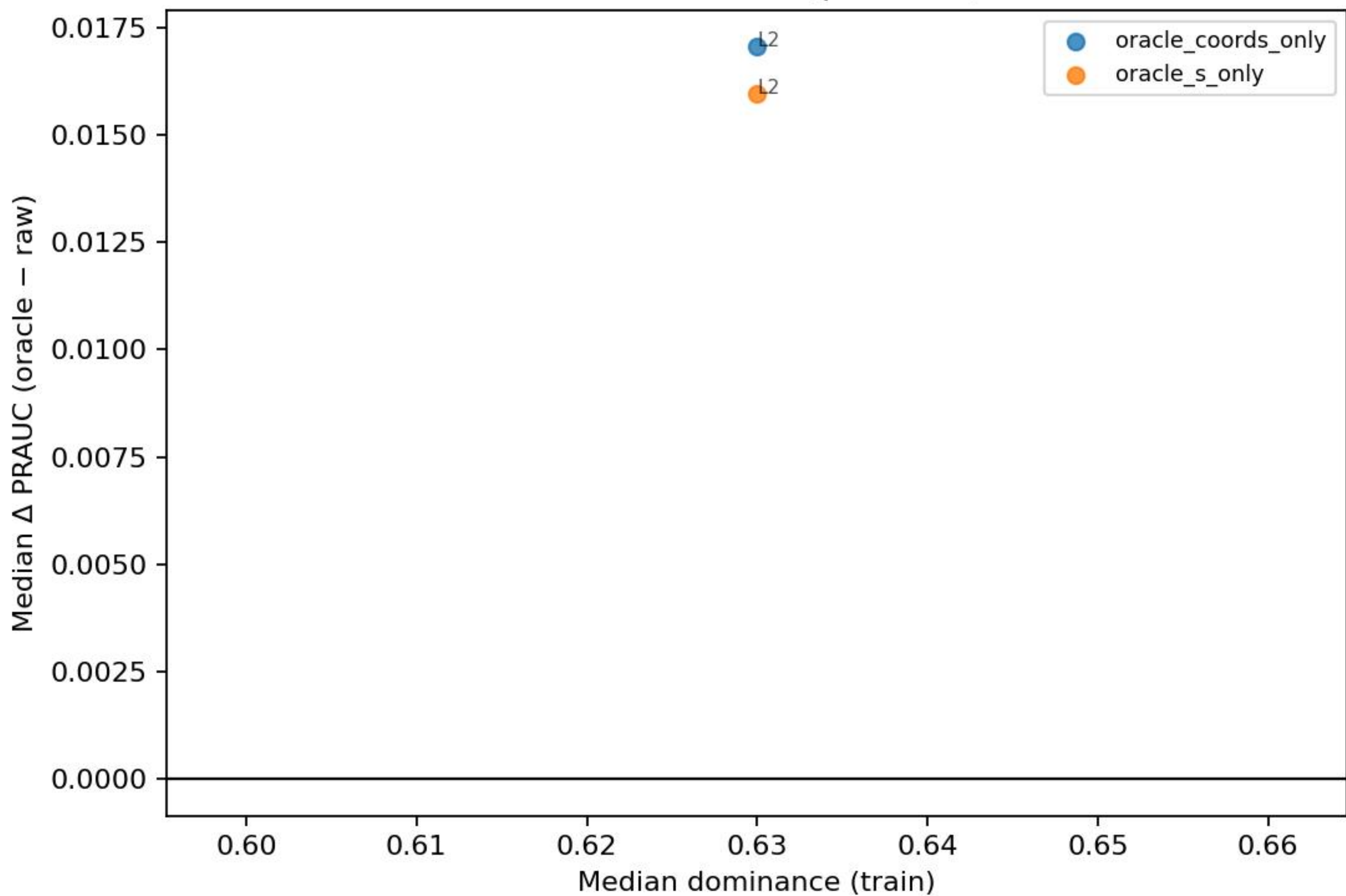
Δ PRAUC (oracle – raw) by task and oracle mode



