

COMP 250

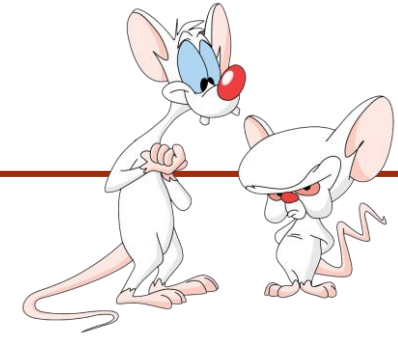
INTRODUCTION TO COMPUTER SCIENCE

34 - Graphs

Giulia Alberini, Fall 2022

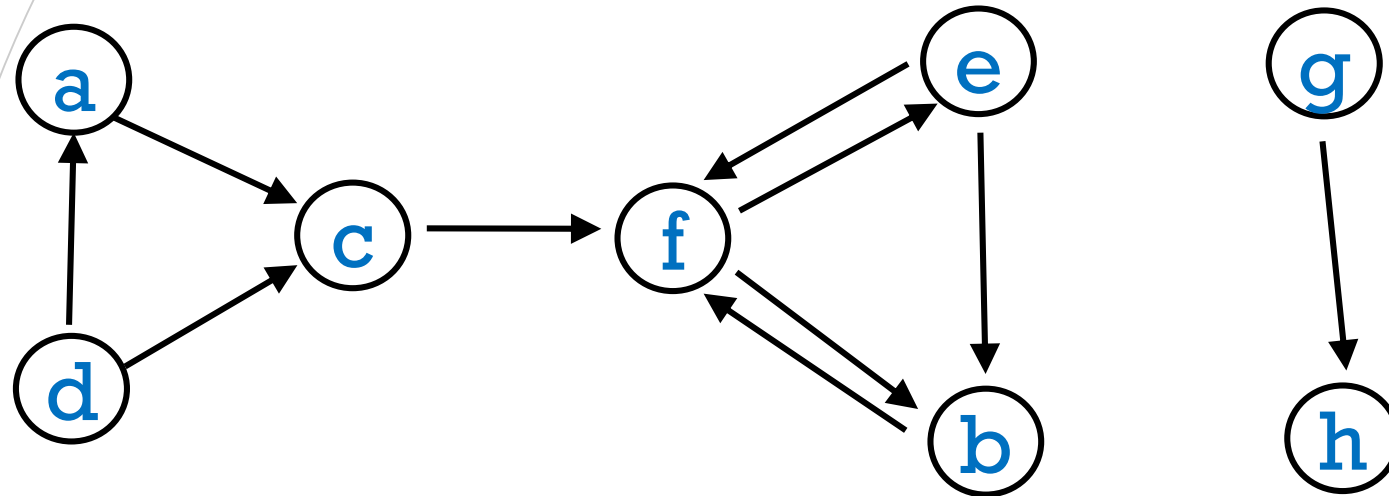
Slides adapted from Michael Langer's

WHAT ARE WE GOING TO DO TODAY?

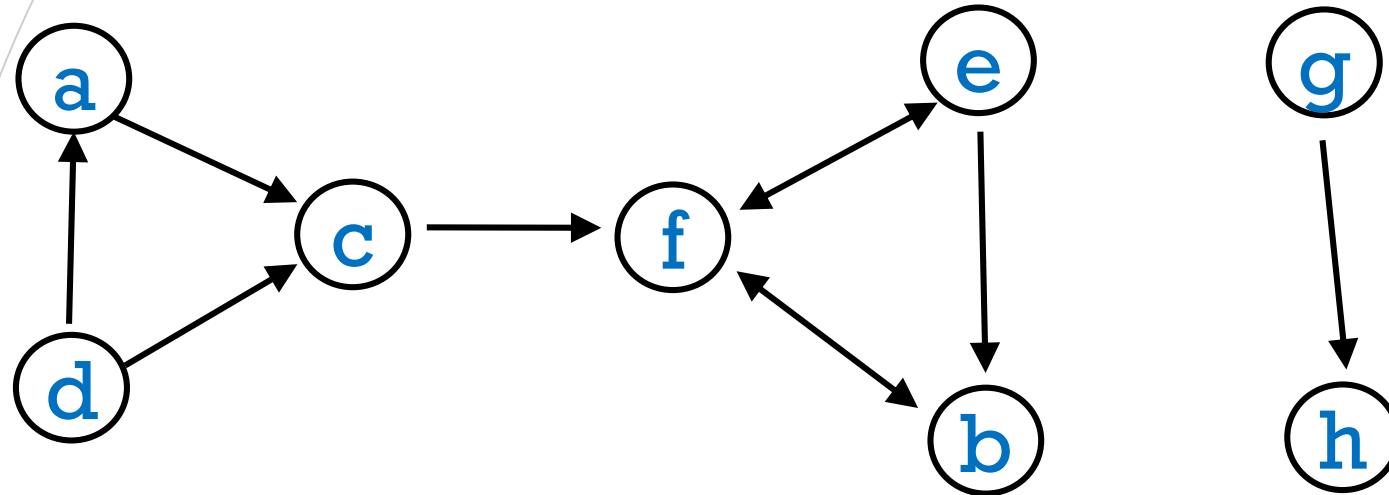


- **Graphs**
 - Definitions
- **Recursive graph traversal**
 - depth first

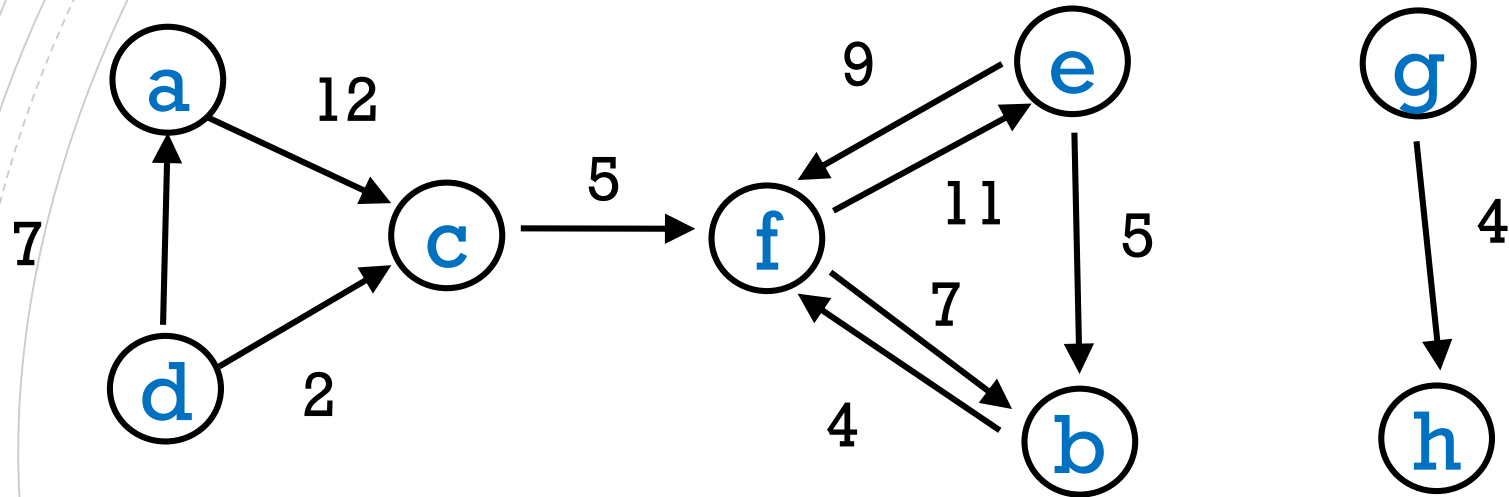
EXAMPLE



SAME EXAMPLE – DIFFERENT NOTATION



WEIGHTED GRAPH



DEFINITION

A *directed graph* is a set of vertices

$$V = \{v_i : i \in \{1, \dots, n\}\}$$

and set of ordered pairs of these vertices called *edges*.

$$E = \{(v_i, v_j) : i, j \in \{1, \dots, n\}\}$$

In an *undirected* graph, the edges are *unordered* pairs.

$$E = \{\{v_i, v_j\} : i, j \in \{1, \dots, n\}\}$$

EXAMPLES

Vertices

airports

web pages

Java objects

Edges

EXAMPLES

Vertices

airports

web pages

Java objects

Edges

flights

EXAMPLES

Vertices

airports

web pages

Java objects

Edges

flights

links (URLs)

