



CUDA UNIFIED MEMORY

Bob Crovella, 6/18/2020



AGENDA



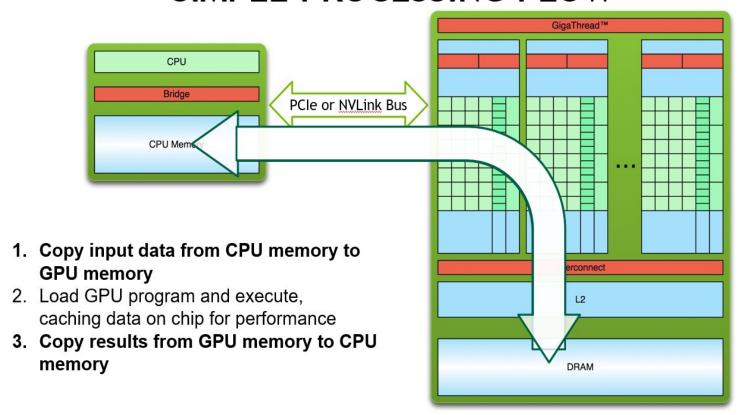
- Managed Memory basic idea, objectives, benefits
- Demand-Paging, Oversubscription, Concurrency, Atomics
- Use Cases: Deep Copies, Linked Lists, C++ Objects, Graph Traversal
- Performance: Prefetching, Hints
- Multi-GPU Considerations
- Further Study
- Homework



THE CUDA 3-STEP PROCESSING SEQUENCE

Recall from Module 1...

SIMPLE PROCESSING FLOW







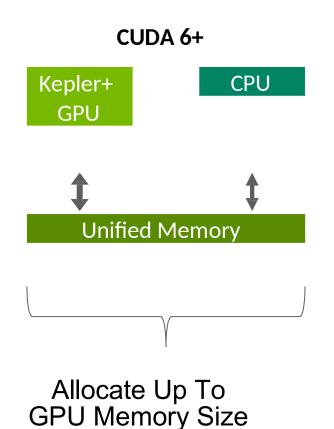
INTRODUCING UNIFIED MEMORY WITH DEMAND PAGING

UNIFIED MEMORY

统一内存



Reduce Developer Effort



Simpler Programming & Memory Model Single allocation, single pointer, accessible anywhere
Eliminate need for *explicit* copy
Simplifies code porting

Maintain
Performance
through
Data Locality

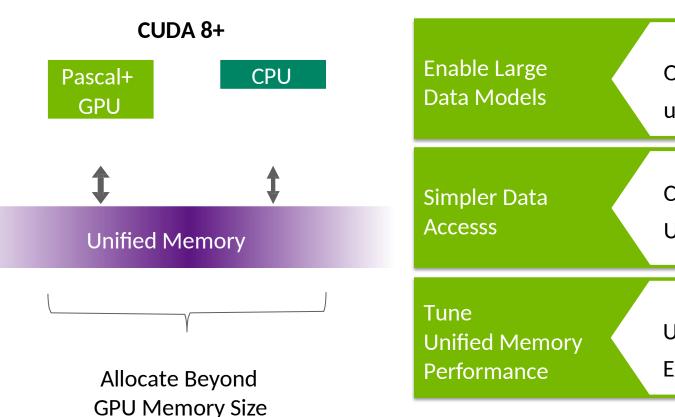
Migrate data to accessing processor
Guarantee global coherence
Still allows explicit hand tuning



CUDA 8+: UNIFIED MEMORY



Demand Paging For Pascal and Beyond



Oversubscribe GPU memory Allocate up to system memory size

cesss CPU/GPU Data coherence
Unified memory atomic operations

Usage hints via cudaMemAdvise API Explicit prefetching API



SIMPLIFIED MEMORY MANAGEMENT CODE



CPU Code

```
void sortfile(FILE *fp, int N) {
  char *data;
  data = (char *)malloc(N);

fread(data, 1, N, fp);

  qsort(data, N, 1, compare);

  use_data(data);

  free(data);
}
```