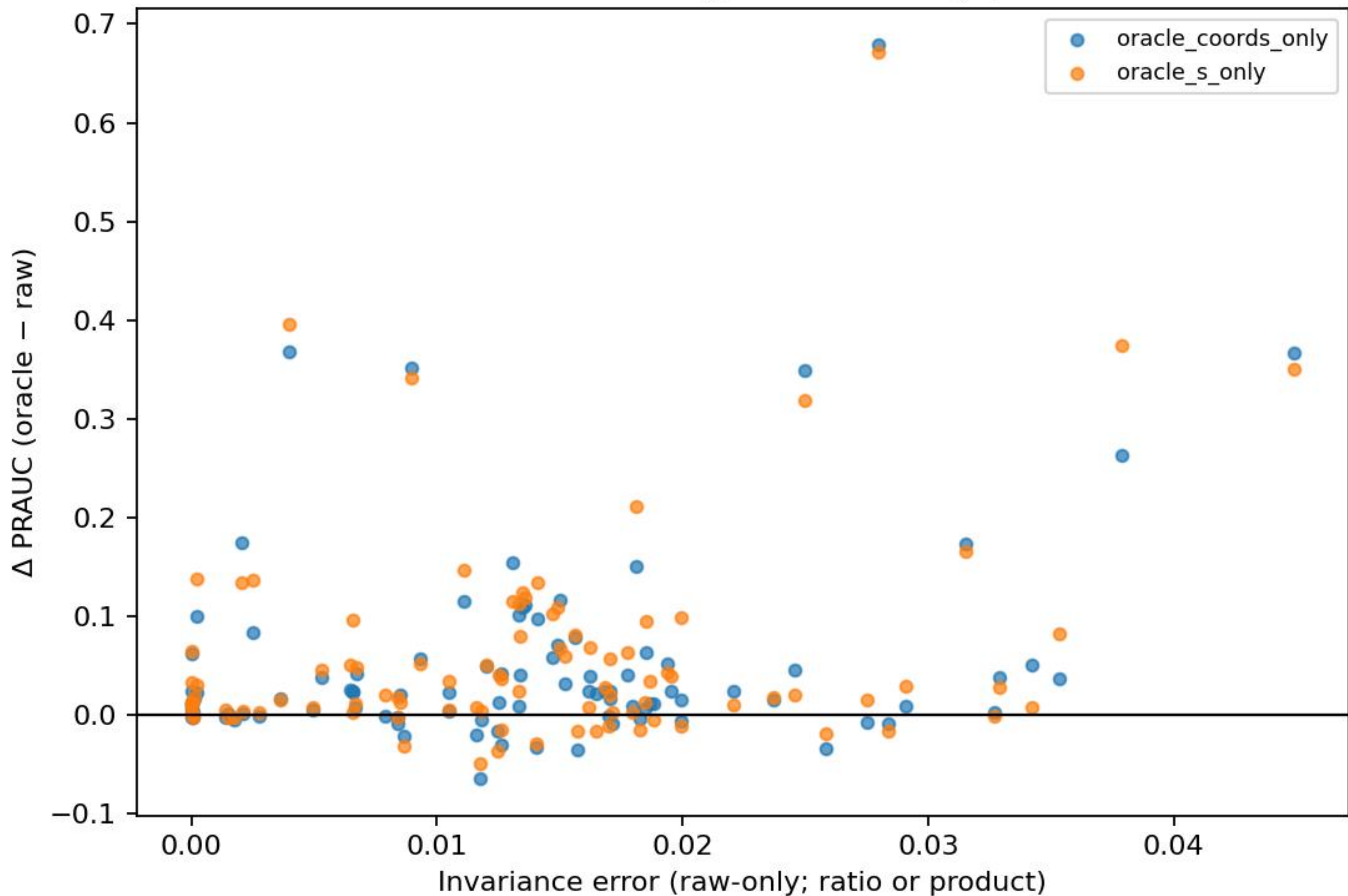
Sum dominance vs generalization gap



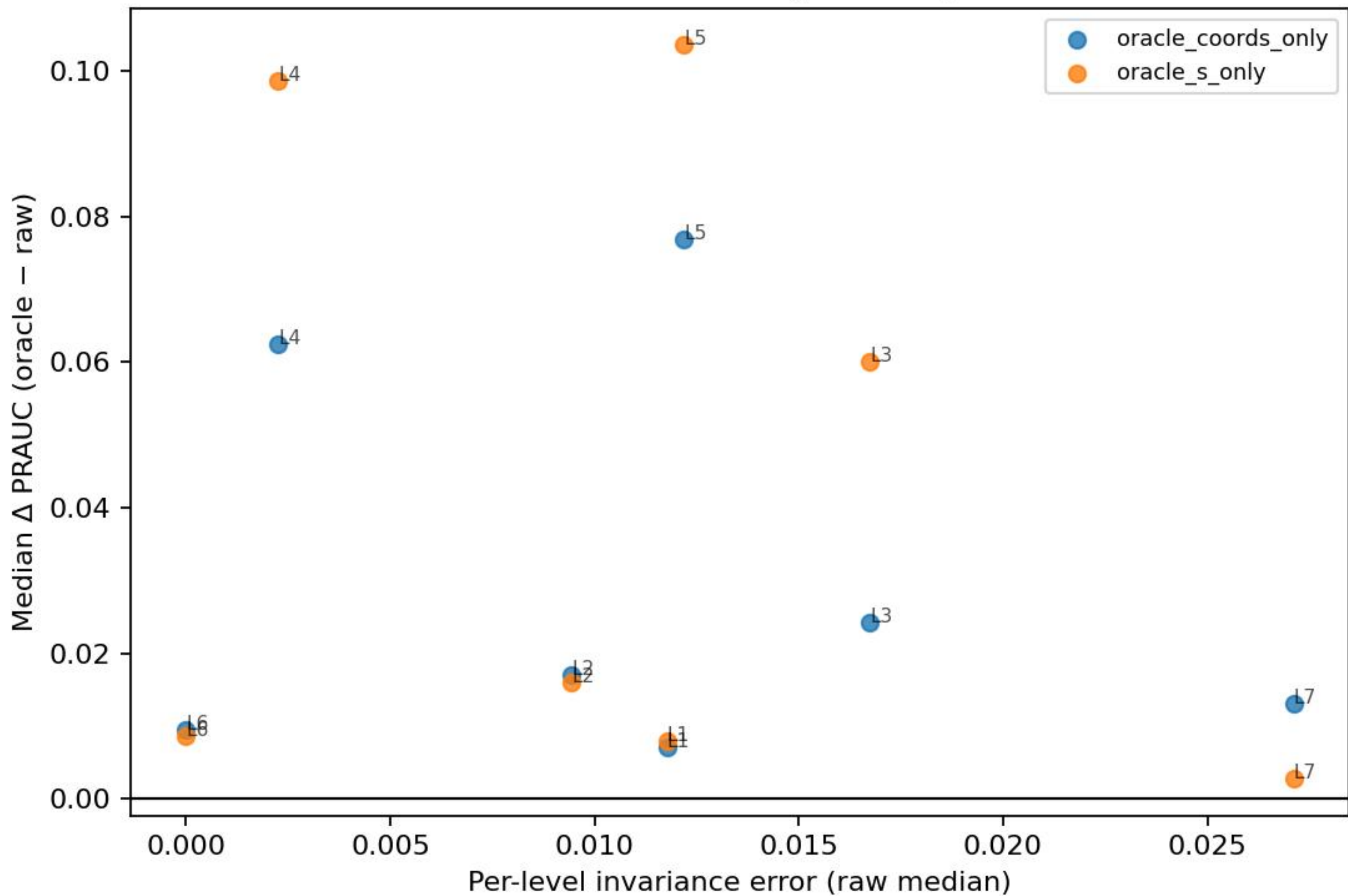
Δ vs dominance (per level)



Invariance vs generalization gap

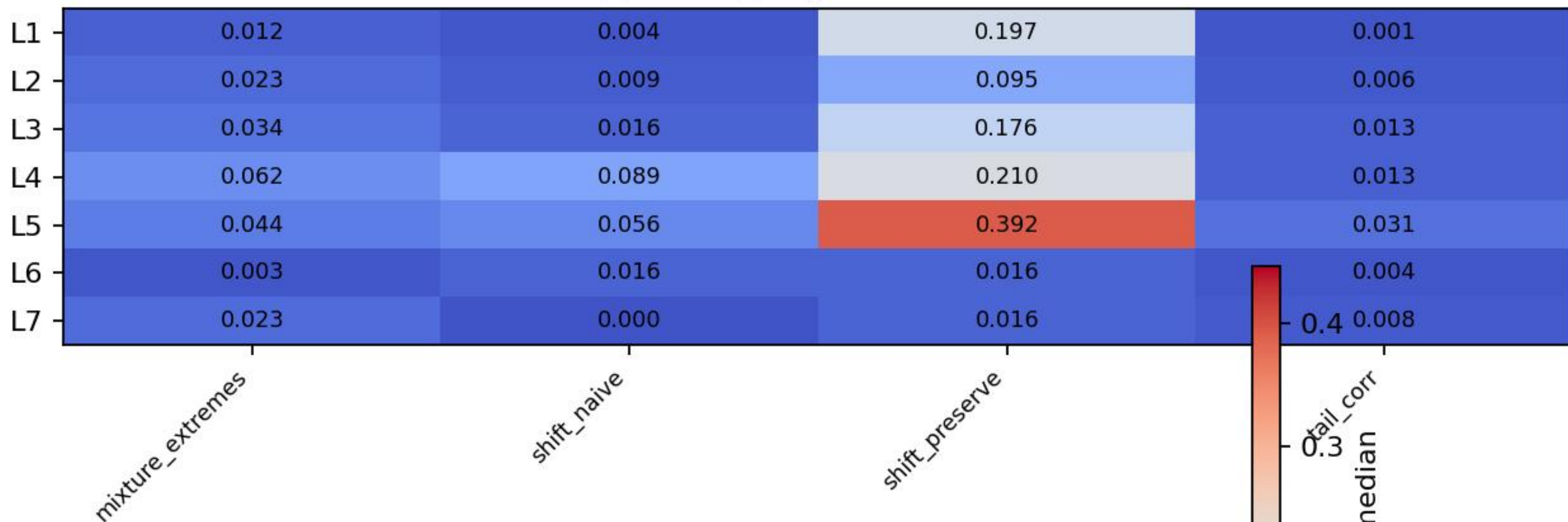


Δ vs invariance (per level)

