

Codebook

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1 Templates and Scripts

1.1 template.cpp

```
#include <bits/stdc++.h>
using namespace std;
```

```
// Template
// =====
// pbds
// #include <ext/pb_ds/assoc_container.hpp>
// #include <ext/pb_ds/tree_policy.hpp>
// using namespace __gnu_pbds;
// template<typename T, typename comp = less<T>>
// using ordered_set = tree<T, null_type, comp,
// rb_tree_tag, tree_order_statistics_node_update>;

// Debugging
#ifdef LOCAL
#include "debug.h"
#else
#define debug(...)
#define see(x)
#endif

typedef long long ll;
typedef vector<int> VI;
typedef vector<long long> VLL;
typedef vector<bool> VB;
typedef vector<vector<int>> VVI;
typedef pair<int, int> PI;
typedef pair<ll, ll> PLL;
typedef vector<pair<int, int>> VPI;

#define pb push_back
#define ff first
#define ss second
#define mp make_pair
#define all(a) a.begin(), a.end()
#define revall(a) a.rbegin(), a.rend()

#define loop(i, s, e) for (int i = s; i < e; ++i)
#define inp(v) for (auto& x : v) cin >> x
#define outp(v) for (int i = 0, n = v.size(); i < n; ++i) cout << v[i] << " \n"[i == n - 1]

#define nl "\n"
#define yep cout << "YES\n"
#define nope cout << "NO\n"

#define INF (int) 1e9
#define INFL (ll) 1e18
// #define MOD 998244353
#define MOD 1000000007
#define MAXN 300002
// =====

void solve()
{
}

int main()
{
    ios_base::sync_with_stdio(false);
```

```
cin.tie(NULL);

int t = 1;
cin >> t;
while(t--) solve();

#ifdef LOCAL
cerr << "Execution time: " << 1000.f * clock() /
CLOCKS_PER_SEC << " ms." << nl;
#endif

return 0;
}
```

1.2 debug.h

```
#include <iostream>
using namespace std;

#define see(x) cerr << #x << ": " << x << nl

template<typename... Args>
void debug(Args... args)
{
    ((cerr << " " << args), ...) << "\n";
}
```

1.3 sublime.build

```
{
    "shell_cmd": "g++ -Wall -std=c++20 -O2 -DLOCAL $file -o $file_base_name && ./ $file_base_name <input.in> output.out 2> error.log",
    "file_regex": "^(..[^:]*):([0-9]+)?(?:([0-9]+)?(?:\\.*)$)",
    "working_dir": "${file_path}",
    "selector": "source.c++, source.c, source.cpp",

    "variants":
    [
        {
            "name": "sanitize",
            "shell_cmd": "g++ -Wall -std=c++20 -fsanitize=address -fsanitize=undefined -DLOCAL $file -o $file_base_name && ./ $file_base_name <input.in> output.out 2> error.log"
        }
    ]
}
```

1.4 tasks.json (vs code)

```
{
  "version": "2.0.0",
  "tasks": [
    {
      "label": "cp",
      "type": "shell",
      "command": "",
      "args": [
        "g++",
        "-Wall",
        "-std=c++20",
        "-O2",
        "-DLOCAL",
        "\\${file}\\",
        "-o",
        "\\${fileDirname}/${fileBasenameNoExtension}
      ]\\",
      "&&",
      "\\${fileDirname}/${fileBasenameNoExtension}
    ]\\",
    "<",
    "input.in",
    ">",
    "output.out",
    "2>",
    "error.log"
  ],
  "group": "build",
  "presentation": {
    "reveal": "silent"
  },
  "problemMatcher": {
    "owner": "cpp",
    "fileLocation": ["relative", "${workspaceRoot}"],
    "pattern": {
      "regexp": "^(.*):(\\d+):(\\d+):\\s+(warning|error):\\s+(.*)$",
      "file": 1,
      "line": 2,
      "column": 3,
      "severity": 4,
      "message": 5
    }
  }
}
]
```

1.5 Interactive

```
socat EXEC:"./interactor" EXEC:"./soln"
```

2 Number Theory

2.1 Mod Template

```
ll mod(ll n)
{
    n %= MOD;
    return n < 0 ? MOD + n : n;
}

ll modpow(ll n, ll k)
{
    ll ret = 1;

    while (k)
    {
        if (k & 1) ret = (ret * n) % MOD;
        n = (n * n) % MOD;
        k >>= 1;
    }

    return ret;
}

inline ll inv(ll n)
{
    return modpow(n, MOD - 2);
}

inline ll mul(ll x, ll y)
{
    return ((x % MOD) * (y % MOD)) % MOD;
}

inline ll dvd(ll x, ll y)
{
    return mul(x, inv(y));
}
```