EXAMPLES

Vertices

airports

web pages

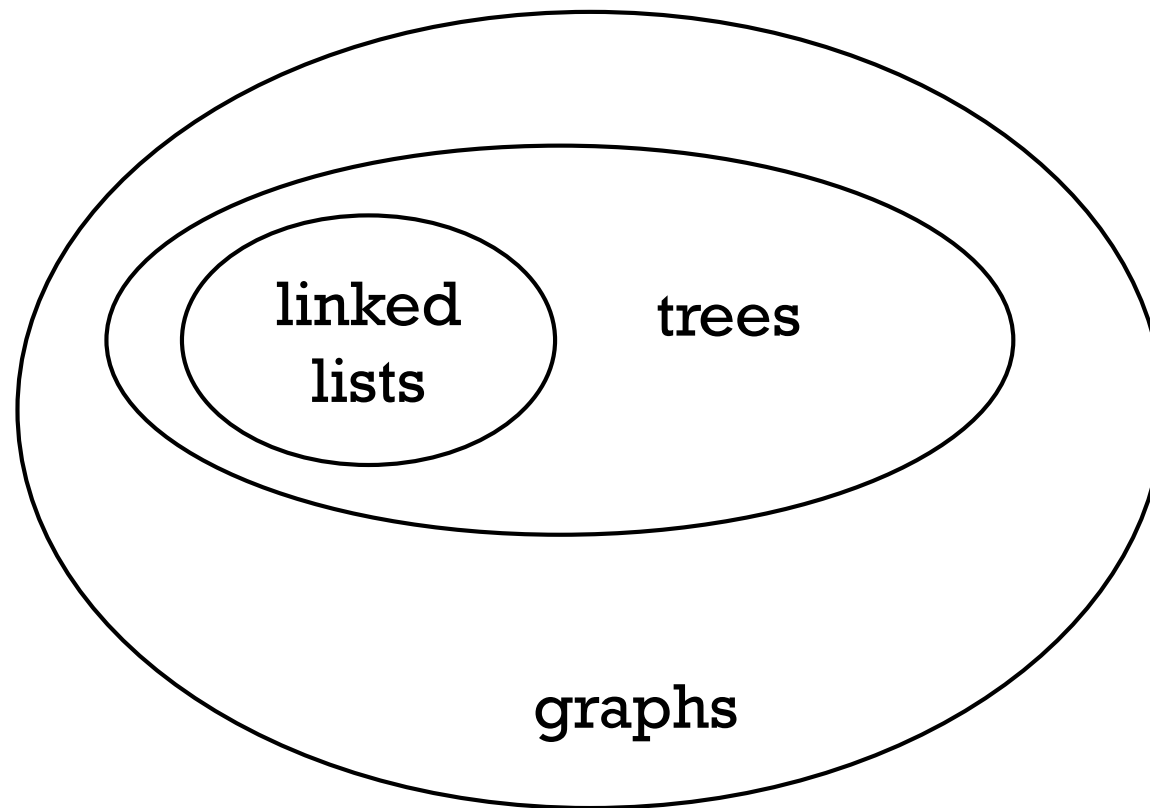
Java objects

Edges

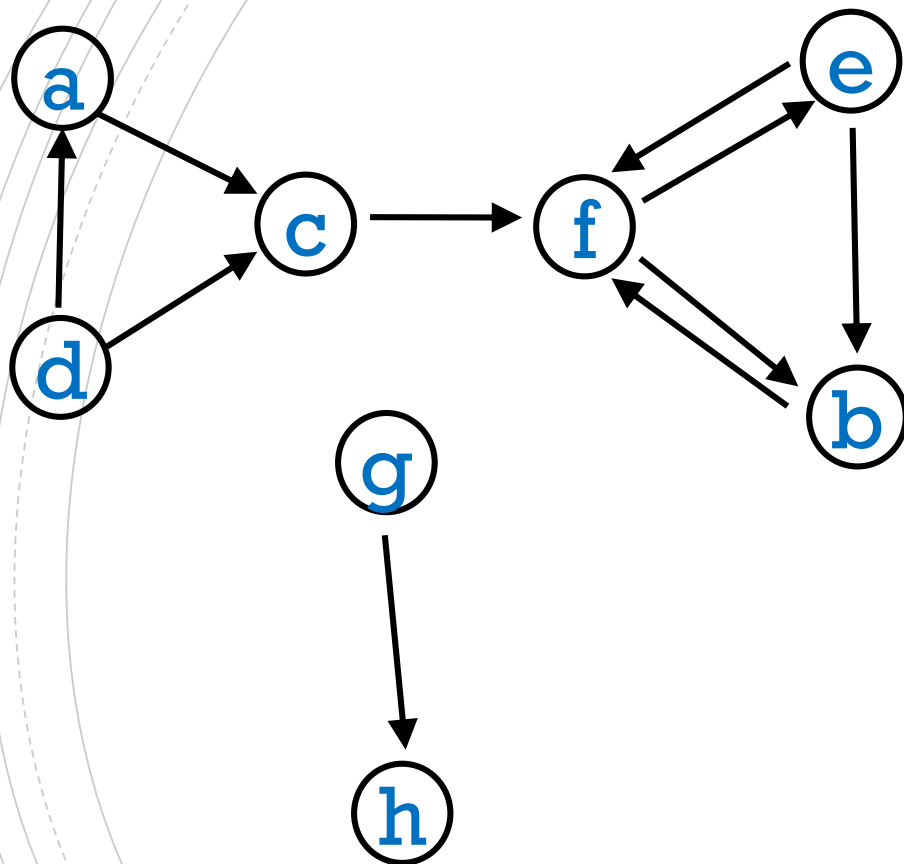
flights

links (URLs)

references



TERMINOLOGY: "IN DEGREE"

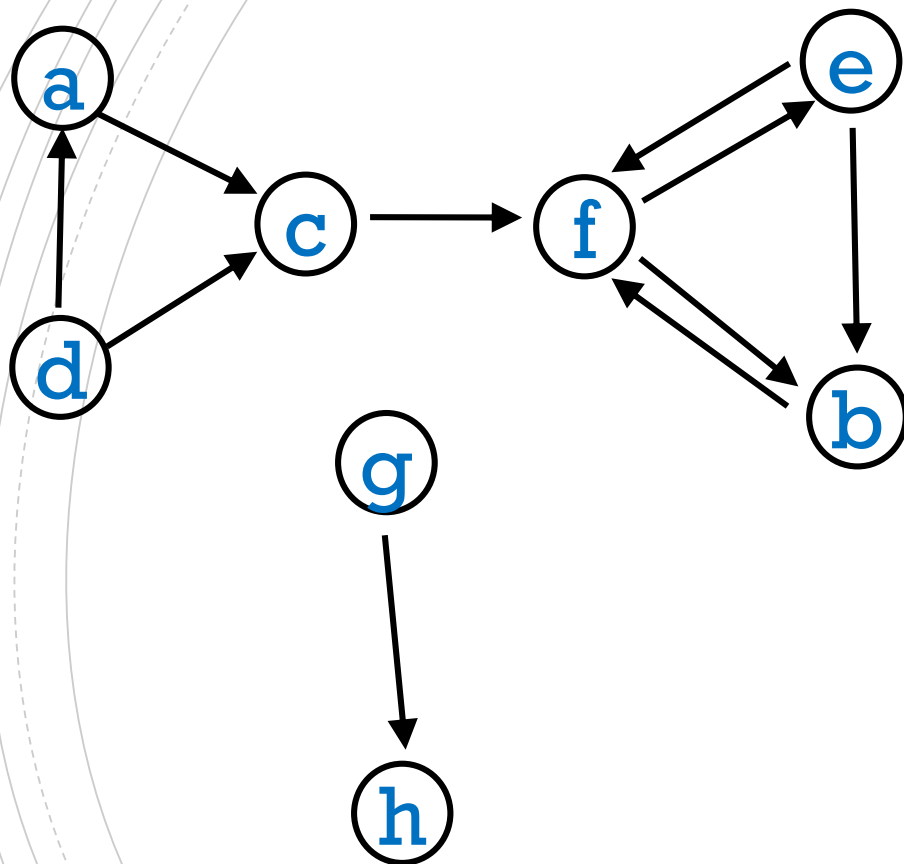


v
a
b
c
d
e
f
g
h

in degree

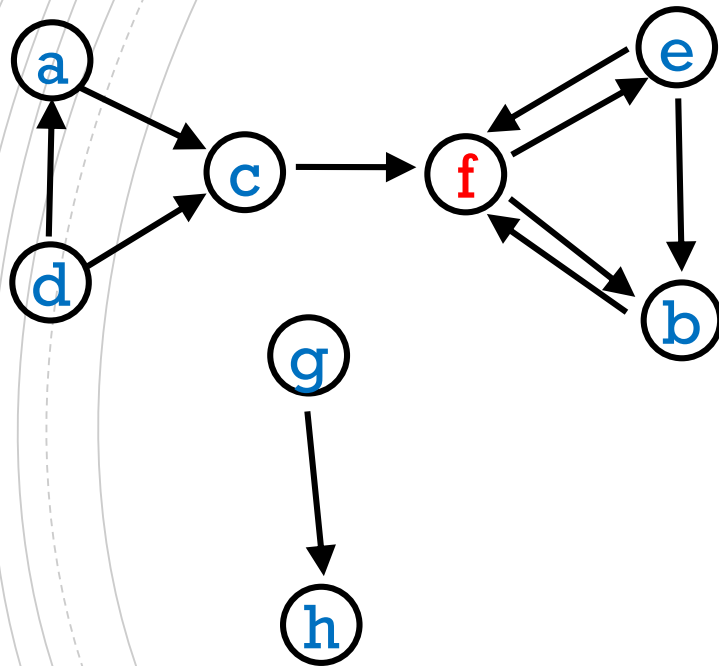
1
2
2
0
1
3
0
1

TERMINOLOGY: "OUT DEGREE"



<u>v</u>	<u>out degree</u>
a	1
b	1
c	1
d	2
e	2
f	2
g	1
h	0

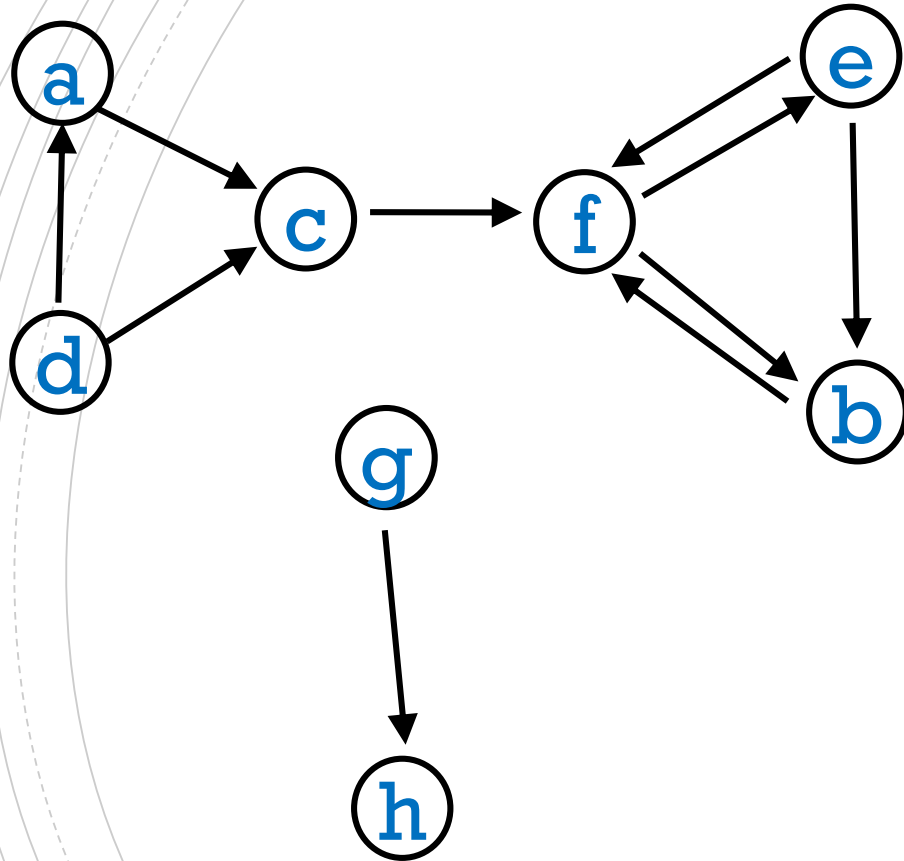
EXAMPLE: WEB PAGES



In degree: How many web pages link to some web page (e.g. **f**) ?