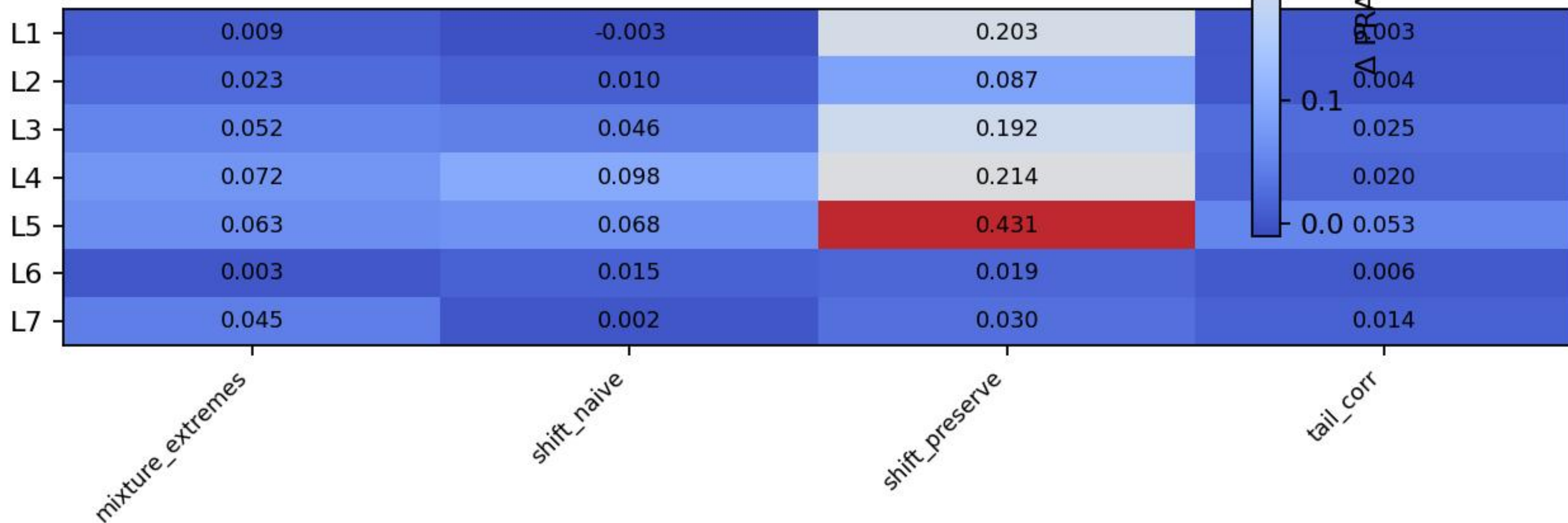


No n-sweep data

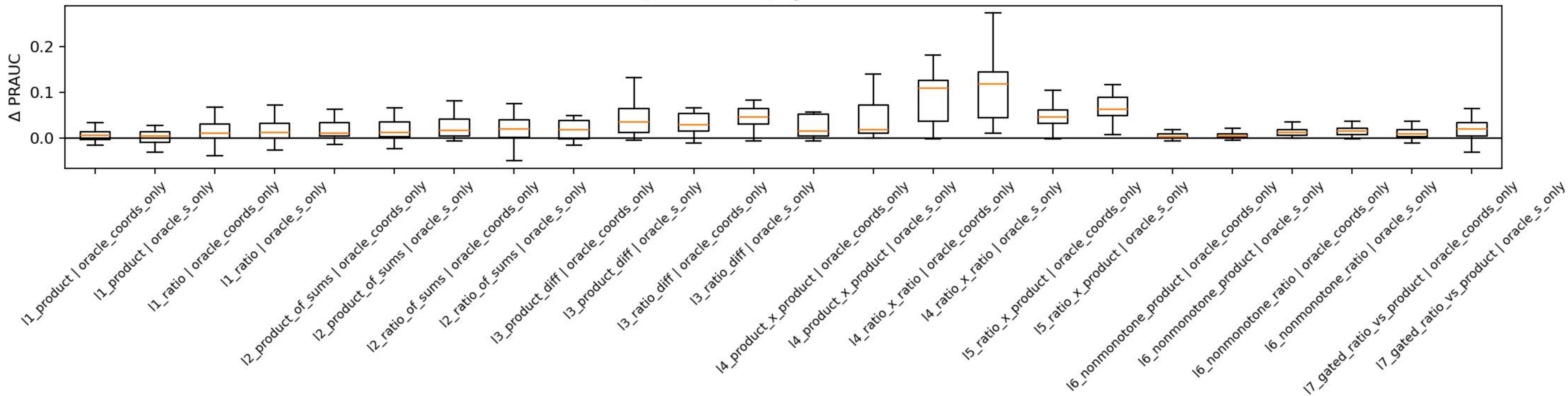
oracle_coords_only: Δ PRAUC median