2.2 Binomial Coefficient

```
ll fact[MAXN];

void calc_fact()
{
    fact[0] = 1;
    for (int i = 1; i < MAXN; ++i)
    {
        fact[i] = (fact[i - 1] * i) % MOD;
    }
}

ll C(int n, int k)
```

```
{
    if (k > n) return 0;
    return (1LL * fact[n] *
        inv((1LL * fact[k] * fact[n - k]) % MOD)) % MOD;
}
```

2.3 Sieve

```
VI primes;
bool isprime[MAXN];

void sieve()
{
    isprime[1] = false;
    for (int i = 2; i < MAXN; ++i) isprime[i] = true;

    for (int i = 2; i < MAXN; ++i)
    {
        if (!isprime[i]) continue;
        primes.pb(i);

        if (1LL * i * i >= MAXN) continue;
        for (int j = i * i; j < MAXN; j += i)
            isprime[j] = false;
    }
}
```

2.4 CRT

```
int extended_gcd(ll a, ll b, ll& x, ll& y)
{
    if (!b)
    {
        x = 1, y = 0;
        return a;
    }

    ll g = extended_gcd(b, a % b, x, y);
    swap(x, y);
    y -= x * (a / b);
    return g;
}

ll modinv(ll a, ll m)
{
    ll x, y;
    extended_gcd(a, m, x, y);

    x %= m;
    return x < 0 ? x + m : x;
}

ll crt(vector<pair<ll, ll>>& mods)
```

```
{
    ll mod = 1;
    for (auto& p : mods) mod *= p.ss;

    ll ans = 0;
    for (auto [x, p] : mods)
    {
        ll m = mod / p;
        m = (m * modinv(m, p)) % mod;
        m = (m * x) % mod;

        ans = (ans + m) % mod;
    }

    return ans;
}
```

3 Data Structure

3.1 Fenwick Tree

```
struct fenwick
{
    int n;
    vector<ll> tree;

    fenwick(int s)
    {
        n = s;
        tree.assign(n + 1, 0);
    }

    ll get(int i)
    {
        ll res = 0;
        for(; i > 0; i -= i & -i) res += tree[i];
        return res;
    }

    void add(int i, int x)
    {
        for (; i <= n; i += i & -i) tree[i] += x;
    }

    ll rsq(int l, int r)
    {
        return get(r) - get(l - 1);
    }
};
```