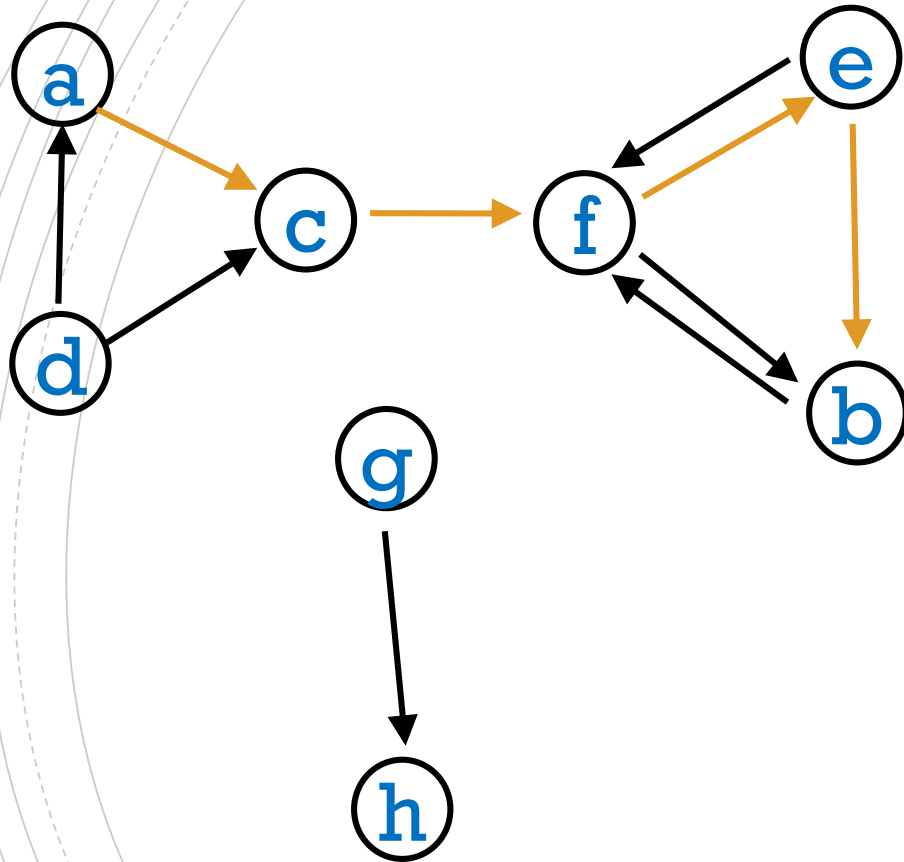
Out degree: How many web pages does some web page (e.g. **f**) link to ?

TERMINOLOGY: PATH



A *path* is a sequence of edges such that the end vertex of one edge is the start vertex of the next edge and no vertex is repeated except maybe first and last.

TERMINOLOGY: PATH

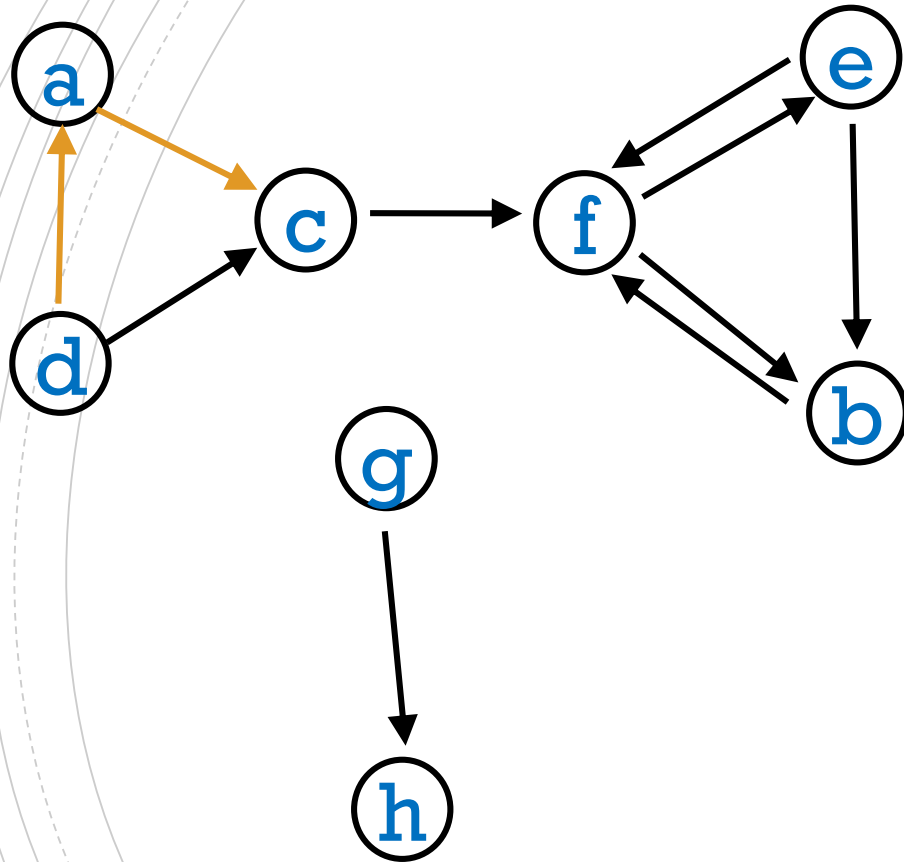


A *path* is a sequence of edges such that the end vertex of one edge is the start vertex of the next edge and no vertex is repeated except maybe first and last.

Examples

- acfeb

TERMINOLOGY: PATH

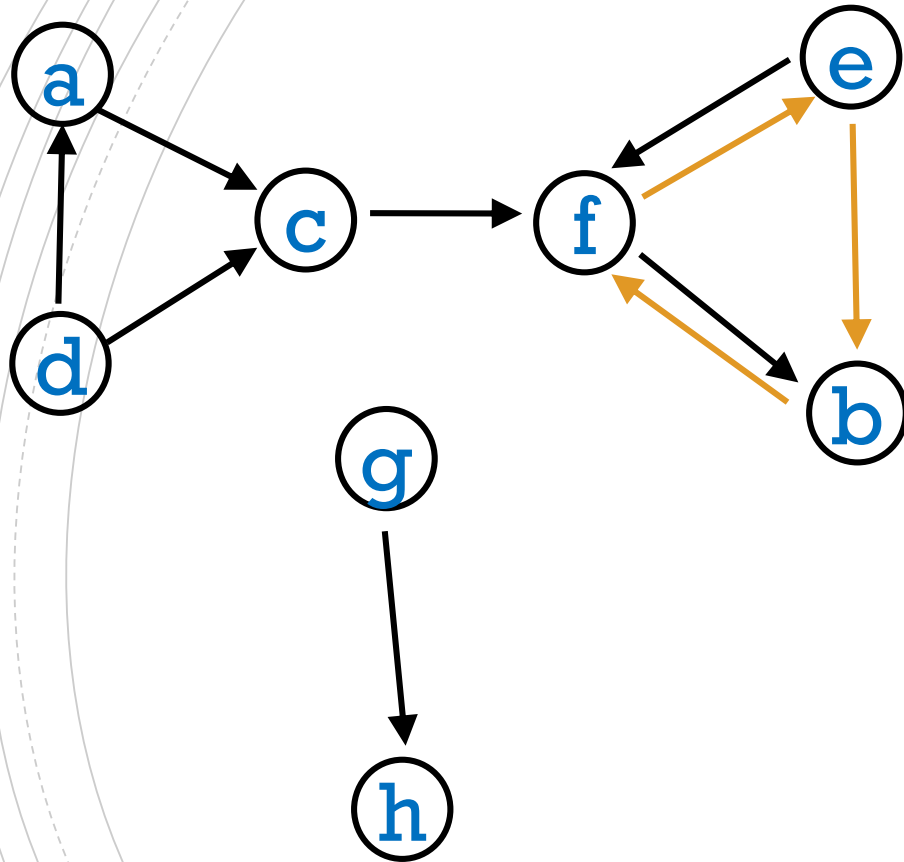


A *path* is a sequence of edges such that the end vertex of one edge is the start vertex of the next edge and no vertex is repeated except maybe first and last.

Examples

- acfeb
- dac

TERMINOLOGY: PATH



A *path* is a sequence of edges such that the end vertex of one edge is the start vertex of the next edge and no vertex is repeated except maybe first and last.

Examples

- acfeb
- dac
- febf
-

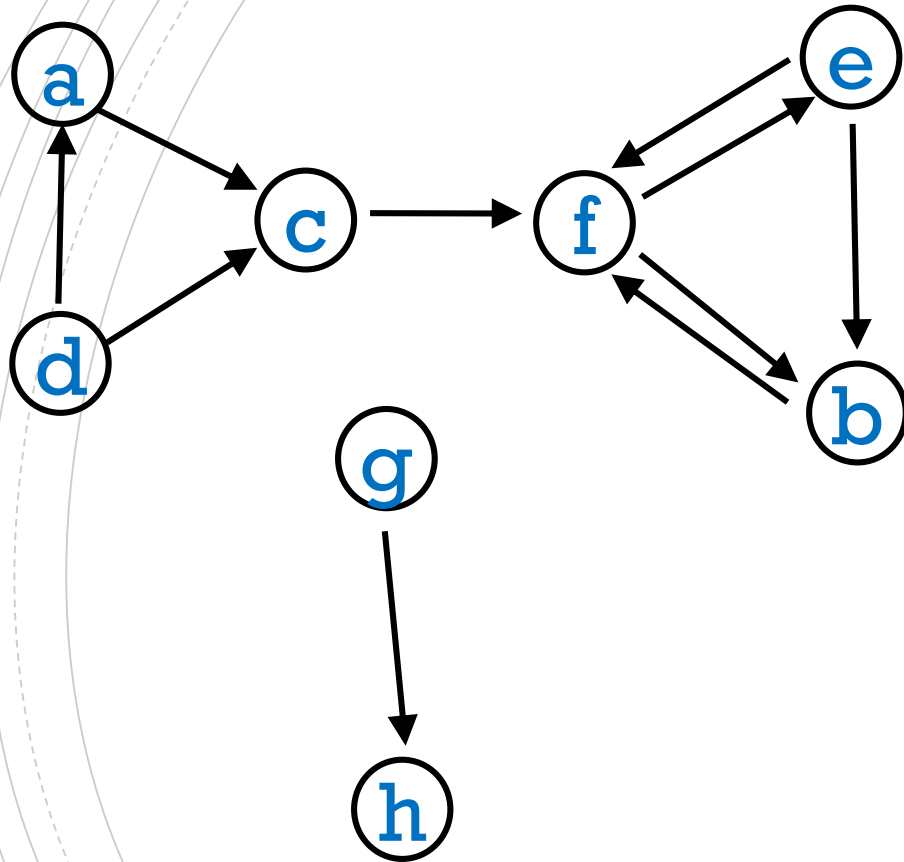
GRAPH ALGORITHMS IN COMP 251 (DIJKSTRA'S ALGORITHM)

Given a graph, what is the shortest (weighted) path between two vertices?