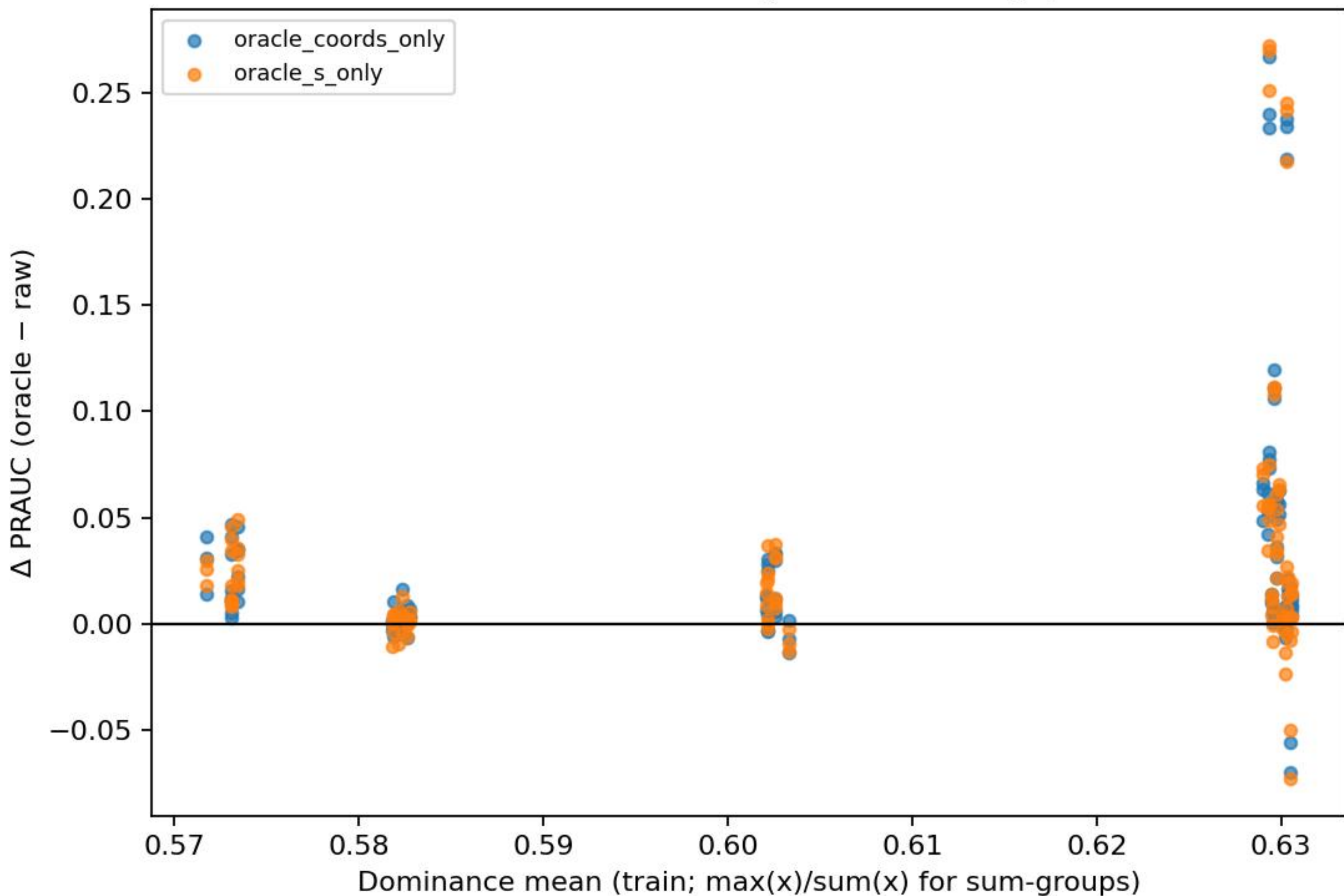
oracle_s_only: Δ PRAUC median



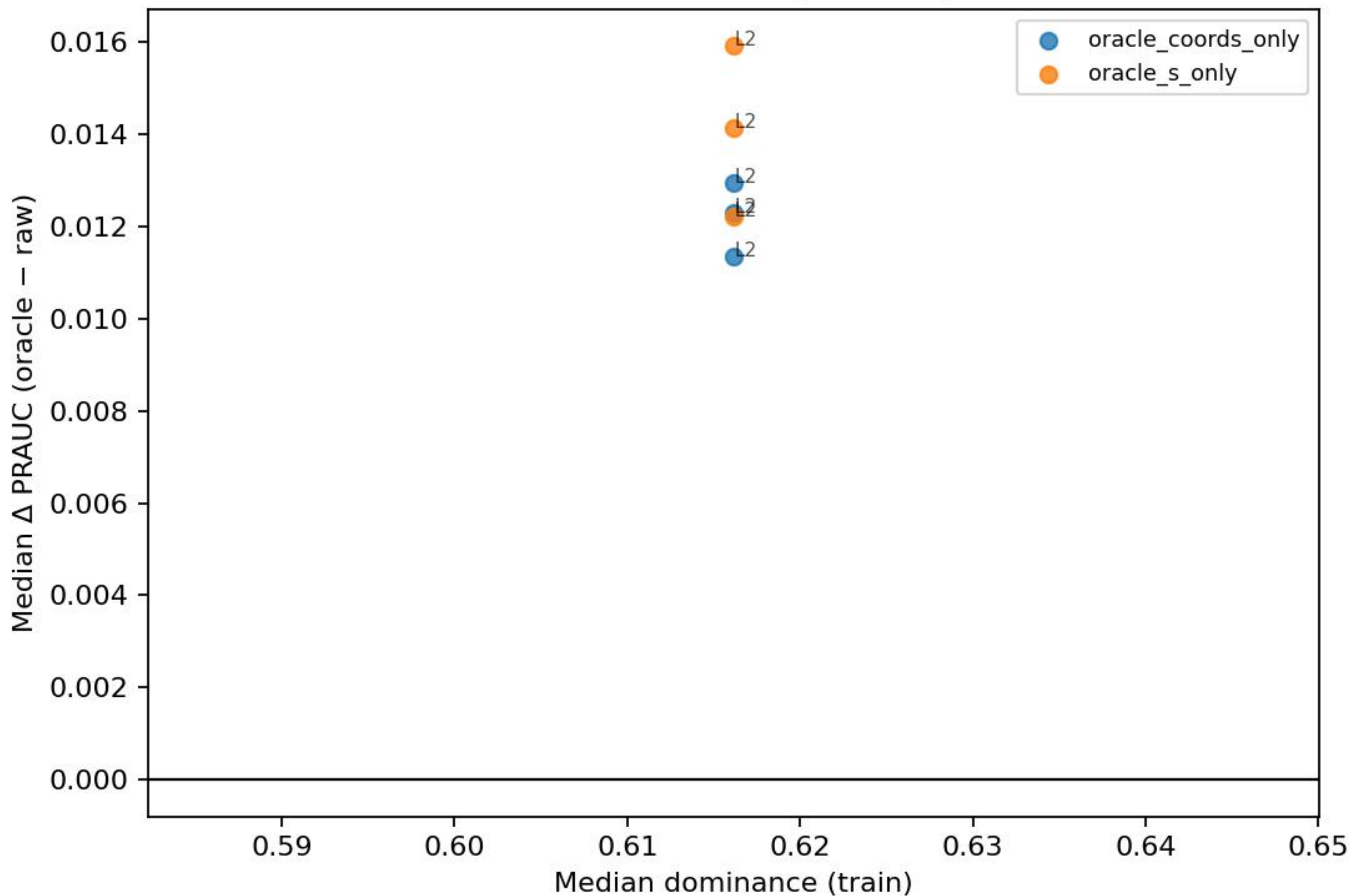
Δ PRAUC (oracle – raw) by task and oracle mode



