

R.E.C.A.R

Recursive Explore and Check Abstraction Refinement

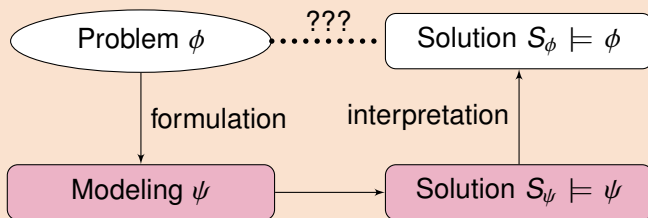
Jean-Marie Lagniez, Daniel Le Berre,
Tiago de Lima and Valentin Montmirail

CRIL-CNRS UMR 8188, F62300 Lens, France

Séminaire CRIL - Lens - September 14th 2017

Abstraction: Idea & Motivation

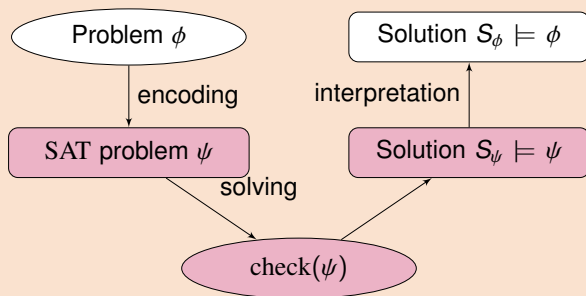
- Comes from: **Mathematical Modeling**



- Works for theoretical problems
- But what about practice?

Modeling: Propositional Formula

- For many **NP** problems: Encoding into SAT



- Is it always a good idea?

SAT solver

- ▶ Extremely efficient software
- ▶ Based on CDCL approach [SS99, MMZ⁺01]
- ▶ One of the current best is: Glucose [ES03a, AS09] ☺
- ▶ Able to solve efficiently problems with $\approx 10^8$ variables/clauses

SAT solver: Features

- ▶ Answer *SAT* and a model when the formula is satisfiable
- ▶ Answer *UNSAT*:
 - ▶ with a proof of unsatisfiability if asked [Gel02]
 - ▶ A unsatisfiable core if asked [ES03a]
- ▶ Can work in an incremental way [ES03b, ES03a, ALS13]
- ▶ Can work under assumptions [ES03a]

Unsatisfiable core

Basically the “reason” why a formula is UNSAT (subset of clauses)

SAT solver: One limitation

- ▶ What happen when the encoding of the problem is too big ?
- ▶ Could be solved 'easily' but will not because of memory...

HCP via SAT: does not scale

- ▶ Ex. The Hamiltonian Cycle Problem (HCP)
- ▶ HCP: $O(n^3)$ clauses [Pre03]
- ▶ Transitive relations for any three nodes
- ▶ HCP via SAT: hard to solve HCP of over 1000 nodes
- ▶ HCP solver 'LKH' scales up to 10,000 nodes

We need a SAT solver in a more complex procedure...

V is a set of n nodes, A is a set of vertexes, and $G = (V,A)$ is a digraph. $x_{ij} = 1 \leftrightarrow (i,j) \in A$ is used in a solution cycle.

$$\sum_{(i,j) \in A} x_{ij} = 1 \quad \text{for each } i = 1, \dots, n \text{ (out-degree)}$$

$$\sum_{(i,j) \in A} x_{ij} = 1 \quad \text{for each } j = 1, \dots, n \text{ (in-degree)}$$

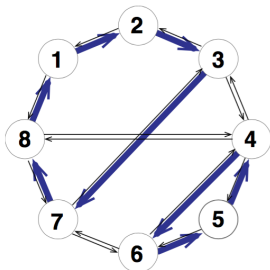
$$\sum_{(i,j) \in S} x_{ij} \leq |S| - 1 \quad S \subset V, 2 \leq |S| \leq n - 2 \text{ (connectivity)}$$

- ▶ in/out-degree constraints ensure that in/out-degrees are respectively exact one for each node in solution cycles
- ▶ connectivity constraint prohibits the formulation of sub-cycles

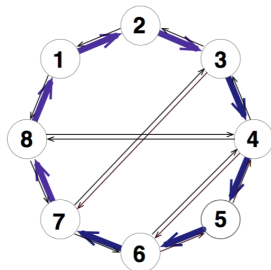
SAT solver: how to solve HCP efficiently?

