

## 7a laboratory work

### UART Read

#### 1. Aim

- Learn how to use UART read functions.
- Learn, how to write a code for packet parsing.

#### 2. Theory

To read bytes from UART, there are several methods.

First method is called as pulling. If you use this method – means you are always waiting on some data received from UART and cannot do something else.

```
/* USER CODE BEGIN PD */
#define UART_BUFFER_SIZE 2
/* USER CODE END PD */

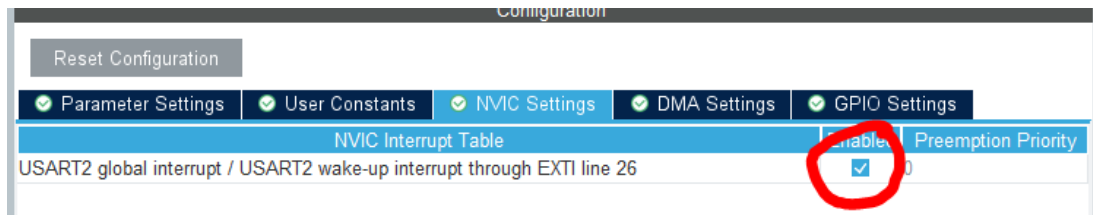
/* USER CODE BEGIN PM */
uint8_t dateBuffer[UART_BUFFER_SIZE];
/* USER CODE END PM */

/* USER CODE BEGIN WHILE */
while (1)
{
    HAL_UART_Receive(&huart2, dateBuffer, UART_BUFFER_SIZE, 1000);
    if ( dateBuffer[0] == 'R')
    {
        if (dateBuffer[1] == '1')
        {
            HAL_GPIO_WritePin(LED_GREEN_GPIO_Port, LED_GREEN_Pin, RESET);

        }
        if (dateBuffer[1] == '0')
        {
            HAL_GPIO_WritePin(LED_GREEN_GPIO_Port, LED_GREEN_Pin, SET);
        }
        dateBuffer[0] = 0;
        dateBuffer[1] = 0;
    }
    HAL_Delay(100);
}
/* USER CODE END WHILE */
```

More efficient method is to use interrupts.

First you need to enable interrupt generation from UART.



After generate the code you need to initiate RX interrupt in main.c

```
/* USER CODE BEGIN 2 */
HAL_UART_Receive_IT(&huart2, (uint8_t *)dateBuffer, UART_BUFFER_SIZE);
/* USER CODE END 2 */
```

Interrupt function which give you notification, that UART did receive UART\_BUFFER\_SIZE bytes is called **void HAL\_UART\_RxCpltCallback(UART\_HandleTypeDef \*huart)**.

```
/* USER CODE BEGIN 4 */
void HAL_UART_RxCpltCallback(UART_HandleTypeDef *huart)
{
    if (huart->Instance == USART2)
    {
        packetIsReady = 1;
        HAL_UART_Receive_IT(&huart2, (uint8_t *)dateBuffer, UART_BUFFER_SIZE);
    }
}
/* USER CODE END 4 */
```

In this function you are actually checking which UART did generate interrupt, setting packetIsReady flag for packet parser in main loop and running interrupt again.

Parser in main loop is working only if flag packetIsReady become 1 (True).

```
/* USER CODE BEGIN WHILE */
while (1)
{
    if (packetIsReady)
    {
        if (dateBuffer[0] == 'R')
        {
            if (dateBuffer[1] == '1')
            {
                HAL_GPIO_WritePin(LED_GREEN_GPIO_Port, LED_GREEN_Pin, RESET);
            }
            if (dateBuffer[1] == '0')
            {
                HAL_GPIO_WritePin(LED_GREEN_GPIO_Port, LED_GREEN_Pin, SET);
            }
            dateBuffer[0] = 0;
            dateBuffer[1] = 0;
        }
        packetIsReady = 0;
    }
}
/* USER CODE END WHILE */
```

### 3. Tasks

- a. Write code for read ASCII numbers from UART from "1" to "9" and blink an LED so many times.
- b. User 3 color LED's. Write a code to read commands - sequence of bytes: „R11“, „G21“, „B31“ and blinks dedicated LED's. If you will get „R10“, „G20“, „B30“ – the dedicated LED needs to stop blinking. Please use two interrupts for UART and the Time of the blinking period. For the parser, please use a **switch case**.

### 4. Report content

- 1) Title.
- 2) Main blocks of source code for tasks with comments.
- 3) Conclusions.

### 5. References

1. <https://deepbluembedded.com/how-to-receive-uart-serial-data-with-stm32-dma-interrupt-polling/>
2. <http://www.emcu.eu/how-to-manage-two-uart-usart2-and-usart1-under-interrupt/>
3. <https://www.programmingsought.com/article/4525115054/>