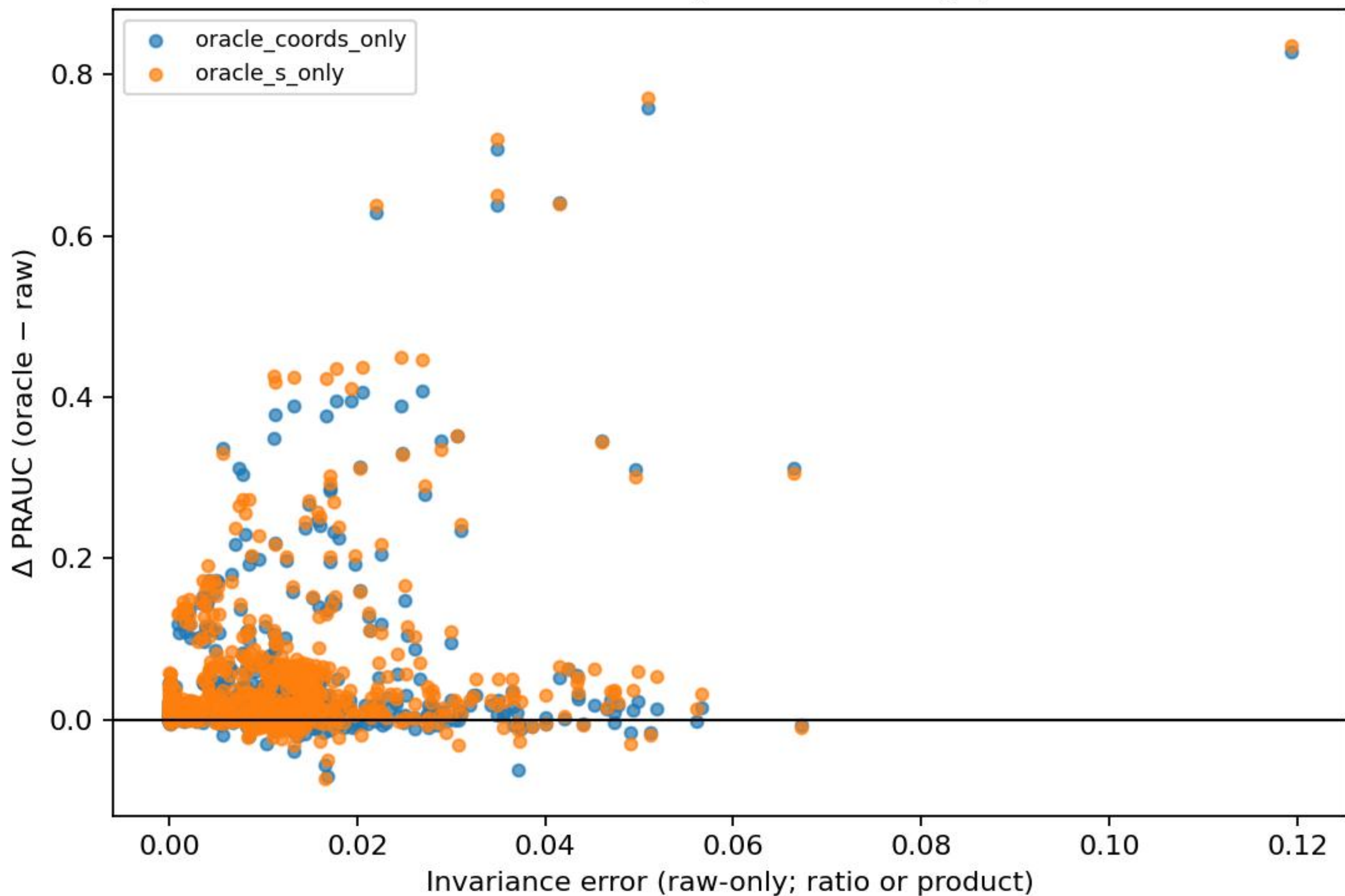
Sum dominance vs generalization gap



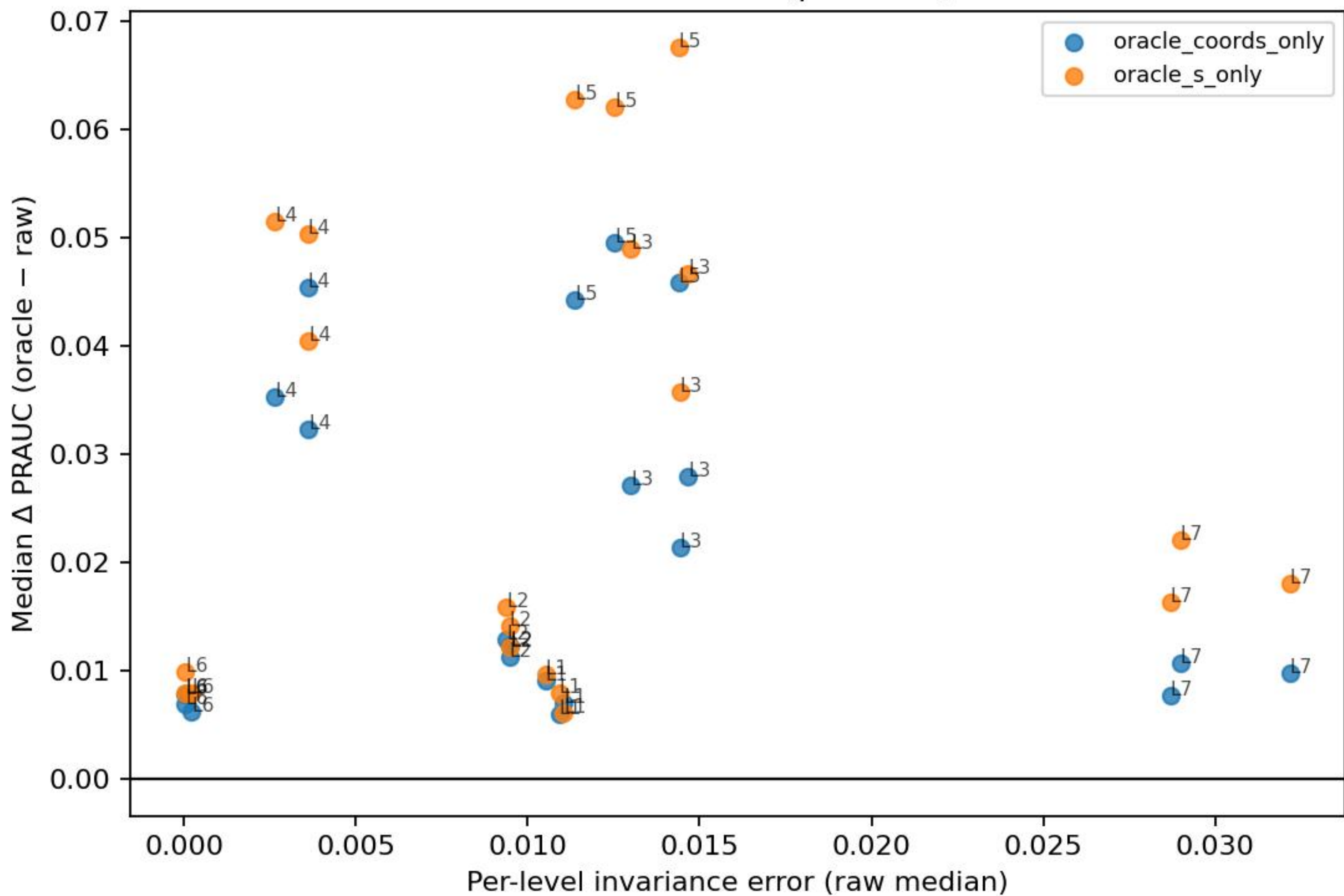
Δ vs dominance (per level)