Ordinary CUDA Code

```
void sortfile(FILE *fp, int N) {
  char *data, *d_data;
  data = (char *)malloc(N);
  cudaMalloc(&d_data, N);
  fread(data, 1, N, fp);
  cudaMemcpy(d_data, data, N, ...); // 1
  qsort<<<...>>>(data,N,1,compare); // 2
  cudaMemcpy(data, d_data, N, ...); // 3

  use_data(data);
  cudaFree(d_data);
  free(data);
}
```



SIMPLIFIED MEMORY MANAGEMENT CODE



CPU Code

```
void sortfile(FILE *fp, int N) {
  char *data;
  data = (char *)malloc(N);

fread(data, 1, N, fp);

  qsort(data, N, 1, compare);

use_data(data);

free(data);
}
```

CUDA Code with Unified Memory

```
void sortfile(FILE *fp, int N) {
  char *data;
  cudaMallocManaged(&data, N);

fread(data, 1, N, fp);

  qsort<<<...>>>(data,N,1,compare);
  cudaDeviceSynchronize();

use_data(data);

cudaFree(data);
}
```



UNIFIED MEMORY EXAMPLE



With On-Demand Paging

```
global
void setValue(int *ptr, int index, int val)
  ptr[index] = val;
void foo(int size) {
  char *data;
                                                            Unified Memory allocation
  cudaMallocManaged(
                            size);
  &data,
  memset(data, 0, size);
                                                            Access all values on CPU
  setValue<<<...>>>(data, size/2, 5);
                                                            Access one value on GPU
  cudaDeviceSynchronize();
  useData(data);
  cudaFree (data);
```



HOW UNIFIED MEMORY WORKS ON PASCAL+



Servicing CPU and GPU Page Faults

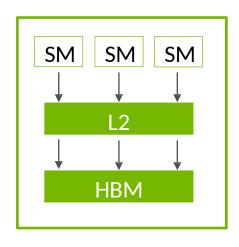
CPU Code GPU Code global Void setValue (char cudaMallocManaged(&array, size); *ptr, int index, char val) memset(array, size); ptr[index] = val; setValue <<<...>>> (array, size/2, 5); **GPU Memory Mapping CPU Memory Mapping** array array Page Fault Page Fault Interconnect