The screenshot displays the Google Maps interface for a walking route. The origin is 'McGill University, Sherbrooke Street West, Montreal' and the destination is 'The White House, Pennsylvania Avenue North, Washington, D.C.'. The map shows a blue line representing the suggested route across North America, passing through cities like Toronto, Detroit, Cleveland, and New York. The left sidebar contains the following information:

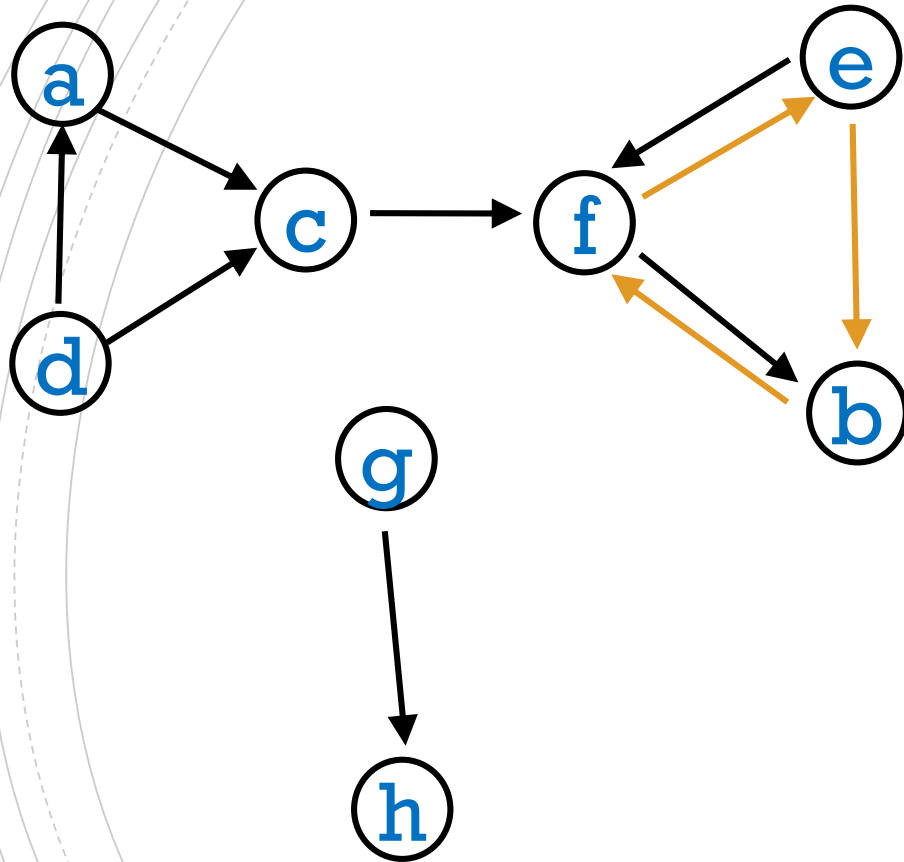
- Get directions** | **My places**
- Icons for car, bus, walking, and cycling.
- Origin: McGill University, Sherbrooke Street West, Montreal
- Destination: The White House, Pennsylvania Avenue North
- [Add Destination - Show options](#)
- GET DIRECTIONS**
- Walking directions are in beta.**
Use caution - This route may be missing sidewalks or pedestrian paths.
- Suggested routes**
- | | |
|----------|-------------------|
| U.S. 9 S | 914 km, 188 hours |
| US-11 S | 945 km, 194 hours |
- Or take **Public Transit** (4 transfers) 16 hours 1 min
- Walking directions to The White House** [3D](#)

TERMINOLOGY: CYCLE



A *cycle* is a path such that the last vertex is the same as the first vertex.

TERMINOLOGY: CYCLE

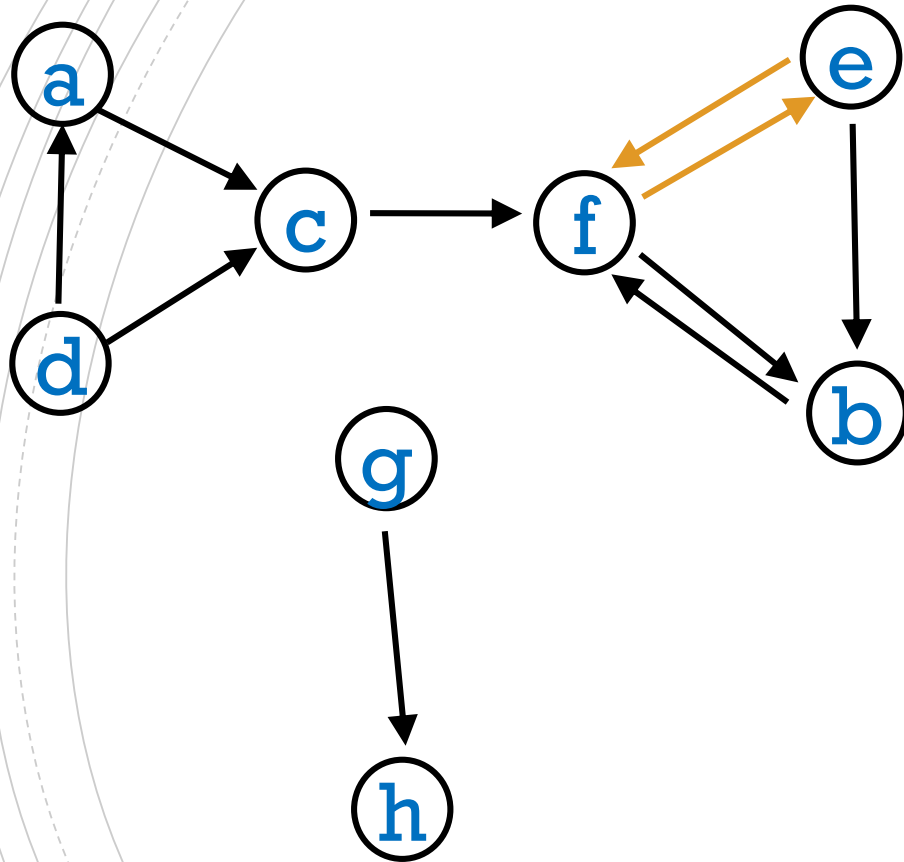


A *cycle* is a path such that the last vertex is the same as the first vertex.

Examples

- febf

TERMINOLOGY: CYCLE

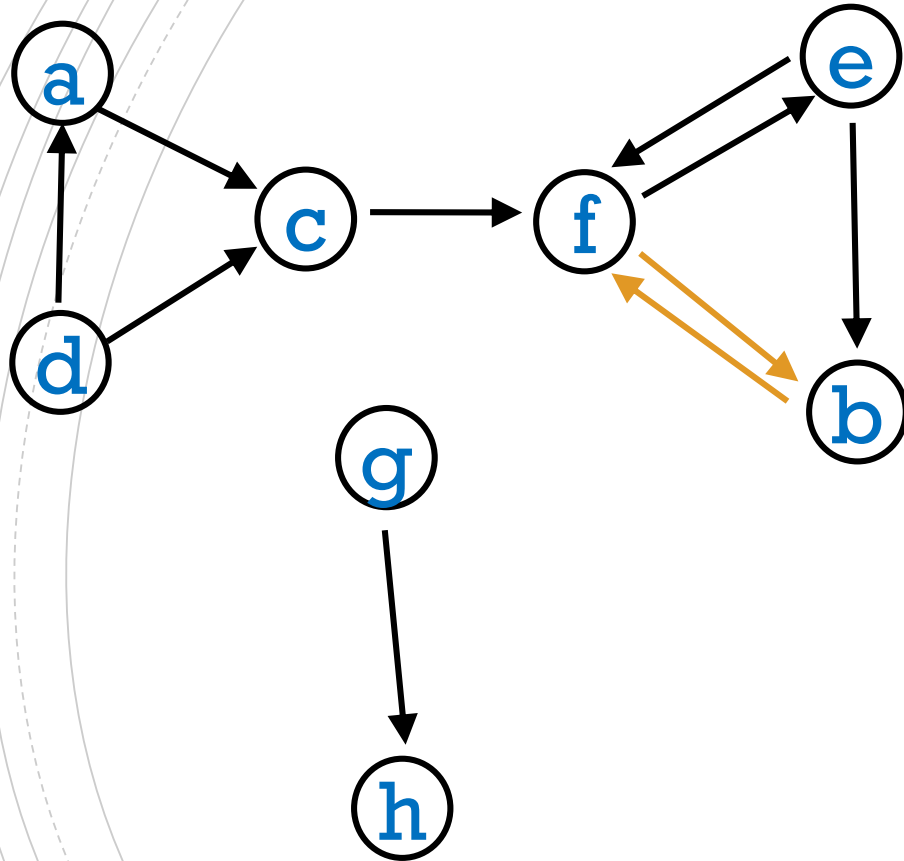


A *cycle* is a path such that the last vertex is the same as the first vertex.

Examples

- febf
- efe

TERMINOLOGY: CYCLE

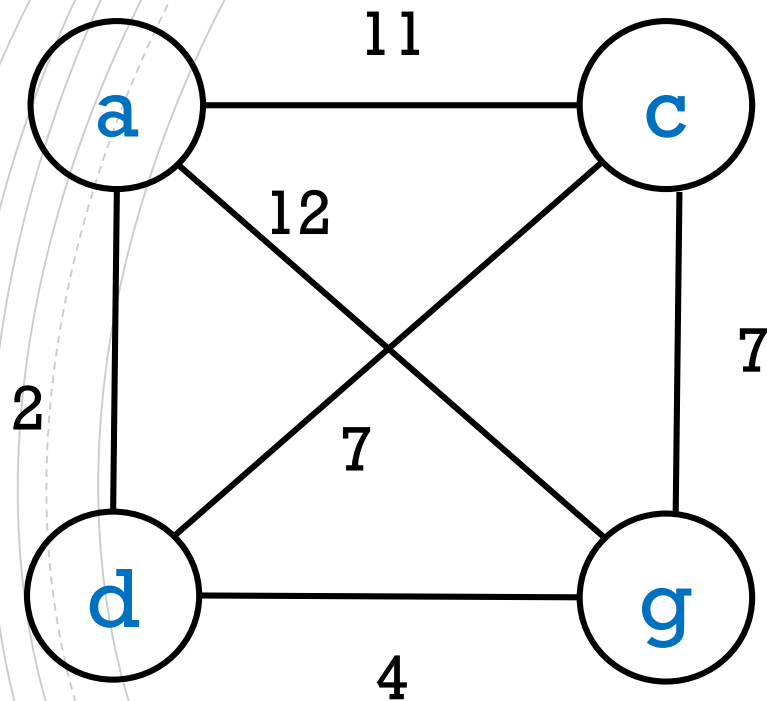


A *cycle* is a path such that the last vertex is the same as the first vertex.

Examples

- febf
- efe
- fbf
- ...