3.2 Segment Tree

```
template<typename T>
struct segtree
```

```
{
    #define left(u) 2 * u + 1
    #define right(u) 2 * u + 2

    int n;
    T init_val;
    vector<T> tree;
    function<T (T, T)> f;

    bool is_lazy = false;
    T init_lazy;
    vector<T> lazy;
    function<void (T&, T, int, int)> apply_lazy;
    function<void (T&, T)> merge_lazy;

    segtree() {} // Dummy constructor for global declaration

    segtree(int sz, function<T (T, T)> f, T val = 0)
    {
        n = sz;
        this->f = f;
        init_val = val;

        tree.assign(1 << (ceil(log2(n - 1) + 2)), init_val);

        // apply(tree[u], lazy[u], l, r)
        // merge(lazy[left(u)], lazy[u])
        void make_lazy(function<void (T&, T, int, int)> apply,
            function<void (T&, T)> merge, T init = 0)
        {
            is_lazy = true;
            init_lazy = init;
            apply_lazy = apply;
            merge_lazy = merge;

            lazy.assign(tree.size(), init_lazy);
        }

        void build(vector<T>& a) { _build(0, 0, n - 1, a); }
        void update(int i, T x) { _update(0, 0, n - 1, i, x); }
        void update(int l, int r, T x) { _update_range(0, 0, n - 1, l, r, x); }
        T get(int l, int r) { return _get(0, 0, n - 1, l, r); }

        void _build(int u, int l, int r, vector<T>& a)
        {
            if (l == r)
            {
                tree[u] = a[l];
                return;
            }

            int mid = (l + r) / 2;
            _build(left(u), l, mid, a);
            _build(right(u), mid + 1, r, a);
            tree[u] = f(tree[left(u)], tree[right(u)]);
        }
    }
```

```
}

void _update(int u, int l, int r, int i, T x)
{
    if (l == r)
    {
        tree[u] = x;
        return;
    }

    int mid = (l + r) / 2;
    if (i <= mid) _update(left(u), l, mid, i, x);
    else _update(right(u), mid + 1, r, i, x);
    tree[u] = f(tree[left(u)], tree[right(u)]);
}

void propagate(int u, int l, int r)
{
    if (lazy[u] == init_lazy || l == r) return;

    int m = (l + r) / 2;
    apply_lazy(tree[left(u)], lazy[u], l, m);
    merge_lazy(lazy[left(u)], lazy[u]);
    apply_lazy(tree[right(u)], lazy[u], m + 1, r);
    merge_lazy(lazy[right(u)], lazy[u]);

    lazy[u] = init_lazy;
}

void _update_range(int u, int tl, int tr, int l, int r,
    T x)
{
    if (l > tr || r < tl) return;
    if (tl >= l && tr <= r)
    {
        apply_lazy(tree[u], x, tl, tr);
        merge_lazy(lazy[u], x);
        return;
    }

    propagate(u, tl, tr);

    int mid = (tl + tr) / 2;
    _update_range(left(u), tl, mid, l, r, x);
    _update_range(right(u), mid + 1, tr, l, r, x);

    tree[u] = f(tree[left(u)], tree[right(u)]);
}

T _get(int u, int tl, int tr, int l, int r)
{
    if (l > tr || r < tl) return init_val;

    if (l <= tl && r >= tr) return tree[u];

    if (is_lazy) propagate(u, tl, tr);
```

```

        int mid = (tl + tr) / 2;
        return f(_get(left(u), tl, mid, l, r),
                _get(right(u), mid + 1, tr, l, r));
    }

    #undef left
    #undef right
};

```

3.3 DSU

```

struct dsu
{
    vector<int> parent, size;

    dsu(int n)
    {
        parent.resize(n + 1);
        size.resize(n + 1);

        for (int i = 1; i <= n; ++i)
        {
            parent[i] = i;
            size[i] = 1;
        }
    }

    int find(int u)
    {
        if (parent[u] == u) return u;
        return parent[u] = find(parent[u]);
    }

    void merge(int u, int v)
    {
        u = find(u);
        v = find(v);

        if (u != v)
        {
            if (size[u] < size[v]) swap(u, v);
            parent[v] = u;
            size[u] += size[v];
        }
    }
};

```

4 Graph

4.1 Dijkstra

```

struct Node
{
    int u;

```

```

    ll dist;

    bool operator< (const Node& v) const
    {
        return dist > v.dist;
    }
};

void dijkstra(int start, vector<ll>& dis, vector<VPI>& adj)
{
    priority_queue<Node> q;
    dis[start] = 0;
    q.push({start, 0});

    while (!q.empty())
    {
        Node node = q.top();
        int u = node.u;
        q.pop();

        if (dis[u] < node.dist) continue;

        for (auto e : adj[u])
        {
            if (node.dist + e.ss < dis[e.ff])
            {
                dis[e.ff] = node.dist + e.ss;
                q.push({e.ff, dis[e.ff]});
            }
        }
    }
}

```

4.2 LCA

```

struct LCA
{
    int step = 0;
    VI vis_start, vis_end;
    VVI st;

    int k;
    VVI& tree;

    LCA(VVI& tree) : tree(tree)
    {
        init(tree.size() - 1);
    }

    void build_st(int u, int p)
    {
        st[u][0] = p;
        for (int i = 1; i <= k; ++i)
            st[u][i] = st[st[u][i - 1]][i - 1];
    }
}

```

```

void dfs(int u, int p)
{
    vis_start[u] = step++;
    build_st(u, p);

    for (auto v : tree[u])
    {
        if (v != p) dfs(v, u);
    }

    vis_end[u] = step++;
}

bool is_ancestor(int a, int b)
{
    return vis_start[a] < vis_start[b] && vis_end[a] >
        vis_end[b];
}

int get(int a, int b)
{
    if (a == b) return a;
    if (is_ancestor(a, b)) return a;
    if (is_ancestor(b, a)) return b;

    for (int i = k; i >= 0; --i)
    {
        if (!is_ancestor(st[a][i], b)) a = st[a][i];
    }

    return st[a][0];
}

void init(int n)
{
    vis_start.assign(n + 1, 0);
    vis_end.assign(n + 1, 0);

    k = __lg(2 * n - 1);
    st.assign(n + 1, VI(k + 1));
    dfs(1, 1);
}

// Extra
int get_ancestor(int u, int n)
{
    for (int i = 0; n > 0; ++i)
    {
        if (n & (1 << i))
        {
            u = st[u][i];
            n -= (1 << i);
        }
    }

    return u;
}