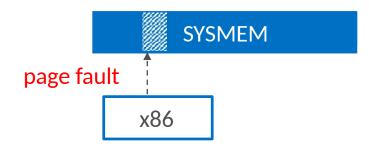


ANALYTICS USE CASE



Concurrent Access To Hash Table



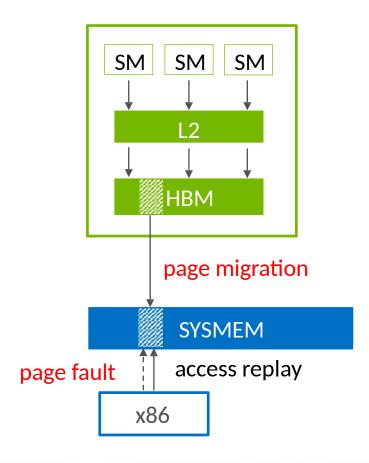




ANALYTICS USE CASE



Concurrent Access To Hash Table

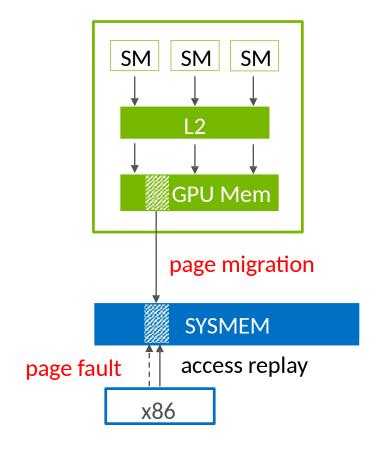


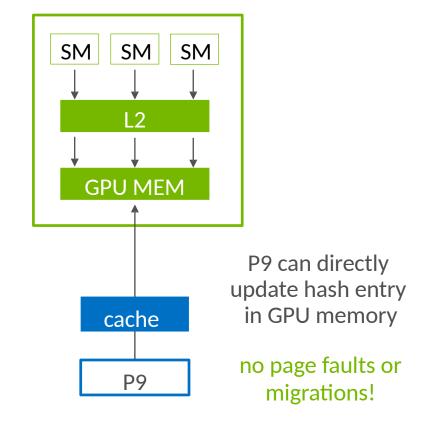


ANALYTICS USE CASE



Concurrent Access To Hash Table



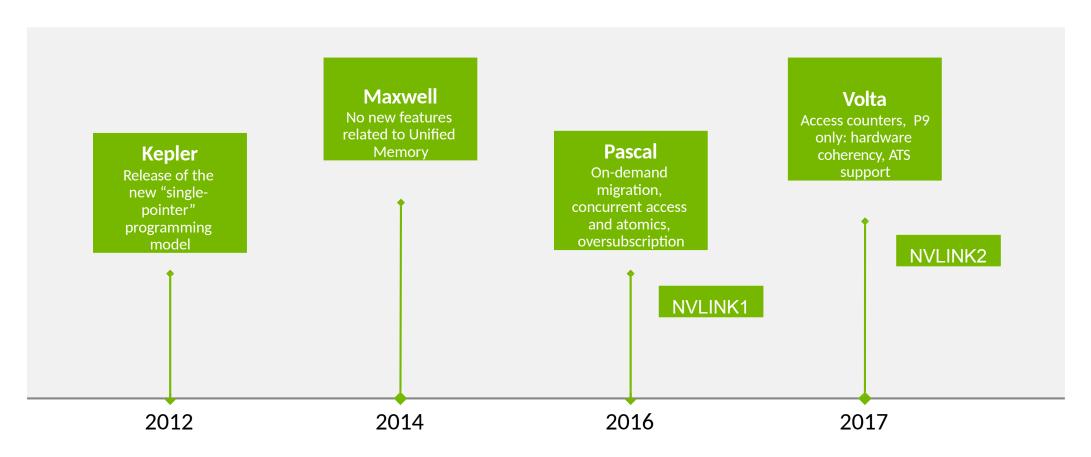




UNIFIED MEMORY



Evolution of GPU architectures





ASIDE: PRE-PASCAL UM REGIME



Summary

- In effect if your device is prior to Pascal (Jetson is a special case)
- In effect if you are on windows OS (CUDA 9.x +).
- Managed data is moved en-masse at point of kernel launch (even data that your kernel may not appear to explicitly touch)
- After a kernel launch, cudaDeviceSynchronize() triggers the runtime to make data available to CPU code again
- No concurrent access, no on-demand migration to GPU, no oversubscription
- Just use cudaMallocManaged() where you would use malloc(), or new
- Use cudaFree() instead of free(), or delete



UNIFIED MEMORY ON PASCAL+



GPU Memory Oversubscription

```
void foo() {
  // Assume GPU has 16 GB memory
  // Allocate 64 GB
  char *data;
  // be careful with size type:
  size_t size = 64ULL*1024*1024*1024;
  cudaMallocManaged(&data, size);
}
```

64 GB allocation

Pascal supports allocations where only a subset of pages reside on GPU. Pages can be migrated to the GPU on demand.

Fails on Kepler/Maxwell



UNIFIED MEMORY (UM) ON PASCAL+



Concurrent CPU/GPU Access to Managed Memory

```
global void mykernel(char *data) {
  data[1] = 'q';
void foo()
  { char
  *data;
  cudaMallocM
  mykeedeldat...>>> (data);
  a/ ab; synchronize here
  data[0] = 'c';
  cudaFree (data);
```

OK on Pascal+: just a page fault

Concurrent CPUs access to 'data' on previous GPUs (e.g. Kepler/Maxwell) caused a fatal segmentation fault

Note that there may still be ordering issues or data visibility issues; UM concurrency does not provide any ordering or visibility guarantees, but see system-wide atomics



UNIFIED MEMORY ON PASCAL+



System-Wide Atomics

```
global void mykernel(int *addr) {
  atomicAdd system(addr, 10);
void foo() {
  int *addr;
  cudaMalloc
  Managed (ad
  dr, 4);
  *addr = 0;
 mykernel<<
  <...>>> (ad
  dr);
  // cpu
  atomic:
  sync fetch
  and add(a
  ddr, 10);
```

Pascal enables system-wide atomics

- Direct support of atomics over NVLink
- Software-assisted over PCIe

System-wide atomics not available on Kepler / Maxwell

System-wide atomics: atomic for all threads in the current program including other CPUs and GPUs in the system. These are suffixed with _system, e.g., atomicAdd_system.