"TRAVELLING SALESMAN" COMP 360 - (HAMILTONIAN CIRCUIT)

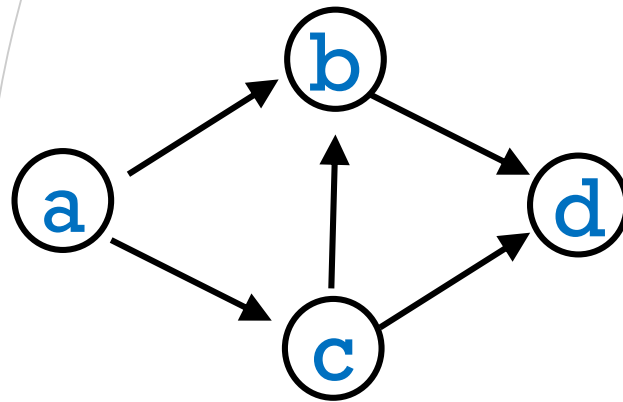


Find the shortest cycle that visits all vertices once.

How many potential cycles are there in a graph of n vertices ?

DIRECTED ACYCLIC GRAPH

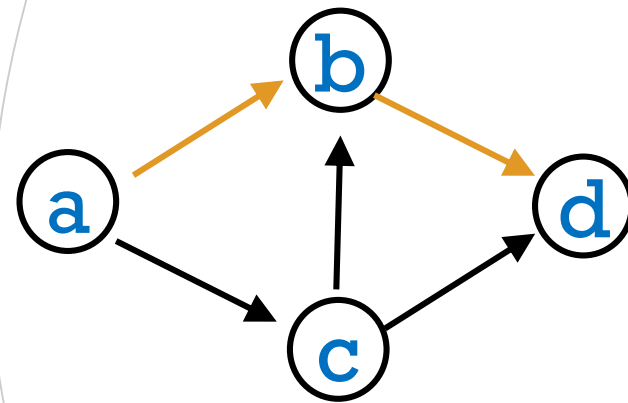
no cycles



Used to capture dependencies.

There are three paths from **a** to **d**.

DIRECTED ACYCLIC GRAPH

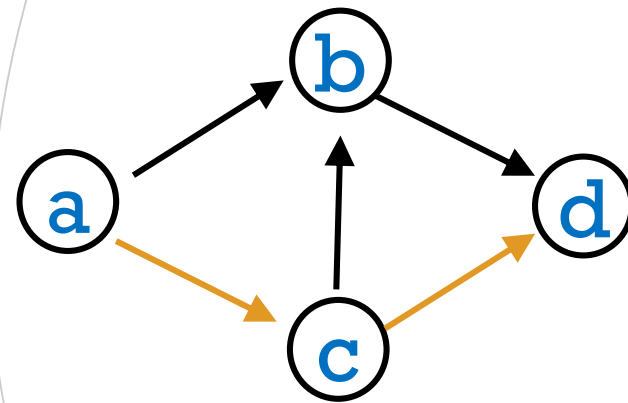


no cycles

Used to capture dependencies.

There are three paths from **a** to **d**.

DIRECTED ACYCLIC GRAPH

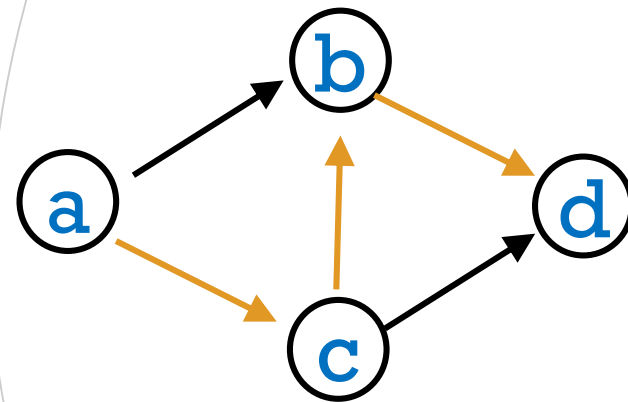


no cycles

Used to capture dependencies.

There are three paths from **a** to **d**.

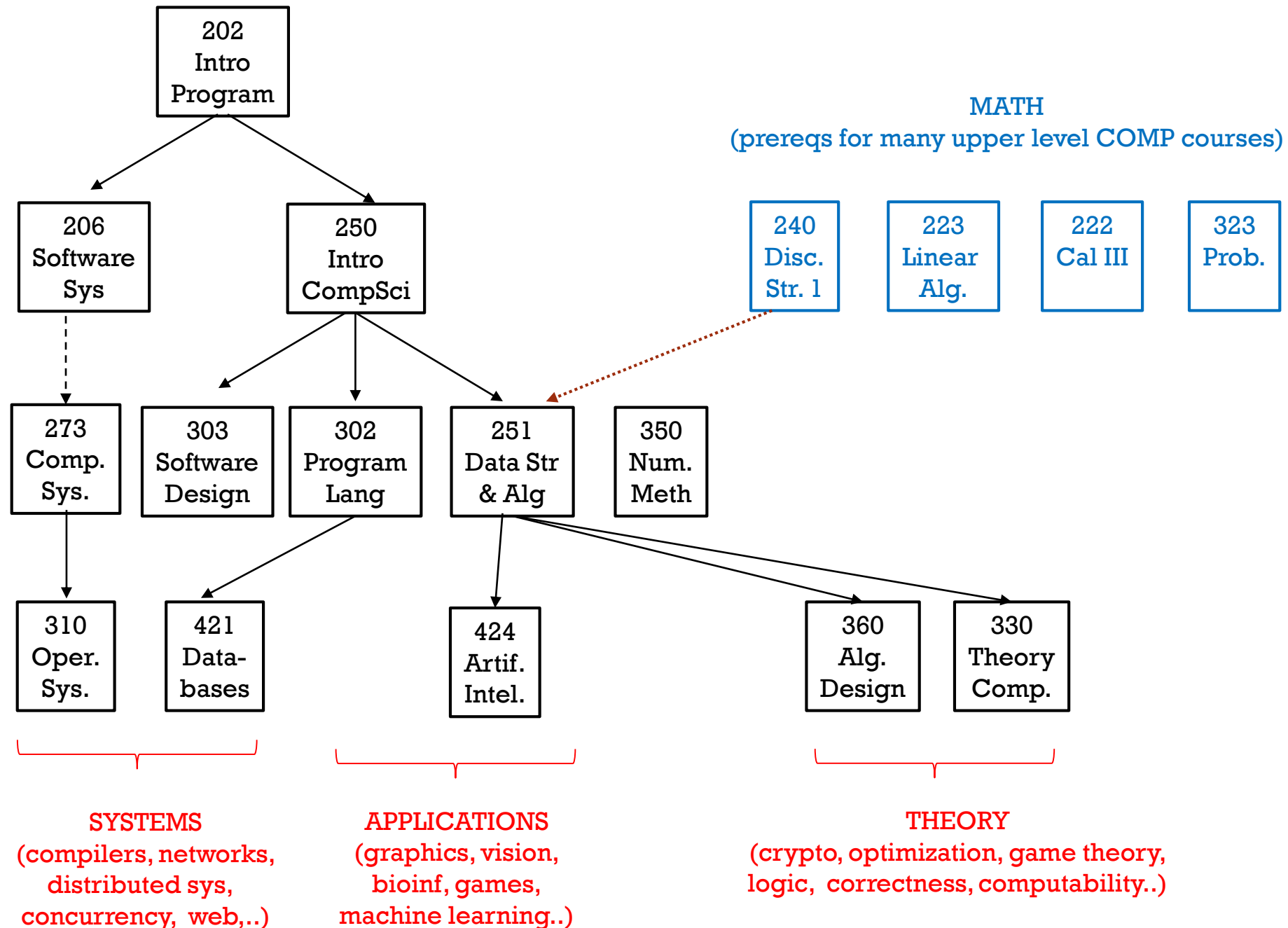
DIRECTED ACYCLIC GRAPH



no cycles

Used to capture dependencies.

There are three paths from **a** to **d**.



GRAPH ADT

- `addVertex()`, `addEdge()`
- `containsVertex()`, `containsEdge()`
- `getVertex()`, `getEdge()`
- `removeVertex()`, `removeEdge()`
- `numVertices()`, `numEdges()`
- ...

How to implement a Graph class?

A graph is a generalization of a tree, so ...

RECALL: HOW TO IMPLEMENT A ROOTED TREE IN JAVA ?

```
class Tree<T>{
    TreeNode<T> root;
    :

    class TreeNode<T>{
        T element;
        ArrayList<TreeNode<T>> children;
        TreeNode<T> parent; // optional
    }
}
```

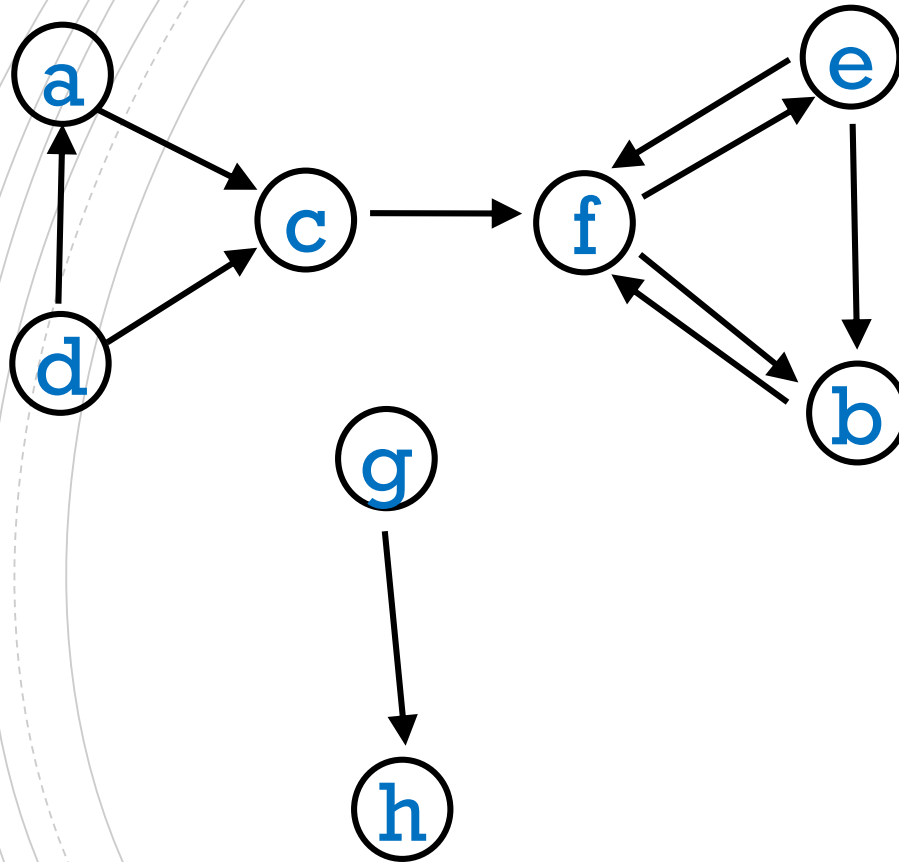
// alternatively....

```
class Tree<T>{
    TreeNode<T> root;
    :

    class TreeNode<T>{
        T element;
        TreeNode<T> firstChild;
        TreeNode<T> nextSibling;
    }
}
```

ADJACENCY LIST

(GENERALIZATION OF CHILDREN FOR GRAPHS)



v
a
b
c
d
e
f
g
h

v.adjList
c
f
f
a, c
b, f
b, e
h

Here each adjacency list is sorted, but that is not always possible (or necessary).