```

```
};
```

4.3 SCC

```
VVI scc;
VI stk;
int disc[MAXN], low[MAXN];
bool instk[MAXN];
int cur_time;

void dfs_scc(int u, VVI& g)
{
    disc[u] = low[u] = ++cur_time;
    instk[u] = true;
    stk.pb(u);

    for (int v : g[u])
    {
        if (!disc[v])
        {
            dfs_scc(v, g);
            low[u] = min(low[u], low[v]);
        }
        else if (instk[v])
            low[u] = min(low[u], disc[v]);
    }

    if (low[u] < disc[u]) return;

    scc.pb(VI());
    bool rem = true;
    while (rem)
    {
        int v = stk.back();
        stk.pop_back();
        instk[v] = false;
        scc.back().pb(v);
        rem = v != u;
    }
}

void tarjan(VVI& g)
{
    cur_time = 0;
    int n = g.size();

    for (int i = 0; i < n; ++i) disc[i] = 0;
    for (int u = 1; u < n; ++u) if (!disc[u]) dfs_scc(u, g);
}
```

4.4 HLD

```
VI heavy, chain, label, par, sz, dep;
int timer;

void dfsz(int u, int p, VVI& tree)
{
    sz[u] = 1;
    par[u] = p;
    dep[u] = dep[p] + 1;

    int mx = -1;
    for (int v : tree[u])
    {
        if (v == p) continue;

        dfsz(v, u, tree);
        sz[u] += sz[v];
        if (sz[v] > mx) mx = sz[v], heavy[u] = v;
    }
}

void dfshld(int u, int p, VVI& tree, int head)
{
    label[u] = timer++;
    chain[u] = head;

    if (heavy[u] != -1) dfshld(heavy[u], u, tree, head);

    for (int v : tree[u])
    {
        if (v == p || v == heavy[u]) continue;

        dfshld(v, u, tree, v);
    }
}

void inithld(int n, VVI& tree)
{
    heavy = VI(n + 1, -1);
    chain = VI(n + 1);
    label = VI(n + 1);
    sz = VI(n + 1);
    par = VI(n + 1);
    dep = VI(n + 1);

    timer = 1;
    dfsz(1, 0, tree);
    dfshld(1, 0, tree, 1);
}

int qryup(int u, int v)
{
    if (dep[u] < dep[v]) swap(u, v);

    int head = chain[u];
    int ret = 0; // init value
    while (dep[head] > dep[v])
```

```
{
    // ret = ... (label[head], label[u]);
    u = par[head];
    head = chain[u];
}

// ret = ... (label[v], label[u]);
return ret;
}
```

4.5 Centroid Decomposition

```
struct CD
{
    vector<set<int>> tree;
    vector<int> par, sz;

    CD(vector<vector<int>>& tree)
    {
        for (auto& v : tree)
        {
            this->tree.emplace_back(v.begin(), v.end());
        }

        par.resize(tree.size());
        sz.resize(tree.size());
        build(1, 0);
    }

    void build(int u, int p)
    {
        dfs(u, p);
        int centroid = dfs(u, p, sz[u]);
        par[centroid] = p;

        vector<int> adj(tree[centroid].begin(), tree[centroid].end());
        for (int v : adj)
        {
            tree[v].erase(centroid);
            tree[centroid].erase(v);

            build(v, centroid);
        }
    }

    void dfs(int u, int p)
    {
        sz[u] = 1;

        for (int v : tree[u])
        {
            if (v == p) continue;

            dfs(v, u);
            sz[u] += sz[v];
        }
    }
}
```

```

    }
}

int dfs(int u, int p, int n)
{
    for (int v : tree[u])
    {
        if (v == p) continue;

        if (sz[v] > n / 2) return dfs(v, u, n);
    }

    return u;
}

int operator[](int i)
{
    return par[i];
}
};