Device-wide atomics: atomic for all CUDA threads in the current program executing in the same compute device as the current thread. These are not suffixed and just named after the operation instead, e.g., atomicAdd.

Block-wide atomics: atomic for all CUDA threads in the current program executing in the same thread block as the current thread. These are suffixed with _block, e.g., atomicAdd_block.

```
struct dataElem {
  int key;
  int len;
  char *name;
```

USE CASE: DEEP COPY



```
char buffer[len];
```

- Both entities (object and buffer) need to be transferred to the device
- Pointer in object needs to be "fixed" to point to new address on device for device copy of buffer

```
void launch(dataElem *elem, int N) { // an array of dataElem
  dataElem *d_elem;
  // Allocate storage for array of struct and copy array to device
  cudaMalloc(&d_elem, N*sizeof(dataElem));
  cudaMemcpy(d_elem, elem, N*sizeof(dataElem),
  cudaMemcpyHostToDevice);
  for (int i = 0; i < N; i++) { // allocate/fixup each buffer separately
      char *d_name;
      cudaMalloc(&d_name, elem[i].len);
      cudaMemcpy(d_name, elem[i].len);
      cudaMemcpy(d_name, elem[i].name, elem[i].len, cudaMemcpyHostToDevice);
      cudaMemcpy(&(d_elem[i].name), &d_name, sizeof(char *), cudaMemcpyHostToDevice);}
  // Finally we can launch our kernel
  Kernel<<< ... >>>(d_elem);}
```



USE CASE: LINKED LIST





- Similar to deep copy case
- Complex to code up the copy operation
- Unified Memory makes it trivial



USE CASE: C++ OBJECTS

Overloading new and delete

Overload new and delete in base class

```
class Managed {
public:
  void *operator new(size t len) {
    void *ptr;
    cudaMallocManaged(&ptr, len);
    cudaDeviceSynchronize();
    return ptr;
  void operator delete(void *ptr) {
    cudaDeviceSynchronize();
    cudaFree(ptr);
```

inherit to build string class

```
// Deriving allows pass-by-reference
class umString : public Managed {
  int length;
  char *data;
public:
  // UM copy constructor allows
  // pass-by-value
  umString (const umString &s) {
    length = s.length;
    cudaMallocManaged(&data,
length);
    memcpy(data, s.data,
    length);
```



USE CASE: C++ OBJECTS



Overloading new and delete

Inherit to build my class;

```
// Note "managed" here also
class dataElem : public Managed {
public:
 int key;
 umString name;
```

```
dataElem *data = new dataElem[N];
...
// C++ now handles our deep copies
Kernel<<< ... >>> (data);
```





Demand Paging Impact

This kernel call runs much slower than the Pre-pascal UM 6 case, or the non-UM case.

Each page fault triggers service overhead.

Relying on page faults to move large amounts of data, page-by-page, with overhead on each page, is inefficient.