Invariance vs generalization gap

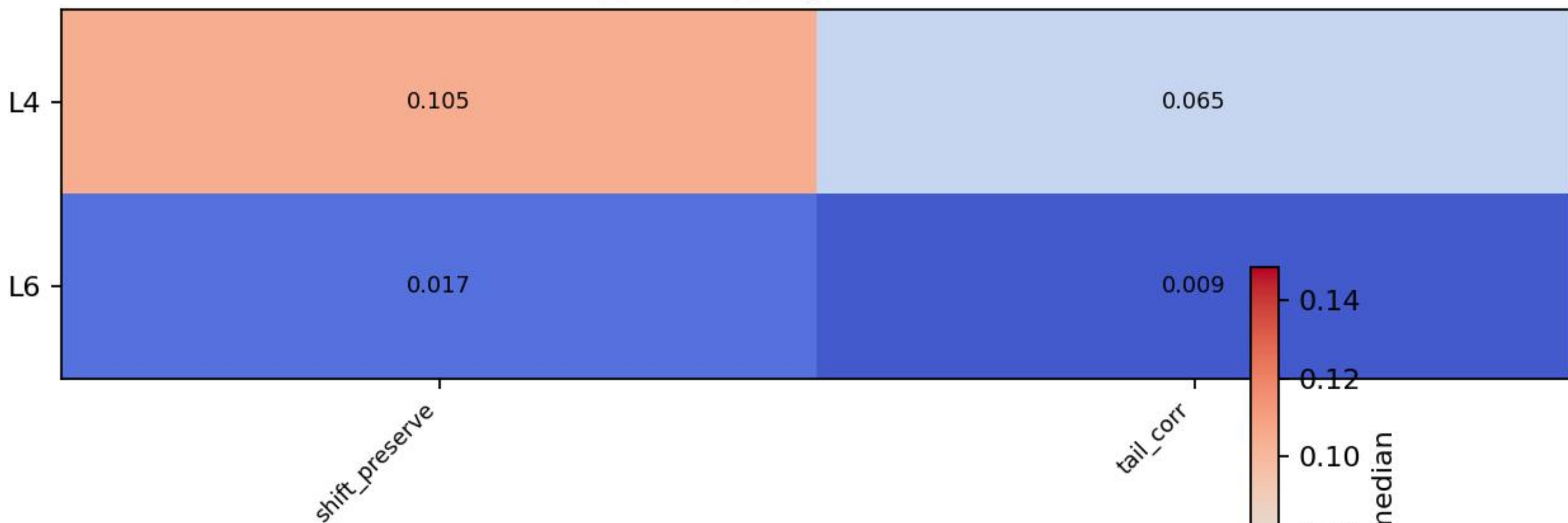


Δ vs invariance (per level)