HOW TO IMPLEMENT A GRAPH CLASS IN JAVA?

A very basic Graph class:

```
class Graph<T> {  
    class Vertex<T> { // We could have called it GNode  
        ArrayList<Vertex> adjList;  
        T element;  
    }  
}
```

HOW TO IMPLEMENT A GRAPH CLASS IN JAVA?

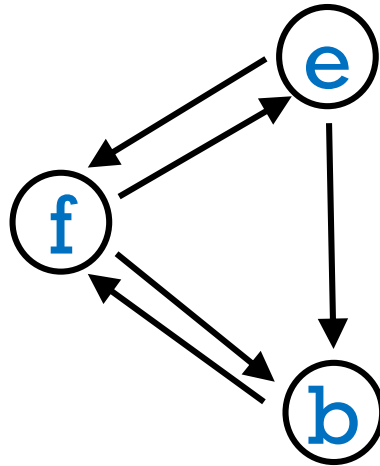
```
class Graph<T> {  
    class Vertex<T> {  
        ArrayList<Edge> adjList;  
        T element;  
        boolean visited;  
    }  
  
    class Edge {  
        Vertex endVertex;  
        double weight;  
        :  
    }  
}
```

Note that, unlike a rooted tree, there is no notion of a root vertex in a graph.

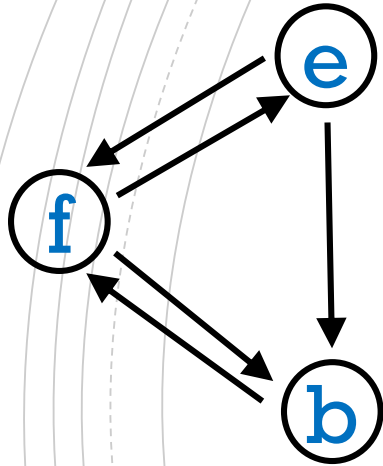
HOW TO REFERENCE VERTICES?

```
class Graph<T> {  
    ArrayList< Vertex<T> > vertexList;  
    :  
    class Vertex<T> { ... }  
    class Edge<T> { ... }  
}
```

HOW MANY OBJECTS ?



HOW MANY OBJECTS ?



Graph

ArrayList <Vertex>

Vertex

Vertex

Vertex

Edge

Edge

Edge

Edge

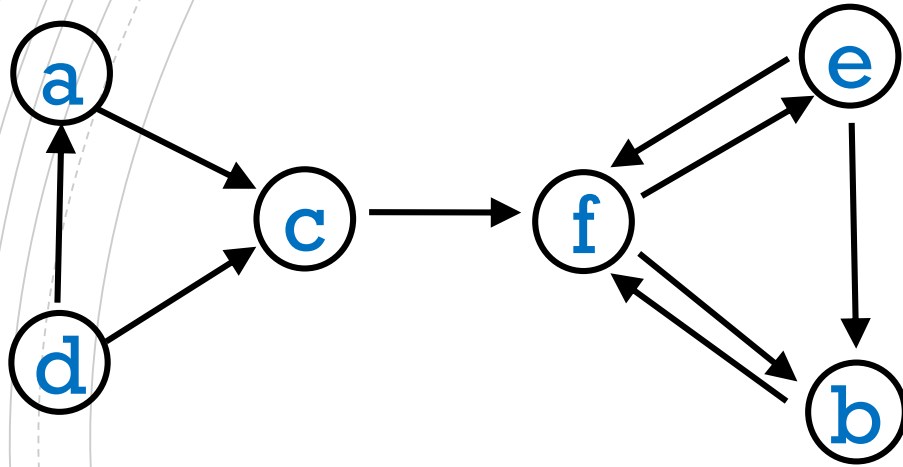
Edge

ArrayList<Edge>

ArrayList<Edge>

ArrayList<Edge>

ADJACENCY MATRIX

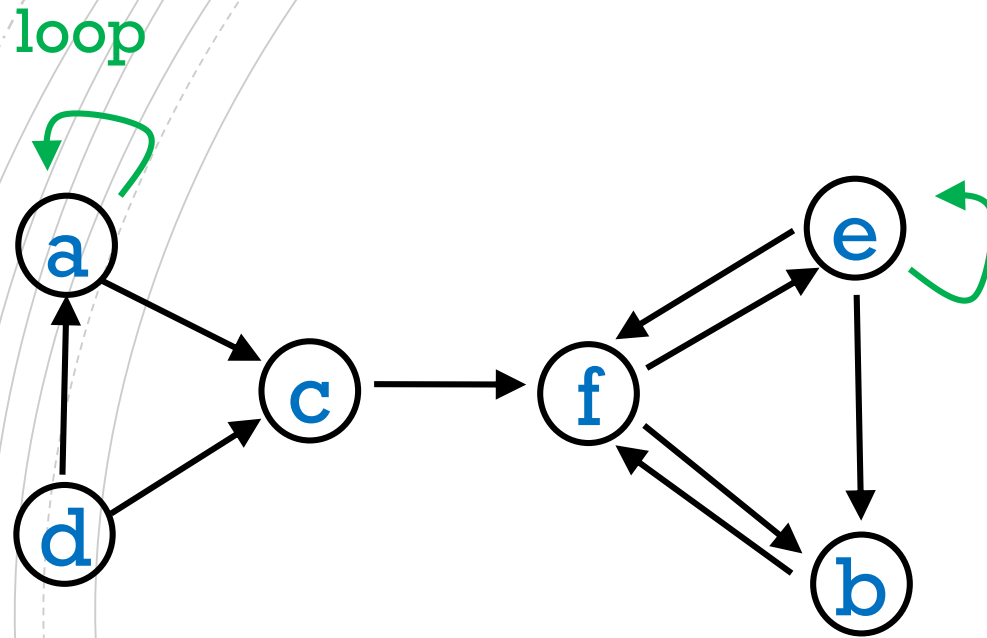


	a	b	c	d	e	f
a	0	0	1	0	0	0
b	0	0	0	0	0	1
c	0	0	0	0	0	1
d	1	0	1	0	0	0
e	0	1	0	0	0	1
f	0	1	0	0	1	0

Assume we have a mapping from vertex names to 0, 1, ..., n-1.

```
boolean[][] adjMatrix = new boolean[6][6]
```

ADJACENCY MATRIX



	a	b	c	d	e	f
a	1	0	1	0	0	0
b	0	0	0	0	0	1
c	0	0	0	0	0	1
d	1	0	1	0	0	0
e	0	1	0	0	1	1
f	0	1	0	0	1	0

Assume we have a mapping from vertex names to 0, 1, ..., n-1.

```
boolean[][] adjMatrix = new Boolean[6][6]
```

"DEFINITIONS"

Consider a graph with n vertices.

We say that the graph is *dense* if the number of edges is close to n^2 .

We say that the graph is *sparse* if the number of edges is close to n .

(These are not formal definitions.)

EXERCISE

Would you use an *adjacency list* or *adjacency matrix* for each of the following scenarios?

- The graph is sparse e.g. 10,000 vertices and 20,000 edges and we want to use as little space as possible.
- The graph is dense e.g. 10,000 vertices and 20,000,000 edges, and we want to use as little space as possible. .
- Answer the query `areAdjacent()` as quickly as possible, no matter how much space you use.
- Perform operation `insertVertex(v)`.
- Perform operation `removeVertex(v)`.

The background features a series of concentric circles in a light gray color, centered around the middle of the slide. A solid dark red rectangle is positioned in the center, containing the title text. Below this rectangle is a horizontal white line, followed by another solid dark red rectangle of the same width.

GRAPH TRAVERSAL

(RECURSIVE)

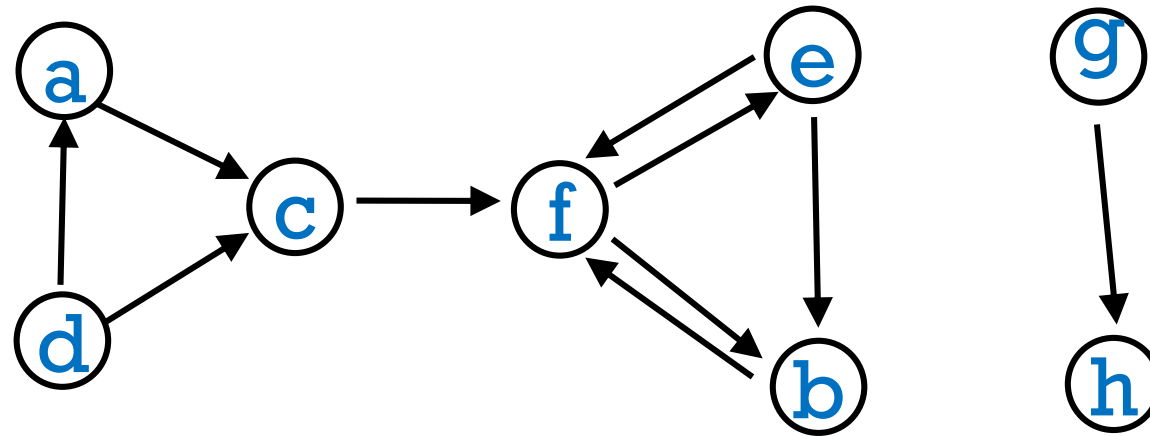
RECALL: TREE TRAVERSAL (RECURSIVE)

```
depthFirst_Tree (root){  
    if (root is not empty){  
        visit root // preorder  
        for each child of root  
            depthfirst_Tree( child )  
    }  
}
```

GRAPH TRAVERSAL (RECURSIVE)

Need to specify a starting vertex.

Visit all nodes that are “reachable” by a path from a starting vertex.