8

- ▶ With only in/out-degree constraints, we have cycles but they may not be connected (Case A)
- ▶ With all constraints, we can find a Hamiltonian cycle (Case B)



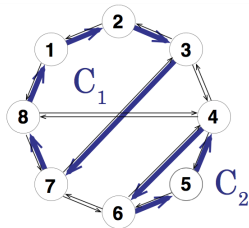
(Case A)
in/out-degree



(Case B)
in/out-degree + connectivity

HCP via SAT: no need to generate connectivity constraints

- ▶ Refine overall constraints by adding blocking clauses generated from counter examples [SLR⁺14].
- ▶ We can get lucky and find a Hamiltonian Cycle quickly



Blocking Clauses

$$C_1 \quad \neg x_{12} \vee \neg x_{23} \vee \neg x_{37} \vee \neg x_{78} \vee \neg x_{81}$$

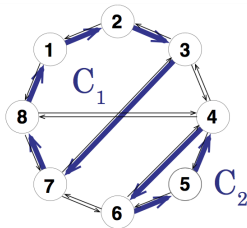
$$C'_1 \quad \neg x_{87} \vee \neg x_{73} \vee \neg x_{32} \vee \neg x_{21} \vee \neg x_{18}$$

$$C_2 \quad \neg x_{46} \vee \neg x_{65} \vee \neg x_{54}$$

$$C'_2 \quad \neg x_{45} \vee \neg x_{56} \vee \neg x_{64}$$

HCP via SAT: no need to generate connectivity constraints

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This idea of going step by step and refining each step is called:

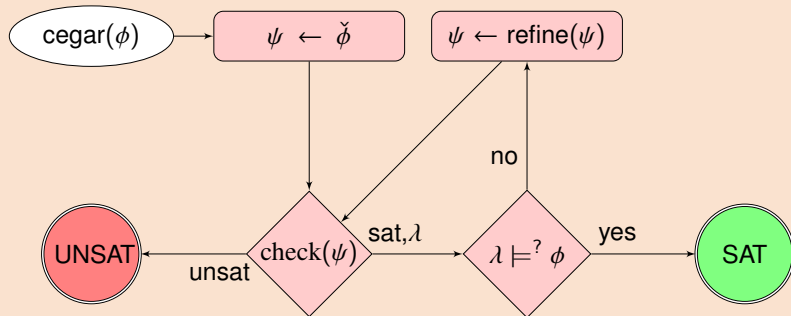
CEGAR: CounterExample Guided Abstraction Refinement

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To solve a problem, we may need to consider only a small part of it
[CGJ⁺03]

- ▶ To abstract problems: hoping it will be easier to solve
- ▶ Two variants of abstraction:
 - ▶ Under-abstraction: abstraction has **more** solutions
 - ▶ Over-abstraction: abstraction has **less** solutions
- ▶ CEGAR-over: CEGAR approach using over-abstractions
- ▶ CEGAR-under: CEGAR approach using under-abstractions

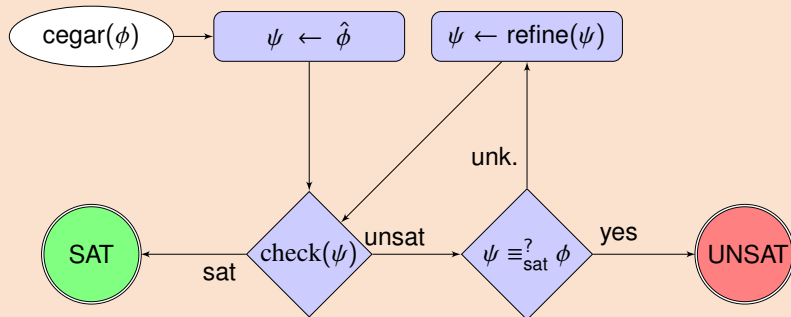
CEGAR-under



Example

SAT problem, by increasing step by step, the number of clauses

CEGAR-over



Example

Planification problem, by increasing step by step, the horizon

Advantages

- ▶ If problem mainly satisfiable: CEGAR-over
- ▶ If problem mainly unsatisfiable: CEGAR-under
- ▶ Everytime check improves, CEGAR improves
- ▶ Many applications already use CEGAR