```

5 String

5.1 Trie

```

struct trienode
{
    bool endmark;
    vector<int> child;

    trienode(int sz)
    {
        endmark = false;
        child.resize(sz, 0);
    }
};

struct trie
{
    int sz;
    char fst;
    vector<trienode> nodes;

    trie(int alpha_sz, char alpha_start)
    {
        sz = alpha_sz;
        fst = alpha_start;

        // root at idx 0
        nodes.pb(trienode(sz));
    }

    void insert(string& s)
    {
        int cur = 0;

```

```

        for (char c : s)
        {
            if (!nodes[cur].child[c - fst])
            {
                nodes[cur].child[c - fst] = nodes.size();
                nodes.pb(trienode(sz));
            }

            cur = nodes[cur].child[c - fst];
        }

        nodes[cur].endmark = true;
    }

    bool search(string& s)
    {
        int cur = 0;
        for (char c : s)
        {
            if (!nodes[cur].child[c - fst])
                return false;

            cur = nodes[cur].child[c - fst];
        }

        return nodes[cur].endmark;
    }

    bool erase(string& s)
    {
        int cur = 0;
        for (char c : s)
        {
            if (!nodes[cur].child[c - fst])
                return false;

            cur = nodes[cur].child[c - fst];
        }

        if (!nodes[cur].endmark) return false;

        nodes[cur].endmark = false;
        return true;
    }
};

```

5.2 Z Algorithm

```

VI z(string s)
{
    int n = s.size();
    VI z(n);

    int l = 0, r = 0;
    for (int i = 0; i < n; ++i)
    {

```

```

        if (i <= r) z[i] = min(z[i - l], r - i + 1);

        while (i + z[i] < n && s[z[i]] == s[i + z[i]])
            l = i, r = i + z[i]++;
    }

    return z;
}

```

6 Geometry

6.1 Vector3d

```

#define EPS 1e-12
#define pi
3.141592653589793115997963468544185161590576171875L

bool feq(long double a, long double b)
{
    long double del = fabs1(a - b);
    if (del <= EPS) return true;

    return del <= EPS * max({1.0L, fabs1(a), fabs1(b)});
}

struct vector3d
{
    long double x, y, z;

    bool operator==(const vector3d p)
    {
        return feq(x, p.x) && feq(y, p.y) && feq(z, p.z);
    }

    vector3d operator+(const vector3d p)
    {
        return {x + p.x, y + p.y, z + p.z};
    }

    vector3d operator-(const vector3d p)
    {
        return {x - p.x, y - p.y, z - p.z};
    }

    vector3d operator*(long double scalar)
    {
        return {x * scalar, y * scalar, z * scalar};
    }

    vector3d operator/(long double scalar)
    {
        return {x / scalar, y / scalar, z / scalar};
    }

    long double magnitude()

```

```

{
    return sqrtl(x * x + y * y + z * z);
}

vector3d unit()
{
    long double m = magnitude();
    if (feq(m, 0)) return {0, 0, 0};
    return *this / m;
}
};

long double dist(vector3d& p1, vector3d& p2)
{
    vector3d p = p1 - p2;
    return p.magnitude();
}

long double dot(vector3d& v1, vector3d& v2)
{
    return v1.x * v2.x + v1.y * v2.y + v1.z * v2.z;
}

long double angle(vector3d& v1, vector3d& v2)
{
    long double v = dot(v1, v2) / (v1.magnitude() * v2.
    magnitude());
    return acosl(min(1.0L, max(-1.0L, v)));
}

vector3d cross(const vector3d& a, const vector3d& b)
{
    return {
        a.y * b.z - a.z * b.y,
        a.z * b.x - a.x * b.z,
        a.x * b.y - a.y * b.x
    };
}

```

7 Miscellaneous

7.1 Generationg Permutations

```

VI a;
//...

sort(all(a));
do
{
    // Process permutation...
} while (next_permutation(all(a)));

```

7.2 Iterating over Submasks

```

int n = 17;

for (int mask = 0; mask < (1 << n); ++mask)
{
    for (int sub = mask; sub; sub = (sub - 1) & mask)
    {
        // Process submask...
    }
}

```

7.3 pbds

```

// ordered set
ordered_set<int> st;
// ordered multiset
ordered_set<int, less_equal<int>> multi;

// insert element
st.insert(x);
// get index
st.order_of_key(x);
// access by index
st.find_by_order(idx);

```