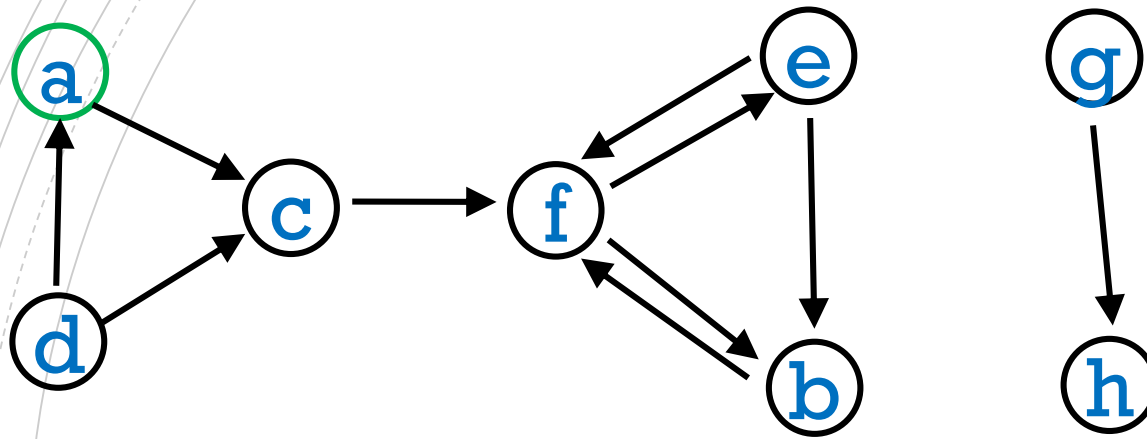
GRAPH TRAVERSAL (RECURSIVE)

```
depthFirst_Graph (v) {  
    v.visited = true  
    for each w such that (v,w) is in E  
        // i.e. v.adjList.contains(w) returns true  
        ??  
}
```

GRAPH TRAVERSAL (RECURSIVE)

```
depthFirst_Graph (v) {  
    v.visited = true  
    visit v // do something with v  
    for each w such that (v,w) is in E  
    // i.e. for each w in v.adjList  
        if !(w.visited) // avoid cycles!  
            depthFirst_Graph(w)  
}
```

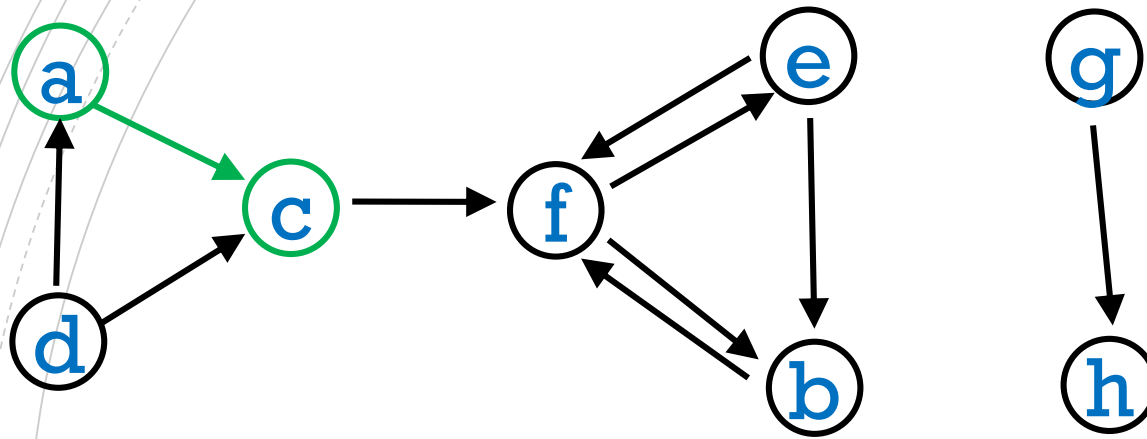
CALL STACK FOR depthFirst(a)



a

```
depthFirst_Graph (v) {  
    v.visited = true  
    for each w s.t. (v,w) is in E  
        if !(w.visited)  
            depthFirst_Graph(w)  
}
```

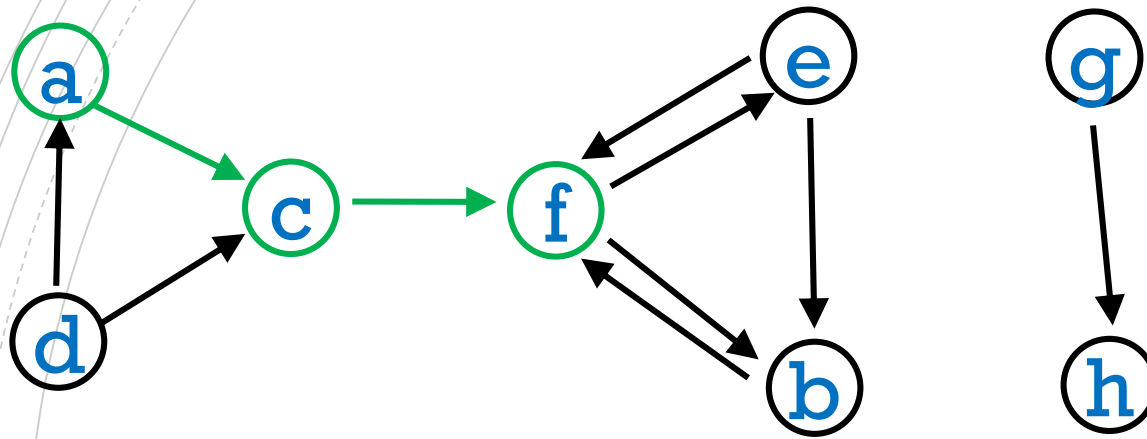
CALL STACK FOR depthFirst(a)



a c
a

```
depthFirst_Graph (v) {  
    v.visited = true  
    for each w s.t. (v,w) is in E  
        if !(w.visited)  
            depthFirst_Graph(w)  
}
```

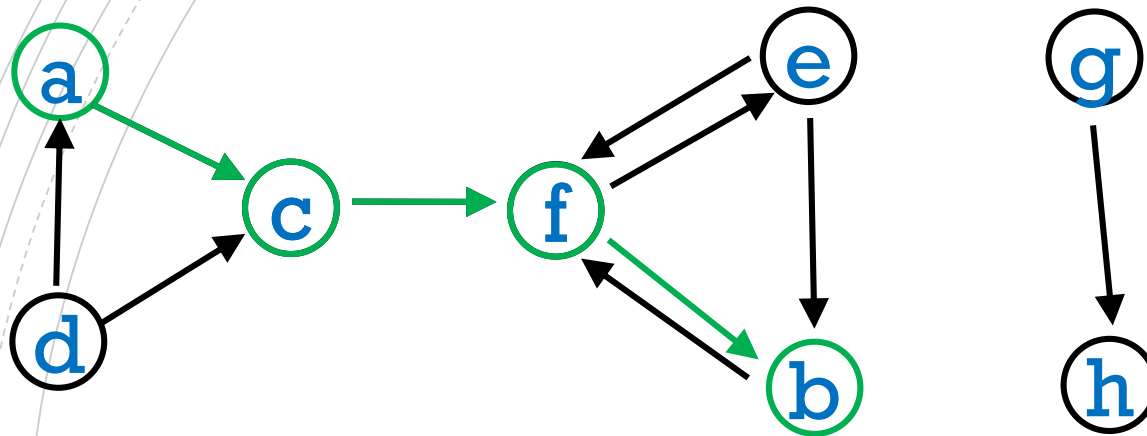

CALL STACK FOR depthFirst(a)



a c f
a c a

```
depthFirst_Graph (v) {  
    v.visited = true  
    for each w s.t. (v,w) is in E  
        if !(w.visited)  
            depthFirst_Graph(w)  
}
```

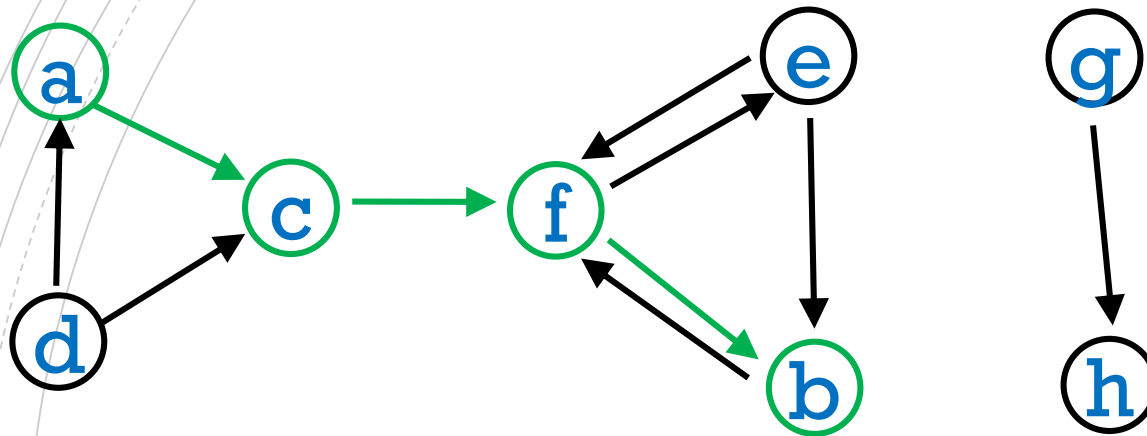
CALL STACK FOR depthFirst(a)



			b
		f	f
	c	c	c
a	a	a	a

```
depthFirst_Graph (v) {  
    v.visited = true  
    for each w s.t. (v,w) is in E  
        if !(w.visited)  
            depthFirst_Graph(w)  
}
```

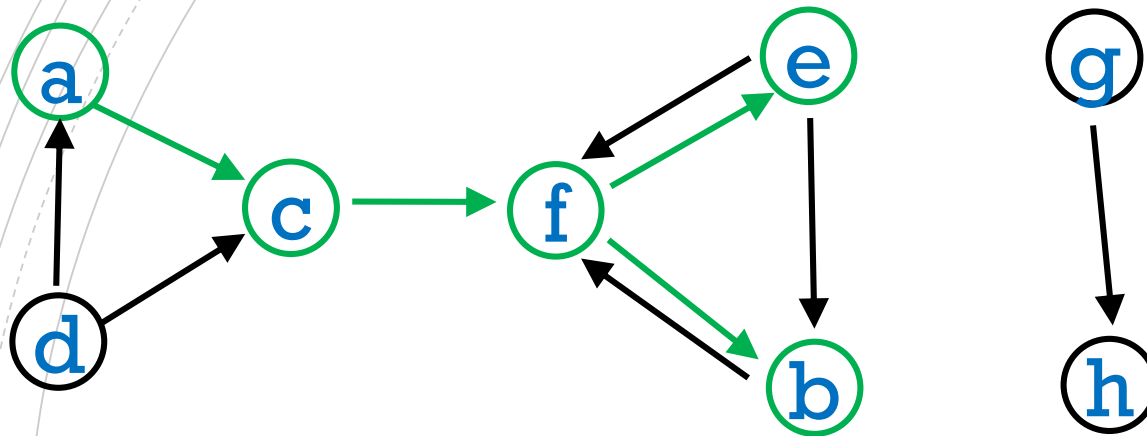
CALL STACK FOR depthFirst(a)



			b	
		f	f	f
	c	c	c	c
a	a	a	a	a

```
depthFirst_Graph (v) {  
    v.visited = true  
    for each w s.t. (v,w) is in E  
        if !(w.visited)  
            depthFirst_Graph(w)  
}
```