Drawbacks

- ▶ Not efficient when 50/50 chances of being SAT/UNSAT
- ▶ Not efficient when we need many refinement steps

Recursive Explore and Check Abstraction Refinement

- ▶ Called *RECAR* [LLdLM17]
- ▶ Inspired by CEGAR [CGJ⁺03]
- ▶ Rely on 5 very important assumptions

RECAR Assumptions

1. Function 'check' is sound, complete and terminates
2. $isSAT(\hat{\phi})$ implies $isSAT(refine(\hat{\phi}))$
3. $\exists n \in \mathbb{N}$ s.t. $refine^n(\hat{\phi}) \equiv_{sat}^? \phi$.
4. $isUNSAT(\check{\phi})$ implies $isUNSAT(\phi)$
5. $\exists n \in \mathbb{N}$ s.t. $RC(under^n(\phi), under^{n+1}(\phi))$ is false.



$\exists n \in \mathbb{N}$ s.t. $RC(\text{under}^n(\phi), \text{under}^{n+1}(\phi))$ is false.

RC function

- ▶ 'true' if we can do a recursive call, 'false' otherwise
- ▶ It compares $\text{under}^i(\phi)$ and $\text{under}^{i+1}(\phi)$
- ▶ It checks if $\text{under}^{i+1}(\phi)$ will be "easier to solve" than $\text{under}^i(\phi)$




```

graph TD
    Start([recar(φ)]) --> Init[ψ ← φ̂]
    Init --> Check{check(ψ)}
    Check -- sat --> SAT((SAT))
    Check -- unsat --> Eq{ψ ≡?_sat φ}
    Eq -- yes --> UNSAT((UNSAT))
    Eq -- unk. --> RC{RC(φ, φ̃)}
    RC -- yes --> RecarPhi[recar(φ̃)]
    RC -- no --> RecarPhi
    RecarPhi --> Refine[ψ ← refine(ψ)]
    Refine --> Check
  
```

RECAR

- ▶ 2 levels of abstractions
 - ▶ One at the Oracle level ($\text{check}(\psi)$)
 - ▶ One at the Domain level (recursive call)
- ▶ Efficient even when 50/50 chance of being SAT/UNSAT
- ▶ Everytime check improves, RECAR improves
- ▶ The return of the recursive call can reduce the number of refinement
- ▶ Totally generic, can change SAT solver \rightarrow FO solver?

RECAR for Modal Logic K

- ▶ Modal Logic K is **PSPACE**-complete [[Lad77](#), [Hal95](#)]
- ▶ What is Modal Logic K?
- ▶ How we over-approximate a formula ϕ ?
- ▶ How we under-approximate a formula ϕ ?
- ▶ Is it competitive against a CEGAR approach?
- ▶ Is it competitive against the state-of-the-art approaches?

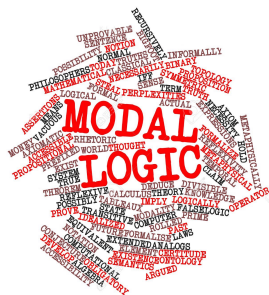
Modal Logic = Propositional Logic + \Box and \Diamond

Modal Logic

- ▶ $\Box\phi$ means ϕ is necessarily true
- ▶ $\Diamond\phi$ means ϕ is possibly true

$$\Diamond\phi \leftrightarrow \neg\Box\neg\phi$$

$$\Box\phi \leftrightarrow \neg\Diamond\neg\phi$$



- ▶ \mathbb{P} finite non-empty set of propositional variables

Kripke Structure [Kri59]

$M = \langle W, R, V \rangle$ with:

- ▶ W , a non-empty set of possible worlds
- ▶ R , a binary relation on W
- ▶ V , a function that associate to each $p \in \mathbb{P}$, the set of possible worlds where p is true

Pointed Kripke Structure: $\langle \mathcal{K}, w \rangle$

- ▶ \mathcal{K} : Kripke Structure
- ▶ w : a possible world in W

Definition (Satisfaction Relation)

The relation \models between Kripke Structures and formulae is recursively defined as follows:

$\langle \mathcal{K}, w \rangle \models p$	iff	$w \in V(p)$
$\langle \mathcal{K}, w \rangle \models \neg \phi$	iff	$\langle \mathcal{K}, w \rangle \not\models \phi$
$\langle \mathcal{K}, w \rangle \models \phi_1 \wedge \phi_2$	iff	$\langle \mathcal{K}, w \rangle \models \phi_1$ and $\langle \mathcal{K}, w \rangle \models \phi_2$
$\langle \mathcal{K}, w \rangle \models \phi_1 \vee \phi_2$	iff	$\langle \mathcal{K}, w \rangle \models \phi_1$ or $\langle \mathcal{K}, w \rangle \models \phi_2$
$\langle \mathcal{K}, w \rangle \models \Box \phi$	iff	$(w, w') \in R$ implies $\langle \mathcal{K}, w' \rangle \models \phi$
$\langle \mathcal{K}, w \rangle \models \Diamond \phi$	iff	$(w, w') \in R$ and $\langle \mathcal{K}, w' \rangle \models \phi$

\mathcal{K} that satisfied a formula ϕ will be called “Kripke model of ϕ ”

✓ $\phi_1 = \Box(\bullet)$

✗ $\phi_2 = \Box\Diamond(\circ)$

✓ $\phi_3 = \Diamond(\bullet \wedge \Diamond\neg\bullet)$

✓ $\phi_4 = (\bullet \vee \bullet \vee \circ)$

✗ $\phi_5 = \Diamond\Diamond(\circ \wedge \Box\neg\circ)$

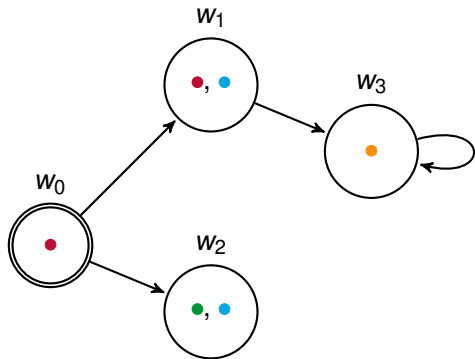


Figure: Example \mathcal{K}

MoSaiC

- ▶ Open-Source Modal Logic K solver
- ▶ Uses Glucose as internal SAT solver
- ▶ Uses a RECAR approach

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RECAR Assumptions: Reminder

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- ?2 $isSAT(\hat{\phi})$ implies $isSAT(refine(\hat{\phi}))$
- ?3 $\exists n \in \mathbb{N}$ s.t. $refine^n(\hat{\phi}) \equiv_{sat}^? \phi$
- 4 $isUNSAT(\check{\phi})$ implies $isUNSAT(\phi)$
- 5 $\exists n \in \mathbb{N}$ s.t. $RC(under^n(\phi), under^{n+1}(\phi))$ is false

ϕ always in NNF and $\text{over}(\phi, i)$ in CNF thanks to Tseitin

$$\text{over}(\phi, n) = \text{over}'(\phi, 0, n)$$

$$\text{over}'(p_k, i, n) = p_{k,i} \quad \text{over}'(\neg p_k, i, n) = \neg p_{k,i}$$

$$\text{over}'(\Box \phi, i, n) = \bigwedge_{j=0}^n (r_{i,j} \rightarrow \text{over}'(\phi, j, n))$$

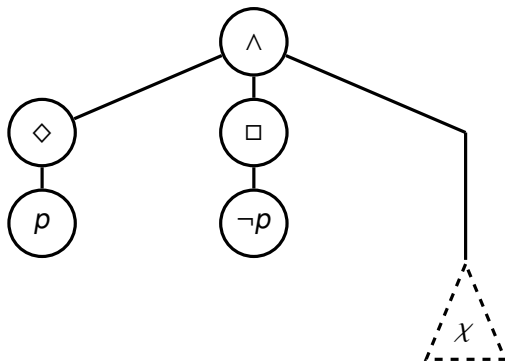
$$\text{over}'(\Diamond \phi, i, n) = \bigvee_{j=0}^n (r_{i,j} \wedge \text{over}'(\phi, j, n))$$

- ▶ $p_{k,i}$ means p_k is true in the world w_i
- ▶ $r_{i,j}$ means that there is a relation between worlds w_i and w_j