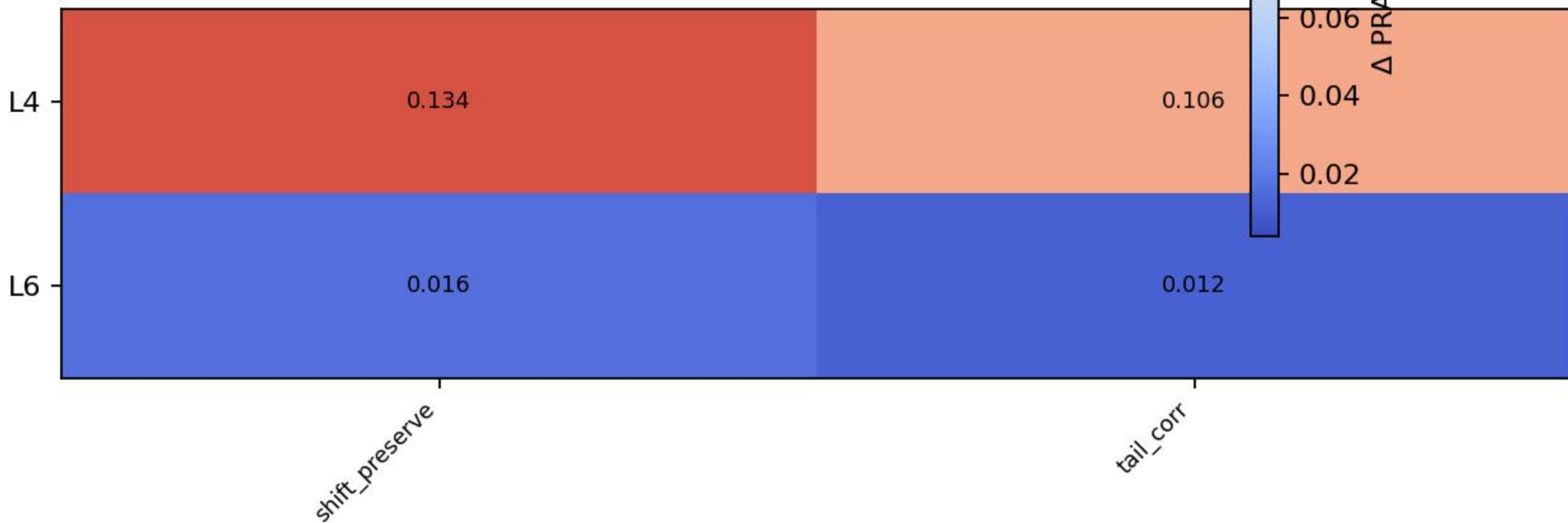


No n-sweep data

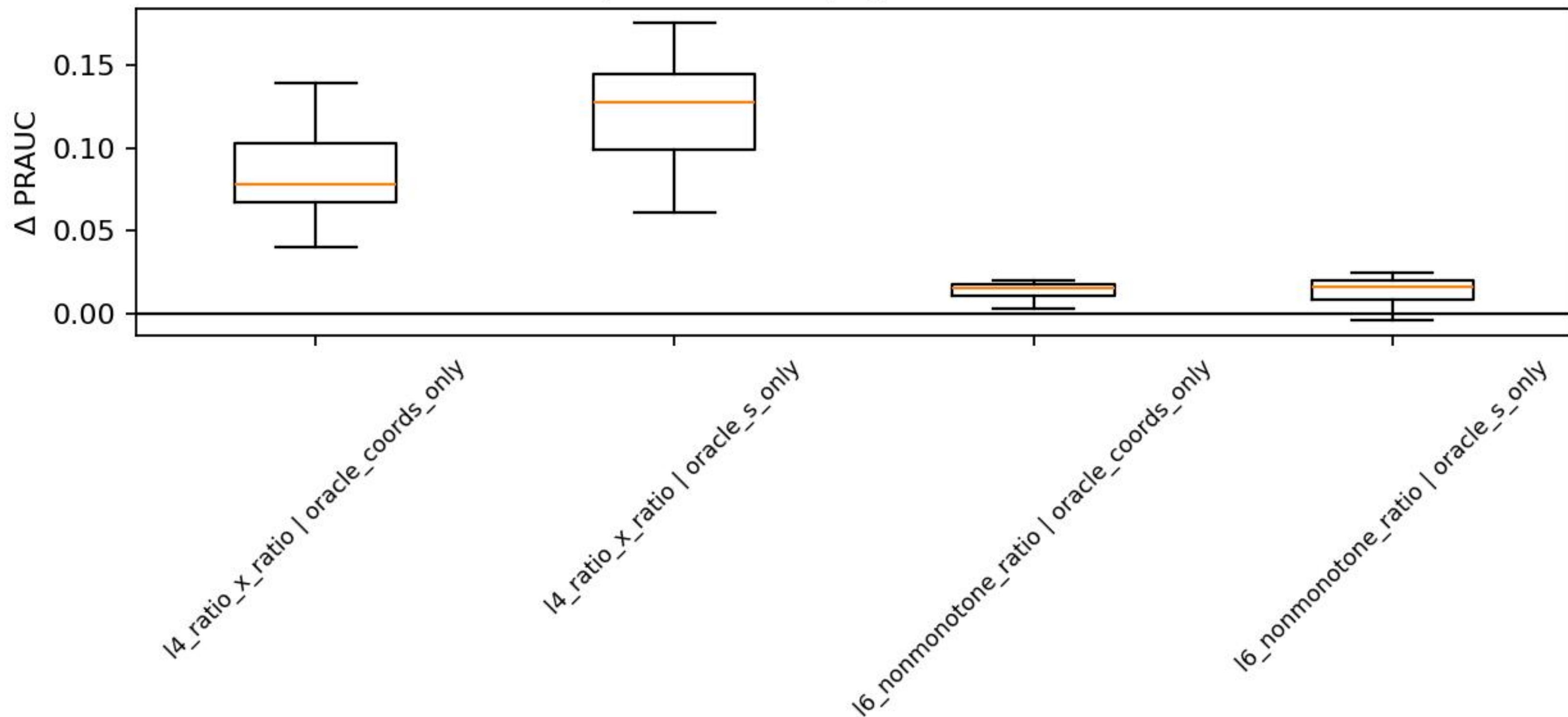
oracle_coords_only: Δ PRAUC median



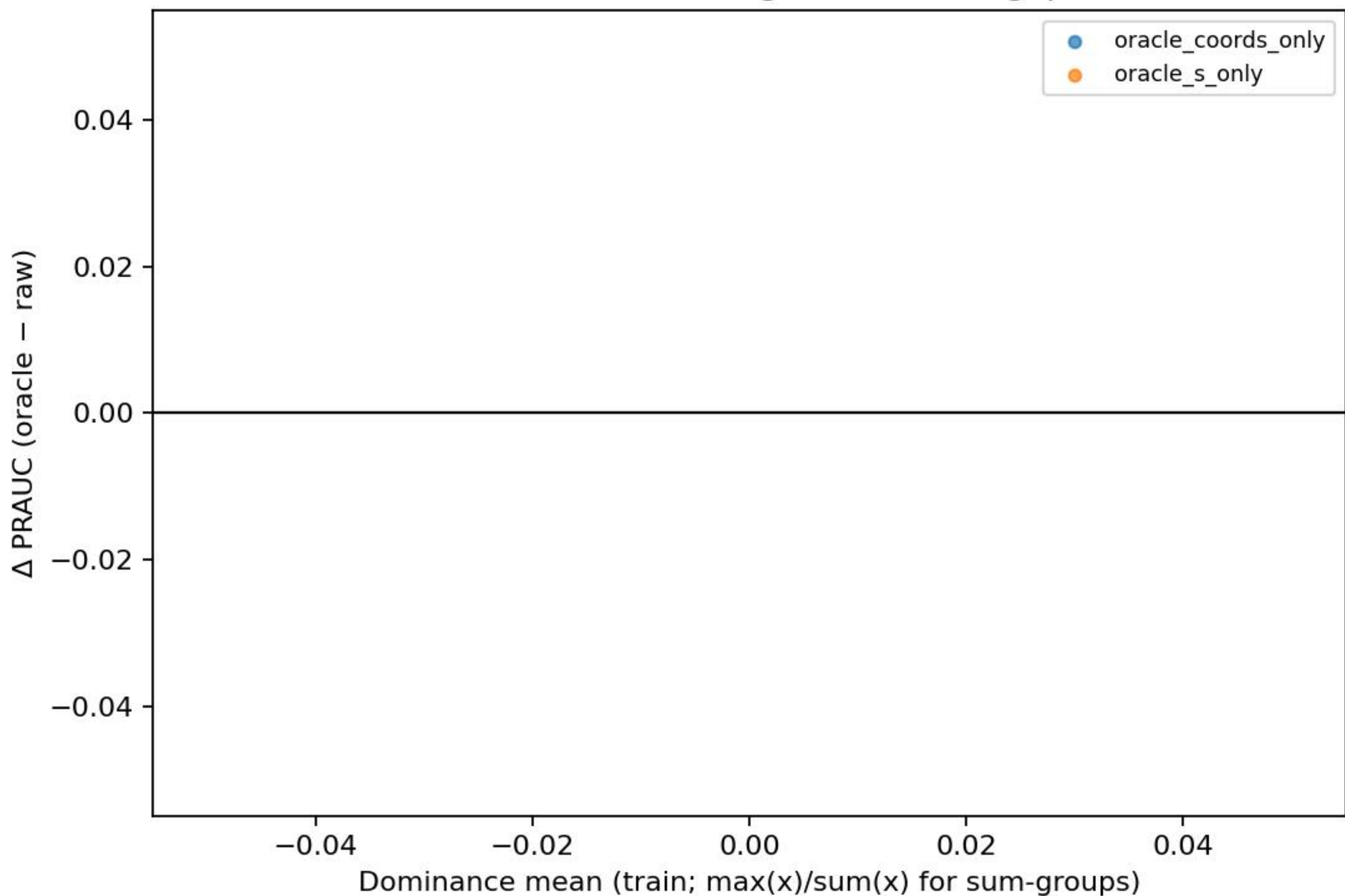
oracle_s_only: Δ PRAUC median



Δ PRAUC (oracle – raw) by task and oracle mode