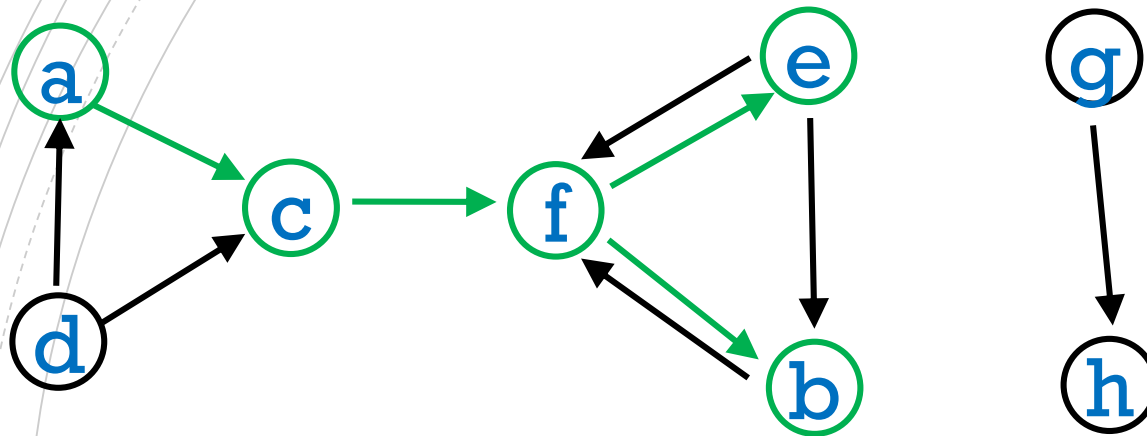
CALL STACK FOR depthFirst(a)



			b		e
		f	f	f	f
	c	c	c	c	c
a	a	a	a	a	a

```
depthFirst_Graph (v) {  
    v.visited = true  
    for each w s.t. (v,w) is in E  
        if !(w.visited)  
            depthFirst_Graph(w)  
}
```

CALL STACK FOR depthFirst(a)

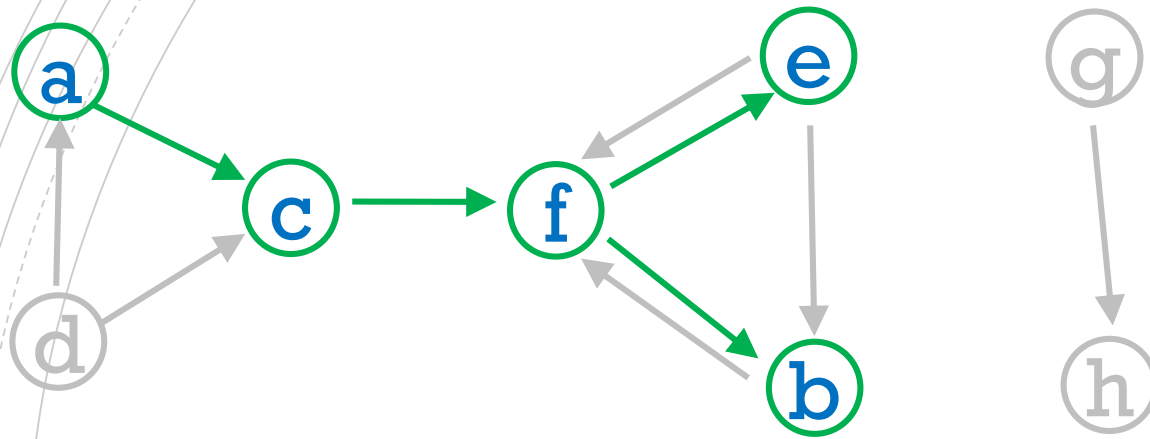


			b		e			
		f	f	f	f	f		
	c	c	c	c	c	c	c	
a	a	a	a	a	a	a	a	a

```
depthFirst_Graph (v) {  
    v.visited = true  
    for each w s.t. (v,w) is in E  
        if !(w.visited)  
            depthFirst_Graph(w)  
}
```

CALL TREE

root

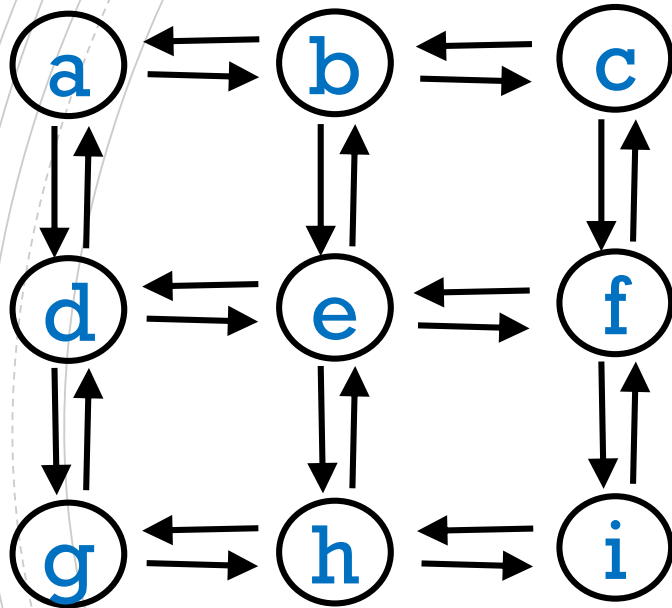


The diagram illustrates the evolution of a word through a series of stages, represented by columns of letters. The letters are arranged in a grid-like structure, with some letters appearing in multiple columns. The letters are: 'a', 'c', 'f', 'b', and 'e'. The letters are arranged in a way that suggests a progression from left to right. The letters 'a' and 'c' are in the bottom row, 'f' is in the middle row, and 'b' and 'e' are in the top row. The letters are arranged in a way that suggests a progression from left to right. The letters 'a' and 'c' are in the bottom row, 'f' is in the middle row, and 'b' and 'e' are in the top row.

GRAPH TRAVERSALS

- Unlike tree traversal for rooted tree, a graph traversal started from some arbitrary vertex does not necessarily reach all other vertices.
- *Knowing which vertices can be reached by a path from some starting vertex is itself an important problem. You will learn about such graph 'connectivity' problems in COMP 251.*
- The order of nodes visited depends on the order of nodes in the adjacency lists.

EXAMPLE 2



Adjacency List

a - (b,d)

b - (a,c,e)

c - (b,f)

d - (a,e,g)

e - (b,d,f,h)

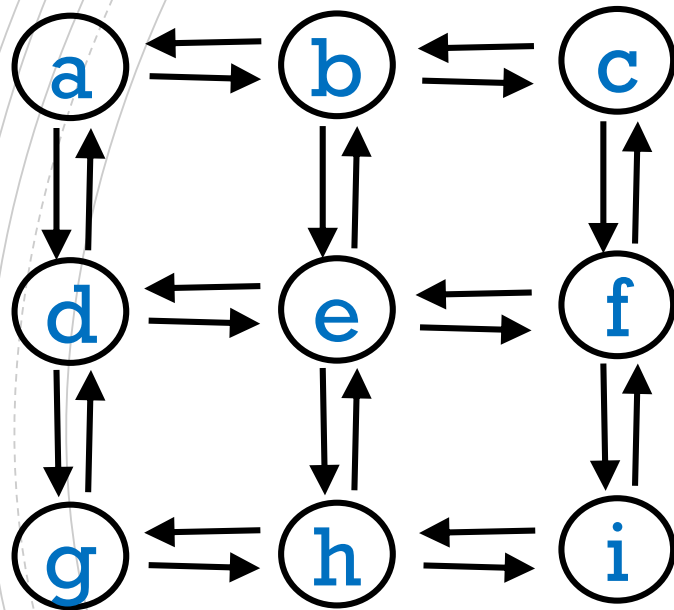
f - (c,e,i)

g - (d,h)

h - (e,g,i)

i - (f,h)

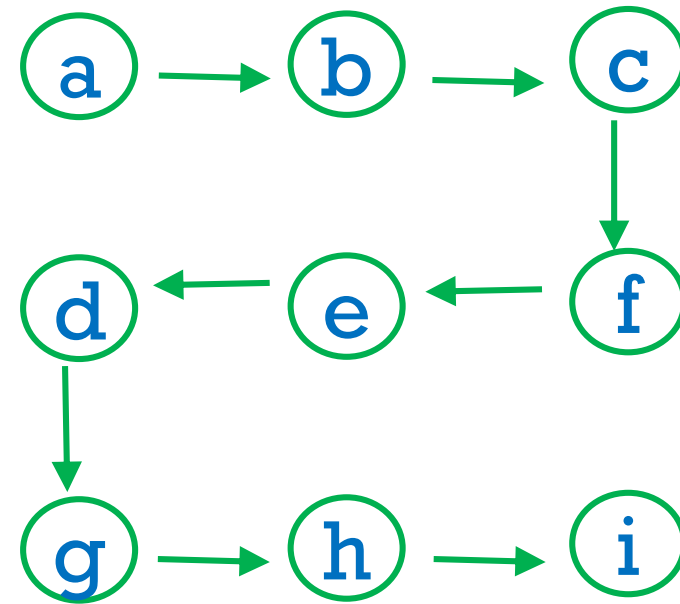
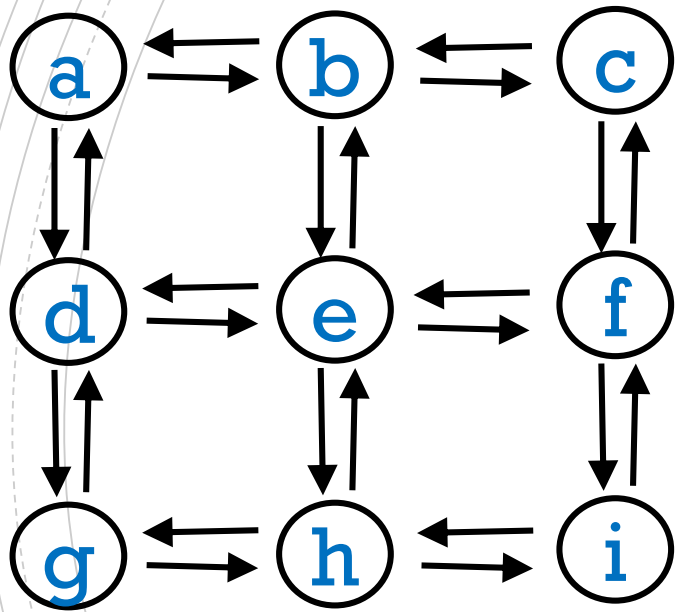
EXAMPLE 2



What is the call tree
for `depthFirst(a)` ?

(Do it in your head)

EXAMPLE 2



call tree for `depthFirst` (**a**)



Coming Soon

Coming next:

- Non-recursive graph traversal
 - depth first
 - breadth first
- Shortest path in a DAG
 - Dijkstra's Algorithm