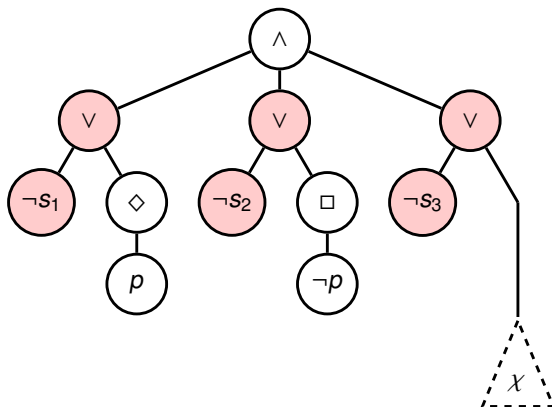
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Let's take an example, with χ huge but satisfiable...

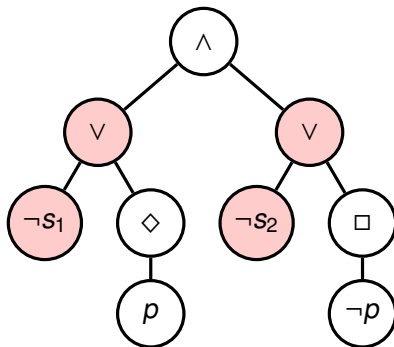


Worst case for CEGAR using our 'over' function



Modern SAT solvers returns 'the reason' why a formula with n worlds is unsatisfiable ($core = \{s_1, s_2\}$)

We want to cut what is not part of the 'unsatisfiability' ($s_i \notin \text{core}$)



We just create $\check{\phi}$ smaller than ϕ and easier to solve.
The function *RC* from RECAR just says here: did we cut something ?

$$\text{under}(p, \text{core}) = p$$

$$\text{under}(\neg p, \text{core}) = \neg p$$

$$\text{under}(\Box \phi, \text{core}) = \Box(\text{under}(\phi, \text{core}))$$

$$\text{under}(\Diamond \phi, \text{core}) = \Diamond(\text{under}(\phi, \text{core}))$$

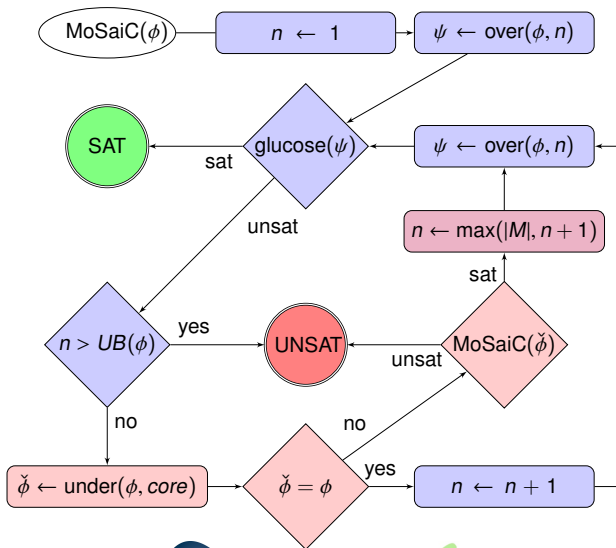
$$\text{under}((\phi \wedge \psi), \text{core}) = \text{under}(\phi, \text{core}) \wedge \text{under}(\psi, \text{core})$$

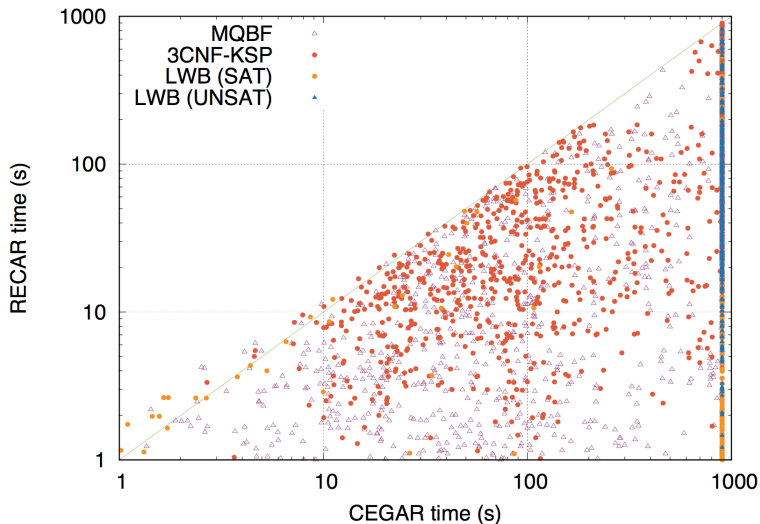
$$\text{under}((\psi \vee \chi), \text{core}) = \begin{cases} \text{under}(\chi, \text{core}) & \text{if } \psi = \neg s_i, s_i \in \text{core} \\ \top & \text{if } \psi = \neg s_i, s_i \notin \text{core} \\ (\text{under}(\psi, \text{core}) \\ \vee \text{under}(\chi, \text{core})) & \text{otherwise} \end{cases}$$