For bulk movement, a single "memcpy-like" operation is much more efficient

```
global void kernel(float *data) {
  int idx = ...;
  data[idx] = val;}
int n = 256*256;
float *data:
cudaMallocManaged(&data, n*sizeof(float);
Kernel<<<256,256>>> (data);
```





Prefetching

Explicit prefetching:

cudaMemPrefetchAsync(ptr, length, destDevice,

stream)

UM alternative to cudaMemcpy(Async)

Can target any GPU and also the CPU

"Restores" performance

```
__global__ void kernel(float *data) {
   int idx = ...;
   data[idx] = val; }
...
int n = 256*256;
int ds = n*sizeof(float);
float *data;
cudaMallocManaged(&data, ds);
cudaMemPrefetchAsync(data, ds, 0);
Kernel<<<256,256>>> (data);
cudaMemPrefetchAsync(data, ds, cudaCpuDeviceId); // copy back to host
```





Explicit Memory Hints

Advise runtime on expected memory access behaviors with:

cudaMemAdvise(ptr, count, hint, device);

Hints:

cudaMemAdviseSetReadMostly: Specify read duplication
cudaMemAdviseSetPreferredLocation: suggest best location
cudaMemAdviseSetAccessedBy: suggest mapping

Hints don't trigger data movement by themselves





Hints: cudaMemAdviseSetReadMostly

Data will usually be read-only

UM system will make a "local" copy of the data for each processor that touches it

If a processor writes to it, this invalidates all copies except the one written.

Device argument is ignored





Hints: cudaMemAdviseSetPreferredLocation

Suggests which processor is the best location for data

Does not automatically cause migration

Data will be migrated to the preferred processor ondemand (or if prefetched)

If possible, data (P2P) mappings will be provided when other processors touch it

If mapping is not possible, data is migrated

Volta+ adds access counters to help GPU make good decisions for you



PERFORMANCE



Final Words

- UM is first and foremost about ease of programming and programmer productivity
- UM is not primarily a technique to make well-written CUDA codes run faster
- UM cannot do better than expertly written manual data movement, in most cases
- It can be harder to achieve expected concurrency behavior with UM.
- Misuse of UM can slow a code down dramatically
- There are scenarios where UM may enable a design pattern (e.g. graph traversal).
- Oversubscription does not easily/magically give you GPU-type performance on arbitrary datasets/algorithms
- For codes that tend to use many different libraries, each of which makes some demand on GPU memory with no
- regard for what other libraries are doing, UM can sometimes be a primary way to tackle this challenge (via use of
- oversubscription), rather than an entire rewrite of the codebase



FUTURE SESSIONS



- Concurrency (streams, copy/compute overlap, multi-GPU)
- Analysis Driven Optimization
- Cooperative Groups



FURTHER STUDY



UM basics:

https://devblogs.nvidia.com/unified-memory-cuda-beginners/

https://devblogs.nvidia.com/unified-memory-in-cuda-6/

optimization:

https://devblogs.nvidia.com/maximizing-unified-memory-performance-cuda/

UM architecture:

http://on-demand.gputechconf.com/gtc/2018/presentation/s8430-everything-vou-need-to-know-about-unified-memory.pdf

Programming Guide:

https://docs.nvidia.com/cuda/cuda-c-programming-guide/index.html#um-unified-memory-programming-hd

CUDA Sample Code: conjugateGradientUM

DLI: Introduction to Accelerated Computing with CUDA C++ (3 labs)



HOMEWORK



- Log into Summit (ssh <u>username@home.ccs.ornl.gov</u> -> ssh summit) Clone
- GitHub repository:
 - Git clone git@github.com:olcf/cuda-training-series.git
- Follow the instructions in the readme.md file:
 - https://github.com/olcf/cuda-training-series/blob/master/exercises/hw6/ readme.md
- Prerequisites: basic linux skills, e.g. ls, cd, etc., knowledge of a text editor like vi/emacs, and some knowledge of C/C++ programming





BACKUP



HOW UNIFIED MEMORY WORKS IN CUDA 6

En-masse Movement of Data to GPU

Page Fault

Interconnect

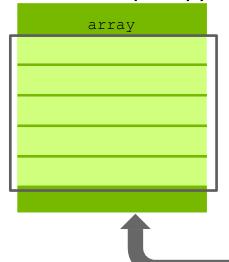
GPU Code

```
__global_
void setValue(char *ptr, int index, char val)
{
   ptr[index] = val;
}
```

CPU Code

```
cudaMallocManaged(&array, size);
memset(array, size);
setValue<<<...>>>(array, size/2, 5);
```

GPU Memory Mapping



CPU Memory Mapping