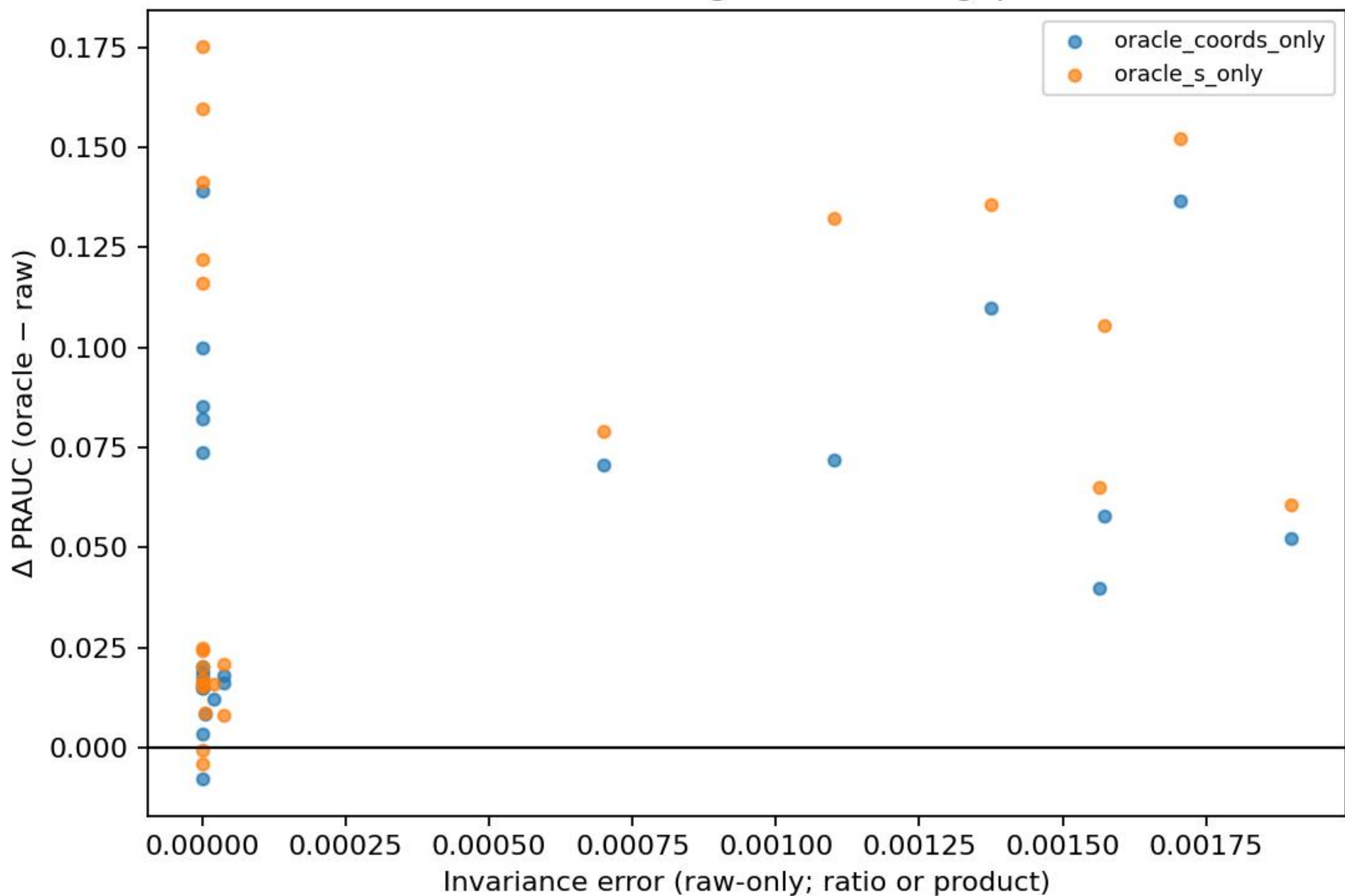


Sum dominance vs generalization gap

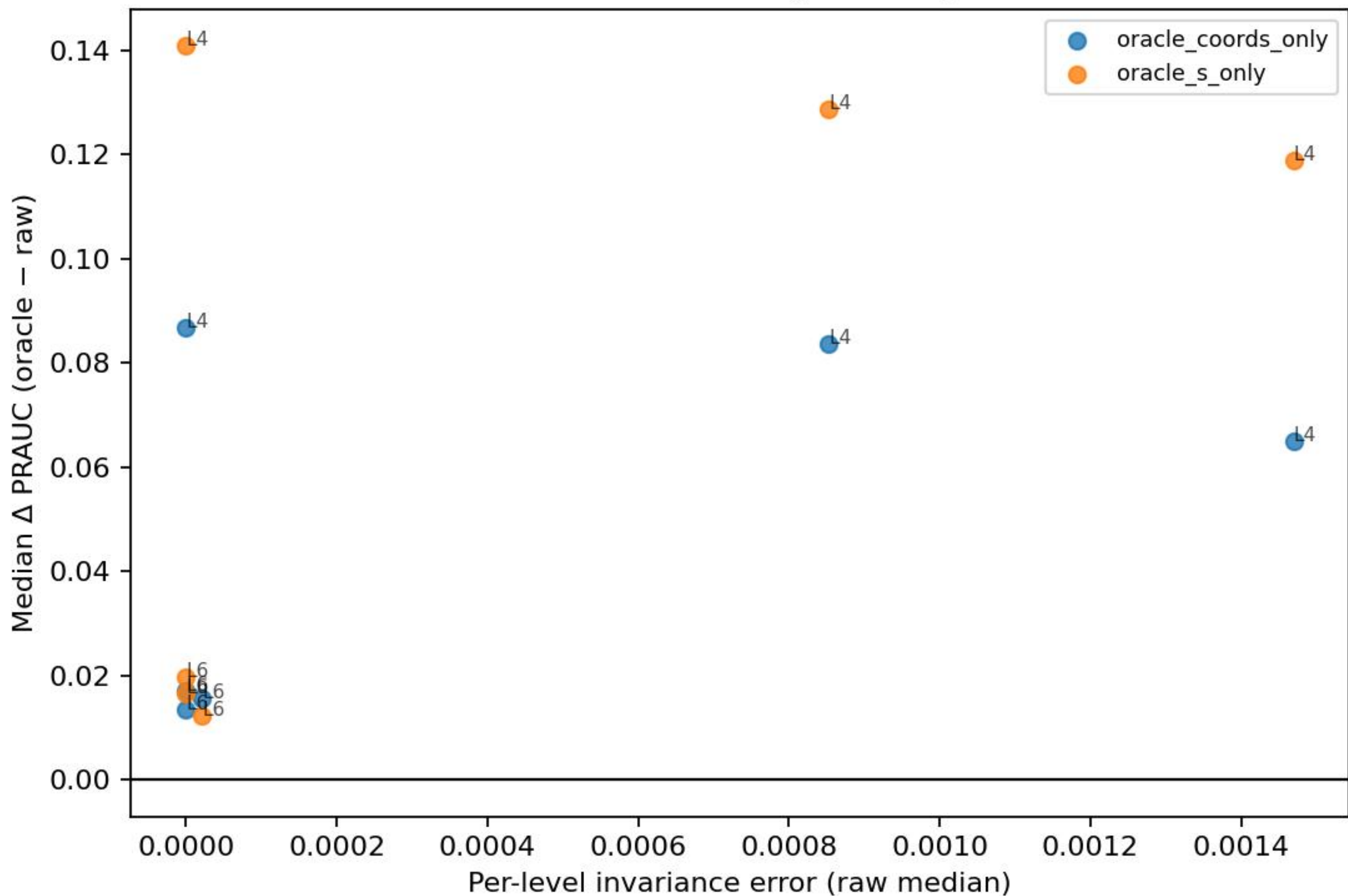


No dominance metrics available

Invariance vs generalization gap



Δ vs invariance (per level)



No n-sweep data