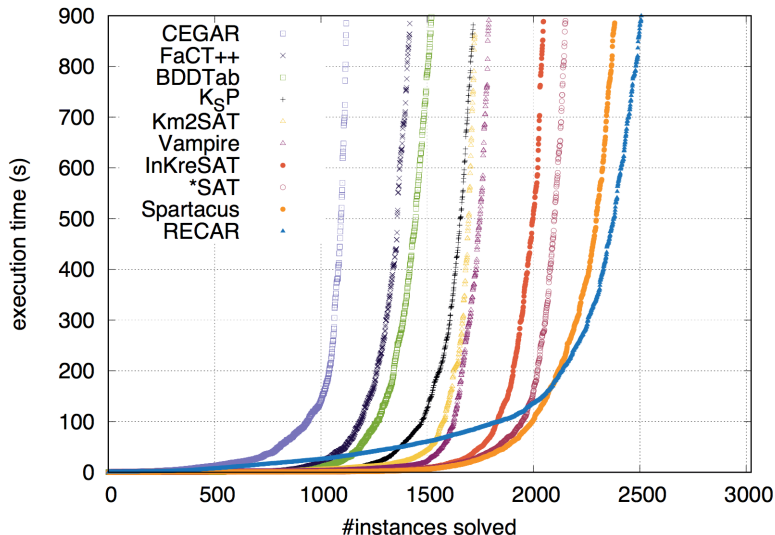
- Unsatisfiable-cores: To create our under-approximations

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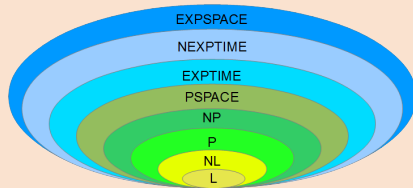






Abstractions according to complexity

- ▶ **PSPACE**: RECAR
- ▶ **NP**: CEGAR (over/under)



What is next ?

- ▶ RECAR for QBF (**PSPACE**)?
- ▶ RECAR for other modal logic?

Sum-up of complexities in modal logics

NP
K5
K45
KB45
KD5
KD45
KT5

PSPACE
K
KT
KT4
KB
KD4
KD
K4
KDB
KBT

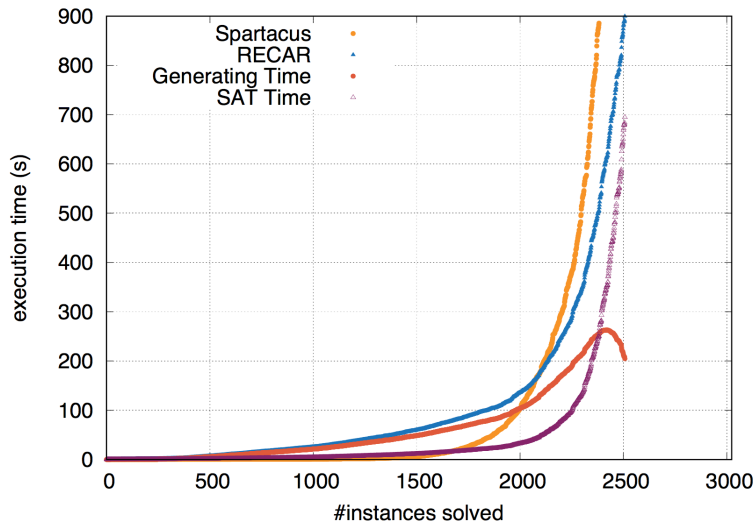
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